



# The Fast Protection System for CSNS Accelerator

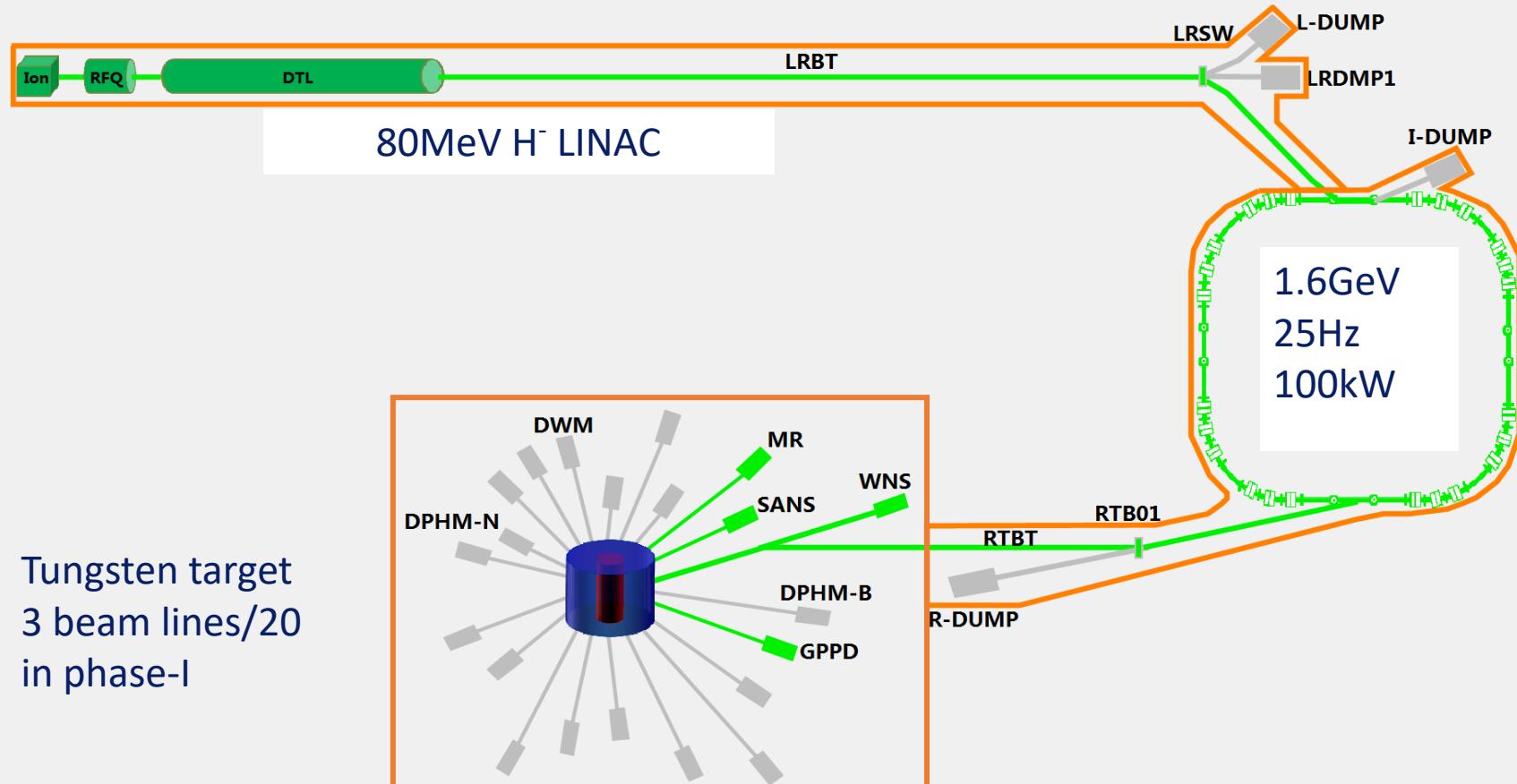
Yuliang Zhang  
CSNS@IHEP

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# Outline

- 1** Brief Introduction of CSNS Protection Systems
- 2** Design and Deployment of Fast Protection System
- 3** Logic of the Beam Interlock and Mitigation Measures
- 4** Summary

