

Porting VME-Based Optical-Link Remote I/O Module to a PLC Platform

- an Approach to Maximize Cross-Platform Portability
Using SoC

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Outline

- Background
 - Optical-linked remote I/O system
 - Platform consideration
- Development of module
 - Design policy
 - Hardware implementation
 - Software implementation
 - Implementation of FPGA logic
- Summary



Background

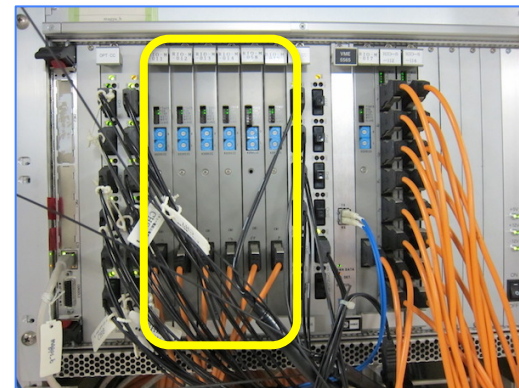
- VME
 - employed at SPring-8 as FE computers.
- Optical-linked Remote I/O systems
 - utilized to cover widely distributed accelerator equipment.
 - consist of **VME-based** master boards and several kinds of slave boards.
 - two types of optical-linked remote I/O system
 - *RIO system*
 - *OPT-VME system*



Background

- *RIO system*
 - developed by Mitsubishi Electric Co.
 - used since 1997, already **discontinued**.
 - employ **over 1,400 slave boards** in SPring-8.
 - mainly for SR magnet power supplies control.
 - many of them can be replaced with *OPT-VME system*.
 - developed the compatible slave boards.

RIO Master boards



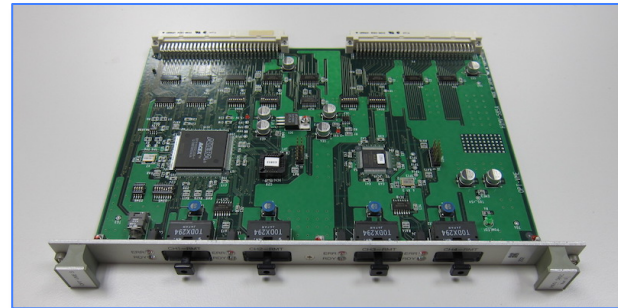
RIO Slave boards



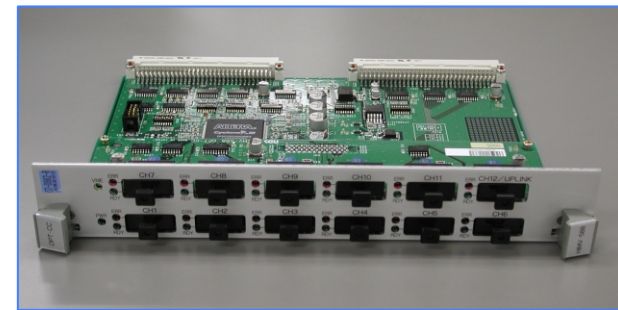
Background

- *OPT-VME system*
 - developed by SPring-8 at 2001.
 - two types of **VME-based** master boards.
 - OPT-VME
 - OPT-CC

OPT-VME: 4ch single-slot VME board



OPT-CC: 12ch dual-slot VME board



Background

- *OPT-VME system*
 - developed by SPring-8 at 2001.
 - two types of **VME-based** master boards.
 - OPT-VME
 - OPT-CC
 - employ **over 400 slave boards** in SPring-8.
 - 10 types of slave boards are available.

a kind of slave board

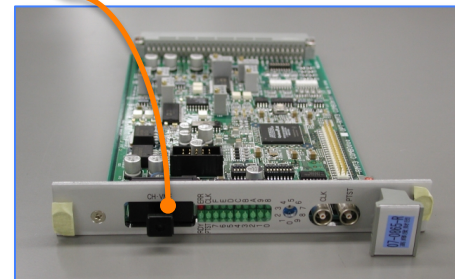
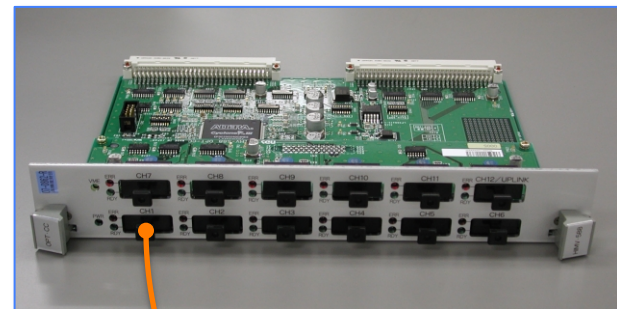


Used for steering magnet PSs control at the booster ring.



Background

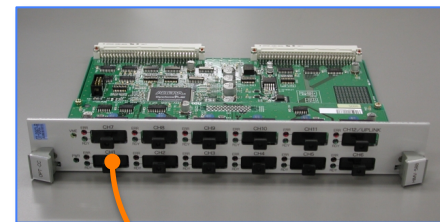
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 - developed by SPring-8 at 2001.
 - two types of **VME-based** master boards.
 - OPT-VME
 - OPT-CC
 - employ **over 400 slave boards** in SPring-8.
 - 10 types of slave boards are available.
 - original communication protocol (OPT-Protocol 2006)
 - Only support point-to-point connection.



