

Evaluation of PLC-Based EtherNet/IP Communication for Upgrade of Electromagnet Power Supply Control at RIBF

RIKEN Nishina Center
Beam Dynamics & Diagnostics Team

<u>Akito UCHIYAMA</u>, Keiko Kumagai, Misaki Komiyama, Nobuhisa Fukunishi

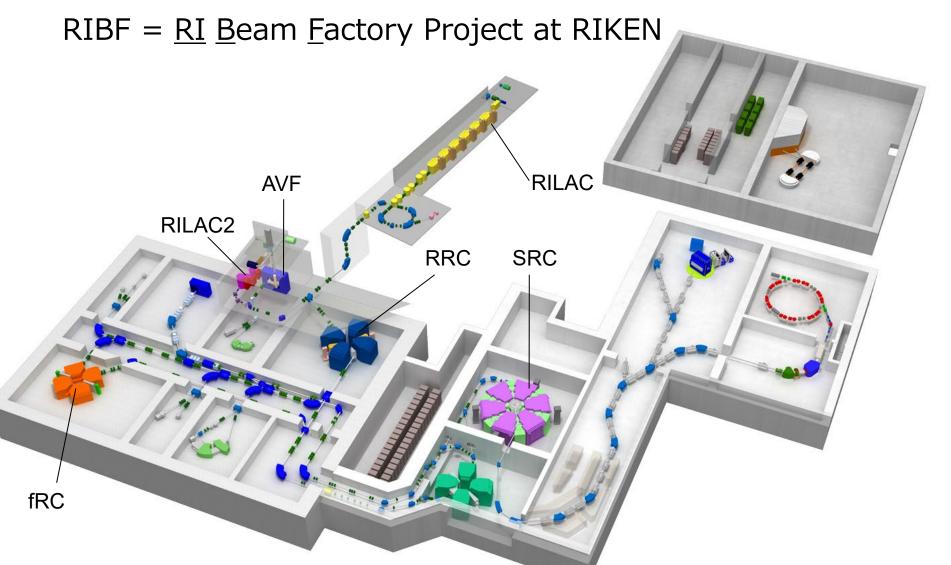


### Outline

- Overview of RIBF
- Control system for RIBF
- Electromagnet power supply control
- Field network as the device interface layer
- Evaluation of PLC-based EtherNet/IP
- Conclusion

