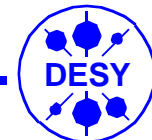
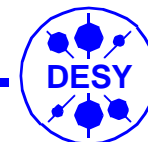

Control of Microphonics and Lorentz Force Detuning with a Fast Mechanical Tuner

S. Simrock, DESY
for the TESLA collaboration



Outline

- Motivation for Detuning Control
- Lorentz Force and Microphonics
- Actuators and Sensors for Detuning Control
- Feedforward vs Feedback
- Performance of Resonance Control
- Conclusion



Motivation for Detuning Control

- Microphonics (vibrations) modulate the cavity resonance frequency \Rightarrow Amplitude and phase error of accelerating field
- Regulation of the accelerating field requires **additional rf power** due to the time varying cavity de-tuning $\Delta f(t)$

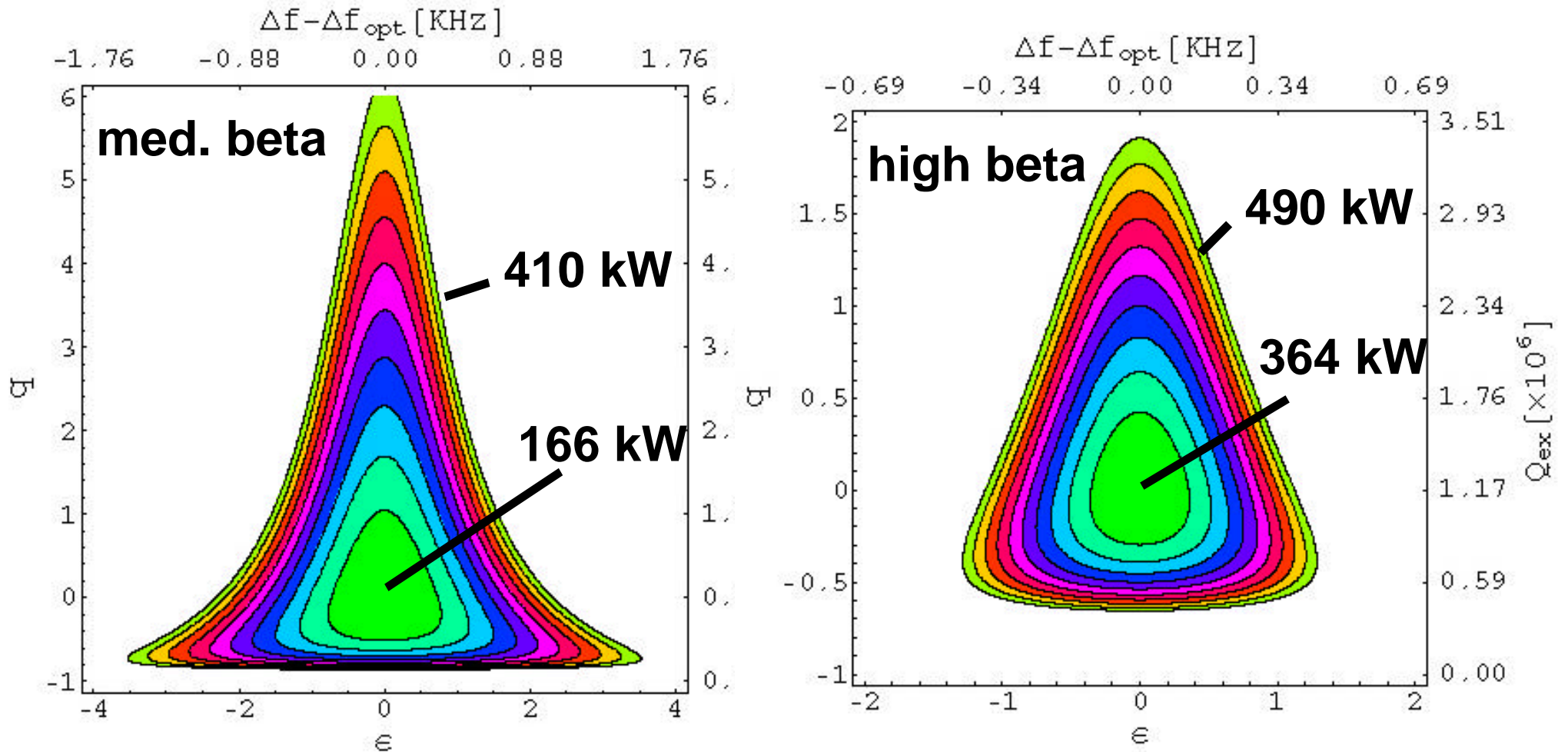
- $\frac{P}{P_0} = 1 + 0.25 \cdot \left(\frac{\Delta f(t)}{f_{12}}\right)^2$ with beam (matched conditions)

$$\frac{P}{P_0} = 1 + 1 \cdot \left(\frac{\Delta f(t)}{f_{12}}\right)^2 \quad \text{without beam}$$

where Δf : cavity detuning, f_{12} : cavity bandwidth (HWHM)

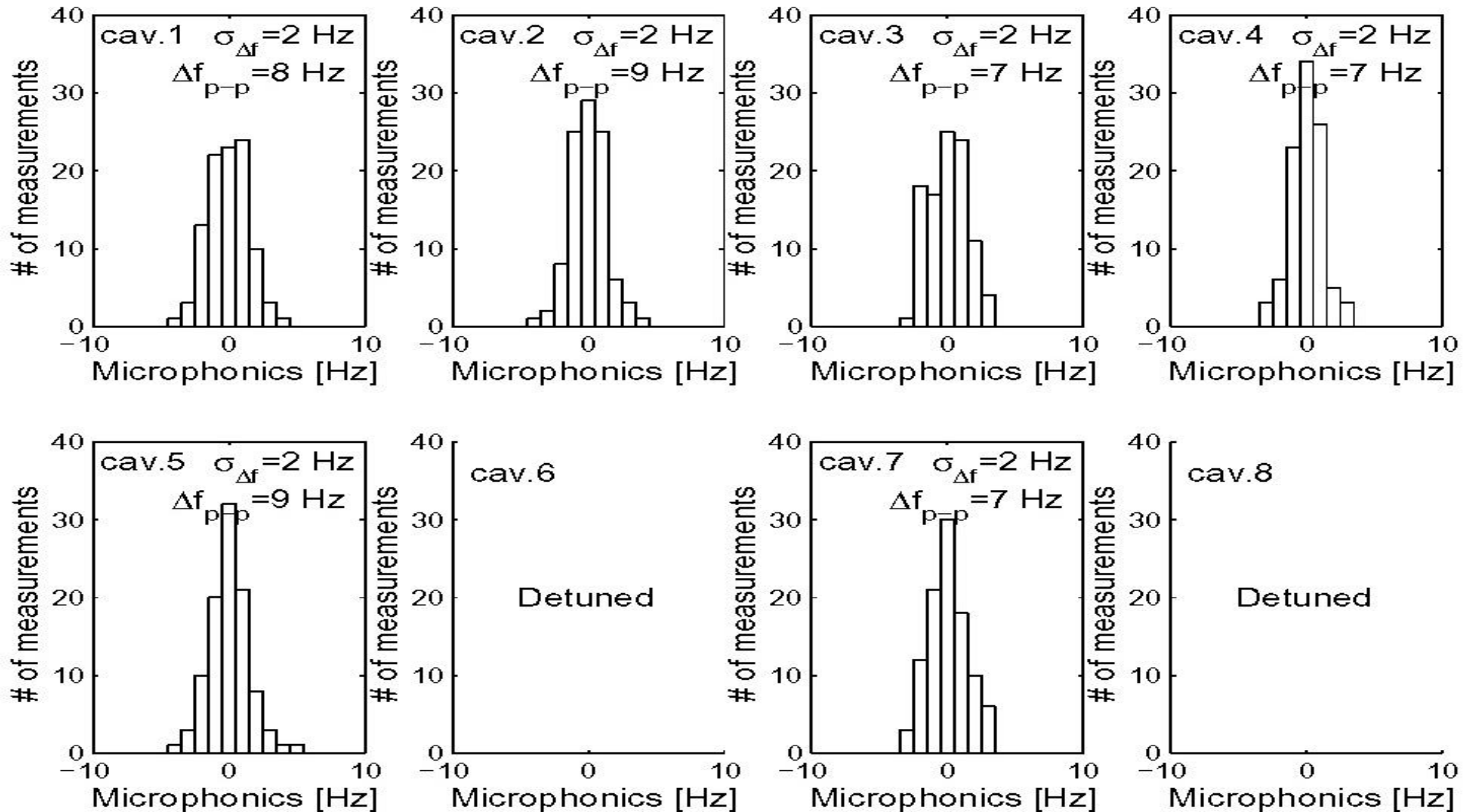
- Potential Solution: Fast piezo tuner in feedback loop

Detuning Limit for SNS Cavities

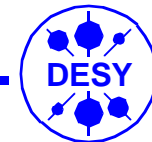


courtesy: M. Doleans, ORNL

Microphonics at TTF (ACC 5)

