

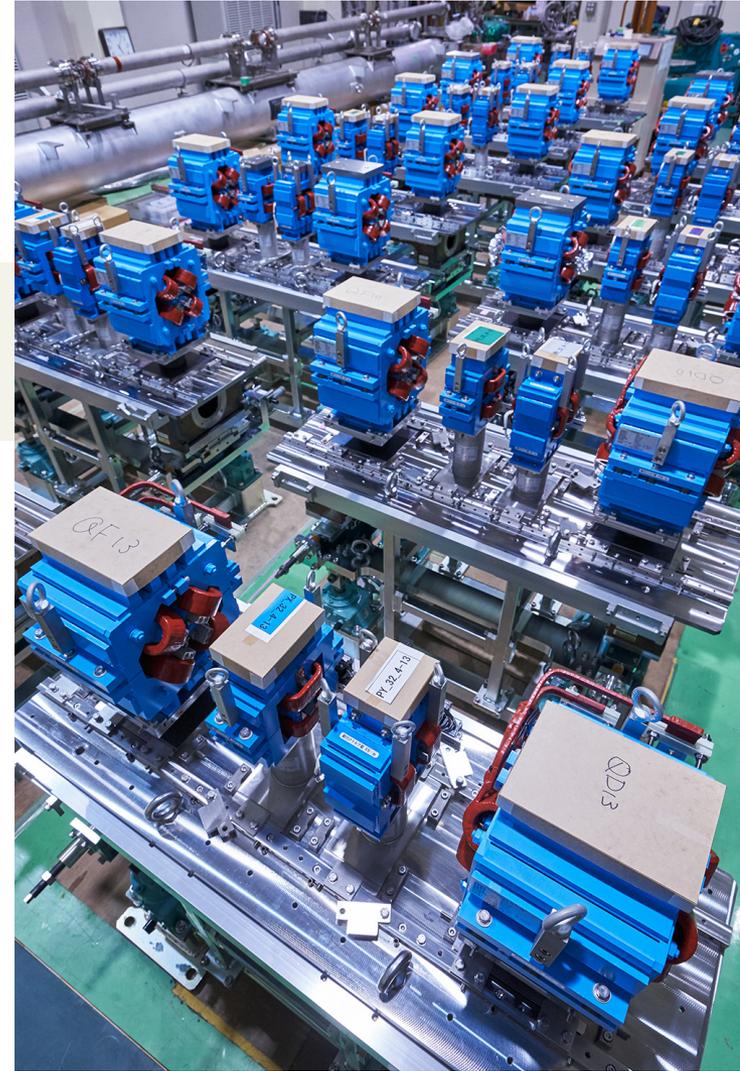
Pulse-to-pulse beam modulation for 4 storage rings with 64 pulsed magnets

Yoshinori Enomoto (KEK)

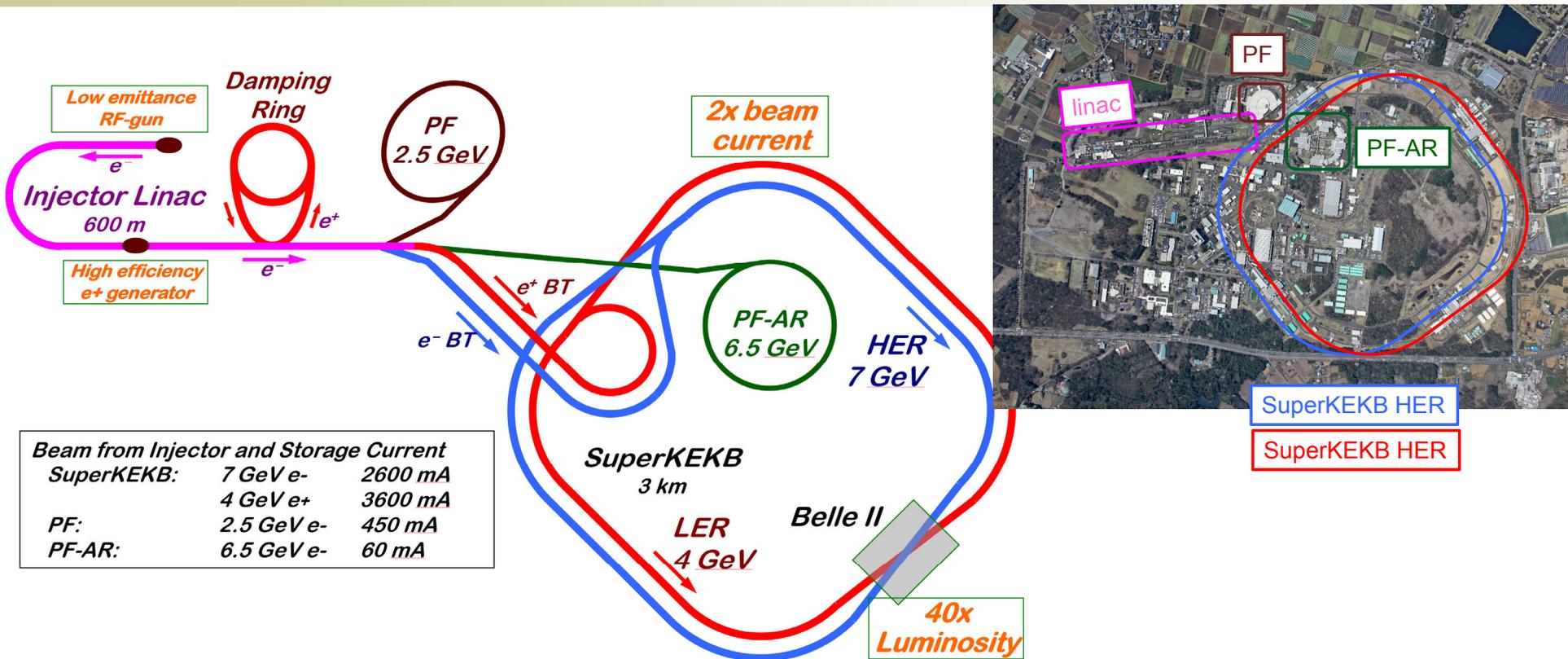
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2018/9/19