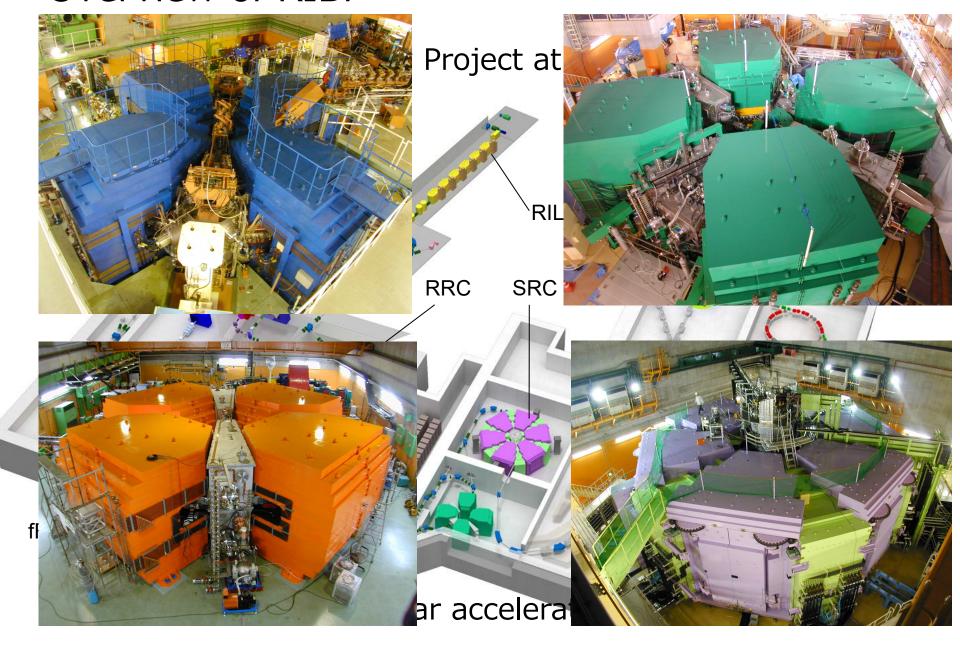


### Overview of RIBF



4 Ring Cyclotrons, 2 linear accelerators and AVF cyclotron.

# Overview of RIBF



## Control System for RIBF

### RIBF control system is based on EPICS.

#### **EPICS** covers

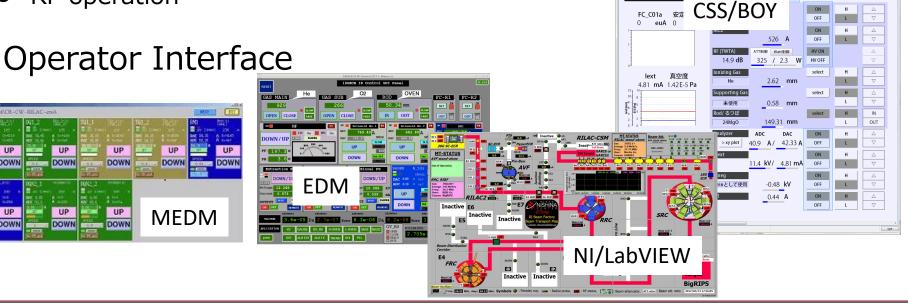
- Magnet Control
- Beam Diagnostics
- **ECR Ion Source Control**
- Vacuum Control
- Machine protection system

RF operation

### Other EPICS services

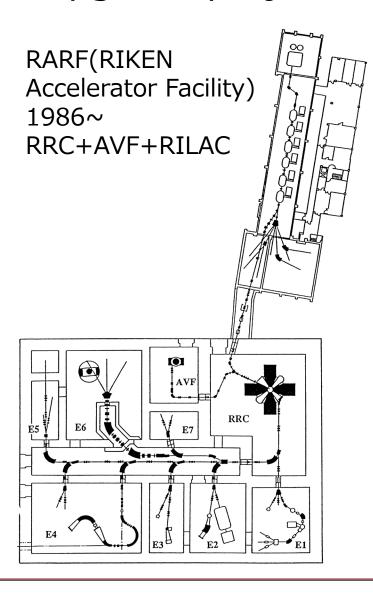
- Operational Log system
- Data Archive system (Archiver Appliance)
- EPICS Management system (like IRMIS)
- Alarm system