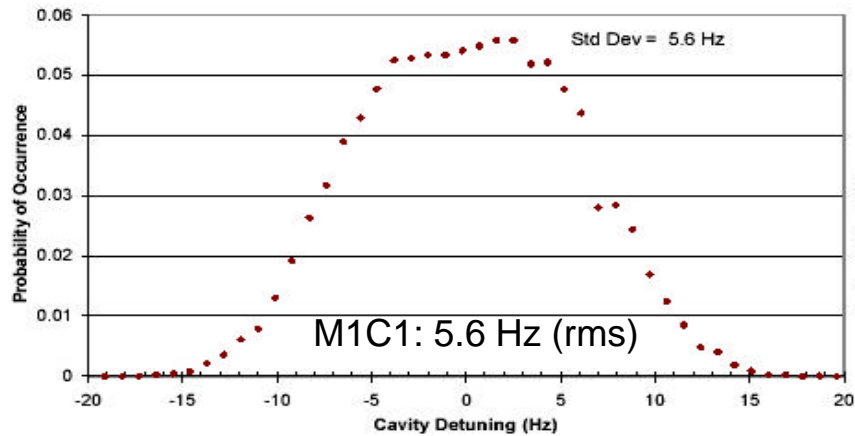


courtesy: V. Ayvazyan, DESY

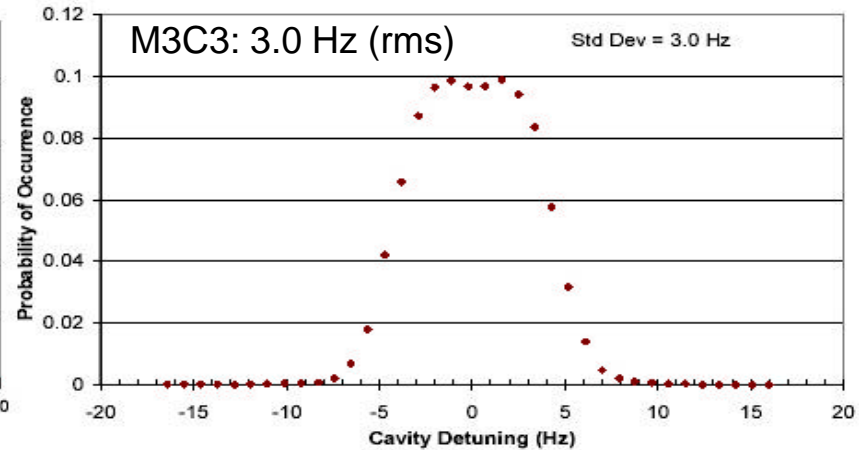


Microphonics in SNS Cavities

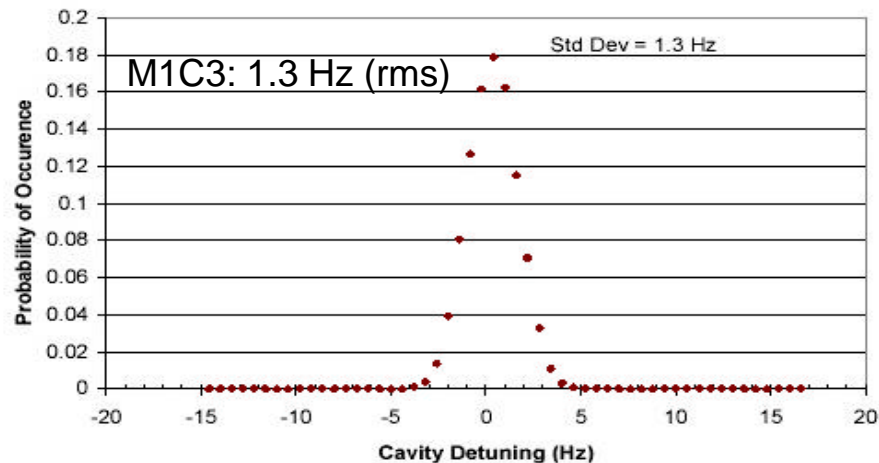
SNS M03, CAVITY 1 BACKGROUND MICROPHONICS HISTOGRAM



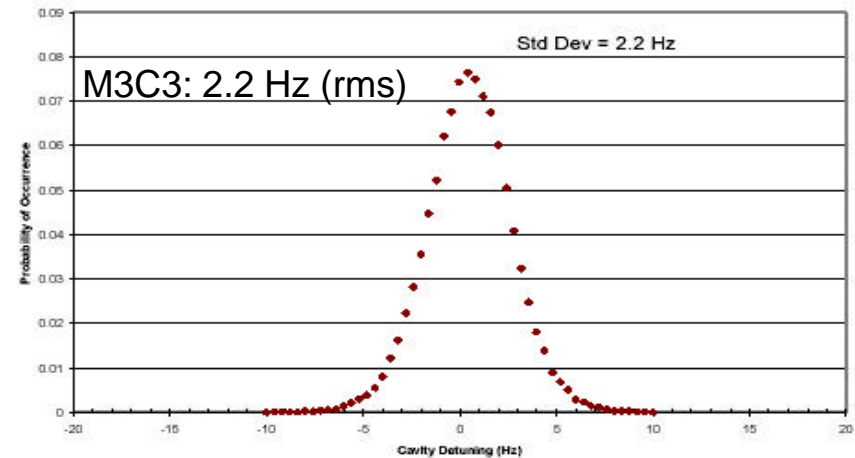
SNS M03, CAVITY 3 BACKGROUND MICROPHONICS HISTOGRAM



SNS M01, CAVITY 3 BACKGROUND MICROPHONICS HISTOGRAM



SNS M02, CAVITY 3 BACKGROUND MICROPHONICS HISTOGRAM



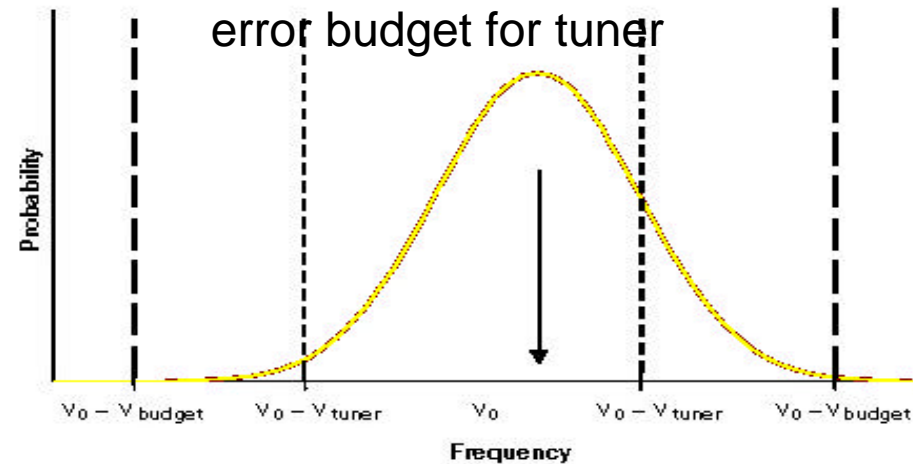
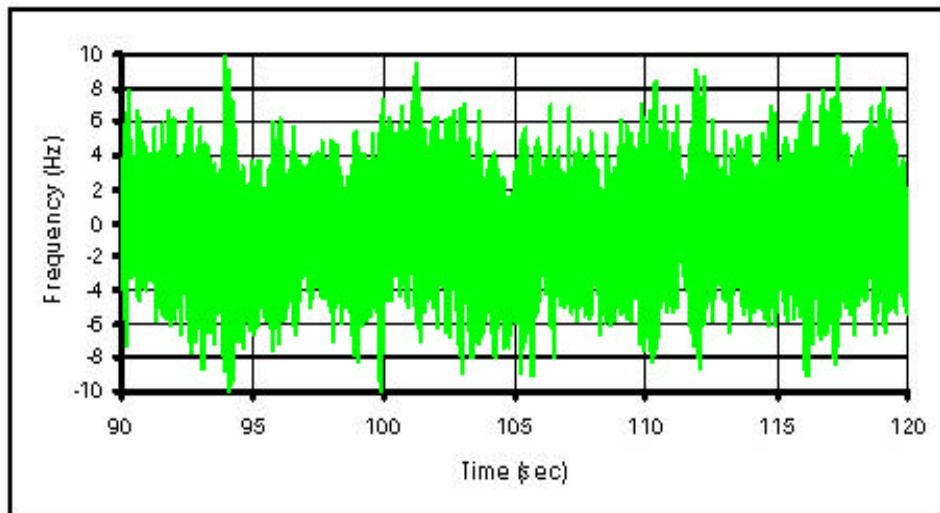
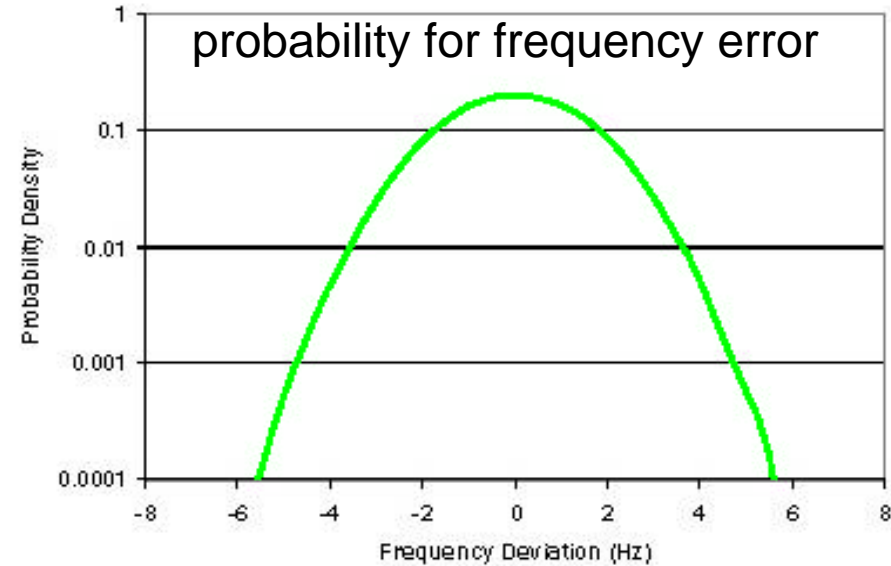
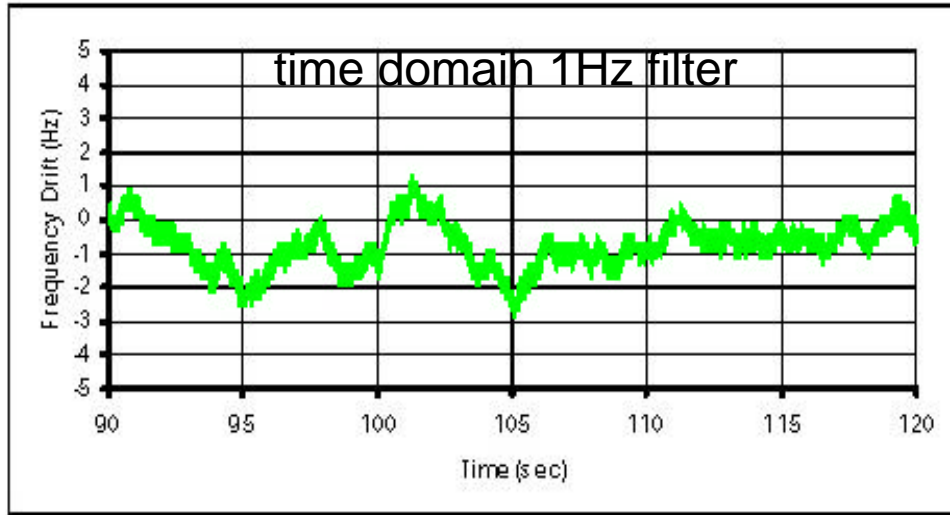
courtesy : J. Delayen, JLAB

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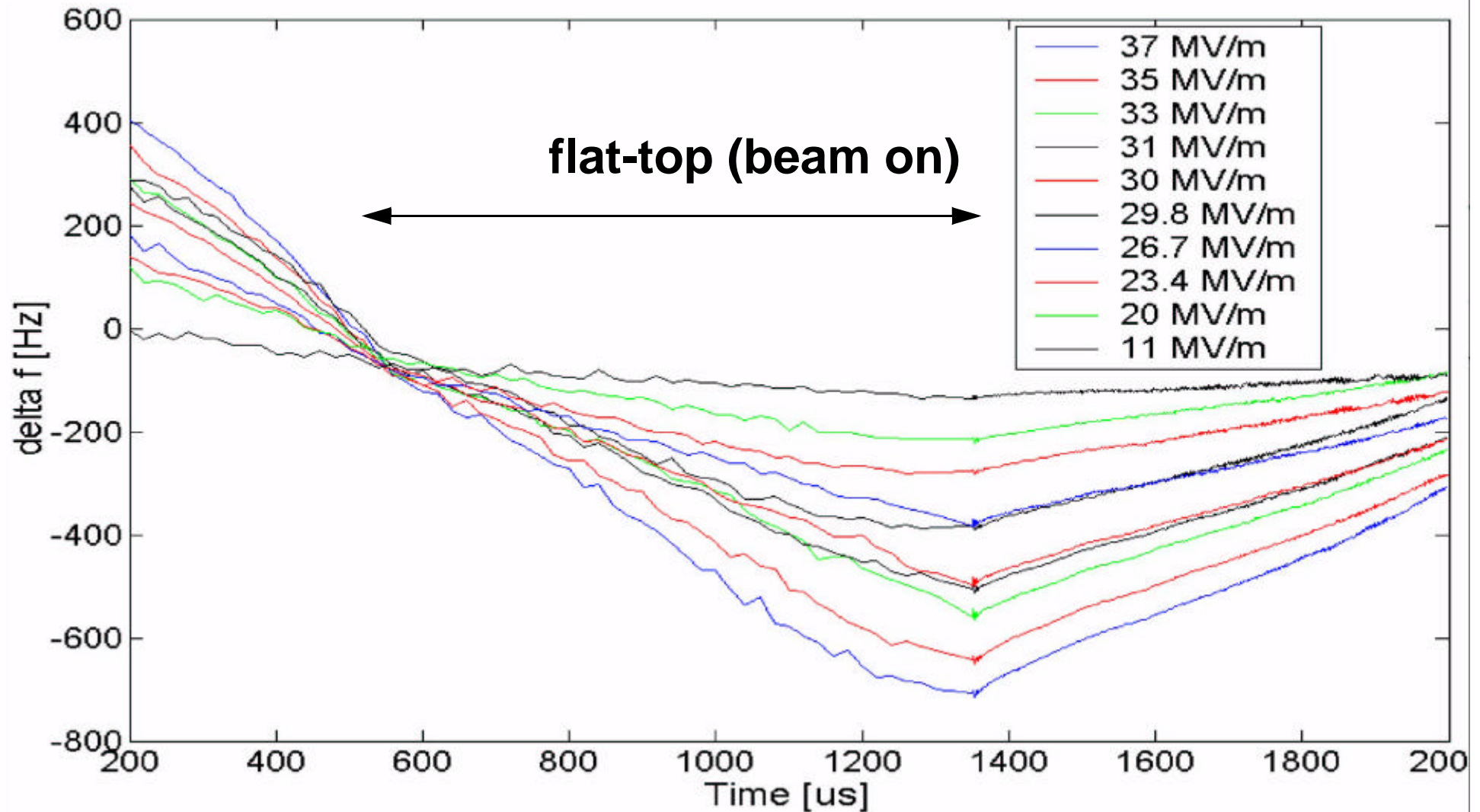


