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## **Review of Permanent Magnet Technology for Accelerators**

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### OUTLINE

## Introduction

## Principal characteristics of permanent magnets (PM)

- Magnetic performance •
- Material temperature stability •
- Radiation damage \*

## Recent PM development in accelerators

- High gradient PM Quadrupoles \*
- •

## Conclusion and perspectives

Longitudinal Gradient PM Dipoles for low emittance storage rings (DLSR)



The European Synchrotron

### INTRODUCTION

### Permanent magnets are widely used in our daily life



Consumer electronic industry



Automotive industry



renewable energy industry



Health industry



### INTRODUCTION

## Permanent magnets are widely used in our daily life



Consumer electronic industry



Automotive industry

PM Family	Discovered
Alnico	30's
Ferrites	50's
SmCo	60's
NdFeB	80's



renewable energy industry



Health industry



### INTRODUCTION

## Permanent magnets are widely used in our daily life



Consumer electronic industry



Automotive industry

PM Family	Discovered
Alnico	30's
Ferrites	50's
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# Permanent magnets are used in accelerators mainly for insertion devices and for some dedicated devices





renewable energy industry



Health industry





ESRF



### Magnetic performance

- Sm<sub>2</sub>Co<sub>17</sub> and Nd<sub>2</sub>Fe<sub>14</sub>B used for Accelerator devices
- High remnant magnetization for Nd<sub>2</sub>Fe<sub>14</sub>B
- High resistance to radiation damage for Sm<sub>2</sub>Co<sub>17</sub>

Туре	B <sub>r</sub> (T)	H <sub>cj</sub> (kA/m)
Sm <sub>2</sub> Co <sub>17</sub>	1.05 – 1.15	1500 – 2100
Nd <sub>2</sub> Fe <sub>14</sub> B	1.06 – 1.45	900 - 3000



### PRINCIPAL CHARACTERISTICS OF PERMANENT MAGNETS

### Magnetic performance at low temperature

Higher performance (B<sub>r</sub> and H<sub>ci</sub>) at cryogenic temperature

- $Nd_2Fe_{14}B$  and  $Pr_2Fe_{14}B$  used at cryogenic temperature
- $Nd_{2}Fe_{14}B$  performance (B<sub>r</sub>) limited by the Spin Reorientation Transition around 135 K •  $Pr_{2}Fe_{14}B$  performance (B<sub>r</sub>) not limited by the SRT and can be cooled to 77 K

Туре	B <sub>r</sub> (%/C)	Н <sub>сј</sub> (%/С)
Sm <sub>2</sub> Co <sub>17</sub>	- 0.03	- 0.2
$Nd_2Fe_{14}B$	- 0.1	- 0.6
$Pr_2Fe_{14}B$	- 0.1	- 0.6



Cryogenic Permanent Magnet Undulator (CPMU)

0.0

**T. Hara** et al., *PRSTAB*, *7*, *050702* (2004)

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Samples provided by Konit (China)



### Material temperature stability





### Radiation damage

- Radiation exposure leads to demagnetization of permanent magnet
  - $Sm_2Co_{17}$  has a higher resistance to radiation damage (high coercivity  $H_{ci}$ )
  - Demagnetization depends on magnet shape and working point in the magnet
- Effect similar to that of a thermal partial demagnetization
- Undulator damaged by radiation in several facilities (ESRF, APS, PETRA III)
- The radiation damage risk has increased with the development of small gap devices (in-vacuum IDs)
- CPMUs Have better resistance to radiation damage risks (very high coercivity H<sub>ci</sub>)

**T. Bizen,** ERL 2011, Tsukuba, Japan, p. 121-126, (2011) **T. Bizen,** *NIMA*, 467-468, p. 185-189, (2001)





## High gradient quadrupoles are of great interest for

### > Colliders

Free Electron Lasers

Low emittance storage rings



## High gradient quadrupoles are of great interest for

## > Colliders

Free Electron Lasers

Low emittance storage rings

Permanent magnets are a good candidate for this type of device

Small surfaces with high magnetisation No power consumption and no water cooling

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### Fixed gradient PM quadrupoles

Ultra high gradient

Very compact devices

Homogeneity very sensitive to PM quality

- Remnant magnetization variation
- Magnetization angle variation
- Mechanical assembly