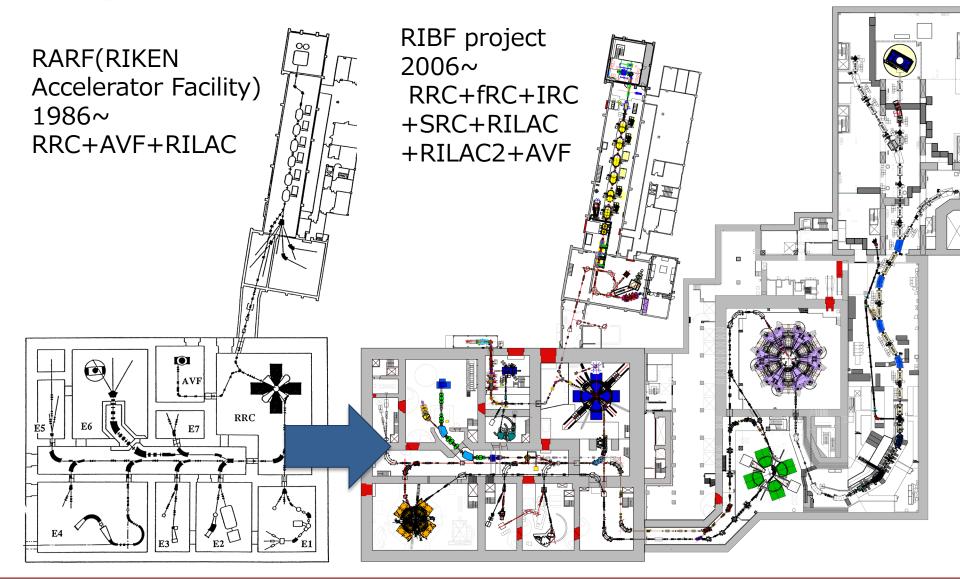


# Upgrade project





# Upgrade project





## Upgrade project

RIBF project 2006~ RRC+fRC+IRC +SRC+RILAC +RILAC2+AVF The electromagnets of RARF are still in use. The old electromagnet power supplies  $(\sim 300)$  are also in operation. The controller of electromagnet power

Beamline locations, which continue to be used since the RARF.

supply is aging.



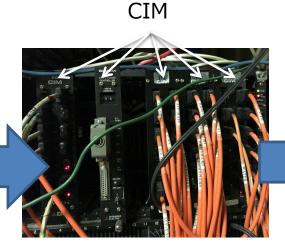
### 1986~

- The CIM installed in the CAMAC crate was connected to the DIM.
- DIM was installed into the power supply.
- The connection was through optical fiber.

Device Interface Module(DIM)



Minicomputer as controller



CAMAC crate with Communication Interface Module (CIM).



Magnet power supply

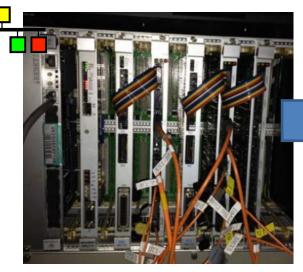


2001~

- The VME CPU board was adopted to support EPICS.
- But the CIM and DIM were still used.

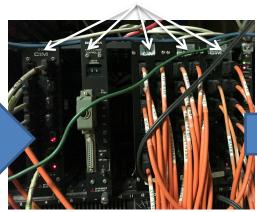
Device Interface Module(DIM)

**EPICS** 



VME CPU board with EPICS

CIM



CAMAC crate with Communication Interface Module (CIM).



Magnet power supply

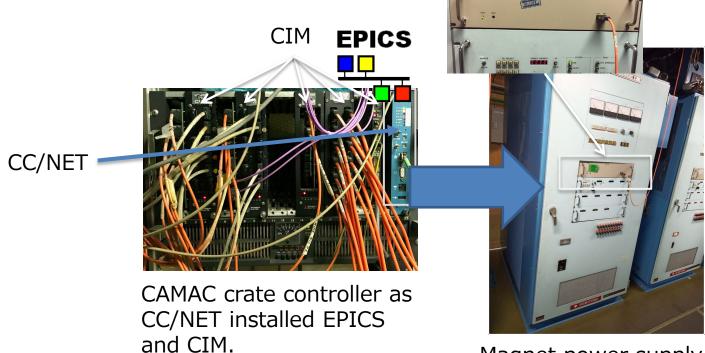


2004~

The VME CPU board was replaced by CC/NET.

CC/NET is a CAMAC crate controller running EPICS. Device Interface Module(DIM)

But the CIM and DIM were still used.



Magnet power supply



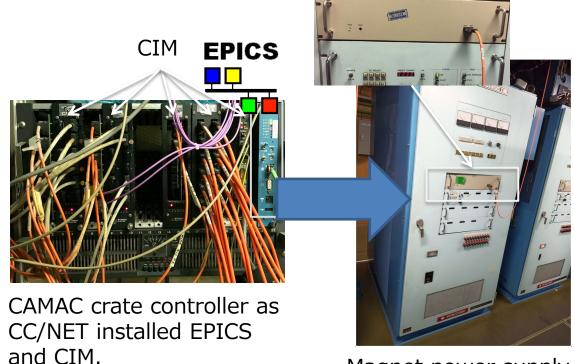
2004~

The VME CPU board was replaced by CC/NET.