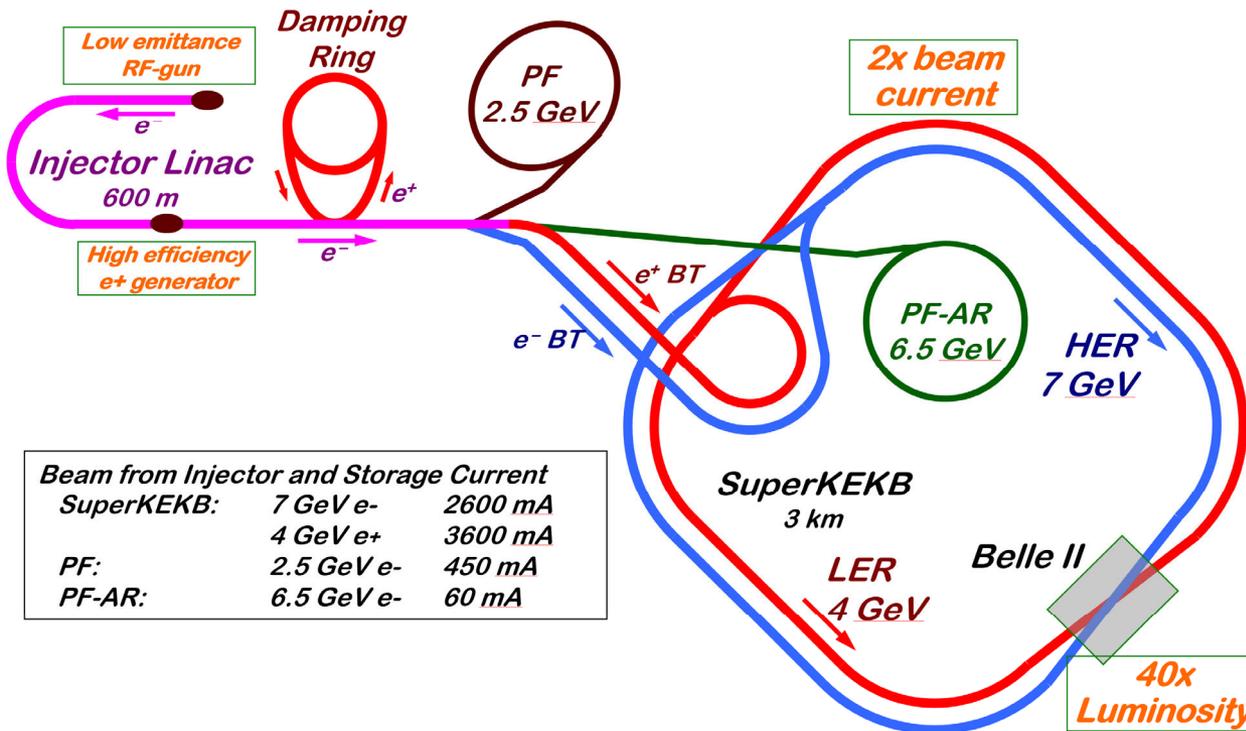
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Accelerator complex in KEK Tsukuba



Accelerator complex in KEK Tsukuba



- 4 rings and 1 linac
 - Two light source rings
 - PF, PF-AR
 - Two collider rings
 - SuperKEKB LER, HER
- Parallel configuration
 - No booster ring
- All storage rings
 - Full energy injection
- Top-up injection
 - Keep intensity of photon constant
 - Compensate short life time (360sec.)
- Two electron guns
 - RF gun for low emittance injection to SuperKEKB HER
 - Thermionic gun for high charge (10 nC) to produce large number of positrons
- Positron injection to LER

Requirements and progress on pulse-to-pulse operation

- Slow switch operation (-2009)

PF	PF-AR	KEB HER/LER	PF	PF-AR	KEKB HER/LER
20 min.	10 min.	7.5 hours	20 min.	10 min.	7.5 hours

- 3 ring injection with **DC magnets (2010)**

- **PF pulsed bending magnet** (switching magnet) was installed at the end of the linac.

PF-AR	PF, KEB HER/LER	PF-AR	PF, KEKB HER/LER
10 min.	7.8 hours	10 min.	7.8 hours

- Toward SuperKEKB (2018-)

- Very short beam life time in the SuperKEKB rings (360 sec.).
 - 10 min. Interruption is not acceptable.
 - **PF-AR direct injection line was constructed.**
- Small dynamic aperture
 - Low emittance beam is required for injection.
 - RF gun and positron dumping ring were installed.
 - For emittance preservation, optimization of the optics for each ring is required.