Microphonics for SNS Cavities



courtesy : J. Delayen, JLAB

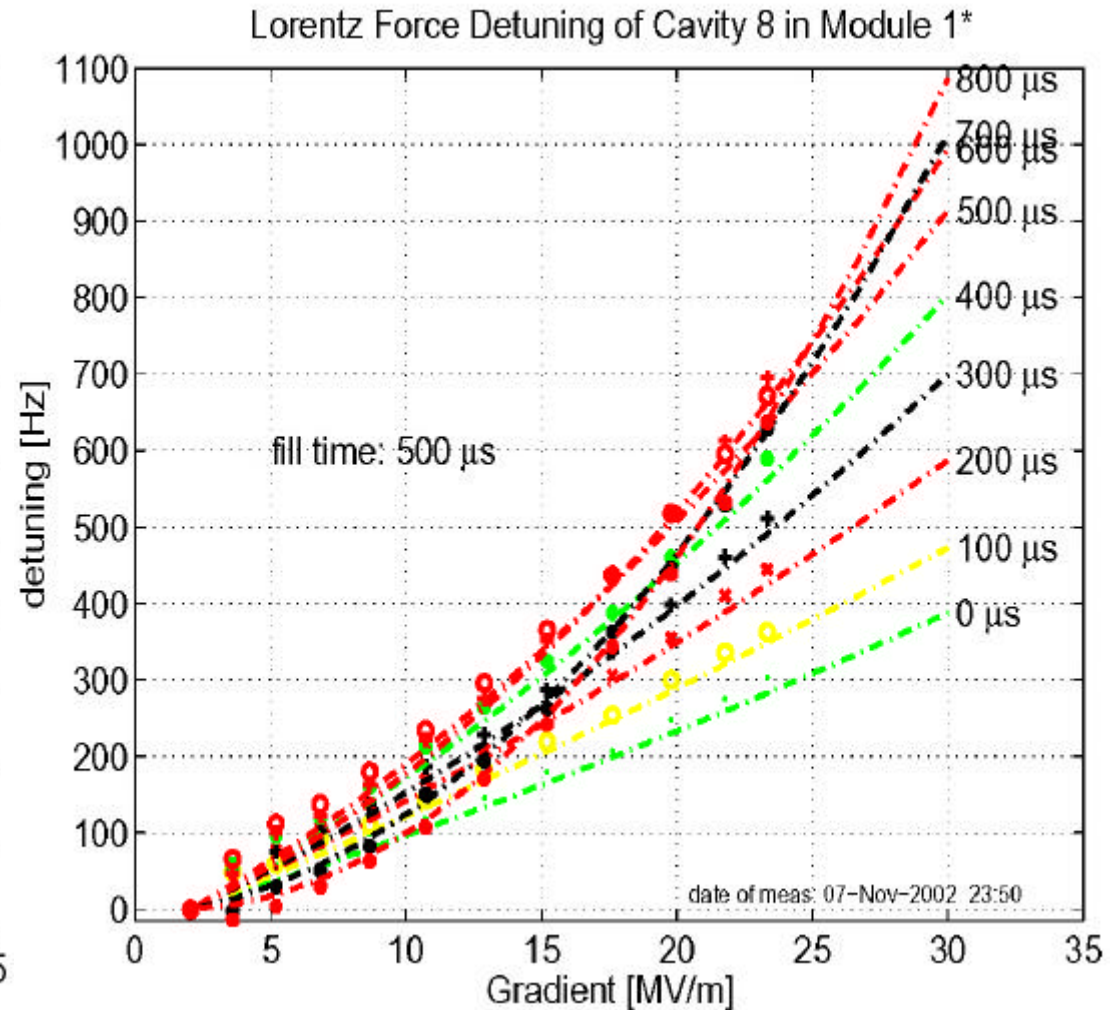
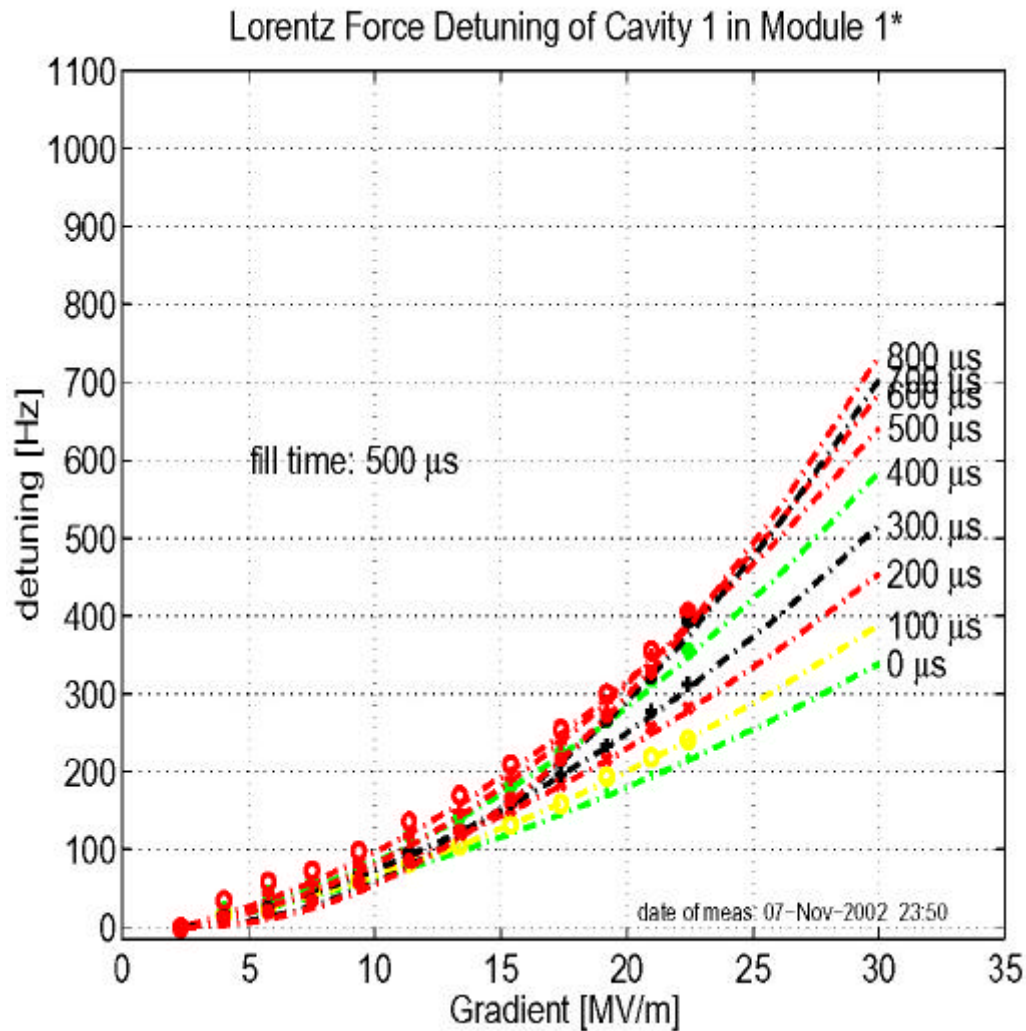
Lorentz Force Detuning (AC73)