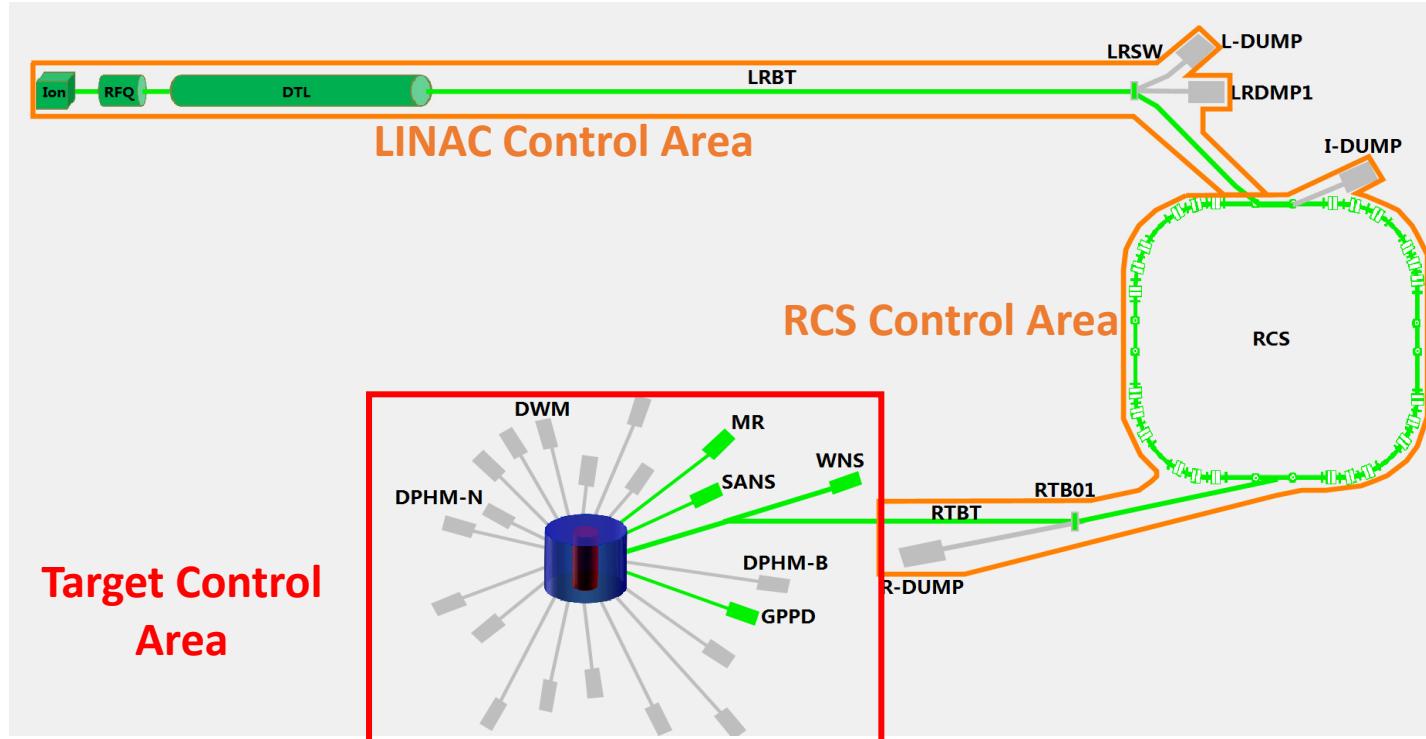
# Brief Introduction of CSNS



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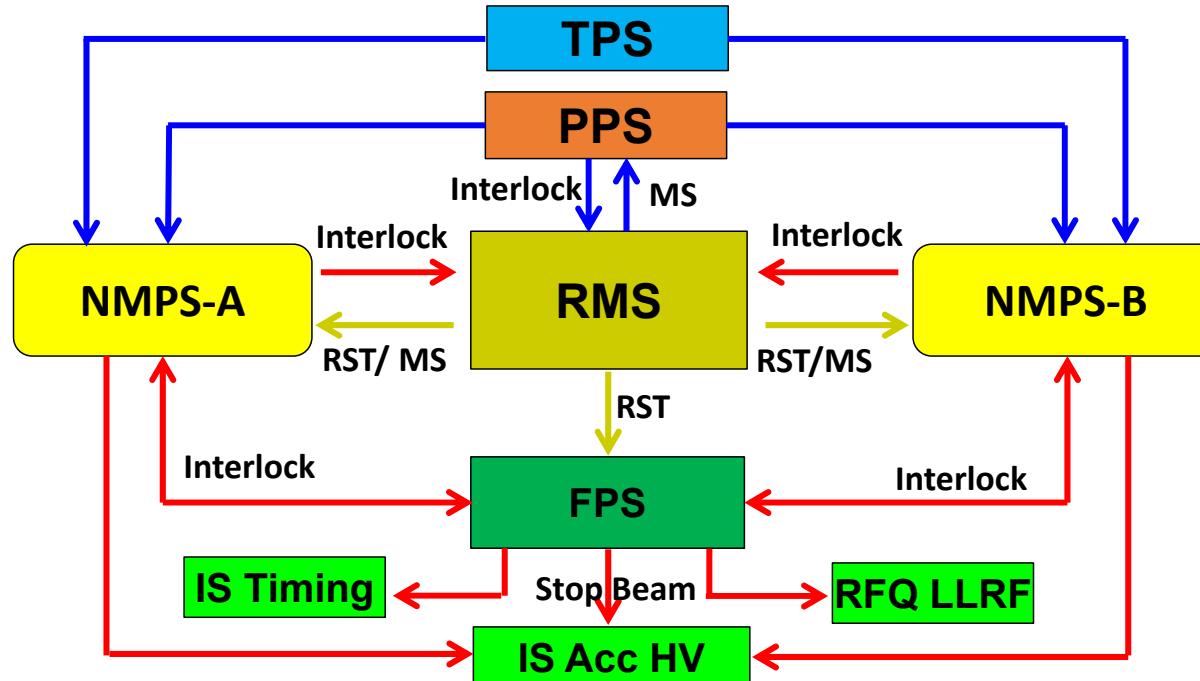


