

Use of Automated Commissioning Simulations for Error Tolerance Evaluation for the APS-U



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Workshop on Future Light Source 2023

APS-U – the nearest Future Light Source

- APS is in dark time now – started April 2023
- The first light will be delivered in April 2024
 - Brightness increase factor: up to 500
- Installation progresses on schedule



Quantity	APS Now	APS MBA Timing Mode	APS MBA Brightness Mode	Units
Beam Energy	7	6	6	GeV
Beam Current	100	200	200	mA
Number of Bunches	24	48	324	
Bunch Duration (rms)	34	104	88	ps
Energy Spread (rms)	0.095	0.156	0.135	%
Bunch Spacing	153	76.7	11.4	ns
Emittance Ratio	0.013	1	0.1	
Horizontal Emittance	3100	31.9	41.7	pm-rad
Horizontal Beam Size (rms)	275	12.9	14.7	μm
Horizontal Divergence (rms)	11	2.5	2.8	μrad
Vertical Emittance	40	31.7	4.2	pm-rad
Vertical Beam Size (rms)	10	8.7	3.2	μm
Vertical Divergence (rms)	3.5	3.6	1.3	μrad

General approach when considering tolerances

What we want:

Reasonably fast commissioning

Good injection efficiency and long lifetime

Target emittance

Stable orbit

Target beam current and fill pattern

How we get there:

Alignment

Magnet quality

Mechanical design of magnets and supports

Power supply design

Mechanical design of vacuum chamber

Static errors

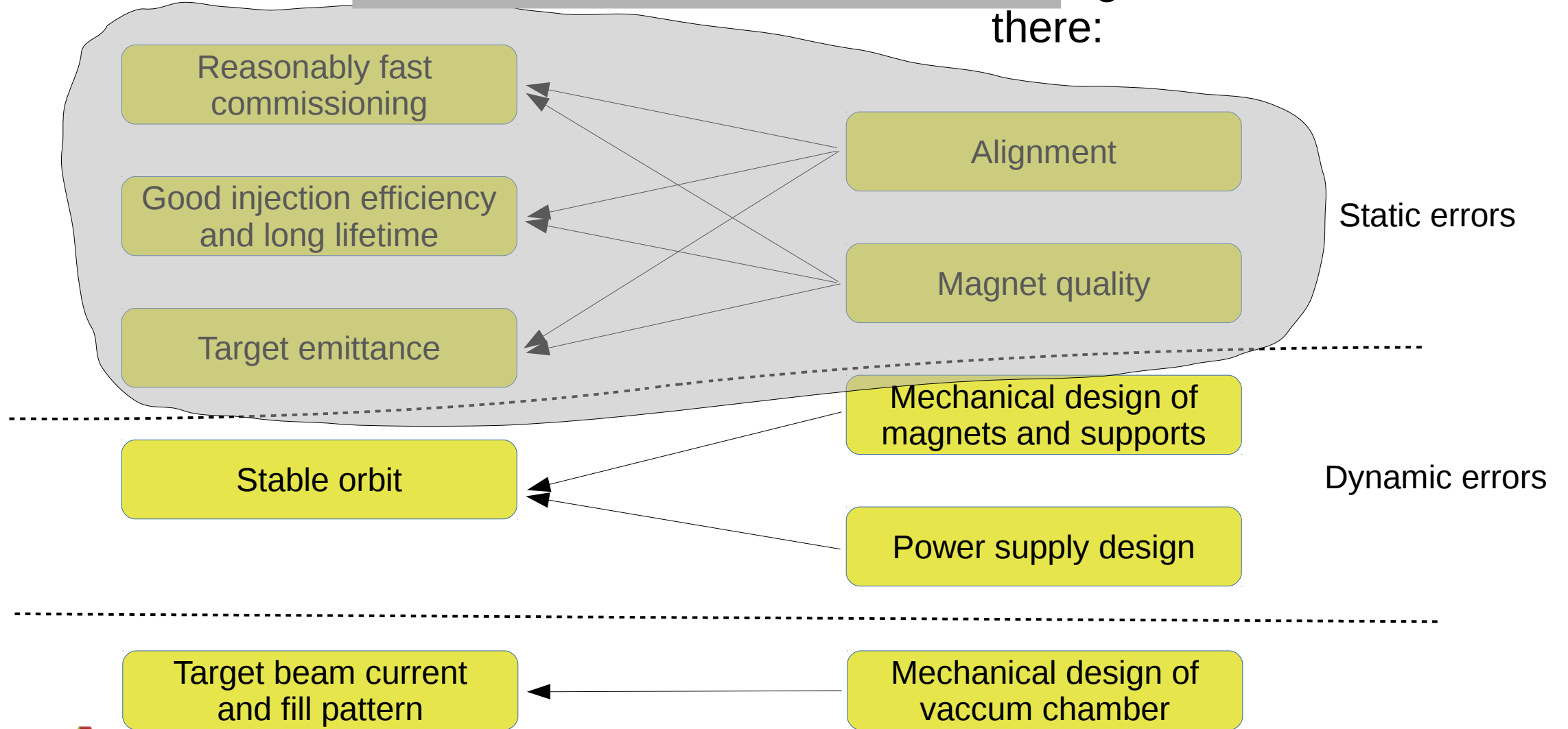
Dynamic errors

General approach when considering tolerances

Commissioning simulations cover static errors

What we

we get there:



Static errors: How it was done for earlier machines

- Assume some distribution and magnitude of errors (alignment and/or manufacturing), calculate resulting machine distortions, limit distortions to reasonable values
 - Orbit and beta functions errors; could be done semi-analytically
- As focusing increased, orbit errors became too big – required including orbit correction in assumptions
 - Included dynamic aperture in considerations, required simulations¹ with orbit correction
 - No lattice correction yet considered
- In early 2000s, lattice correction based on response matrix fit² became widely used but light sources designed at the time still didn't consider lattice correction in tolerance calculations
 - Some designs even included remote girder movers³ to improve girder alignment post-construction to improve accelerator performance
 - Tolerances were likely overspecified

¹E. Crosbie, et. al., 1993 PAC Proc.

²J. Safranek, NIM A 388, 27 (1997)

³S. Zelenika et al., NIM A 467-468, 2001

Typical pre-MBA workflow for error effect evaluation

- Generate error ensembles
- Correct closed orbit
- Correct lattice
- Calculate expected injection efficiency (or DA) and lifetime (or MA)
- Repeat 100s times, calculate statistics
- Limit amplitudes of error distributions to those that provide acceptable performance

- For simplicity, one can isolate a single kind of error and treat its effect separately
- Example of isolated treatment: tolerance on longitudinal quad alignment
 - Use ideal lattice, add longitudinal quad misalignment with Gaussian distribution
 - Calculate resulting beta function errors
 - Limit median rms beta functions errors to 1%, obtain requirement for quad misalignment
 - Resulted in 70 μm rms for APS-U