Background

- *OPT-VME system*
 - OPT-CC
 - also available in the relay-mode.
 - max. 132 slave boards can be controlled from a master.

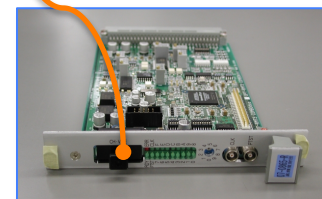
OPT-CC: *master mode*



OPT-CC: *relay mode*

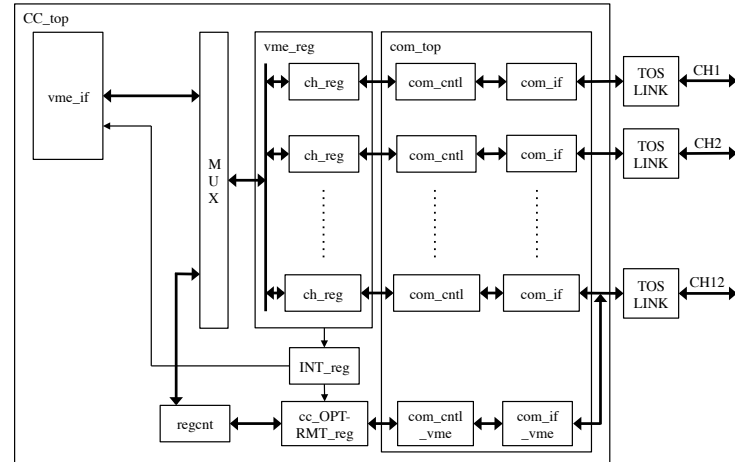


slave board



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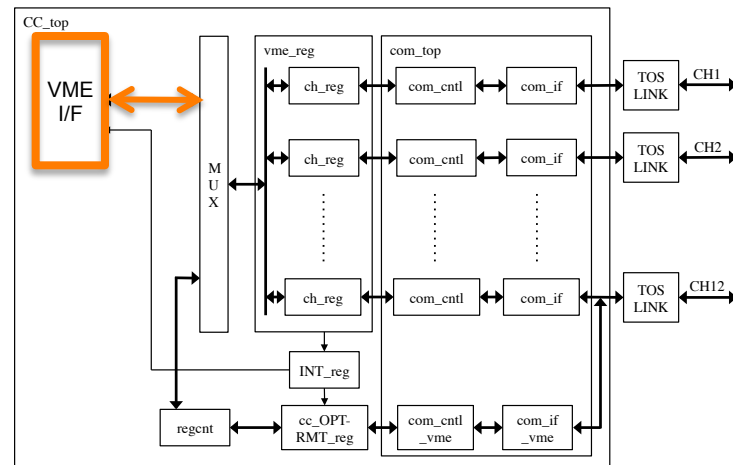
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In a master mode



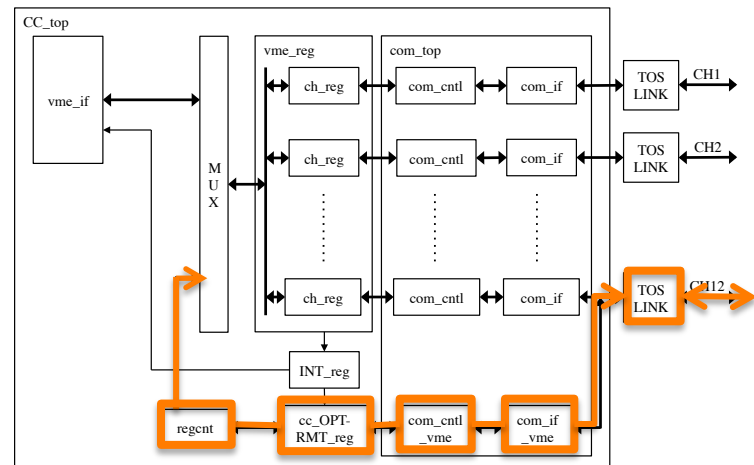
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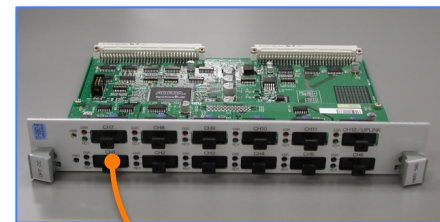
In a relay mode



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 - communication procedure with the remote slave board is **implemented in the device driver** for the master board.

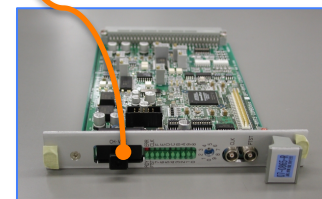
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slave board

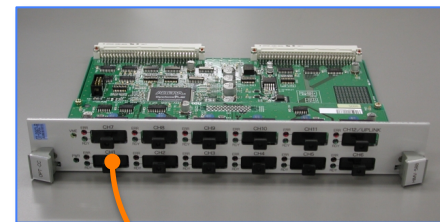


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The device driver is responsible for the high-level communication procedures including the remote slave control.

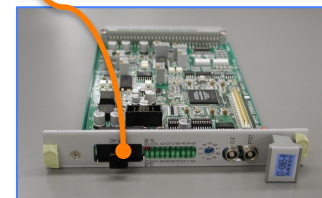
OPT-CC: *master mode*



OPT-CC: *relay mode*



slave board



Platform Consideration

- **VME**

- Passed over 30 years, become out-of-date.
 - Two major issues;
 - Lack of bandwidth.
 - **Discontinued the de-fact standard bus-bridge chip *Tsi148*.**
- *This has been a big problem for VME users.***

- considering the next-generation alternative platform.



