

Progress towards nanometre beam stabilisation at ATF2

Feedback On Nanosecond Timescales (FONT)

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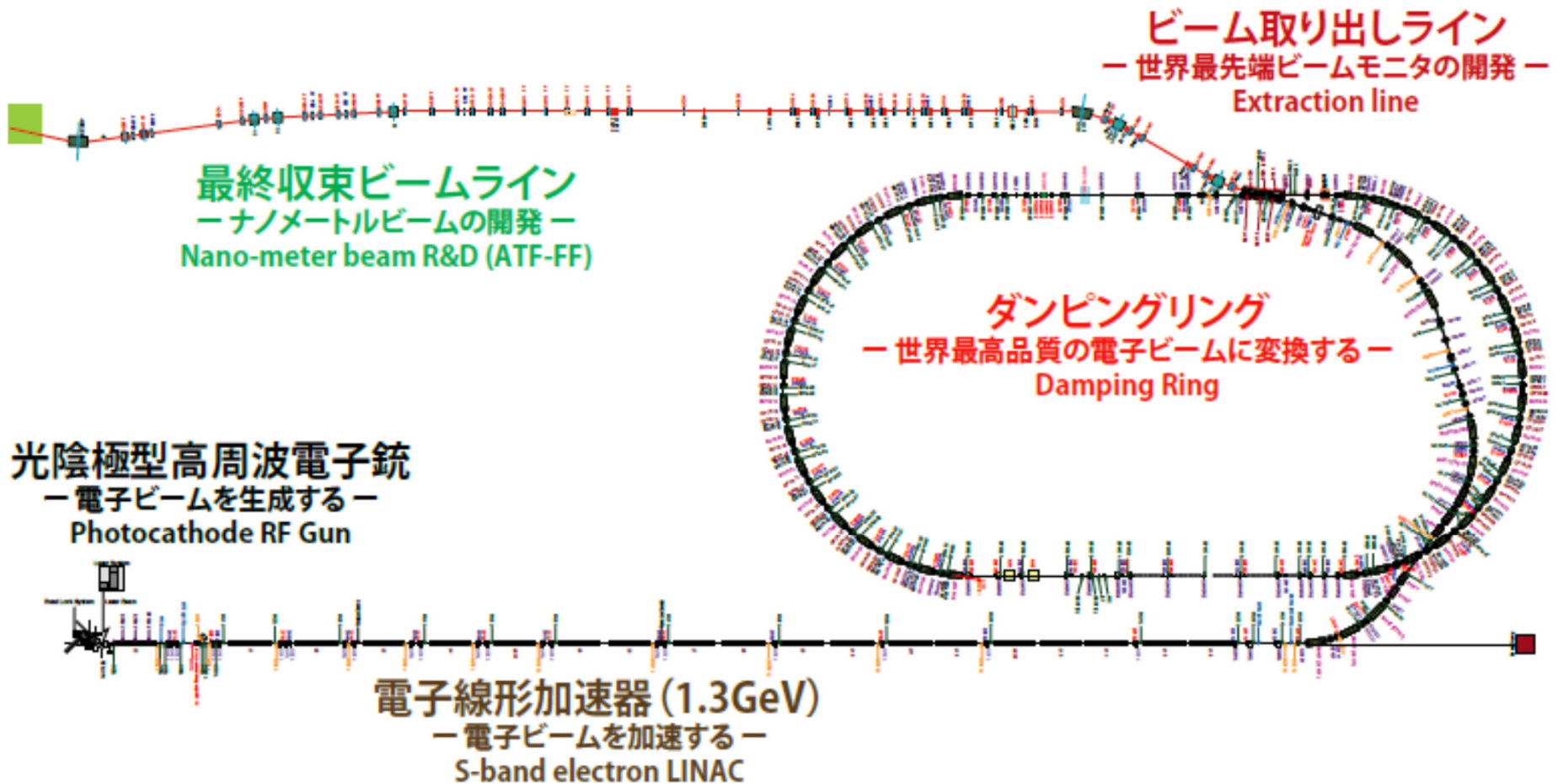
Now at: *CERN; **UBS

in collaboration with: KEK, KNU, LAL

Outline

- **ATF2 project at KEK**
- **Stripline BPM system**
- **Coupled-loop y , y' feedback system**
- **Cavity BPMs and progress towards nm resolution**
- **Summary + outlook**

ATF2/KEK



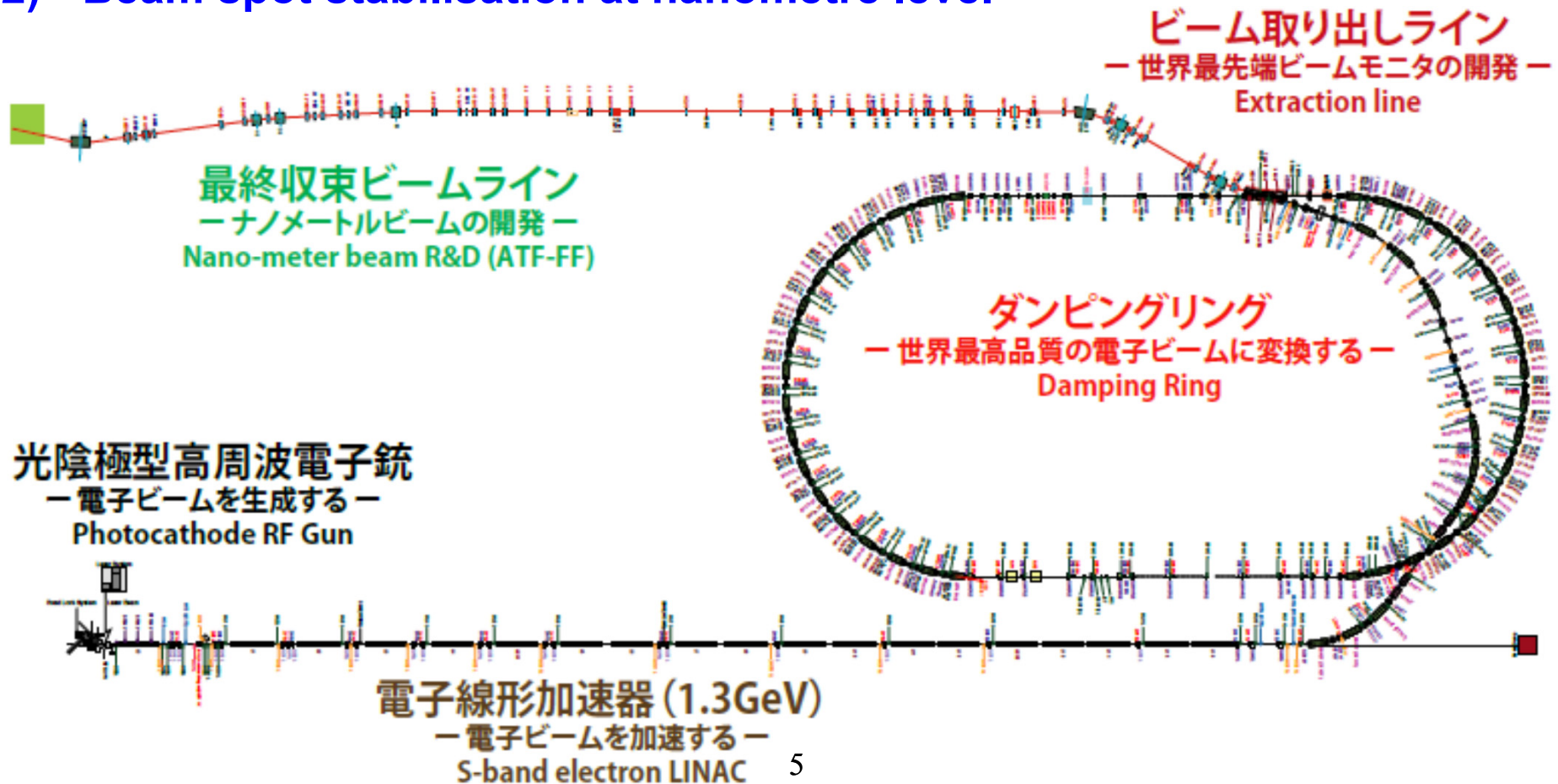
ATF2 design parameters

Parameter			Design value
Energy		(GeV)	1.3
Intensity		(electrons/bunch)	1×10^{10}
Repetition rate		(Hz)	3.12
Horizontal emittance	ϵ_x	(m rad)	2×10^{-9}
Vertical emittance	ϵ_y	(m rad)	1.2×10^{-11}
Horizontal IP beam size	$\hat{x}^*$	(m)	2.8×10^{-6}
Vertical IP beam size	$\hat{y}^*$	(m)	3.7×10^{-8}
Horizontal IP beta function	β_x^*	(m)	4×10^{-3}
Vertical IP beta function	β_y^*	(m)	1×10^{-4}
RMS energy spread		(%)	0.08

ATF2/KEK: prototype final focus

Goals:

- 1) 37 nm beam spot (44 nm achieved 2014 – reproducibly)
- 2) Beam spot stabilisation at nanometre level



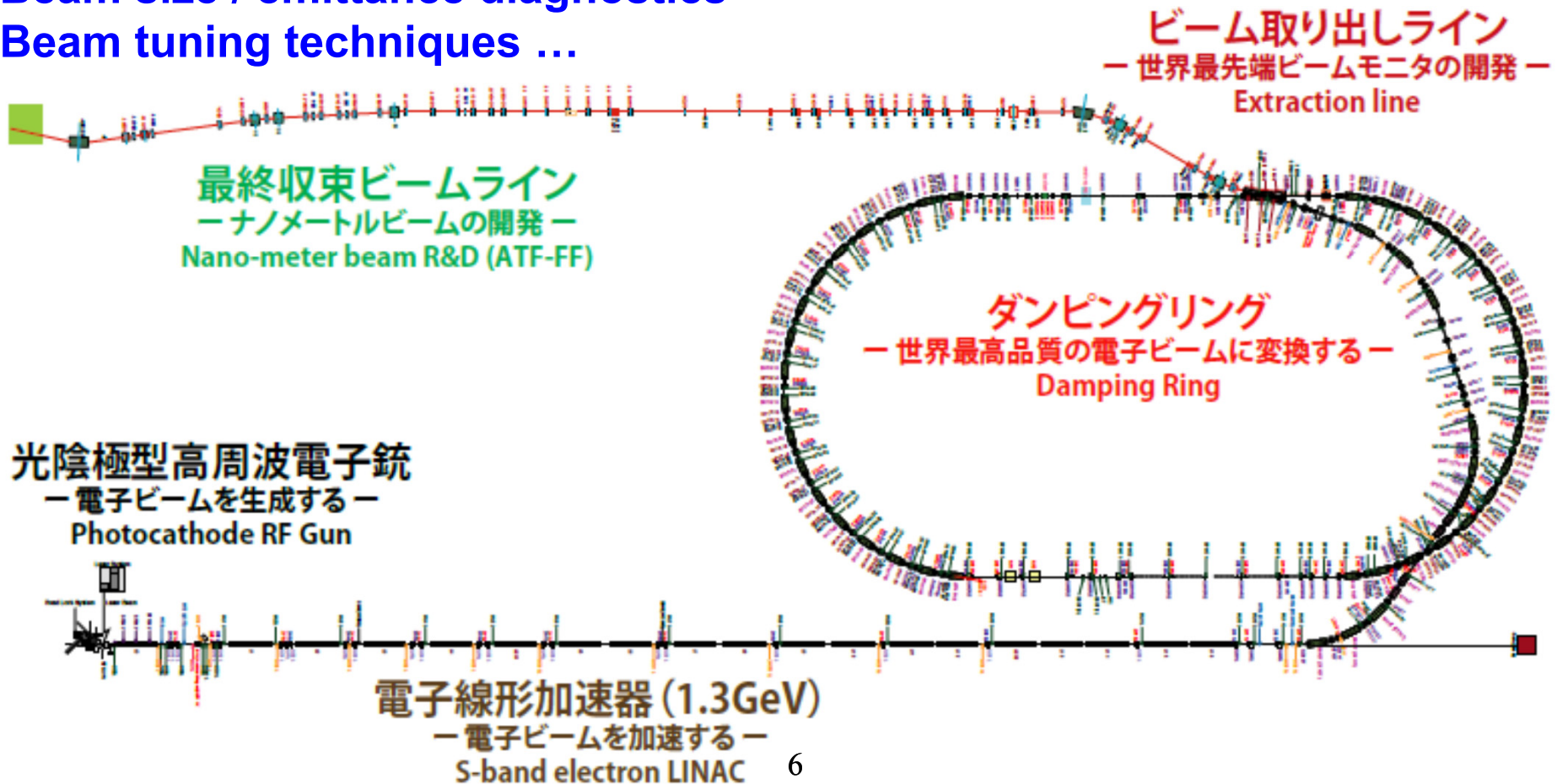
ATF2/KEK: prototype final focus

Beam feedback + feed-forward systems

Precision cavity + stripline BPMs

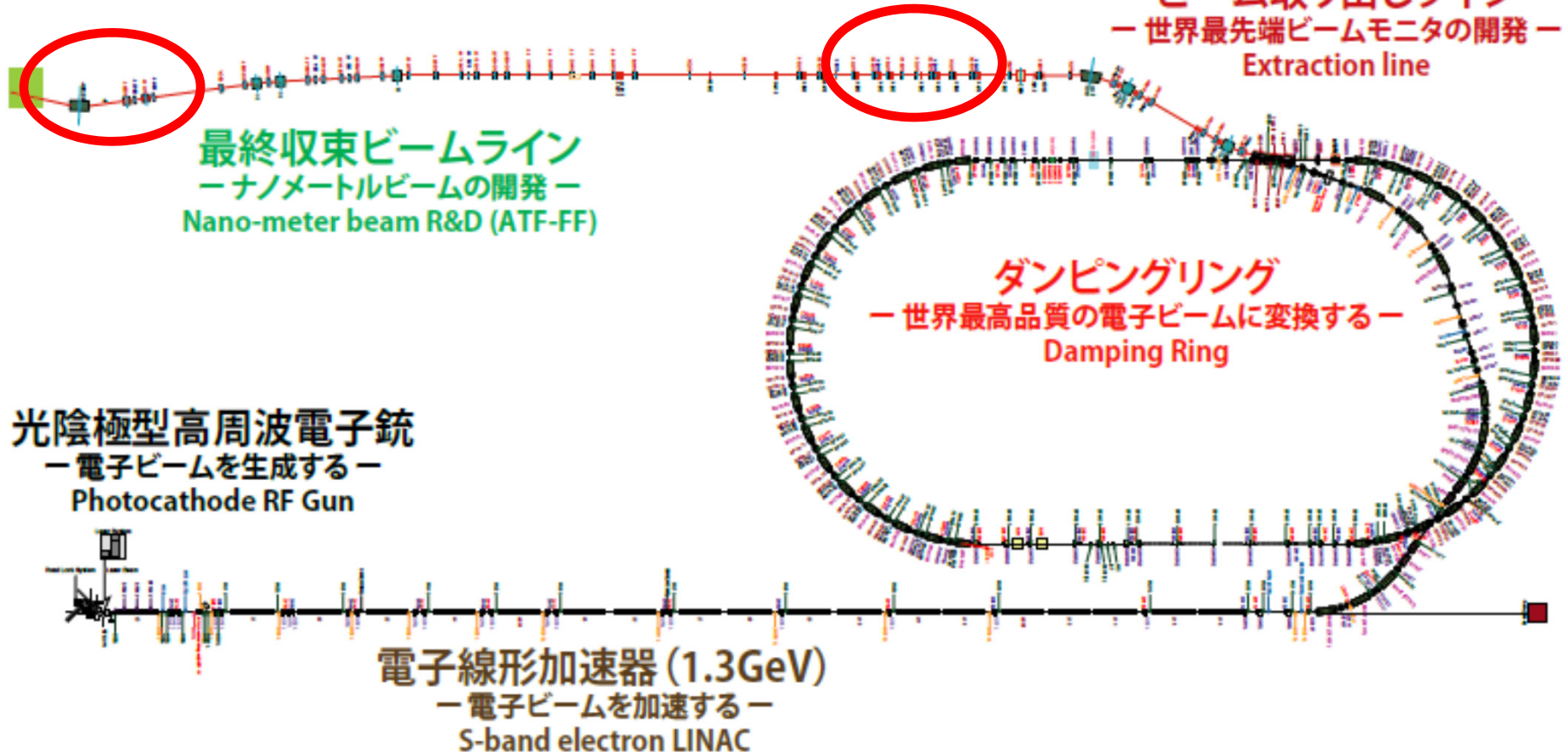
Beam size / emittance diagnostics

Beam tuning techniques ...