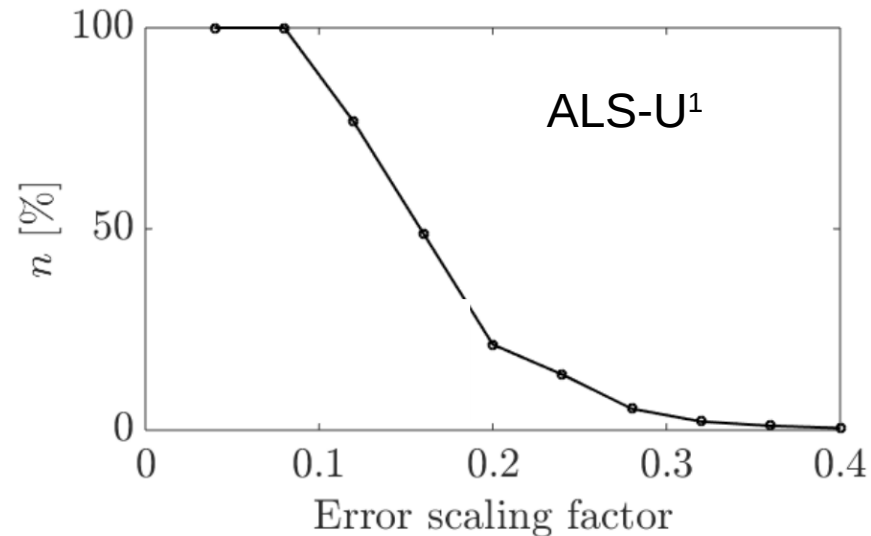
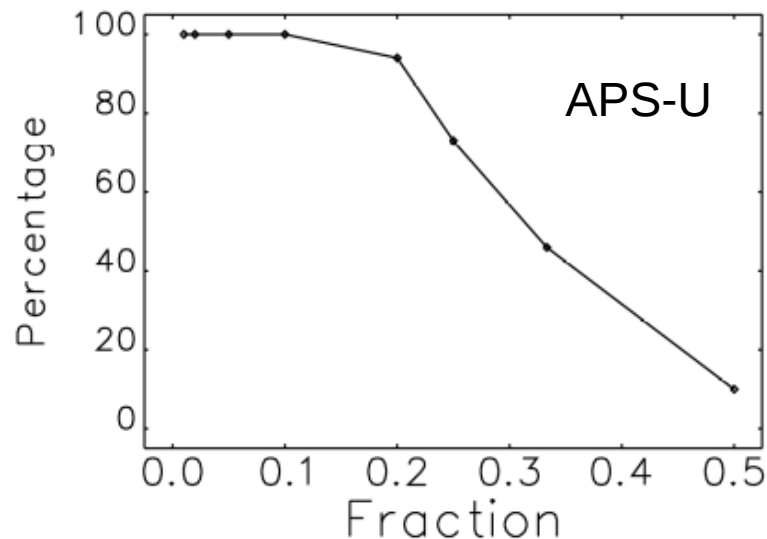
Old approach did not work for new rings

- Evaluated hundreds of APS-U error sets – no closed orbit exists for reasonable error sets in 100% of cases
- Repeated the same study for different fractions of the nominal error set
- To ensure closed orbit existence, one needs to reduce errors by a factor of 5-10 – unrealistic!

APS-U alignment and strength errors (rms, 2σ cutoff)

Girder misalignment X/Y/Z (1σ cutoff)	100 μm
Elements within girder X/Y	30 μm
Elements within girder Z	250 μm
Dipole/Quadrupole/Sextupole/Girder tilt	0.4 mrad
Dipole pitch/yaw	0.1 mrad
Quadrupole/Sextupole pitch/yaw	0.7 mrad
Dipole/Quadrupole fractional strength error	$1 \cdot 10^{-3}$

Percentage of error ensembles with existing closed orbit as a function of a fraction of the nominal error set



Commissioning simulation is the new way to evaluate errors

- Two ways to get around the orbit existence problem
 - Ramping of errors
 - Straightforward ramping while correcting orbit with reasonable ramping steps didn't work
 - Required extra thinking
 - Simulation of “real” machine commissioning
 - Start with trajectory correction and go forward as we would do for real commissioning
 - More complicated than ramping
 - In addition, allows to study actual commissioning strategies

Commissioning simulation is made as realistic as possible^{1,2,3}

- Procedure is based on **multi-particle bunch** tracking and consists of the following steps:
 - Error generation – alignment, strengths, multipoles, **injection**, etc.
 - First-turn correction with zero sextupoles
 - Global trajectory correction
 - **Beam-based alignment**
 - Sextupole ramping while performing correction of pseudo-orbit (multi-turn trajectory averaged on each BPM)
 - Betatron tune and **RF adjustments**
 - Results in beam capture
 - Orbit correction
 - Beta functions and coupling correction **using response matrix fit**
 - Calculate DA/MA or injection efficiency and lifetime
- Single run requires about 2-3 days to complete on a single core
 - Hundreds of runs are essential to generate statistics
- Blue color shows steps not needed if one only wanted to evaluate tolerances – quasi-commissioning

¹V. Sajaev, PRAB 22, 040102 (2019)

²T. Hellert et al., PRAB 22, 100702 (2019)

³T. Hellert et al., PRAB 25, 110701 (2022)

