

LCLS-II KB Mirror Systems: Technical Challenges and Solutions

(Practice of Design Optimization)

L. Zhang, D. Cocco, N. Kelez, D.S. Morton

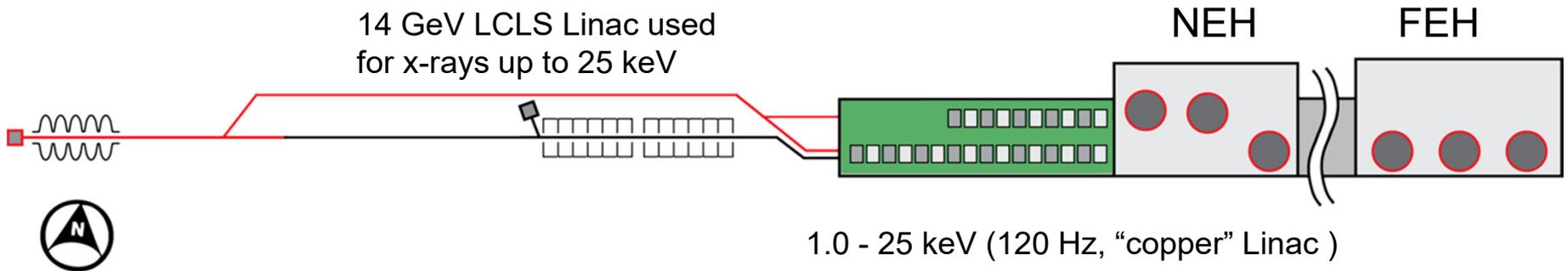
LCLS, SLAC National Accelerator Laboratory

2575 Sand Hill Road, Menlo Park, CA, 94025, United States

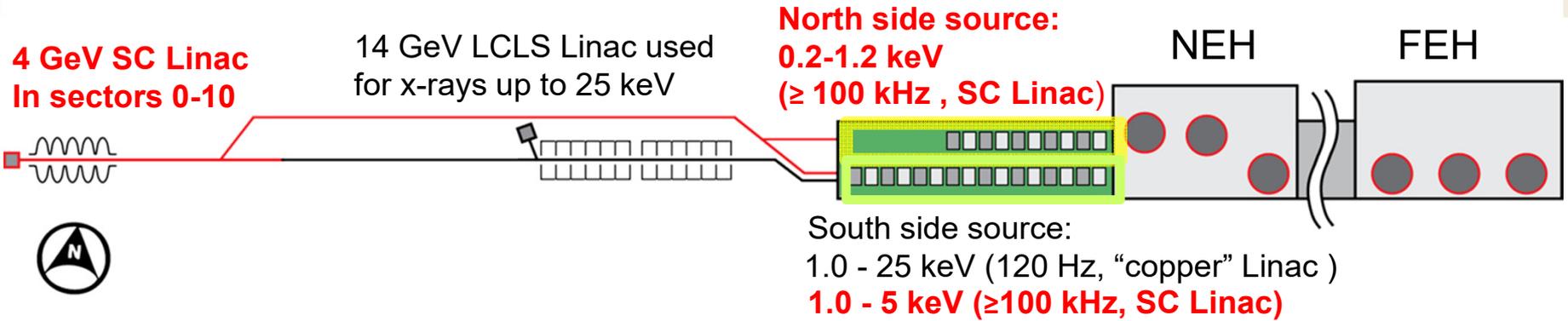
zhanglin@slac.stanford.edu

LCLS: Linac Coherent Light Source

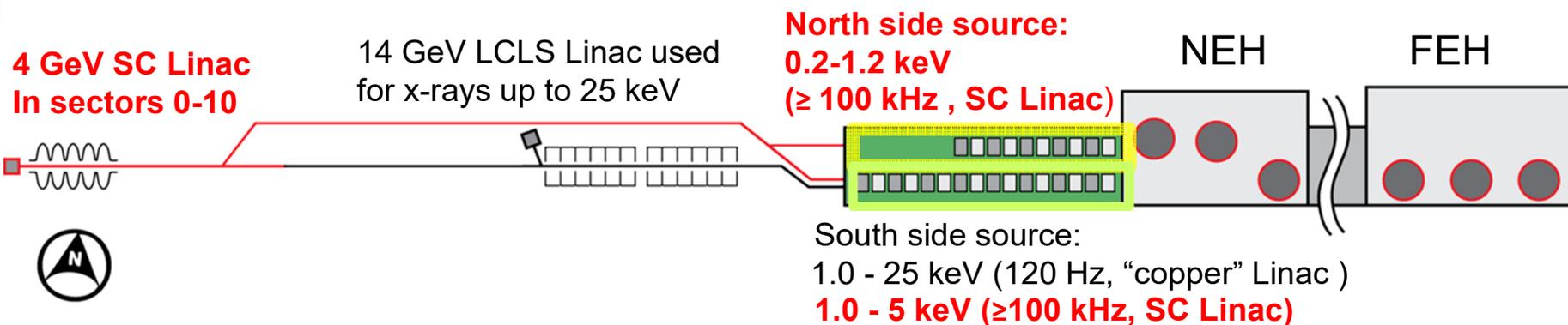
LCLS vs. LCLS-II



LCLS vs. LCLS-II

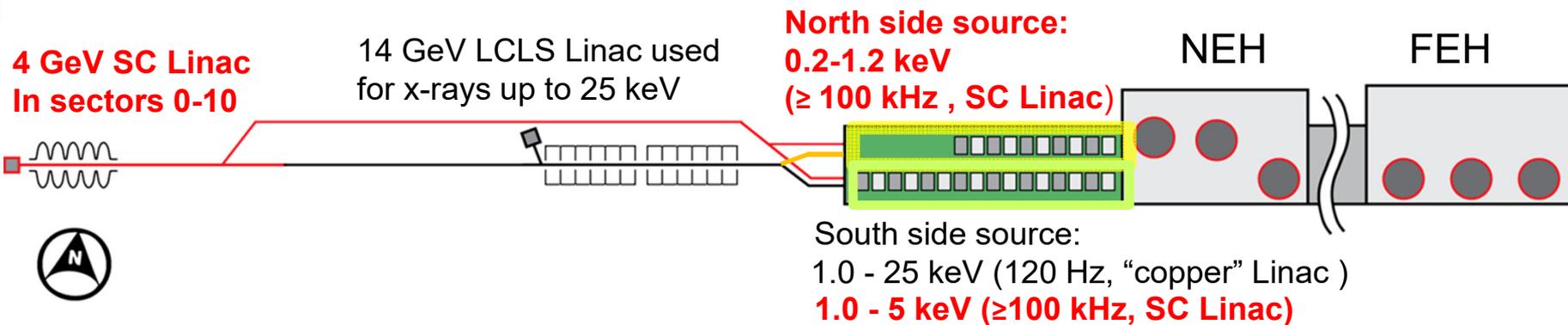


LCLS vs. LCLS-II



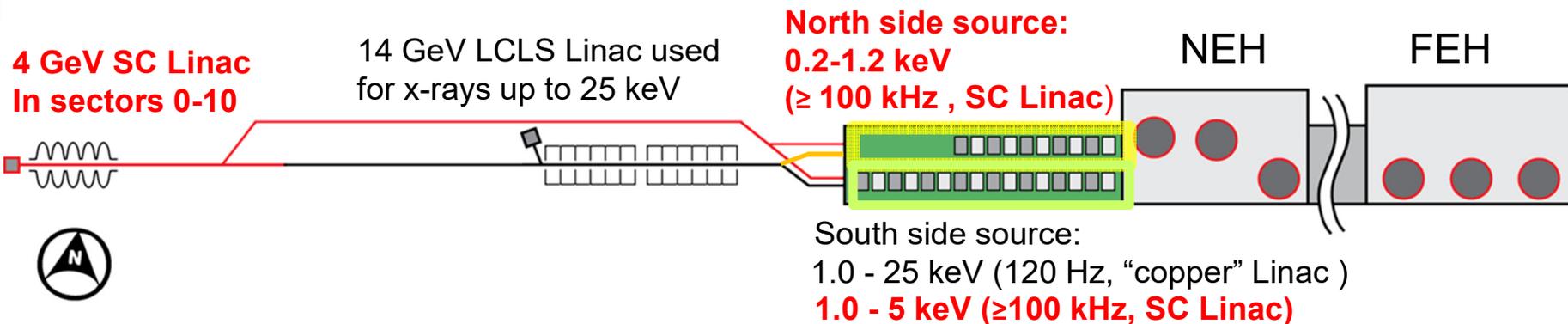
	LCLS-I Baseline	Now	HXU - Cu	HXU - SC	SXU - SC	SXU - Cu (TBC)
Photon Energy Range (eV)	800 - 8,000	250 - 12,800	400 - 25,000	1000 - 5000	200 - 1300	250 - 6000
Repetition Rate (Hz)	120	120	120	929,000	929,000	120
Per Pulse Energy (mJ)	~ 2	~ 4	~ 4	~ 0.2	~ 2	~ 8
Maximum average power (W)	0.24	0.48	0.48	200	600	0.96
Photons/Second	~ 10^{14}	~ 10^{14}	~ 10^{14}	~ 10^{16}	~ 10^{17}	~ 10^{14}

LCLS vs. LCLS-II



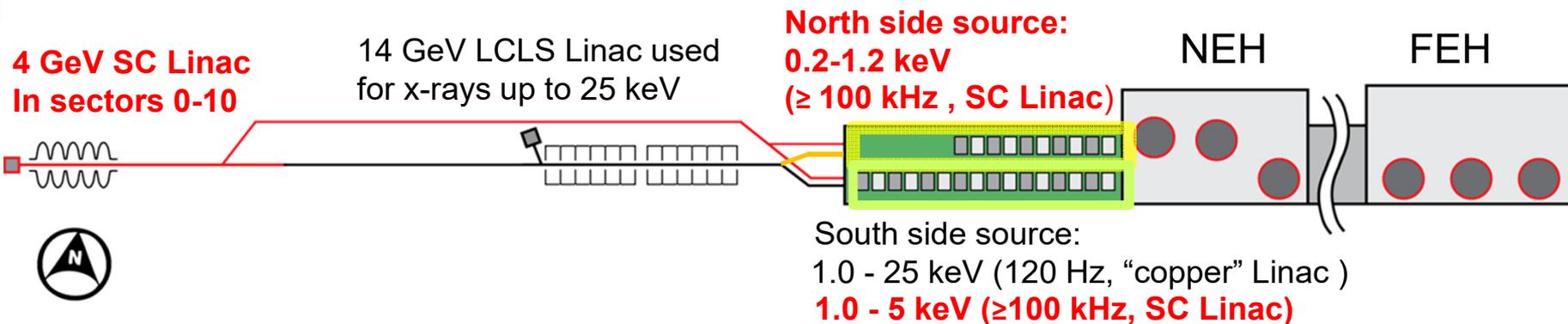
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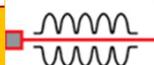
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LCLS vs. LCLS-II

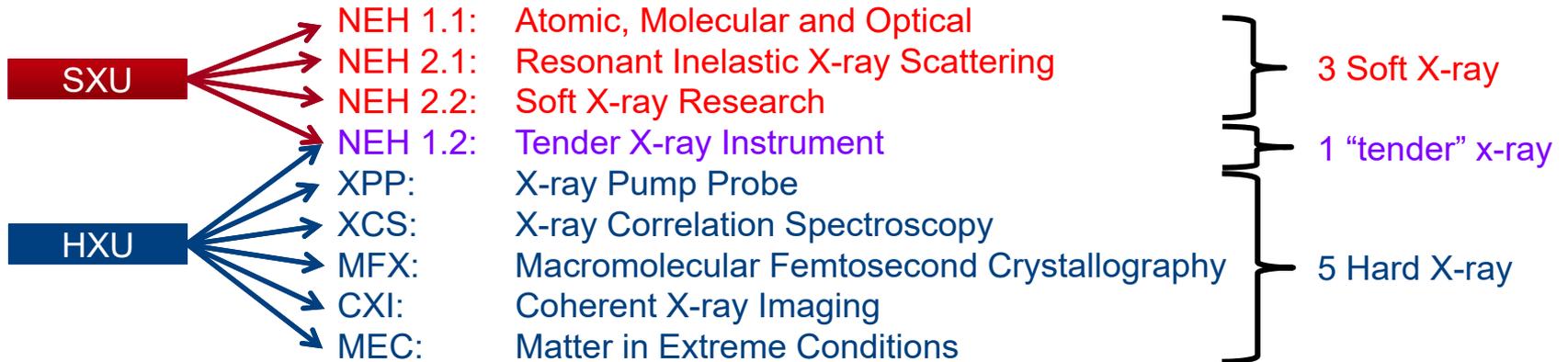
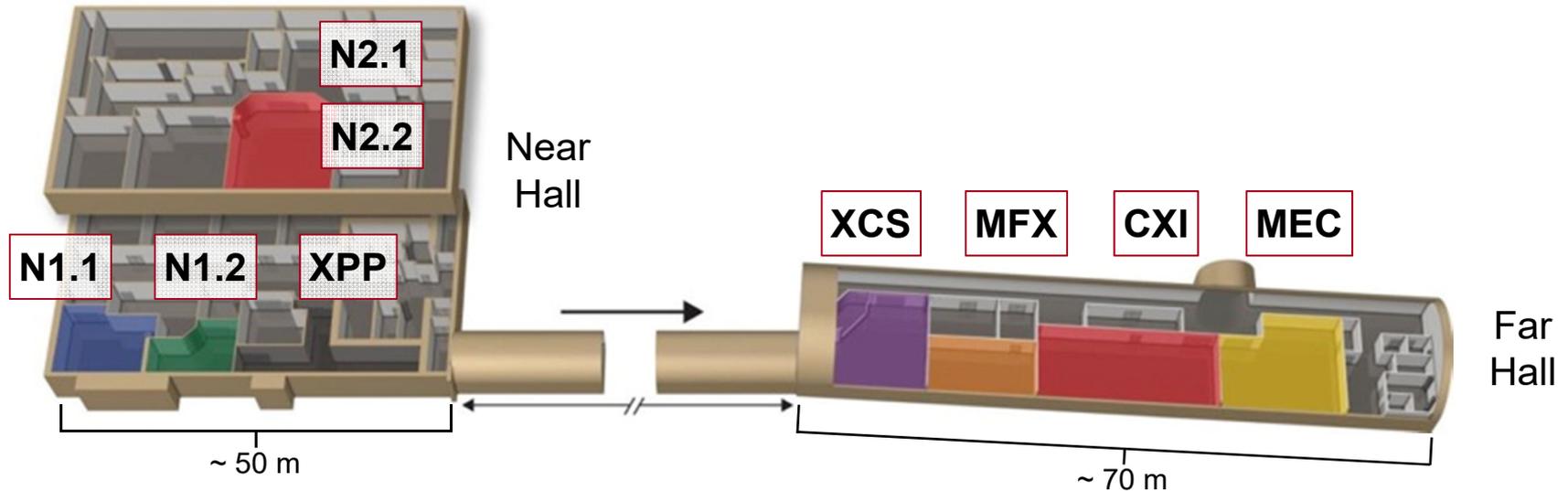


LCLS-II-HE:  **→ 25 keV (≥ 100 kHz, SC Linac)**

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X-ray instrument plans for LCLS-II

