

Bayesian Techniques for Accelerator Characterization and Control

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Bayesian Optimization Based Accelerator Control

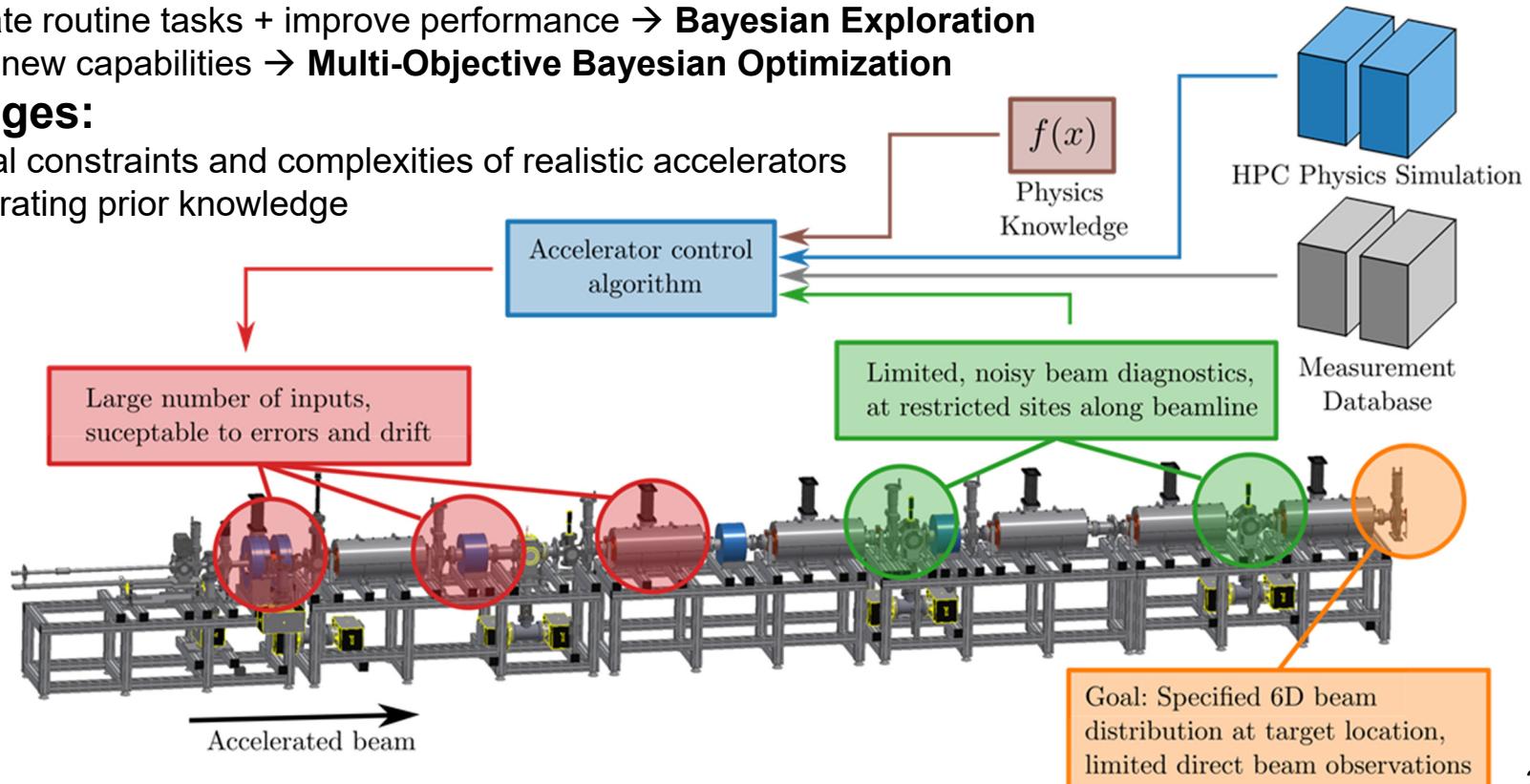
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Goals:

- Automate routine tasks + improve performance → **Bayesian Exploration**
- Enable new capabilities → **Multi-Objective Bayesian Optimization**

Challenges:

- Practical constraints and complexities of realistic accelerators
- Incorporating prior knowledge
- Scaling