Commissioning simulations allow to evaluate many effects

- Commissioning simulations are complex, but allow for evaluation of many errors:
 - Misalignment, magnet strength errors, and high-order multipoles
 - Injection errors, injected beam parameters
 - BPM offset/noise
 - Realistic aperture
- Due to many dimensions, hard to perform scans

Alignment and strength errors (rms, 2σ cutoff)

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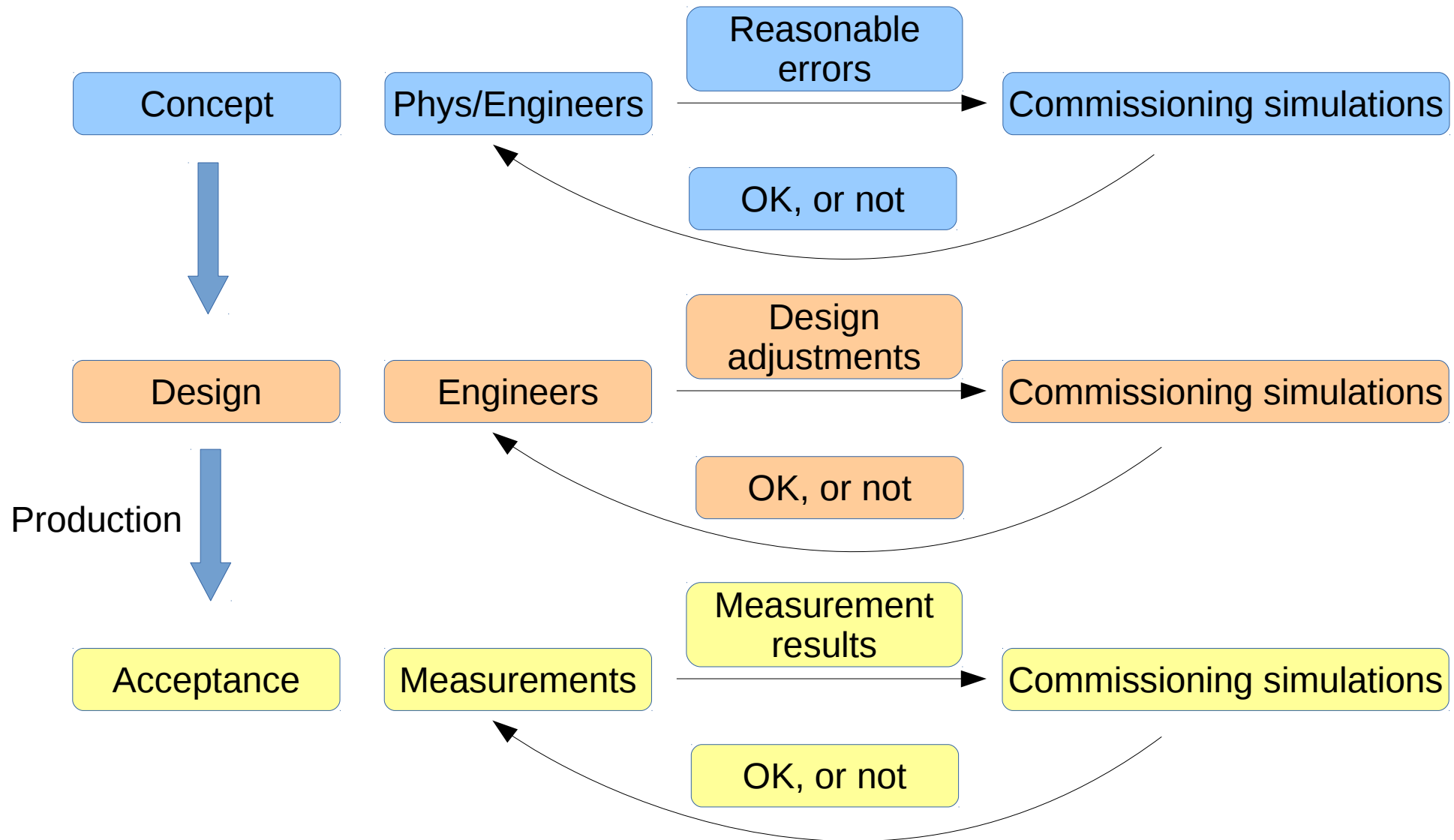
BPM/corrector errors (rms)