- Three independent PPS control areas
- Five beam destinations, beam power limit is different for each destination



# CSNS Protection Systems

- CSNS accelerator machine protection system consists of **NMPS (PLC-based)** and **FPS (FPGA-based)**, Normal-MPS consists of two independent systems(NMPS-A and NMPS-B)
- Both NMPS and FPS use independent cable routes to interlock beam.



MS: Machine Status

RMS: Run Management System

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Summary

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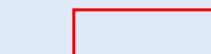
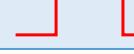
# Requirements and Design Rules for FPS



- Response time: <10μs (from receiving fault signal to switch off the H<sup>-</sup> beam)
- Performing different actions according to the input signal's type
- All interfaces should be fail-safe or online real-time checked to make sure the reliability
- Interlock logic should be as simple as possible and developed with reliable tools
- Providing software mask for each input channel and friendly operator interface to check the status of the system.

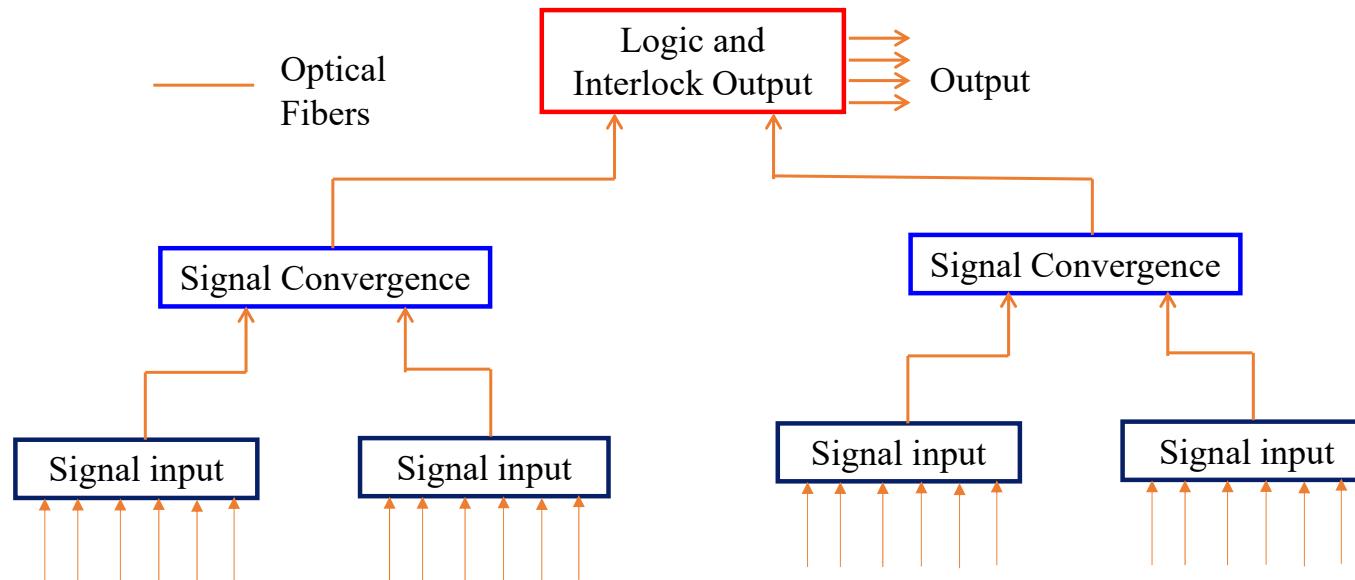
# Input Signals Classification

- All input signals can be masked or unmasked automatically based on the selected beam destination.