Characterizing functions with Bayesian Exploration

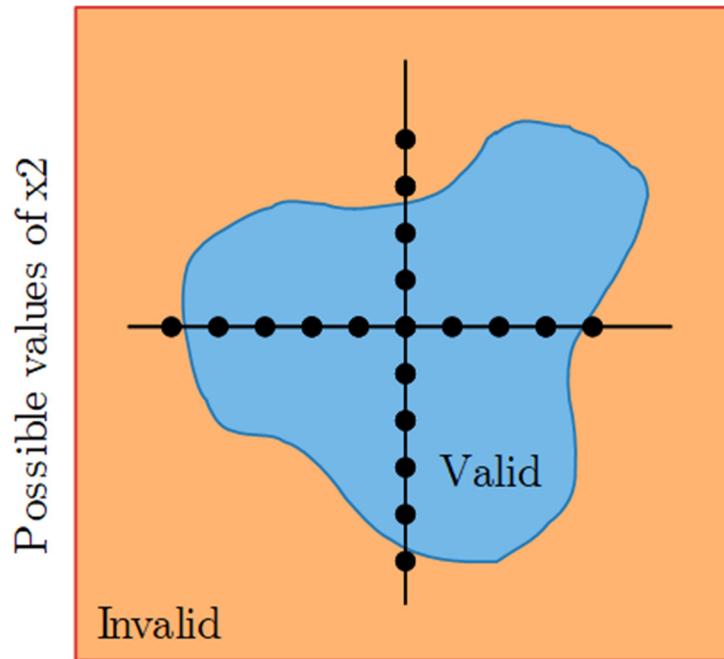
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Favorite tool of the accelerator operator: **the 1D parameter scan**

- How quickly do we expect the beam response to change? -> **need to select a step size and the # of steps**
- What is the upper and lower bound of our parameter value? -> **usually dictated by whether the beam stays on the screen / fits on the screen**
- What should be the value of the other parameters? -> **usually, a historical running point**

What do we get from this effort? **The beam response when one parameter varies**, which hopefully generalizes when other parameters are varied?

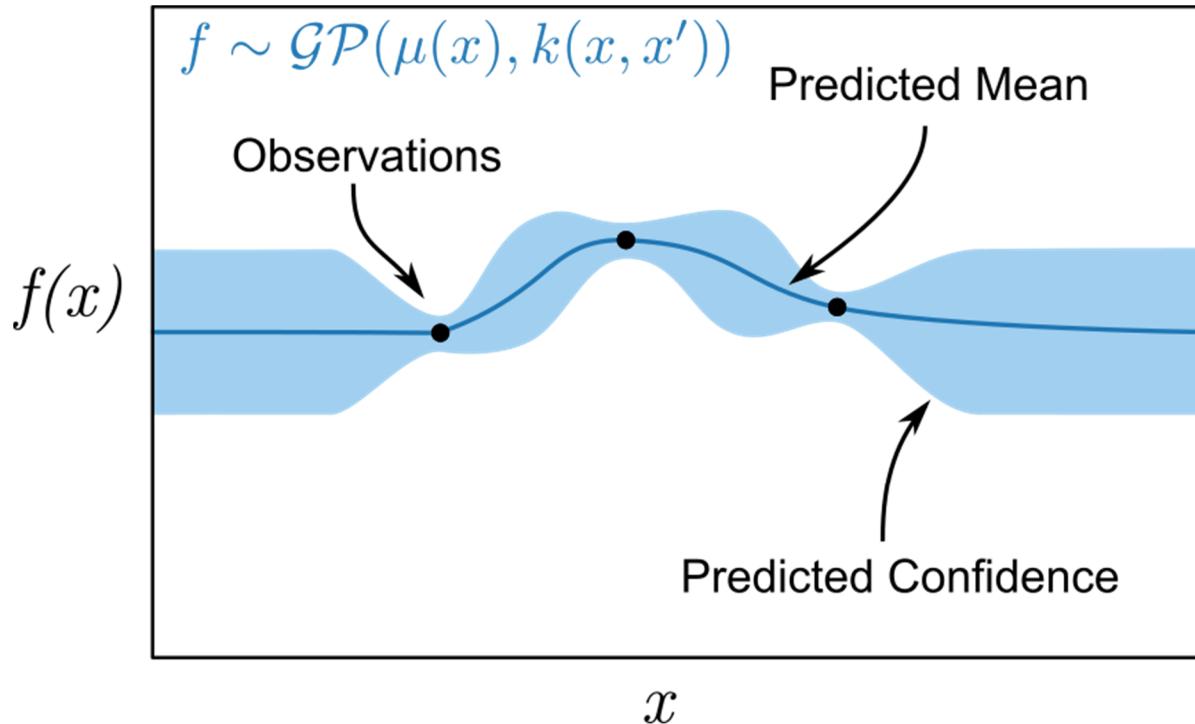
- **Works fine for a 1D system, but we exist in a many dimensional space!**