CC/NET is a CAMAC crate controller running EPICS. Device Interface Module(DIM)

But the CIM and DIM were still used.

The CIM/DIM has already been in use for 35 years!!



Magnet power supply





Device Interface Module(DIM)

The DIM functional part currently under development. Yokogawa FA-M3 PLC is a candidate to update the DIM.



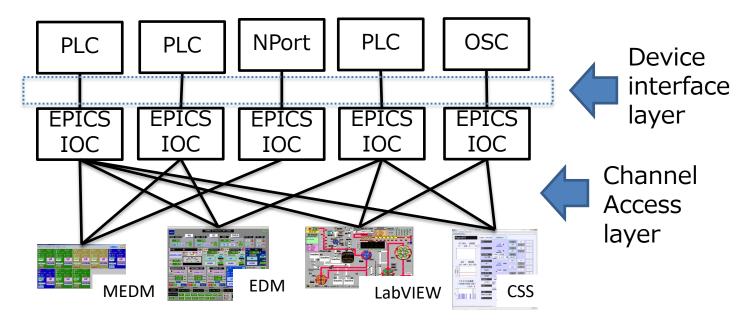
The communication between the controllers, and the EPICS implementation method are studied.



Magnet power supply



- FA-M3 CPU module is equipped with standard Ethernet.
- EPICS device support software is ready.(NetDev, AsynDriver, StreamDevice)
- TCP/IP is very useful and used for general purpose!!
- The system development is low cost in case of TCP/IP as the device interface layer.







In-house network device



Mitsubishi PLC (MLSEC-Q, MELSEC iQ-R)



Yokogawa PLC (FA-M3)



Ondotori

We are using about 600 TCP/IP-based device for RIBF control system.