Input Device Name	Number of Input Signals	Input Signal Type	Inhibit Beam Next N Cycle
LEBT Chopper Power Supply	1		
MEBT Power Supply	22		
DTL Power Supply	98		
Linac RF	8	 or 	✓
Linac Beam Loss Monitor	40		✓
RCS Beam Loss Monitor	85		✓
RTBT Beam Loss Monitor	50		✓
Total	304		

# FPS Architecture

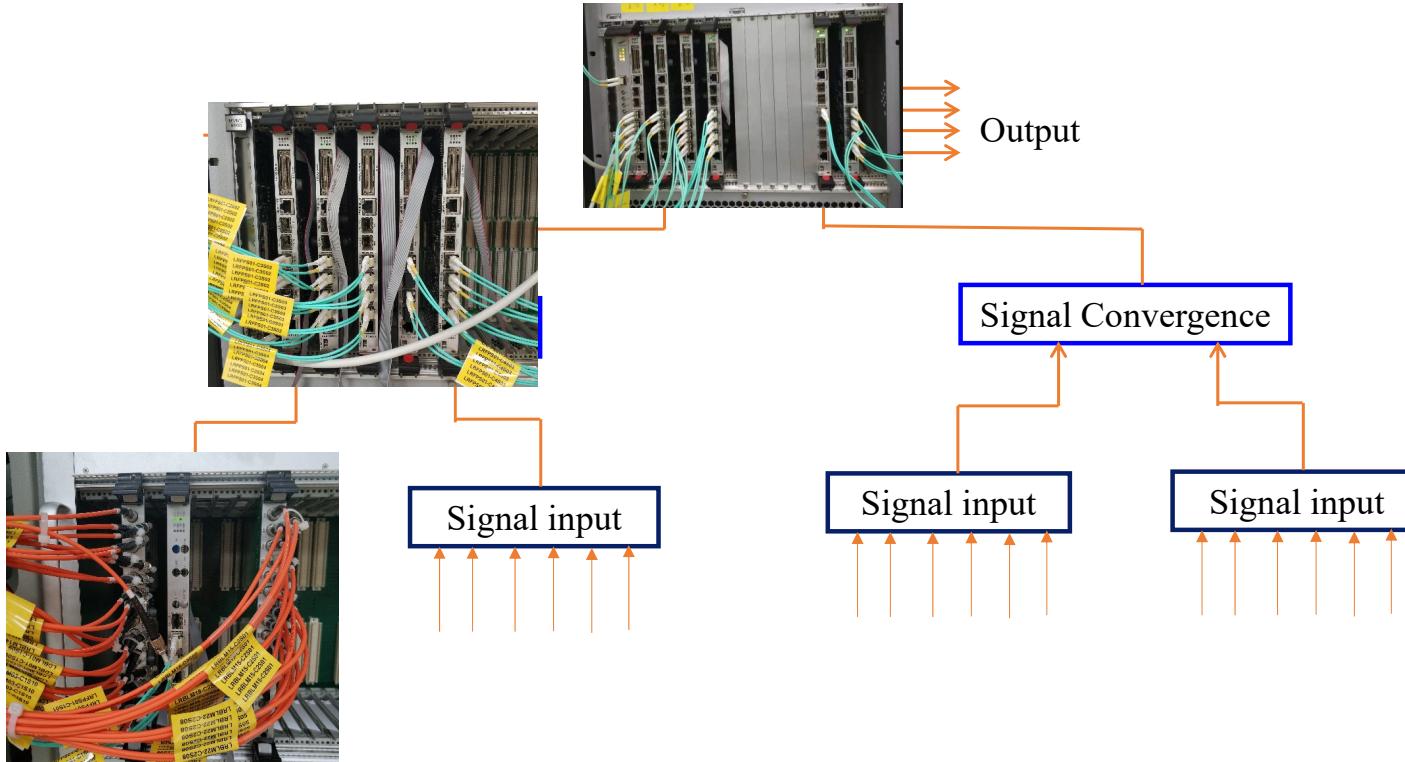
- The tree topology was adopted by FPS, consists of three layers.
- All signals are transmitted through optical fibers.



# FPS Architecture



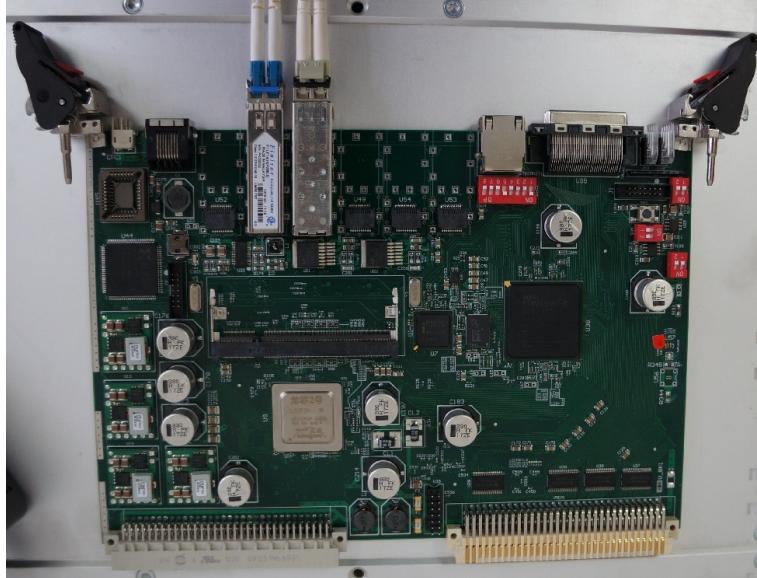
- The tree topology was adopted by FPS, consists of three layers.
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# FPS Hardware