Possible values of x1

Gaussian Process Construction

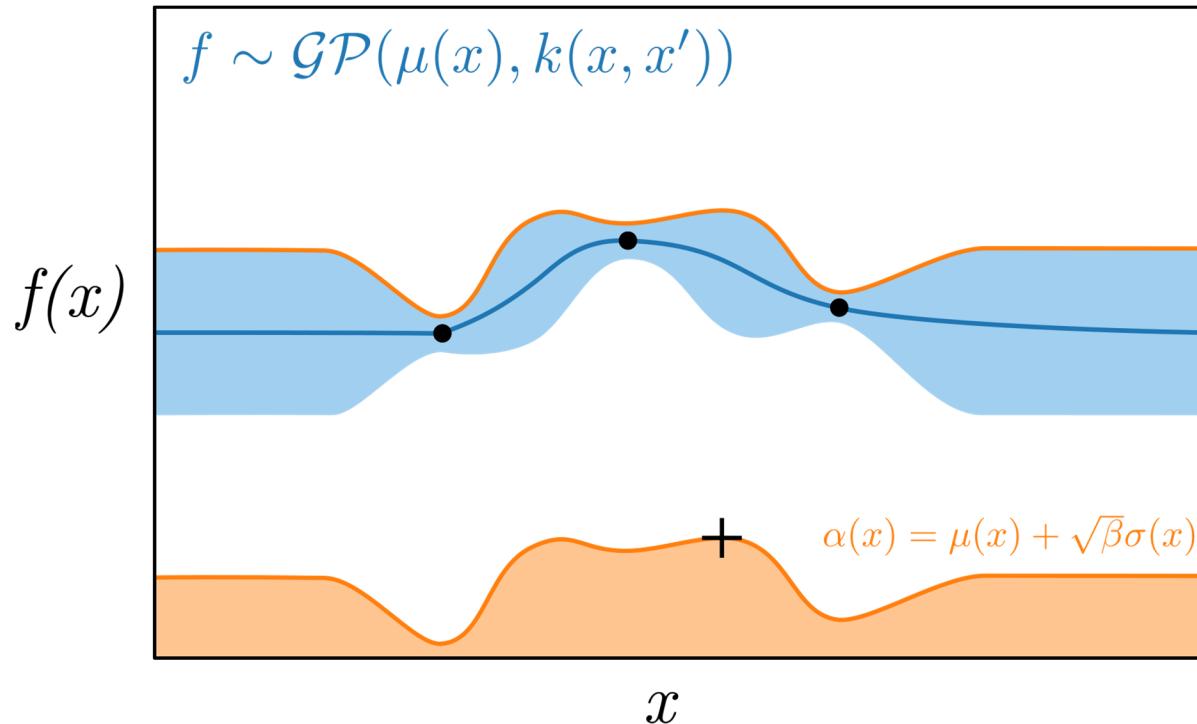
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A **kernel** encodes
high level
functional behavior

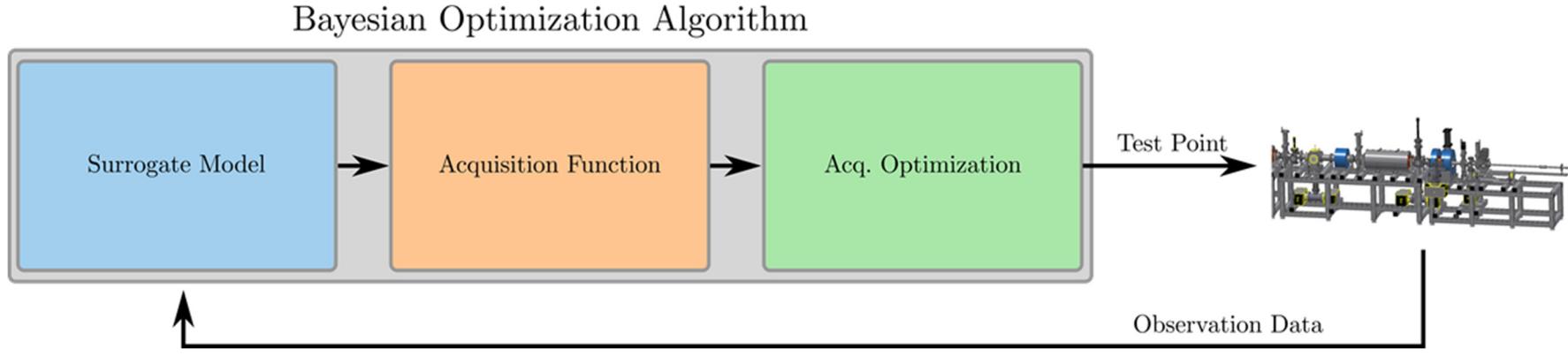
Acquisition Function

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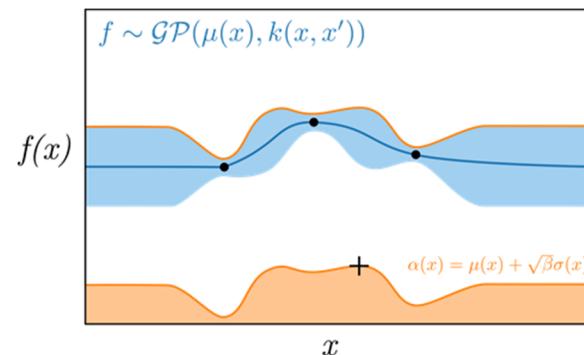
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Benefits:

- Specify trade-off between exploration and exploitation
- Inherently improves model accuracy in regions of interest
- Enables serial or parallelized optimization strategies

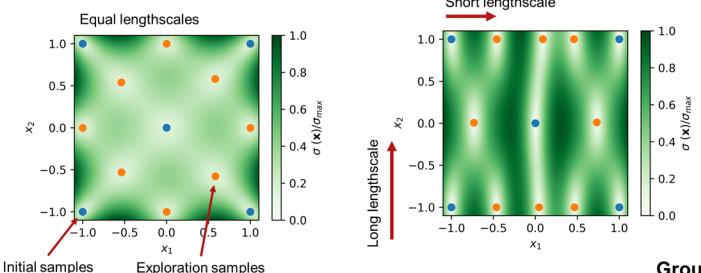


Bayesian Exploration

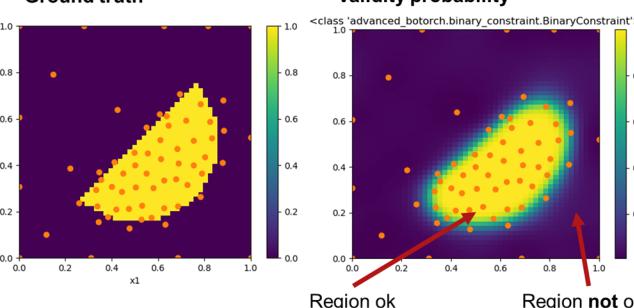
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$$\alpha(x) = \sigma(x) \prod_{i=1}^N p_i(g_i(x) \geq h_i) \Psi(x, x_0)$$