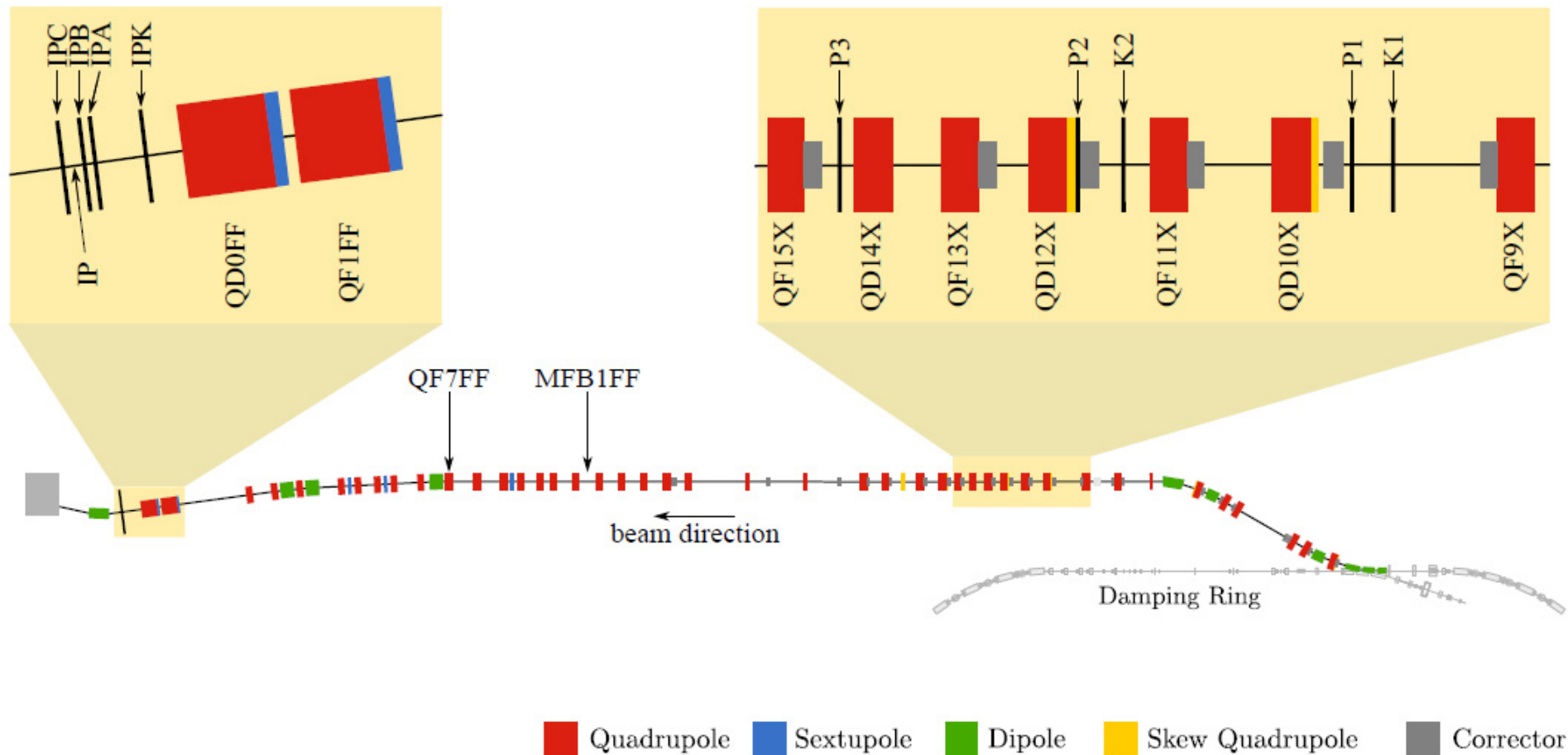


FONT5 'intra-train' feedbacks

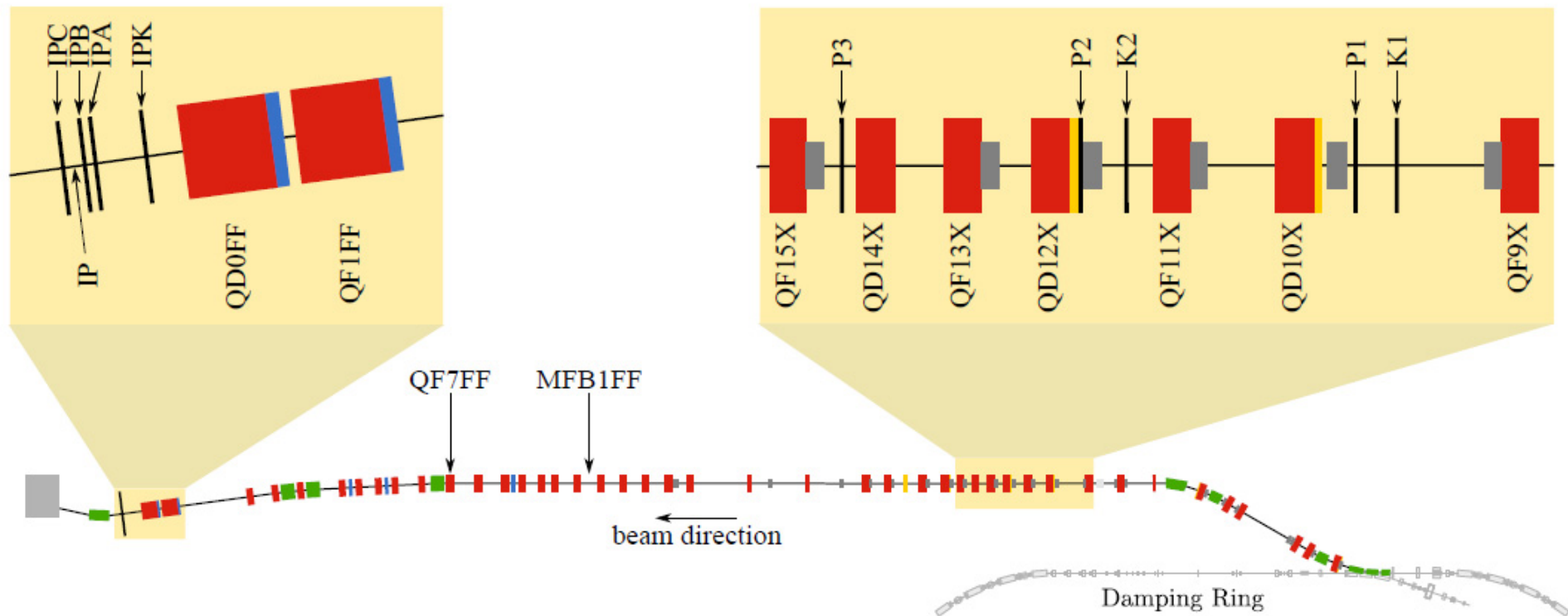
ATF2 extraction line



FONT5 'intra-train' feedbacks

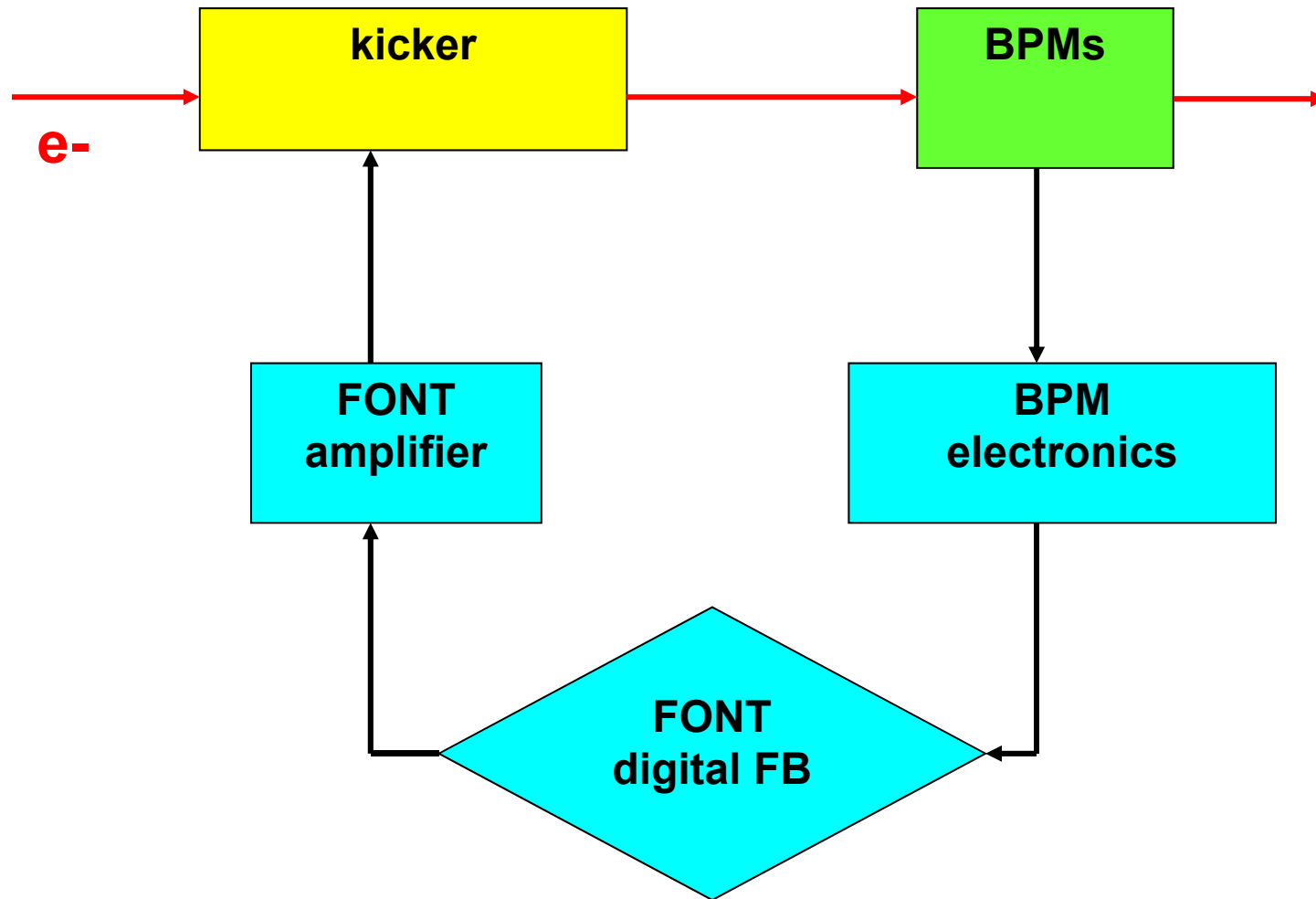


Stabilising beam near IP

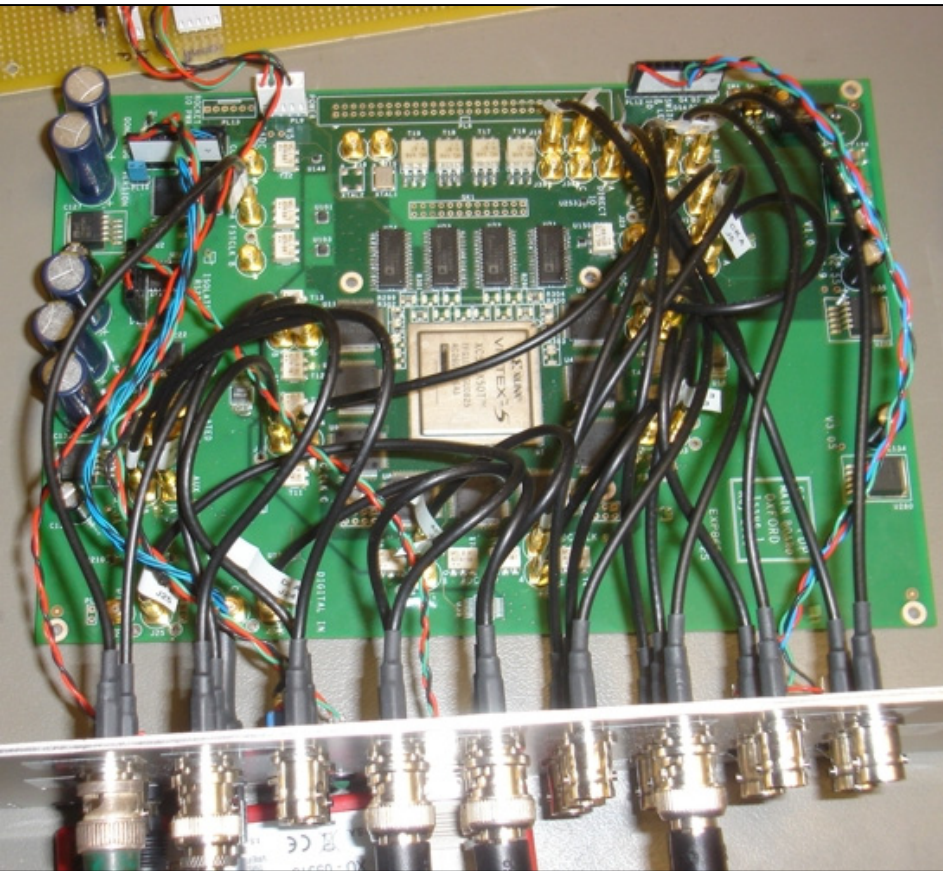


1. **Upstream FB:** monitor beam at IP
2. **Feed-forward:** from upstream BPMs → IP kicker
3. **Local IP FB:** using IPBPM signal and IP kicker

FB loop schematic



FONT5 digital FB board



Xilinx Virtex5 FPGA

**9 ADC input channels
(TI ADS5474)**

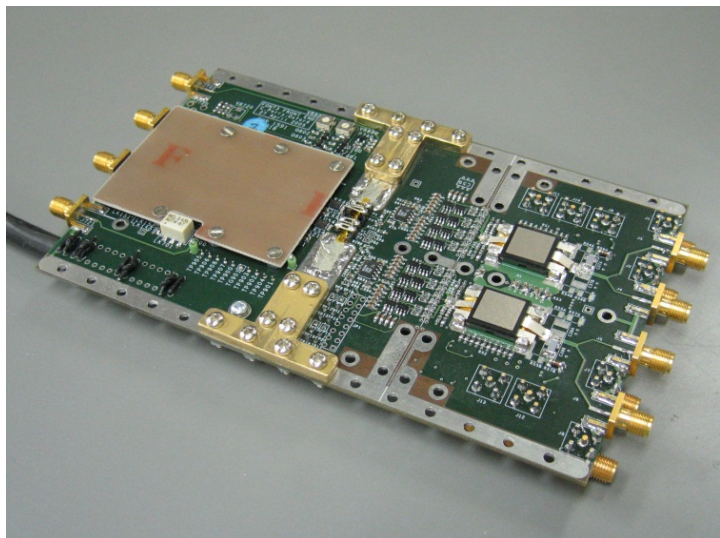
**4 DAC output channels
(AD9744)**

**Clocked at up to 400 MHz
(phase-locked to beam)**

High-power, low-latency amps



**CLIC CTF3
phase
feed-forward
amp**



MOPB063

FONT4 drive amplifier

- FONT4 amplifier, outline design done in JAI/Oxford
- Production design + fabrication by TMD Technologies
- Specifications:

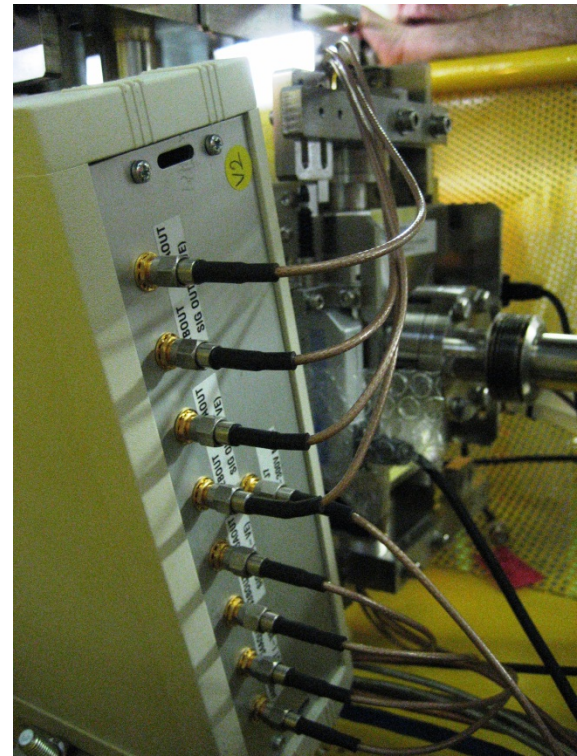
+ - 15A (kicker terminated with 50 Ohm)

+ - 30A (kicker shorted at far end)

35ns risetime (to 90%)

pulse length 10 us

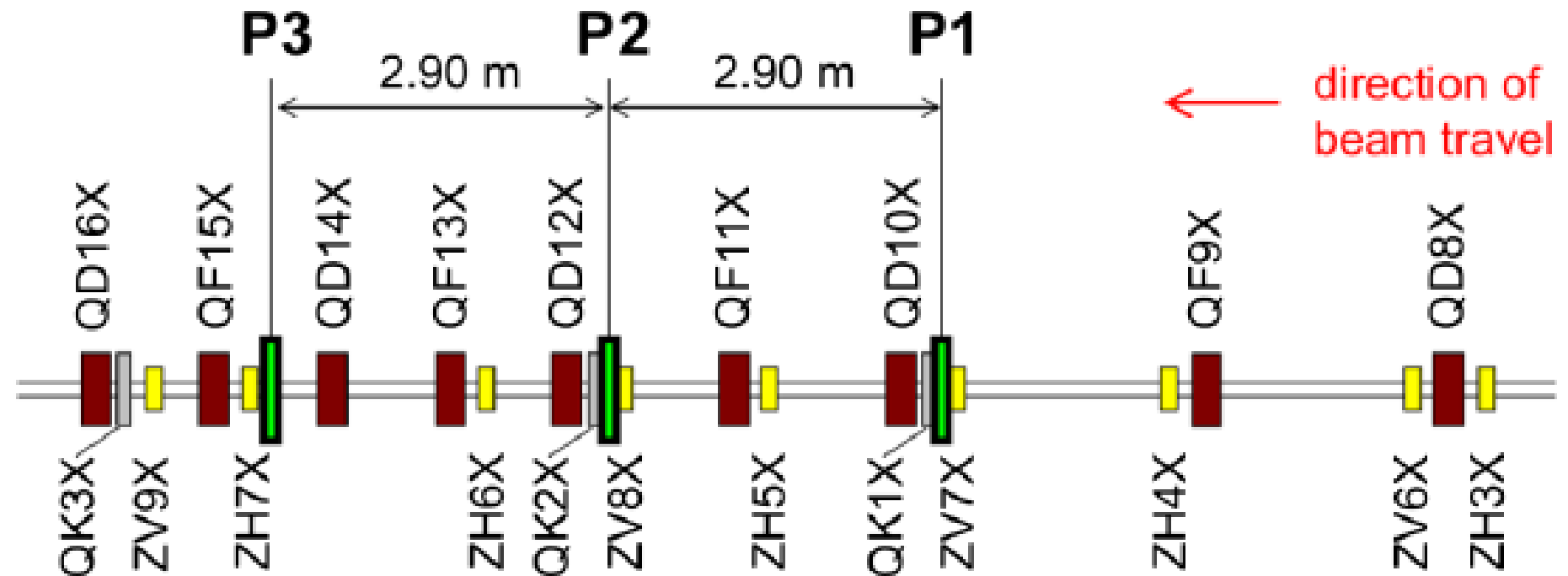
repetition rate 10 Hz



The technical drawing consists of two views of a mechanical component:

- Top View (Left):** A circular component with a central hub and four radial arms. Key dimensions include:
 - Outer diameter: $\Phi 80$
 - Inner diameter of the central hub: $\Phi 27$
 - Distance from the center to the center of each arm: 27
 - Angle between adjacent arms: 28.8°
 - Radius of the circular path of the arm centers: 67
 - Inner diameter of the central hub: $\Phi 23.9$
 - Outer diameter of the central hub: $\Phi 38.24$
 - Angle between the arm and the radial line: 26.0°
 - Angle between the arm and the tangent line: 35.0°
 - Angle between the arm and the radial line: 55.0°
- Side View (Right):** A cross-sectional view of the component. Key dimensions include:
 - Total width: 210
 - Distance from the left edge to the center of the arm: 70
 - Distance from the center of the arm to the right edge: 140
 - Distance from the left edge to the center of the arm: 30
 - Distance from the center of the arm to the right edge: 24
 - Distance from the center of the arm to the right edge: 30
 - Distance from the center of the arm to the right edge: 90
 - Distance from the left edge to the center of the arm: 12.7
 - Outer diameter of the central hub: $\Phi 70$
 - Inner diameter of the central hub: $\Phi 30$
 - Inner diameter of the central hub: $\Phi 23.9$
 - Distance from the left edge to the center of the arm: 120
 - Material specification: $\Phi 45 \times \Phi 25 \times 16$ L