Platform Consideration

- **MTCA.4**

- Decided to introduce MTCA.4 **as a high-end platform**.
- Analog-based old SR LLRF system controlled by VME is planed to be replaced with MTCA.4-based digital LLRF system.



Platform Consideration

- MTCA.4
 - Decided to introduce MTCA.4 as a high-end
 - Analog-based old SR LLRF system controlled by VME is planed to be replaced with MTCA.4-based digital LLRF system.
- **Linux PLC (Programmable Logic Controller)**
 - one of the candidate to **cover a low-end side**.
 - e.g. e-RT3 (FA-M3) by Yokogawa Electric Co.
 - already applied as front-end computers in both SPring-8 and SACLA.



Background

- Developed the new master module of the OPT-VME system based on the e-RT3 platform.
 - To effectively utilize the resources of large amount of *OPT-VME* slave board (~400).
 - RIO slave boards (~1,400) are also integrated by replacing OPT-VME based compatible slave boards.
 - Considering alternative platform portability such as a PCI Express (MTCA.4)

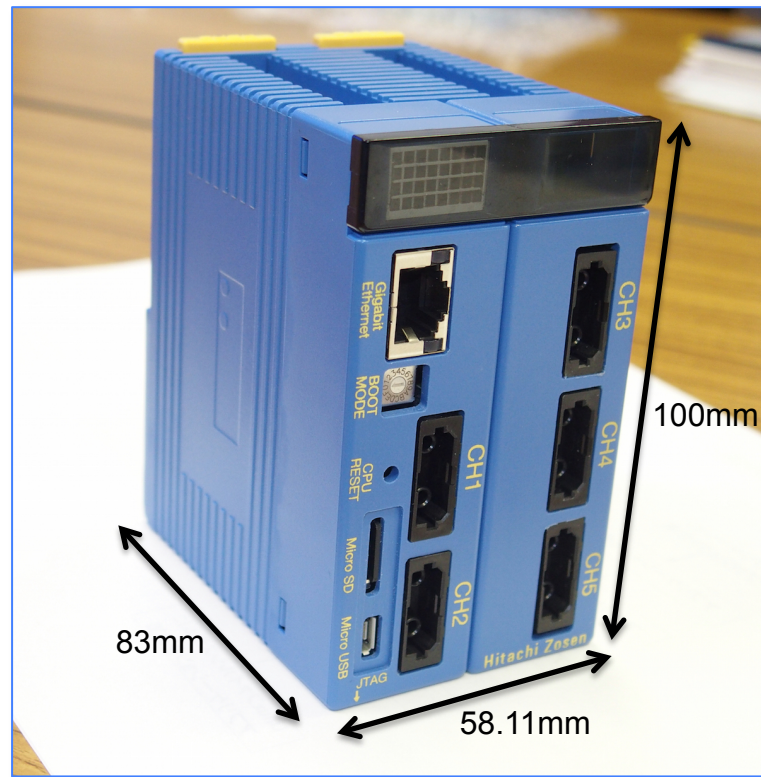


Development of the new master module

- **OPT-PLC**

- e-RT3-based new master module for the *OPT-VME system*.

SoC	Xilinx Zynq 7015 : XC7Z015-1CLG485C
Memory	1GB DDR3-SDRAM 128MB QSPI Flash
LAN	1 port (RJ-45 Connector)
MicroSD	1 port (Micro-SD socket)
UART	1 port (Micro-USB connector)
High-Speed Serial I/F	4 pairs x 6.25GBps in a 70pins stacking connector (Molex 53625-0774)
JTAG	1 port
Power	+5V±5%



OPT-PLC module

- Design Policies

1. Equip with as many optical channels as possible.
2. Separate an I/O unit from a logic control unit.
3. Control the module using the e-RT3 general-purpose device driver.
4. Control the module from a sequence CPU in addition to a Linux CPU.



OPT-PLC module

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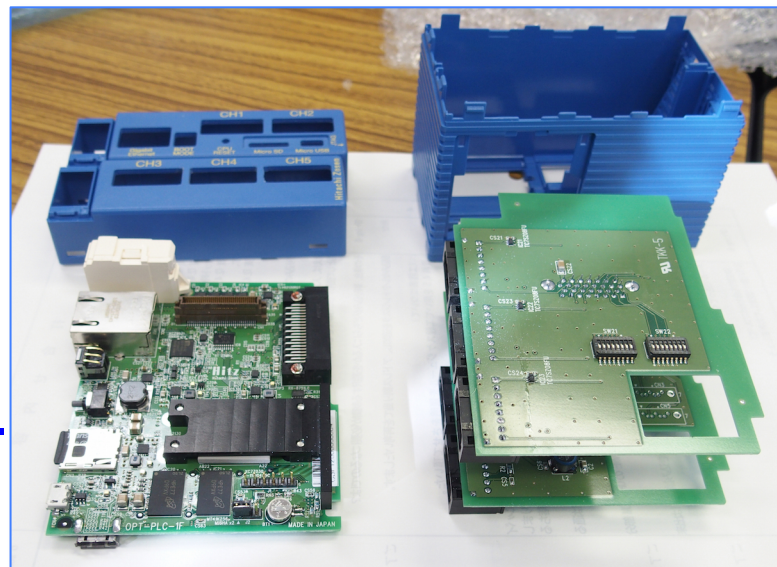
3. Control the module using a sequence CPU in addition to a Linux CPU. → Hardware Implementation driver.