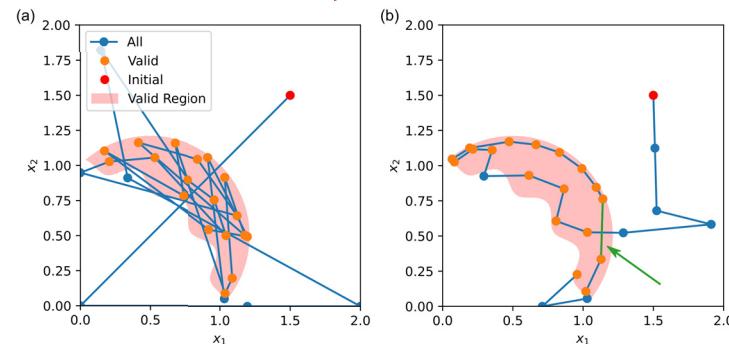
Adaptive sampling



Unknown constraints



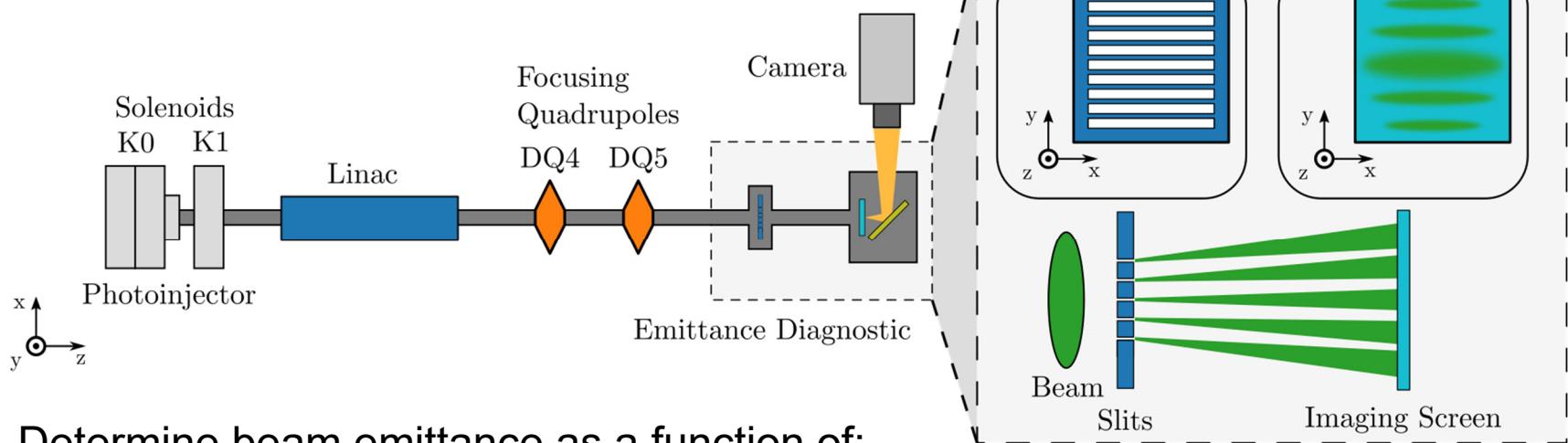
Proximal biasing



Roussel et. Al. *Nat. Comm.* 2021

Characterizing Photoinjector Emittance at AWA

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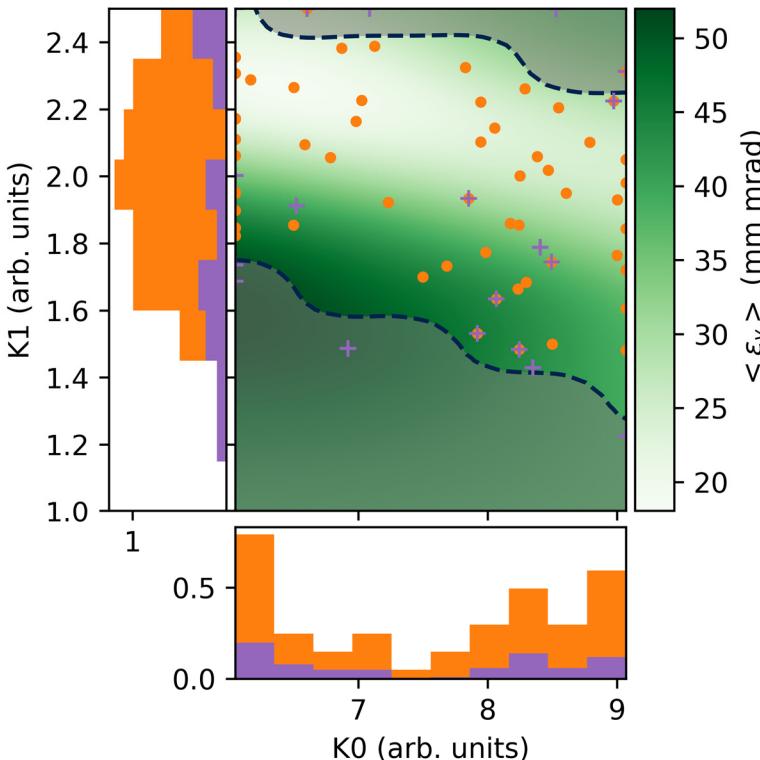
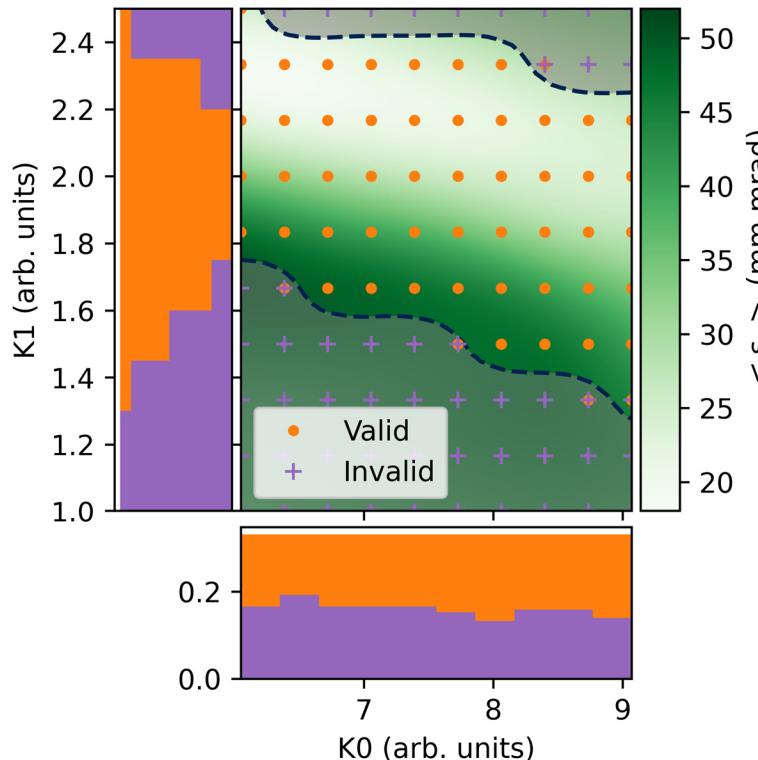


Determine beam emittance as a function of:

- 2 solenoids
- 2 quadrupoles

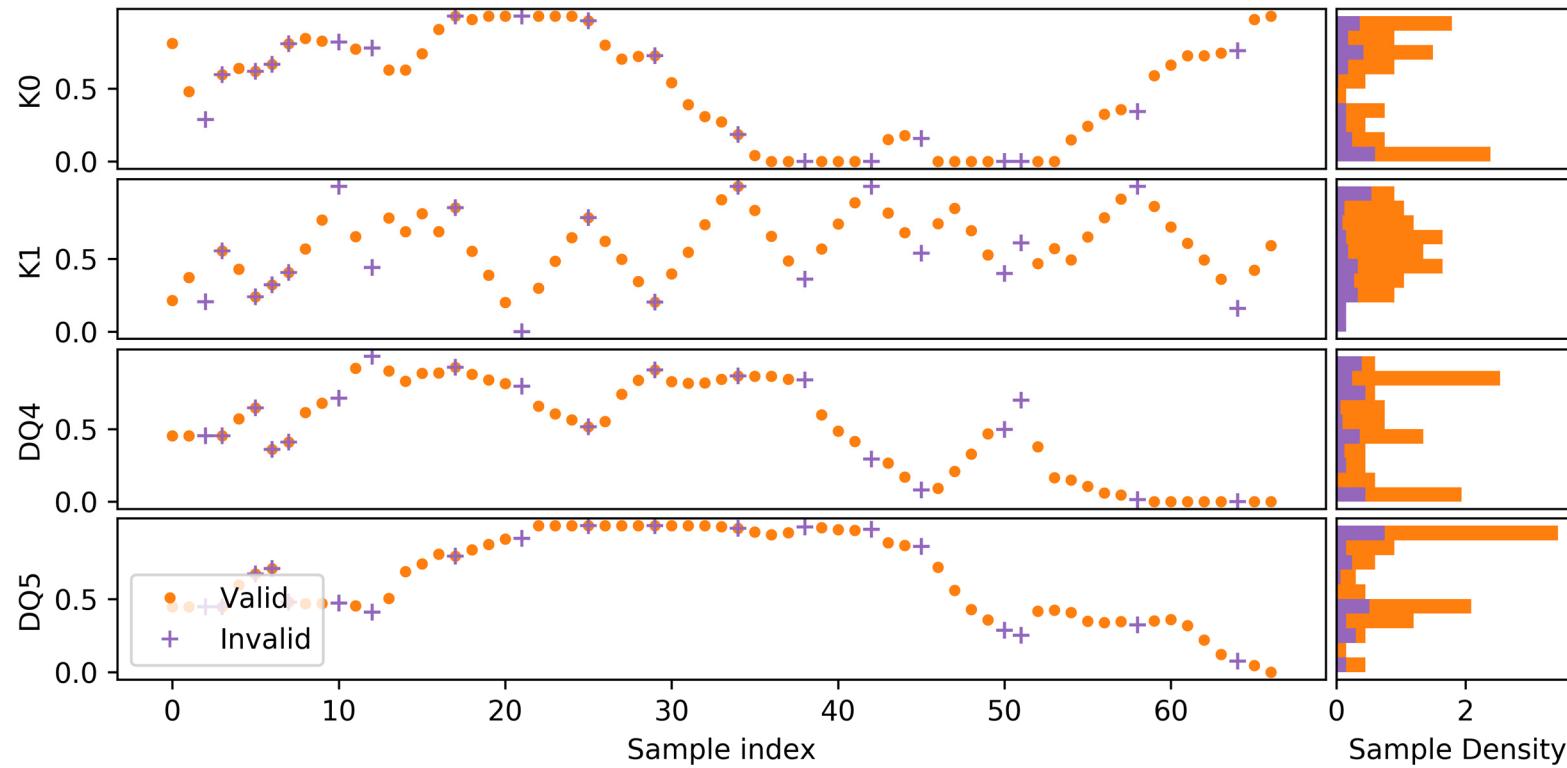
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Characterizing Photoinjector Emittance at AWA

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Multi-Objective Bayesian Optimization



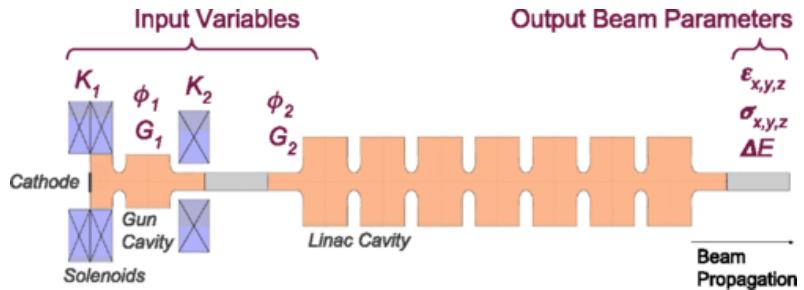
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Multi-Objective Photoinjector Optimization

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For online photoinjector optimization we wish to simultaneously:

- Minimize **emittances** (3x)
- Minimize **bunch sizes** (3x)
- Minimize **energy spread** (1x)

7 objectives

Tuning knobs:

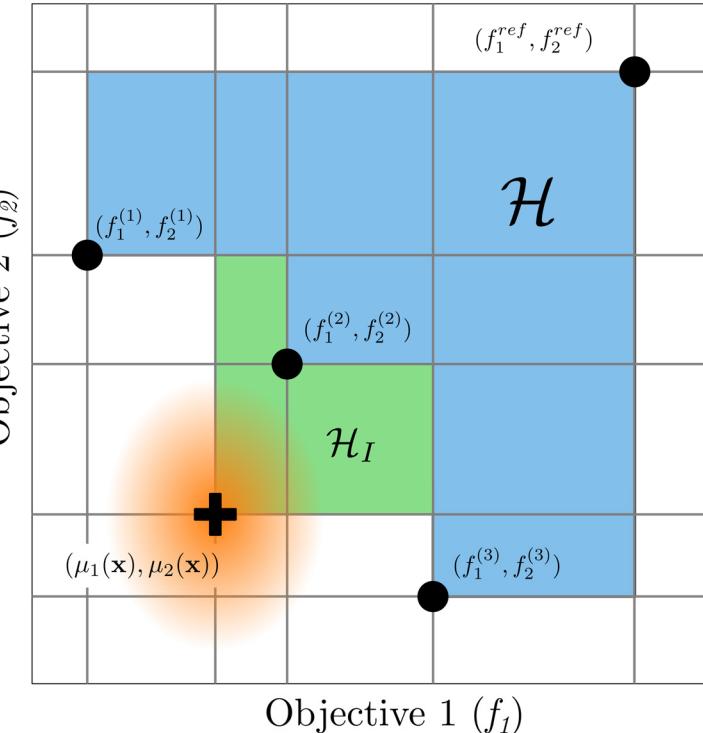
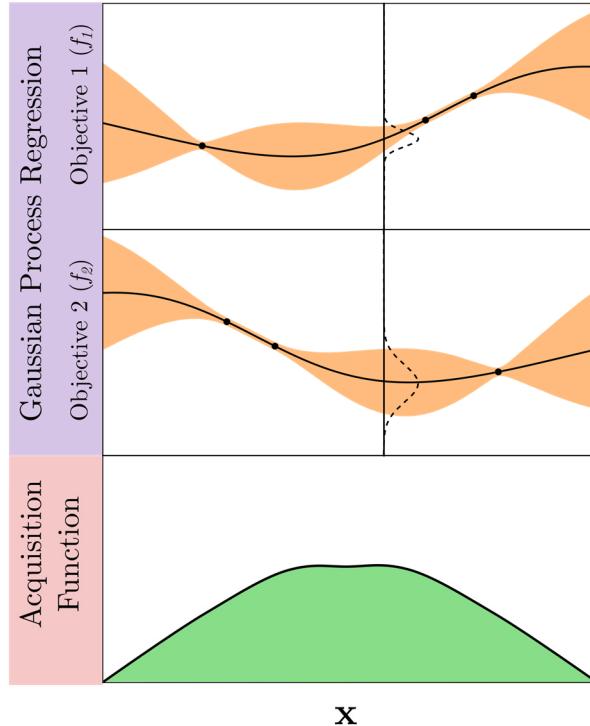
- Solenoid strengths (**2x**)
- RF Amplitudes (**2x**)
- RF Phases (**2x**)

6 input parameters

Expected Hypervolume Improvement

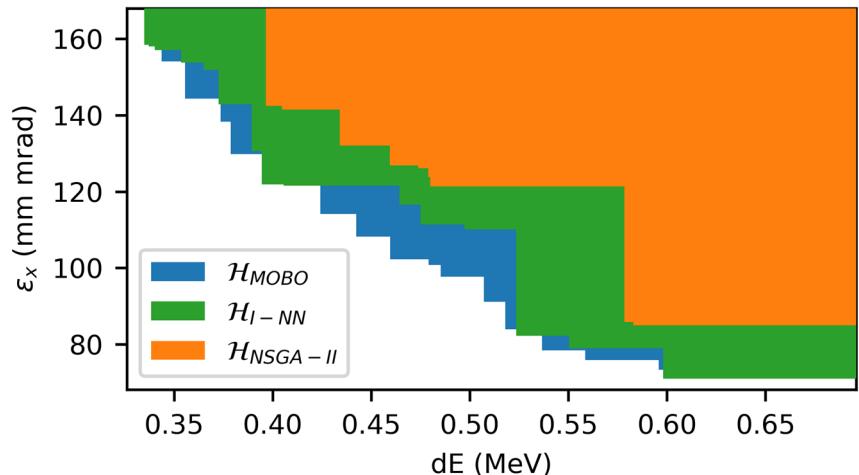
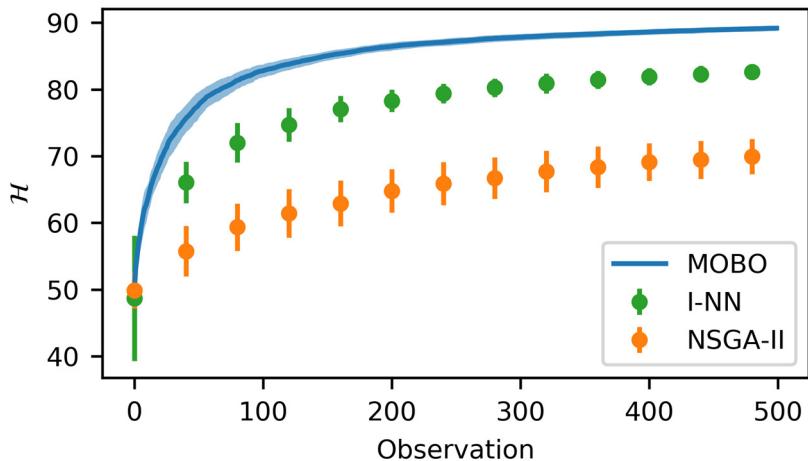
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This allows us to find the Pareto front with a **small number of measurements in serial**, unlike genetic or swarm optimization methods