FONT5 stripline BPM system

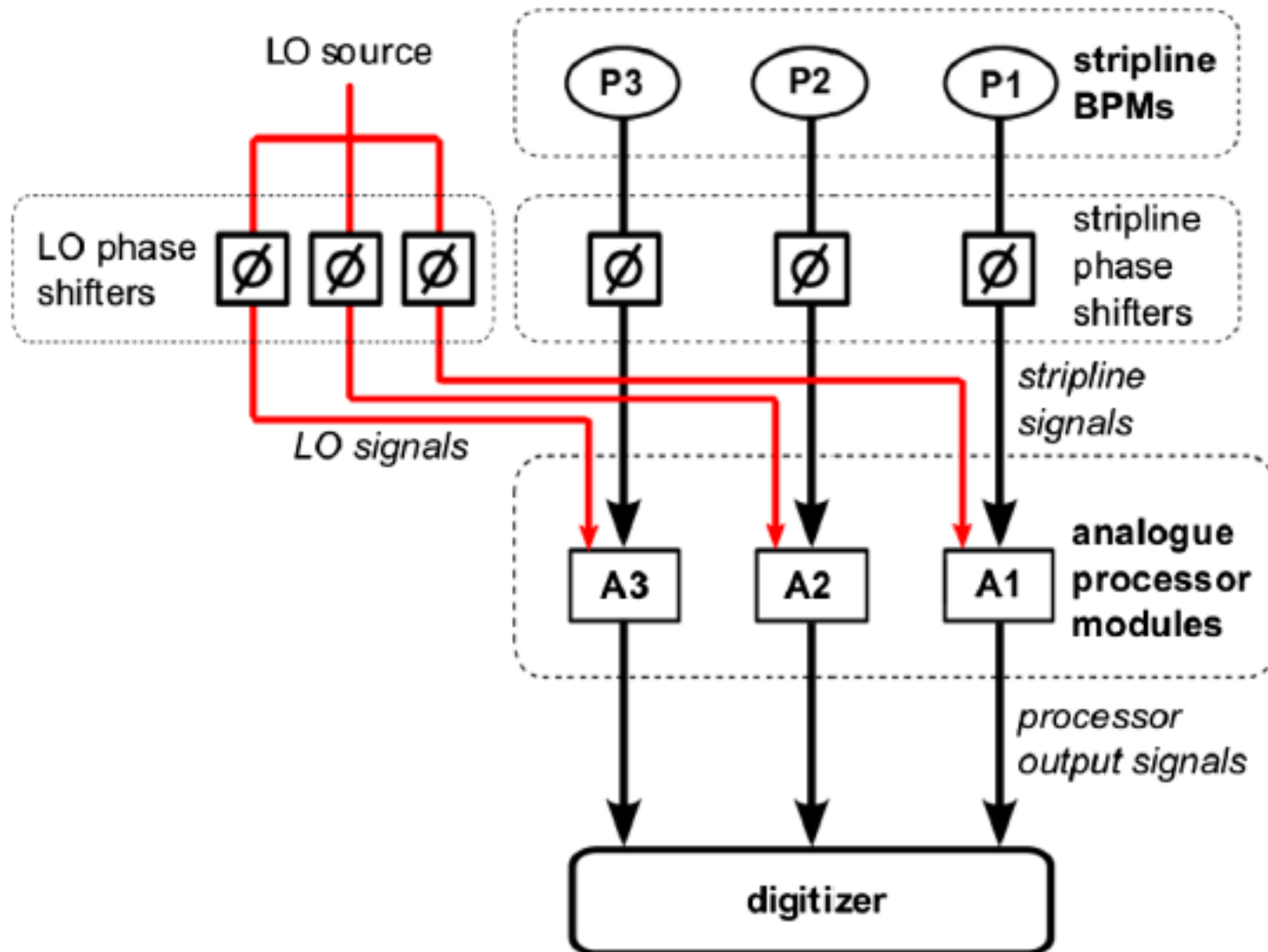


Stripline BPMs

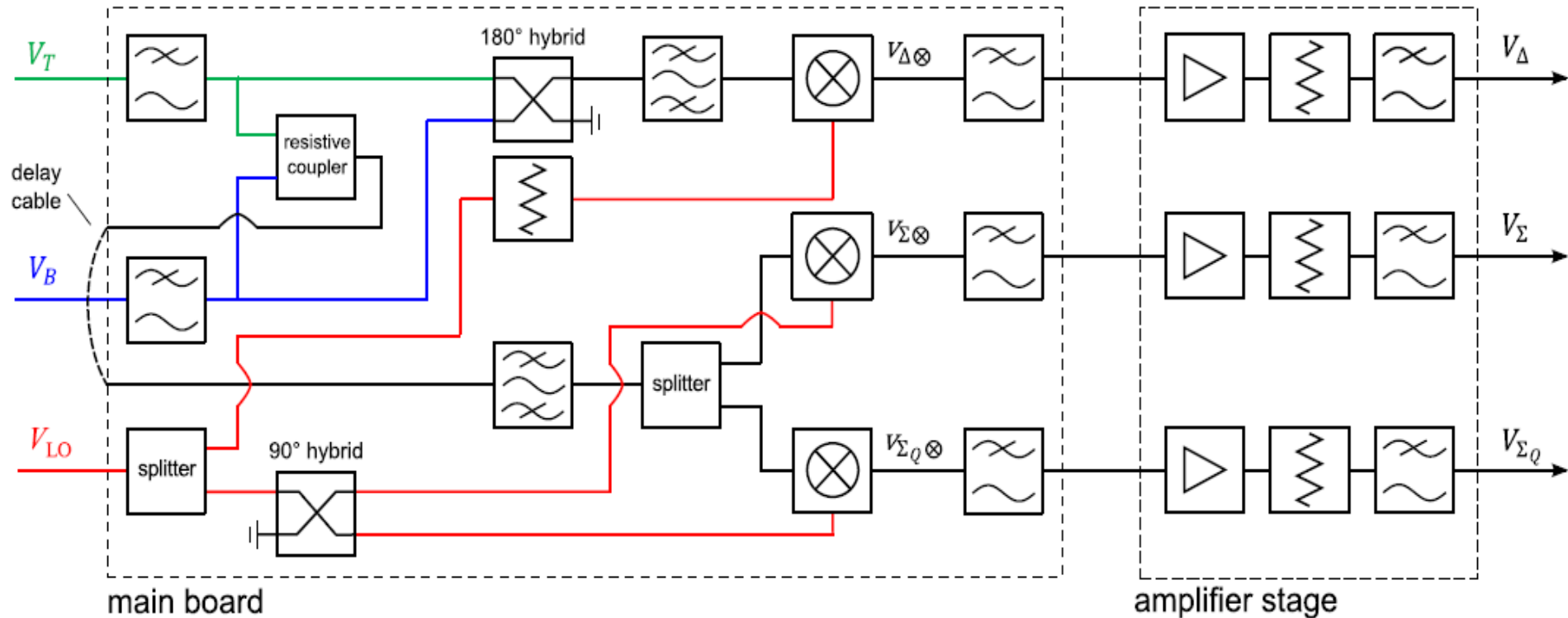
**BPM on
x-y mover
system (IFIC)**



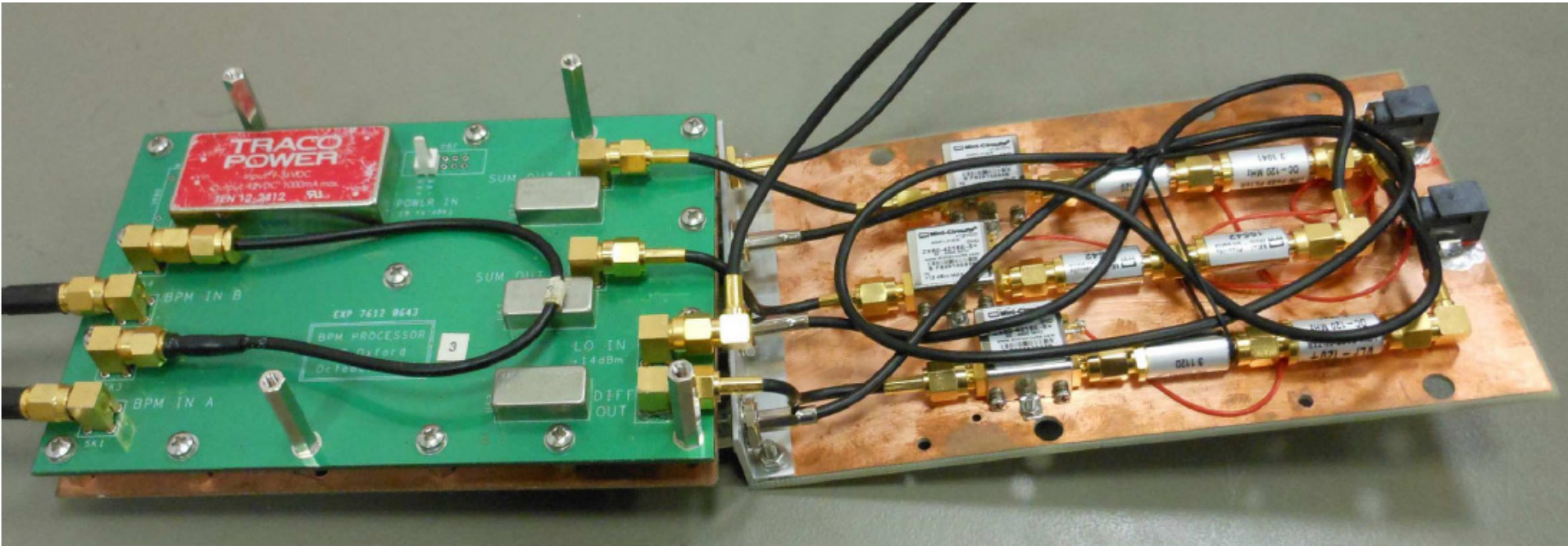
BPM readout



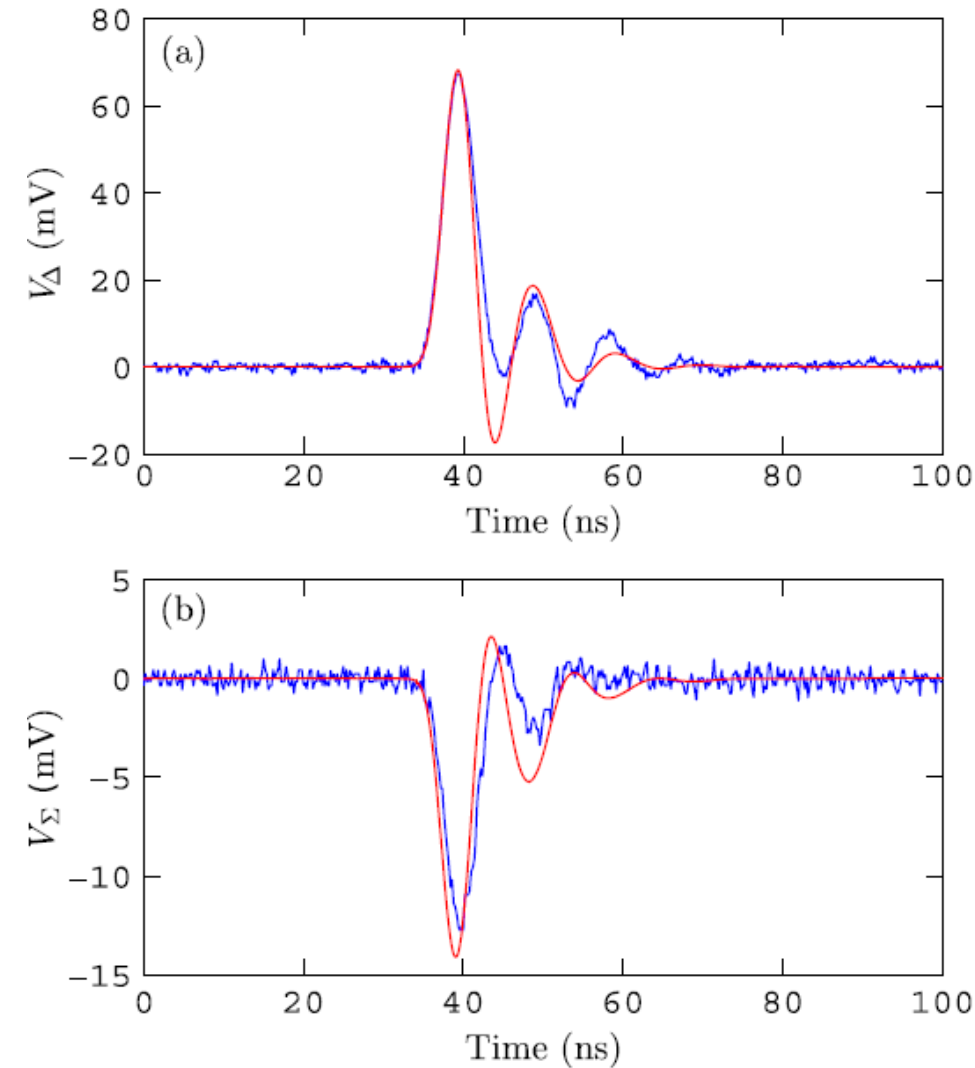
BPM signal processing



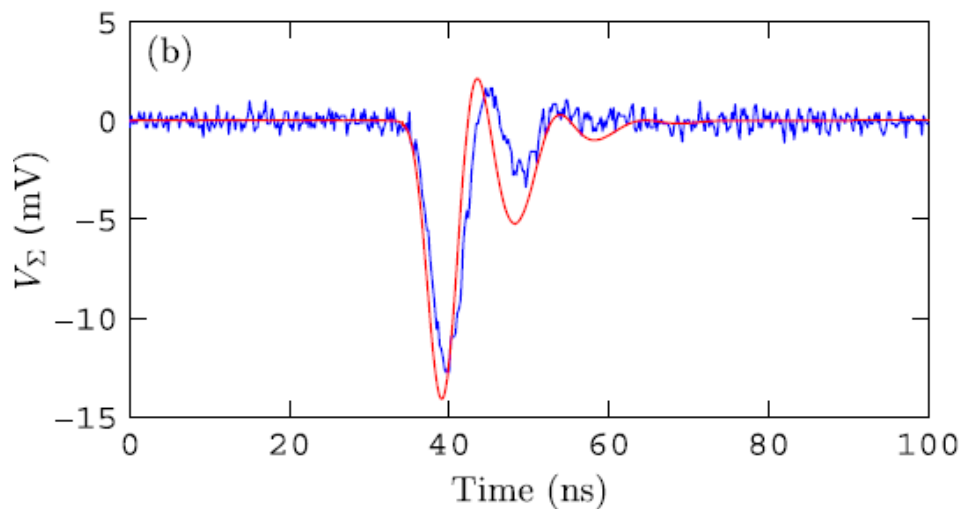
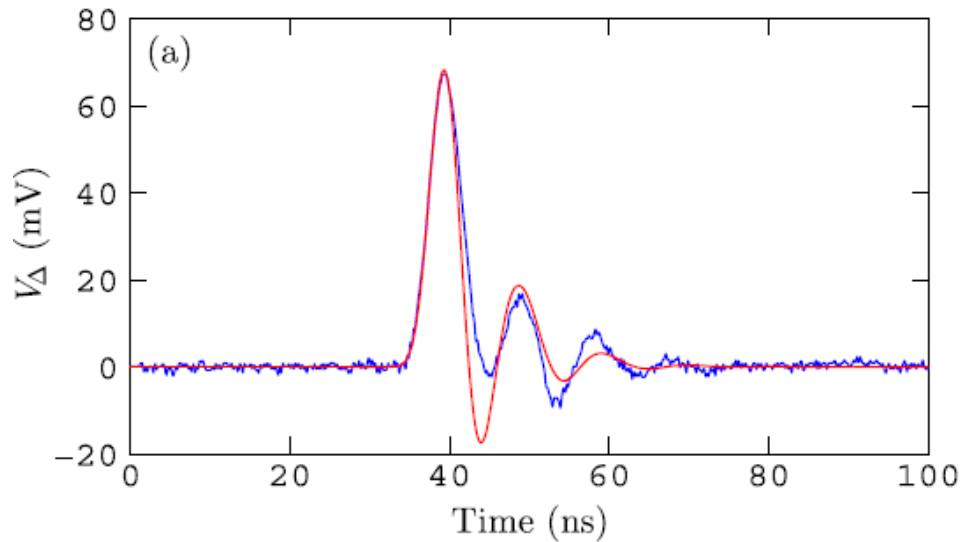
BPM signal processor



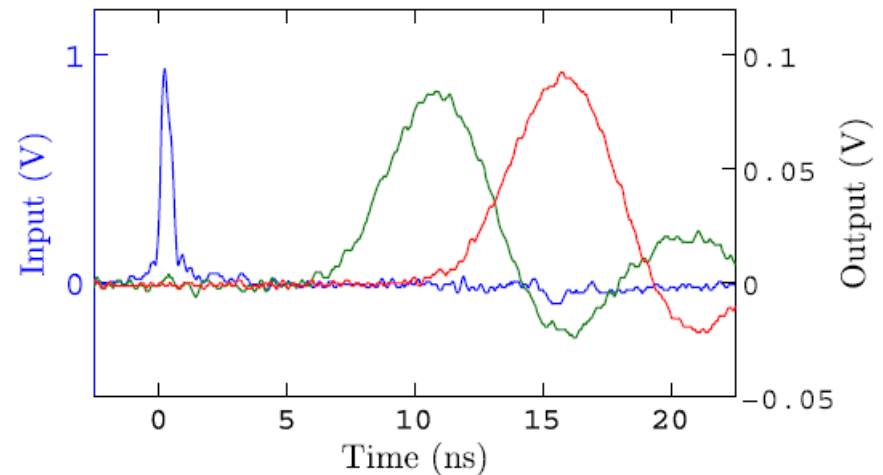
BPM signal processor outputs



BPM signal processor latency

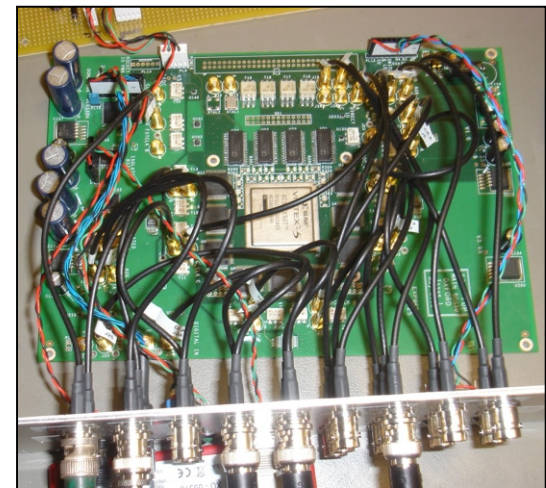
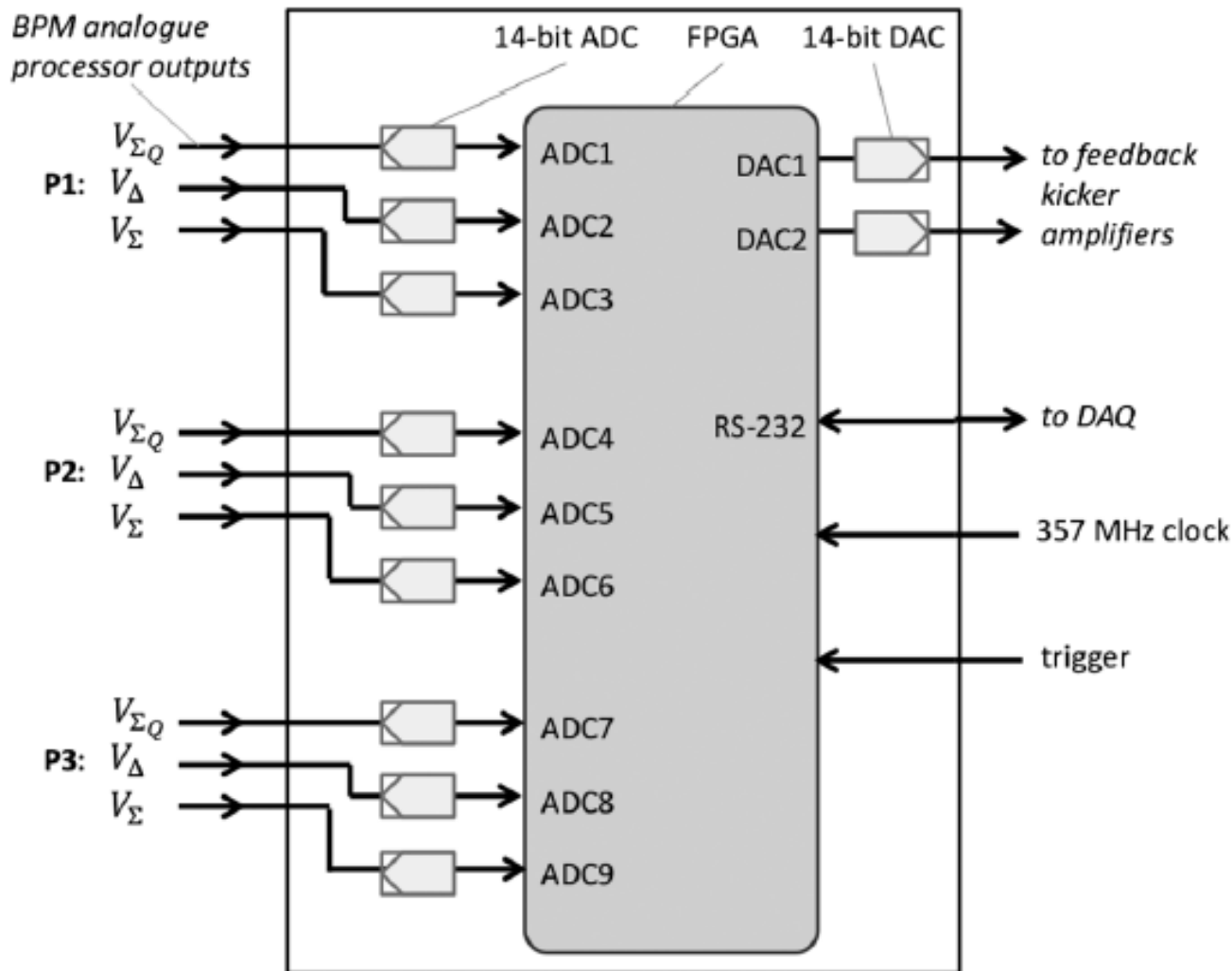


Bench latency meas:



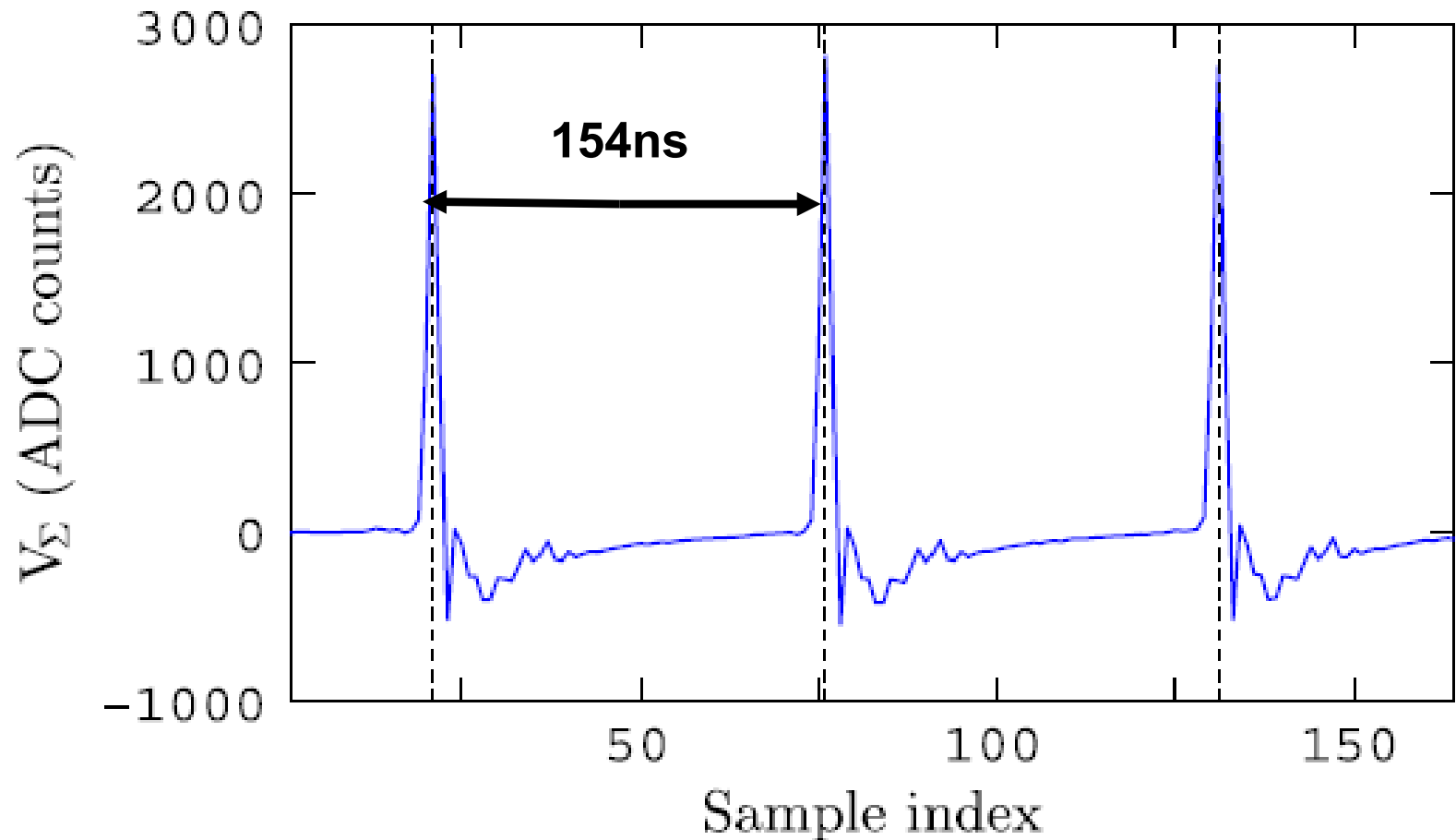
**10ns or 15ns with
amplifier stage**

BPM signal digitisation

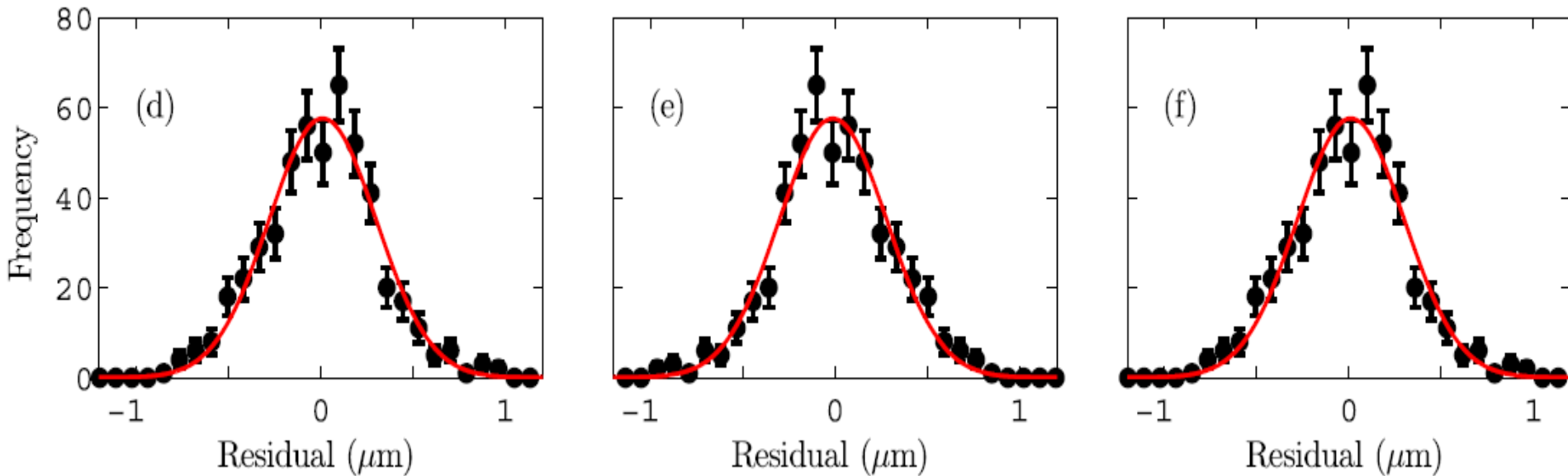
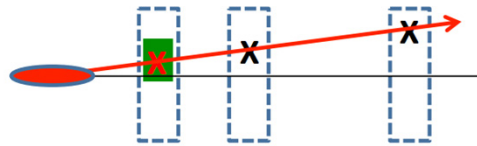


3-bunch train at ATF (proxy for ILC)

Single-shot measurement



BPM system resolution



Resolution = 291 ± 10 nm
($Q \sim 1\text{nC}$)

Design and performance of a high resolution, low latency stripline beam position monitor system

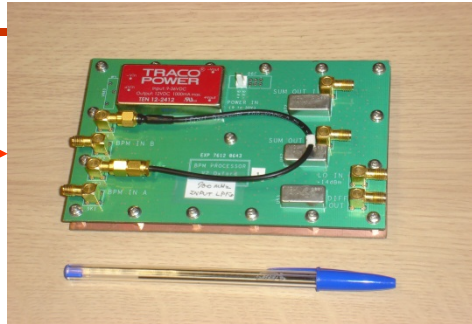
R. J. Apsimon,^{*} D. R. Bett,[†] N. Blaskovic Kraljevic, P. N. Burrows, G. B. Christian,[‡]
C. I. Clarke,[§] B. D. Constance, H. Dabiri Khah, M. R. Davis, C. Perry,
J. Resta López,^{||} and C. J. Swinson[¶]

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Keble Road, Oxford OX1 3RH, United Kingdom*

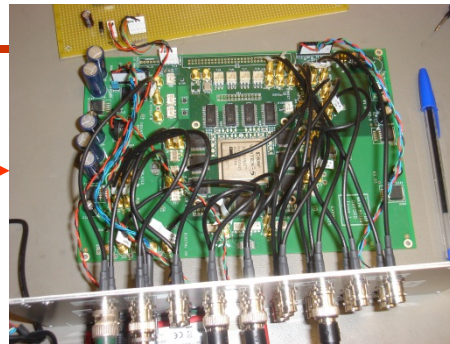
(Received 1 October 2014; published 19 March 2015)

A high-resolution, low-latency beam position monitor (BPM) system has been developed for use in particle accelerators and beam lines that operate with trains of particle bunches with bunch separations as low as several tens of nanoseconds, such as future linear electron-positron colliders and free-electron lasers. The system was tested with electron beams in the extraction line of the Accelerator Test Facility at the High Energy Accelerator Research Organization (KEK) in Japan. It consists of three stripline BPMs instrumented with analogue signal-processing electronics and a custom digitizer for logging the data. The design of the analogue processor units is presented in detail, along with measurements of the system performance. The processor latency is 15.6 ± 0.1 ns. A single-pass beam position resolution of 291 ± 10 nm has been achieved, using a beam with a bunch charge of approximately 1 nC.