- 7 instruments fed by a single undulator at present
- 9 instruments available for LCLS-II



KB mirror systems for Soft and Tender X-ray

NEH 1.1

- High Flux Soft X-ray
- Bendable K-B Pair
 - 1 μm
- Fixed Figure K-B Pair
 - 300nm
- 250-1300 eV

NEH 1.2

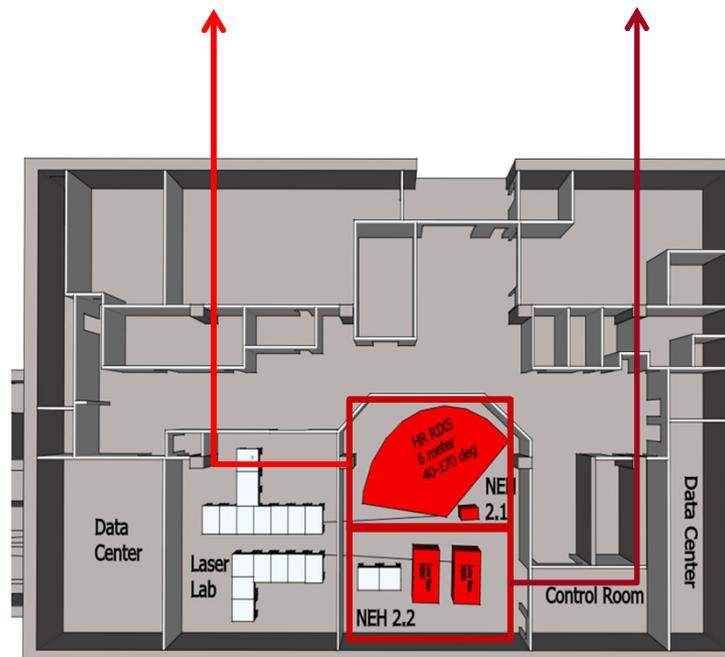
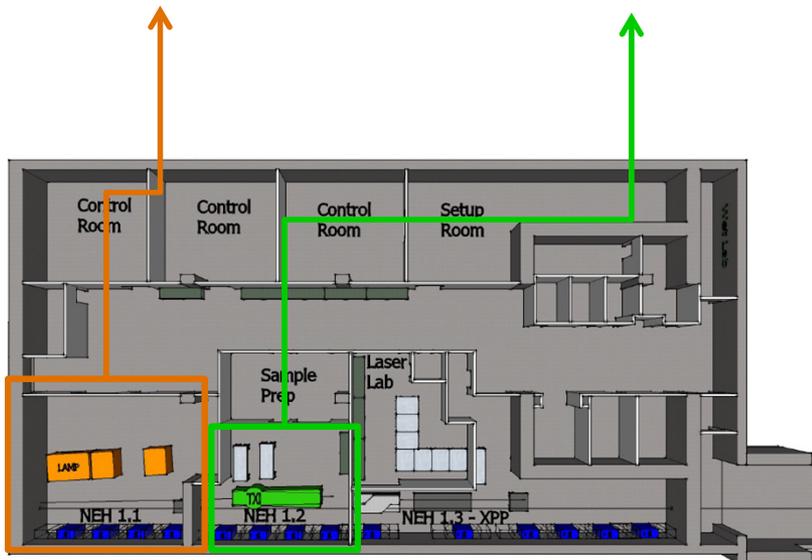
- Tender X-ray Instrument
- SXR Bendable K-B Pair
 - 1 μm
- HXR Bendable K-B Pair
 - 1 μm
- 400-6000 eV

NEH 2.1

- RIXS
- Bendable K-B Pair
 - 2x10 μm
- 250-1350 eV

NEH 2.2

- Mono Soft X-Ray
- Bendable K-B Pair
 - 1x4 μm
- 250-1350 eV



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NEH 1.2

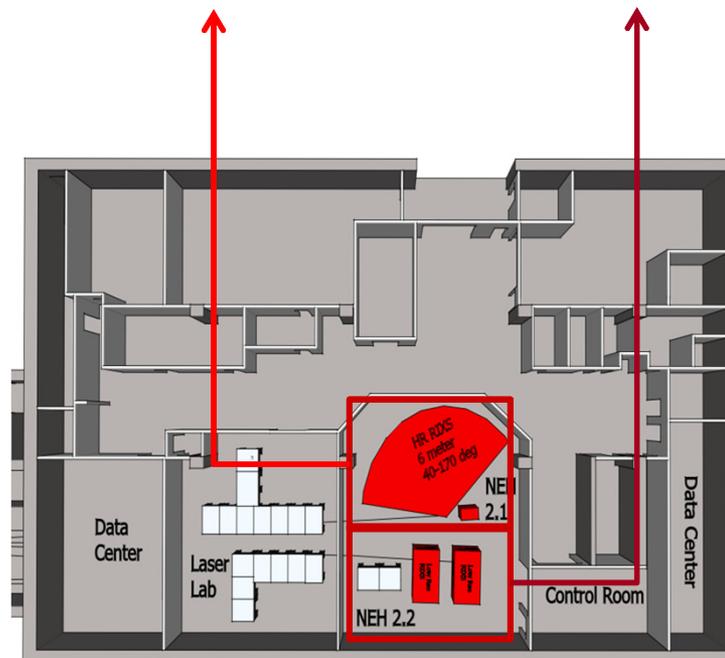
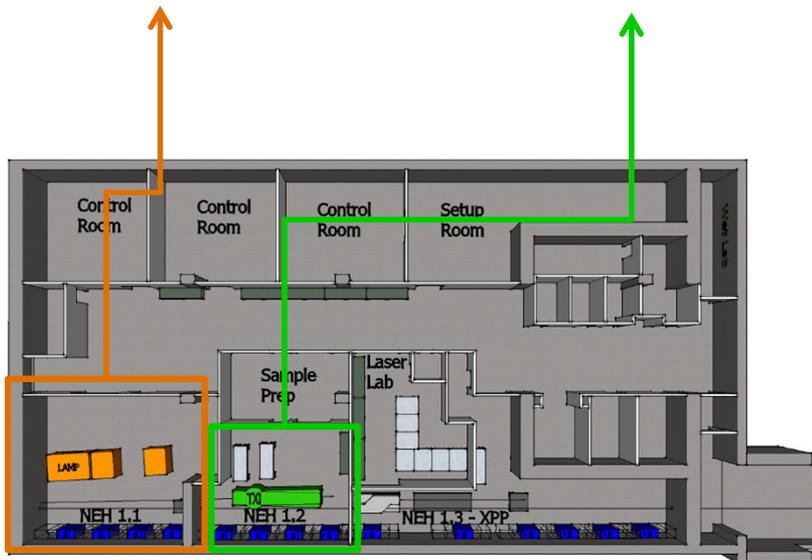
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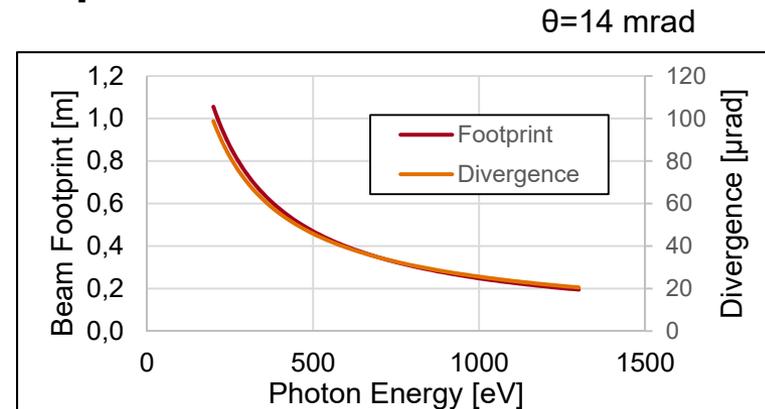
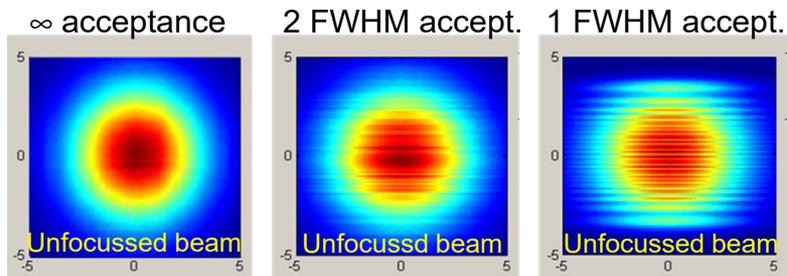
→ 6 pairs of KB mirror systems

Some properties of XFEL, optics requirements

- **Nearly monochromatic beam (especially with self-seeding)**
 - K-B mirrors absorbs $\sim 10\%$ XFEL beam power, \rightarrow to be actively **cooled**

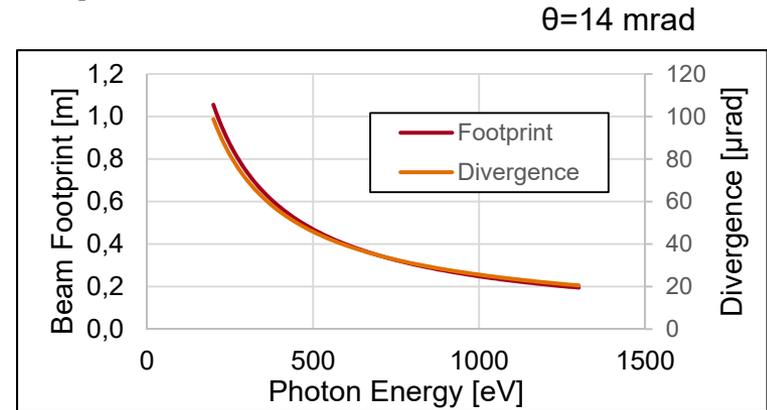
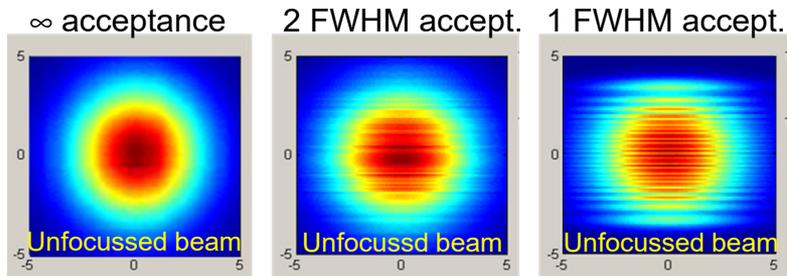
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- **Fully coherent photon beam \rightarrow Wavefront preservation**
 - **2*FWHM beam size needed**

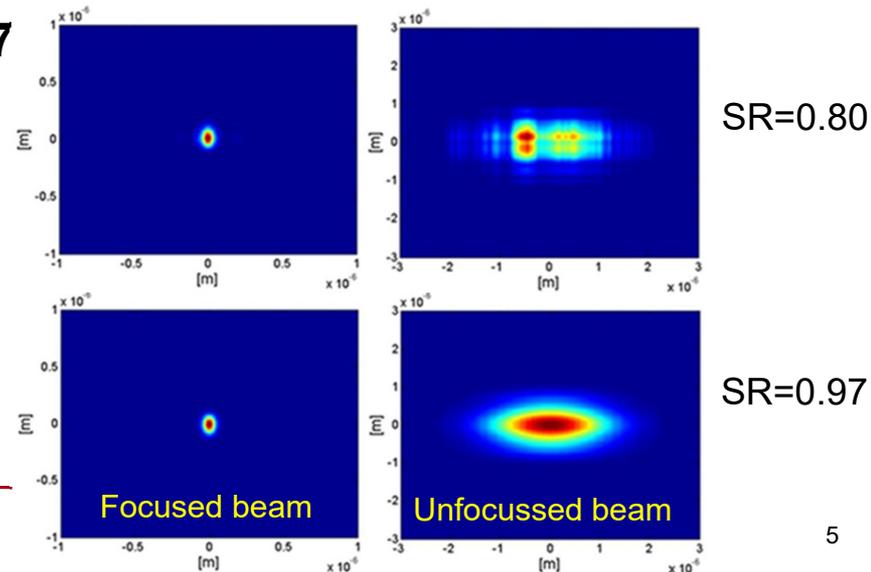
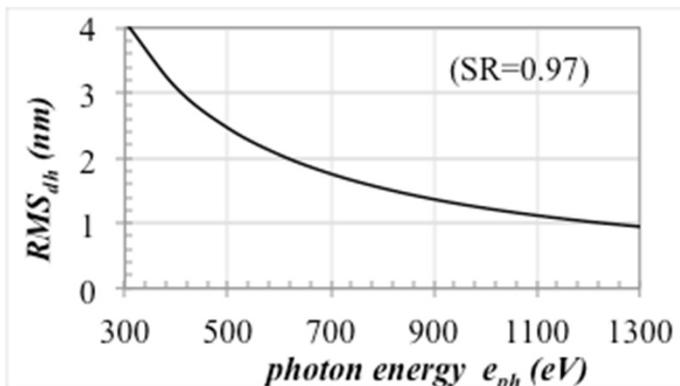


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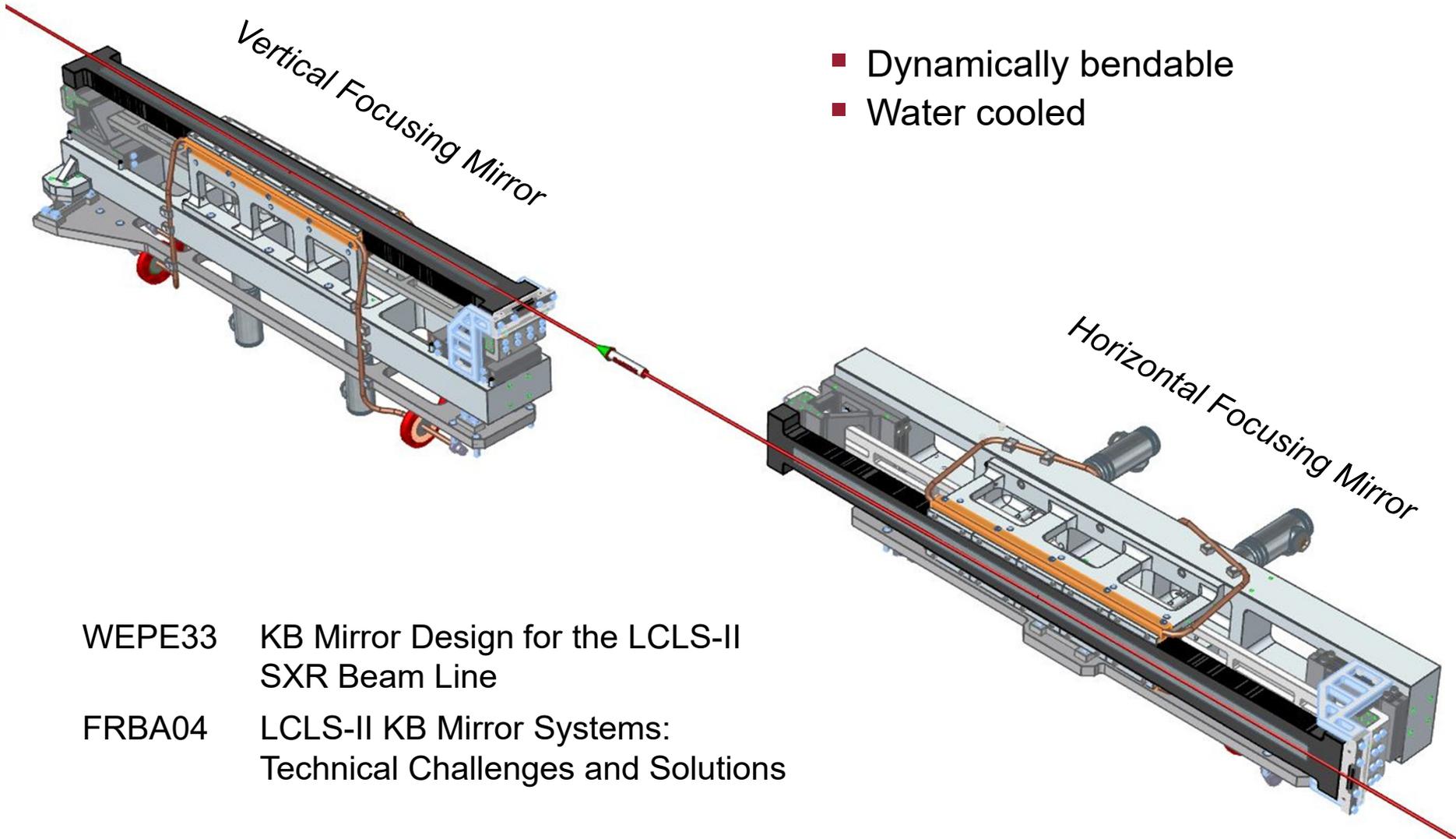
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- **Shape error requirement ($SR \geq 0.97$)**



