

bandwidth of the klystron as required for low group delay. In addition, the loaded Q factor of the input cavity is well below 200 and that of the output cavity is 35. The penultimate cavity is tuned to more than 2% above the operating frequency, and therefore contributes little to the total group delay within the specified frequency range. The third cavity is tuned to a few MHz below the second harmonic of the operating frequency; it does not contribute to the group delay but enhances the klystron efficiency by about 4-5%. About 10% of the group delay is due to the electron transit time between input and output cavity.

The relatively low Q and the detuning of the input cavity causes, however, a low overall signal gain of only 37 dB; this is unusual for klystrons.

Table 1: Main Klystron Parameters at Rated Output Power

Rated Output Power	300 kW cw
Operating Frequency (f_0)	400.8 MHz
RF Input-to-Output Gain	≥ 37 dB
DC-to-RF Conversion Efficiency	≥ 62 %
-1dB Bandwidth (@1dB below rated output power)	$\geq \pm 1$ MHz
Group Delay at $f_0 \pm 1$ MHz and 1dB below rated output power	≤ 120 ns
Load VSWR at any RF Phase	≤ 1.2
Harmonic Content in Output Signal at 2 nd and 3 rd Harmonic	≤ -30 dB
Beam Voltage (U_B)	54 kV
Beam Current (I_B)	≤ 9 A
Gun Perveance	$1.5 \text{ mA/V}^{3/2}$ -0/+10%
Modulation Anode Voltage (U_{MA})	≤ 35 kV
Modulation Anode Current (I_{MA})	$\leq \pm 2.5$ mA
Body Dissipation	≤ 10 kW
Collector Dissipation Capability	≥ 500 kW
Test Power at $U_B \leq 58$ kV and $I_B \leq 10$ A (for at least 1 hour)	330 kW cw

A special feature of the LHC klystron is the built-in modulation anode. It allows the cathode current to be controlled between 0 and 10 A. Unlike the LEP klystron, the LHC one does not require the cathode current to be ramped down in the absence of an RF drive signal, because the water-cooled collector of the LHC klystron can dissipate the full DC input power of 500 kW. The modulation anode is used only for optimizing the working point of the klystron.

The tube operation is stable up to the rated output power for a load mismatch of $VSWR \leq 1.2$ which is assured by a three-port junction circulator in the output

line of each klystron. In case of a higher VSWR (e.g. an arc in the output waveguide) a fast PIN-diode switch interrupts the RF drive signal to the klystron.

CIRCULATOR WITH TERMINATING LOAD

The LHC/RF three-port circulators must cope with high peak power levels, induced in the SC cavities by the proton beam. During injection they can be as high as twice the incident klystron power of 300 kW. These reflected signals are in the microsecond range and their contribution to the power dissipation in the circulator is negligible. However, the superposition of incident and reflected signals could cause arcing between the ferrite plates. This was simulated on the prototype circulator by short-circuiting the output port and applying the appropriate input power (P_{IN}), which is defined by:

$$P_{IN} = \frac{1}{4} \left(\sqrt{P_F} + \sqrt{P_R} \right)^2$$

For $P_F = 300$ kW and $P_R = 600$ kW the input power P_{IN} is 440 kW. No arcing was observed when 440 kW were applied with the short-circuit at port 2 being moved by steps of 5 cm over half a waveguide wavelength.

The saturation magnetization of the ferrites is temperature dependent. The external magnetization of the ferrites has therefore to be adjusted as a function of their temperatures, which depend on the incident and reflected power and cooling water temperature. The external field is generated by both a permanent and an electro magnet. The temperatures of the cooling water and the permanent magnet are measured, and the 'Temperature Control Unit' adjusts the current of the electro-magnet accordingly. At RF power levels up to 330kW and inlet water temperature variations of $25 \pm 3^\circ\text{C}$ the input match (S_{11}) and isolation (S_{12}) of the circulator can, thus, be kept at ≤ -28 dB within the specified bandwidth of $f_0 \pm 1$ MHz .

For reasons of better performance and smaller size it was decided to use 330 kW ferrite-loaded waveguide absorbers instead of water-loads as port 3 terminations. In such a load small ferrite tiles are glued onto the inner walls of a waveguide, which is short-circuited at its far end. A crucial parameter is the power dissipated per unit surface of ferrite, which should not exceed 15 W/cm^2 . It is achieved by choosing thin ferrite tiles at the input of the load and by gradually increasing their thickness towards the shortened end. The advantages of ferrite compared to water loads are the absence of water inside the waveguide or coaxial line, smaller size, higher bandwidth, and a nearly invariable phase angle of its reflected signal as a function of the absorbed power.

The total input reflection of the circulator is composed of S_{11} , S_{12} , and S_{13} (see Fig.2). The magnitudes of S_{12} (isolation) and S_{13} (reflection from ferrite load) are both about -28 dB. The phase angle between these two signals

is virtually constant and independent of input power and load mismatch at port 2. By adjusting the electrical length of the waveguide between circulator and ferrite load this angle can be made 180°. The input reflection can thus be reduced substantially and becomes nearly independent of the load conditions at port 2. An almost constant circulator input impedance is essential for stable klystron output power.