PF pulsed bending magnet

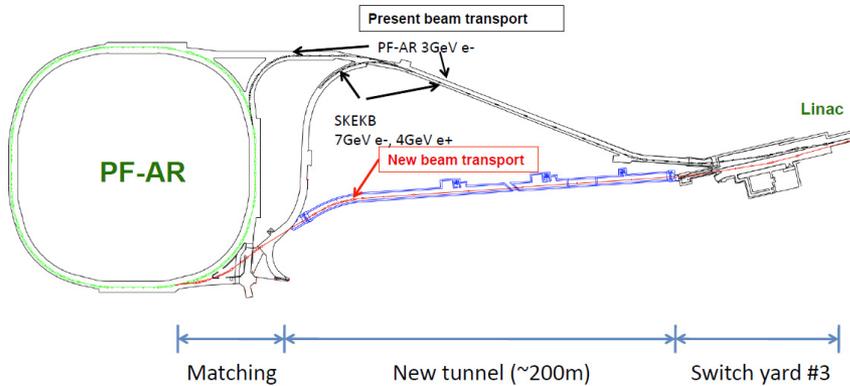
PF, PF-AR, SuperKEB HER/LER

always

Replace DC magnets with pulsed magnets

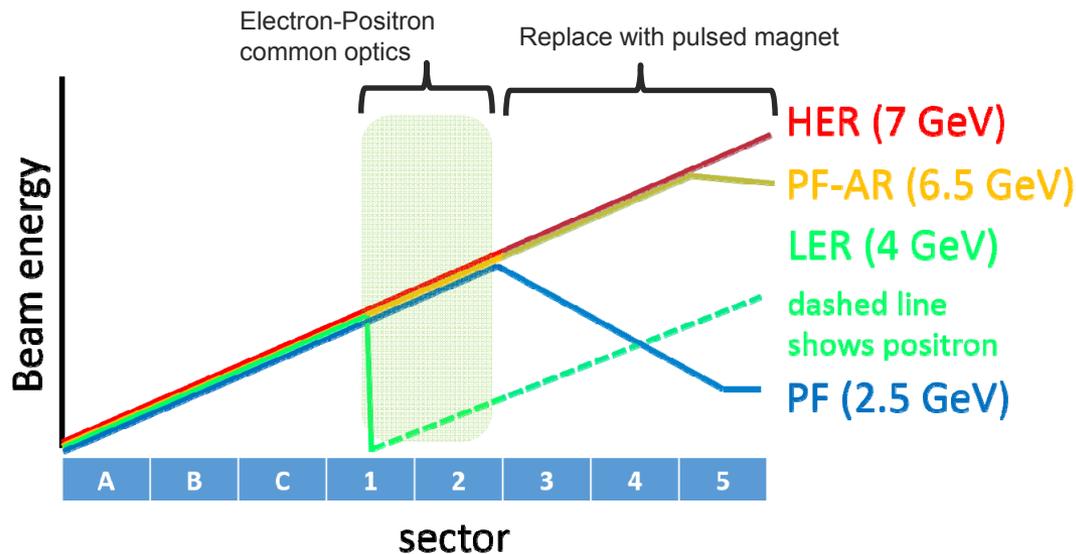
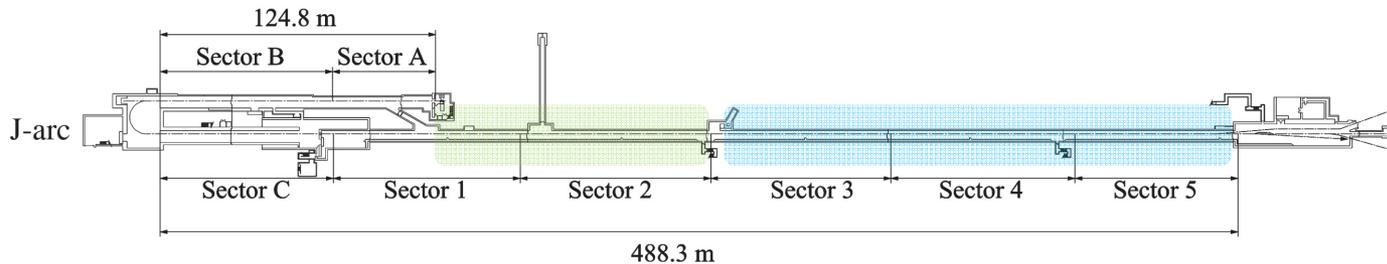
Requirements and progress on pulse-to-pulse operation

New beam transport for PF-AR



	KEKB		SuperKEKB	
	Charge	Emittance	Charge	Emittance
electron	1 nC	300 mm·mrad	5 nC	50 (H) / 20 (V) mm·mrad
positron	1 nC	1500 mm·mrad	4 nC	100 (H) / 20 (V) mm·mrad

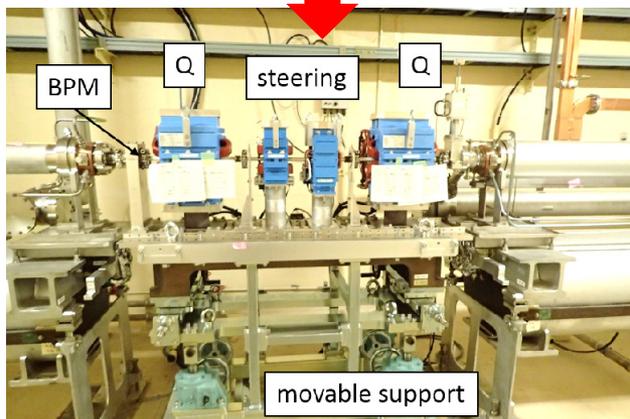
Beam energy and structure of our linac



- 600 m long, 8 sectors
- Maximize common energy section to use DC magnets as much as possible
- Install pulsed magnets mainly in sector 3 to sector 5

26 quads and 26 steerings @ sector 3-5
 10 steerings @ sector 1,2
 2 quads @ positron production target

Replacement of magnets



type	L@1 kHz	R	max current	magnetic field	gap	Installed Num.
PX_16_5	2.4 mH	71 mohm	40 A	1040 AT	72 mm	1
PY_16_5	2.4 mH	71 mohm	40 A	1040 AT	72 mm	1
PX_17_2	2.6 mH	127 mohm	40 A	1440 AT	39 mm	4
PY_17_2	2.6 mH	126 mohm	40 A	1440 AT	39 mm	4
PX_32_4	2.9 mH	115 mohm	40 A	1440 AT	20 mm	13
PX_32_4	2.9 mH	115 mohm	40 A	1440 AT	20 mm	13
PM_32_4	1.0 mH	8 mohm	330 A	60 T/m	ϕ 20 mm	28

Maximum design current of steering magnets are 40 A but operated at 10 A

- 64 magnets were installed in 2017.
 - Several types of steering magnets
 - One type of quad magnet
- 52 magnets of them were installed as a common unit.
 - 2 x quad magnets.
 - horizontal and vertical steering magnets
 - BPM
 - Movable support