Upstream FONT5 System



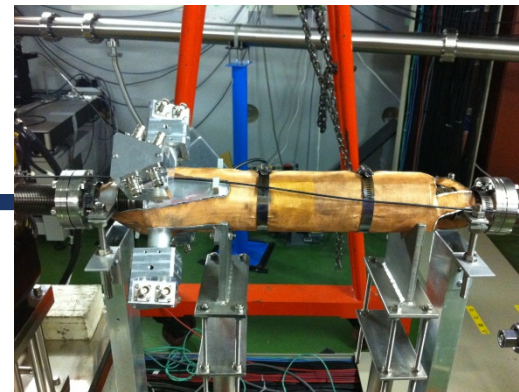
**Analogue Front-end
BPM processor**



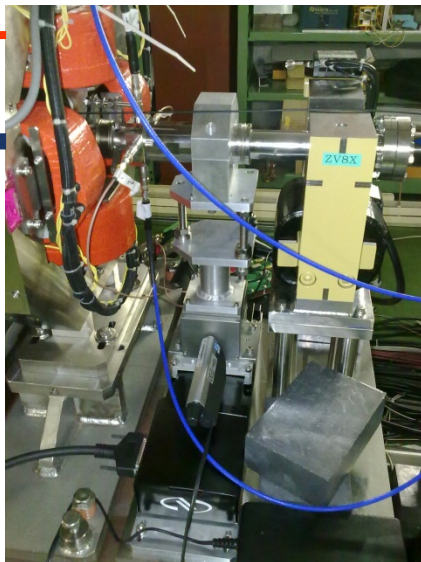
**FPGA-based digital
processor**



Kicker drive amplifier

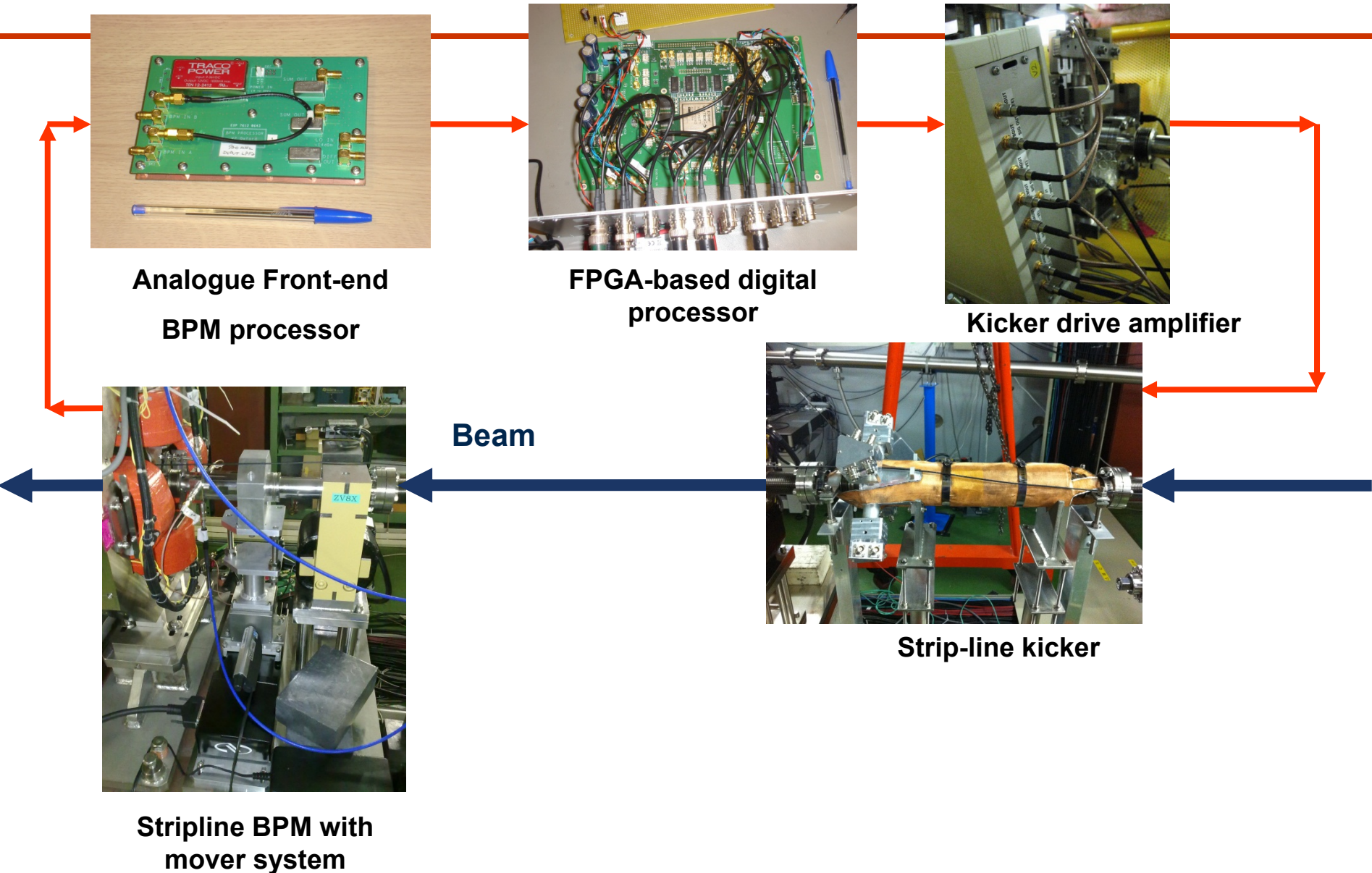


Strip-line kicker

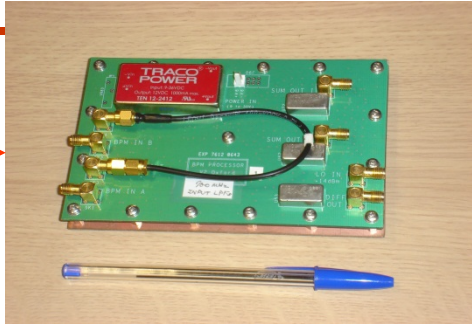


**Stripline BPM with
mover system**

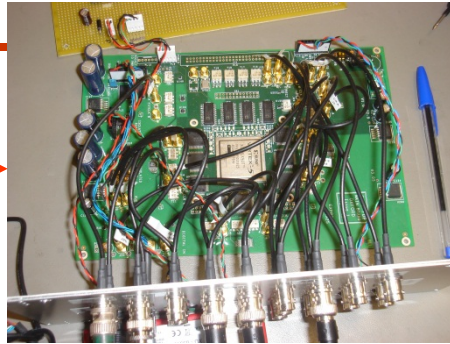
Beam



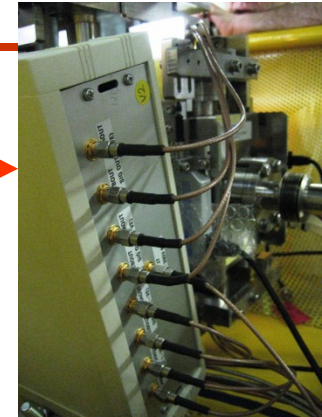
Upstream FONT5 System



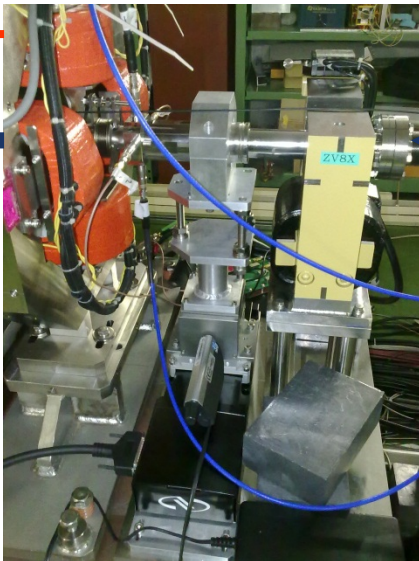
**Analogue Front-end
BPM processor**



**FPGA-based digital
processor**



Kicker drive amplifier



**Stripline BPM with
mover system**

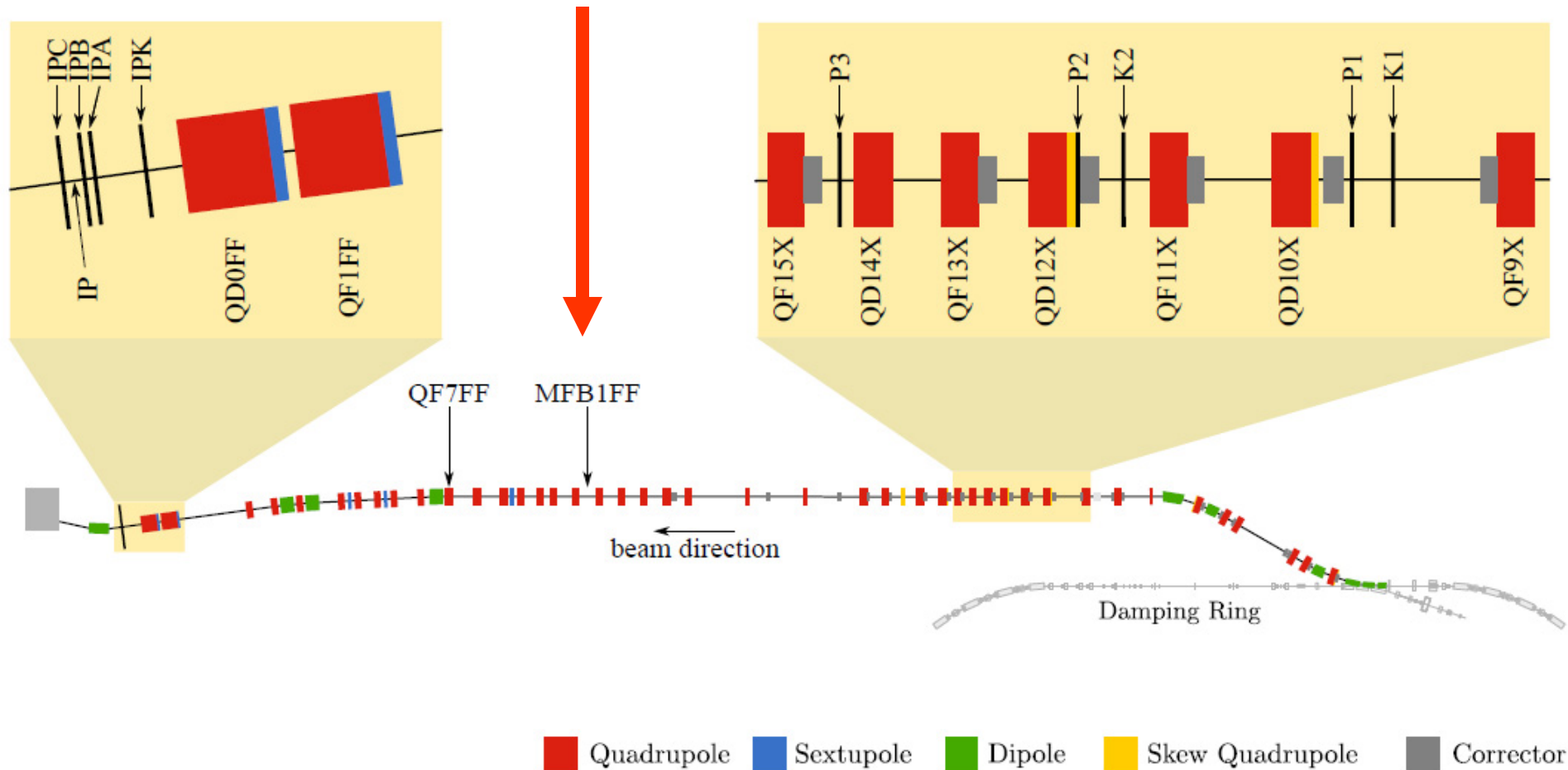


Strip-line kicker

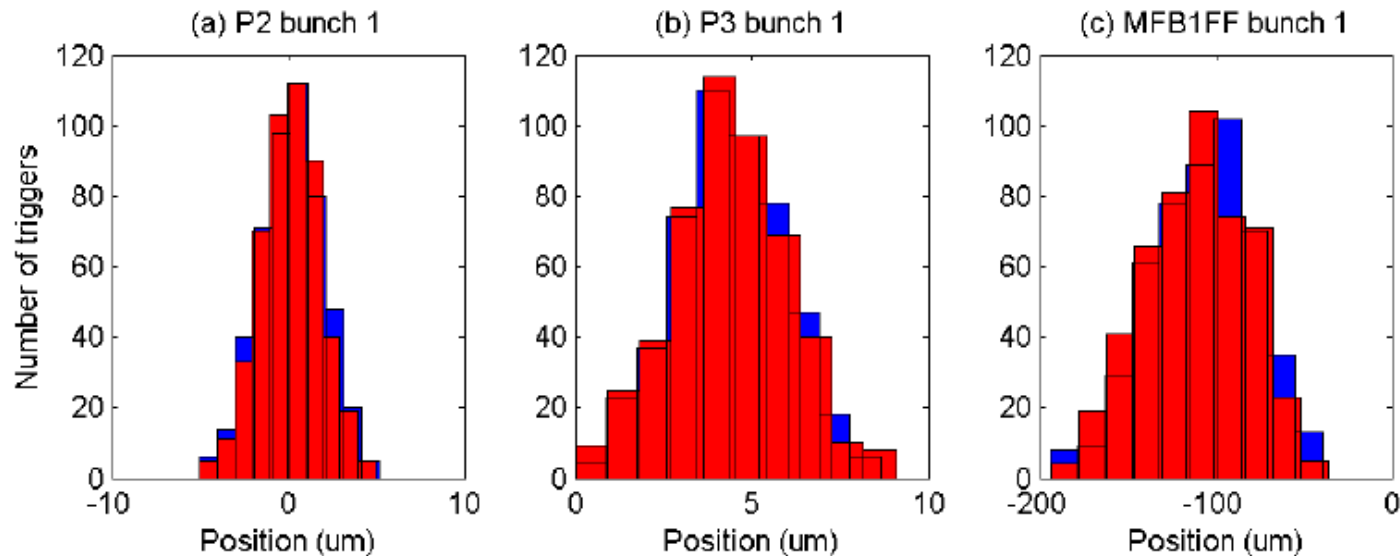
Beam

**Meets ILC requirements: BPM resolution
Dynamic range
Latency**

Witness BPM



FONT5 system performance

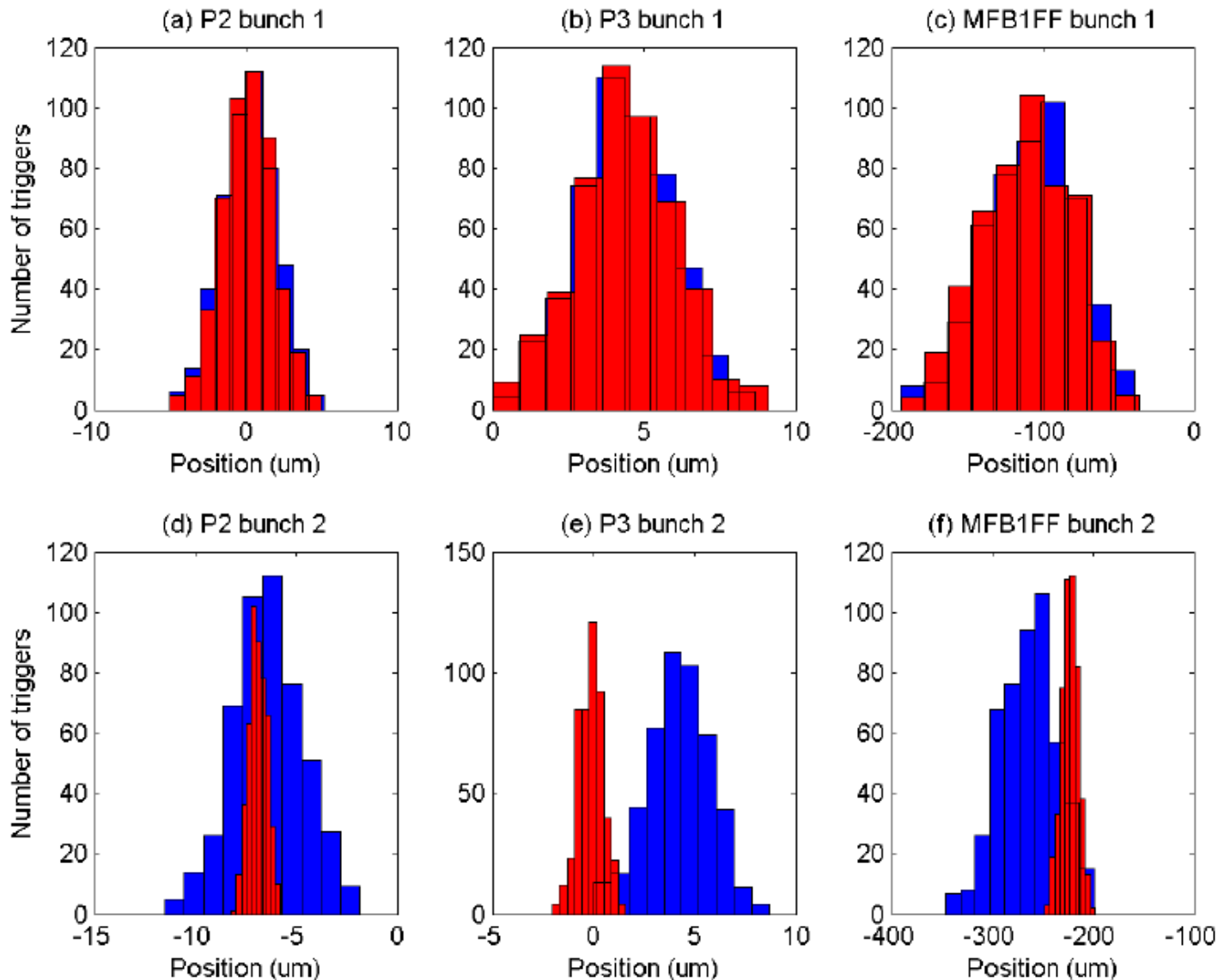


**Bunch 1:
input to FB**

FB off

FB on

FONT5 system performance



**Bunch 1:
input to FB**

FB off
FB on

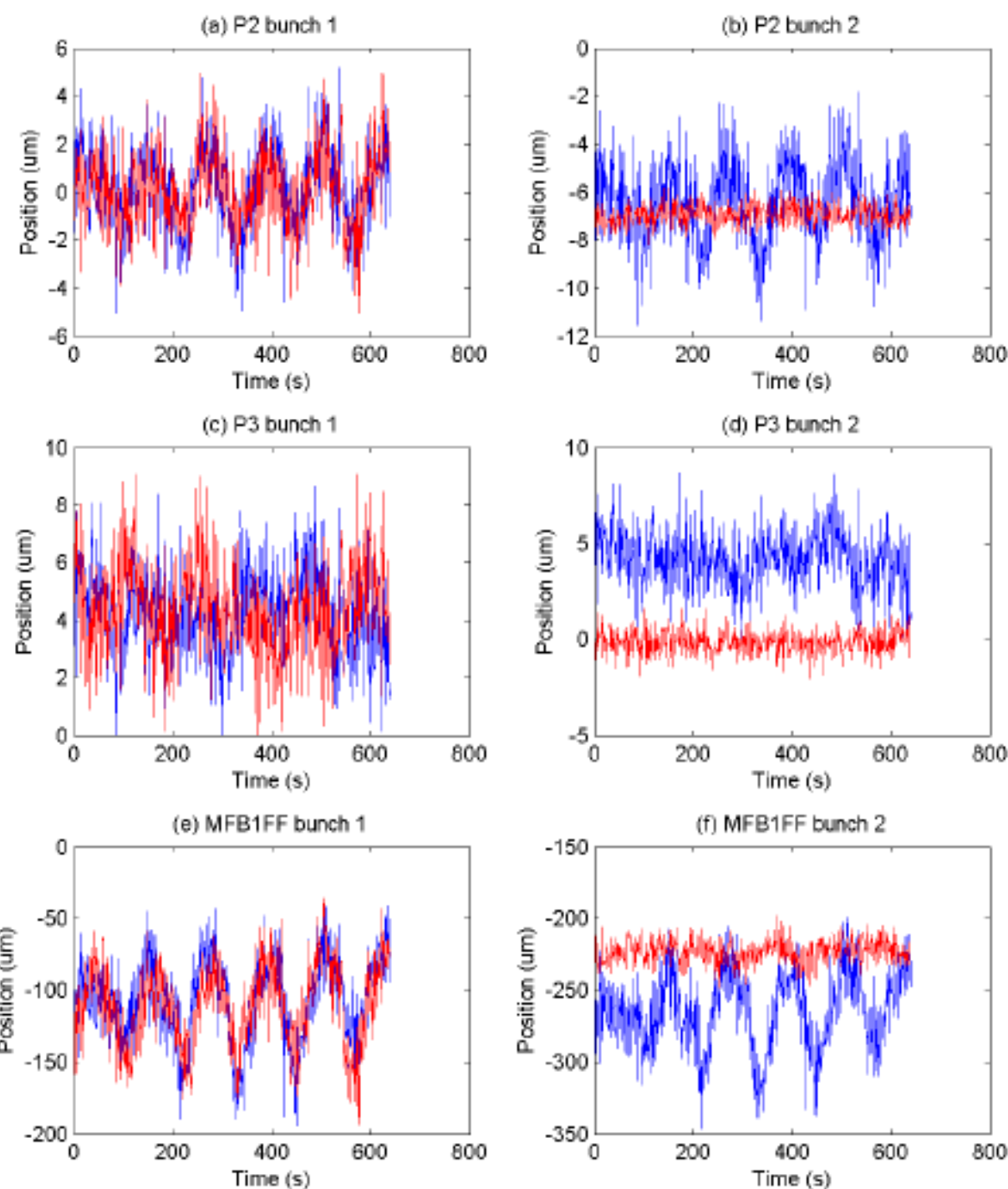
**Bunch 2:
corrected**

FB off
FB on

Time sequence

**Bunch 2:
corrected**

FB off
FB on

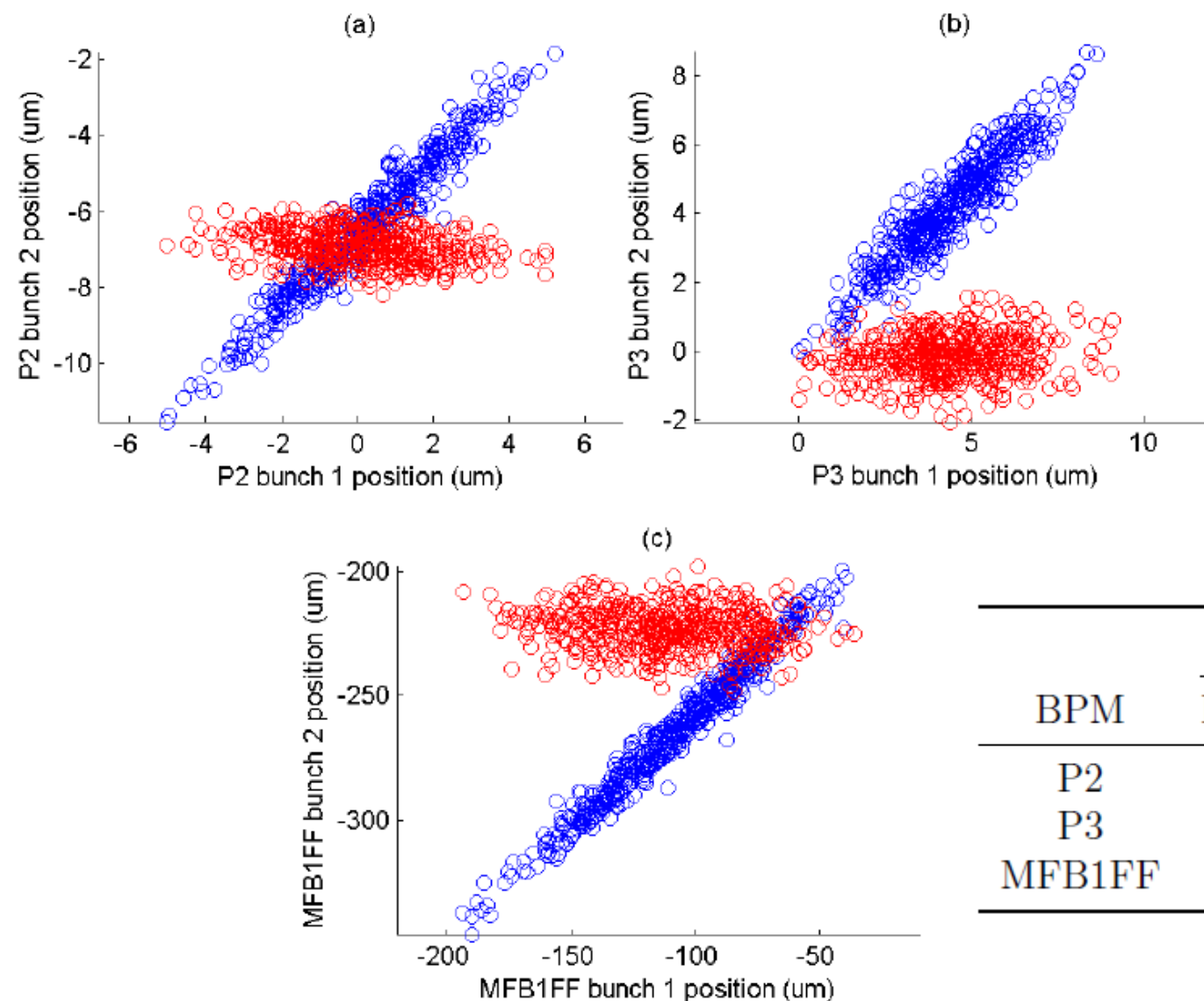


Jitter reduction

BPM	Position jitter (μm)			
	Bunch 1		Bunch 2	
	Feedback off	Feedback on	Feedback off	Feedback on
P2	1.80 ± 0.06	1.70 ± 0.05	1.74 ± 0.06	0.44 ± 0.01
P3	1.56 ± 0.05	1.66 ± 0.05	1.55 ± 0.05	0.61 ± 0.02
MFB1FF	29.9 ± 1.0	29.4 ± 0.9	27.5 ± 0.9	8.3 ± 0.3