4. Control the module from a sequence CPU in addition to a Linux CPU.



Hardware Implementation

- Consists of three PCBs.
 - Separate two I/O boards from the control logic board.
 - Connected using 70 pins stacking connector each other.
 - *PCB is a little small to mount the FMC.*
- Equipped with 5 optical channels.



control logic board

I/O boards



OPT-PLC module

- Design Policies

1. Equip with as many optical channels as possible.
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3. **Control the module using the e-RT3 general-purpose device driver.**
4. Control the module from a PLC CPU.

→ Implementation of Software & FPGA logic



OPT-PLC module

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3. **Control the module using the e-RT3 general-purpose device driver.**
4. Control the module from a PLC CPU.

→ Implementation of Software & FPGA logic
Keyword : SoC



e-RT3 General-Purpose Device Driver

- supplied and supported by Yokogawa Electric Co.
- primitive device driver to handle memory access and interrupt.



e-RT3 General-Purpose Device Driver

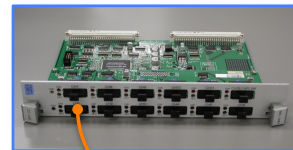
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The device driver is responsible for the high-level communication procedures including the remote slave control.

OPT-CC: master mode



OPT-CC: relay mode



slave board



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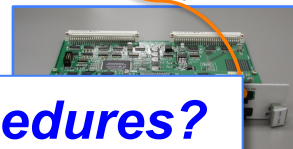
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slave board



How do we implement this high-level communication procedures?

board is implemented in the device driver for the master board.

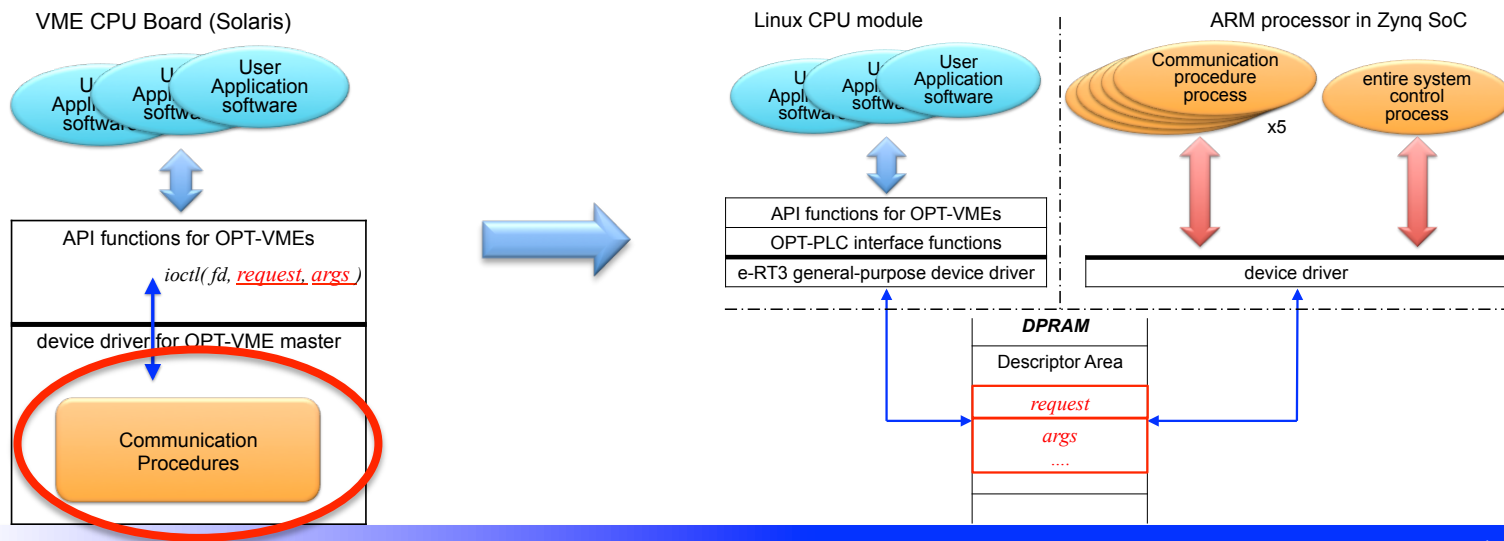
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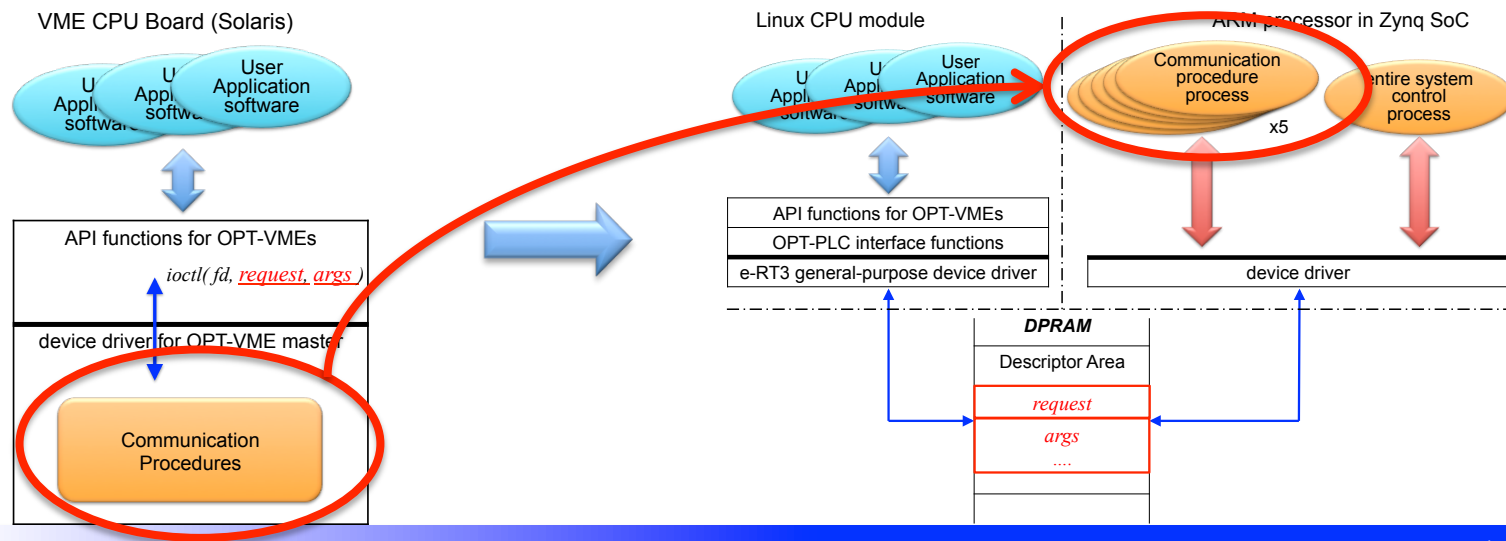
Software Implementation