Simulated Photoinjector Optimization

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- 10 optimization runs
- 20 initial points each
- Peak hypervolume using < 500 observations (NSGA-II $\sim 17.5k$)
- factor of 35x speedup, tuned in < 45 mins!

Xopt – Flexible Optimization in Python

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Flexible implementation of advanced optimization algorithms in python

- Requires only a single python script to evaluate
 - Available algorithms:
 - Bayesian exploration
(*Nat. Comm.* **12**, 5612 (2021))
 - Multi-objective Bayesian optimization
(*PRAB* **24**, 062801 (2021))
 - Multi-fidelity Bayesian optimization
 - Continuous NSGA
 - Serial and parallel optimization using python threading, MPI etc.
 - Used on HPC systems (NERSC)
 - Used for real-time control at AWA
- <https://christophermayes.github.io/Xopt/>

```
xopt:
    output_path: null

algorithm:
    name: cnsga
    options:
        max_generations: 50
        population_size: 128
        crossover_probability: 0.9
        mutation_probability: 1.0
        selection: auto
        verbose: true
        population: null

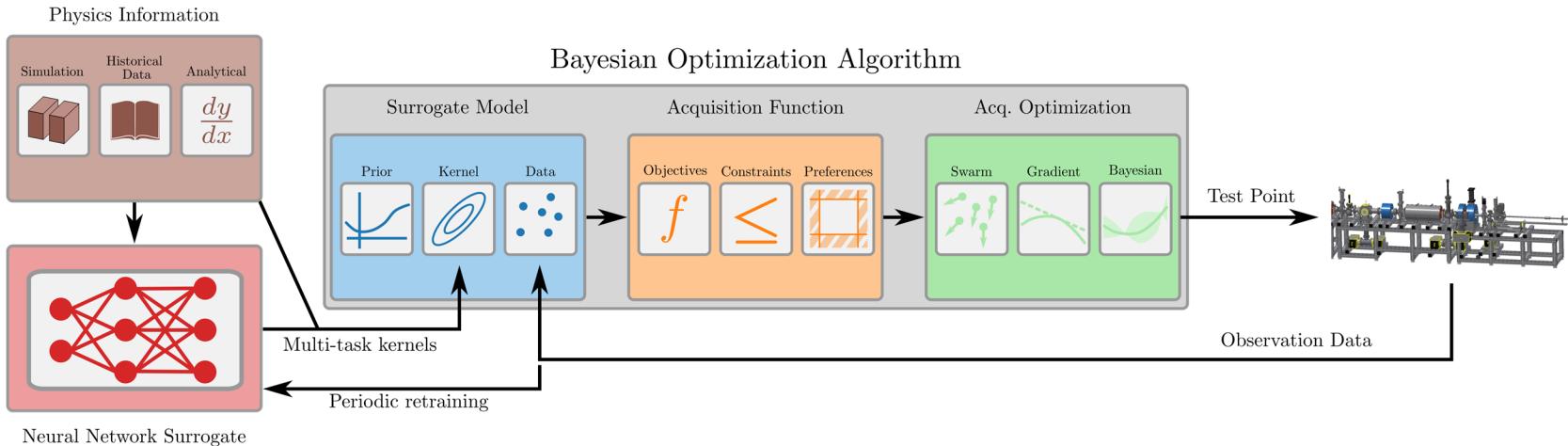
simulation:
    name: test_TNK
    evaluate: xopt.tests.evalutors.TNK.evaluate_TNK

voocs:
    variables:
        x1: [0, 3.14159]
        x2: [0, 3.14159]
    objectives:
        y1: MINIMIZE
        y2: MINIMIZE
    constraints:
        c1: [GREATER_THAN, 0]
        c2: [LESS_THAN, 0.5]
    linked_variables:
        x9: x1
    constants:
        a: dummy_constant
```



Conclusion

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Bayesian exploration and hysteresis modeling represent steps towards a unified characterization and control system for accelerators