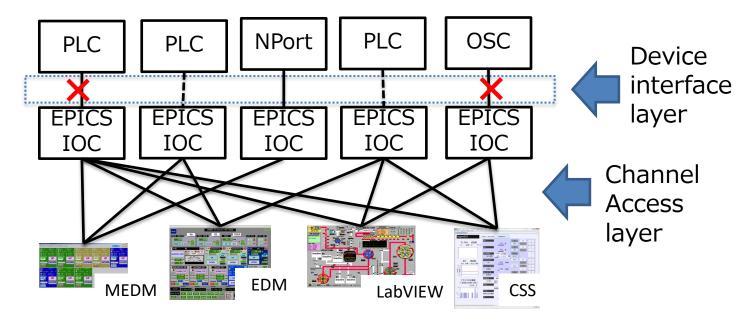
Omron PLC



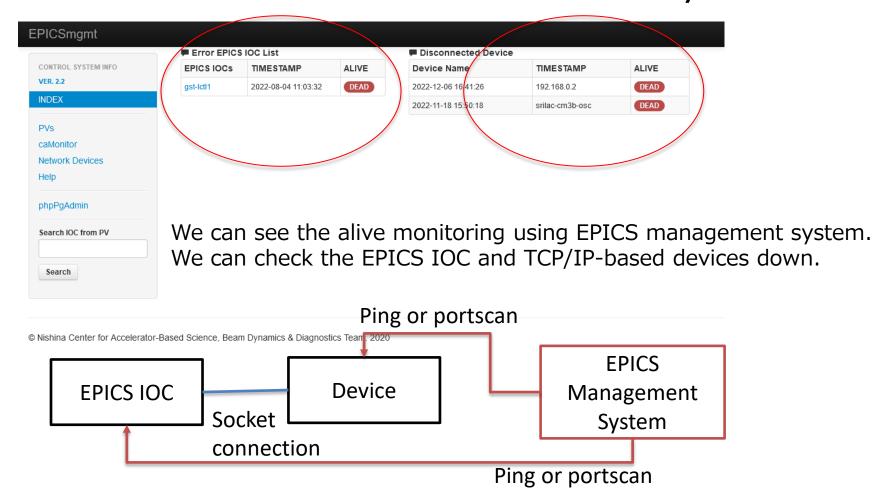
Keysight



- In some case, the reconnection is failed after TCP/IP is disconnected by trouble (need to restart EPICS IOC).
  - When the socket is closed properly, the reconnection is usually succeeded.
- TCP/IP is low real-time performance (low reliability).
- Slow I/O communication (not suitable for interlock).







However, the EPICS management system checks the status using ping and portscan by an external program, so it does not check the socket status between EPICS IOC and the devices.



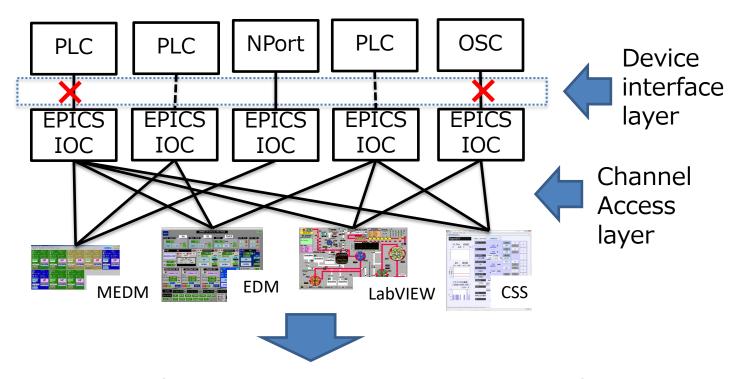
```
EPICS SNC:ndim scan restart comp.
drvNetMpf: sanity check OK (22144 times)
cancel: 8 times
receive: 1099887 times
timeout: 105 times
send : 1100000 times
delta : 0 times
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.179"...
drvNetMpf: connected to "172.23.2.179"
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.178"...
drvNetMpf: connected to "172.23.2.178"
EPICS SNC:ndim_scan_restart ndim_reset.
PV: ndim vac:vac B12:vac Pa dbGetLinkValue
PV: ndim vac:vac B12:vac Pa dbGetLinkValue
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.45"...
drvNetMpf: connected to "172.23.2.45"
EPICS SNC:ndim_scan_restart start.
EPICS SNC:ndim scan restart comp.
EPICS SNC:ndim_scan_restart ndim_reset.
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.177"...
drvNetMpf: connected to "172.23.2.177"
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.176"...
drvNetMpf: connected to "172.23.2.176"
EPICS SNC:ndim_scan_restart start.
EPICS SNC:ndim scan restart comp.
drvNetMpf: EOF found while receiving
drvNetMpf: tcp client trying to connect to "172.23.2.180"...
drvNetMpf: connected to "172.23.2.180"
```

PV: ndim vac:vac B12:vac Pa dbGetLinkValue

- We can check the status of the TCP/IP connection on the EPICS startup screen.
- It is very easy to implement this function.
- But this is for developer, not for operators.



- In some case, the reconnection is failed after TCP/IP is disconnected by trouble (need to restart EPICS IOC).
  - When the socket is closed properly, the reconnection is usually succeeded.
- TCP/IP is low real-time performance (low reliability).
- Slow I/O communication (not suitable for interlock).



Ethernet-based field network as the device interface layer



Development of dedicated protocol is usually high cost.



Ethernet-based standard protocol. General technology to reduce the cost of debugging.

EtherCAT
 Hard realtime, fast response, but require dedicated network.

FL-net
 Realtime, middle response, but require dedicated network.

EtherNet/IP
 Realtime, middle response, allowing
 general-purpose network switches with
 other TCP/IP protocols, low-cost wiring
 work.