- Adopt SoC (Xilinx Zynq 7000)
- Implement the high-level communication procedures as application software running on ARM Linux in SoC.



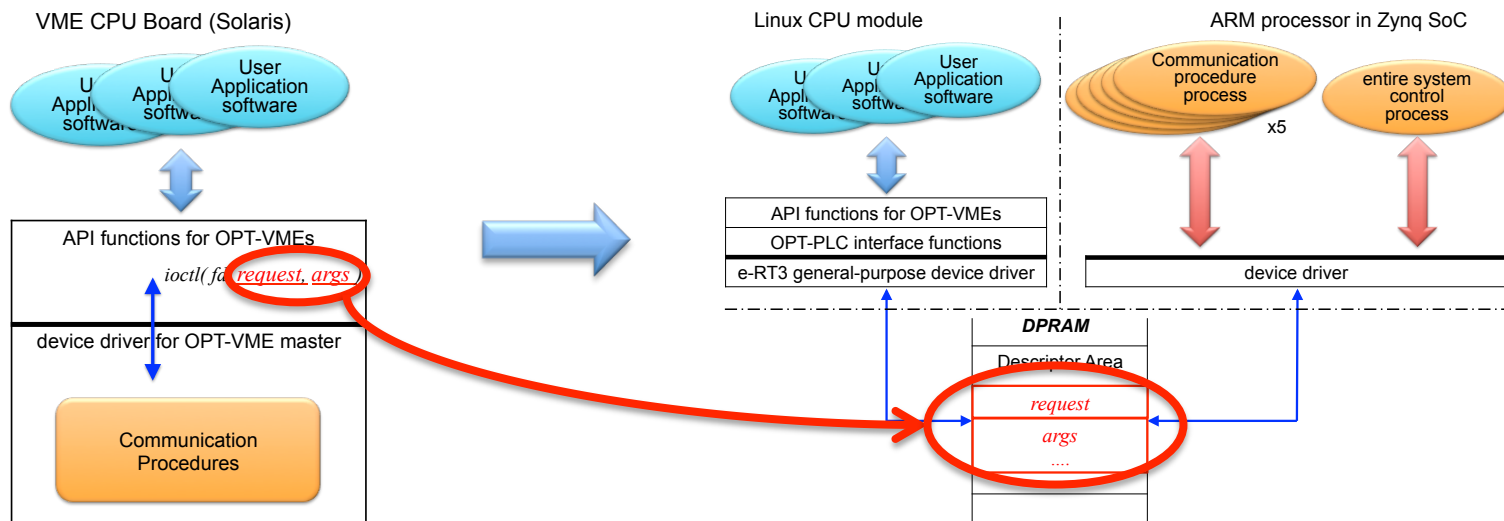
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