LCLS-II K-B mirror system



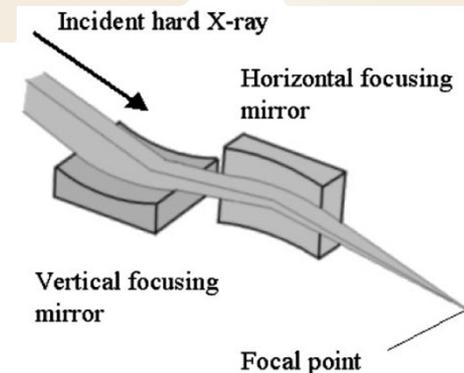
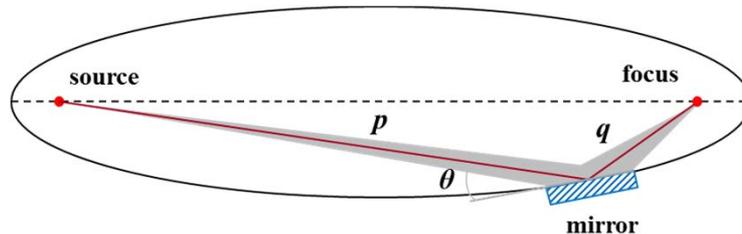
- Dynamically bendable
- Water cooled

WEPE33 KB Mirror Design for the LCLS-II
SXR Beam Line

FRBA04 LCLS-II KB Mirror Systems:
Technical Challenges and Solutions

➤ Kirkpatrick-Baez (K-B) mirror configuration

➤ Ellipsoidal shape



➤ Technical challenges

- Large Acceptance → Long mirror
- Variable Source & Focal Points → Bendable Mirror
- **Sub Nanometer Shape Error** → Limited Suppliers
- High Demagnification → Tight Bending (stress issues,...)
- Few tenth nrad residual bending error → **Variable Mirror Width**
- High Thermal Loads & Variable Footprint → **Innovated Cooling**
- **Minimize the coupling between the mirror Bending & Cooling**

- Large Acceptance → Long mirror
- Variable Source & Focal Points → Bendable Mirror
- Sub Nanometer Shape Error → Limited Suppliers
- High Demagnification → Tight Bending (stress issues,...)
- **Sub- μ rad residual bending error → Variable Mirror Width**
- High Thermal Loads & Variable Footprint → Innovated Cooling
- Minimize the coupling between the mirror Bending & Cooling

➤ Width profile defined by Bending Equation (BE)

$$w(x) = \frac{12M(x)}{Et^3} R(x)$$

$$z(x) = \frac{\sin \theta(p+q)}{4pq + (p-q)^2 \cos^2 \theta} \times \{2pq - 2[(pq)^2 - pqx^2 - xpq(p-q)\cos \theta]^{1/2} - x \cos \theta(p-q)\}$$

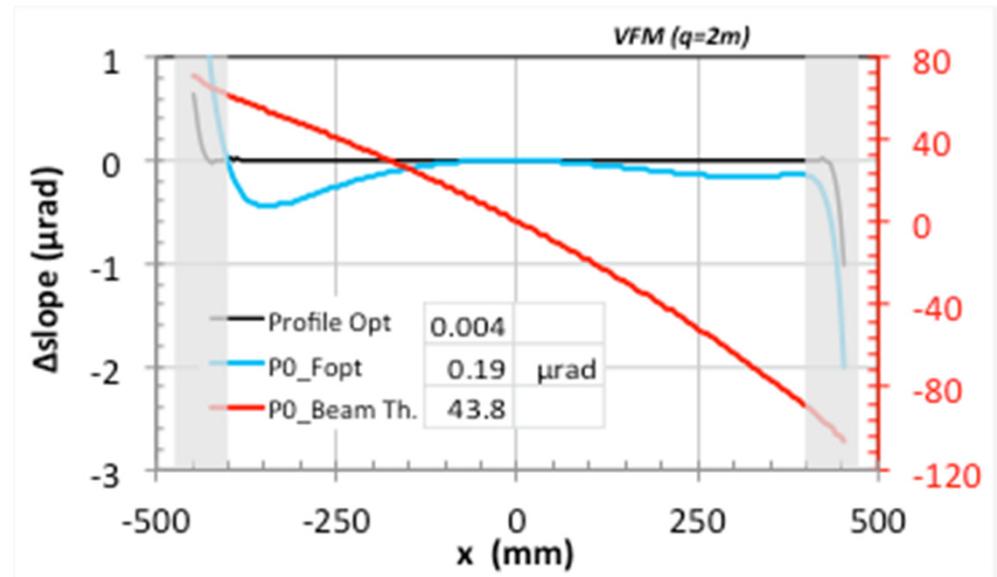
Residual Slope Error (RSE) :

$$\Delta \text{slope} = \text{slope} - \text{slope}_{\text{ellipse}}$$

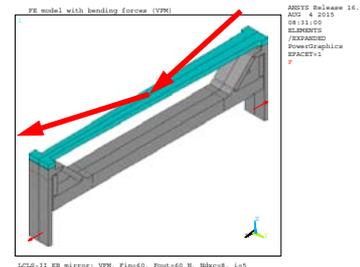
$$F_1 = F_2 = 60 \text{ N}$$

$$F_1 = 62.92 \text{ N}$$

$$F_2 = 63.58 \text{ N}$$

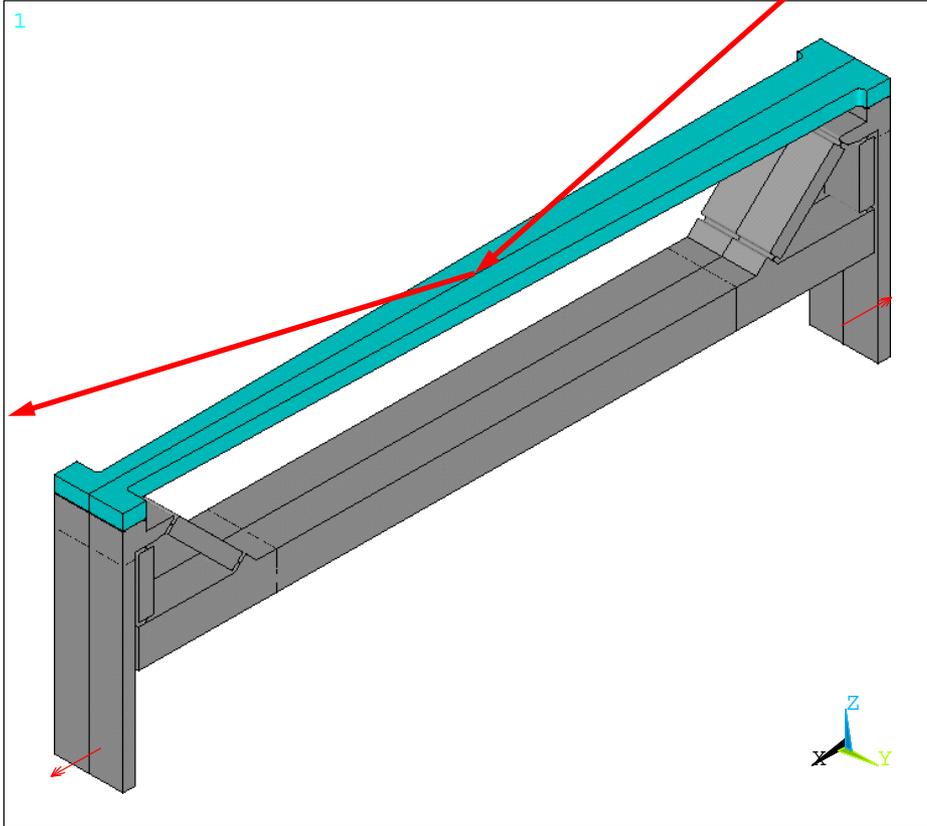


➤ Limitation of the analytical formula (Beam theory approximation)



Mirror profile optimization

FE model with bending forces (VFM)



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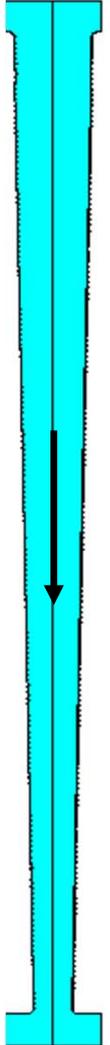
Silicon crystal orientation (low stress & bending force)

- Mirror optical surface // Si (110) plan
- Tangential-axis // [001]

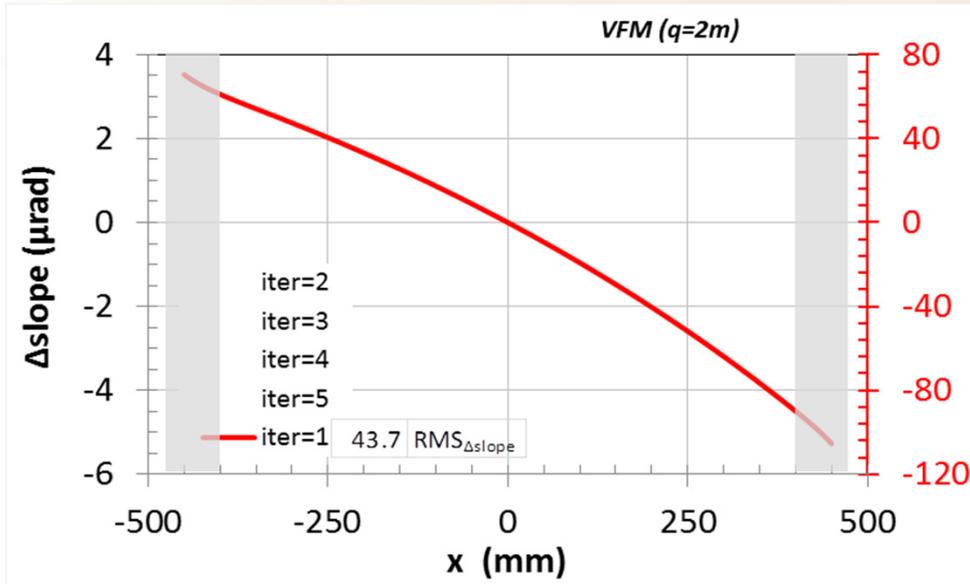
LCLS-II KB mirror: VFM, $F_{in}=60$, $F_{out}=60$ N, $Ndxc=8$, $i=5$

Optimized Mirror Profile (VFM, $q=2m$)

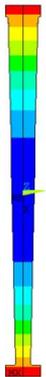
- L. Zhang, *SMEXOS* (2009), Grenoble, France
- L. Zhang et al., *AIP Conference Proceedings* 1234, 801 (2010); doi: 10.1063/1.3463335



Optimized Mirror Profile – bending performance

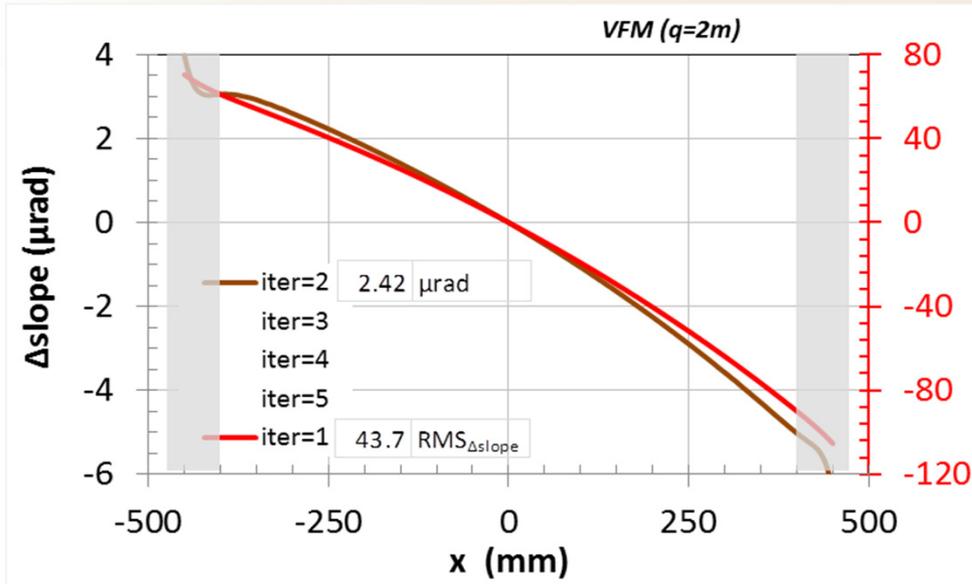


- **Following effects to be taken into account**
- Bender stiffness (not negligible)
 - Anticlastic-bending effects
 - Anisotropy of the Si crystal
 - Geometrical non-linear effects in the simulation