Factor ~ 3.5 improvement

Bunch 1 – bunch 2 correlation

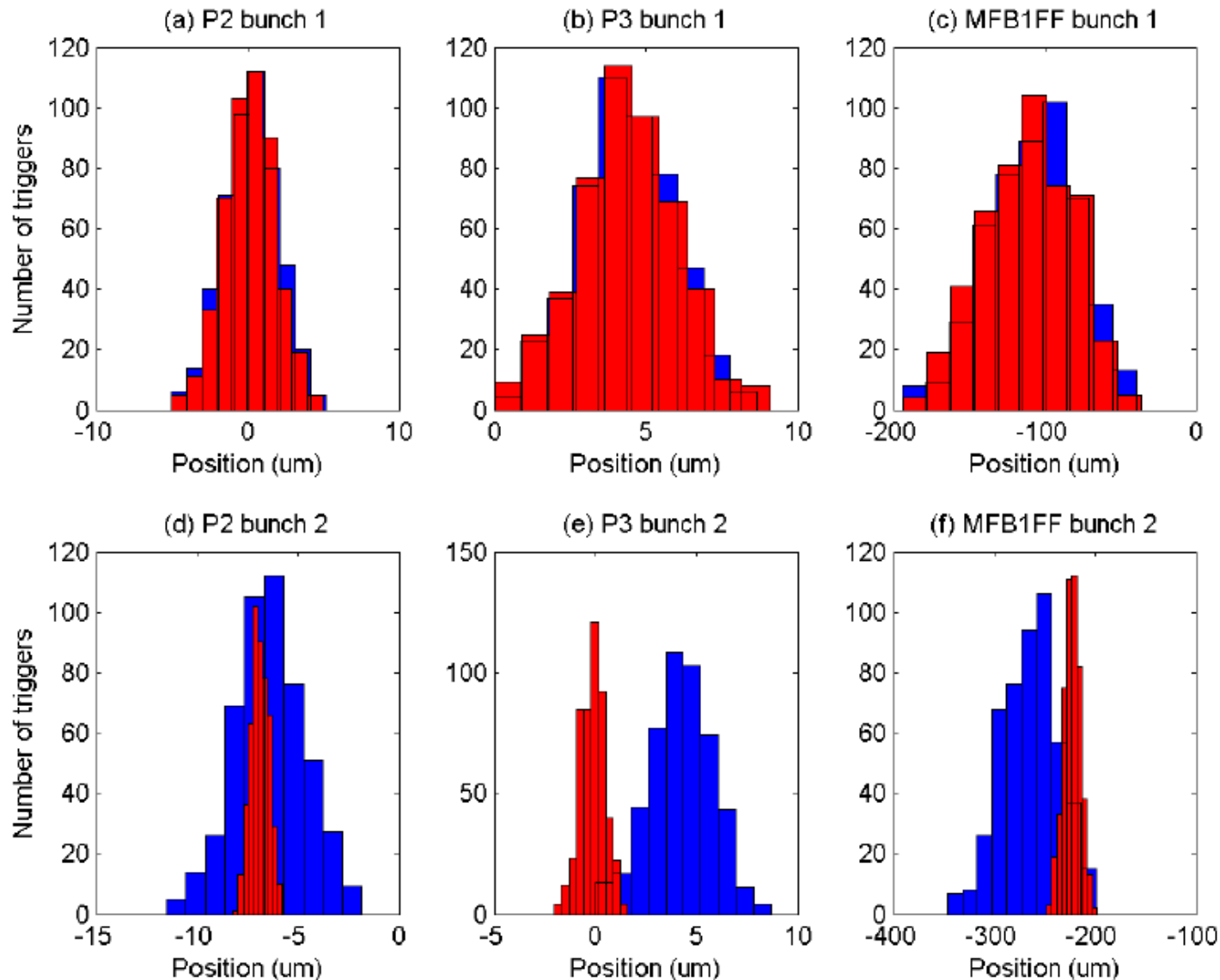


FB off
FB on

BPM	ρ_{12} (%)	
	Feedback off	Feedback on
P2	$+96.9 \pm 0.3$	-25 ± 4
P3	$+93.3 \pm 0.6$	$+15 \pm 4$
MFB1FF	$+98.3 \pm 0.2$	-14 ± 4

Feedback loop

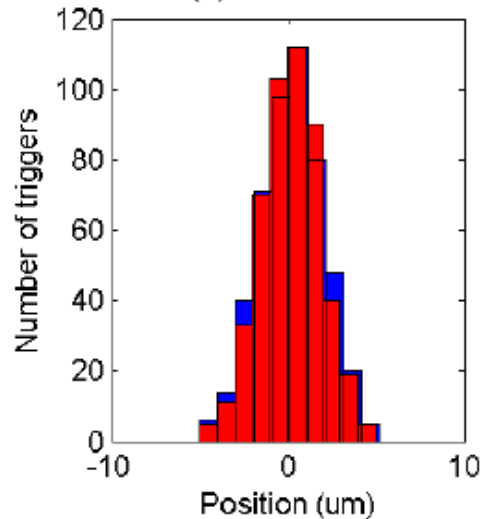
witness



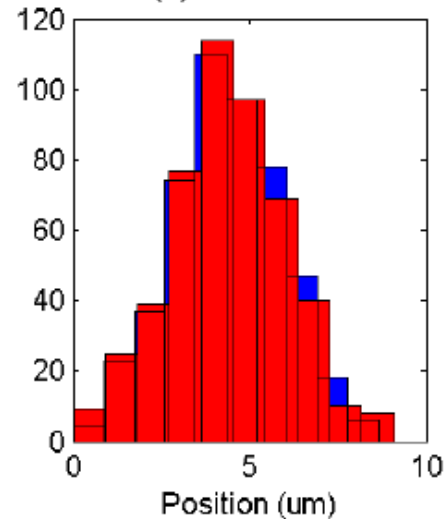
Feedback loop

predict

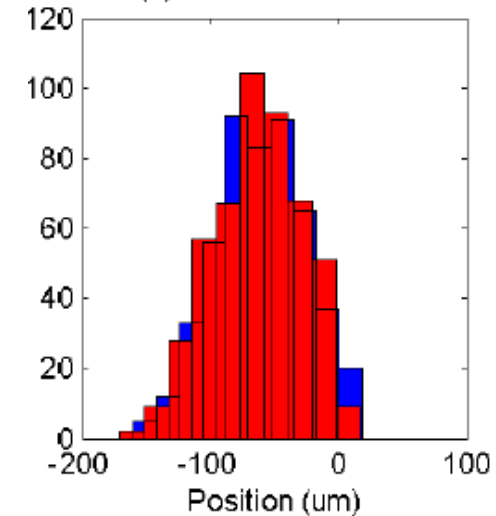
(a) P2 bunch 1



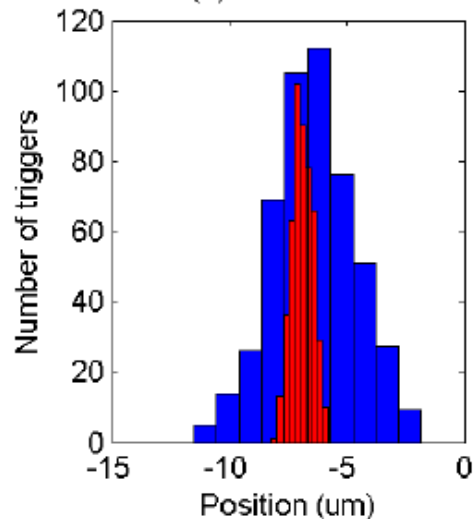
(b) P3 bunch 1



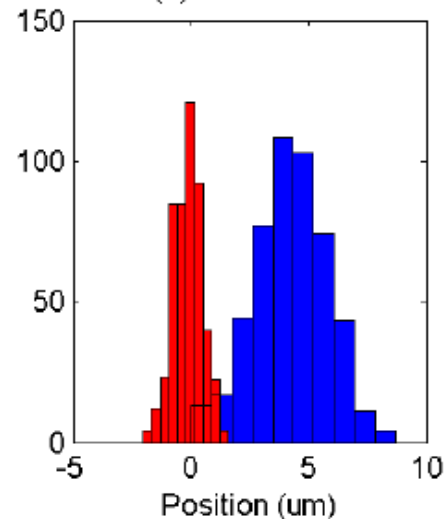
(a) MFB1FF bunch 1



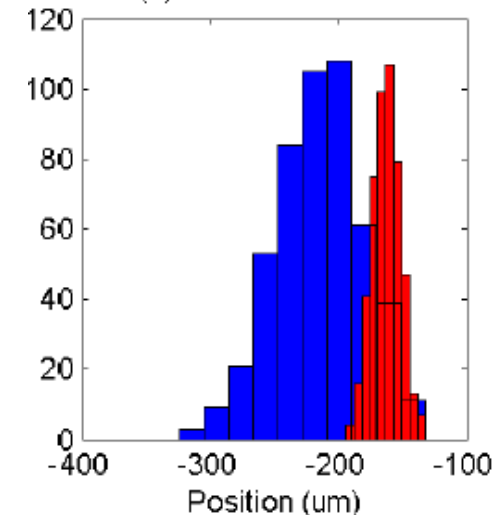
(d) P2 bunch 2



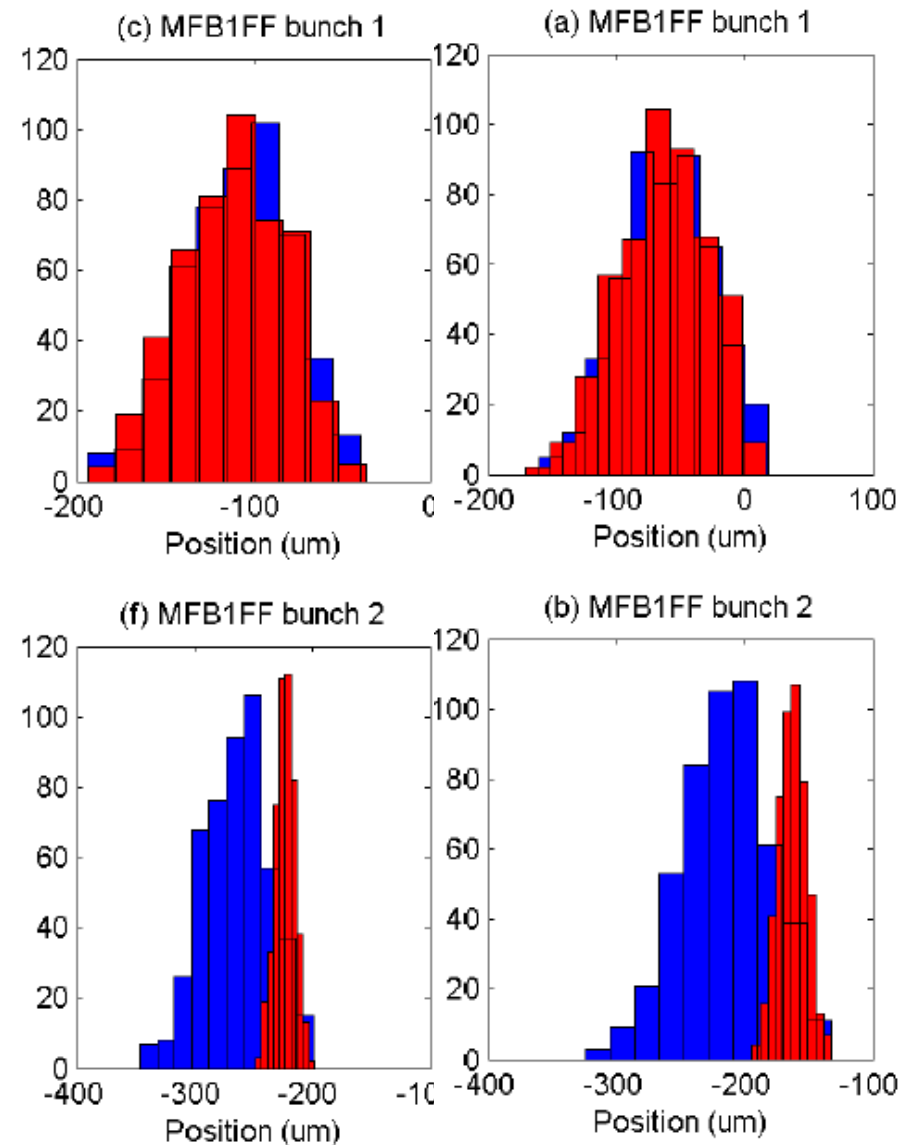
(e) P3 bunch 2



(b) MFB1FF bunch 2

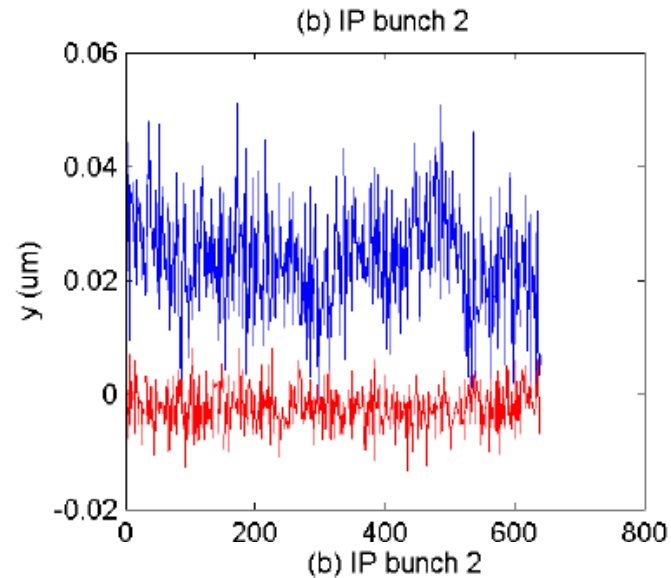
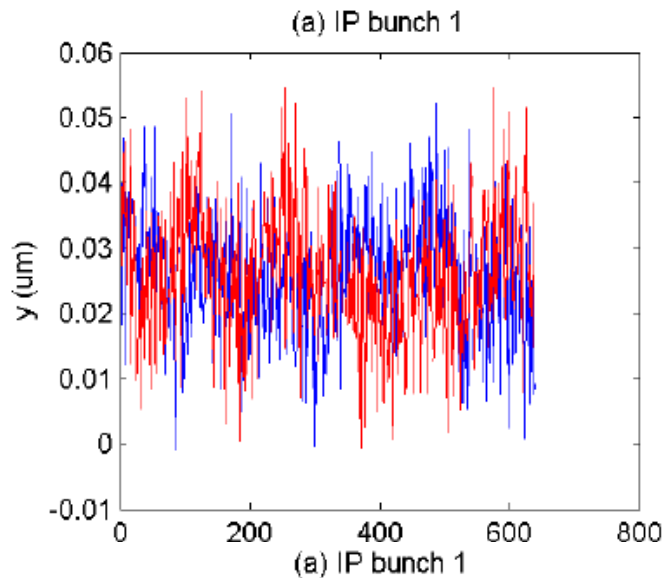


Witness BPM: measure predict



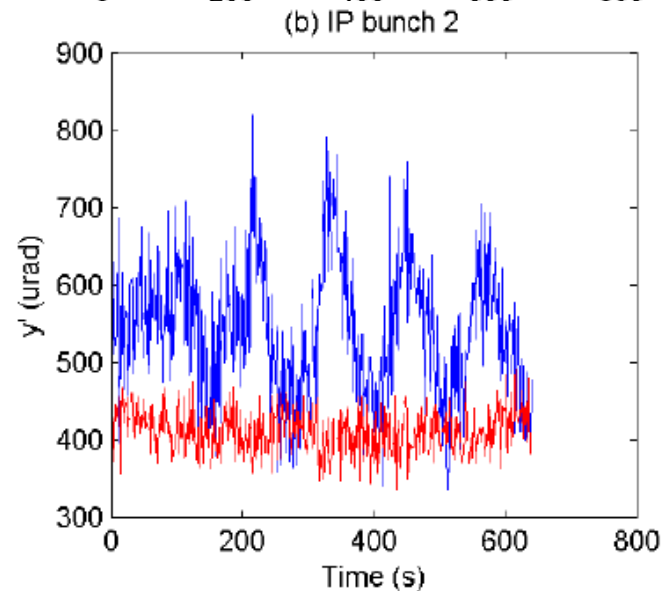
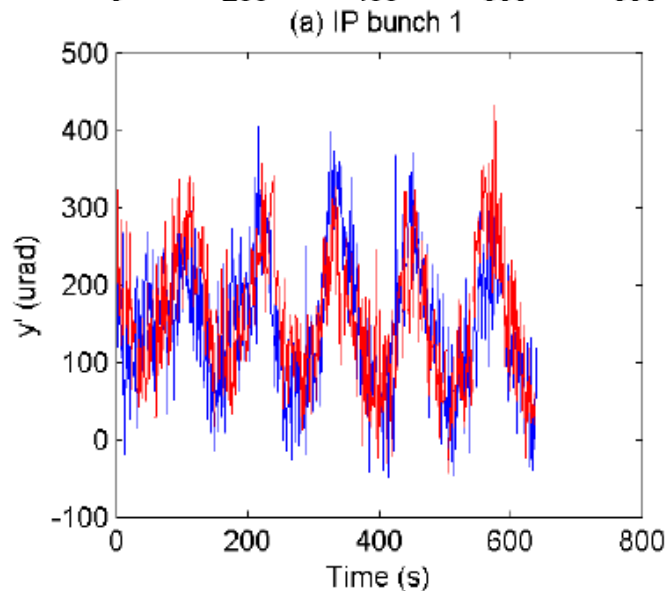
Predicted jitter reduction at IP

y



FB off
FB on

y'



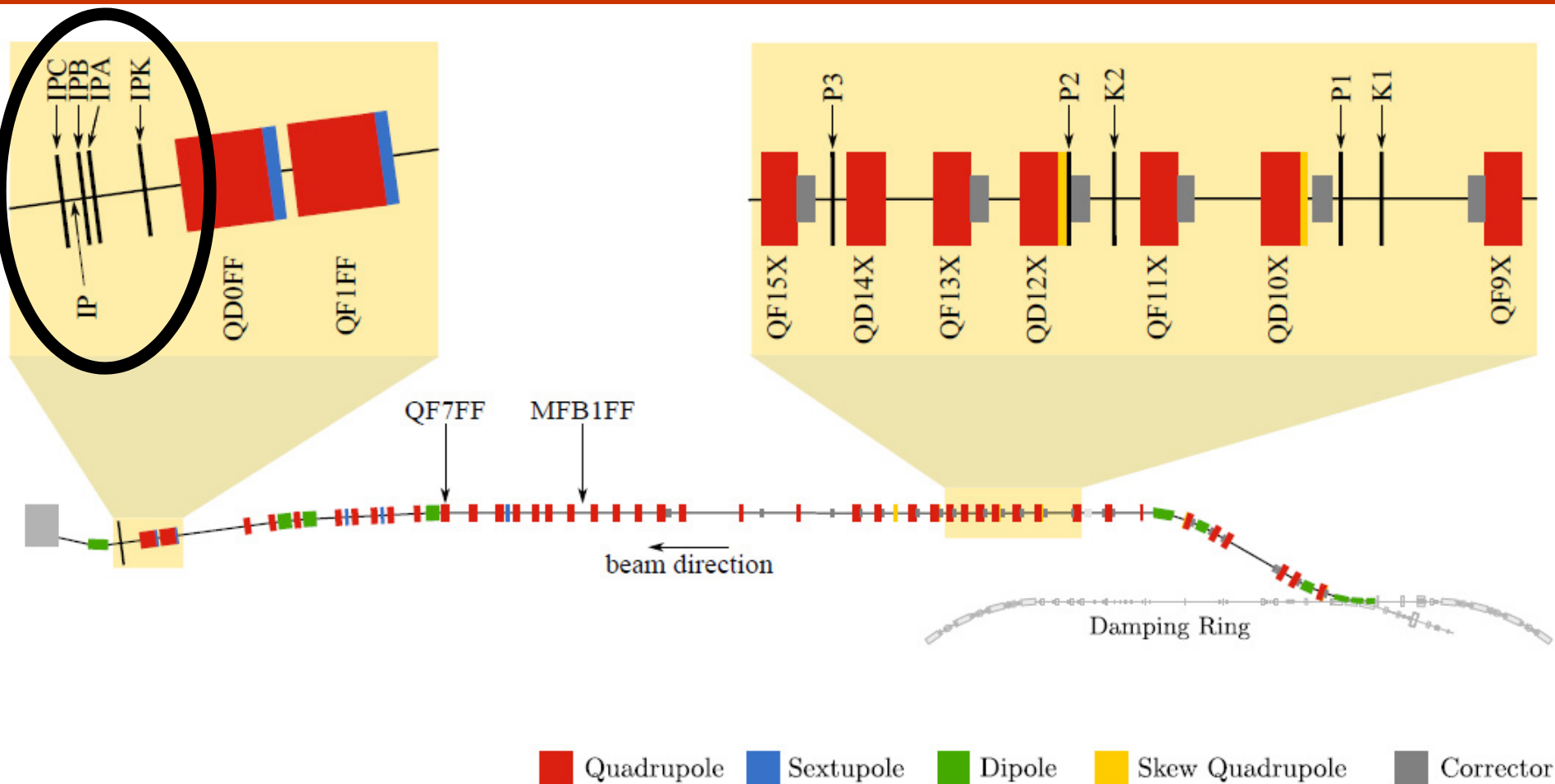
Predicted jitter reduction at IP

Bunch	Position y jitter (nm)		Angle y' jitter (urad)	
	Feedback off	Feedback on	Feedback off	Feedback on
1	9.5 ± 0.3	10.1 ± 0.3	89 ± 3	87 ± 3
2	9.4 ± 0.3	3.6 ± 0.1	87 ± 3	28 ± 1