Requirements for power supply



PF pulsed bending magnet and pulsed power supply

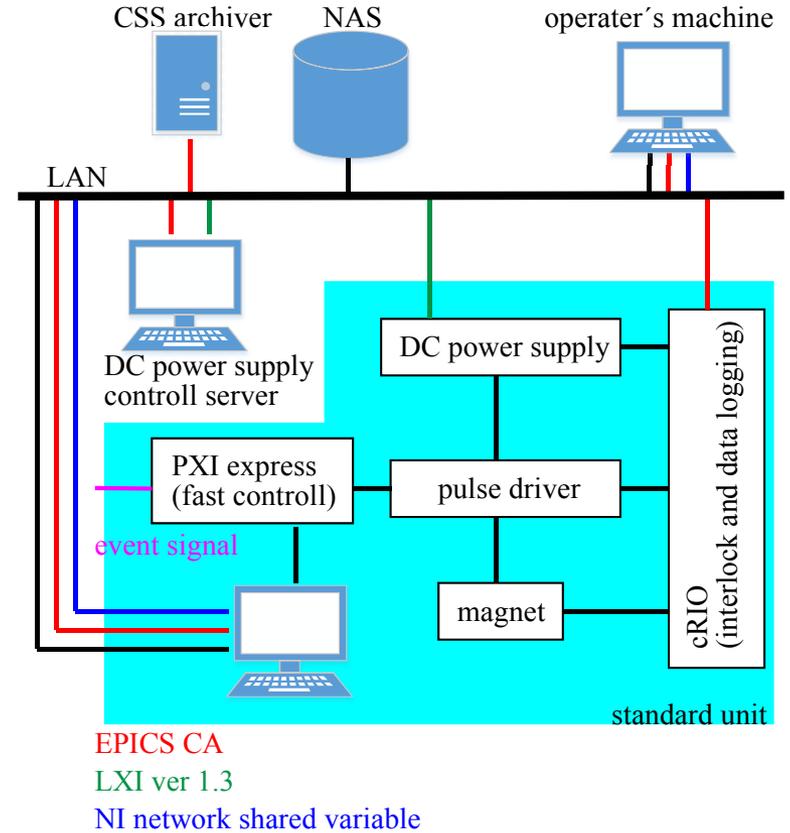
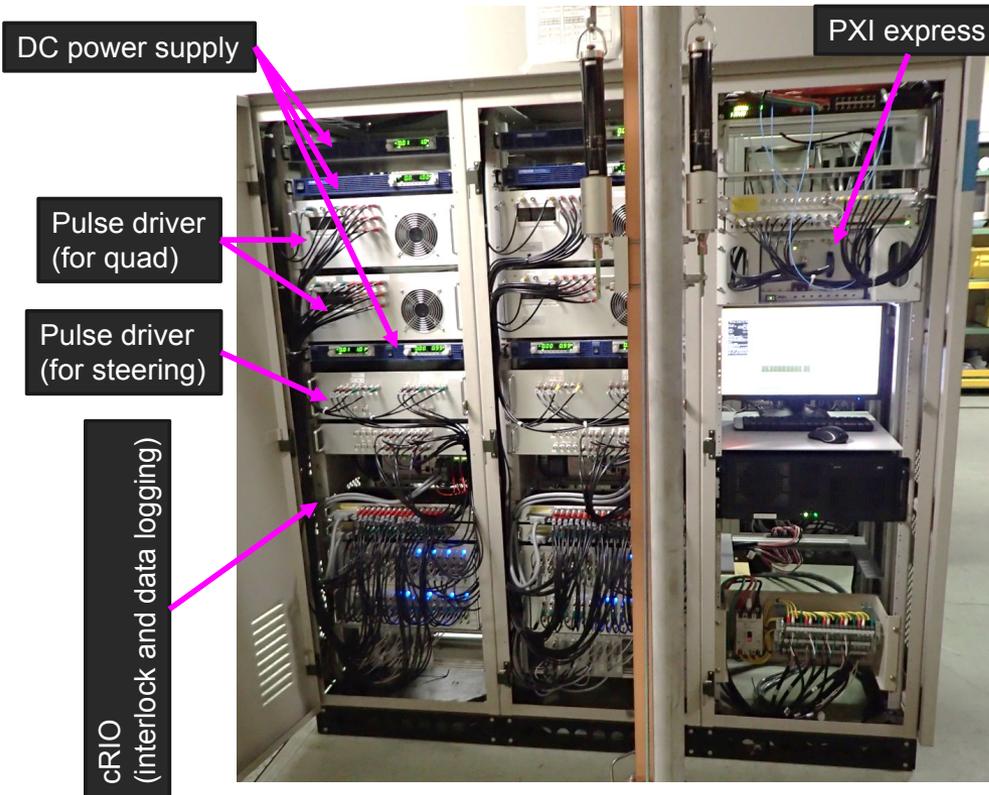
• PF pulsed bending magnet
• Klystron
• Electron gun
etc. are compatible with pulsed operation.
But most of them are off / on or on timing / off timing control.

- Install pulsed power supplies for 28 quads and 36 steerings.
 - budget is limited
 - Installation space is limited
 - Commercial power is limited
- Off / On control is not satisfactory.
 - Output setting should be changed pulse-to-pulse
- Compatible with MRF event timing system.
- Compatible with EPICS control system.