courtesy L. Lilje

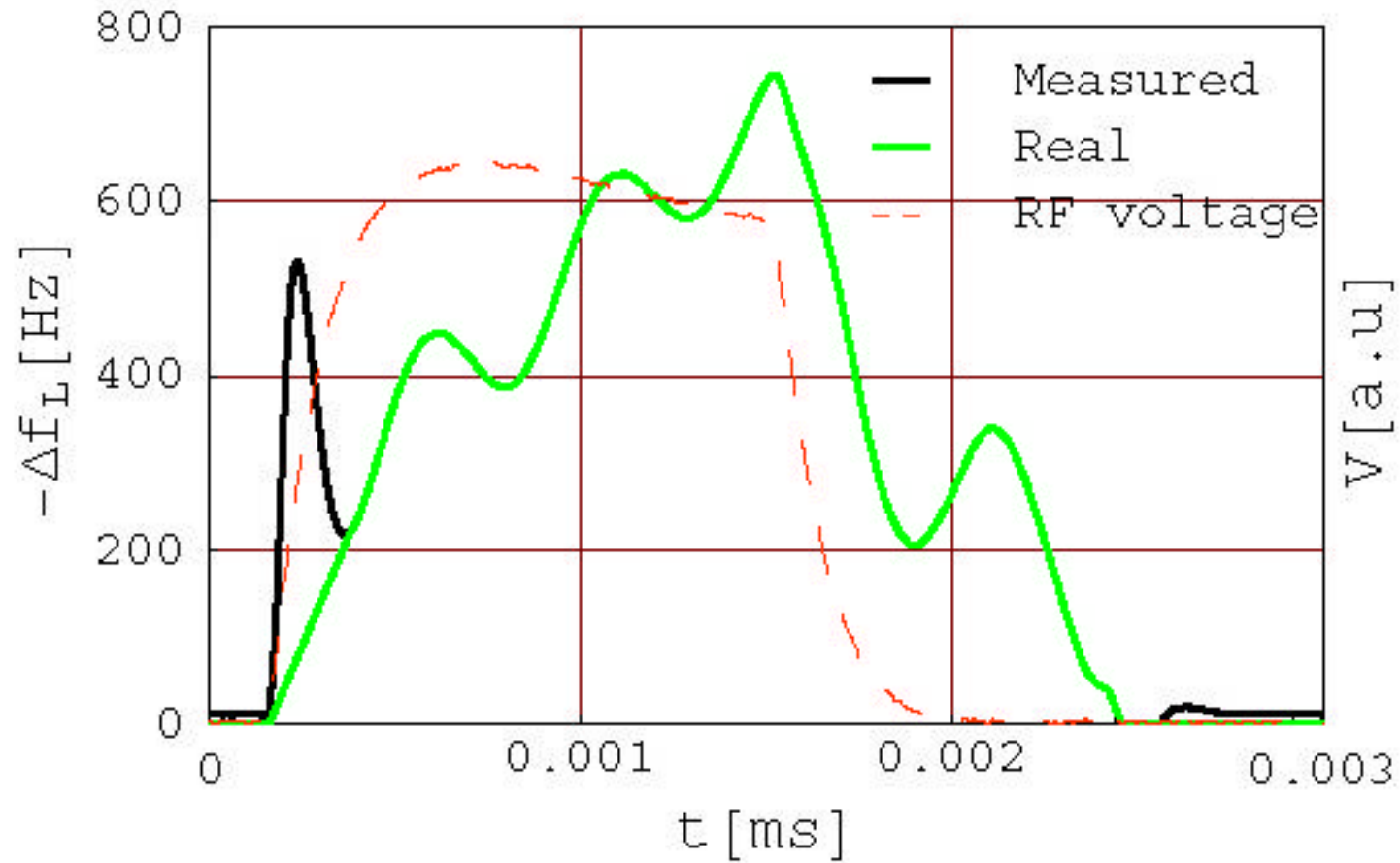


Spread of Lorentz Force Detuning at TTF



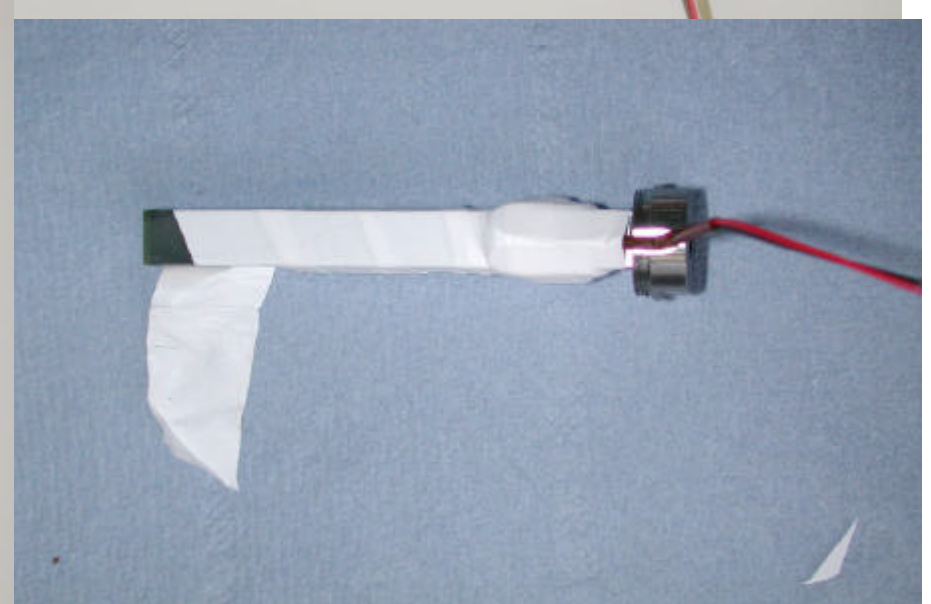
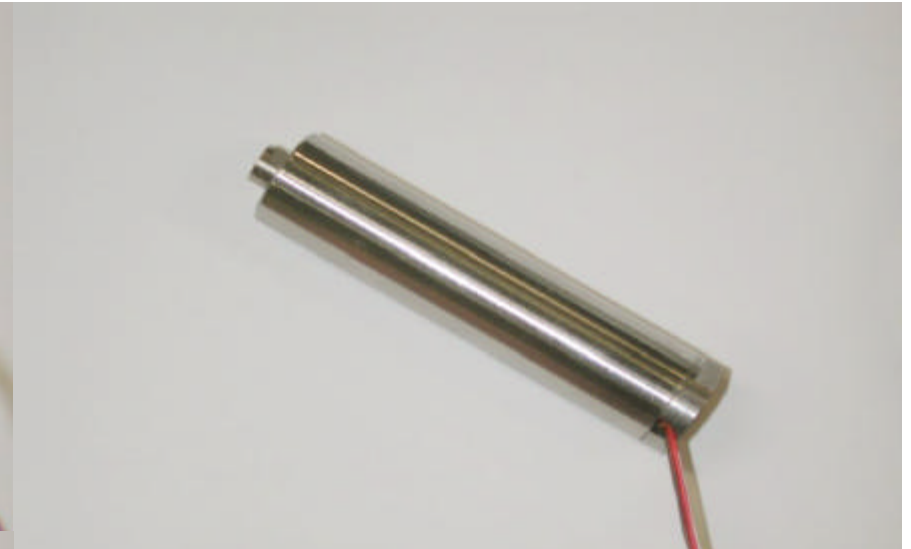
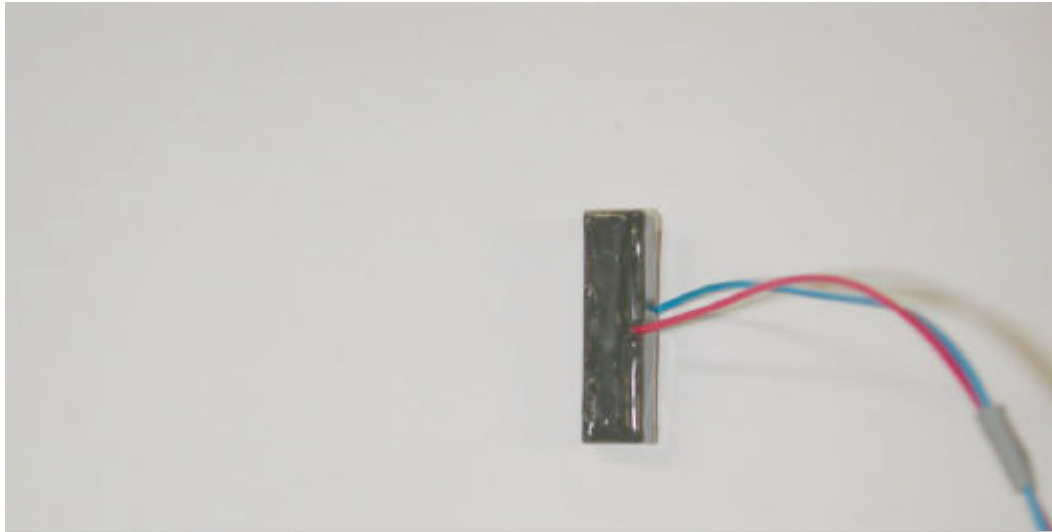
courtesy V. Ayvazyan

Lorentz Force Detuning for SNS cavity

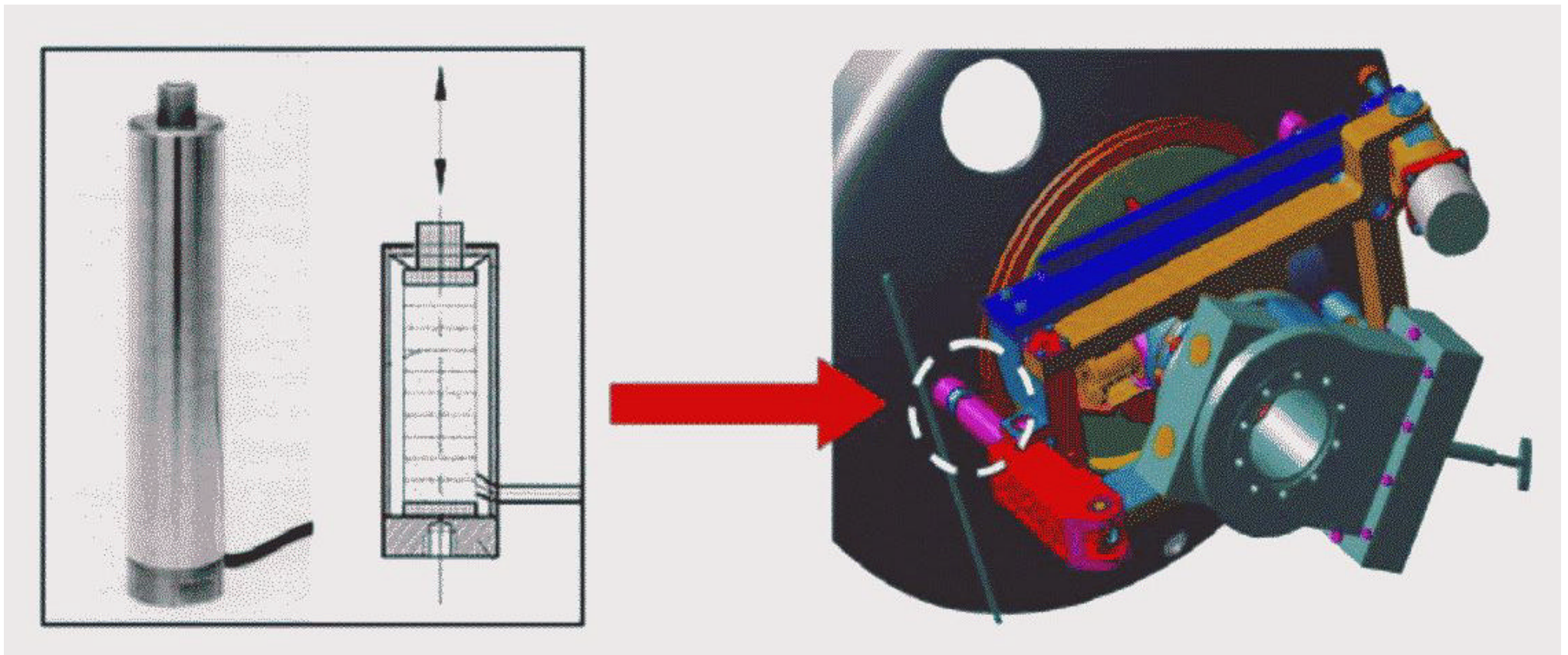


courtesy : J. Delayen, JLAB

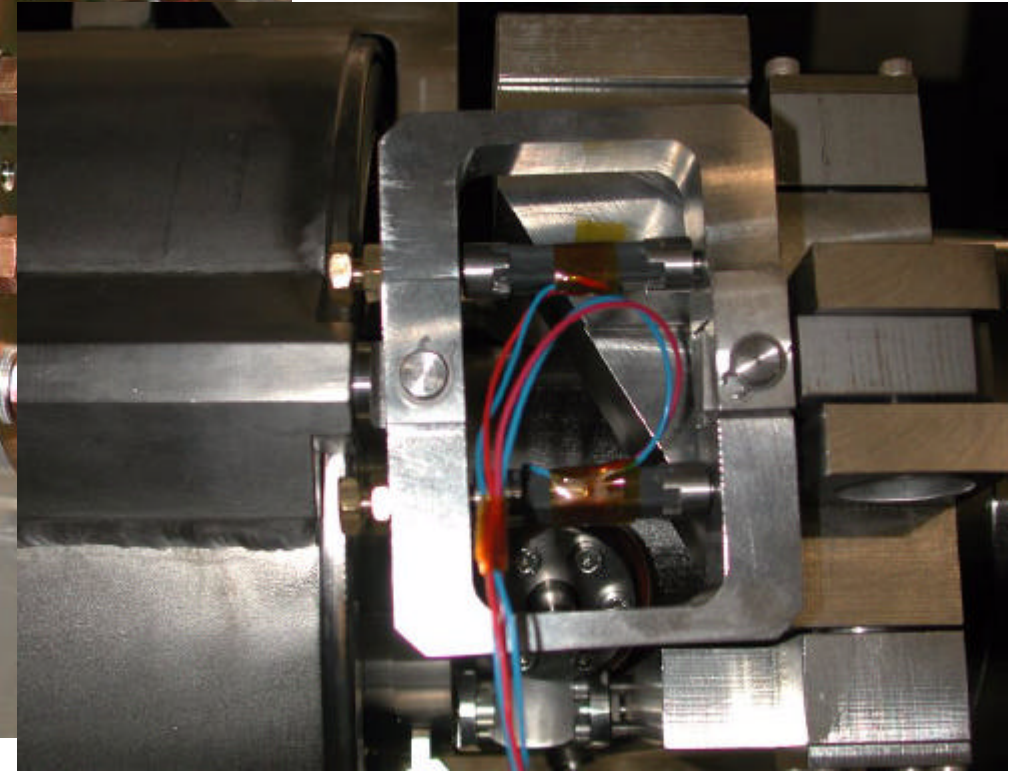
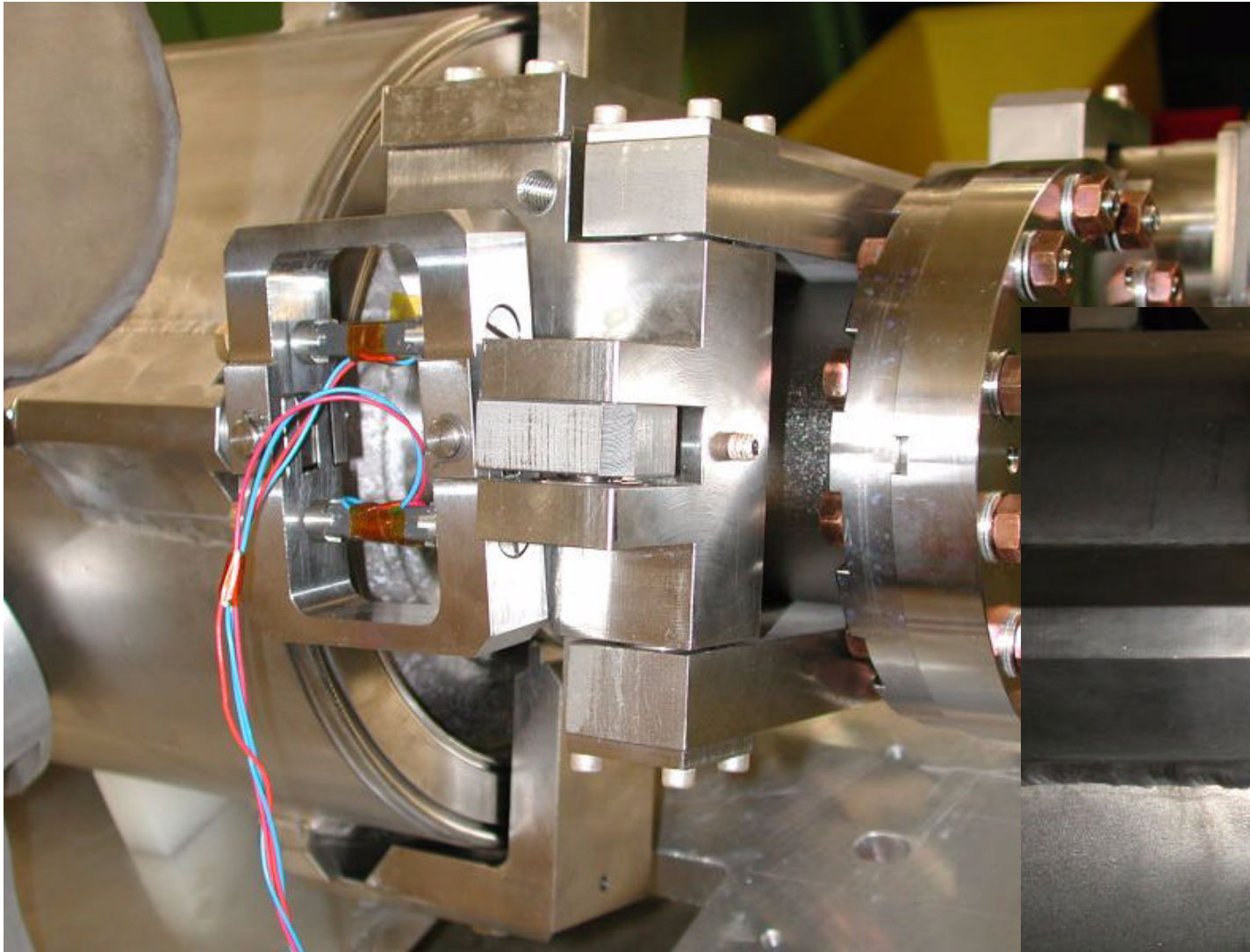
Actuators for Detuning Control Actuators