Corrector calibration error	5%
Initial BPM offset error	500 μm
BPM calibration error	5%
BPM single-shot measurement noise	30 μm
BPM orbit low-current noise	3 μm
BPM orbit high-current noise	0.1 μm
BPM-to-BPM sum signal variation	10%
BPM and corrector tilts	1 mrad

Injection errors

	Static errors (rms)	Jitter (rms)
Horizontal position	2 mm	100 μm
Horizontal angle	0.5 mrad	10 μrad
Vertical position	0.5 mm	25 μm
Vertical angle	0.3 mrad	15 μrad
Energy	0.5%	10^{-4}

Typical APS-U workflow



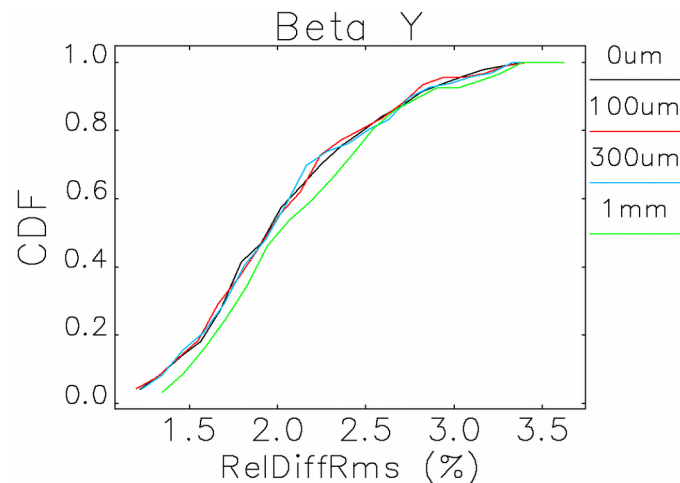
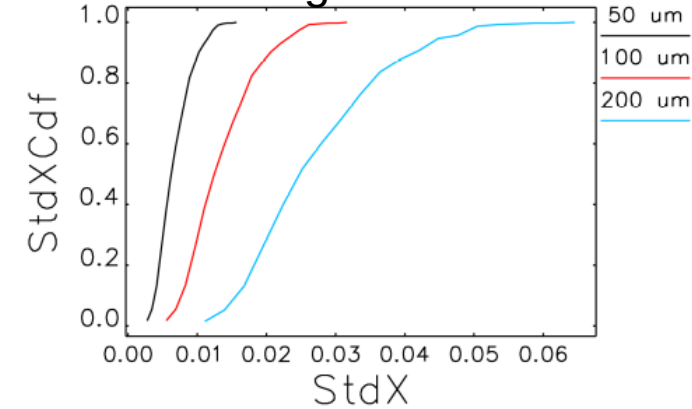
Use examples

- For every request, we re-run commissioning simulations and analyze statistics
- Design step:
 - Switch from support design using 3 large girders to 3 smaller girders + 2 mini-girders – confirmed that performance is comparable
- Acceptance step:
 - 2 quad families and 1 focusing dipole family came with non-zero average tilts and tilt errors exceeding twice the requirements – performance was found to be acceptable
 - 2 sextupoles came with 12 mrad and 4 mrad tilts (requirement is 0.4 mrad) – accepted
 - Longitudinal alignment of one magnet family on girders was exceeding tolerance by a factor of two – relaxed the requirements by a factor of 4

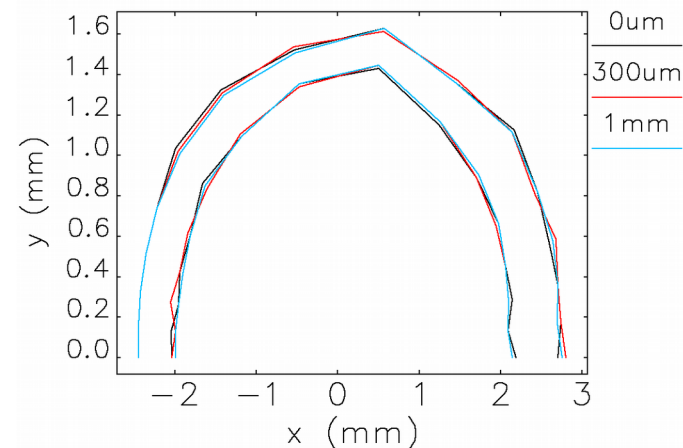
Lattice evaluation could relax requirements a lot