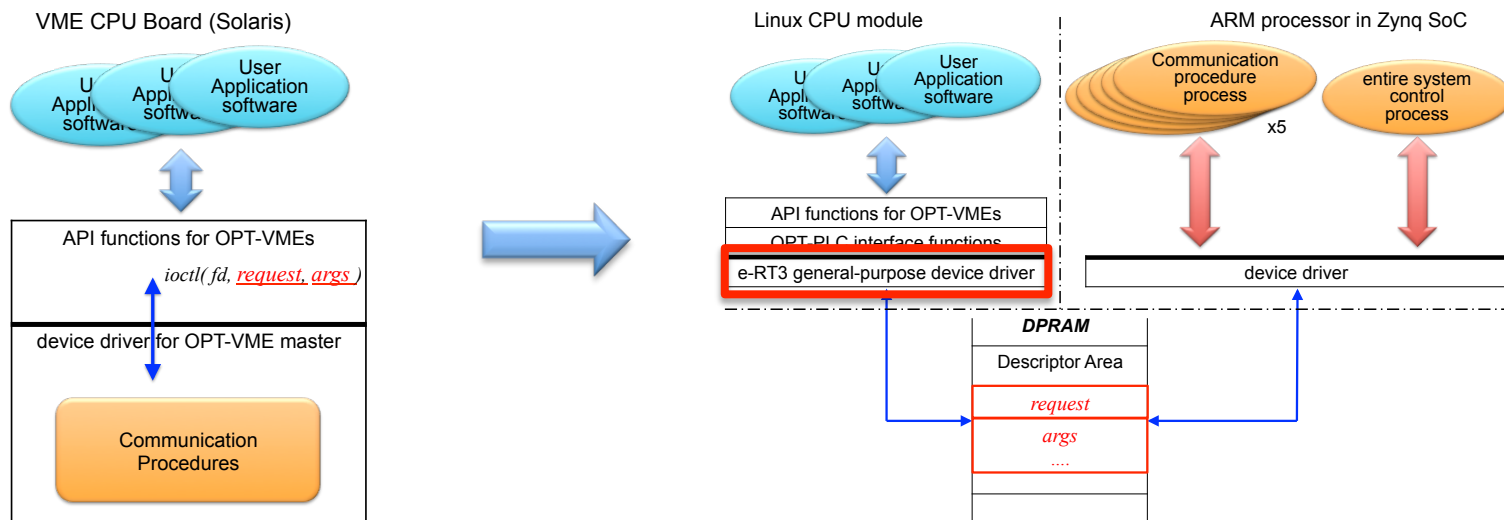
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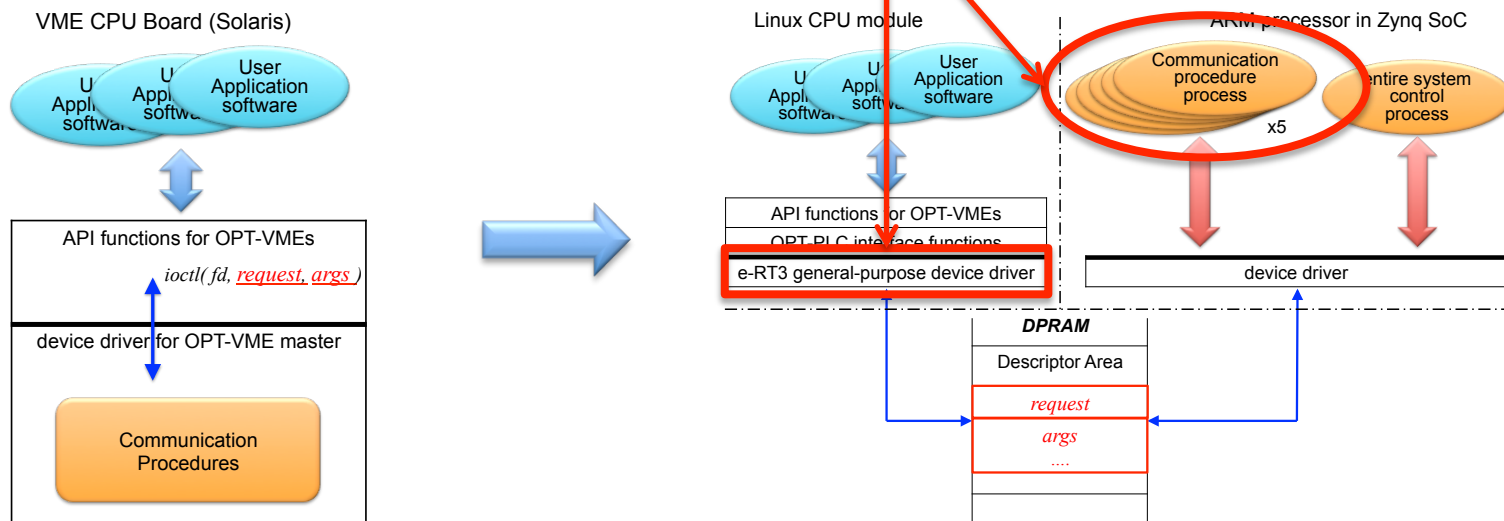
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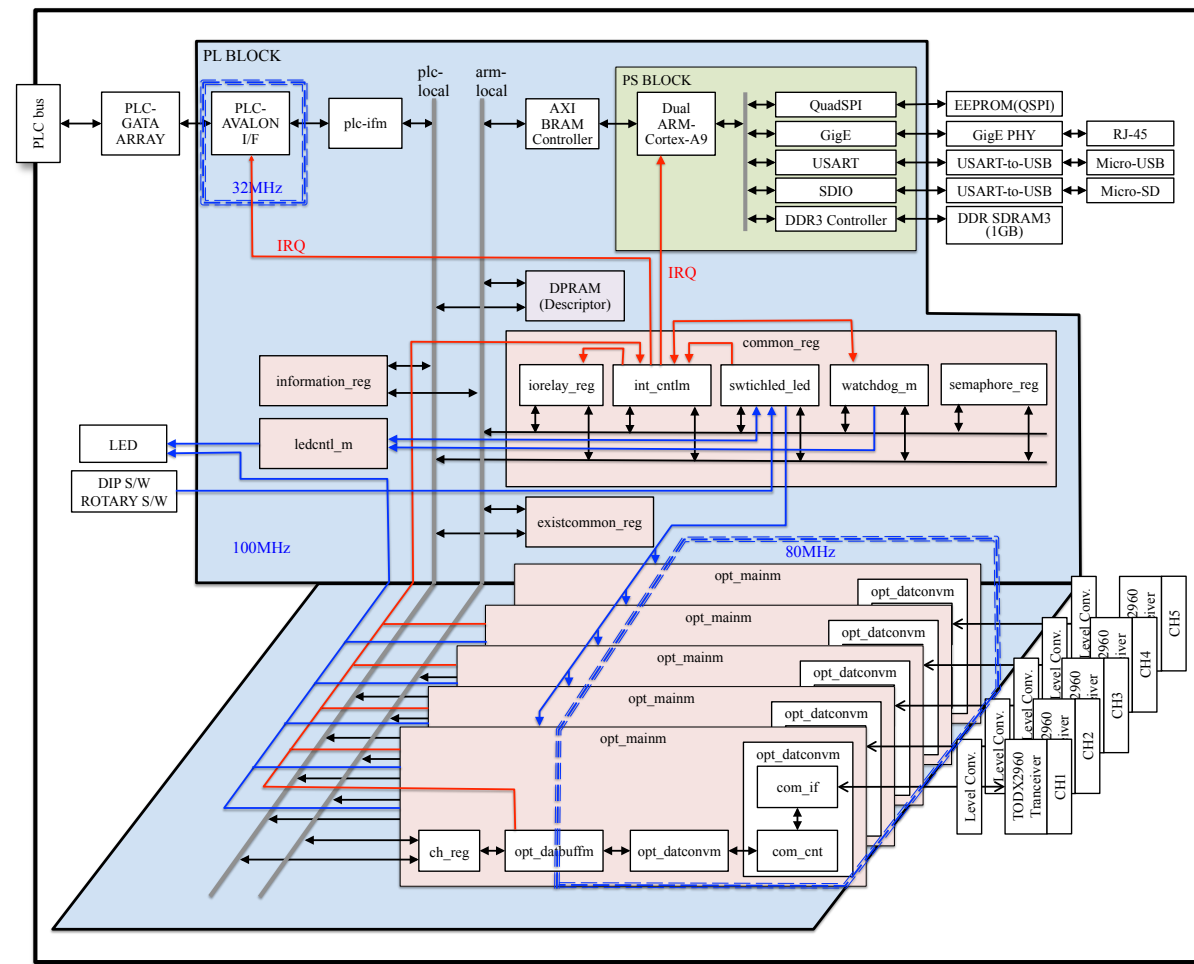