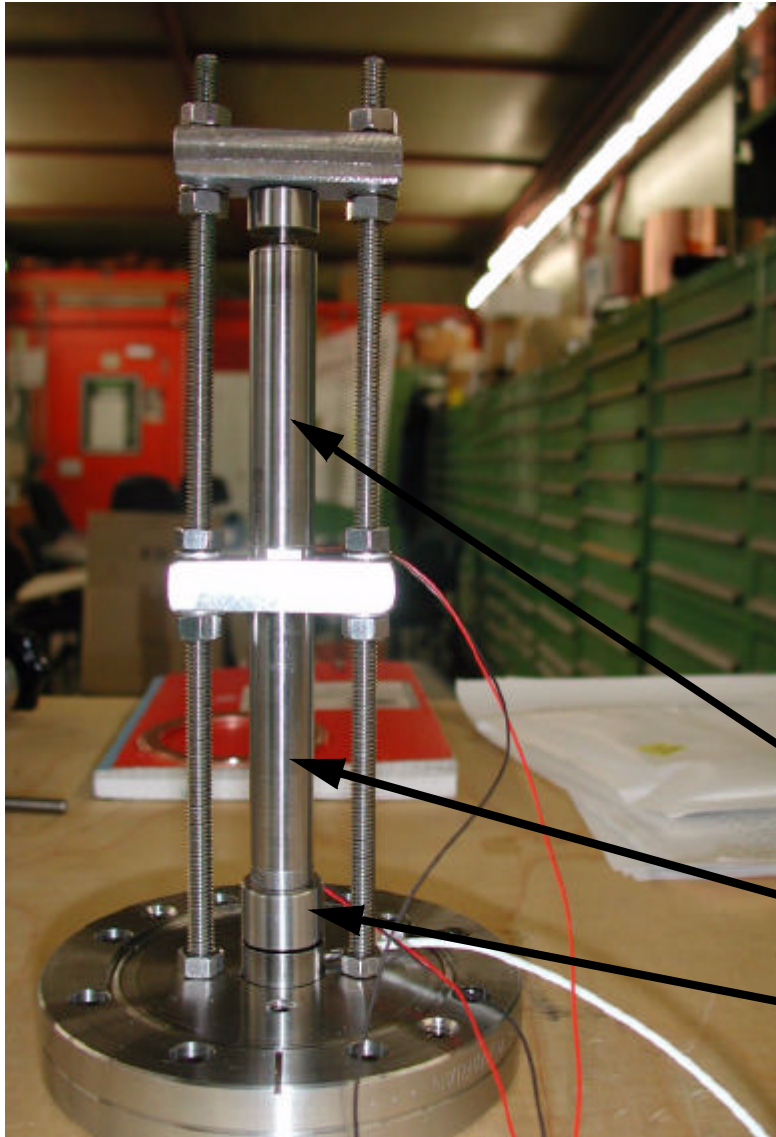
Integration of Piezo Tuner for SNS



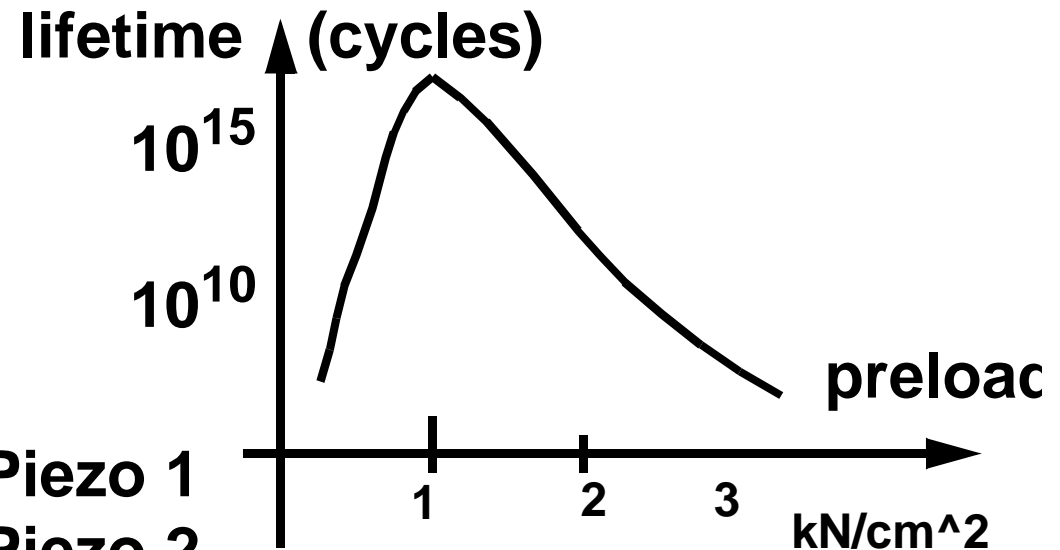
Integration of Piezo Tuner for TTF



Measurement of Mechanical Preload



Lifetime of piezo depends strongly on mechanical preload. Optimum around 1 kN/cm².

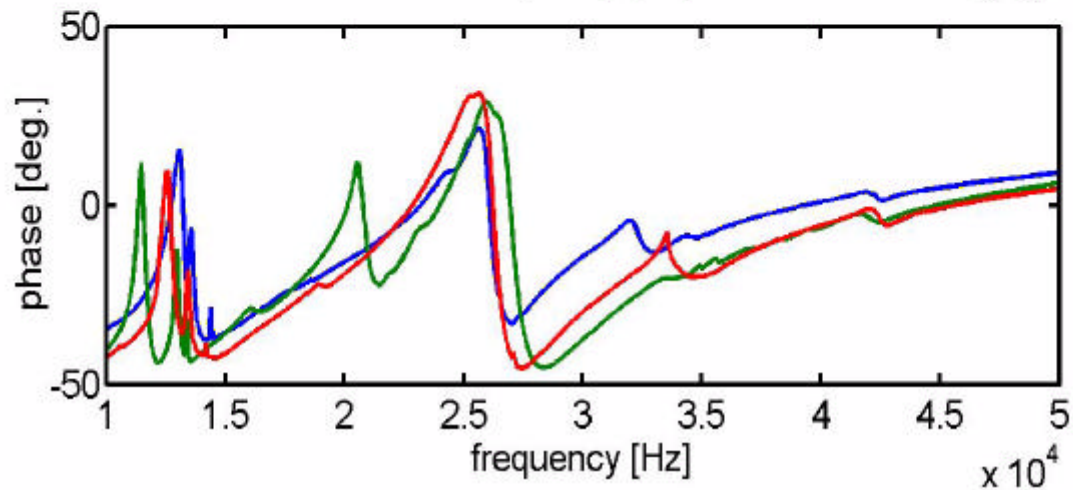
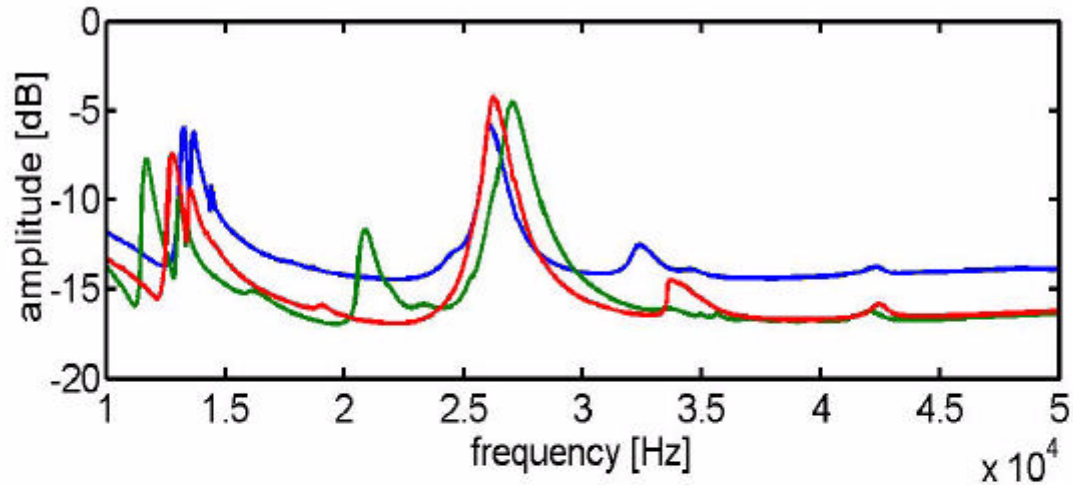