- Longitudinal alignment tolerance: initial simplified tolerance determination
 - Final accuracy of beta function correction after commissioning is 2-3% rms (without longitudinal misalignment)
 - Allow for 1% rms beta function distortion from longitudinal misalignment only
 - Results in 70 μm rms alignment tolerance (on-girder placement)
- To relax, ran commissioning simulations
 - Results showed that even 1 mm rms was acceptable
 - Relaxed requirements to 250 μm rms

Relative β_x error CDF for different longitudinal errors

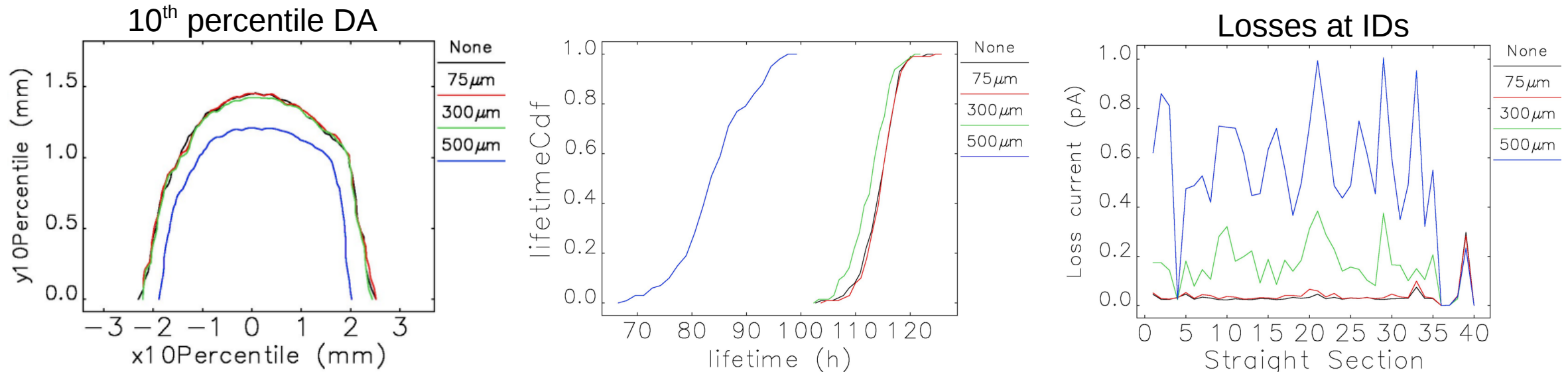


10th and 90th percentile DA



ID vacuum chamber misalignment tolerance¹

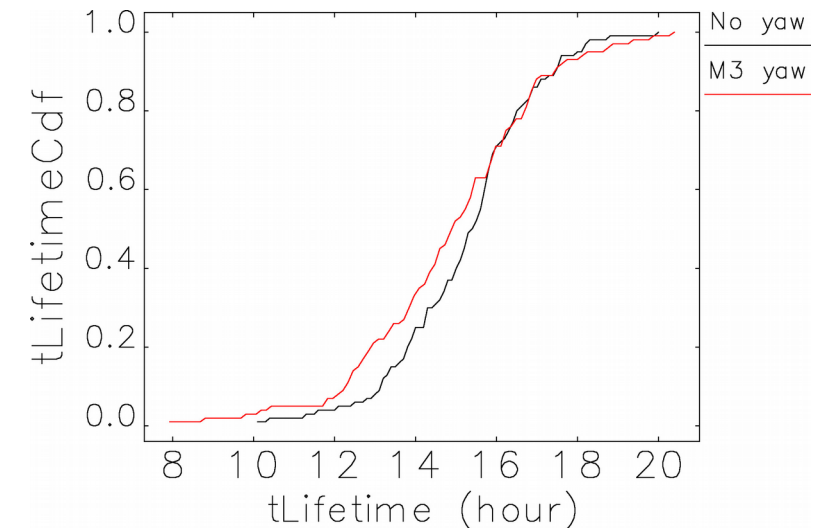
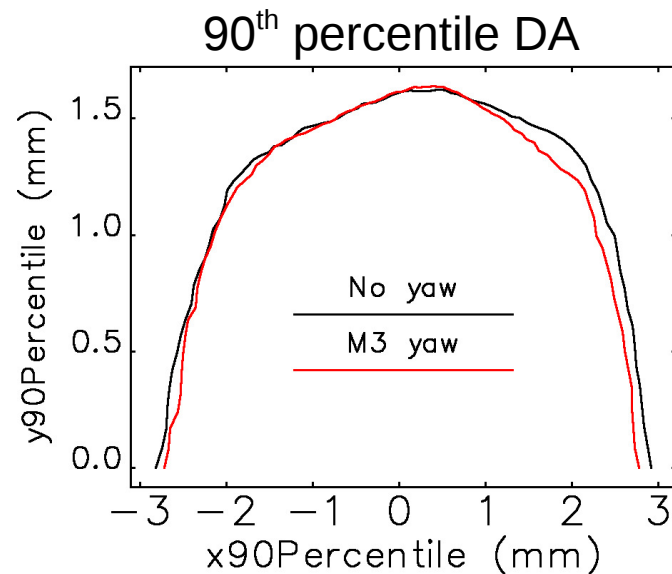
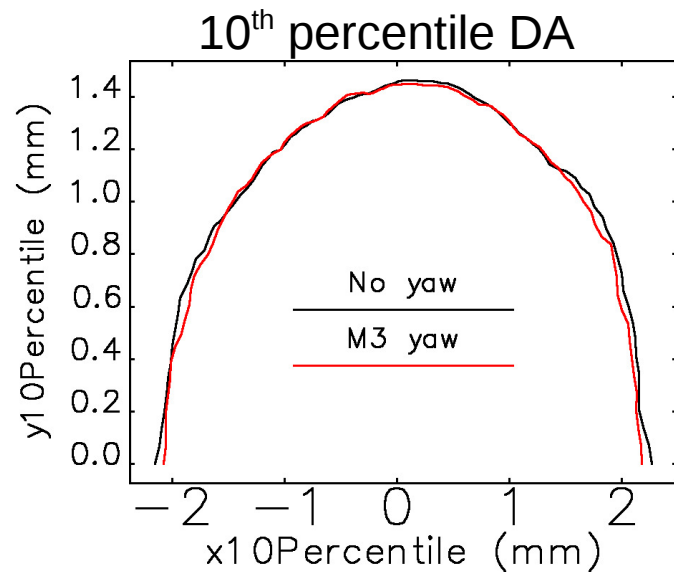
- Concern: lifetime and/or particle loss distribution can change significantly
- Added ID chamber misalignment to commissioned ensembles, evaluated DA, lifetime, and losses
 - Based on DA and lifetime only, 300 μm would be acceptable
 - However, losses at IDs increase significantly above 75 μm



