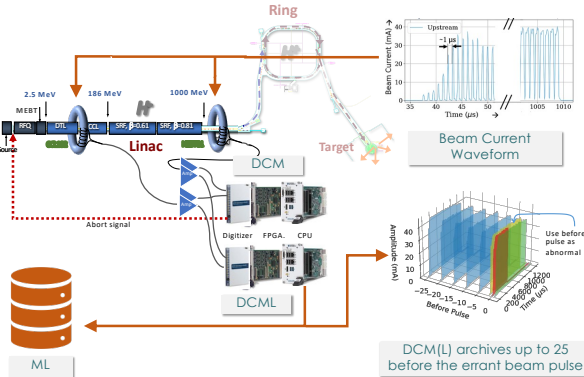


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Introduction

Applying Machine Learning (ML) algorithms to off-line data from the Differential beam Current Monitor (DCM) showed the existence of precursors to errant beam pulses^[1,2].

Duplicating the DCM into the DCML allows us to update and run the ML algorithms during operations without affecting the beam abort functions.

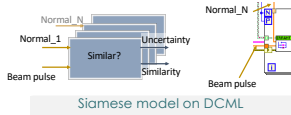


- The DCML runs a Random Forest model on its FPGA and a Siamese Twin model on its real-time CPU
- The ML Server receives a live data-stream containing the waveforms and can archive all data for a limited time (~6 hrs)

Machine Learning Methods

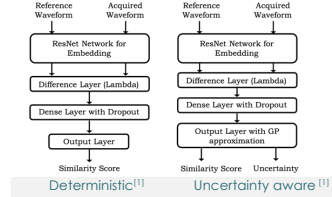
Siamese Neural Network (SNN) Model

Determine similarity between normal and unknown sample. Gaussian Process (GP) approximation is introduced for uncertainty quantification (UQ) including out-of-distribution detection.



Real-time Siamese

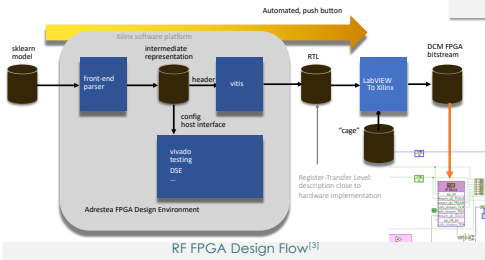
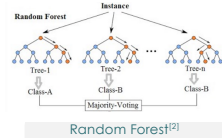
- Makes inferences before the next pulse
- Can abort before the next beam pulse



What performance is needed?
 March 2022, production was 234 days. 1.5% beam lost
 • 0.22% beam lost due to SCL beam loss
 • 1.30% beam lost due to truncated beam
 Predict a reasonable fraction of the errant pulses: TPR = 50% and don't add much down-time due to false positives → 0.2% but each abort holds off beam for 4 pulses → we want to achieve a False Positive Rate = 0.05%

Random Forest (RF) Model on FPGA

RF consists of multiple decision trees to use distinct features in a waveform to vote whether normal or errant. Majority vote established as final class.

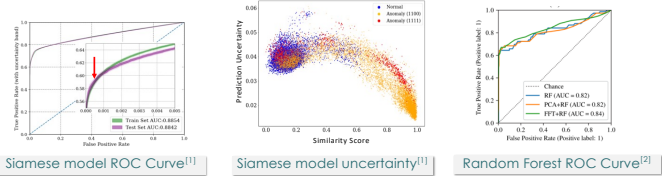


- FPGA RF**
- Makes an inference << 1 µs after the data is available (100 µs used of 1 ms long pulse)
 - Can abort within the beam pulse

Results

Offline training and testing: Receiver Operator Characteristics (ROC) curve from training and test data illustrate binary classification performance → RF and Siamese have < 0.05% FPR with FPR between 50-60%.

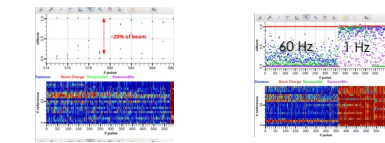
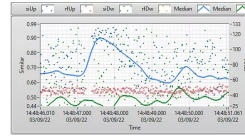
Uncertainty-aware SNN provide uncertainty for prediction to distinguish unseen anomaly types.



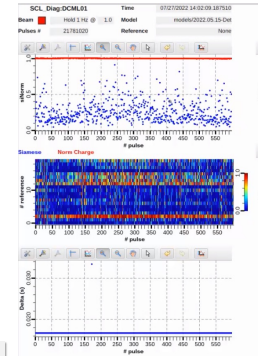
Implementation: We apply trained models, implemented in C++ on DCML and Python on ML server, to incoming accelerator data during production.

DCML:

- Can run up to 4 deterministic inferences



Chopper partial failure is seen as abnormal beam | 1 Hz beam (instead of 60 Hz) is seen as abnormal



ML Server Results Screen

ML Server:

- Can run 20 deterministic inferences per pulse at 60 Hz to compare incoming waveform with multiple references (can be normal or abnormal)
- Create average similarity to improve results
- Presents results over EPICS
- Initial results during production showed some trends and detected errant beam pulses but not good enough to execute an abort during operations. The model and references samples were from data in the past.
- We can now have several sets of 2 hours of all beam pulses (@60 Hz) to analyze

Future

- Finish framework to quickly train new models
 - Support incremental training
- Further improve models and add equipment fault classification
- Abort beam pulses to determine if the errant pulse is avoidable

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