- Main logic board: FPGA + Rocket I/O + 6U VME, with embedded EVR
- Optical signal input board: 6U VME



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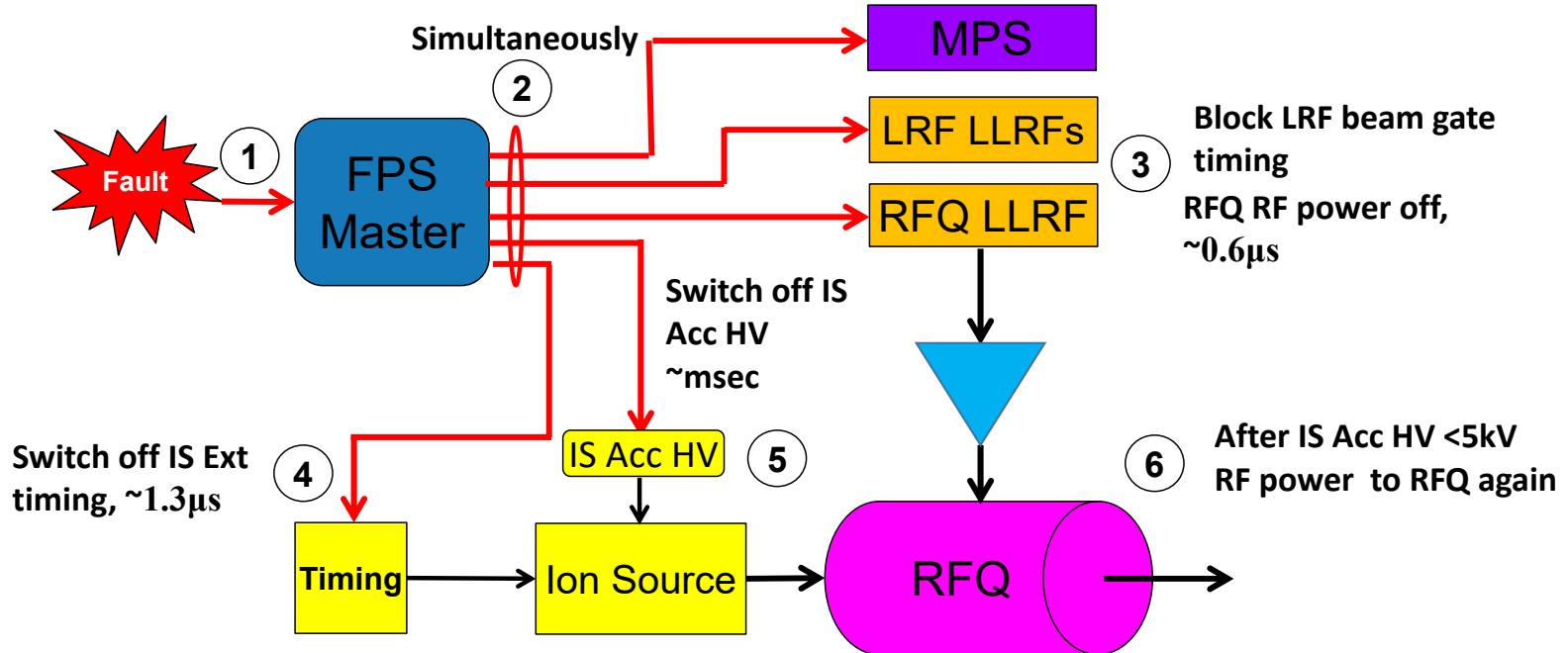
Summary

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# Actions of Shutdown of Beam