### Halbach permanent magnet quadrupole

$$G = 2Br\left(\frac{1}{r_i} - \frac{1}{r_e}\right)K$$

K depends on the number of segments M

$$r_{i} = 10 \text{ mm}$$
  
 $r_{e} = 20 \text{ mm}$   
 $B_{r} = 1.25 \text{ T}$   
 $G = 125 \text{ T/m}$ 

**K. Halbach,** *NIM 169, p. 1-10, (1980)* 



### Fixed gradient PM quadrupoles

### **PPM Halbach PMQ**

Gradient	500 T/m
Bore radius	3 mm
Tunability	No



**T. Eichner** et al., *PRST*, *10*, *082401* (2007) **J.K. Lim** et al., *PRST*, *8*, 072401 (2005)

### Hybrid Halbach PMQ

Gradient	115 T/m
Bore radius	7 mm
Tunability	No



**T. Mihara** et al., *SLAC* – *PUB* – *10248*, *February 2004* 





2.3 cm

### Fixed gradient PM quadrupoles

### Dominated Iron quadrupole

Good field homogeneity

Moderate gradient field

No Tunability

Gradient	80 T/m
Bore radius	12.5 mm
Tunability	No



### Field correction shim

r = 7 mm,  $(b_n / b_2) \cdot 10\,000$  $b_3 = -1.3$  $b_4 = 3$  $b_6 = -8.4$  $b_{10} = -7$ 

**P. N'gotta** et al., *PRAB*, *19*, *122401 (2016)* 







### Variable gradient PM quadrupoles

Hybrid or dominated iron devices High and variable gradient Different type of gradient tunability

- Displacement parts
- Rotation parts
- Additional coils

## Precision and reliability depends on motors and encoders Magnetic center shift with gradient variation





### Variable gradient PM quadrupoles

- Dominated iron quadrupole
- Fixed poles and yoke, displacement of all PMs
- Moderate and variable gradient
- A motor for the displacement of each PM
- Magnetic center shift calibrated using PM position

Bore radius	6.5 mm	
Max Gradient	115 T/m	R
Min Gradient	13 T/m	
Magnetic center shift	2.5 µm	

### **PMs linear retraction**



S. C. Gottschalk et al., PAC05, Knoxville, USA, 2005

![](_page_16_Picture_15.jpeg)

### Variable gradient PM quadrupoles

- Dominated iron quadrupole
- Fixed poles and vertical displacement of PMs and yoke
- Moderate and variable gradient
- High Magnetic center shift
- One motor and gearboxes for the displacement of both parts

Bore radius	13.6 mm
Max Gradient	60 T/m
Min Gradient	15 T/m
Magnetic center shift	100 µm

**B.J.A. Shepherd** et al., IPAC13, Shanghai, China, 2013

![](_page_17_Picture_10.jpeg)

### **Displacement parts (PMs and yoke)**

![](_page_17_Picture_14.jpeg)

![](_page_17_Picture_15.jpeg)

![](_page_17_Picture_16.jpeg)

### Variable gradient PM quadrupoles

- Hybrid quadrupole
- Halbach rings, 1 fixed Hybrid ring and 4 rotated PPM rings
- High and variable gradient
- Magnetic center shift corrected by shimming outer rings

Bore radius	<b>10 mm</b>	25
Max Gradient	120 T/m	E 20
Min Gradient	17 T/m	01 atre
Step	7 T/m	Inte
Magnetic center shift	20 µm	0 turned 0 "Sw Contribut

![](_page_18_Figure_10.jpeg)

**Y. Iwashita** et al., EPAC06, Edinburgh, Scotland, 2006

![](_page_18_Picture_13.jpeg)

### Variable gradient PM quadrupoles

- Hybrid compact quadrupole
- Fixed Hybrid ring and 4 rotated PM cylinders
- High and variable gradient
- Magnetic center shift corrected by translation stages
- Magnetic measurement with different methods
- 7 quadrupoles with lengths from 26 mm to 100 mm

Bore radius	6 mm	200
Max Gradient	210 T/m	THE 160 - 140 -
Min Gradient	110 T/m	120 0 50 100 150 200 250 Theta [deg] Gradient versus tuning magnets angle
Magnetic center shift	20 µm	with ( $\Delta$ ) TOSCA and ( $\Box$ ) RADIA. (Line) sin

(Line) sinus t

![](_page_19_Picture_14.jpeg)

**F. Marteau** et al., APL, submitted (2017) J.T.Volk et al., PAC01, Chicago, USA, 2001

![](_page_19_Picture_16.jpeg)

![](_page_19_Picture_17.jpeg)