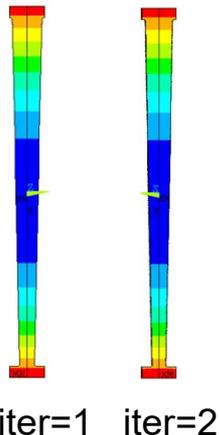


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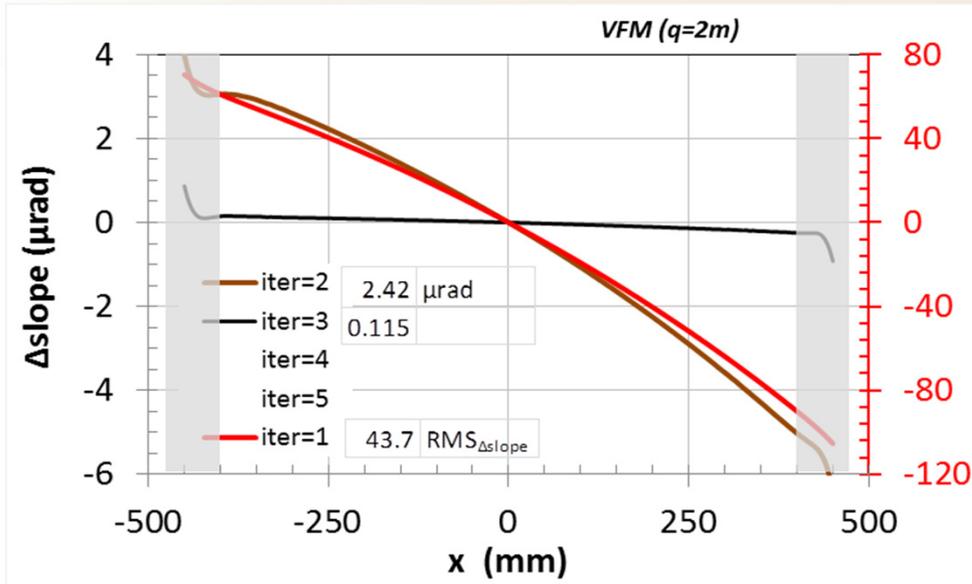
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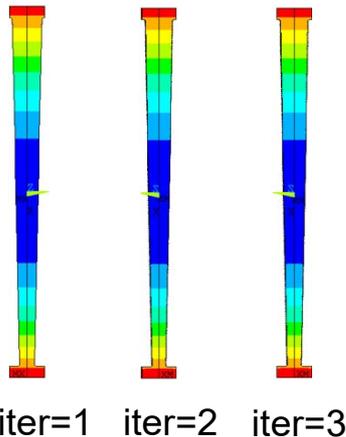
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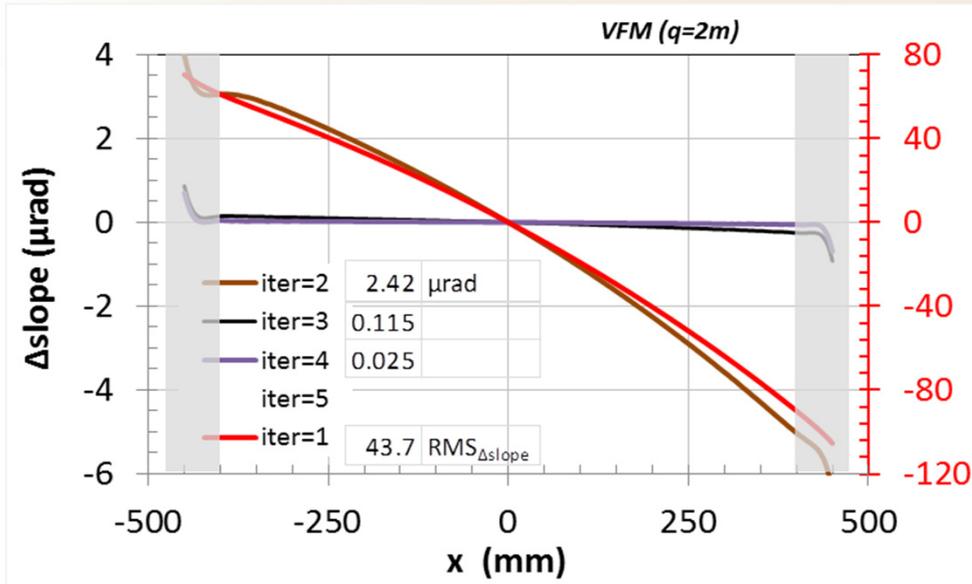
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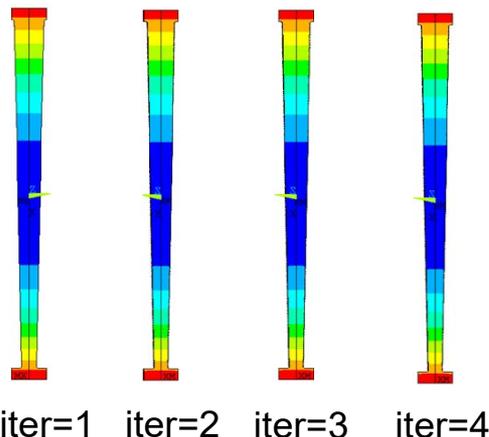
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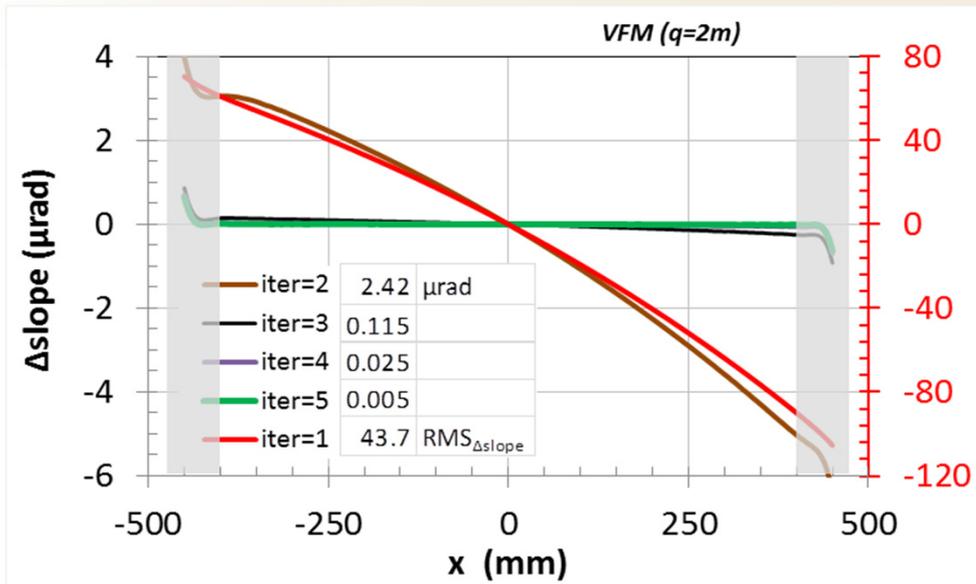
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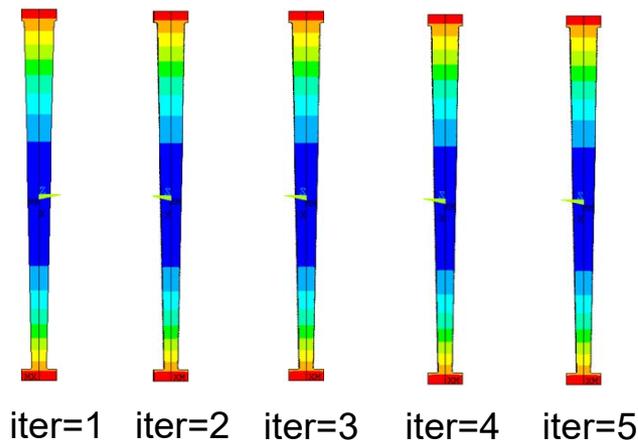
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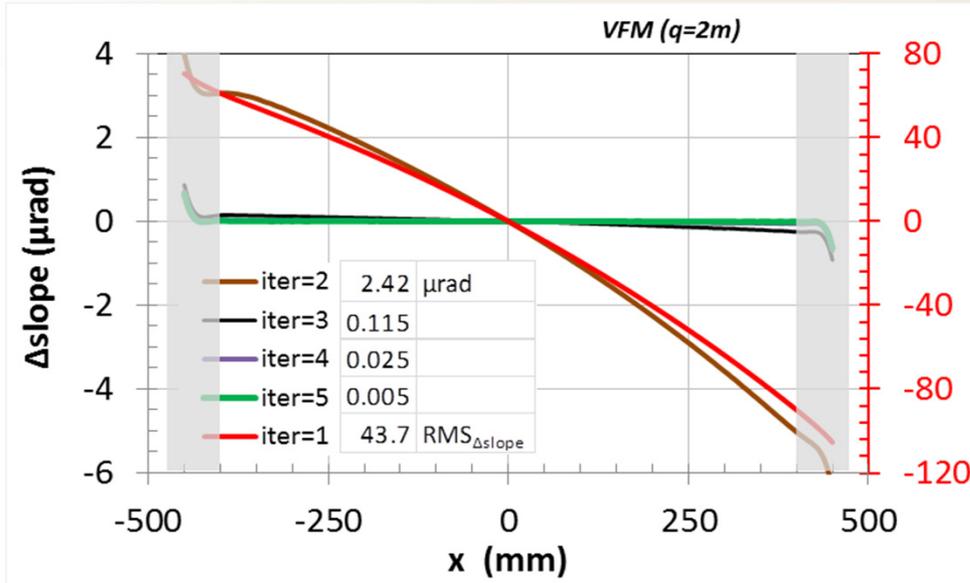
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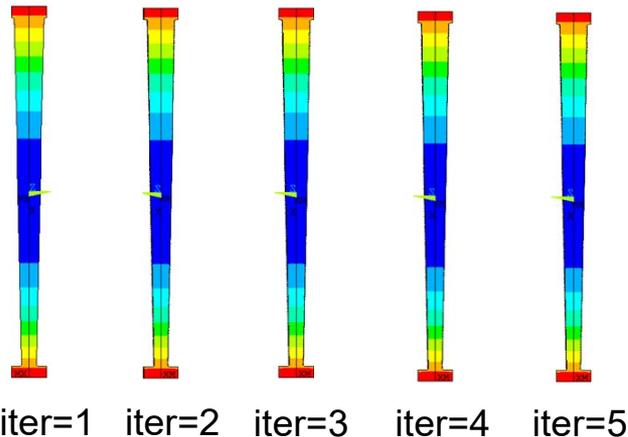
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Optimized Mirror Profile – bending performance



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$RMS_{\Delta slope}$ (reduction factor : $\sim 10^4$)

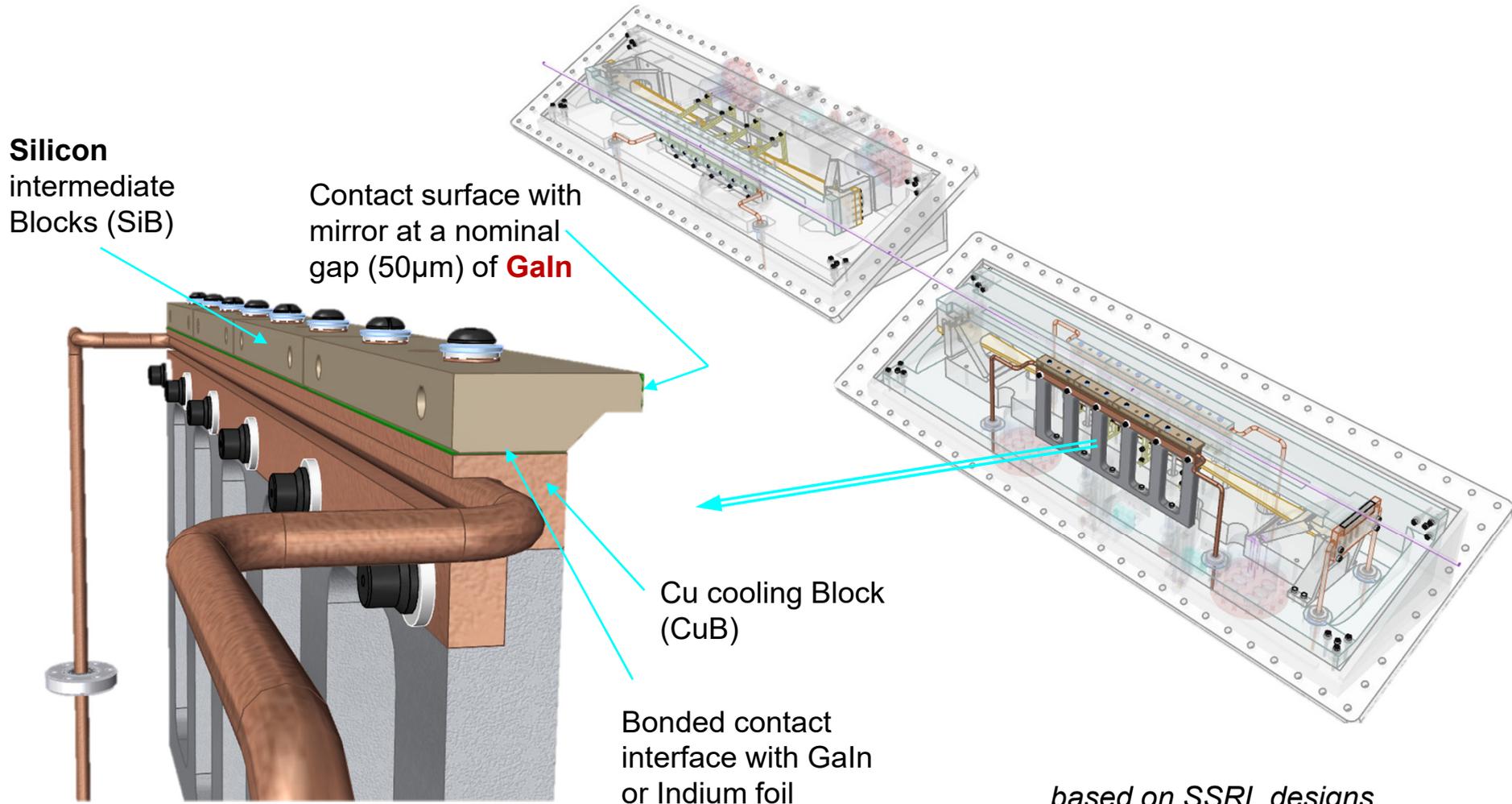
- **43.7 μ rad** (with the profile defined by BE)
- **0.005 μ rad** (with the optimized profile by FEA)

$$RMS_{\Delta slope-opt} / slope_{PV-ellipse} \sim 2 \cdot 10^{-6}$$

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- Minimize the coupling between the mirror Bending & Cooling

