The L-CAPE Project at FNAL

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Summary

- Controls System at FNAL
 - Records data asynchronously from several thousand Linac (Linear Accelerator) devices
 - Frequency ranging from 15 Hz down to once per minute
- Current Operations:
 - Mostly Reactive: Investigating cause after the effect
 - On beam interruption, operators use the data to investigate the source of unplanned beam outage from the FNAL Main Control Room.

Outage Labelling

- > Operator Labeling (also referred to as "Ground Truth Labels")
 - List of outages with labels and times reported by the operators
 - Required for analytics, visualization, and model verification and validation
 - No label if the downtime duration is <1 min
- > Bit Permits

RFICUR

RF1

RF1CT4

RF1CT3

RF1CT2

RF1CT1

- Permits raised by the operators to report downtimes
- Bit-27 (downstream permit) and Bit-28 (upstream permit)

Modelling & Evaluation

- > Goal
 - Apply data-analytic methods to improve information available to the operators

 - Use machine learning to automate the detection & labeling of outages and
 - Discover patterns in the data that could lead to prediction of outages

Table-1: Energy Use During Beam Outages

Event Length	Event Count	Duration (hours)	Energy (MWh)
< 5s	1626	1.04	0.182
< 10s	321	0.59	0.104
< 60s	205	2.01	0.351
< 120s	201	4.70	0.822
< 10m	169	11.69	2.05
≥ 10m	47	111.35	19.49

Data Sources

Data Logger

- Accelerator control system's data logger nodes record data streams into circular buffers
- Pipeline Created by the developers at the FNAL's Controls Department using modern tools
- Solves a common problem and is being used on other ML projects





Figure-2: Comparison of anomaly score (TADGAN), operators' labels, and bit permits.
(a) High anomaly score but no reported fault (False Positive)
(b) Anomaly score aligns well with ground truth and bit permits (True Positive)
(c) No operator label but bit permits report a fault

#Devices: 2081 (status bits, settings, and noisy devices were filtered)
 Only 53 devices with complex data patterns were trained using the TADGAN

RF3CT2

RF3CT3

RF3CT4

RF3CVR

Thresholding

Assumes device value lower than the 5th percentile or higher than the 95th percentile is anomalous

Filtering

Data passes through a lowpass filter to filter highfrequency noise followed by a high-pass filter to filter brief anomalies/spikes

- Data Stats
 - L-CAPE makes 5567 requests over 4292 control system parameters and stores each request in an HDF5 group
 - The HDF5 output is collected by the hour with an average file size of 644MB per period

Figure-3: LRF2 Driver Anode OL

Data Preprocessing Procedures

- > Challenges with Raw Data
 - Hourly raw data files (in HDF5 format) are sampled from devices
 - at their respective cadences (different frequencies), and
 - timestamped by independent front-end nodes' clocks (misaligned timestamps)
 - High disk utilization and read/write time (bulky and slow)
 - Requires preprocessing for data analytics & visualization (inefficient)
- Preprocessing Procedures
 - <u>Reference Clock</u>: Timestamps from the 15Hz devices (devices with highest frequency)
 - DataFrame: Combined data using reference clock for quick analytics & visualization
 - Parquet+Snappy: Reduced disk utilization by 20x and accelerates read/write ops

LRF3 Driver Anode Overload.



Visualizing Processed Data



TADGAN

An unsupervised anomaly detection approach built on Generative Adversarial Networks (GANs) by Geiger et al. [1]

Figure-4: LRF3 Driver Anode OL

Table-2: Performance Comparison - Thresholding, Filtering, and TADGAN. Data for March 2021

	#Devices	True Positives	False Negatives	False Positives	Precision	Recall	F1-Score
Thresholding	2081	99	13	210	0.32	0.88	0.47
Filtering	2081	105	7	279	0.27	0.94	0.42
TADGAN	53	51	61	443	0.1	0.45	0.17

- Overall, statistical techniques better (high recall) than TADGAN
- However, statistical techniques tend to perform poorly for:
 - $\hfill\square$ Devices with multi-modalities
 - □ Real-time inference (smaller windows)
- High false positive rate: no operators label for faults <1min</p>
- > Ensemble of statistical and ML models



360 1440

60

Duration (in minutes



10080

360 1440

60

Duration (in minutes

0 1 2 5 10

Bit-28

Ground Truth



 Subset of devices for a single fault instance – "LRF3 Driver Anode Overload"

- For all the devices, data normalized between 0-1
- <u>Varying Start Time and Duration</u>: Different devices show different patterns during this fault
- <u>Pattern can vary</u>:
- from one instance of a fault to another; and
- from one fault type to another



- required for a scalable and accurate fault detection framework
- Variation in patterns can be exploited for unsupervised labeling (see Figure 3 and 4)



Figure-5: Evaluating the False Negatives

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[1] Alexander Geiger, Dongyu Liu, Sarah Alnegheimish, Alfredo Cuesta-Infante, and Kalyan Veeramachaneni. Tadgan: Time series anomaly detection using generative adversarial networks. In 2020 IEEE International Conference on Big Data (Big Data), pages 33–43. IEEE, 2020.