### Variable gradient PM quadrupoles

- Dominated iron quadrupole
- Combined fixed PMs and coils
- Ultra high and variable gradient
- ✤ Good field quality < 0.1 % in 1 mm GFR</p>
- Less compact device with coils
- Power consumption

Bore radius	<b>4.12 mm</b>
Max Gradient	> 500 T/m
Min Gradient	100 T/m

**M. Modena** et al., IPAC12, New Orleans, USA, 2012 **M. Modena**, Workshop at CERN, Geneva, Switzerland, 2014

FIELD GRADIENT [T/m]

![](_page_20_Figure_12.jpeg)

![](_page_20_Picture_13.jpeg)

![](_page_20_Picture_15.jpeg)

![](_page_21_Figure_1.jpeg)

- Rotation systems are more efficient and more compact \*
- •

Dominated iron with linear displacement have better field quality Magnetic center shift depends on the gradient variation systems

High gradient PM quadrupoles are still dedicated devices

![](_page_21_Picture_9.jpeg)

## The trend is towards Low Emittance Storage Rings

### New facilities

MAX IV in Sweden – 330 pm.rad Commissioning done

Sirius in Brazil – 250 pm.rad Construction in progress

ESRF-EBS will be 7BA 6 GeV lattice

![](_page_22_Picture_6.jpeg)

### **ESRF today has DBA 6 GeV lattice**

### Upgrade facilities using the existing building

**ESRF-EBS in France** – 140 pm.rad Commissioning expected in 2020

**APS-U in USA** – 70 pm.rad Commissioning expected in 2023

SPring-8-II in Japan – 149 pm.rad Upgrade studies on progress

![](_page_22_Picture_14.jpeg)

Emittance  $\propto 1/(N \text{ dipoles})^3$ 

Increase number of dipoles

![](_page_22_Picture_17.jpeg)

![](_page_23_Figure_1.jpeg)

**Red**=DQ: Combined dipole quadrupole Blue=LG: Dipole with longitudinal gradient

Compact electromagnets at MAX IV

![](_page_23_Picture_5.jpeg)

### PM dipole have advantages over electromagnet one

- Compact devices

- No power supply and no cooling systems Better reliability (no water and power supply failures) Less control systems, cables and noise
- Important reduction in operation cost

### Challenges for permanent magnet Dipoles

- Magnetic field design
- Magnetic field tuning and shimming
- Temperature dependence
- Demagnetization risks
- Series production

![](_page_24_Picture_16.jpeg)

Estimation of electric power cost for dipoles in 2016

![](_page_24_Picture_19.jpeg)

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![](_page_25_Picture_16.jpeg)

Estimation of electric power cost for dipoles in 2016

There are almost no PM devices used as standard magnets in accelerator lattices, the only exception being the Fermilab recycler

**G.W. Foster** et al., EPAC98, Stockholm, Sweden, 1998

![](_page_25_Picture_21.jpeg)

Dipole		
Gap	mm	25.5 – 30
Iron length	mm	1788
Permanent magnet		Sm <sub>2</sub> Co
Iron		Pure irc
Number of dipoles		128

![](_page_26_Picture_2.jpeg)

### Dipole constituted by 5 modules

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![](_page_26_Picture_7.jpeg)

### **ESRF-EBS LG Dipole**

## Prototypes to confirm calculated performance and to define the series production process

- Permanent magnet assembly
- Magnetic field strength and quality
- Longitudinal field integral fringe
- Temperature compensation

![](_page_27_Picture_8.jpeg)

### Two modules with 0.62 T and 0.41 T

![](_page_27_Picture_10.jpeg)

PM assembly needs special tools Field quality depends on pole parallelism Shimming required to reach targeted field Longitudinal gap to be defined for flat field

![](_page_28_Picture_2.jpeg)

### Flat field at longitudinal gap $g_s = 5 \text{ mm}$

![](_page_28_Figure_6.jpeg)

![](_page_28_Figure_7.jpeg)

### Tolerance: $\Delta B/B < 10^{-3}$ @13 mm

![](_page_28_Figure_9.jpeg)

- Dominated by PM material temperature coefficient
- Compensated by passive Fe-Ni shunts
  - The Fe-Ni shunts are ~ saturated
  - The magnetization in Fe-Ni has large temperature dependence

![](_page_29_Figure_5.jpeg)

Field integral measurements on PM DL modules NdFeB PM, Sm<sub>2</sub>C0<sub>17</sub> PM

![](_page_29_Picture_11.jpeg)

### ESRF Dipole module

### dB/B/dT after compensation:< 40 ppm/C

![](_page_29_Picture_16.jpeg)

Dipole		
Gap	mm	25
Iron length	mm	1750
Permanent magnet		Sm <sub>2</sub> Co <sub>17</sub>
Iron		Pure iron
Number of dipoles		176

![](_page_30_Picture_2.jpeg)

### Dipole constituted of 3 modules

![](_page_30_Figure_5.jpeg)

The LGB designs are now being modified.