Piezo 1

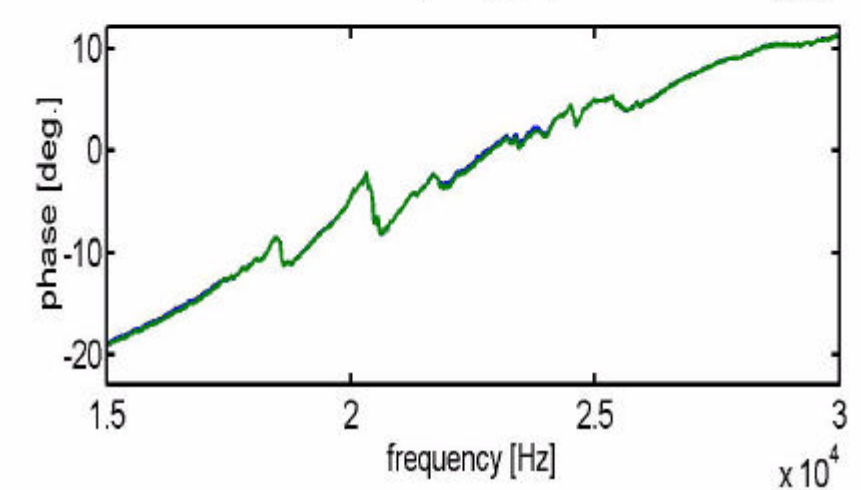
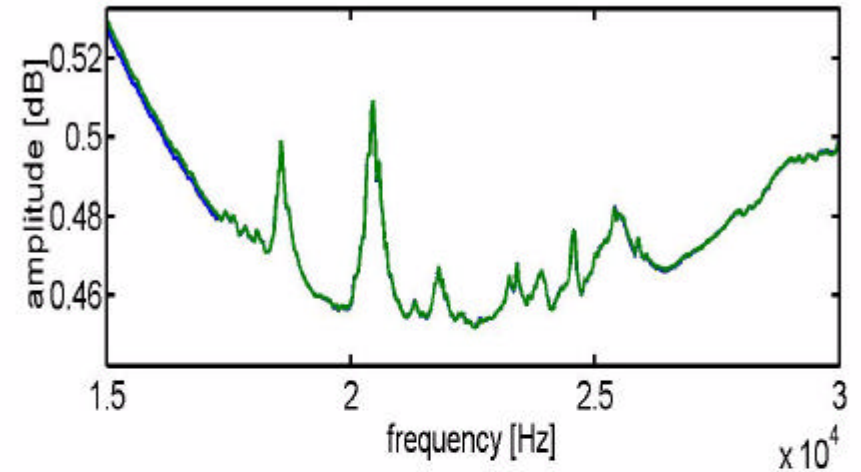
Piezo 2

Force sensor

Piezo Imp. Meas. as Potential Diag. Tool

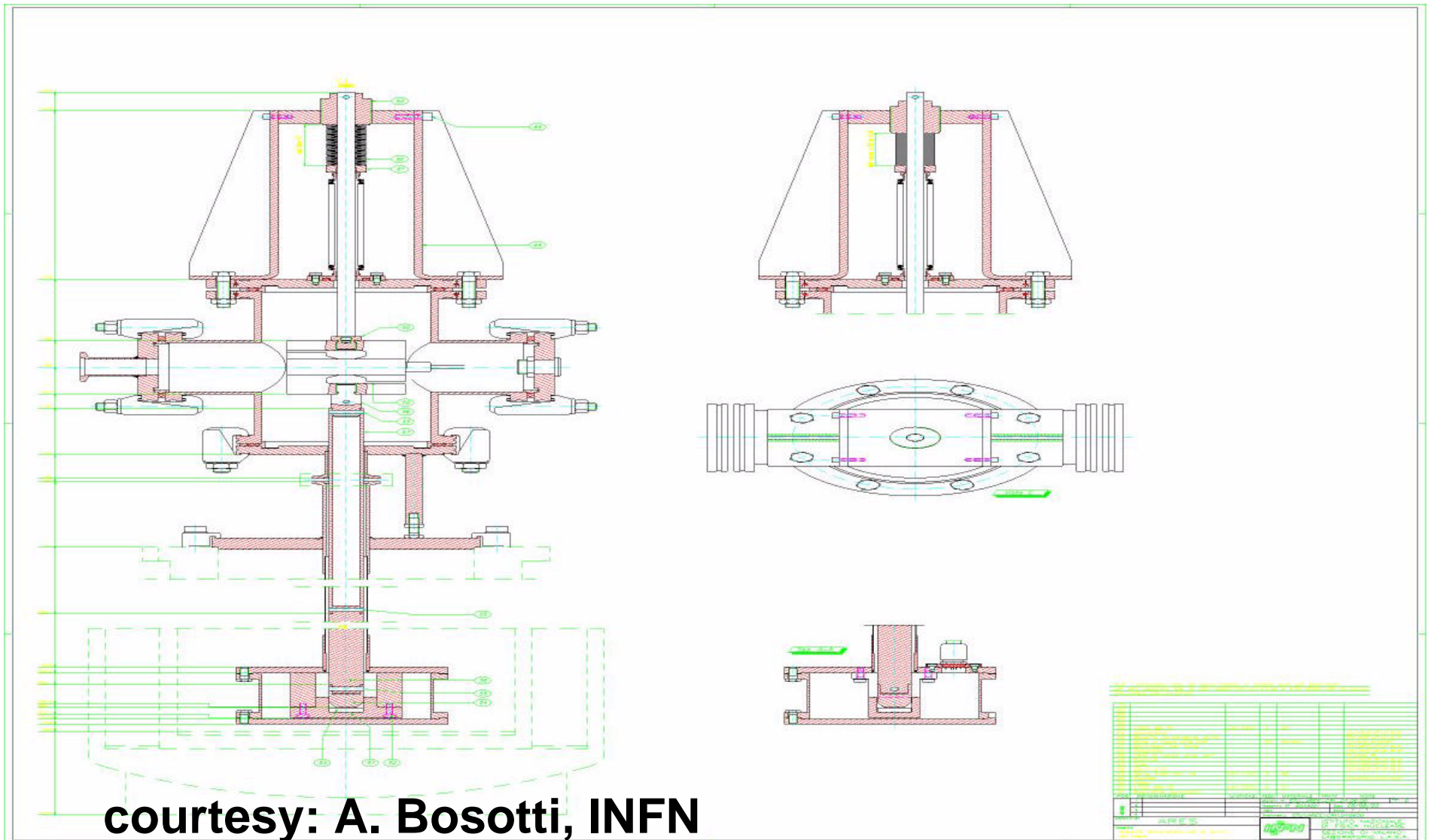


3x Piezomechanik Piezo



Noliac Piezo in Chechia

Measurement of Preload and Stroke



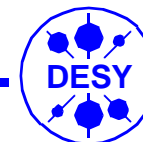
Measurement of Preload and Stroke



courtesy: A. Bosotti, INFN

11th SRF Workshop, 2003

Stefan Simrock

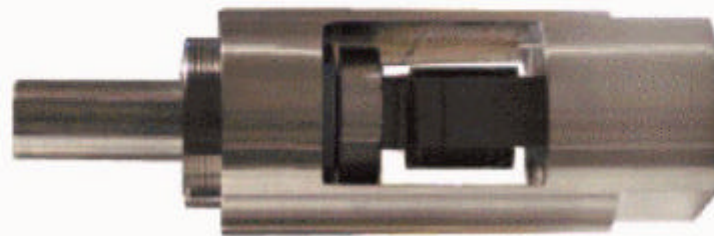
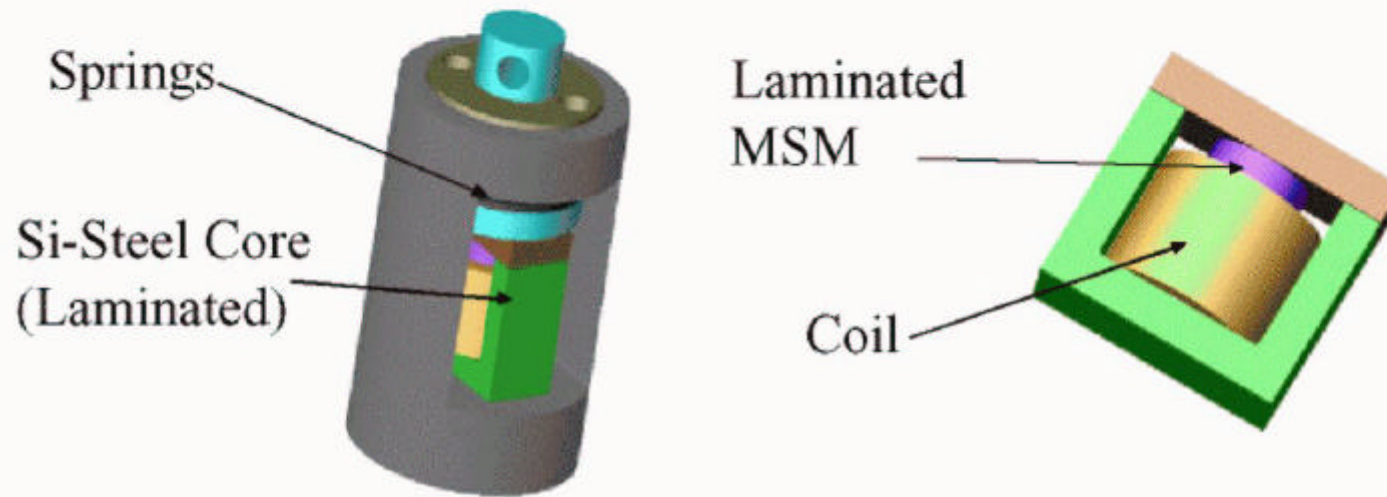


Tuner Specifications:

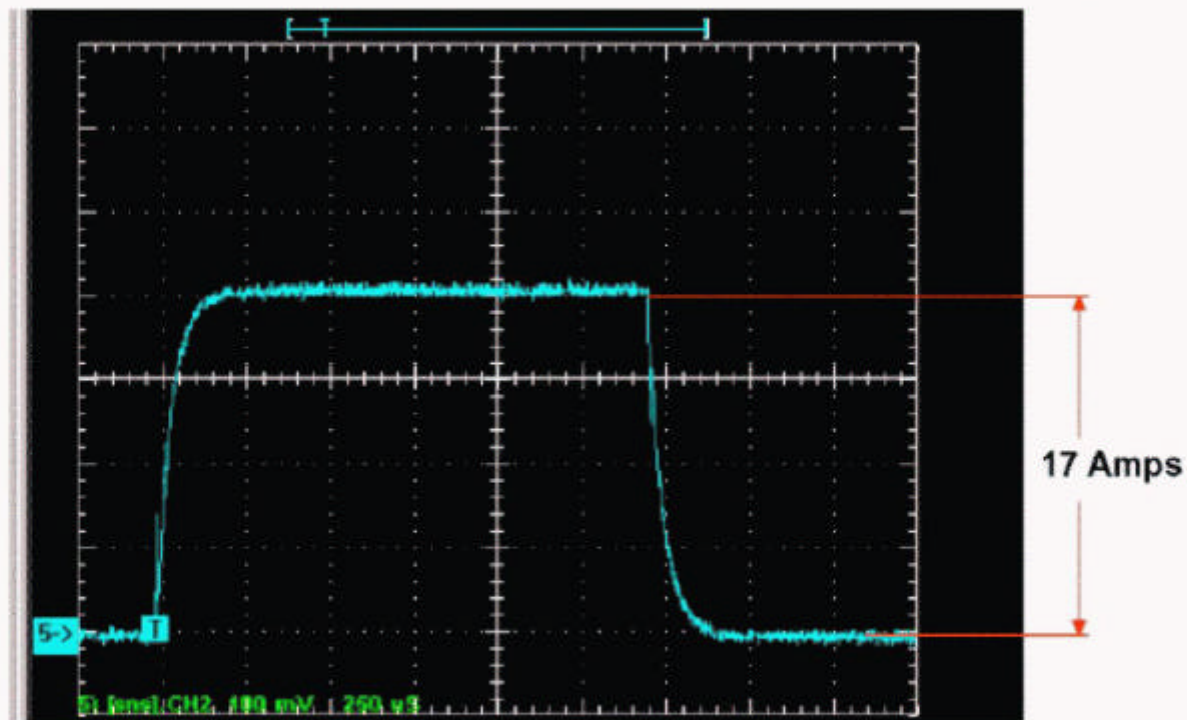
Parameter	Specification
Dimensions:	61.8 mm High x 50 mm Wide x 22 mm Deep
Stroke:	20 μm
Resolution:	better than 0.2 μm
Slew rate:	0.15 $\mu\text{m}/\mu\text{sec}$
Operating Temp:	2.1 K
Load:	3 kN
Stray magnetic field:	< 25mG at 30 mm from actuator
Pulse Length:	1.6 ms
Repetition Rate:	60 per second
Heat Load to 2.1 K:	< 0.1 W
Lifetime:	5×10^{10} Cycles

2

The Fast Tuner



Fast Tuner Ramp Rate Testing



- ⚡ The response of the superconducting coil to a step input.
- ⚡ Takes 130 μ s for the current to ramp up and down.