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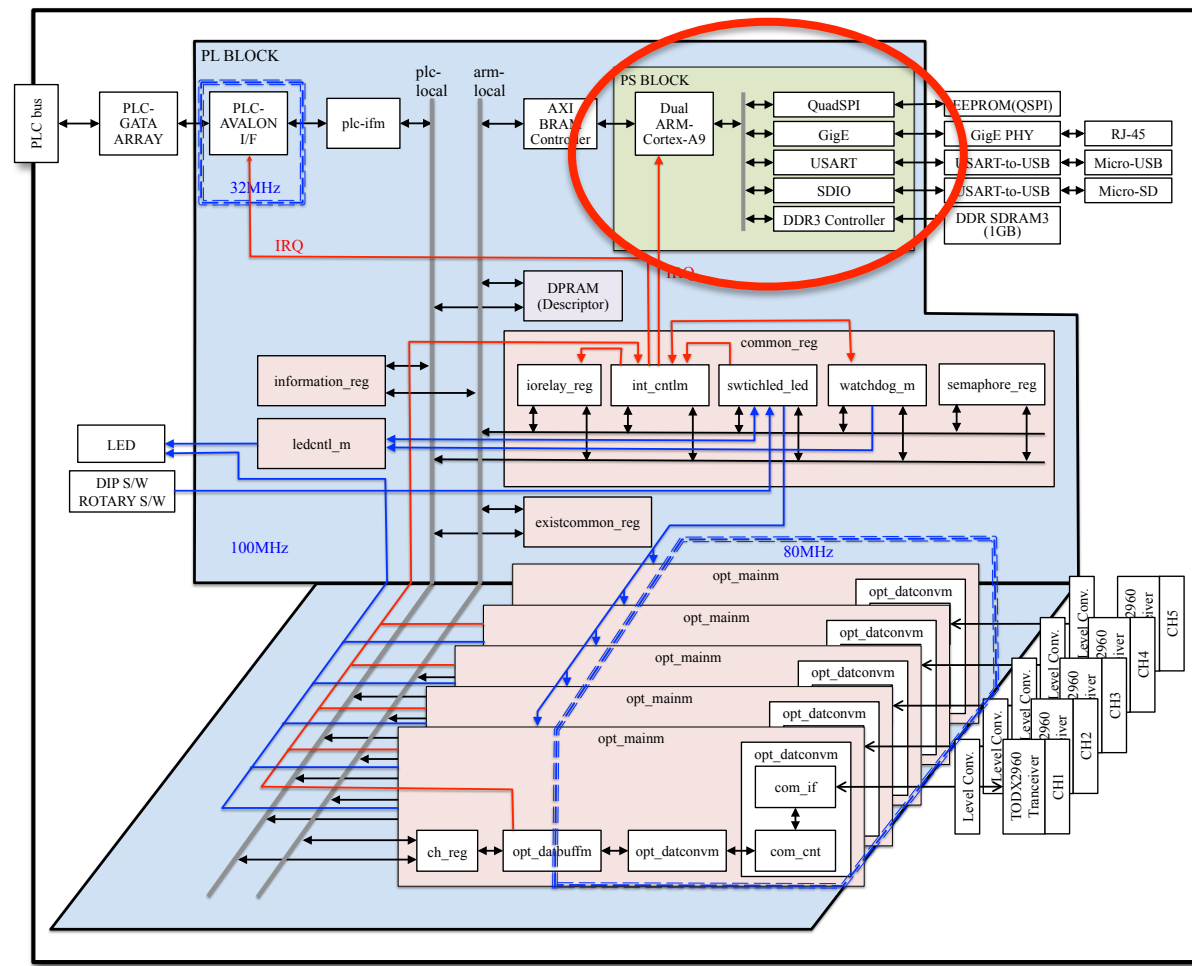
- Adopt SoC (Xilinx) As a result the device driver of platform side is simplified, the module portability to other platform is enhanced.
- Implement the high-level communication procedures as application software running on ARM Linux in SoC.



