Mathematical Methods

Rigorous Fixed Point Enclosures and an Application to Beam Transfer Maps

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Transfer Maps

Typical workflow:

- O Computation of transfer map
 - Using differential algebra (DA) techniques, e.g. COSY INFINITY
 - High order computations
 - Yielding functional relationship between initial and final coordinates
- Particle tracking
 - Pick initial conditions
 - Apply transfer map, correct symplectic errors, repeat
- Analysis
 - Study tracking picture
 - Determine "dynamic aperture"



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Conclusion

Dynamic Aperture

Not a (mathematically) well defined concept!

- Only finitely many initial conditions tracked
- Only a finite number of revolutions tracked Essentially educated guessing from pictures BUT: Pictures can be misleading!



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Dynamic Aperture



0.300

x-a tracking picture of real Tevatron map: nice interior with bad fringes?



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Dynamic Aperture



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Dynamic Aperture



Periodic Point Finder

Goal: Ensure we avoid such surprises!

- Need the "right" initial conditions for tracking
- Catch all possibly problematic points

Island structures form around elliptic periodic points (resonances) \Rightarrow Try to find periodic points!

Note: The following are equivalent problems

- fixed point: f(x) = x
- periodic point: $f^n(x) = x$
- root finding: f(x) = 0



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Naive Newton's method fails, because origin is too "strong"



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Attractive Fixed Point (Existence)

Theorem (Schauder's Theorem)

Let $K \subset \mathbb{R}^n$ be a non-empty, compact, and convex set. Then, any continuous map $f : K \to K$ has a fixed point in K.





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(Super-Brief) Intro to Taylor Model Methods

Taylor Model Methods (Makino, Berz) for verified numerics:

- Extension of differential algebra (DA) techniques
- Automatic rigorous calculation of truncation errors DA:

$$f(x_0 + \delta x) \approx f(x_0) + f'(x_0) \cdot \delta x + \dots + \frac{1}{n!} f^{(n)}(x_0) \cdot \delta x^n$$

TM:

 $f(x_0 + \delta x) \in f(x_0) + f'(x_0) \cdot \delta x + \cdots + \frac{1}{n!} f^{(n)}(x_0) \cdot \delta x^n + [-\varepsilon, \varepsilon]$

• Polynomial bounders (e.g. LDB) provide highly accurate bounds for images of sets under *f*



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Attractive Fixed Point (Uniqueness)

Theorem (Banach's Theorem)

Let K be a non-empty, complete metric space. Then, any contraction $f : K \to K$ has a unique fixed point in K.

Reminder: A map f is a contraction if $\exists 0 \leq K < 1$ such that

$$|f(x) - f(y)| < K |x - y|$$

 $\forall x, y \in K$



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Combining both theorems:

Corollary

Let $K \subset \mathbb{R}^n$ be a convex, compact set, and $f : K \mapsto K$ be continuously differentiable with $|Df(x)| < 1 \ \forall x \in K$. Then f has a unique fixed point in K.

Verification procedure:

- Find small box B around assumed fixed point and show it is mapped into itself (⇒existence)
- **2** Bound |Df| over B and show it is less than 1 (\Rightarrow uniqueness)





Global fixed point finder

- works for all types of fixed points (repelling, hyperbolic, elliptic, attracting)
- Ind verified fixed point enclosures automatically
- If ind all fixed points in given area



Invariant Manifolds

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Conclusion

Preconditioning

For any regular matrix A:

$$f(x) = x \iff A \cdot f(x) = A \cdot x$$

As fixed point problem:

$$f(x) = x \iff A \cdot (f(x) - x) + x = x$$

Idea

Choose A so $A \cdot (f(x) - x) + x$ has a strongly contracting fixed point x_0 .

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Preconditioning

Idea

Choose A so $A \cdot (f(x) - x) + x$ has a strongly contracting fixed point x_0 .

$$A = -(Df(x_0) - I)^{-1}$$

Derivative of

$$A \cdot (f(x) - x) + x$$

at fixed point x_0 :

 $A \cdot (Df(x_0) - I) + I = -(Df(x_0) - I)^{-1} \cdot (Df(x_0) - I) + I = -I + I = 0$



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Preconditioning

Idea

Choose A so $A \cdot (f(x) - x) + x$ has a strongly contracting fixed point x_0 .

- Similar to Newton method applied to f(x) x,
- A does not have to be rigorous, any regular A will do,
- A above is best choice yielding superlinear contraction.



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Effect of Preconditioning



without preconditioning



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Effect of Preconditioning





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with preconditioning

Rigorous Root & Fixed Point Finder

Basic algorithm for Global Fixed Point Finder:

- Start with region of interest on stack
- Itest top box on stack for fixed point
 - No FP: discard
 - FP found: keep box as result (or split if enclosure too big)
 - Unknown: split box
- S While stack not empty: continue with 2.

Yields verified enclosures of all fixed points in area of interest.



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Invariant Manifolds

Theorem (Invariant Manifold Theorem)

Hyperbolic fixed points of diffeomorphisms have invariant manifolds.

Stable manifold of fixed point p:

$$W_p^s = \left\{ x \in \mathbb{R}^n | \lim_{n \to \infty} f^n(x) = p \right\}$$

Unstable manifold of fixed point p:

$$W_p^u = \left\{ x \in \mathbb{R}^n | \lim_{n \to \infty} f^{-n}(x) = p \right\}$$

Hyperbolic fixed points in transfer maps have invariant manifolds!



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Invariant Manifolds in Transfer Maps





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Invariant Manifolds in Transfer Maps





stable and unstable manifolds of all periodic points $\langle \Box \rangle \land d P \rangle \land \exists \rangle \land \exists \rangle$

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Invariant Manifolds in Transfer Maps



stable (blue) and unstable (magenta) manifolds $\langle \Box \rangle \langle \Box \rangle \langle \Box \rangle \langle \Xi \rangle \langle \Xi \rangle$



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Invariant Manifolds in Transfer Maps







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Invariant Manifolds and Chaos Invariant Manifolds can prove chaotic behavior

Theorem (Poincaré-Birkhoff-Smale)

If the stable and unstable manifold of a hyperbolic fixed point intersect transversely, the map exhibits chaos (has positive topological entropy).

Chaos is induced by the construction of a Smale horseshoe from higher iterates of the manifolds:



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Invariant Manifolds in Lorenz





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Invariant Manifolds in Lorenz





Conclusion

- A rigorous fixed point finder
 - can automatically identify fixed points in area of interest
 - utilizes functional dependence in transfer maps
 - is guaranteed to find all periodic points
 - is mathematically fully rigorous

Invariant Manifolds

- can mathematically rigorously prove existence of chaos
- can provide bounds on the island region of the transfer map



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Thank You

Thank you for your attention.

Questions?