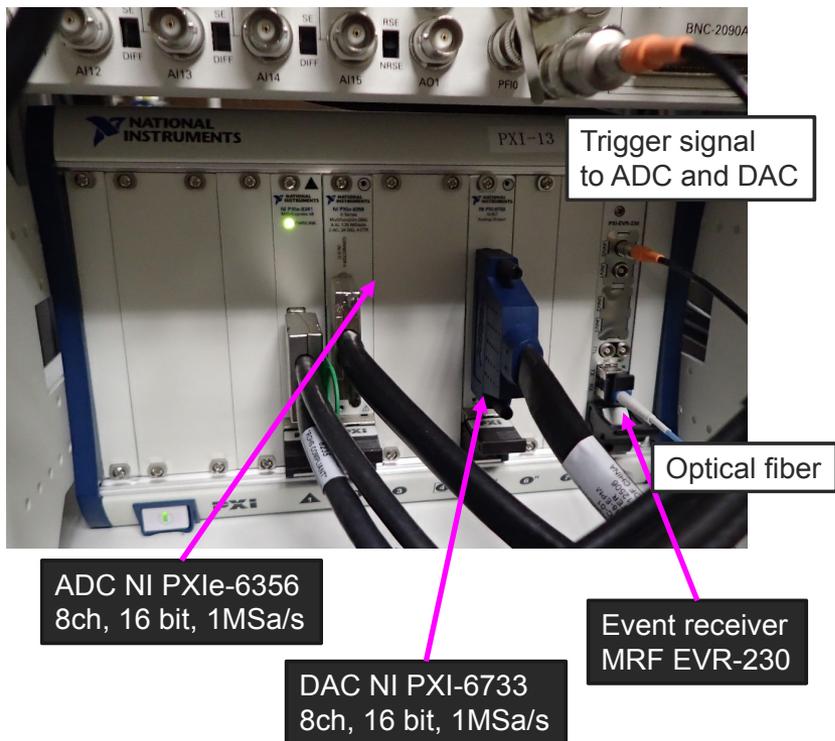
Decided to develop pulsed power supplies by ourselves.

System configuration of the pulsed power supplies

Standard power supply unit (4 x quad + 4 x steering)



Timing and fast control



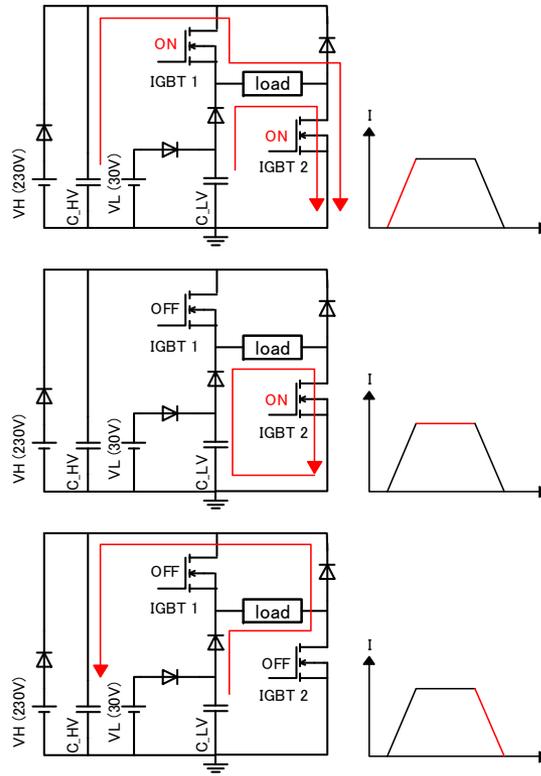
- PXI express system is adopted for fast control of the power supplies.
- All of the intelligent functions are processed by PXI express unit
 - Pulse driver works as a kind of power amplifier
 - Separation of control and power section makes it possible for us to flexible installation of different capacity of power supplies in the future.
- MRF(Micro-Research Finland) event receiver with PXI form factor is used for timing control
 - MRF event timing system is used as a master timing system of our linac.
- Mode and shot ID information are sent to the event receiver via optical fiber
 - Mode determine the destination of the beam.
 - Shot ID is used for tagging the data.

Energy recovery pulse driver for Q magnet

parameter	value
max current	330 A
max voltage	230 V
stability	0.1%
cooling	water cooled
power consumption	1500 W
repetition	50 Hz



Operation principle of the circuit



- Turn on both IGBTs and current flow from both of capacitors.
- Turn off IGBT 1 and control gate voltage of IGBT 2 to keep constant current
- Turn off both IGBTs and stored energy is recovered to the capacitor (C_HV).

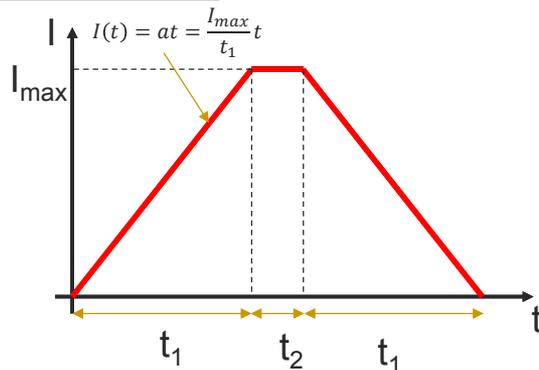
Energy recovery
+
Water cooling
↓
19 inch width
3U height

Energy consumption balance

Stored energy in inductance

$$P_L = \frac{1}{2} LI_{max}^2$$

Ohmic loss per cycle



$$\begin{aligned}
 P_{joule} &= \int_0^{2t_1+t_2} RI(t)^2 dt \\
 &= R \left\{ 2a^2 \int_0^{t_1} t^2 dt + I_{max}^2 t_2 \right\} \\
 &= R \left(2 \frac{I_{max}^2}{t_1^2} \frac{1}{3} t_1^3 + I_{max}^2 t_2 \right) \\
 &= RI_{max}^2 \left(\frac{2}{3} t_1 + t_2 \right)
 \end{aligned}$$