¹Courtesy M. Borland

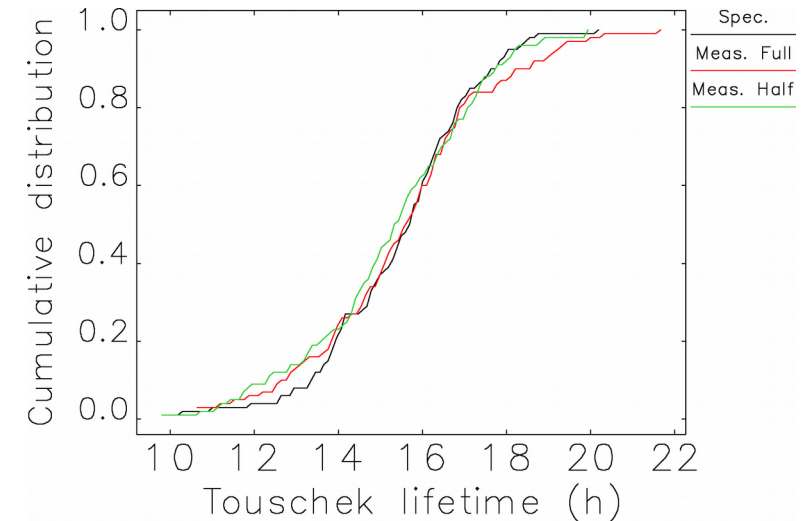
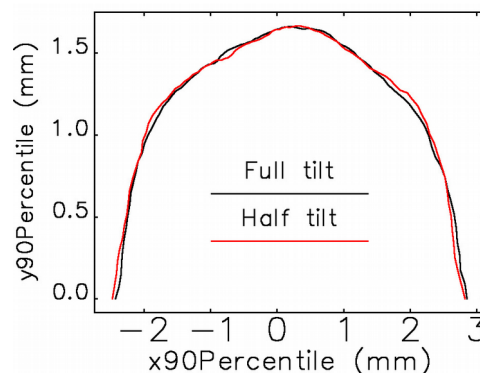
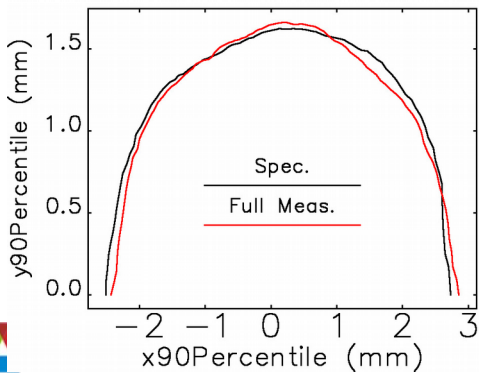
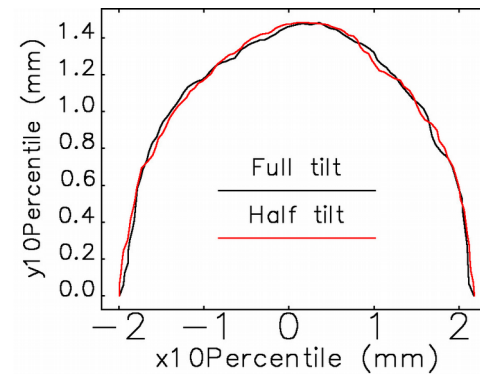
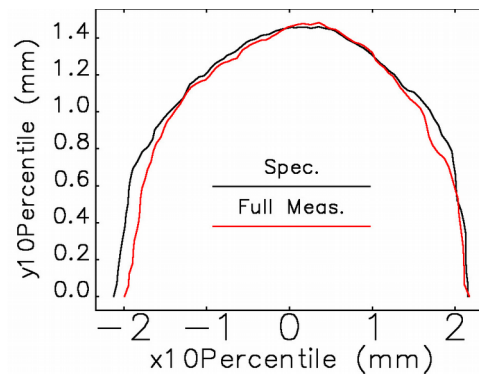
Effect of increased M3 yaw

- Production M3 magnet family was determined to have possible yaw errors of up to 0.5 mrad
- Full commissioning simulation was run with increased M3 yaw errors
- Effect on DA is rather small, but 20% reduction of the minimum lifetime is a concern



Performance with actual measured magnets

- Performance evaluation was performed using magnetic measurements (multipoles and tilts) of 80% of production magnets
- Additionally, M3 family had slightly larger than spec tilts, tested if reduction would be beneficial
- Very small reduction of DA with measured multipoles/tilts, lifetime effect is also very small
- Reduction of M3 tilts does not provide any improvements



Summary

- Various ways exist to calculate effect of errors on the machine performance if one considers error types separately or combines a few types of errors
 - Typically requires careful choice of assumptions or proxies for lifetime/injection
 - Different error types may require different approaches
 - Hard to consider effect on commissioning
- If one wants to consider many errors together – commissioning simulations are the best way
 - Allow to see effect of any type of errors on the accelerator performance
 - Give answer in terms of actual machine performance (injection, lifetime)
 - Do not rely on initial existence of closed orbit
 - Same simulations for all types of errors
 - Too many variables – hard to do error amplitude scans
- Commissioning simulations can be used for acceptance of production items
- Automation of the entire commissioning process is essential

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