Final cooling design

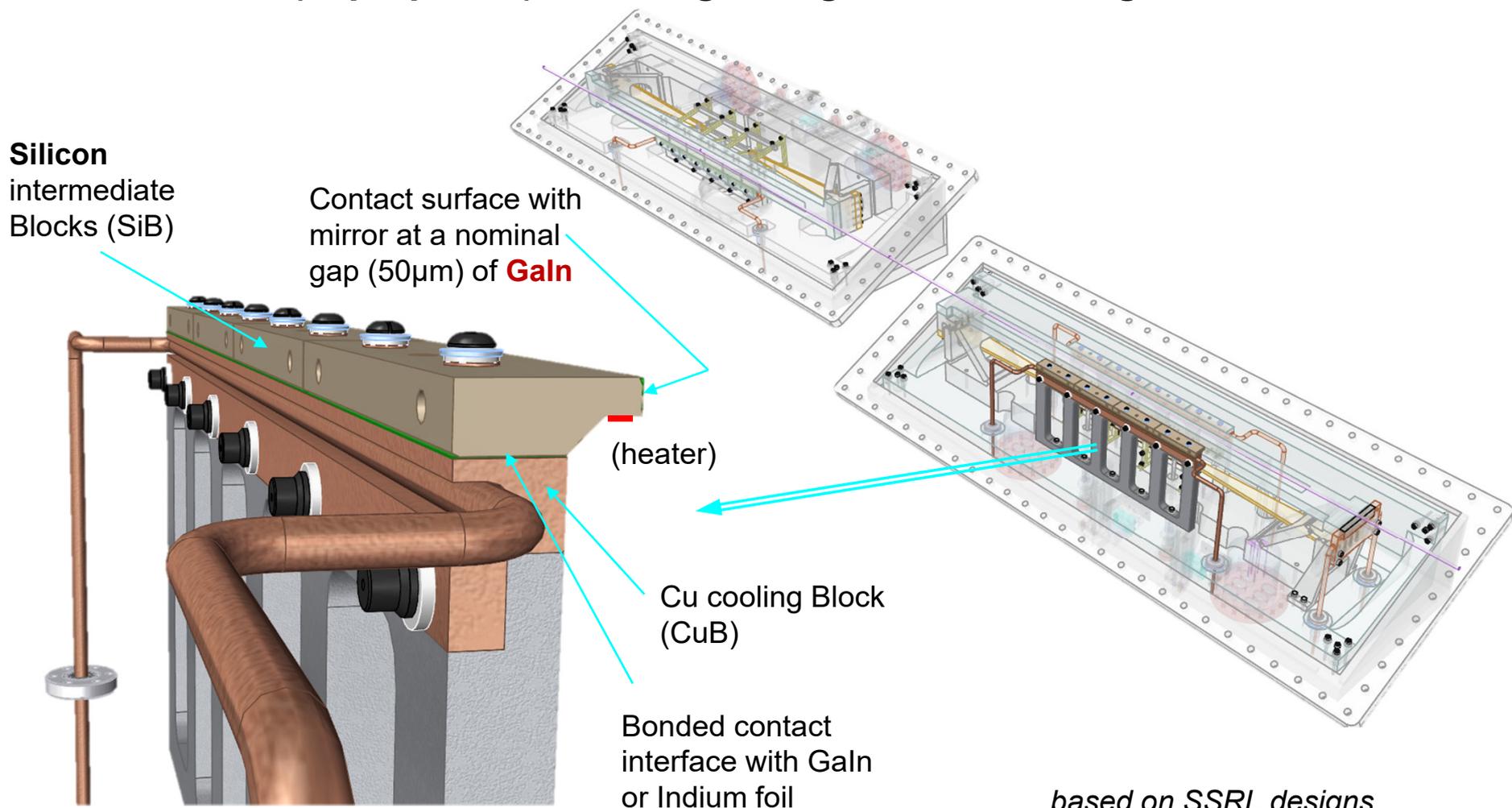
- Contact (Top-up-side), one single length water cooling



based on SSRL designs for contact cooled mirror

Final cooling design

- Contact (Top-up-side), one single length water cooling



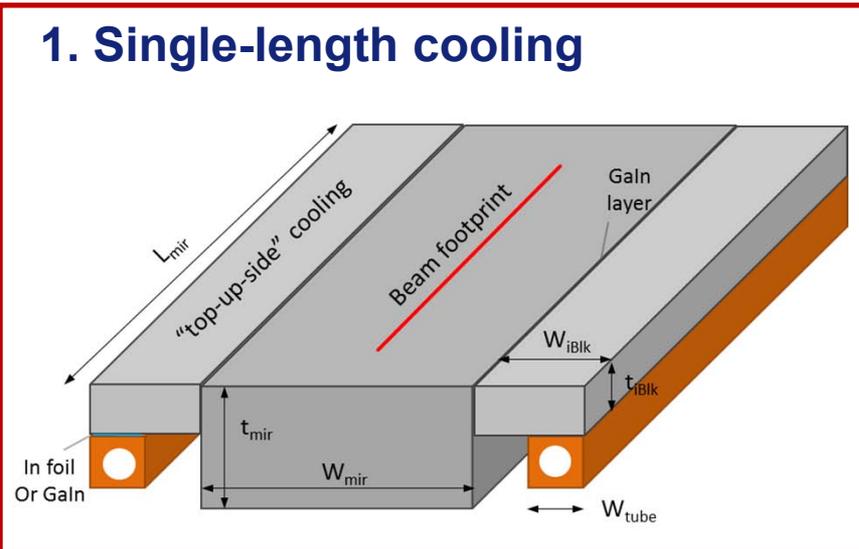
based on SSRL designs for contact cooled mirror

Mirror cooling design – 3 schemes

➤ Top-up-side water cooling

- L. Zhang et al. *J. Syn. Rad.* (2015). 22,1170–1181
- L. Zhang et al. , *SRI 2015 Conference*

1. Single-length cooling

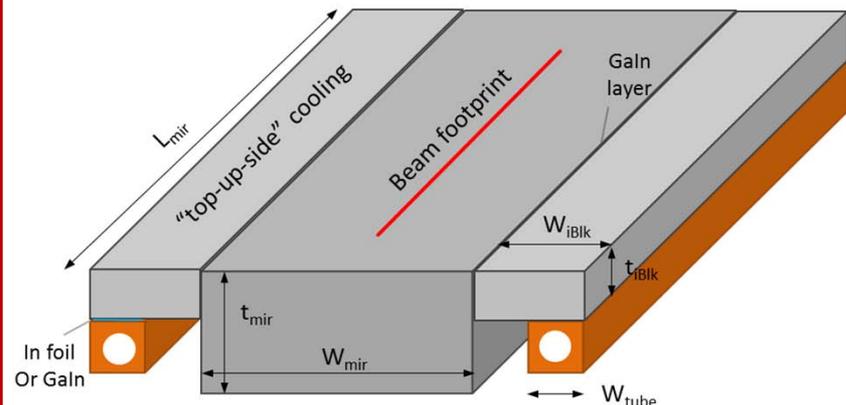


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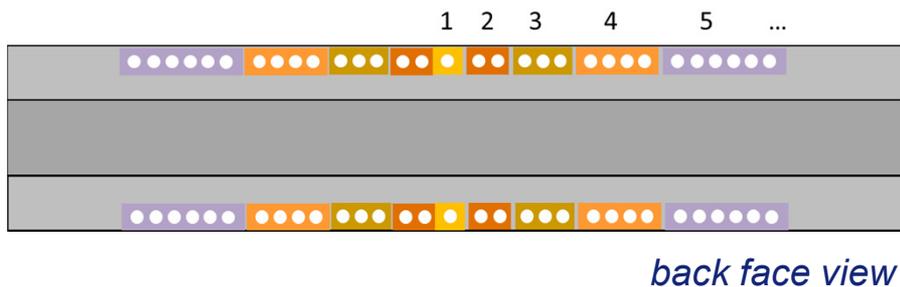
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1. Single-length cooling



2. Variable-length cooling

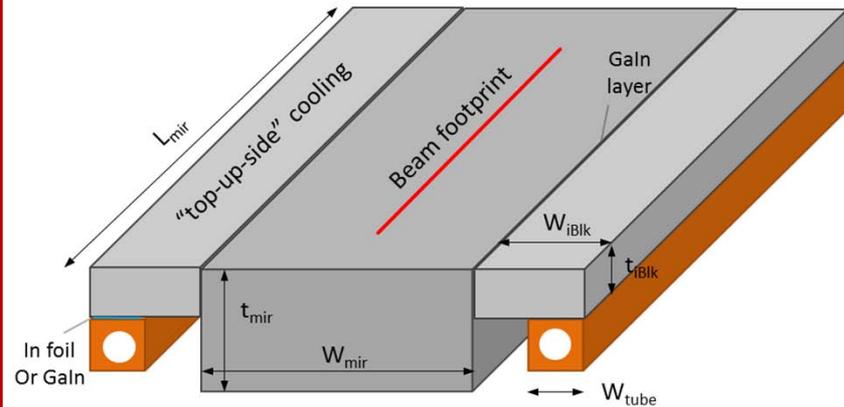


Mirror cooling design – 3 schemes

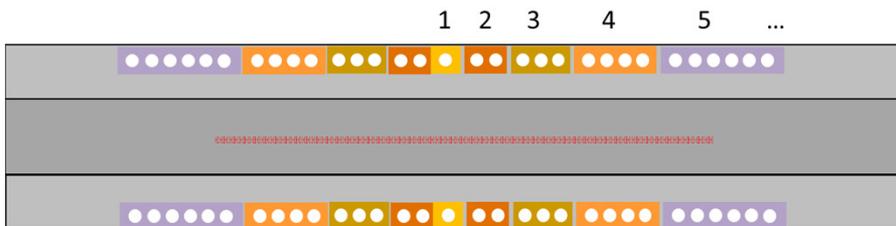
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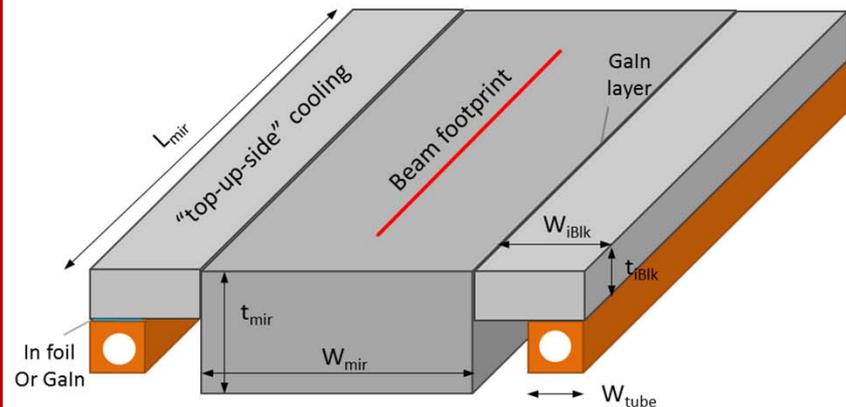
back face view

Mirror cooling design – 3 schemes

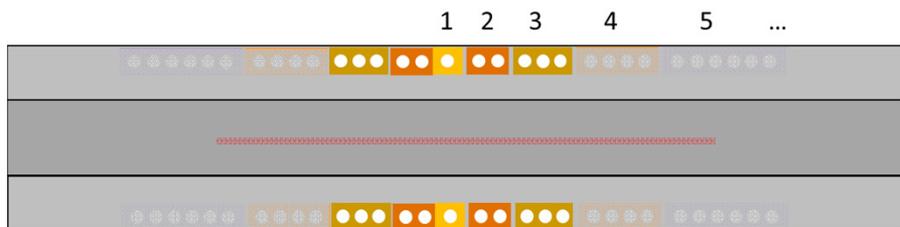
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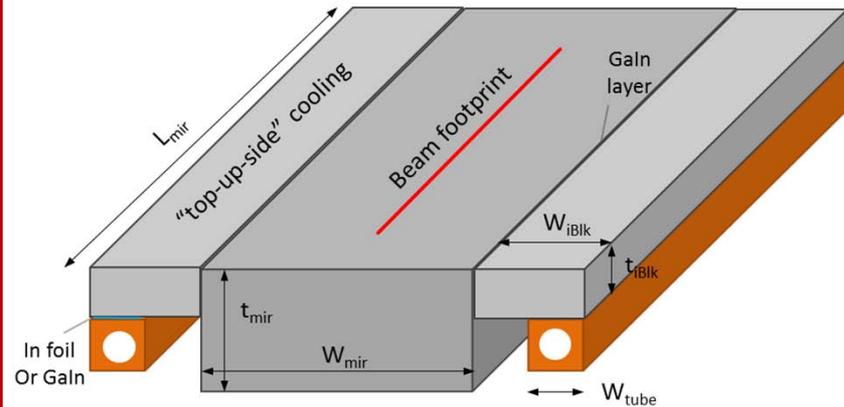
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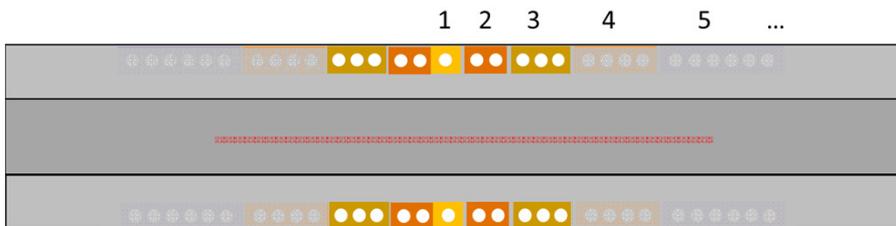
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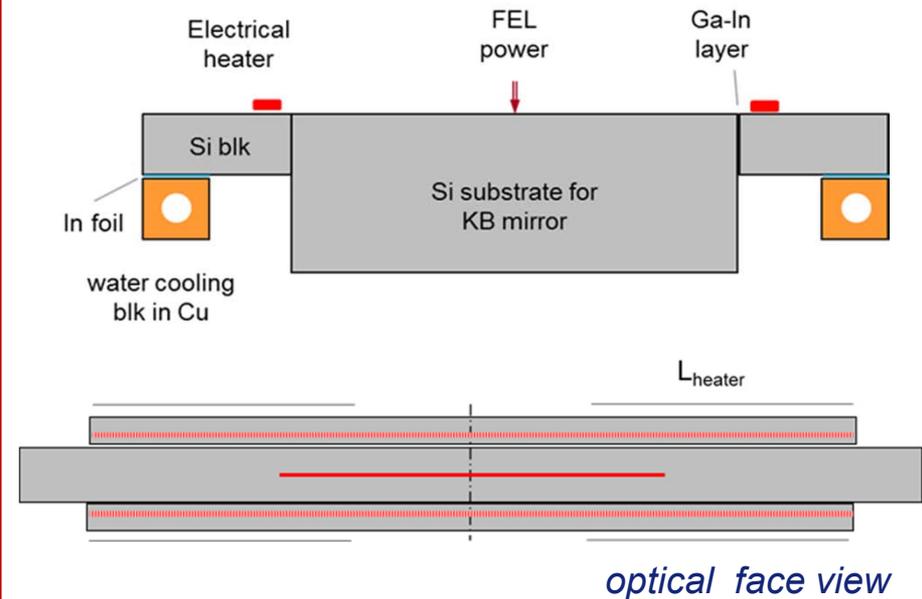


2. Variable-length cooling



back face view

3. Electric heater + Single-length cooling

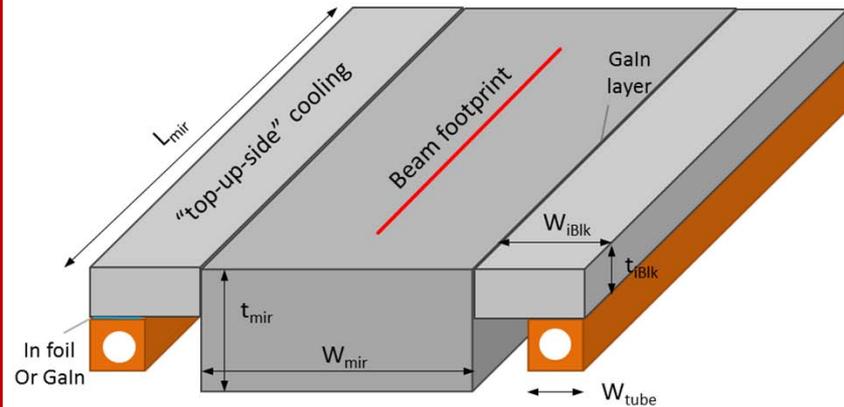


Mirror cooling design – 3 schemes

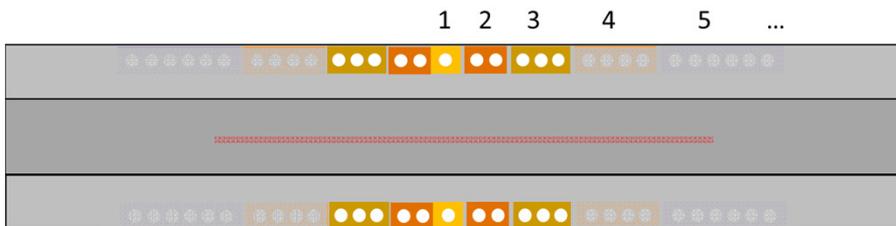
➤ Top-up-side water cooling

- L. Zhang et al. *J. Syn. Rad.* (2015). 22,1170–1181
- L. Zhang et al. , *SRI 2015 Conference*