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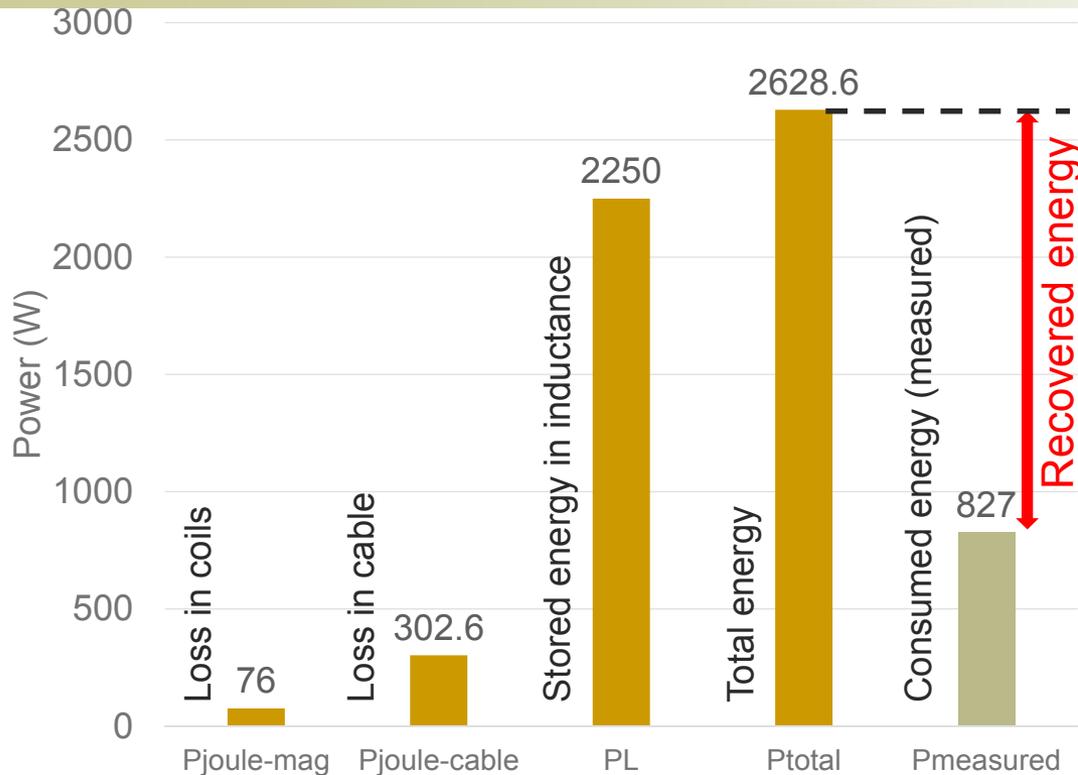
	Q (PM_32_4)	ST (PX_32_4)
t_1 (s)	2.5 m	←
t_2 (s)	0.5 m	←
I_{max} (A)	300	8
L (H)	1 m	3 m
R_{mag} (Ω)	7.8 m	115 m
R_{total} (Ω) incl. cable	38.83 m	298.85 m
$P_{joule-mag}$ (W) @ 50 Hz	76	0.797
$P_{joule-cable}$ (W) @ 50 Hz	302.6	1.275
$P_{joule-total}$ (W) @ 50 Hz	378.6	2.072
P_L (W) @ 50 Hz	2250	4.8
P_{total} (W) @ 50 Hz	2628.6	6.872

- Consumed energy by one quad magnet @ 300 A, 50Hz without energy recovery is 2628.6 W.
- Consumed energy by one steering magnet @ 8 A, 50Hz without energy recovery is 6.872 W.
- Consumed energy by steering magnet is negligibly small.

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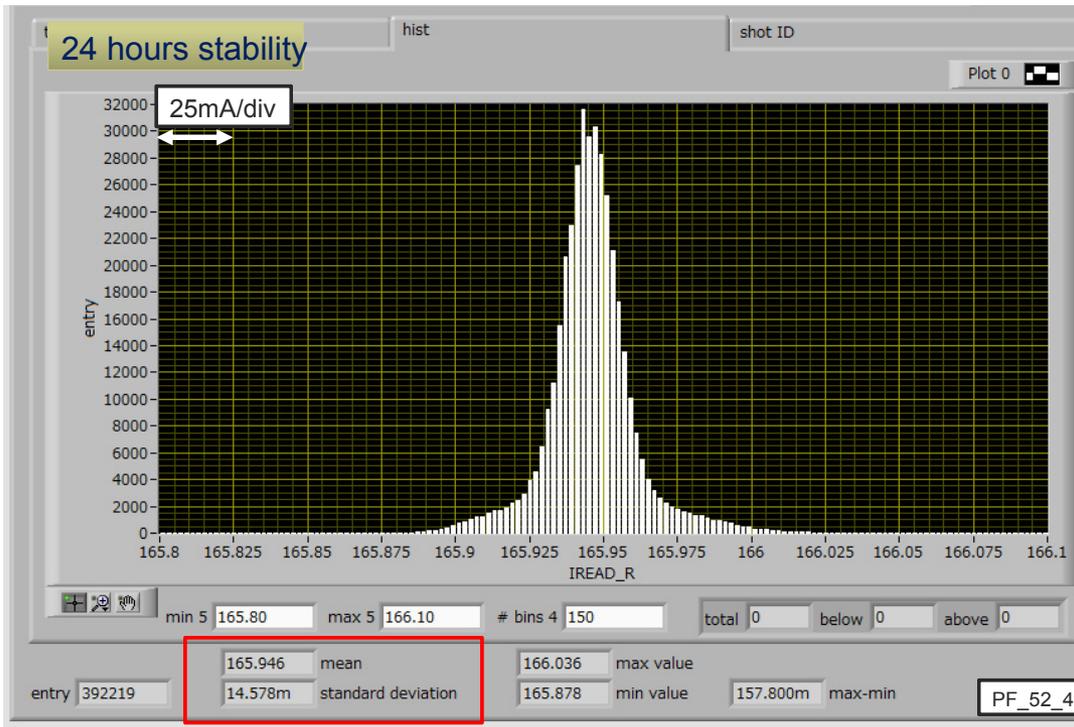
Energy consumption balance