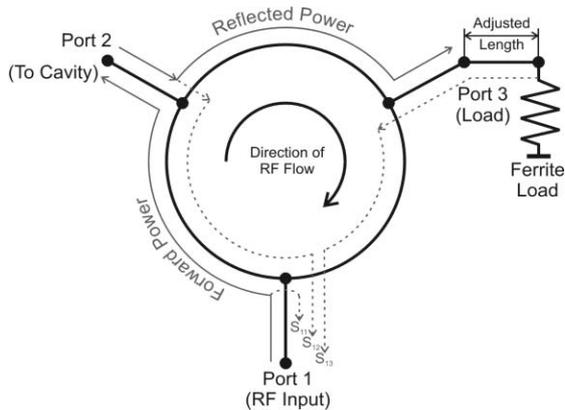


Figure 2: Schematic Diagram of Circulator with Termination Load

The standard ‘Temperature Control Unit’ (TCU) can cope with slow water temperature and load mismatch variations only. This is due to the time constant of the circulator’s cooling circuit. If there are fast and large variations of one or both parameters the input VSWR of the circulator could briefly exceed the specified value. To avoid this, the TCU monitors the reflected RF signal between klystron and circulator. An additional built-in microprocessor controlled loop acts on the magnet current and minimizes rapidly the reflected signal as can be seen in Fig. 2. In this measurement the inlet water temperature was periodically varied by a few degrees.

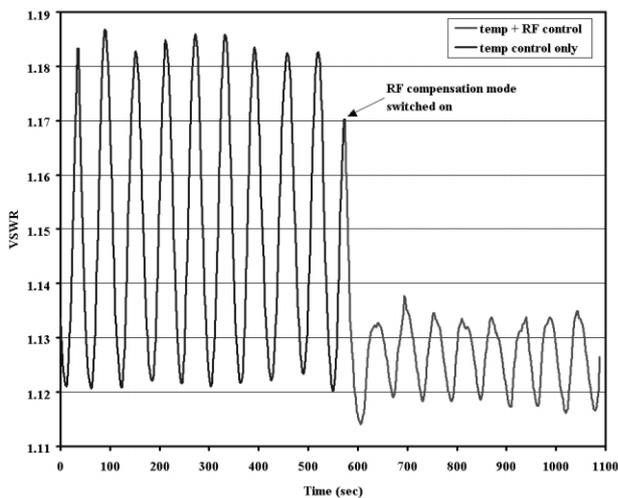


Figure 3: Input VSWR of the circulator with and without RF control at varying water temperatures

HARMONIC SIGNAL MEASUREMENTS

An advanced system for measuring the harmonic content in the klystron output signal based on [1] was developed. It consists of a piece of WR2300 half-height waveguide equipped with calibrated RF probes, an RF switching matrix, band filters, a vector voltmeter and a control computer. The system measures the power levels of all possible propagating modes at the fundamental (TE₁₀), second (TE₁₀, TE₂₀, TE₃₀), and third harmonic (TE₁₀, TE₂₀, TE₃₀, TE₄₀, TE₁₁, TM₁₁, TE₂₁, TM₂₁, TE₀₁). Three probes are used at the narrow and nine probes (including a reference one) at the wide wall of the waveguide for measuring the electric field pattern. These data are inserted into a set of field equations, and the control computer calculates the power of each propagating mode. In its present state, measurements can only be performed using a wideband load, which is matched (VSWR ≤ 1.12) in the frequency range from 400 to 1200 MHz.

Measurements performed on the klystrons delivered so far indicate that the 2nd harmonic content is more than 50 ± 1 dB, and the 3rd harmonic more than 28 ± 1 dB below the fundamental signal. The TE₃₀ mode of the 3rd harmonic signal contains about 50% of the parasitic energy. These measurements will help to determine the type of HOM dampers, which may be required in the waveguide system to avoid arcing.

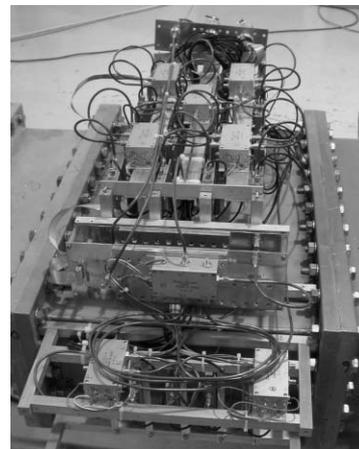


Figure 4: Harmonic measurement device

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REFERENCES

- [1] W.R. Fowkes and E.S. Wu, “Multimode Harmonic Power Output Measurement of SLAC High Power Klystrons”. SLAC-PUB-3009, November 1982