





# Recent On-Line Taper Optimization on LCLS

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The work reported here is within my Early Career Research Program goals: to produce high peak power FEL

Approach: Self-seeded Tapered FEL

### **FEL** physics:

➢ High-gain exponential growth region: dispersion relation → growth rate

Low-gain post-saturation tapered region: Hamiltonian dynamics





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Post-saturation coherent emission

Look at the scaling

$$P_{coh} = \frac{Z_0 K^2 [JJ]^2}{8\sqrt{2}4\pi\sigma_x^2 \gamma^2} \left( \int_0^{L_w} I_{pk}(z) b_1(z) dz \right)^2$$

Constant peak current, constant bunching factor:

$$P_{coh}(z) = \frac{Z_0 K^2 [JJ]^2 I_{pk}^2 b_1^2 z^2}{32\sqrt{2}\pi \sigma_x^2 \gamma^2}$$









Energy conservation, electron energy evolution

$$\frac{d\gamma_r}{dz} = -\mathcal{A}\frac{K^2 z}{\gamma_r^2}$$
$$\mathcal{A} = \frac{e[JJ]^2 Z_0 I_{pk} b_1}{2^{11/4} m c^2 \pi w_0 \sigma_x} \sin(\psi_r)$$

where

Resonant condition gives the taper profile

$$K(z) \approx K_0 \left( 1 - \frac{\mathcal{AB}^2 \gamma_{r0}}{2K_0^2} z^2 \right)$$

where

 $\mathcal{B} = (4\lambda_r)/\lambda_w$ 







THE PHASE SPACE—LCLS-II TYPE SYSTEM Early Career Research Program

### • At locations: 30, 60, 80, 100, 110, and 120 m

2017





- Taper profile
  - Continuous function
    - Add high order terms

$$K(z) = K_0 [1 - b_2 (z - z_0)^2 / L_w^2 - b_4 (z - z_0)^4 / L_w^4]$$

- Discretized
  - Piecewise for 17<sup>th</sup> 32<sup>nd</sup> undulator
- Optimizer
  - Robust Conjugate Direction Search (RCDS);
  - Multi-Object Generic Algorithm (MOGA);
  - Particle Swarm Optimization (PSO);
  - Extreme Seeking (ES);
  - Simulated Annealing (SA);
  - Reinforcement Learning (RL);
  - Markov Chain Monte Carlo (MCMC).







Huang, Corbett, Safranek, Wu, NIMA, 2013 Wu et al., NIMA, 2017 Fang, Wu, et al., FEL Proc., 2015 Scheinker, Huang, Wu, IEEE, 2017 Gupta, Fang, Wu, et al., IPAC Proc., 2015 Wu, Hu, Fang, et al., 2017 Wu, Setiawan, et al., 2017



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#### Three Sections

1 (,4) - 8:  $K_j = K_{1(,4)}[1 - b_1(j - 1(,4))]$  for  $j \in [1(,4) 8]$ : SASE

from 1<sup>st</sup> undulator, and seeding from 4<sup>th</sup> undulator

■ 10 - 15:  $K_i = (K_8 + \Delta K_{10})[1 - b_1(j - 10)]$  for  $j \in [10 \ 15]$ 

■ 17 - 32: 
$$K_j = (K_{15} + \Delta K_{17})[1 - b_1(j - 17) - b_2(j - j_2)^2 - b_4(j - j_4)^4]$$
 for  $j \in [17 32]$ 

**Parameters** 

 $b_1$ : linear taper for Spontaneous Emission & Wakefield;  $\Delta K_{10}$  and  $\Delta K_{17}$ : detuning, phase matching;  $j_2$  and  $j_4$ : starting point for quadratic and quartic taper





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- Seeding phase matching
- Orbit
- Overall residual chirp (XTCAV)
- Seeding
  - Use line with wider bandwidth to find the signal, and then switch to line with narrower bandwidth
  - Yaw, pitch

Correlation Plot 05-Jul-2016 23:11:13



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## Over 100 GW SS @ 4.5 keV

#### Motivation:

✤ To demonstrate high-power feasibility at LCLS and LCLS-II.

### Method:

- ✤ 4.5 keV Hard X-ray Self-seeding (HXRSS).
- ✤ Maximizing LCLS taper of 0.8 %.







(52 m)

(16 m)

(3.2 m)

(60 m)

























## First demonstration of taper optimal phase

#### Motivation:

- \* To demonstrate experimentally the optimum phase for tapering.
- Important to have a dedicated phase shifter around exponential saturation point for future FELs.

### Method:

- ♦ Use Soft X-ray Self-seeding (SXRSS) for ~700 eV.
- ✤ Use HXRSS chicane to vary phase shift versus gain.







In transition region between linear regime and post saturation

regime, bunching factor oscillates, and FEL power increases slowly.

Bunching drops from 0.6 to 0.5  $\rightarrow$  power (0.6)<sup>2</sup> to (0.5)<sup>2</sup> **Deviate** from 0











## Machine learning taper optimization

### Motivation:

- Develop on-line optimization package for taper optimization.
- Make full use of the development in computer science: machine learning and artificial neural network.

### Method:

- Use Machine Learning in LCLS to optimize taper during operation.
- ✤ 5.5 keV HXRSS.









### Discretized

- Piecewise
- Reinforcement learning
  - A set of environment states S;
  - A set of actions: A;
  - Rules of transitioning between states;
  - Rules that determine the scalar immediate reward of a transition; and
  - Rules that describe what the agent observes.
  - Rules are often stochastic.









- Machine Learning (Reinforcement Learning) is adopted for LCLS tapered FEL optimization
  - > A discretized taper solution: due to electron's nonlinear dynamics in the FEL bucket.
- On-line optimization: XTCAV image: Clustering  $\rightarrow$  characterize state information
- Benefited from collaboration with CS@Stanford: Clustering and Reinforcement Learning



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- Learned from Start-to-end simulation data: Zig zag > 50% increase over continuous profile
- Taper optimizer:













- Extensive theoretical and numerical studies:
  - Taper model; transverse focusing
  - Transverse distribution; sideband instability
  - Coherence; mode decomposition
- Simulation optimization:
  - Physics-oriented scan-type optimization
  - Multi-Objective Genetic Algorithm (MOGA)
- On-line optimization
  - Local optimizer and global optimizer
  - Machine learning









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