Results:

- ✦ Total stroke of 20 μm
- ✦ 0 to full stroke in 130 μsec
- ✦ Stray field at a distance of 30 mm from the surface of the actuator is <20mG
- ✦ Tested to 100 million cycles with no change in performance
- ✦ Fatigue analysis is underway

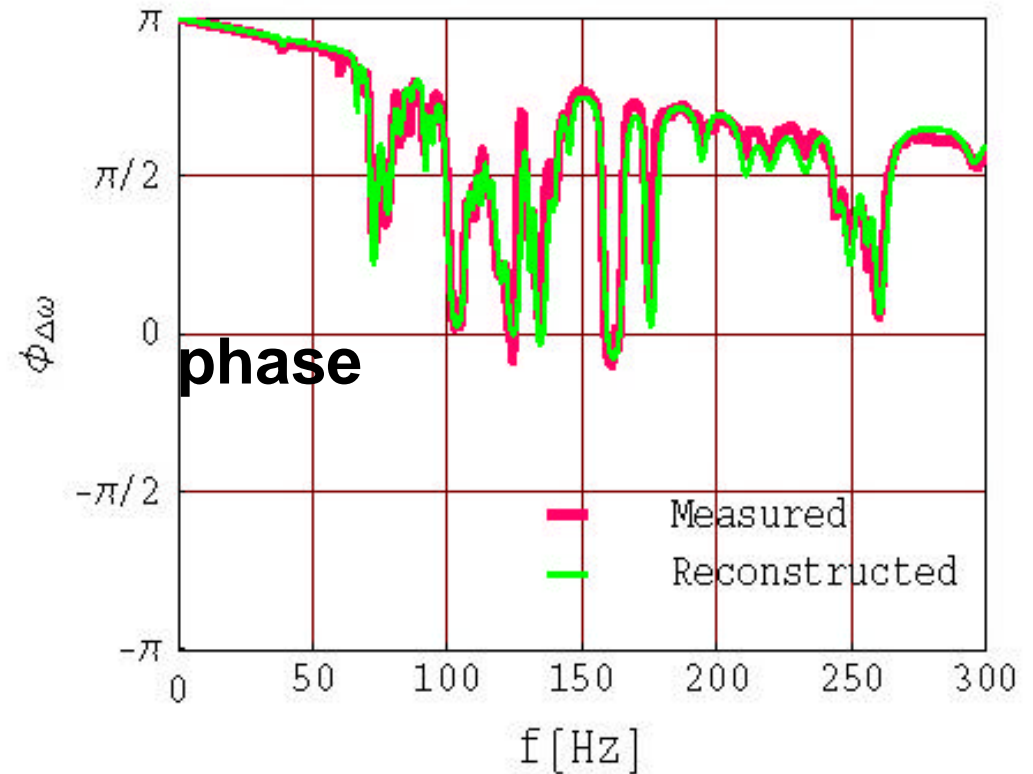
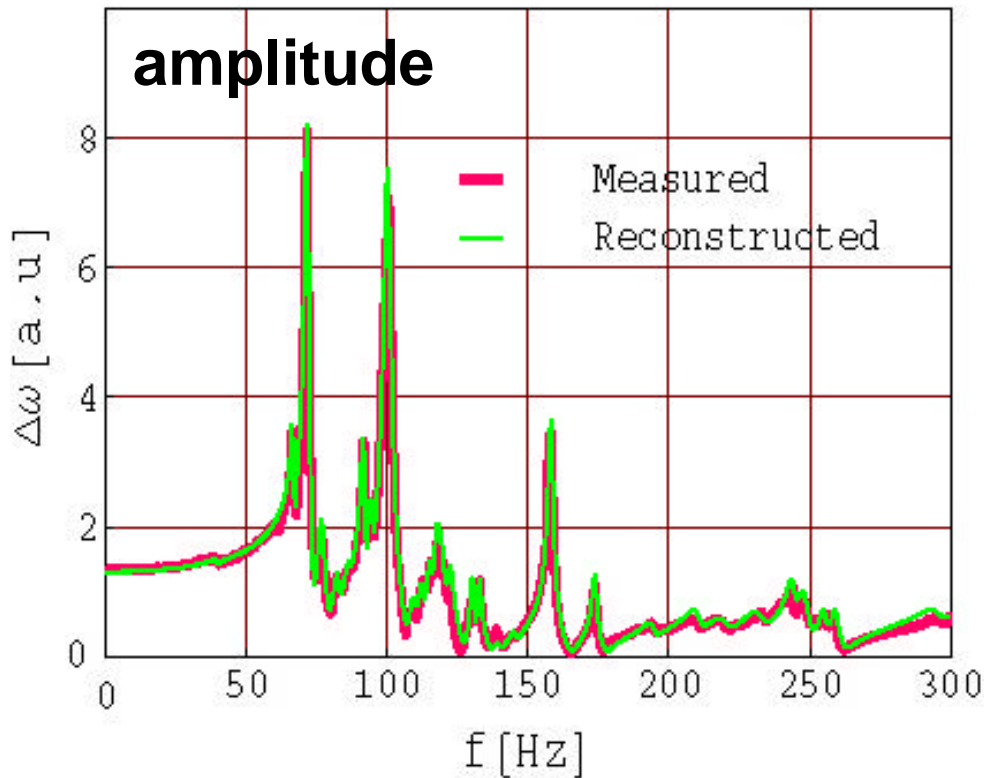
Control of Cavity Detuning

- Feedforward applicable to correct repetitive errors such as Lorentz Force detuning
 - coupling of Lorentz force and piezo actuator to cavity detuning must be similar
 - slow parameter changes can be corrected with adaptive feedforward
- Feedback required for stochastic errors such as microphonics
 - transfer function from piezo actuator to detuning must allow controller design which allows stability of closed loop
 - transfer function must be stable for timescale of adaptation of controller



Transfer Function

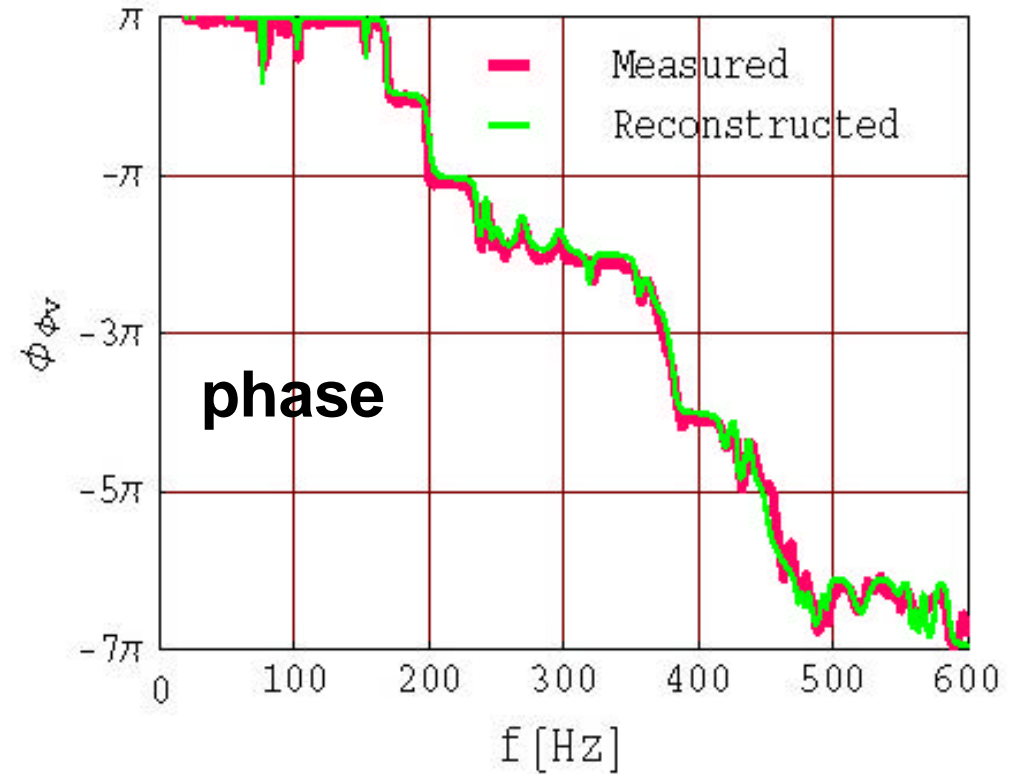
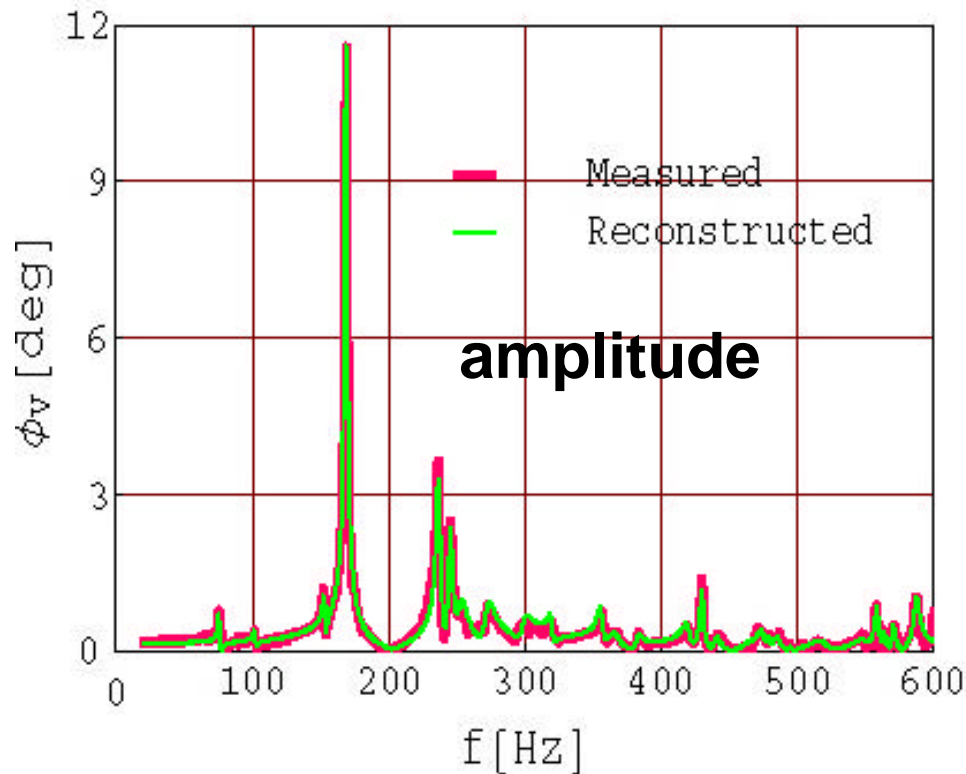
Transfer function Lorentz Force --> Detuning, SNS cavity