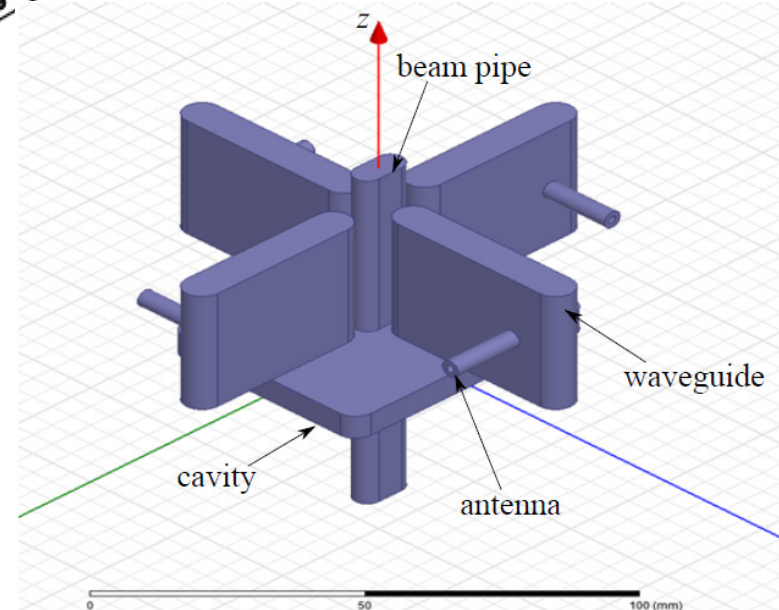
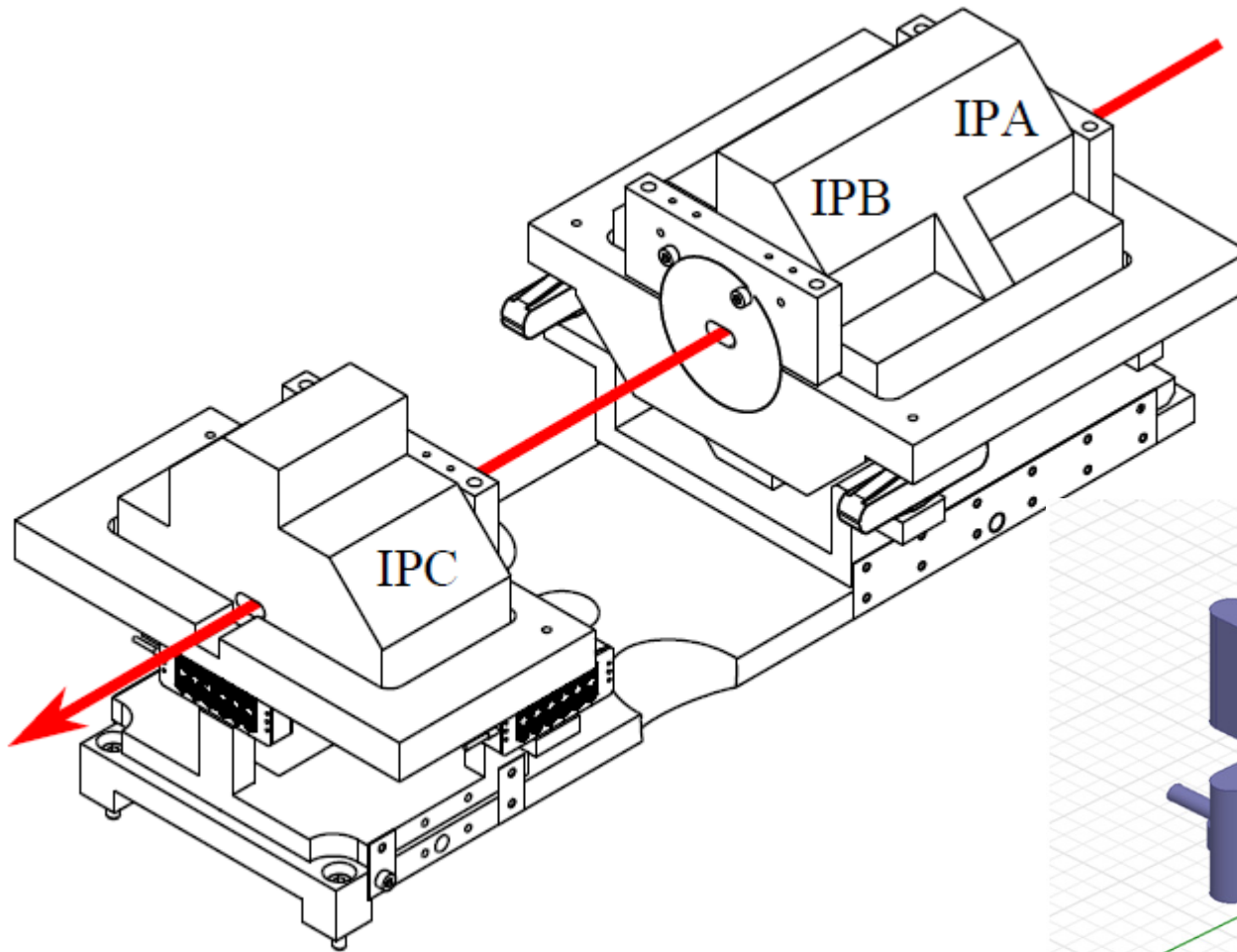
**Predict position stabilised
at few nanometre level...**

How to measure it?!

Cavity BPM system near IP



IP cavity BPM system

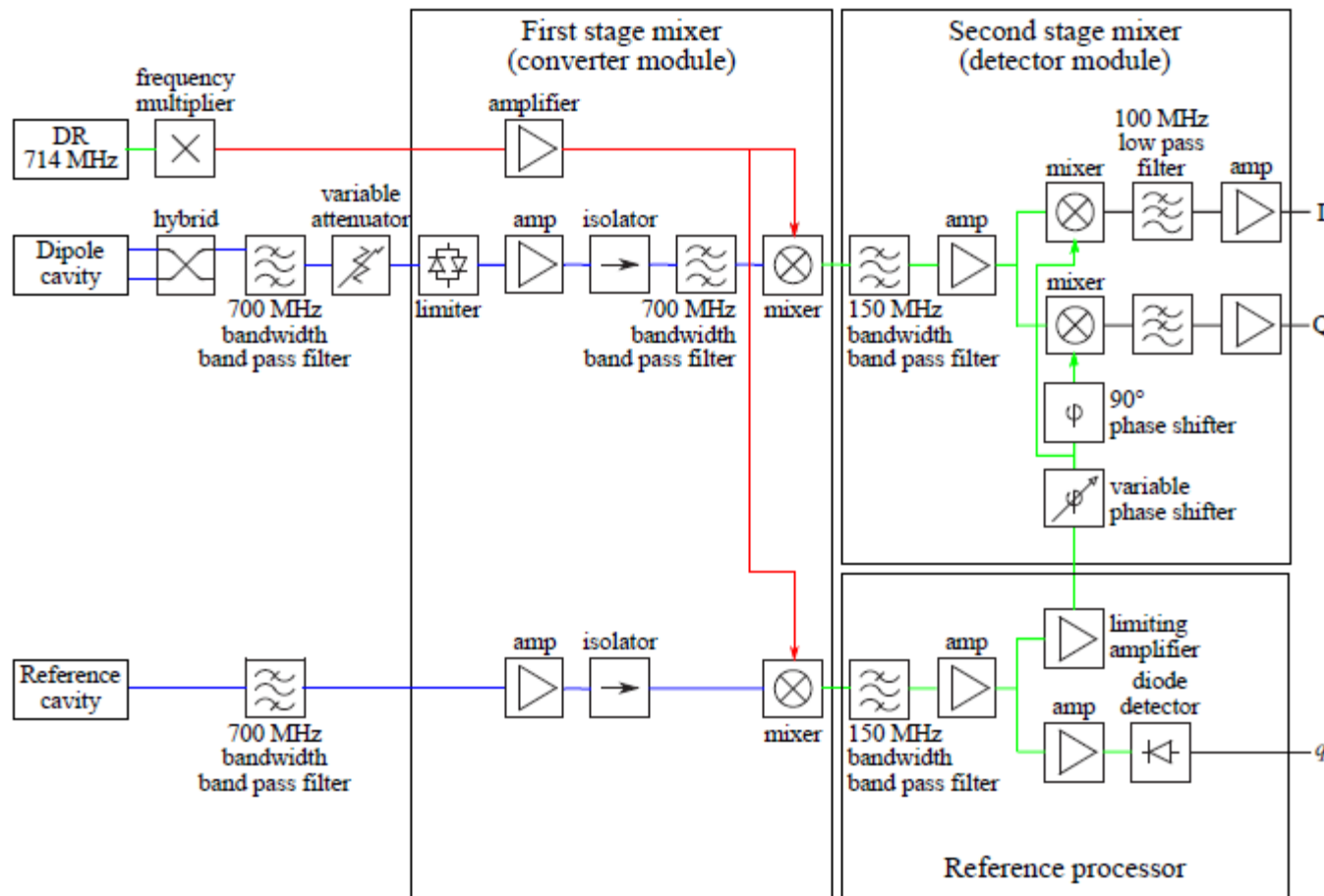


Low-Q cavity BPMs

Design parameters

Parameter			Dipole cavities		Reference cavities	
			x port	y port	x cavity	y cavity
Resonant frequency	f_{mn}	(GHz)	5.712	6.426	5.711	6.415
Internal quality factor	$(Q_0)_{mn}$		4959	4670	1201	1229
Decay time	τ_{mn}	(ns)	18.72	17.23	33.16	30.03

Cavity BPM signal processing



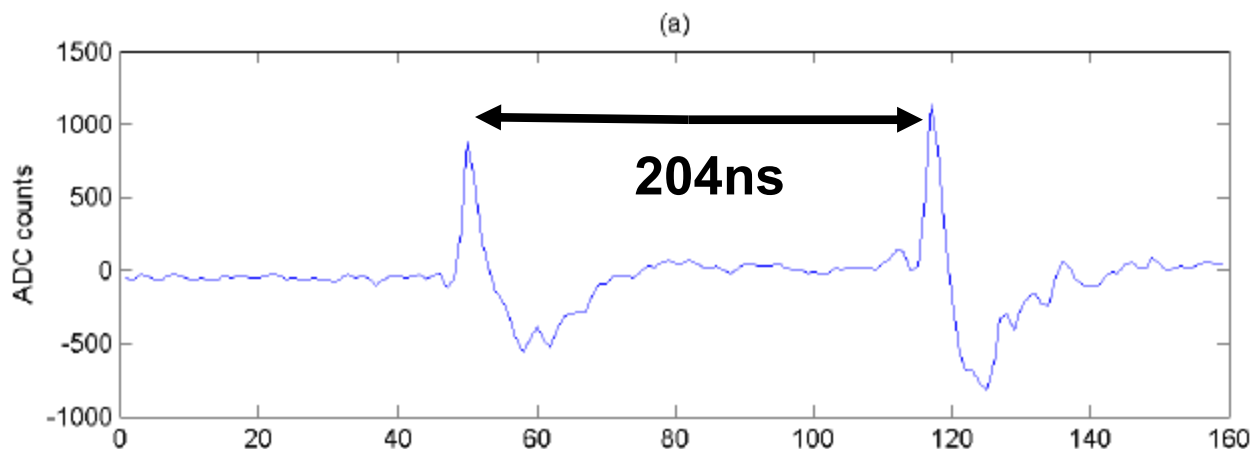
I → **I'**
Q → **Q'**

**bunch
charge**

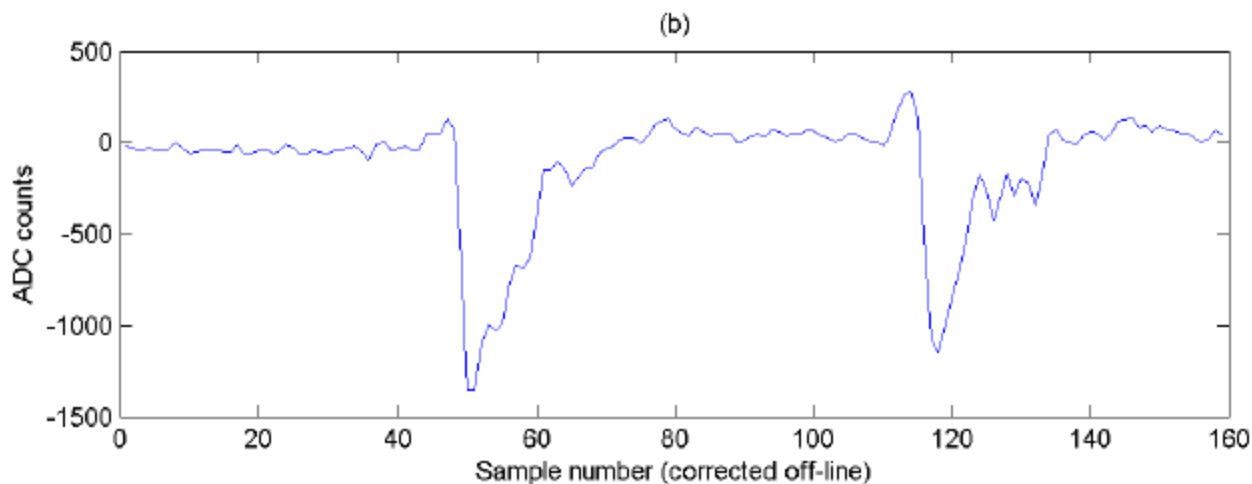
Cavity BPM outputs (2-bunch train)

Single-shot measurement

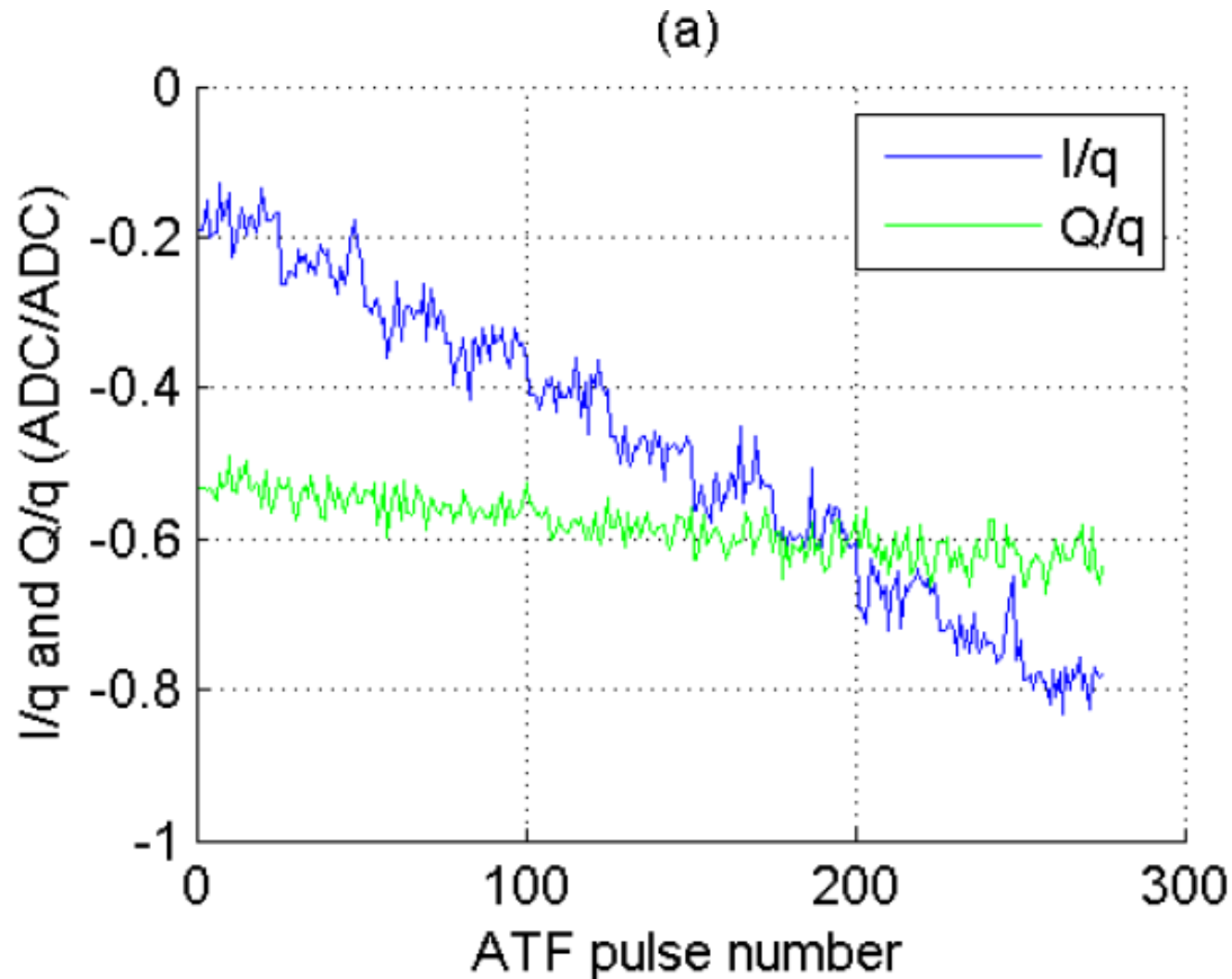
I



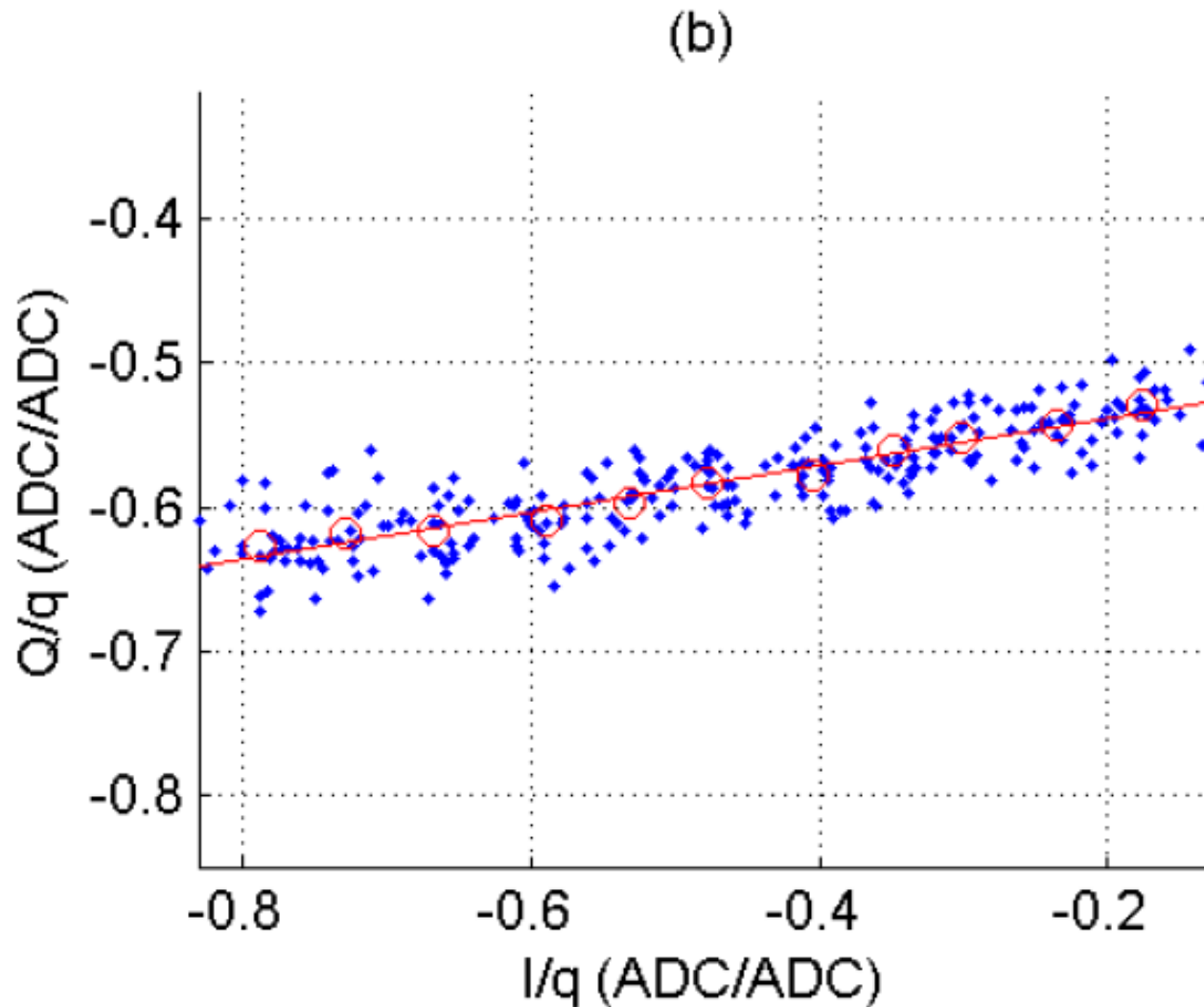
Q



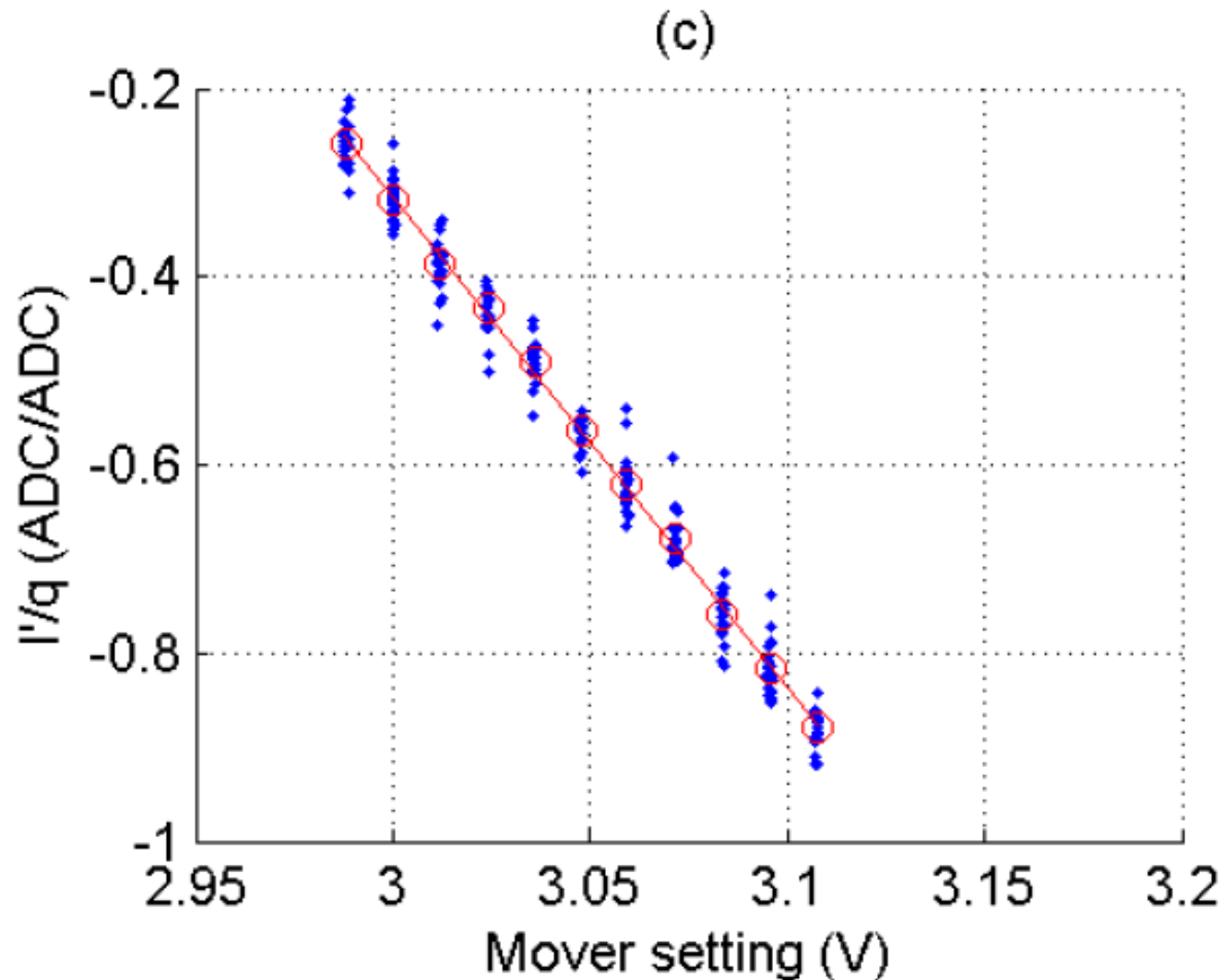
Example position calibration: 1)