### Spring-8-II LG Dipole

Courtesy of T. Watanabe

![](_page_30_Picture_9.jpeg)

Outer plates for B-field tuning "Nose structures" for smooth B-field transition between modules Temperature compensation

![](_page_31_Figure_2.jpeg)

![](_page_31_Figure_3.jpeg)

(14 % B-field tuning by outer plates.)

![](_page_31_Figure_8.jpeg)

Courtesy of T. Watanabe

ESRF

Dipole		
Gap	mm	26 -
Iron length	mm	82
Permanent magnet		Nd <sub>2</sub> F
Iron		Pure
Number of dipoles		2

![](_page_32_Picture_2.jpeg)

![](_page_32_Picture_3.jpeg)

![](_page_32_Figure_6.jpeg)

28

- e<sub>14</sub>B
- iron

### BC Strength Т 3.2 - 0.58

![](_page_32_Figure_12.jpeg)

Vertical field vs. longitudinal position

### Courtesy of Lin Liu

![](_page_32_Picture_15.jpeg)

### **SIRIUS BC Dipole**

### Series production in progress

![](_page_33_Picture_2.jpeg)

![](_page_33_Picture_3.jpeg)

ESRF PM dipoles assembly area

![](_page_33_Picture_6.jpeg)

![](_page_33_Picture_7.jpeg)

Vertical postion [mm]

### Procurement of different parts

- 6 tons of PM material (>15000 blocks)
- 660 Mechanical parts (poles and yokes)

### Development and test of PM assembly tools

- Easy to use tooling
- Management of PM forces
- Robustness for long term use

PM assembly and thermal compensation

- Assembly of PMs on each module
- Fe-Ni amount depends on module type
- Adjustment of the position of the poles
- Magnetic measurement and shimming
  - Measurement and shimming of each model to reach targeted field
  - Measurement and shimming of PM dipole to reach final performances
  - Fiducialisation of the dipole

![](_page_34_Picture_17.jpeg)

![](_page_34_Picture_18.jpeg)

DB/B

![](_page_34_Figure_20.jpeg)

![](_page_34_Picture_21.jpeg)

ESRF stretched wire magnetic bench

![](_page_34_Picture_23.jpeg)

PM Dipole ready for use

47 dipoles out of 128 are assembled

![](_page_34_Picture_26.jpeg)

![](_page_34_Picture_27.jpeg)

### Dedicated high gradient and compact PM quadrupoles have been developed

- Lack of space
- Limitation of electromagnet quadrupole
- Energy saving could be an important criteria
  - Quadrupoles for low heat to air facilities
    Accelerators with a large number of quadrupoles
- PM LG Dipoles development is in progress
- Iattice PM multipole magnets R&D for Low emittance storage rings
  - Dominated iron quadrupole with precise pole shape
    Improve the magnetic center shift with gradient tunability
    Limited tenability quadrupoles with low consumption air coils
    Sextupole and octupole magnets require large tunability

![](_page_35_Picture_10.jpeg)

Resistive magnet close to limit (quadrupoles)

# Complicated vacuum chamber technology with small magnet aperture

![](_page_36_Picture_5.jpeg)

Resistive magnet close to limit (quadrupoles) •

![](_page_37_Figure_2.jpeg)

# Complicated vacuum chamber technology with small magnet aperture

### In- vacuum

Cryogenic cooling (LN<sub>2</sub>) PrFeB magnets

![](_page_37_Picture_7.jpeg)

Resistive magnet close to limit (quadrupoles) •

![](_page_38_Figure_2.jpeg)

# Complicated vacuum chamber technology with small magnet aperture

Cryogenic cooling (LN<sub>2</sub>)

![](_page_38_Picture_7.jpeg)

### MANY THANKS FOR YOUR ATTENTION

![](_page_39_Picture_1.jpeg)

![](_page_39_Picture_3.jpeg)

![](_page_39_Picture_4.jpeg)