1. Single-length cooling

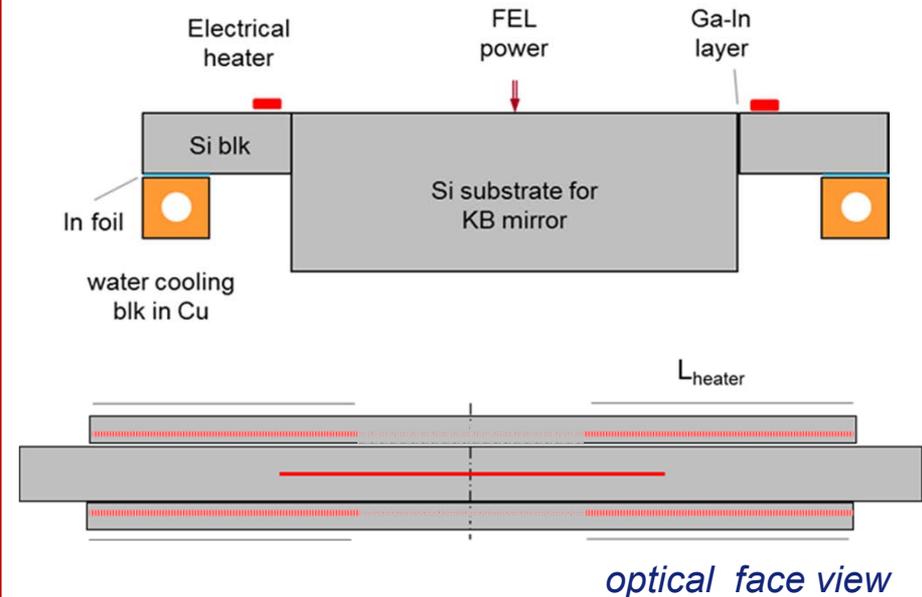


2. Variable-length cooling



back face view

3. Electric heater + Single-length cooling

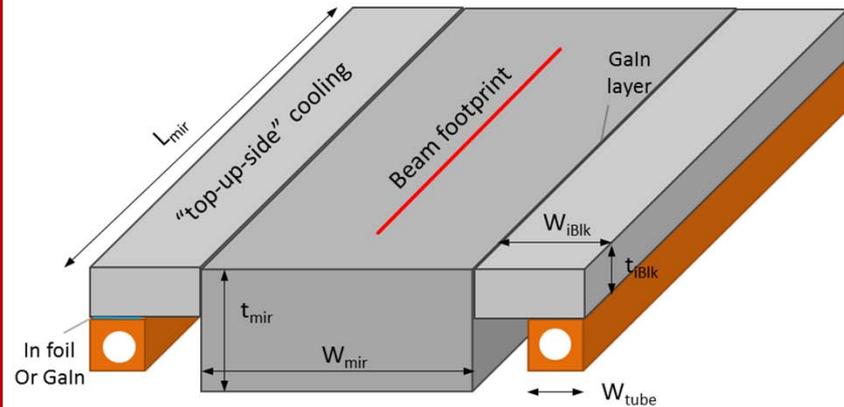


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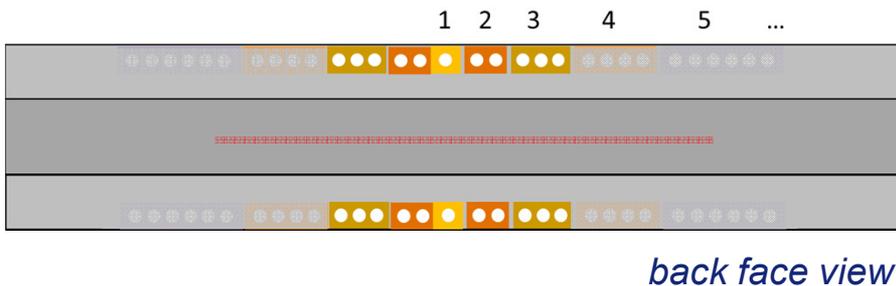
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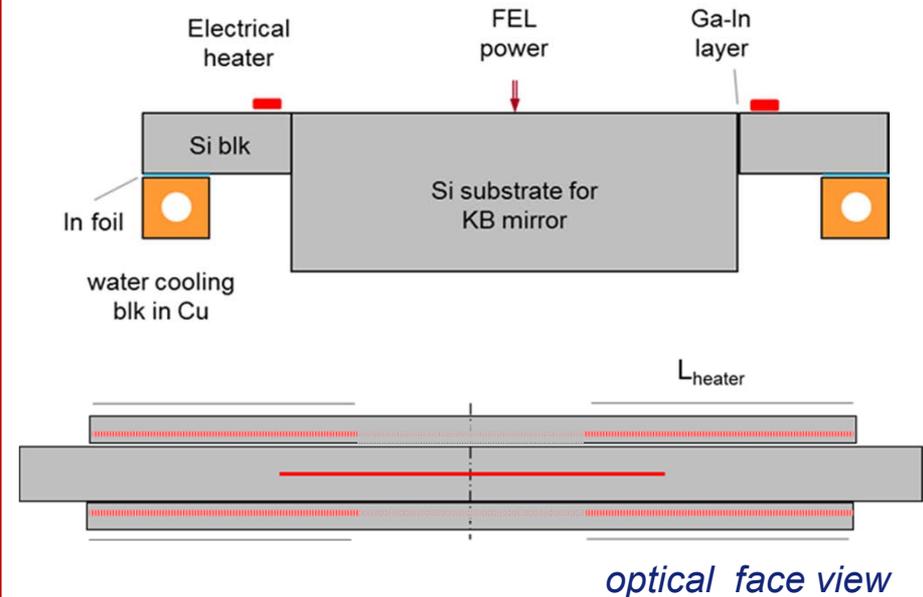
1. Single-length cooling



2. Variable-length cooling

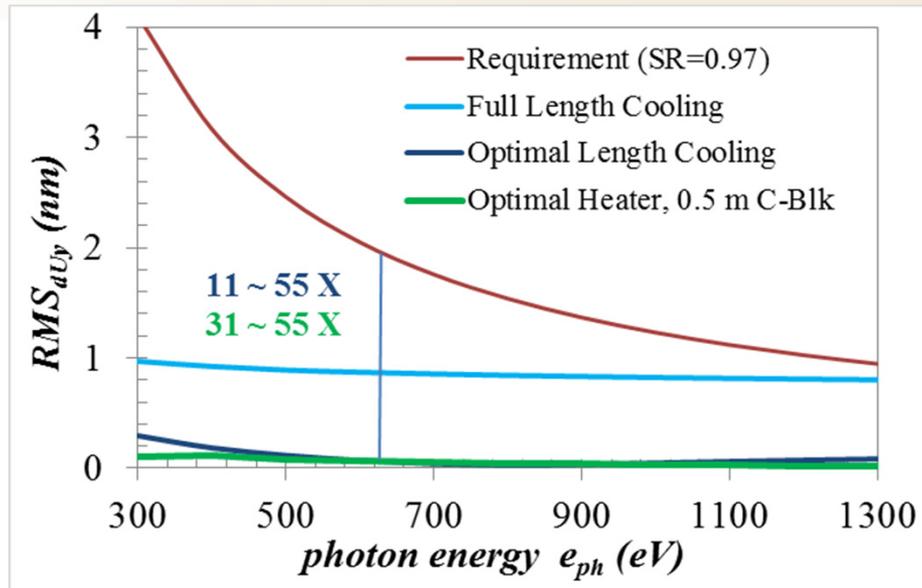


3. Electric heater + Single-length cooling



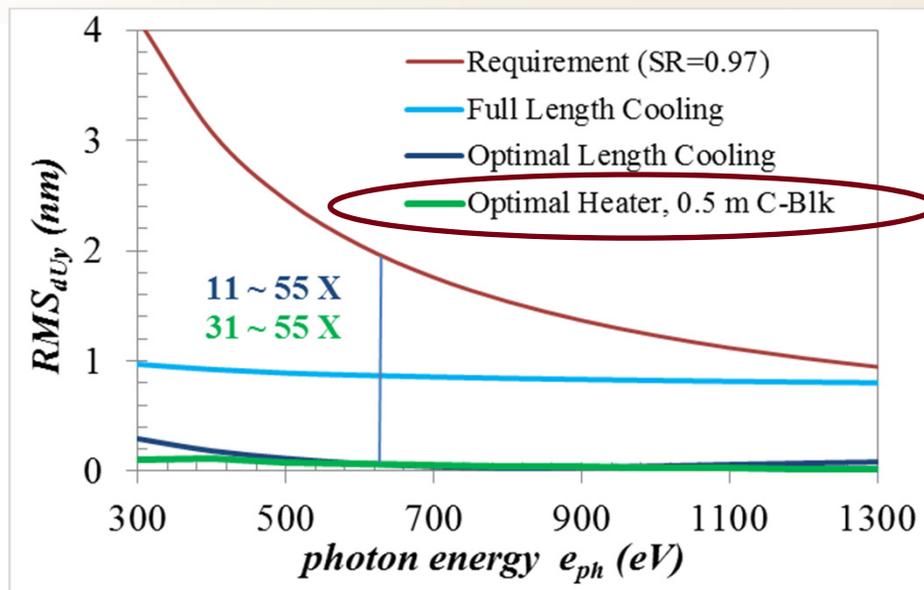
$$RMS_{thermal} := f(L_{heater}, Pa_{heater}, x)$$

Mirror cooling design – performance



➤ LCLS-II SXR K-B mirrors

- For 20 W of XFEL beam power, full-length (top-up-side) cooling is sufficient
- For 200 W of XFEL beam power, optimal, variable-length cooling is needed



Resistive Element Adjustable Length

REAL Cooled Optics

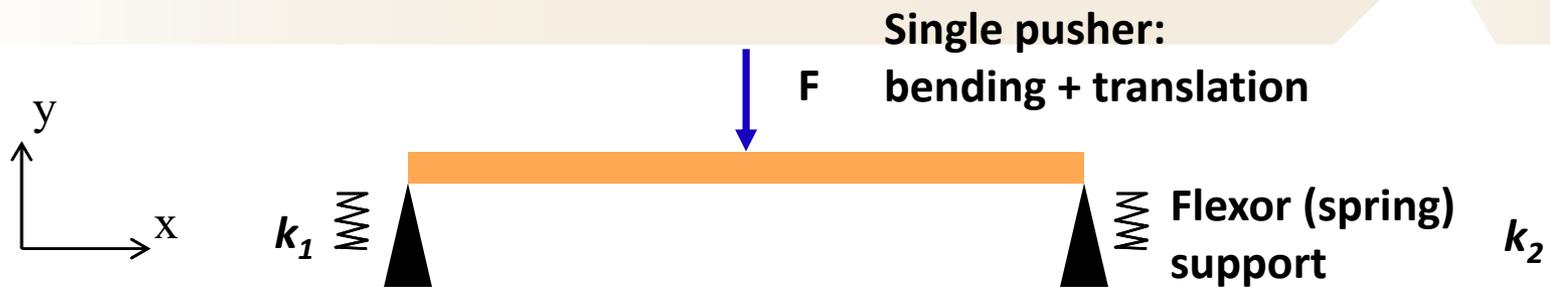
(DoE funded R&D project, 2017-2018 FY)

➤ LCLS-II SXR K-B mirrors

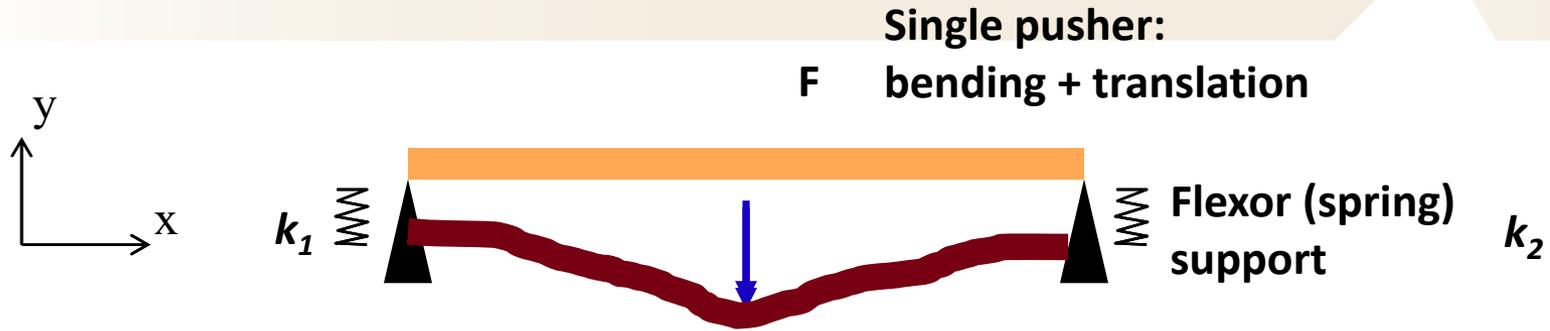
- For 20 W of XFEL beam power, full-length (top-up-side) cooling is sufficient
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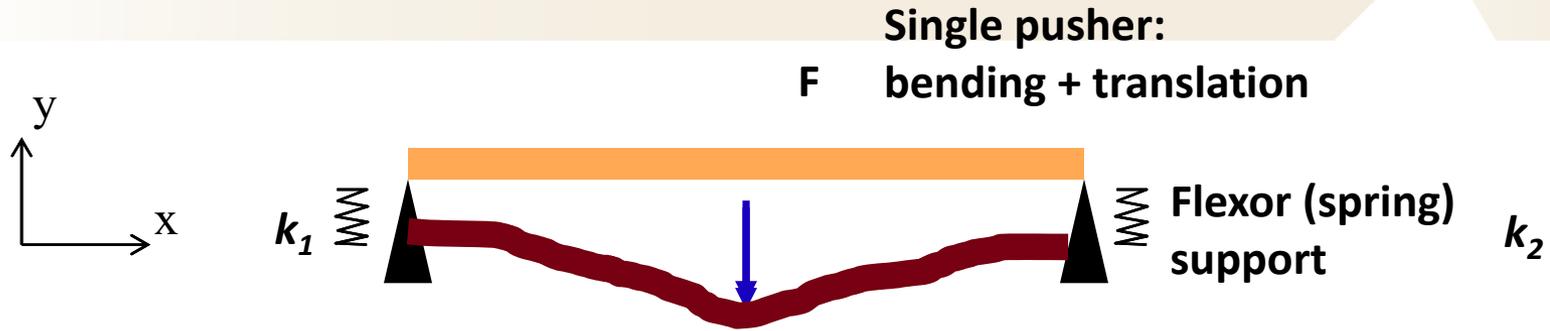
- Large Acceptance → Long mirror
- Variable Source & Focal Points → Bendable Mirror
- Sub Nanometer Shape Error → Limited Suppliers
- High Demagnification → Tight Bending (stress issues,...)
- Sub- μ rad residual bending error → Variable Mirror Width
- High Thermal Loads & Variable Footprint → Innovated Cooling
- Minimize the **coupling between the mirror Bending & Cooling**
 - Minimization of mechanical constraint effects of Eutectic GaIn as thermal interface (*presented WEBA02*)
 - **Bend cooling blocks (design optimization practice)**