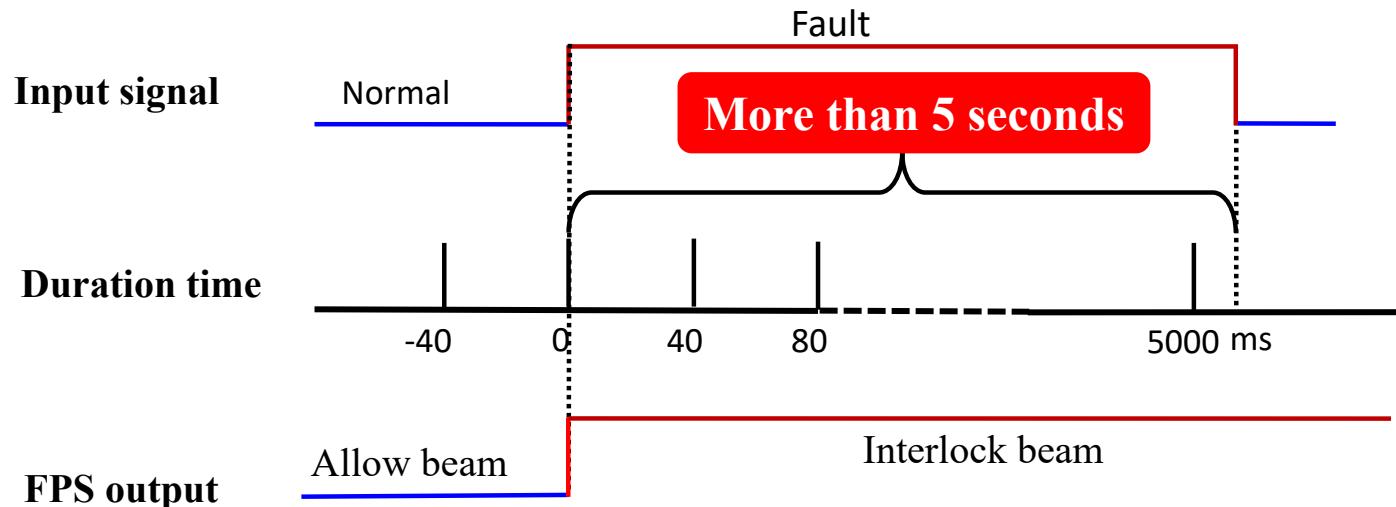
- **Case 1:** Shutdown of the beam and sending interlock signal to RMS, accelerator will switch to BEAMOFF status, beam should be **recovered manually**.



# FPS Output for Shutdown of beam



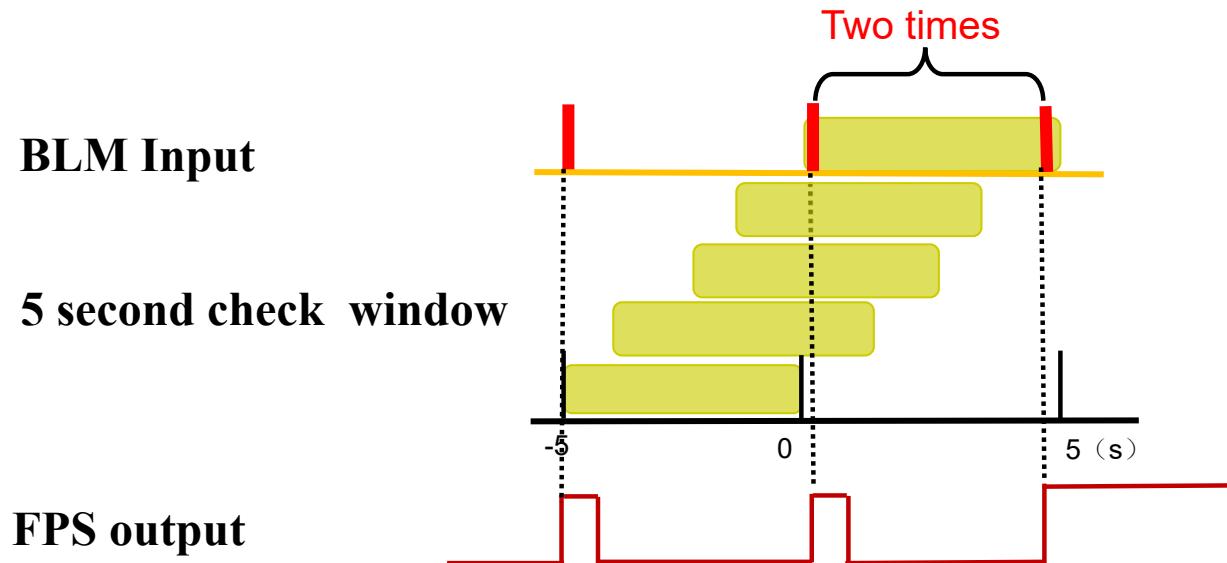
- When FPS receives a fault signal, the output switches to interlock beam immediately, if the duration time of the fault input more than 5 seconds, the output will be locked to interlock status.