Example position calibration: 2)



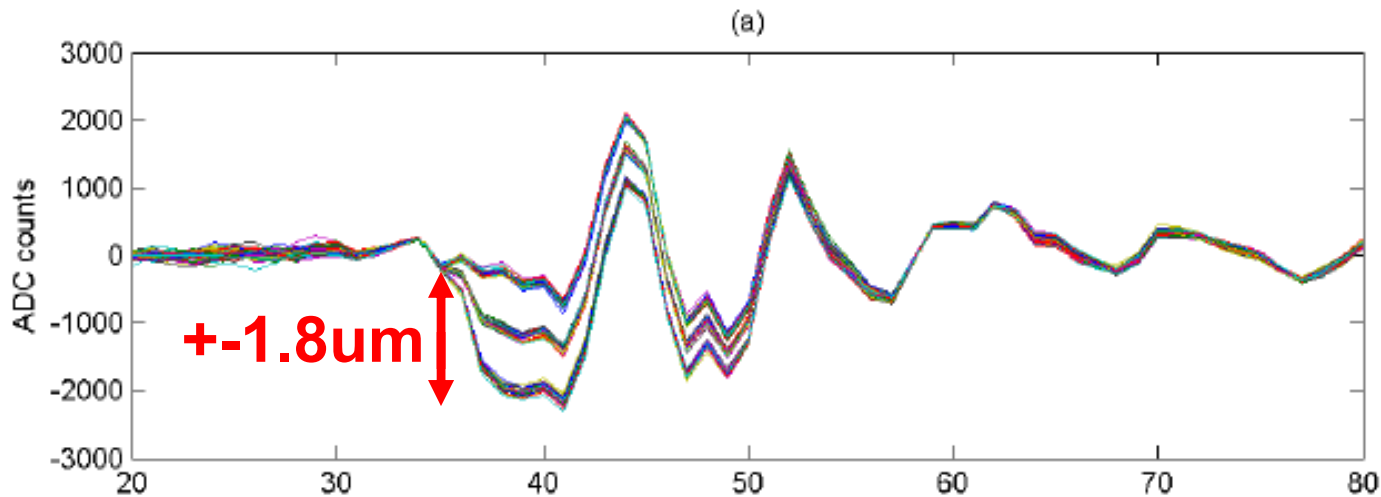
Example position calibration: 3)



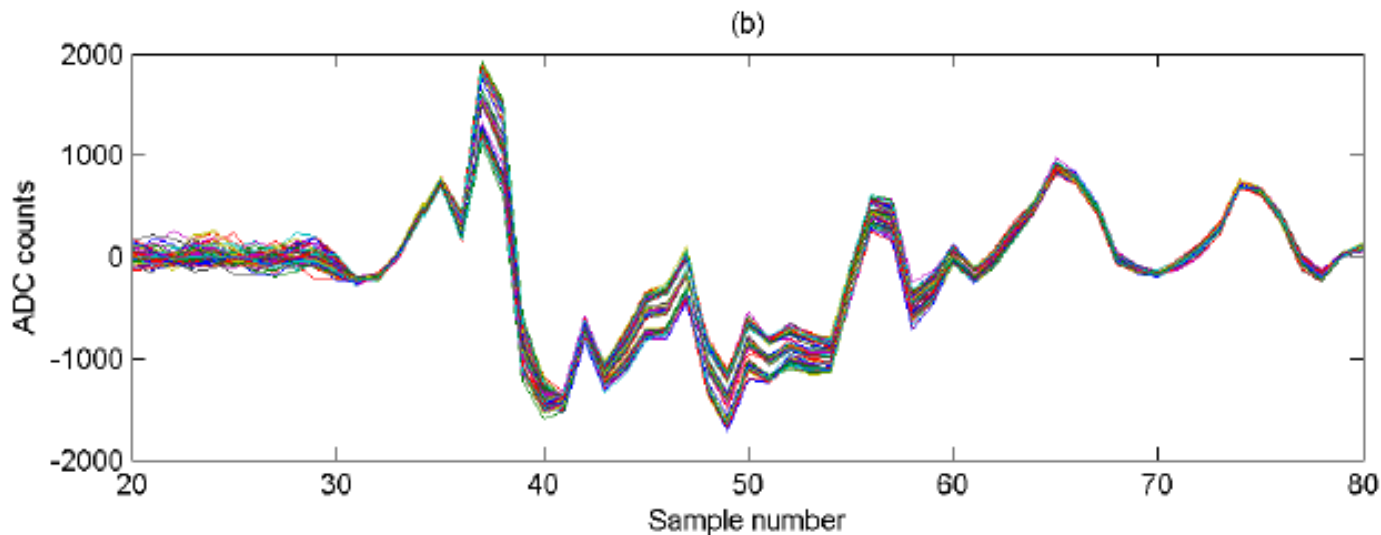
Comments

- **Signal levels $\rightarrow$ saturation $\rightarrow$ non-linear response**
- **Dynamic range $\leftrightarrow$ resolution**
- **Operate with (remotely controlled) attenuation**
- **Optimal resolution (0db) $\rightarrow$
dynamic range $\pm 3\mu\text{m}$ w.r.t. nominal centre**
- **Beam setup + beam quality are critical**

Waveforms at 0db – ugly!

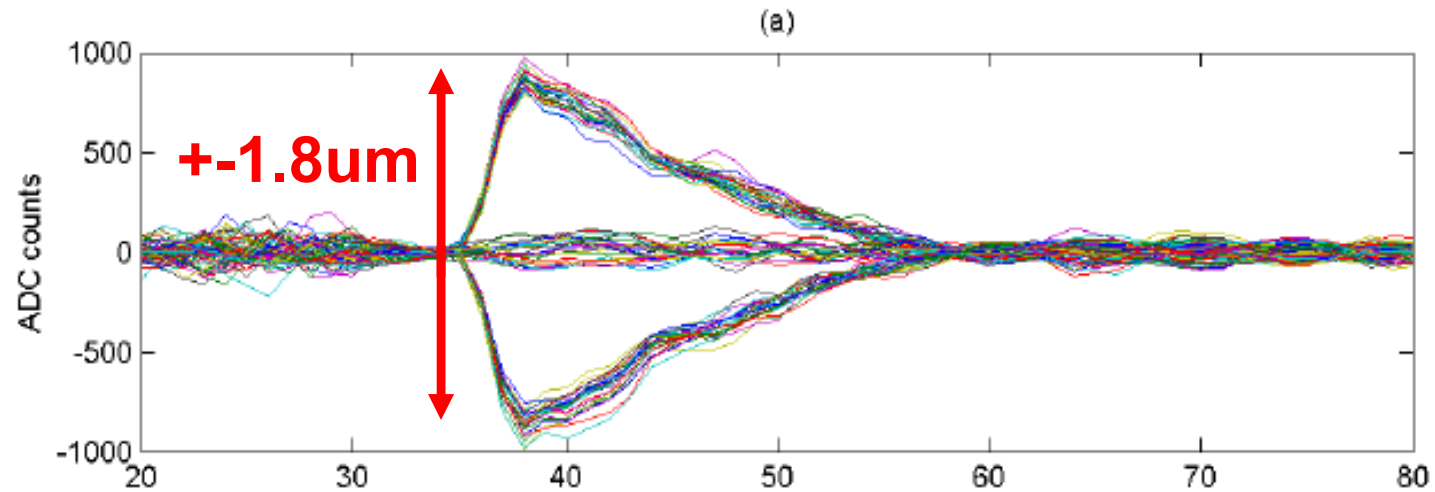


**Position
information
superposed
on static
artefact**

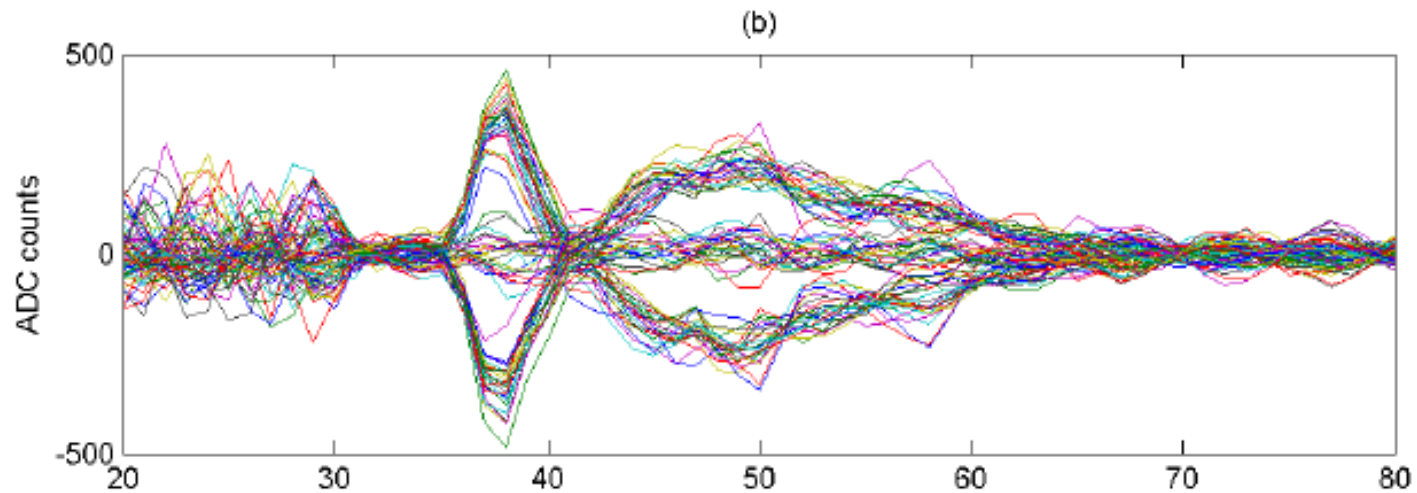


Mean-subtracted waveforms

I

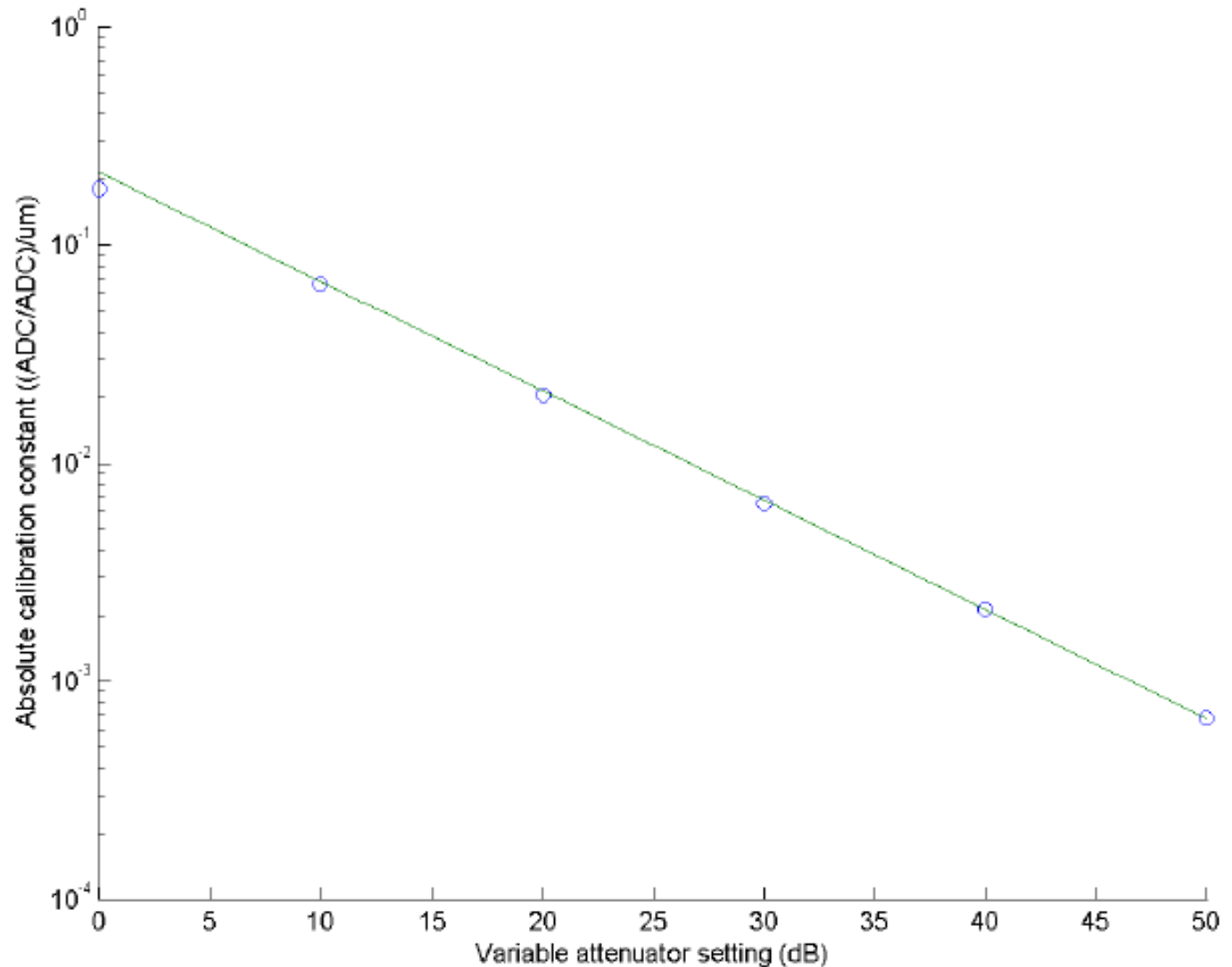


Q

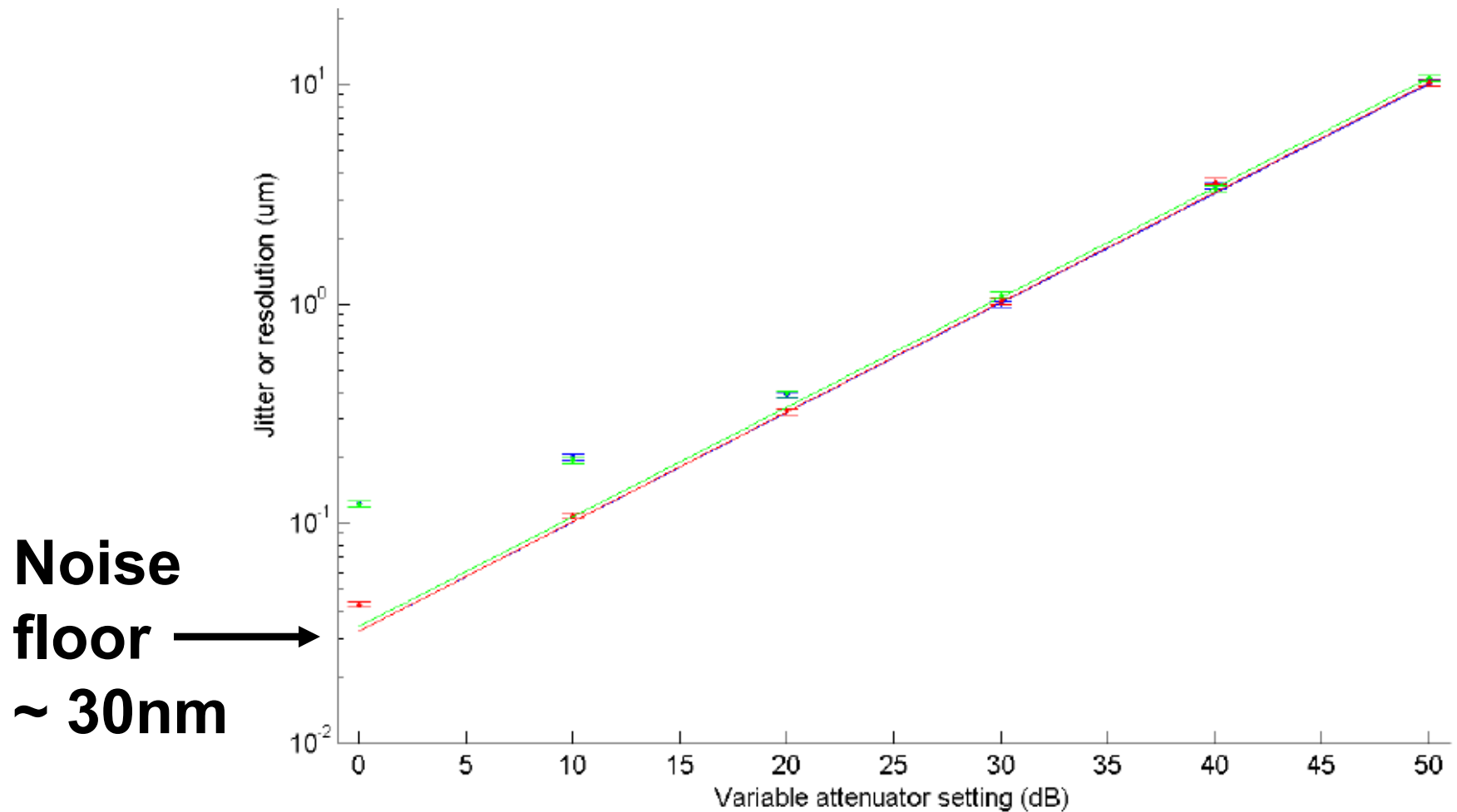


BPM response vs. attenuation

position
calibration
scale

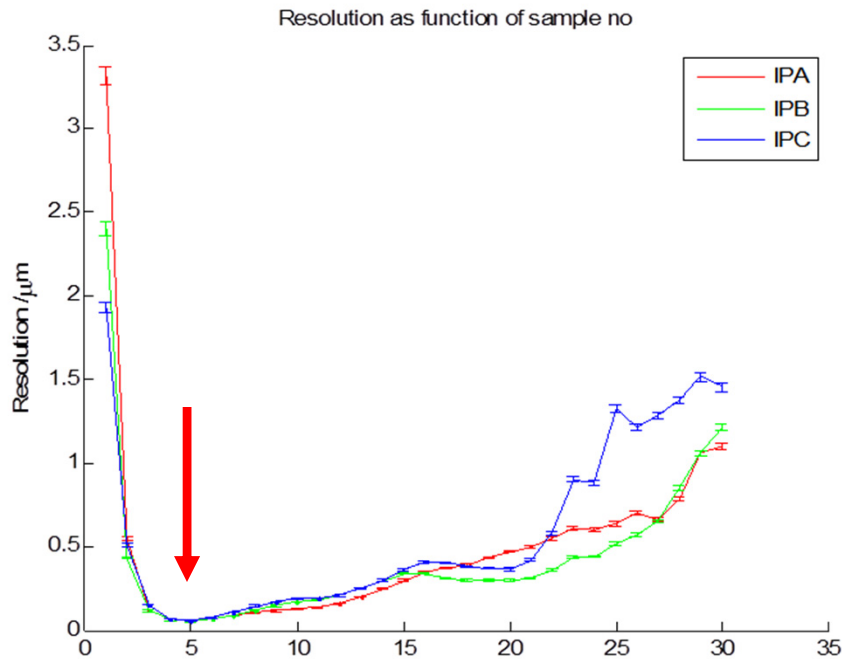


Beam jitter vs. attenuation

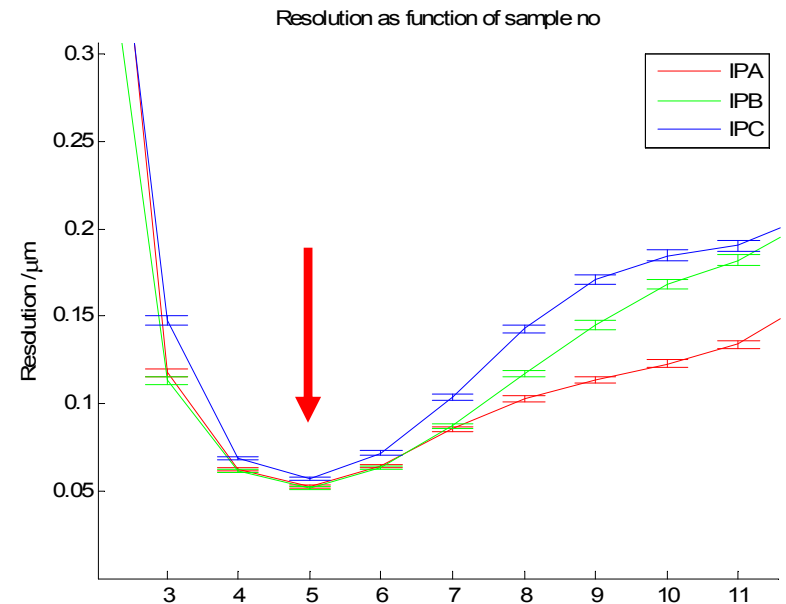


Resolution vs. sample # (0db)