- Measured consumed energy includes loss in pulsed driver circuit and DC power supplies to charge capacitors
 - True energy recovery efficiency (ratio of recovered energy and stored energy in inductance) is better than 80.1%

Total energy recovery efficiency = $100 \times (1 - P_{\text{measured}} / P_{\text{total}}) = 68.5\%$
 L energy recovery efficiency = $100 \times (1 - P_{\text{measured}} / P_L) = 80.1\%$

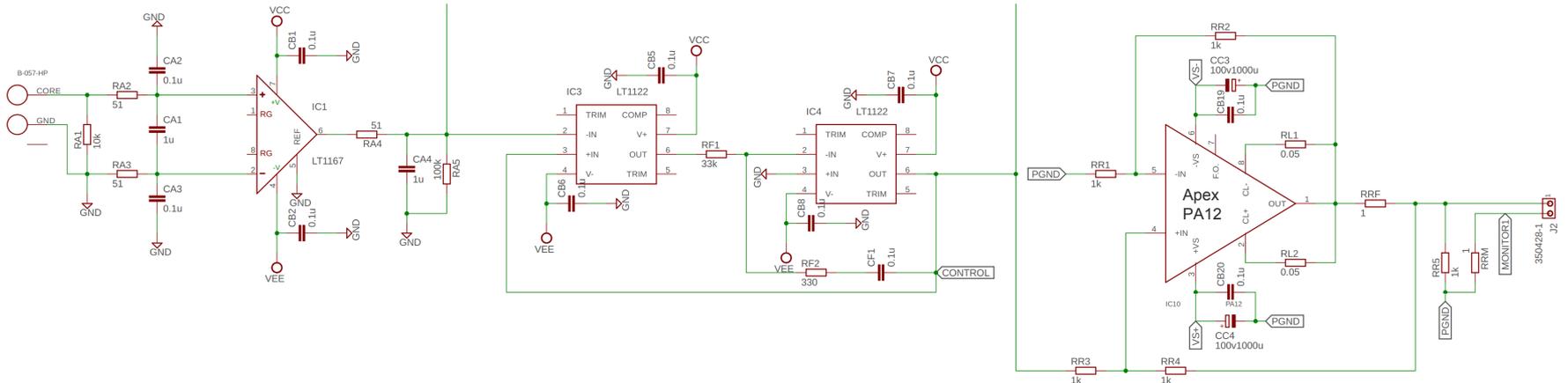
Stability measurement



- Stability measurement for 24 hours
- Output 166 A and 0 A alternately
- Output current was monitored built-in DCCT and PXIe ADC.

$$0.014578 / 165.946 = 0.0088\% \text{ (requirement } 0.1\% \text{ @ } 330 \text{ A)}$$

Pulse driver for steering magnet



Input buffer

Slew rate limiter

Power amplifier

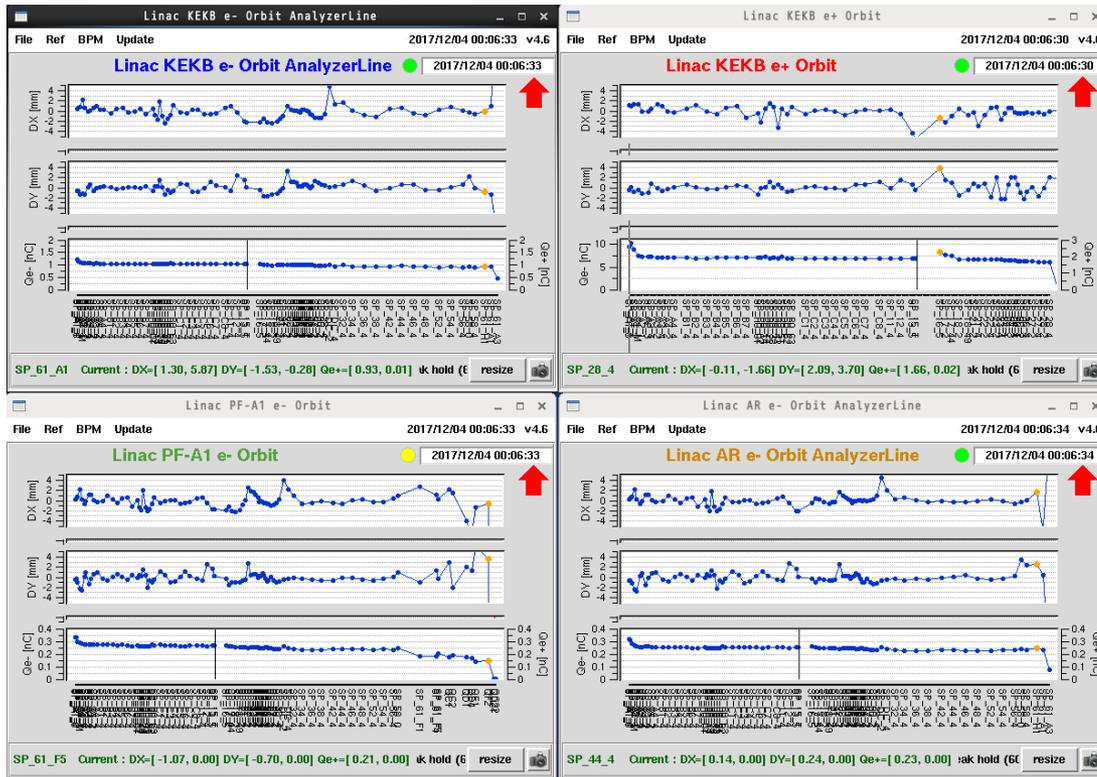
parameter	value
max current	± 10 A
max voltage	± 40 V
stability	0.01%
cooling	air cooled
power consumption	750 W
repetition	50 Hz