Cooling blocks bending and translation



Cooling blocks bending and translation





➤ Cooling block bent shape: $y_{CB}(x, F, k_1, k_2)$

➤ Mirror shape (ideal ellipse): $y_{mir}(x, q)$

➤ For given value of F, k_1, k_2, q

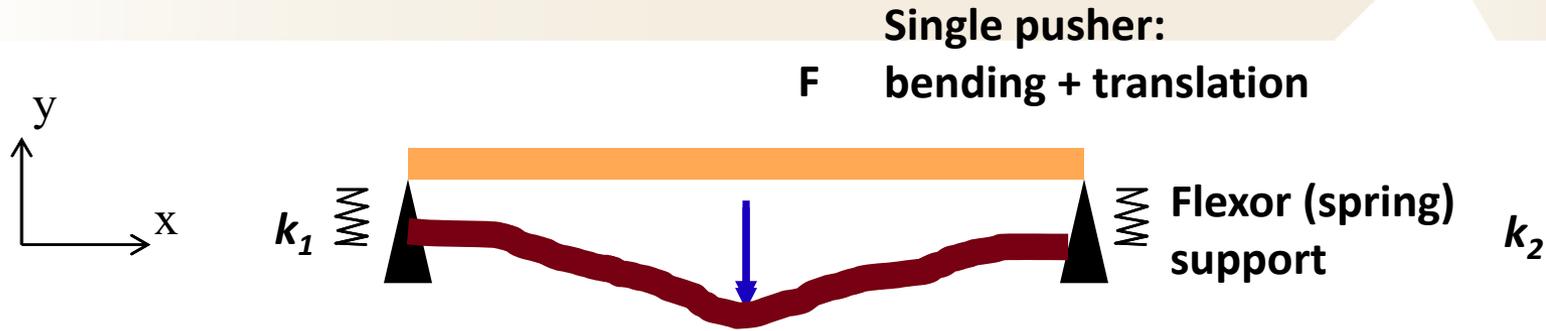
▪ Minimization :

$$dU_y(x) = y_{CB}(x) - y_{mir}(x)$$

▪ $dU_y(x) \rightarrow RMS, d_{pv}$

$$z(x) = \frac{\sin \theta(p+q)}{4pq + (p-q)^2 \cos^2 \theta} \times \{2pq - 2[(pq)^2 - pqx^2 - xpq(p-q) \cos \theta]^{1/2} - x \cos \theta(p-q)\}$$

$$d_{pv} < 5 \mu m$$



➤ Cooling block bent shape: $y_{CB}(x, F, k_1, k_2)$

➤ Mirror shape (ideal ellipse): $y_{mir}(x, q)$

$$z(x) = \frac{\sin \theta(p+q)}{4pq + (p-q)^2 \cos^2 \theta} \times \{2pq - 2[(pq)^2 - pqx^2 - xpq(p-q) \cos \theta]^{1/2} - x \cos \theta(p-q)\}$$

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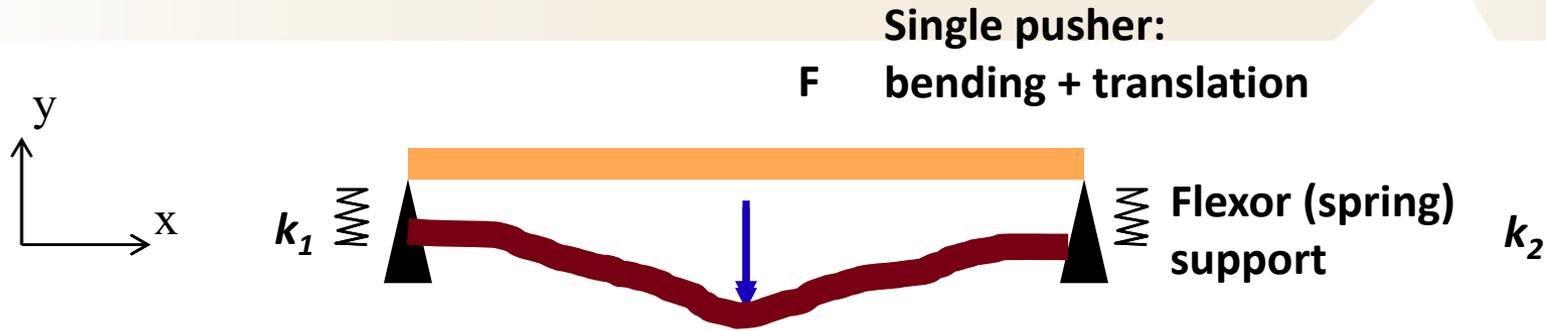
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➤ Objective function: $f(F, k_1, k_2, q)$



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➤ For given value of F, k_1, k_2, q

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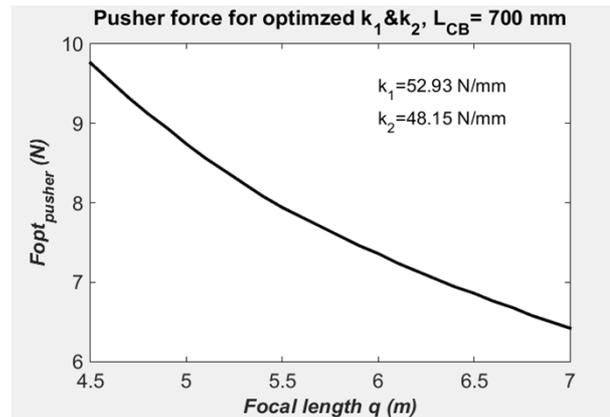
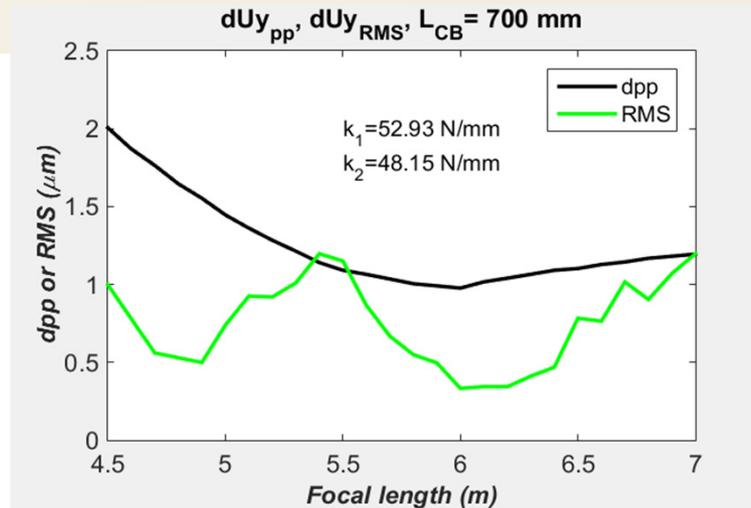
$$dU_y(x) = y_{CB}(x) - y_{mir}(x)$$

▪ $dU_y(x) \rightarrow RMS, d_{pv}$

$$d_{pv} < 5 \mu m$$

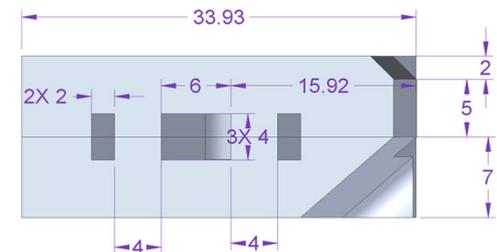
➤ Objective function: $f(F, k_1, k_2, q) = RMS * d_{pv}$

Cooling blocks: single pusher + elastic supports

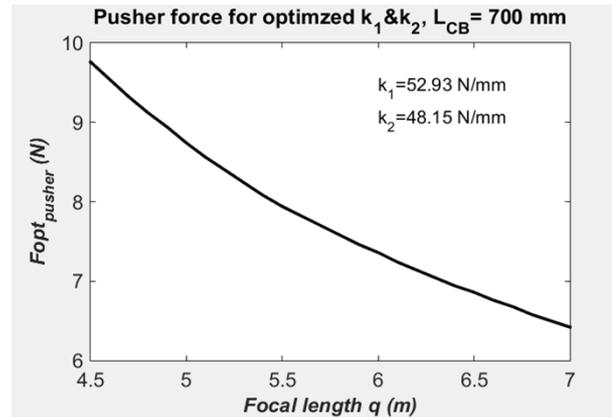
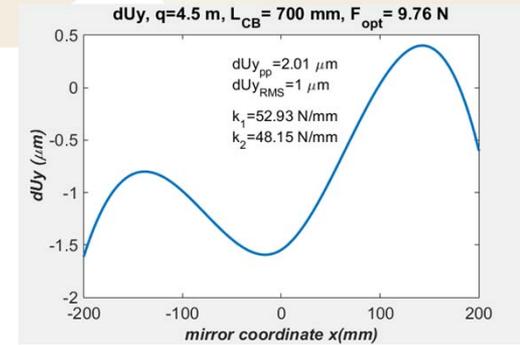
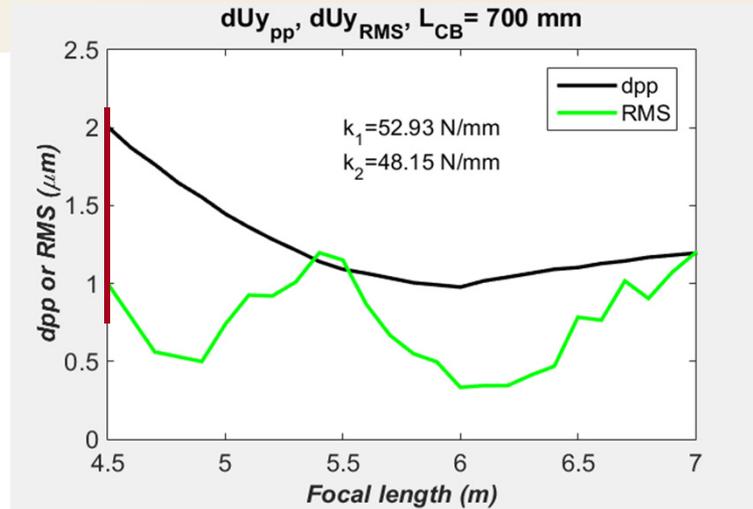
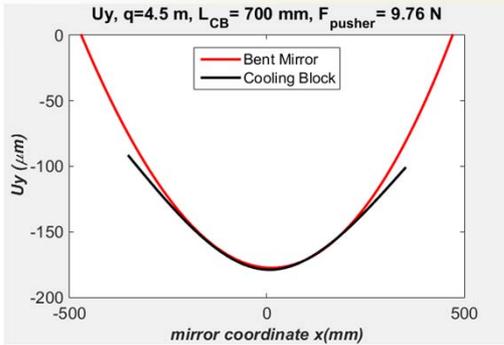


- **1 pusher: F**
- 2 flexor supports: k_1, k_2**
 - $F : 6 \sim 10 \text{ N}$
 - $k_1 = 52.93 \text{ N/mm}, k_2 = 48.15 \text{ N/mm}$

Uniform cross section

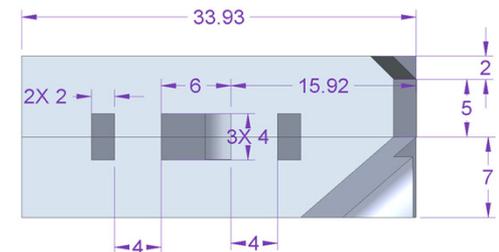


Cooling blocks: single pusher + elastic supports

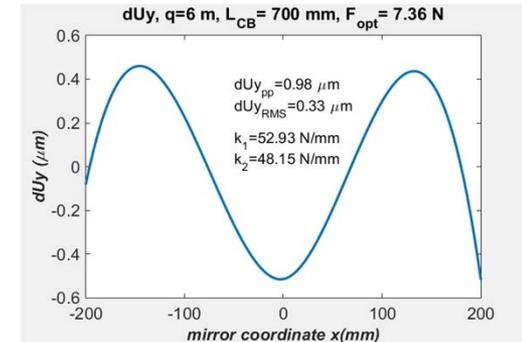
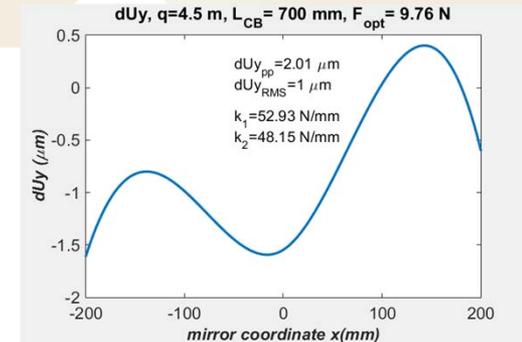
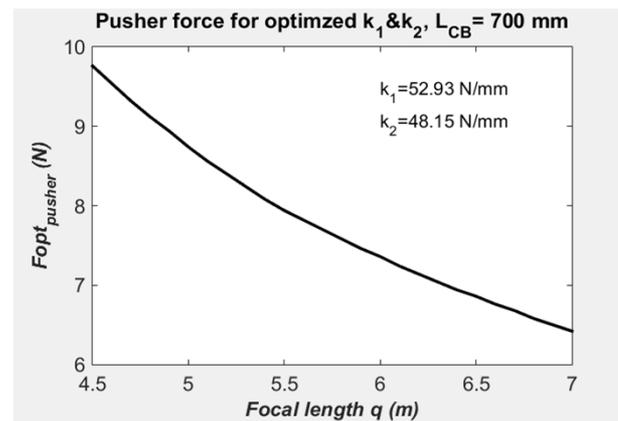
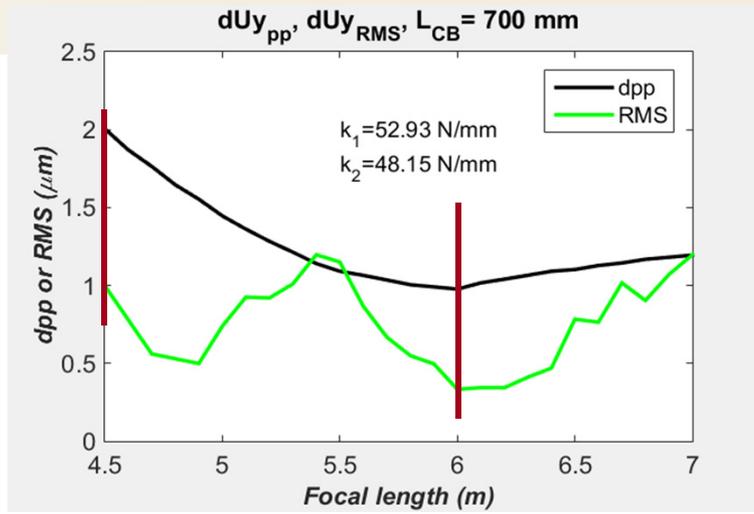
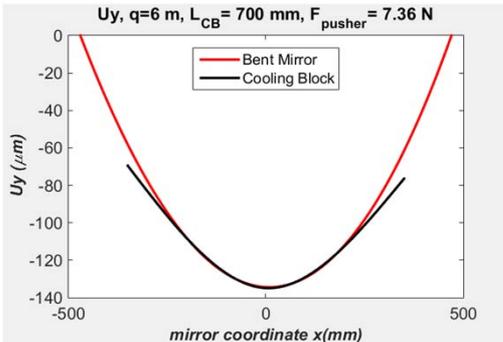
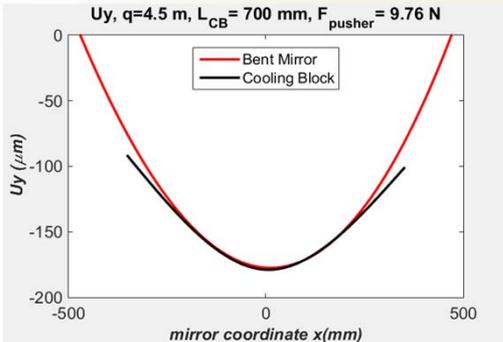


