WEPV016

THE AUTOMATIC LHC COLLIMATOR BEAM-BASED ALIGNMENT SOFTWARE PACKAGE

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Align

num_spikes = 0

Select Threshold & Align Both jaws

Alignmer spike?

Select Threshold

& Align jaw 1

Alian

Alignment campaign

Select Threshold & Align law 2

num spikes ++

m_spikes

Aligned

Introduction

- Collimation system protects LHC.
- 100+ collimators, each made of 2 jaws inside a vacuum tank.
- Alignment campaigns required to set-up the collimation hierarchy.
- 30% of collimators have embedded Beam Position Monitoring (BPM) pick-up buttons
 - BPMs directly measure the beam orbit at the collimator.
- All collimators have Beam Loss Monitoring (BLM) devices installed downstream, outside the beam vacuum.
- BLMs detect losses when halo particles impact the jaws. A spike in the losses indicates the reference halo was touched.

Beam-based Alignment (BBA) with BLMs

Reference collimator aligned with collimator to create reference halo.

Start

Select Beam b (Beam 1, Beam 2)

Select Plane p

(Horizontal, Vertical, Skew

- The collimator jaws are moved towards the beam in steps of 5-20 µm whilst monitoring the BLM signal recorded in the collimator's respective BLM.
- The BBA allows to infer the local orbit position and the relative opening w.r.t. the primary collimator, to establish the collimation hierarchy. Stop

All plane

All collimator aligned?

Re-align TCPba Left & Right onc

Collimators from the 2 beams can be aligned in parallel. Cross-talk must be considered, i.e.



GUI Application Communication

| FESA Class Property | States | Definition |
|---------------------|----------------------|--|
| Auto status | -1, 0, 1 | Alignment: (error, paused/stopped, ongoing) |
| Align status | -3, -2, -1, 0, 1, 2 | Parallel: (ongoing, done), Ignore, Collimator alignment: start, done, done + saved |
| Parallel status | -1, 0, 1, 2, 3, 4, 5 | Deadlock, Ignore, Wait: (crosstalk, parallel, pause, TCP alignment, change collimator) |
| Parallel message | - | Any message to display in GUI |
| TCP status | -4, -3, -2, -1, 0, 1 | Before collimator: (not aligned, aligned), Aligned before parallel, Ignore, Aligning: (before, after coll) |
| Collimator status | - | Name of collimator ongoing alignment |
| Jaw status | -1, 0, 1, 2 | Ignore, Aligning: (first jaw, second jaw, both jaws) |
| Spike class | -2, -1, 0, 1 | Ignore, Error, No spike, Spike |

Software Architecture

- 3-tier structure (see Figure)
- The hardware is abstracted and controlled through FESA (Front-End Software Architecture)
- The control system communicates with FESA through devices.
 - FESA devices are typically abstractions of the hardware, grouped into a FESA class.
- · The Java Swing GUI applications interact with the FESA class through the available Java API

| | FESA class | | |
|--------------|----------------------------|-----|-------------|
| Hardware GET | Acquisition Property - | _ | <u>Java</u> |
| device 1 | | GET | Display |
| | Setting Property | | Button |
| Hardware | - Configuration Property + | SET | Button |
| device 2 SET | | | |

Available Features

- The software was designed to:
 - Be autonomous and efficient.
 - Independently "make decisions"
 - in real-time based on the status. o Imitate users as much as possible. using "smart" features.
 - Ensure the correct alignment.
- The "smart" features include:
- Equal priority for collimators from the two beams
- Limit the overall waiting time. Reacting to user interrupts.

Implementation

- The fully-automatic alignment is implemented in a dedicated FESA class -CollAlignSupervisor.
- It relies on the automation of 3 main components:
 - Collimator selection for parallel alignment avoiding cross-talk.
 - BLM threshold selection to stop collimators moving towards the beam.
 - Spike classification using supervised machine learning to classify between alignment spikes and spurious spikes.

These 3 components are developed as individual modules, independently available for any improvements.

GUI Usability

- New options introduced:
- Subsets of collimators in the list can be further grouped for alignments.
- Collimators can be manually removed from the list during the alignment and re-added at a later stage.
- Pre-set collimator subsets for alignments available.
- Closing the application is an automatic stop if anv alignment is ongoing



- · Only 2 collimators can be aligned in parallel, 1 per beam (shared reference and cross-talk).
- The FESA class is assigned 2 devices, to run 2 instances of the software in parallel, i.e. 2 threads.
- Each thread communicates:
- The beam/plane being aligned.
- The reference collimator status. i.e.: moving/waiting status.
- The current collimator ongoing alignment, for cross-talk purposes
- The global wait status, i.e. if any thread is waiting for an action from the other thread.

Alignment Outlook

- New alignment configurations accessible and feasible:
- o Angular alignments for tighter collimator settings
- o Anv combinations of collimators can be aligned efficiently with minimal effort.
- Subsets of collimators can be aligned more frequently during operation.
- Dedicated collimator configurations e.g. ion beams no longer bound to identical setups as with protons.



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- The BBA allows to infer the local orbit position and the relative opening w.r.t. the primary collimator, to establish the collimation hierarchy.
- Collimators from the 2 beams can be aligned in parallel.
- Cross-talk must be considered, i.e. when losses generated by a collimator are detected by multiple BLMs around the LHC.



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