- Bipolar power supply by power Op amp (Apex PA12)
 - Low efficiency but Simple circuit
- Air cooled
- 2ch / case
- Built-in slew rate limiter

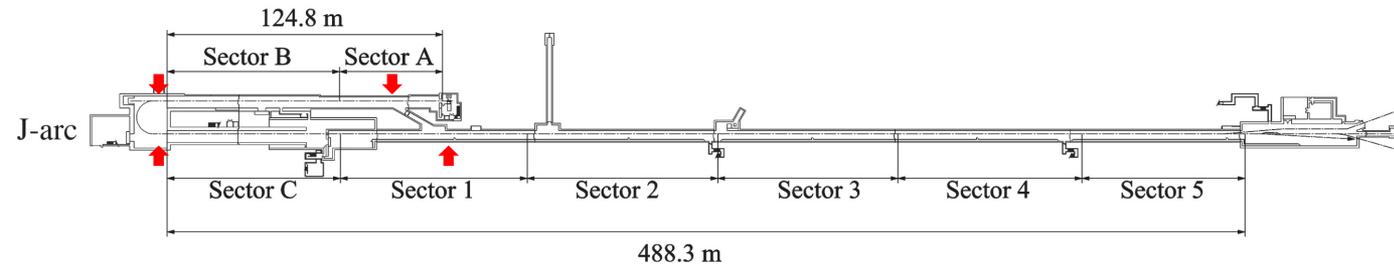
Pulse-to-pulse injection

BPM data (orbit and charge) for 4 different rings



- After the installation, comprehensive test was done in September 2017.
- Pulse-to-pulse operation was demonstrated successfully.
- For one year (Sept. 2017 – Sept. 2018), the system has been working very stably. No severe problem happened.

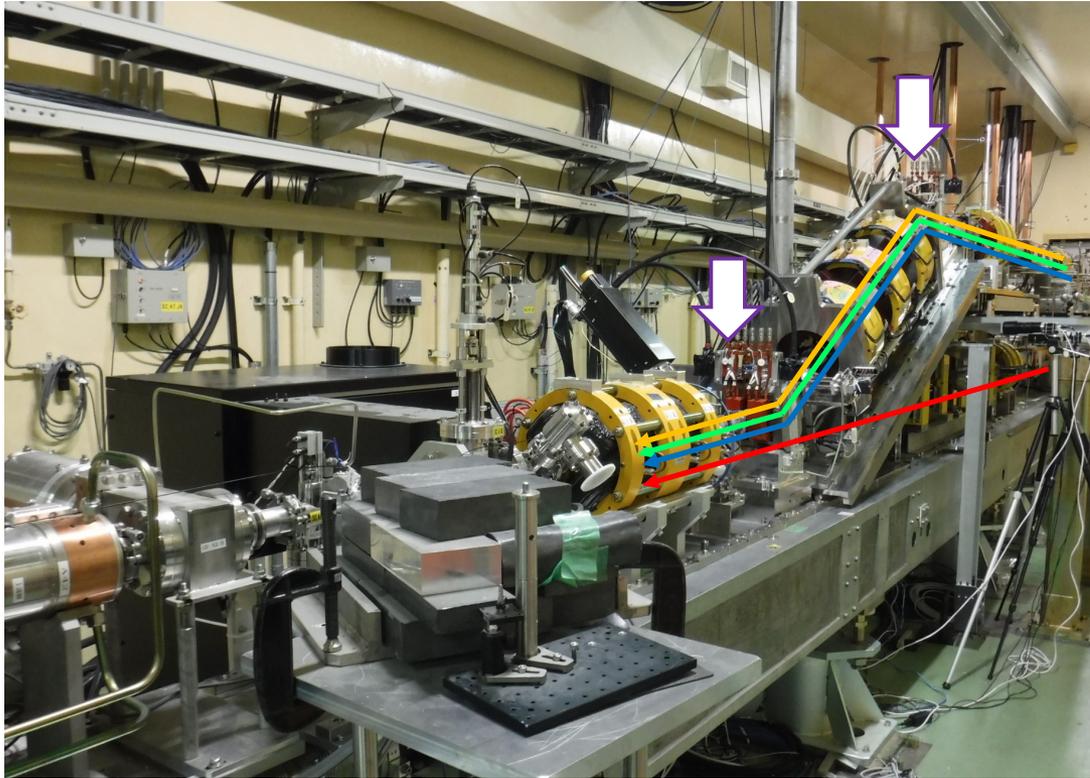
Plan in FY2018



- 2 bend magnets @ merging line.
 - Shot by shot switch of the RF / thermionic e⁻ gun.
- 4 quad and 4 steering magnets @ sector A.
 - To match the beam from the RF/ thermionic e⁻ gun.
- 8 steering magnets @ inlet and outlet of the arc section.
- 1 steering magnet @ sector 1 (before the positron production target)
- Replace power supply and control system of old 11 steering magnets

19 magnets, 30 power supplies will be installed in FY2018

Plan in FY2018



2 bend magnet at merging line

Thermionic e^- gun

PF-AR
LER(for e^+ production)
PF

HER

RF e^- gun

Summary

- In 2017, 64 pulsed magnets (28 quad, 36 steering) were installed.
- New pulsed power supply with energy recovery function was developed.
- Pulse-to-pulse injection to 4 rings were demonstrated.
- The system has been working very stably for one year.
- Further 19 magnets and 30 power supplies are plan to be installed in 2018.

members

- K. Furukawa
 - Adviser, management of the project, timing system
- T. Kamitani
 - Magnet design
- F. Miyahara
 - Timing system
- T. Natsui
 - Energy recovery pulse driver
- M. Satoh
 - Timing and control system, software
- K. Yokoyama
 - Magnet design
- M. Yoshida
 - Energy recovery pulse driver
- S. Ushimoto
 - cRIO interlock and data acquisition system
- H. Satome
 - Device driver for event receiver

Thank you
for your attention!