Implementation of FPGA Logic

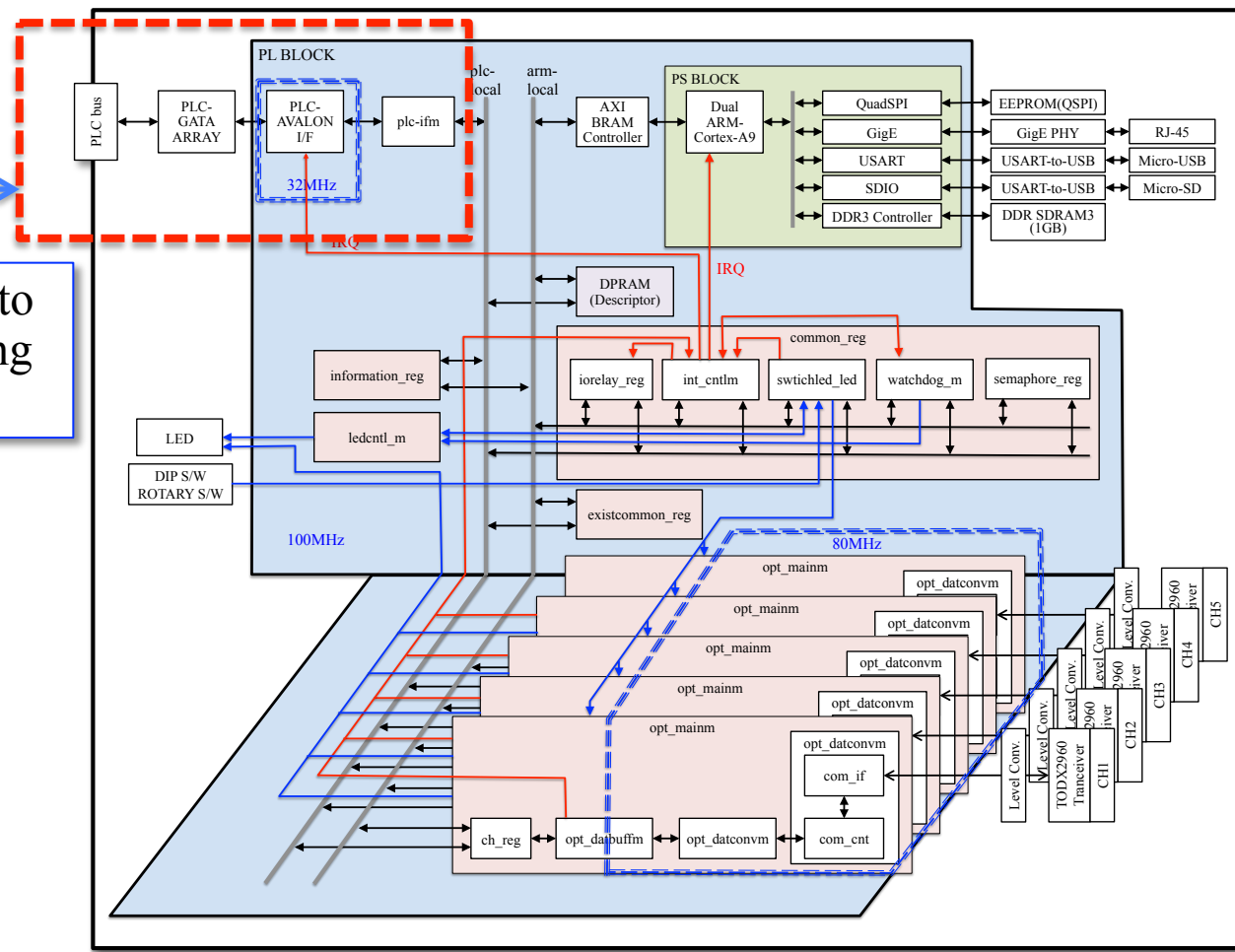


Implementation of FPGA Logic



Implementation of FPGA Logic

We can port the FPGA logic to an alternative bus by replacing this part.



Summary

- We have **successfully ported** the VME-based optical-link remote I/O module **to the e-RT3 platform**.
- The developed module OPT-PLC is **equipped with Zynq 7000 SoC** to **build the communication procedures as the application S/W on the ARM Linux**.
 - **the interface with the PLC bus is simplified** and the e-RT3 general-purpose device driver is available.
- We can **port the developed FPGA logic to an alternative bus** e.g. the PCI express by replacing the PLC bus interface block in the PL part.
- **The interface simplification enhances portability.**



Thank you for your attention.