# FPS Output for Shutdown of beam

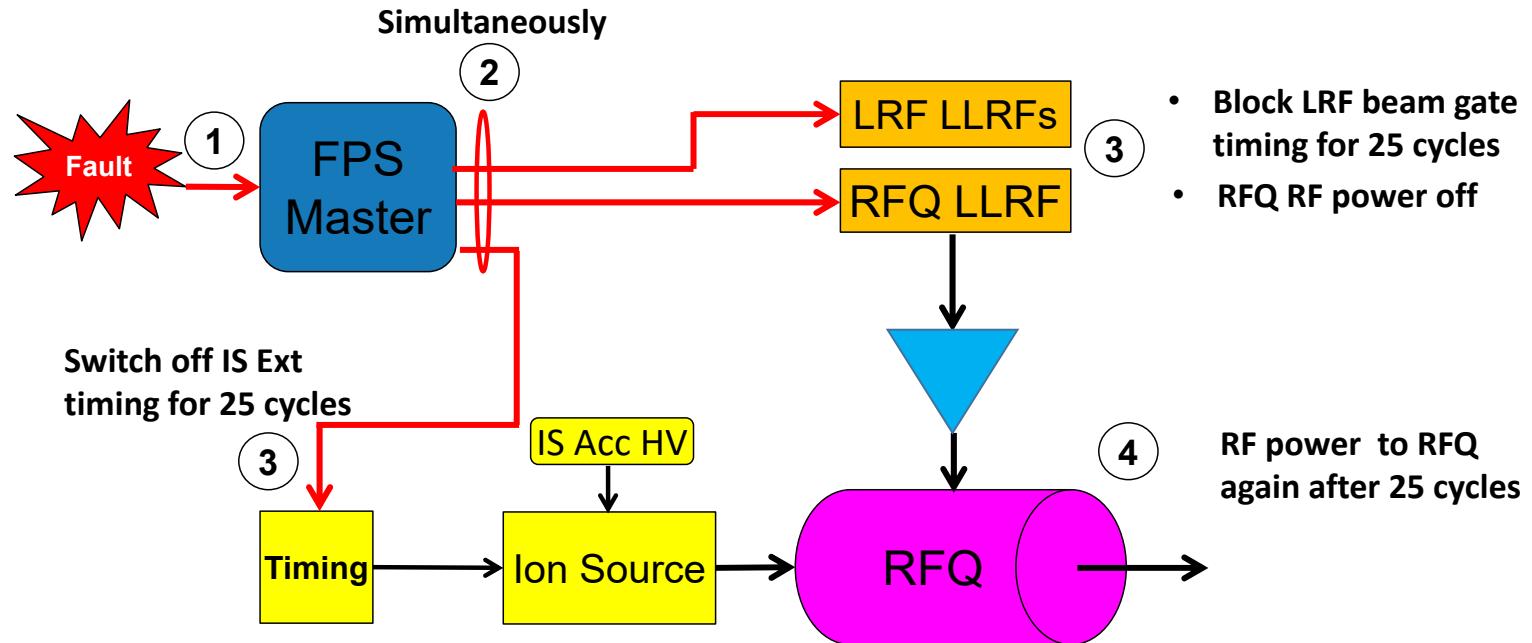


- For the BLM input signal, the over threshold signal is pulsed type.
- If the input only has one pulse in 5 seconds, the mitigation measure will be carried out, if two pulses in 5 seconds, shut down the beam will be taken place.



# Actions of Mitigation

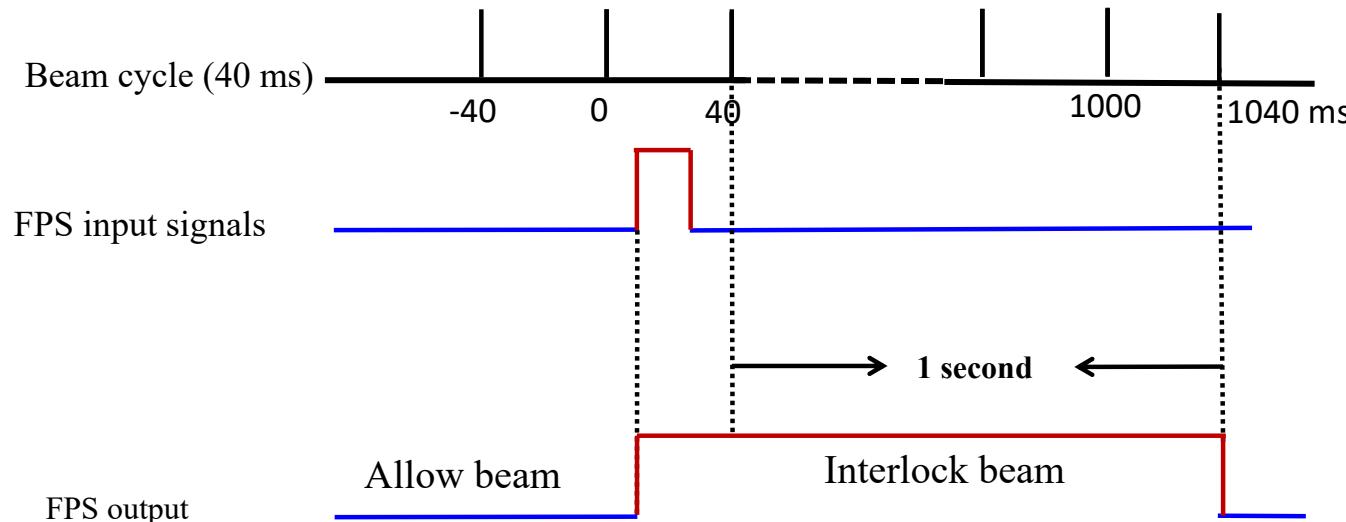
- Case 2: Inhibit the beam for the next 25 cycles and beam will be recovered automatically