Fitting method



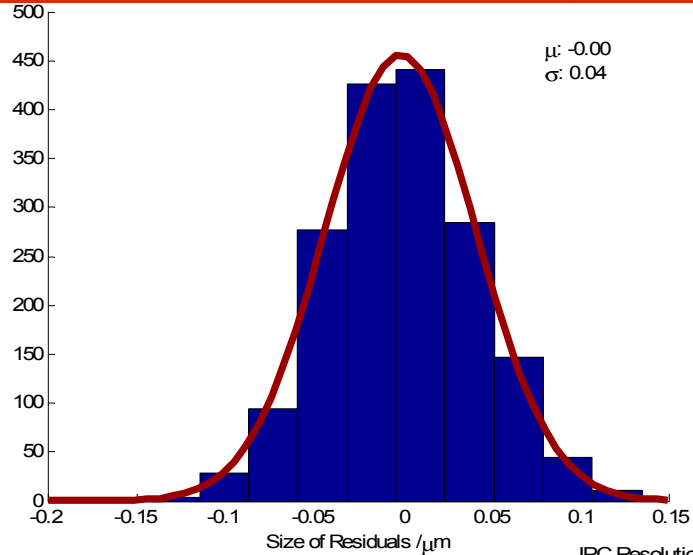
Geometric method



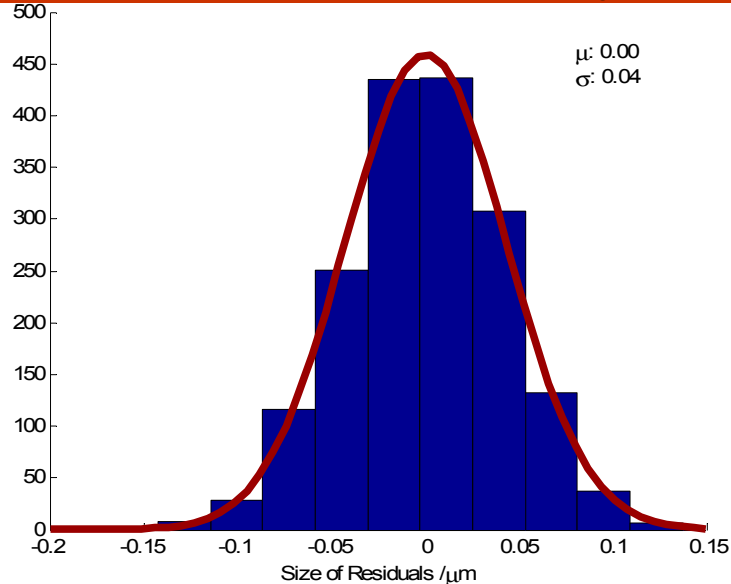
Fitting			Geom
52nm	52nm	57nm	54nm

Resolution – integrate samples 3 - 10

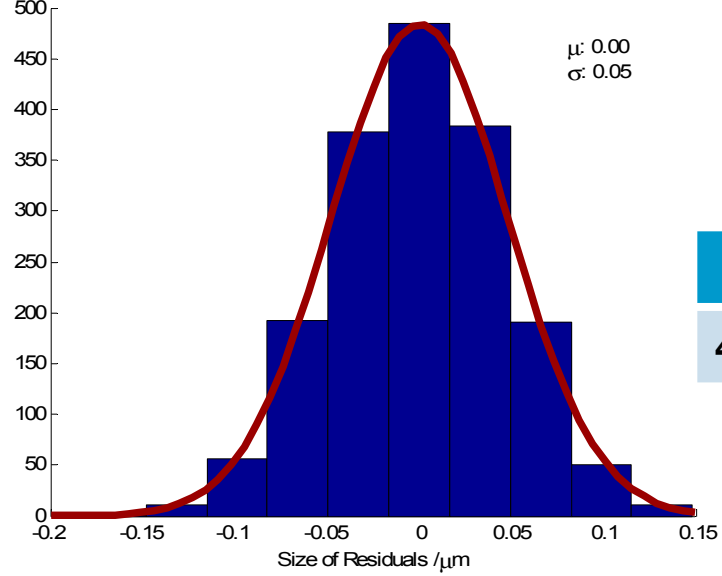
IPA Resolution Residuals from Least Squares Fitting



IPB Resolution Residuals from Least Squares Fitting

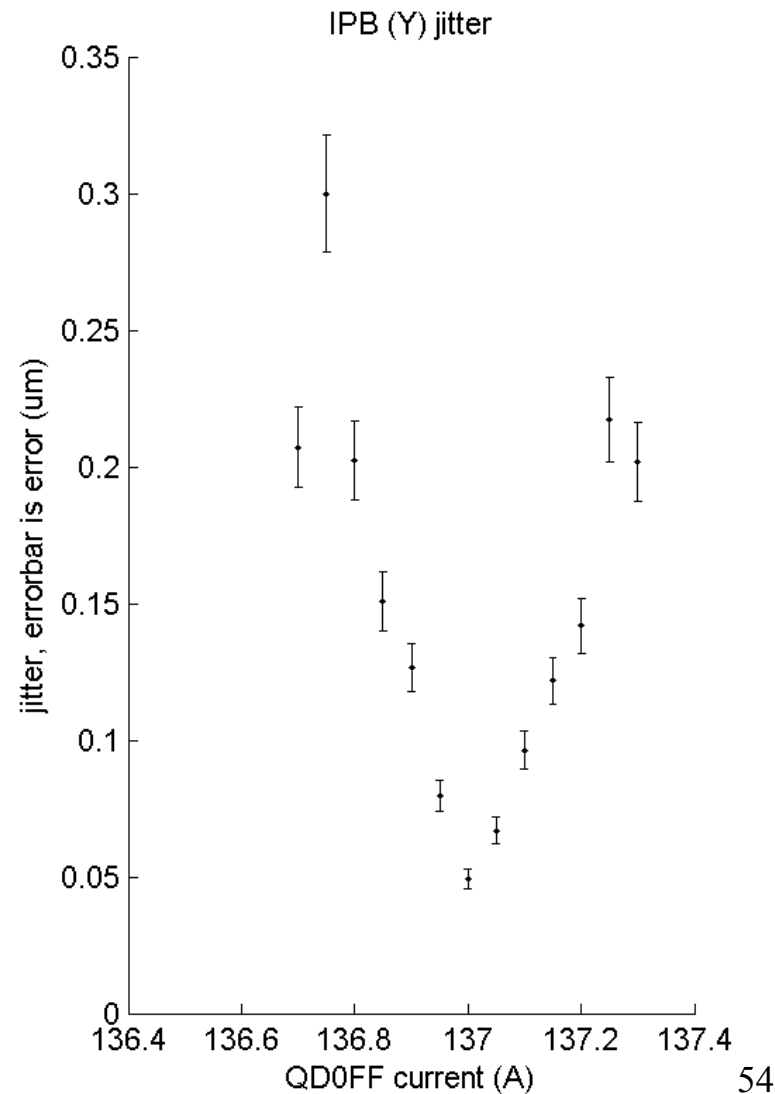


IPC Resolution Residuals from Least Squares Fitting

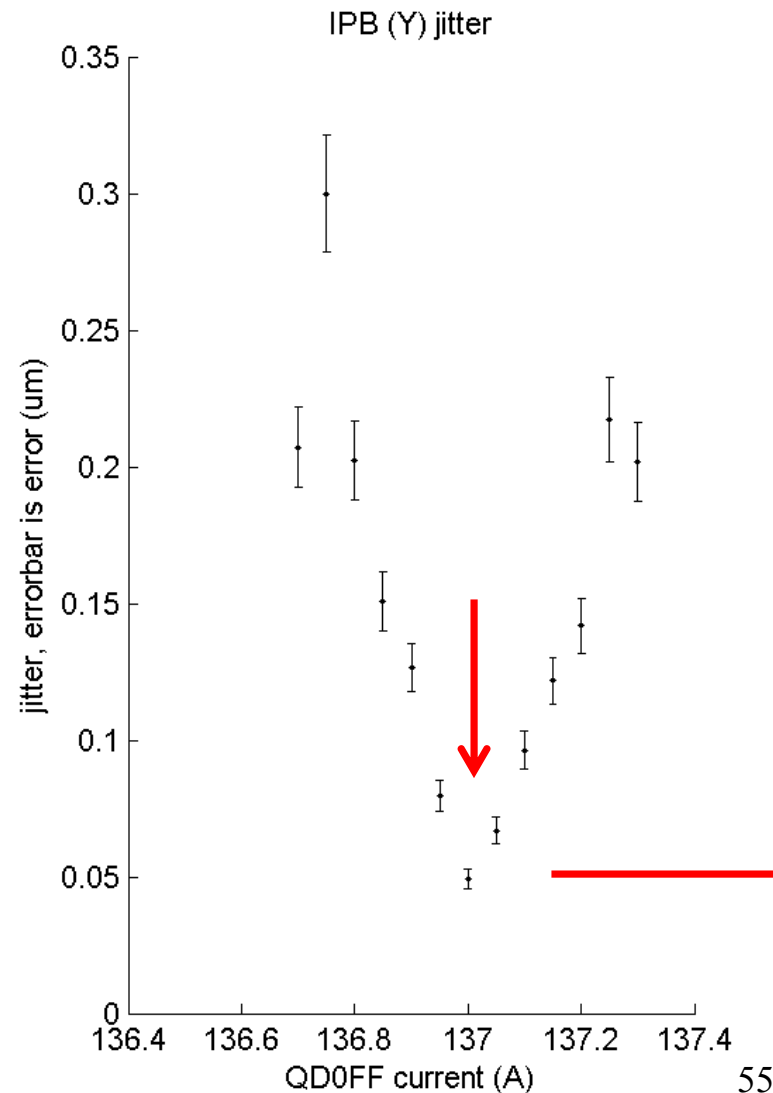


Fitting			Geom
42nm	42nm	47nm	55nm

Jitter vs. QD0FF setting (waist scan)



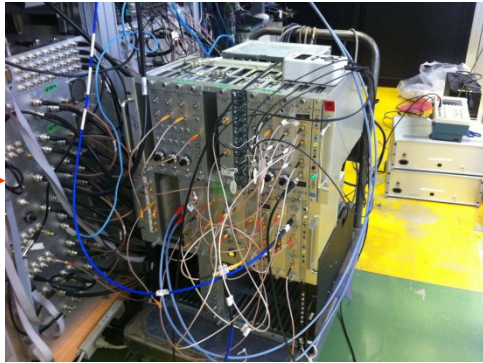
Jitter vs. QD0FF setting (waist scan)



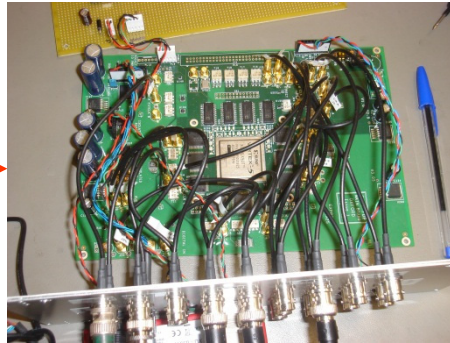
**minimum
jitter:**

**49 nm
(integration)**

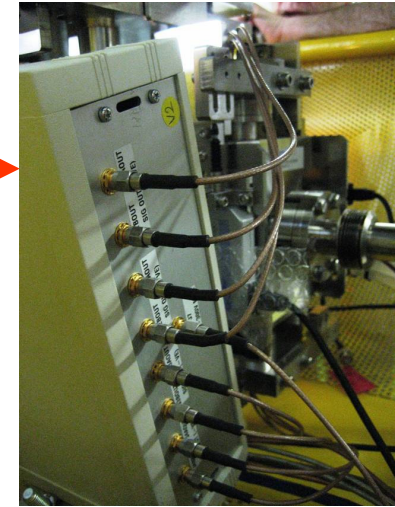
Interaction Point FONT System



Analogue Front-end
BPM processor

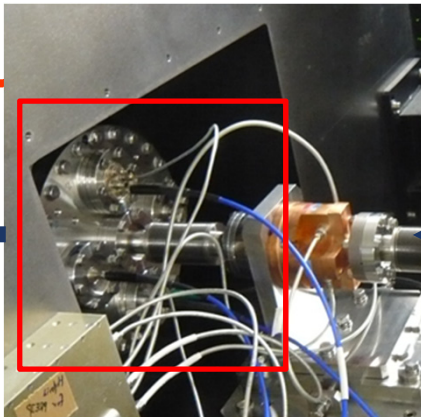


FPGA-based digital
processor

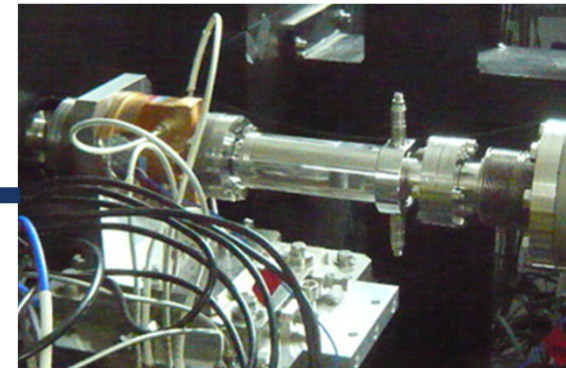


Kicker drive amplifier

Latency ~ 160ns



Cavity BPM

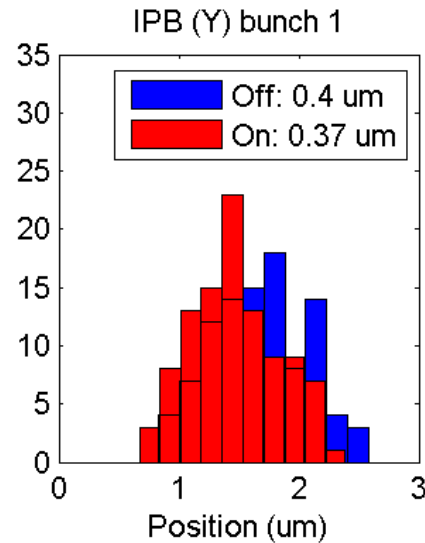


Strip-line kicker

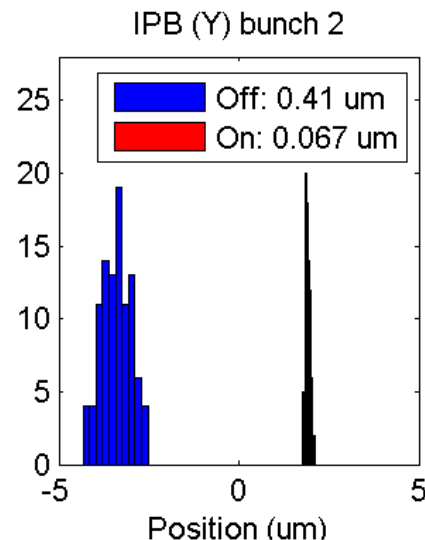
Beam

IPFB results

Bunch 1:
not corrected,
jitter $\sim 400\text{nm}$



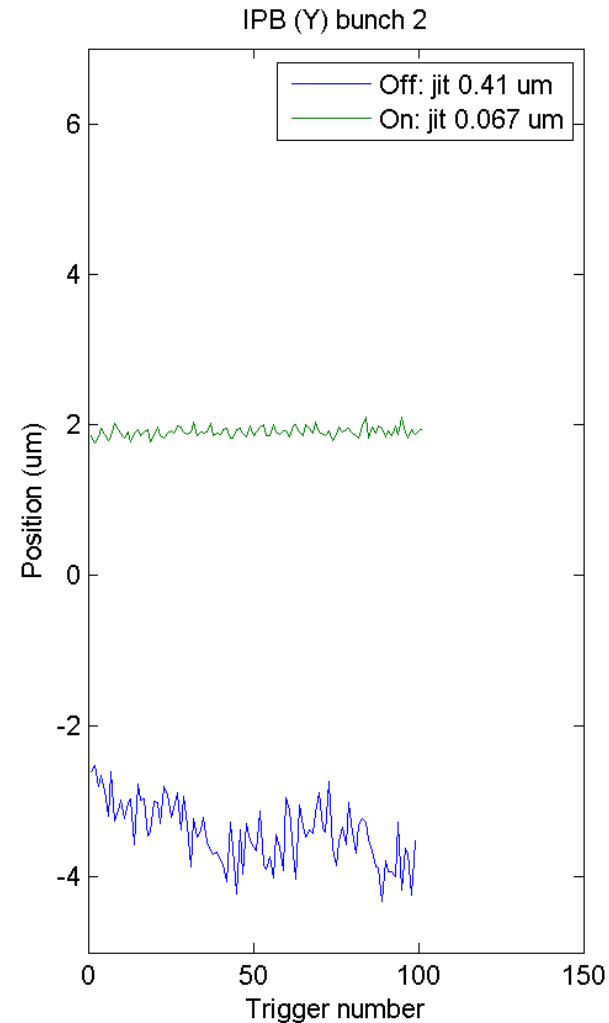
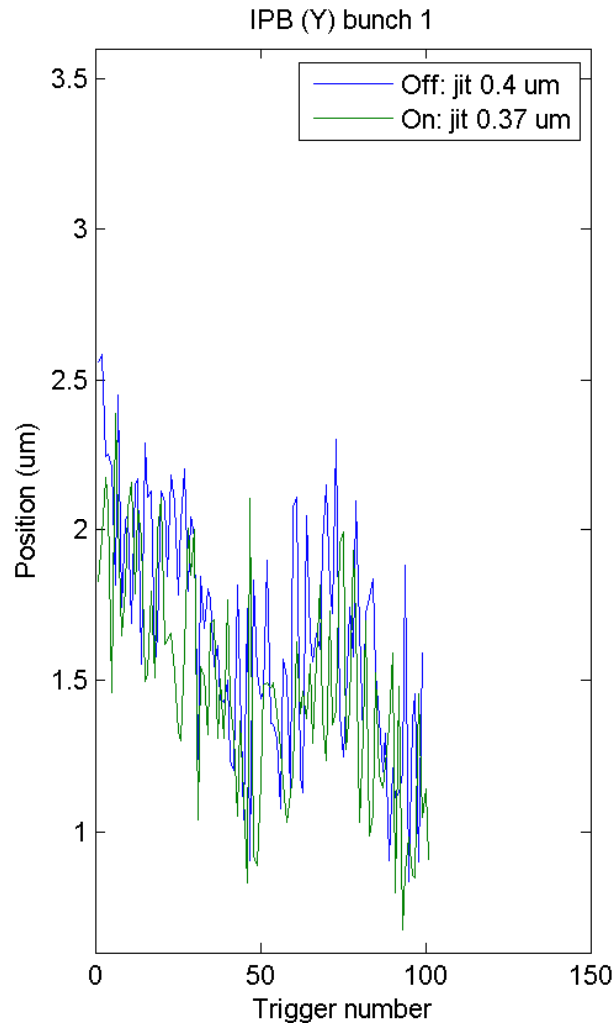
Bunch 2:
corrected,
jitter $\sim 67\text{nm}$



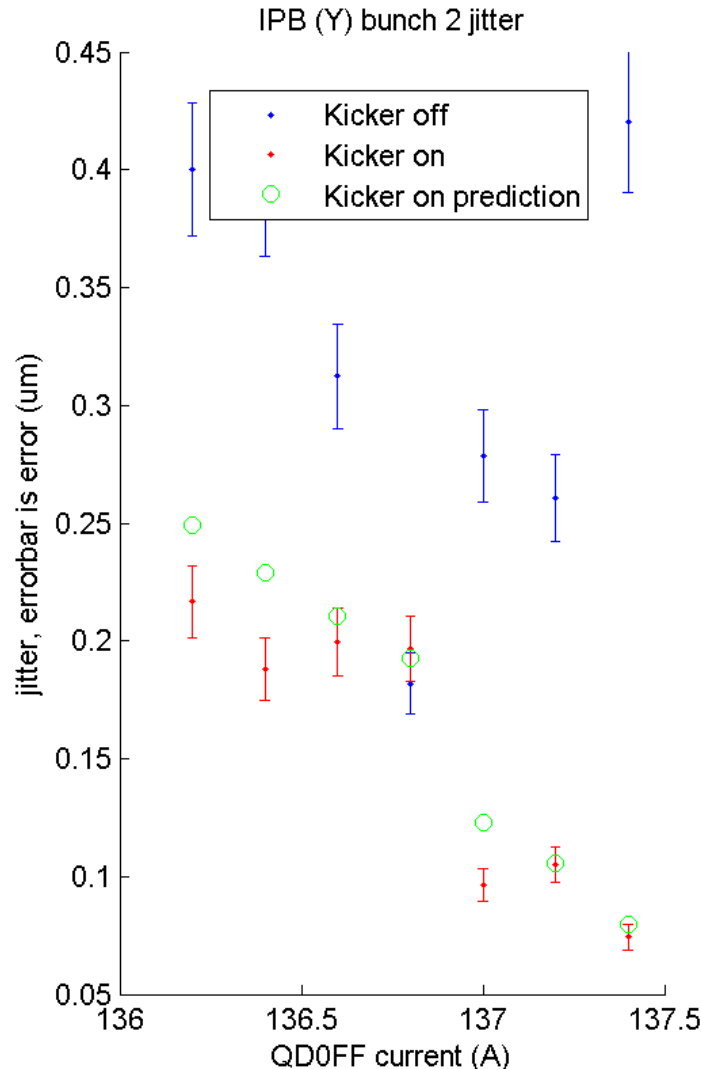
Corrected jitter 67nm

→ resolution 47nm

IPFB results: time sequence



IPFB performance vs. QD0FF setting



Prediction based on incoming jitters of bunches 1 and 2 and measured bunch 1-2 correlation, assuming perfect FB

Summary

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Closed feedback loop

Stabilised beam to 67 nm

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Stabilised beam to 67 nm

Work ongoing to understand/improve cavity BPM resolution

Postscript

In 2008 Honda et al used same electronics on higher-Q BPMs, in single-bunch mode, with 3X bunch charge, and obtained resolution $\sim 9\text{nm}$ (signal integration + 13-parameter fit)

If we use same technique we obtain resolution $\sim 30\text{nm}$

If we scale for bunch charge naively, resolution $\rightarrow 10\text{nm}$

We may actually be close to same performance level, but resolution obtained from a 13-parameter fit does not help with real-time input to a feedback system ...

FONT Group alumni

- **Gavin Nesom:** Riverbed Technology, California
- **Simon Jolly:** UCL faculty
- **Steve Molloy:** ESS staff
- **Christine Clarke:** SLAC staff
- **Christina Swinson:** BNL staff
- **Glenn Christian:** JAI faculty
- **Glen White:** SLAC staff
- **Tony Hartin:** DESY staff
- **Ben Constance:** CERN Fellow → start-up Cambridge
- **Robert Apsimon:** CERN Fellow → Cockcroft
- **Javier Resta Lopez:** Marie Curie Fellow, Cockcroft
- **Alex Gerbershagen:** PSI postdoc
- **Michael Davis:** UBS, London
- **Doug Bett:** CERN Fellow
- **Young-Im Kim:** IBS Daejon