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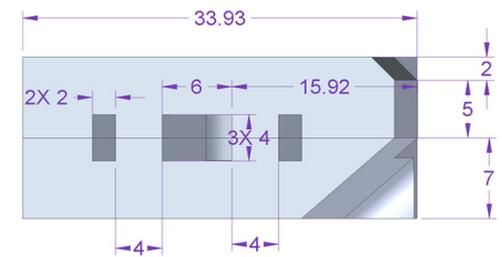


Cooling blocks: single pusher + elastic supports



- **1 pusher: F**
- 2 flexor supports: k_1, k_2**
 - $F : 6 \sim 10 \text{ N}$
 - $k_1 = 52.93 \text{ N/mm}, k_2 = 48.15 \text{ N/mm}$

Uniform cross section

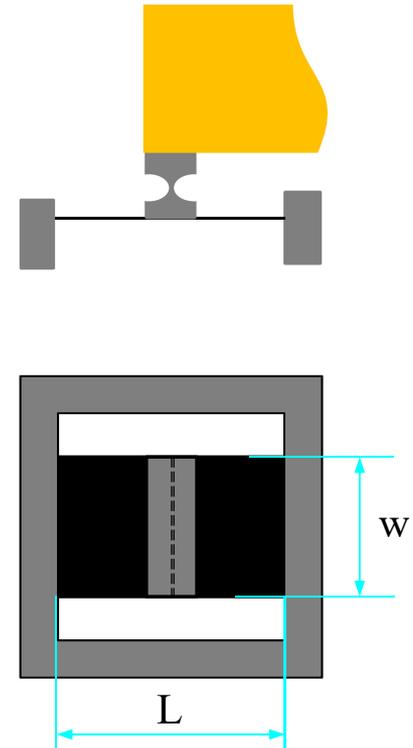


➤ Flexor Supports

- Stainless steel thin blade

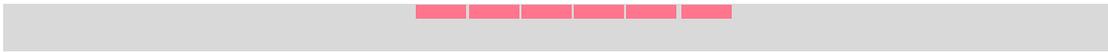
$$k = \frac{192EI}{L^3} = 16Ew\left(\frac{t}{L}\right)^3$$

k_N (N/mm)	k_1	k_2	$\Delta\%$	Δ_0	Δ_{req}
target	52.93	48.15			
			1%	mm	mm
E (N/mm ²)	2.00E+05	2.00E+05			
t (mm)	0.2	0.2	0.3%	0.0006	±0.01
L (mm)	20	20	0.3%	0.06	±0.05
w (mm)	16.54	15.05	1%	0.150	±0.1

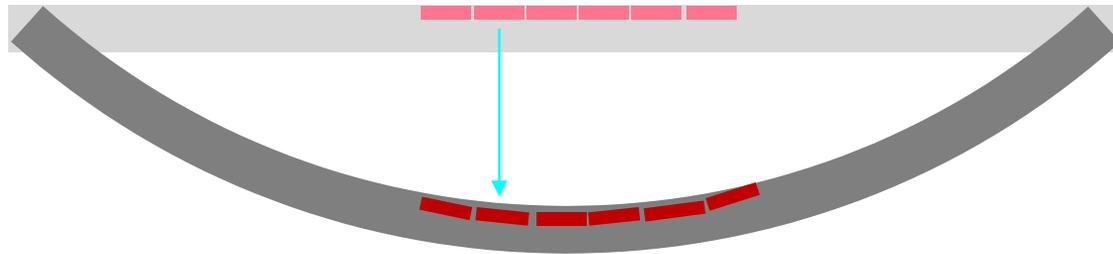


- Width w (add 10% to initial values) can be adjusted (re-machined) to fit exact k-values
- 1% accuracy for the values of k_1, k_2 should be achievable

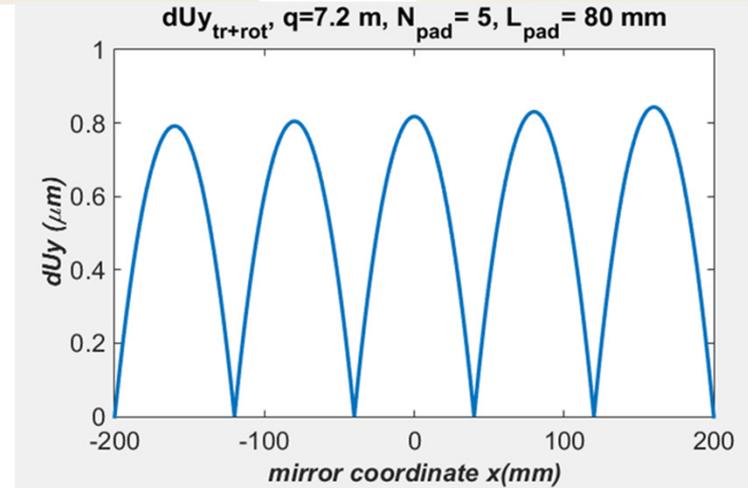
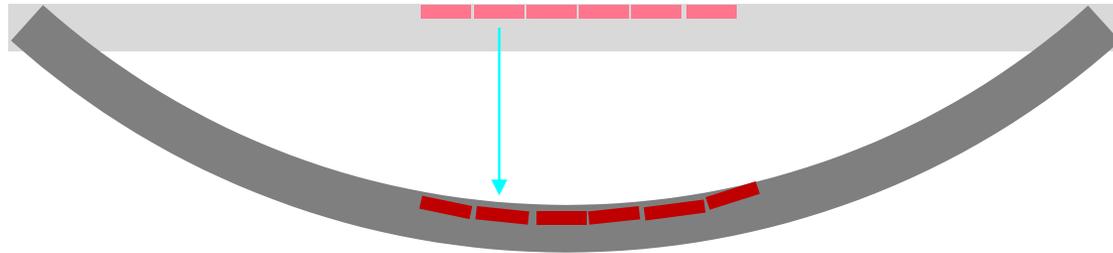
Cooling blocks: translation + rotation



Cooling blocks: translation + rotation

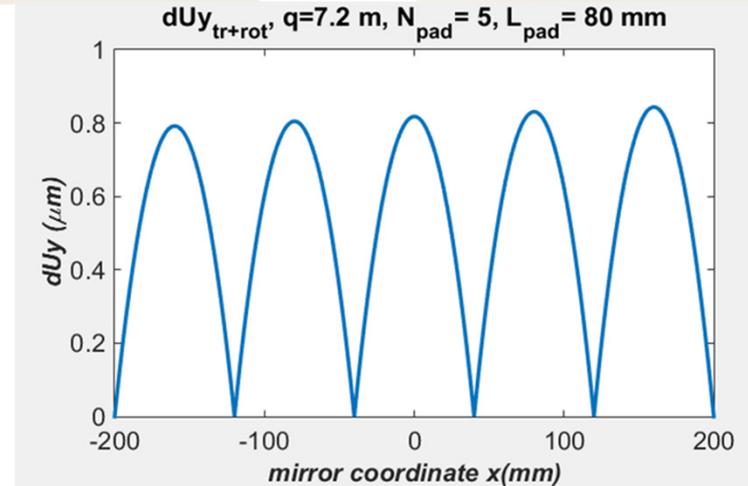
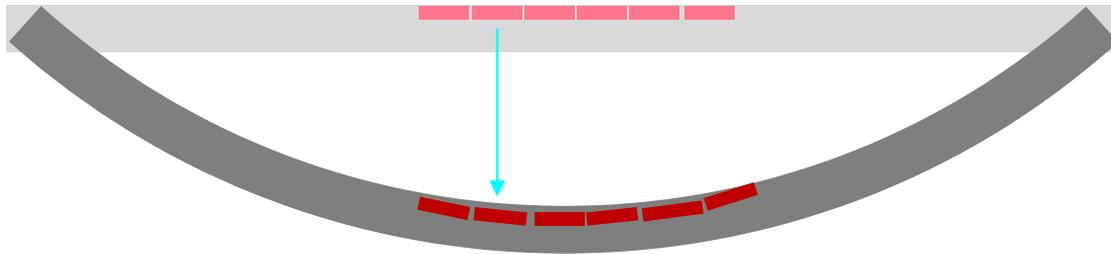


Cooling blocks: translation + rotation

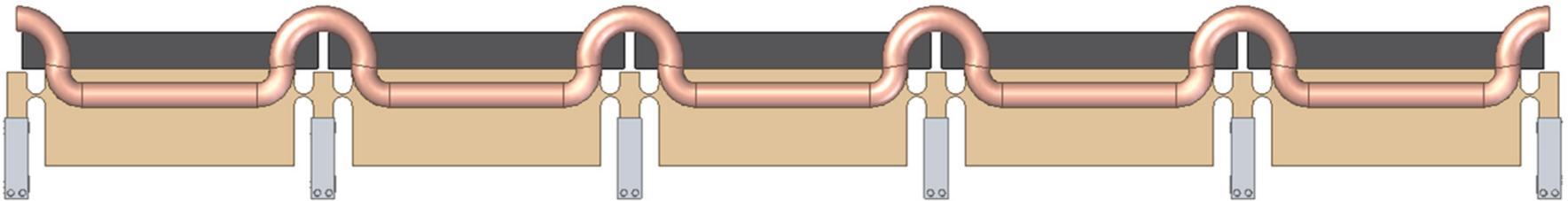


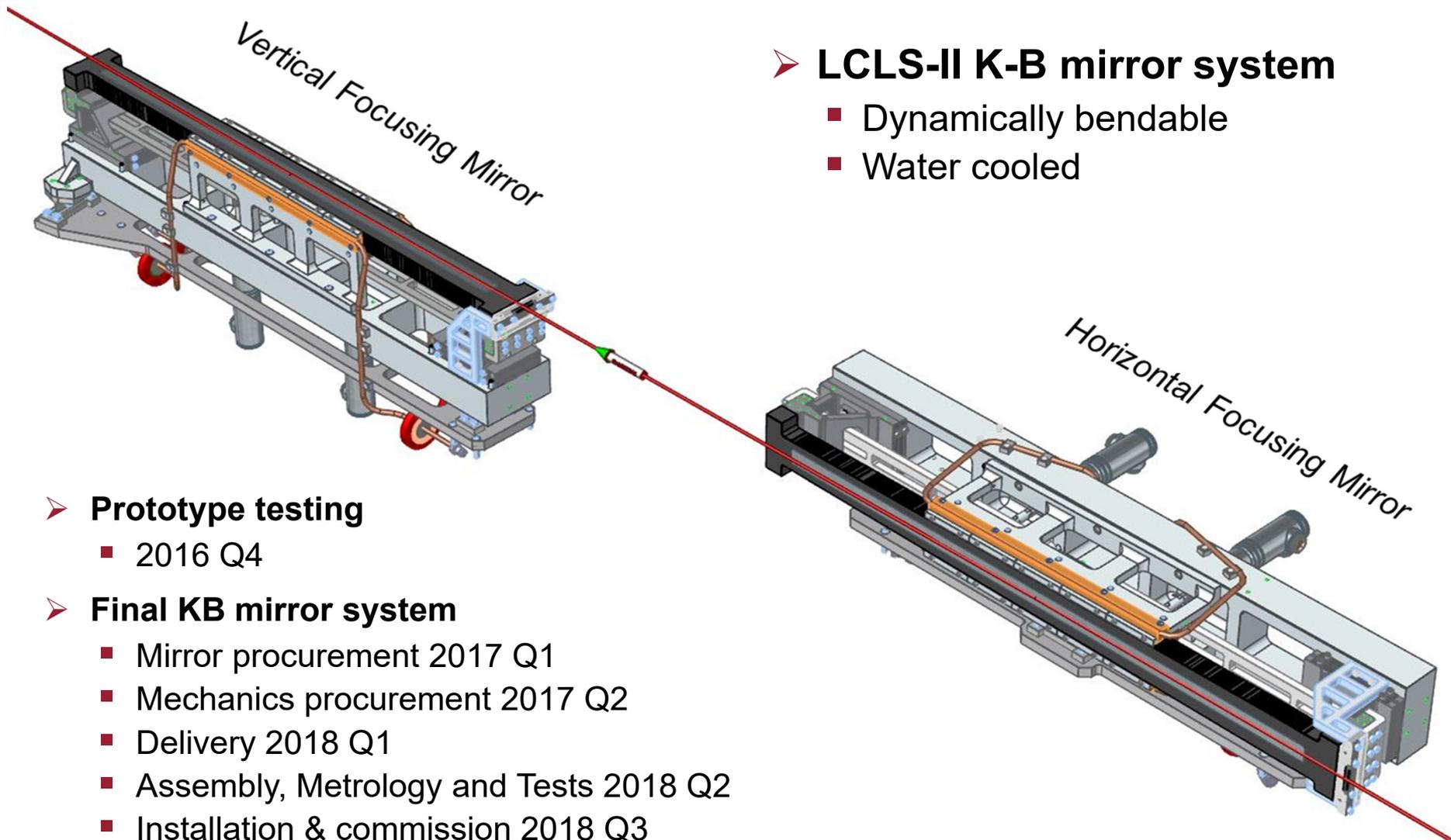
$$dU_y(x) = y_{CB}(x) - y_{mir}(x)$$

Cooling blocks: translation + rotation



$$dU_y(x) = y_{CB}(x) - y_{mir}(x)$$





➤ LCLS-II K-B mirror system

- Dynamically bendable
- Water cooled

➤ Prototype testing

- 2016 Q4

➤ Final KB mirror system

- Mirror procurement 2017 Q1
- Mechanics procurement 2017 Q2
- Delivery 2018 Q1
- Assembly, Metrology and Tests 2018 Q2
- Installation & commission 2018 Q3

Acknowledgement

- **E. Anderssen** LBNL
- **R. Baker** ESRF
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- **P. Stefan** SLAC/LCLS
- **Randy Whitney** SLAC/LCLS

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