Development of dedicated protocol is usually high cost.



Ethernet-based standard protocol.

General technology to reduce the cost of debugging.

EtherCAT
 Hard realtime, fast response, but require dedicated network.

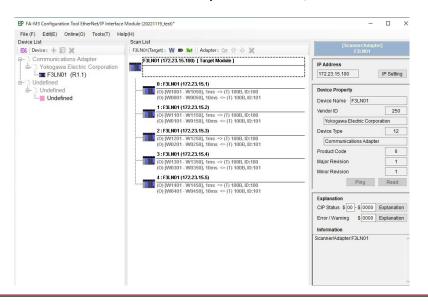
FL-net
 Realtime, middle response, but require dedicated network.

EtherNet/IP
 Realtime, middle response, allowing
 general-purpose network switches with
 other TCP/IP protocols, low-cost wiring
 work.



### EtherNet/IP

- EtherNet/IP is one of the field networks widely used in the industrial field using Ethernet.
- EtherNet/IP is compatible with conventional Ethernet, sharing the same physical layer such as frame structure, connectors, and cables.
- EtherNet/IP is also compatible with TCP/IP. EtherNet/IP utilizes the Common Industrial Protocol (CIP) control communication protocol in the application layer.
- The main features of EtherNet/IP are allowing general-purpose network switches with other TCP/IP protocols, low-cost wiring work, soft real-time performance.



We utilize Yokogawa FA-M3 PLC to implement the EtherNet/IP function.

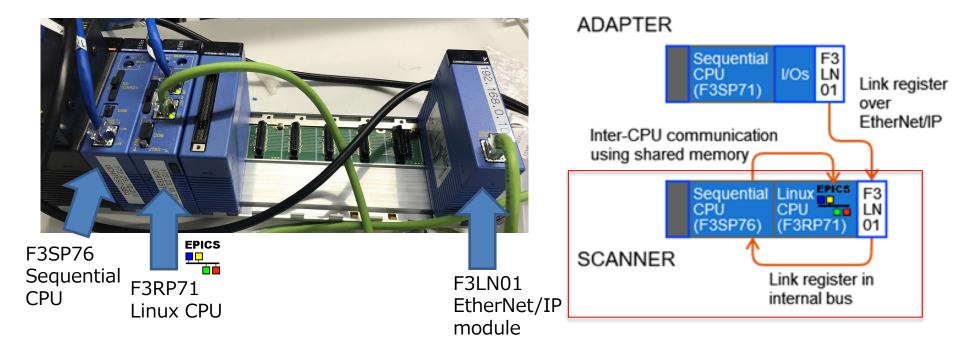
This figure shows about the screenshot to set up for configuration of EtherNet/IP.



#### **EPICS Interface**

- EtherNet/IP-based system consists of a scanner and adapters.
- Scanner has the EPICS IOC, F3RP71 is installed as Linux CPU in second slot.
- The scanner and adapters exchange the data via the link register. (Low development cost)

### **SCANNER**

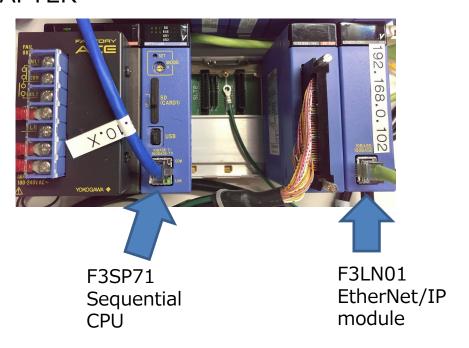


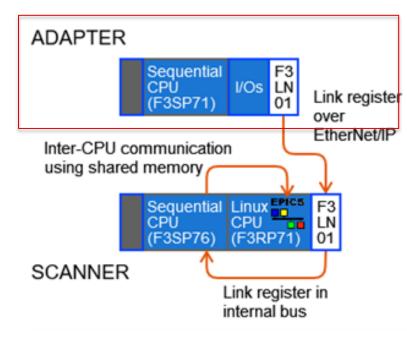


#### **EPICS** Interface

- EtherNet/IP-based system consists of a scanner and adapters.
- Scanner has the EPICS IOC, F3RP71 is installed as Linux CPU in second slot.
- The scanner and adapters exchange data using the link register. (Low development cost)