# FPS Output for Mitigation

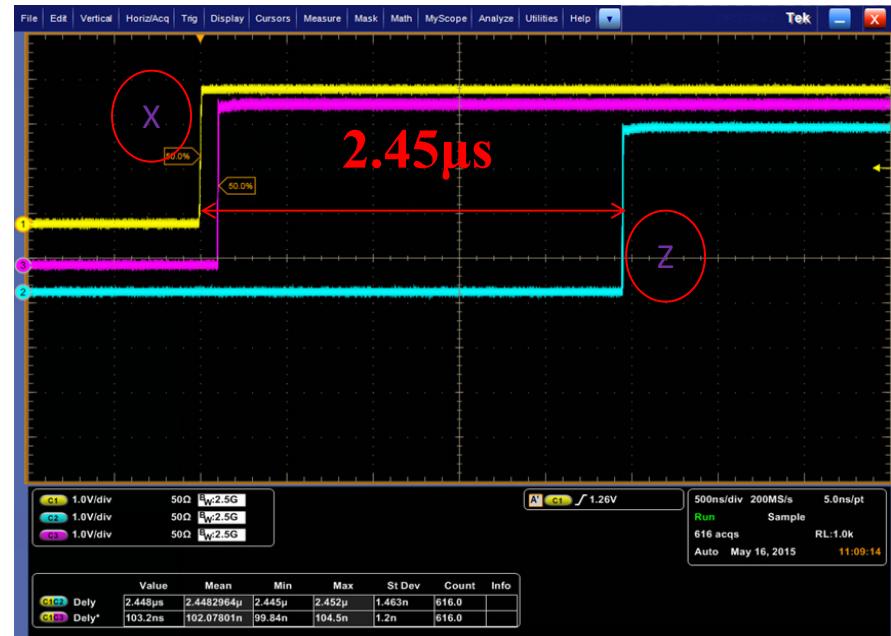
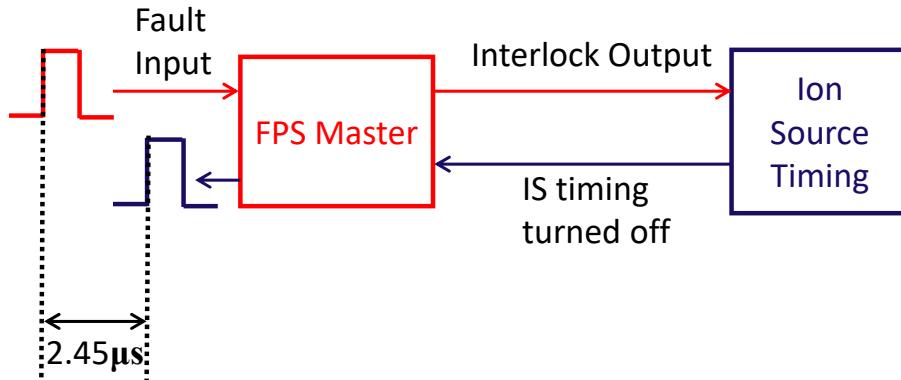


- When FPS received a fault signal, the output switches to interlock beam immediately, if the during time of the fault less 1 repetition cycle, FPS will inhibit the beam for the next 25 cycles as a mitigation measure.



# Measured Response Time

- From the FPS master receives the fault signal, to the timing trigger for ion source is turned off, the time consumption is no more than **1.3μs**



- The fast protection system for CSNS accelerator has been put into operation for more than 3 year, the beam interlock logic has improved due to operation requirements.
- The response time is much less than the requirement, and different mitigation measures has designed and implemented.
- New hardware is under design and will be upgraded in the CSNS-II project.

Thank you for your attention!

