## **MOPV005**

# TOWARDS A NEW CONTROL SYSTEM FOR PETRA IV



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<u>Control</u> <u>System</u> <u>Framework</u> <u>Graphical</u> <u>User</u> <u>Interfaces</u>	<ul> <li>PETRA III:</li> <li>2300-metre-long storage ring feeding 24 user beamlines</li> <li>Operated either in brightness mode (480 equally distributed bunches, 120 mA stored beam) or in timing mode (40 equally distributed bunches, 100 mA stored beam)</li> <li>Research groups from all over the world use the particularly brilliant, intense X-ray light for a variety of experiments - from medical to materials research</li> </ul>	<ul> <li>PETRA IV:</li> <li>High-resolution 3D X-ray microscope for chemical and physical processes</li> <li>Will extend the X-ray view to all length scales, from the atom to millimetres</li> <li>Offers outstanding possibilities and optimal experimental conditions for industry</li> <li>Will replace PETRA III, but keeping the existing experimental halls</li> <li>An additional experimental hall will provide space for additional 18 user beamlines</li> <li>New booster synchrotron DESY IV</li> </ul>	Data Acquisition and Archiving High-Level Control Applications
Hardware Interfaces	<ul> <li>From PETRA III to PETRA IV:</li> <li>Preparatory phase: 2020 – mid 2023 → Technical Design Report</li> <li>Construction: Expected to begin in early 2026</li> <li>Commissioning: In 2028</li> </ul>		<u>Quality</u> <u>Assurance</u>





## **Control System Framework**

- Distributed Object-Oriented Control System (DOOCS)
  - Architecture: Distributed client-server, combined with a device-oriented view
  - Transportation layer: Standardized, industrial RPC protocol
  - Implementation:
    - Server: C++
    - Client: C++, Java, Python or MATLAB
  - Device interface: Variety of fieldbus and hardware interfaces via device classes
  - Development history:
    - Started in 1993
    - Is constantly updated to meet the needs of users and keep pace with developments in IT technologies
  - Interoperability: Client API provides access to

#### e.g.

- EPICS (facility control system at DESY)
- TANGO (beamline control system at PETRA)

#### **Graphical User Interfaces**

- Java DOOCS Data Display (JDDD):
  - Tool of choice for the standard beam operation as well as operating technical accelerator devices and systems
  - Thin-client approach with a functional and rich set of widgets
  - Individual UI components can be easily created through a versatile editor IDE without the knowledge of any programming language
- Python:
  - Tool of choice for rapid prototyping and visualization of scientific procedures and data
- Progressive Web Apps (PWA):
  - Multi-platform, browser-based applications with a look-and-feel of versatile classical desktop applications
  - Based on React JavaScript framework
  - Under investigation

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#### **Hardware Interfaces**

- Interfaces for Triggered, High-Performance Applications:
  - Compliant with <u>MTCA.4 technology</u>
  - Linux
  - Remotely manageable
  - Specific modules, e.g.
    - Timing:
      - Beamline experiments can make use of the same timing system hardware
    - Digital I/O:
      - e.g. for beam diagnostics / control
- Interfaces for Conventional Slow-Control Applications:
  - Compliant with industrial process control standards
  - Generic bridge server available for, e.g.:
    - OPC UA servers
    - Beckhoff controller
    - Classical PLC

## **Data Acquisition and Archiving**

- *Implemention:* Domain-specific interface standards and technologies.
- Data:
  - Time series data:
    - Fast data streams in synchronism with the beam revolution frequency (130 kHz), e.g. single-turn orbit data
    - Slow data stream updated asynchronously with less than 100 Hz, e.g. multi-turn orbit data or magnet currents
  - Snapshot data:
    - Measured and stored once
    - Triggered by e.g. value changes, specific events, operator requests, ...
- Versatile visualization and analysis tools:
  - Particular emphasis will be placed on the capability to support data science applications (e.g. learning feedbacks, failure prediction)

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## **High-Level Control Applications**

- HLC Team:
  - Controls experts and accelerator physicists
  - Interfaces specific needs of beam commissioning and operations and implements corresponding tools and applications
- MATLAB Middle Layer Library Suite:
  - Supplemented by procedures developed for PETRAIII operation
  - Will be adapted for further use at PETRA IV
- Machine Learning:
  - Novel control concepts for PETRA IV are being developed and tested at PETRA III
- Virtual PETRA Accelerator:
  - Similar to Virtual European XFEL Accelerator
  - Will be used to test new concepts, enhancements or just modified and improved applications before they will be put into the field

#### **Quality Assurance**

- Quality Assurance Measures:
  - Issue and bug tracking workflow:
    - Existing workflow has been revised
  - Requirements Management:
    - Template has been worked out to document the requirements
    - Requirements will be regularly reviewed and adapted if needed
  - Training courses for application developers, e.g.:
    - Application software development, graphical user interface design, software testing etc.
- Configuration Management:
  - Includes all software and hardware components
  - During all stages of the PETRA IV life cycle
  - Implementation, e.g.
    - Configuration management data base
    - Well-defined workflows and processes for change and release management

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## Contact

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