#### **ADAPTER**



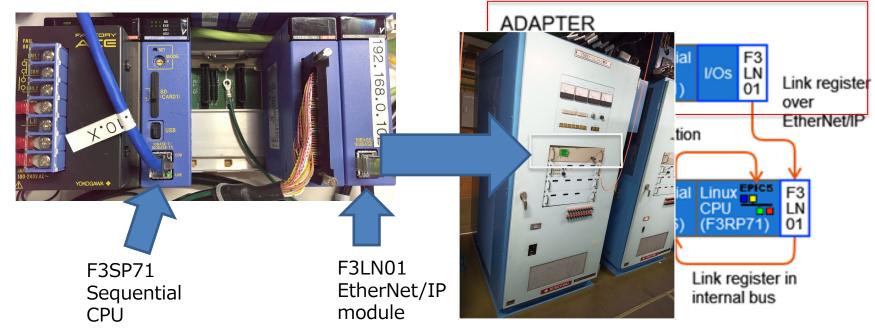




#### **EPICS Interface**

- EtherNet/IP-based system consists of a scanner and adapters.
- Scanner has the EPICS IOC, F3RP71 is installed as Linux CPU in second slot.
- The scanner and adapters exchange data using the link register. (Low development cost)

#### **ADAPTER**



Adapters will become DIM and built inside the power supply chassis.



### Response of EtherNet/IP

- Create a 10 Hz signal in the scanner's sequence CPU, trigger it to output to the scanner and adapter simultaneously.
- Measure the time difference depending on EtherNet/IP communication.
- One Ethernet/IP scanner and one adapter connected in one 1Gbps switching hub.
- Note, the connection with requested packet interval 1 msec.

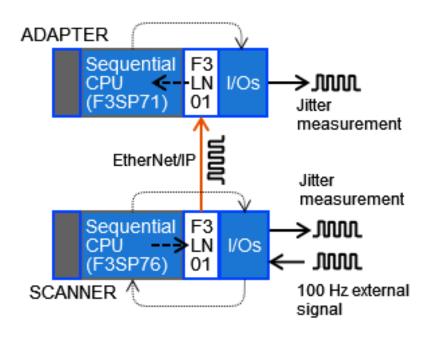


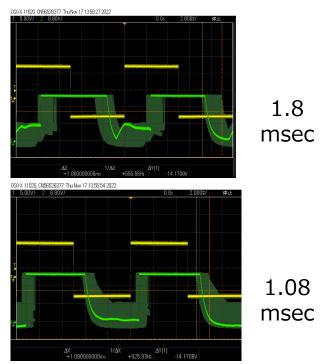
The difference in average response time is about 2.3 msec



### Jitter of EtherNet/IP

- Create a 100 Hz external signal and input to the scanner.
- The scanner triggered the input signal and output to both the scanner and adapter.
- One Ethernet/IP scanner and one adapter connected in one 1Gbps switching hub.
- Note, the connection with requested packet interval 1 msec.



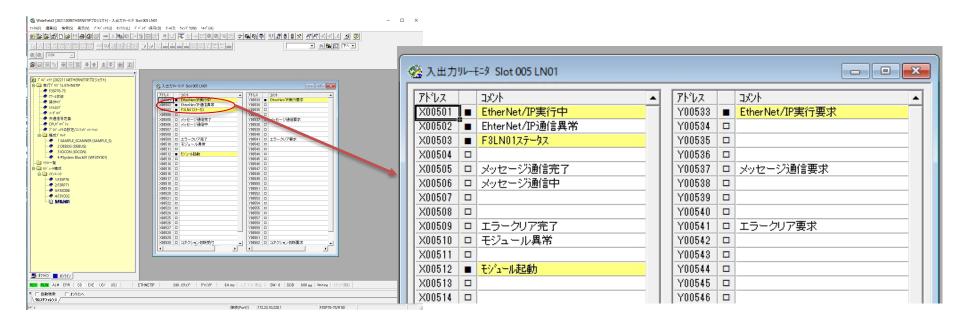


The jitter is about 0.7 ms larger via EtherNet/IP.



### Failure tests of EtherNet/IP

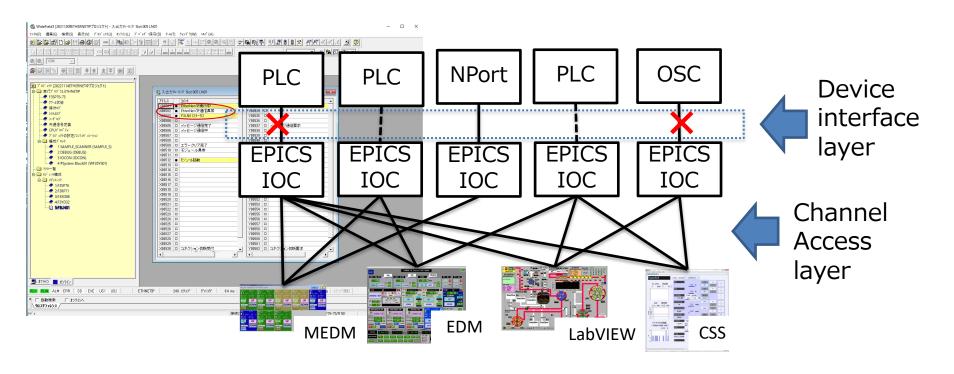
- Disconnect and check the status.
- The PLC CPU is fully capable of detecting failures in the device interface layer.
- The error status by standard registers so that the operator can be informed via EPICS.





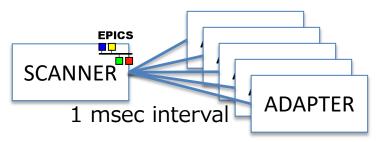
### Failure tests of EtherNet/IP

- Disconnect and check the status.
- The PLC CPU is fully capable of detecting failures in the device interface layer.
- The error status by standard registers so that the operator can be informed via EPICS.

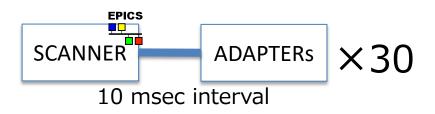




- In requested packet interval is 1 msec, EtherNet/IP connection takes 2.3 msec to deliver the signal.
- We had an FL-net-based application with the minimum number of nodes before.
- About response time of EtherNet/IP, the performance was comparable to FL-net.
- While the transmission time of FL-net becomes proportionally slower as the number of connected nodes increases.
- The jitter is only about 0.7 ms larger via EtherNet/IP, though soft realtime system.
- Sufficient performance as an interlock signal to be output when stopping the beam due to power supply problems.
- It is possible to transmit interlock signals to distant locations via a general-purpose network switches.



In requested packet interval is <u>1 msec</u>, SCANNER handles <u>5 ADAPTERs</u>.



In requested packet interval is <u>10 msec</u>, SCANNER handles <u>30 ADAPTERs</u> without interlock signal.



### Conclusion

- To upgrade the old electromagnet power supply control, we studied the EPICS IOC and the device interface layer.
- General TCP/IP-based device is very useful but there are some concerns for electromagnet power supply operation.
- EtherNet/IP does not require the dedicated network and it can be mixed with the other protocols, so low-cost wiring work.
- As a result of evaluation EtherNet/IP communication, the performance is sufficient.
- When updating 50 old DIMs for RIBF, this method will be the first choice.

## Thank you