courtesy: J. Delayen, JLAB, M. Doleans, ORNL

Transfer Function

Transfer function Lorentz Force --> Detuning, SNS cavity

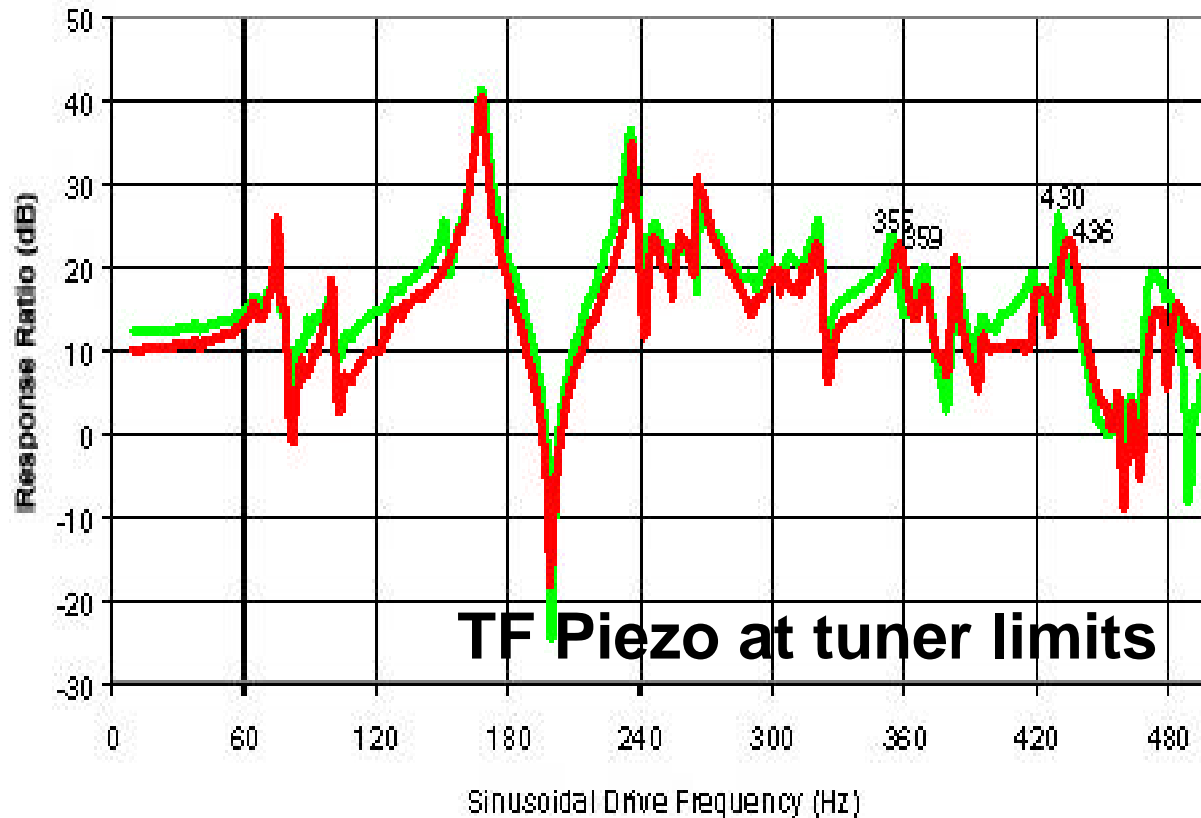


courtesy: J. Delayen, JLAB, M. Doleans, ORNL

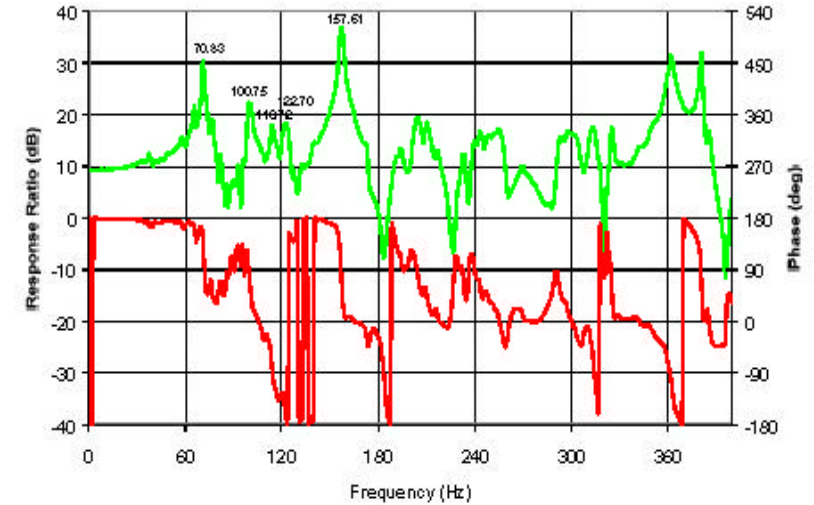


Transfer Function Piezo for SNS Cavities

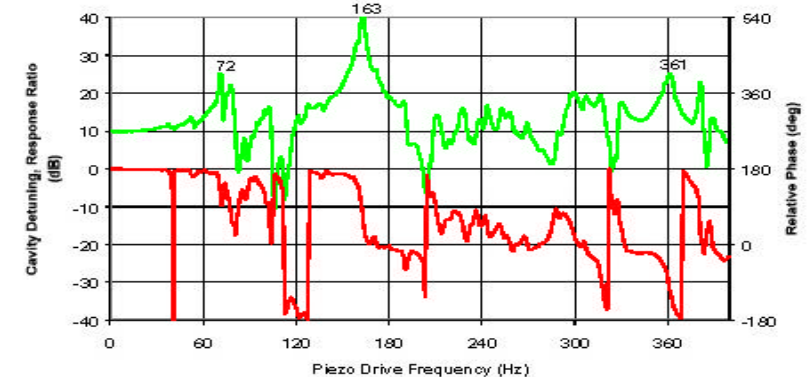
Piezo Transfer Function at Two Extremes of Coarse Tuner
 Med Cryomodule Prototype, Cavity Position 2, 3.5 MV/m GW



Cavity Pos 1, Piezo Transfer Function



Cavity Position 3, Piezo Transfer Function



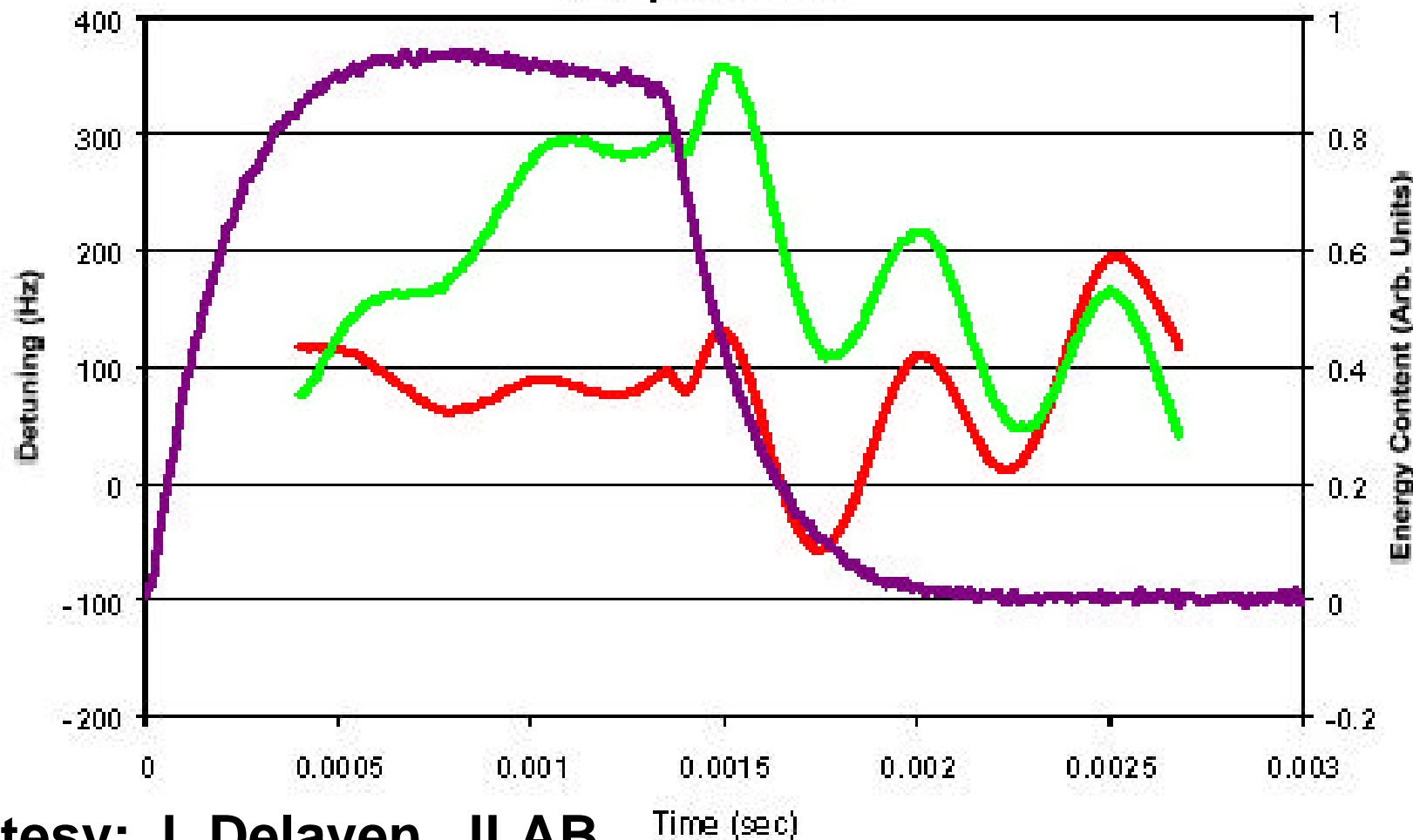
TF Piezo for 2 cavities

courtesy: J. Delayen, JLAB

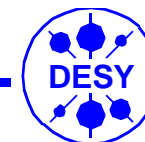


Control of Lorentz Force Detuning

Cavity # 2 @ 10 MV/m, with and without piezo compensation

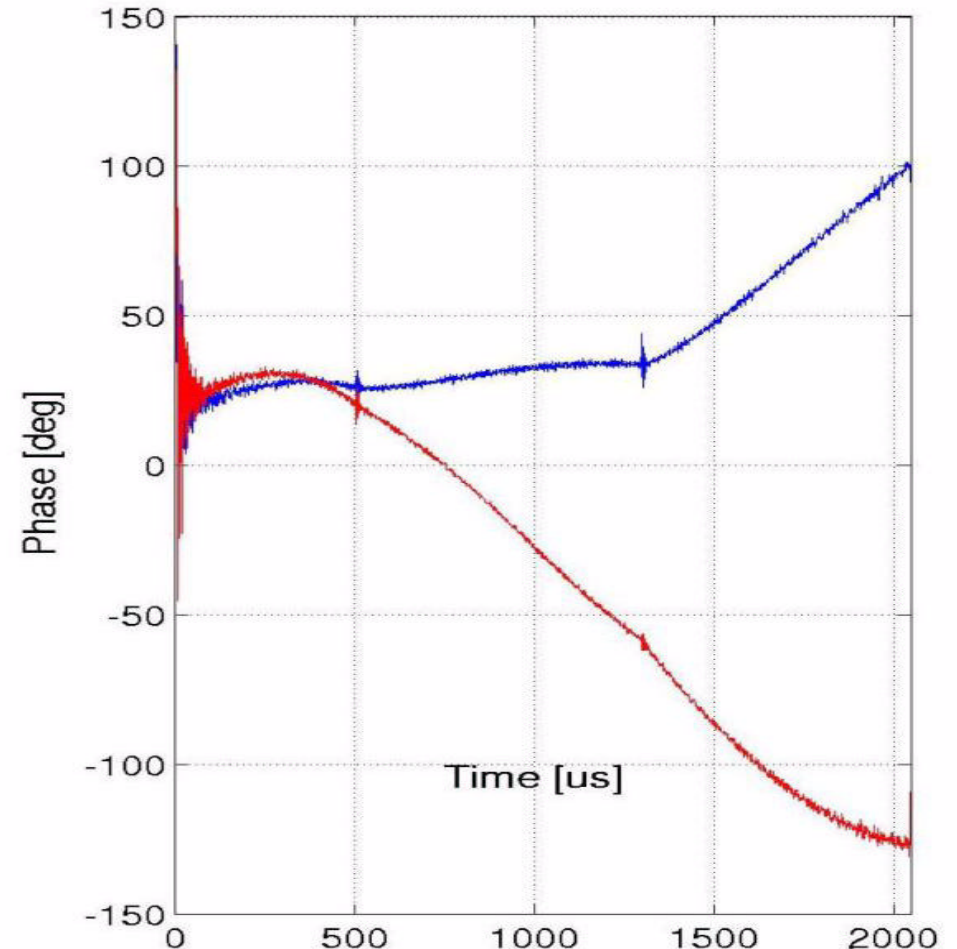
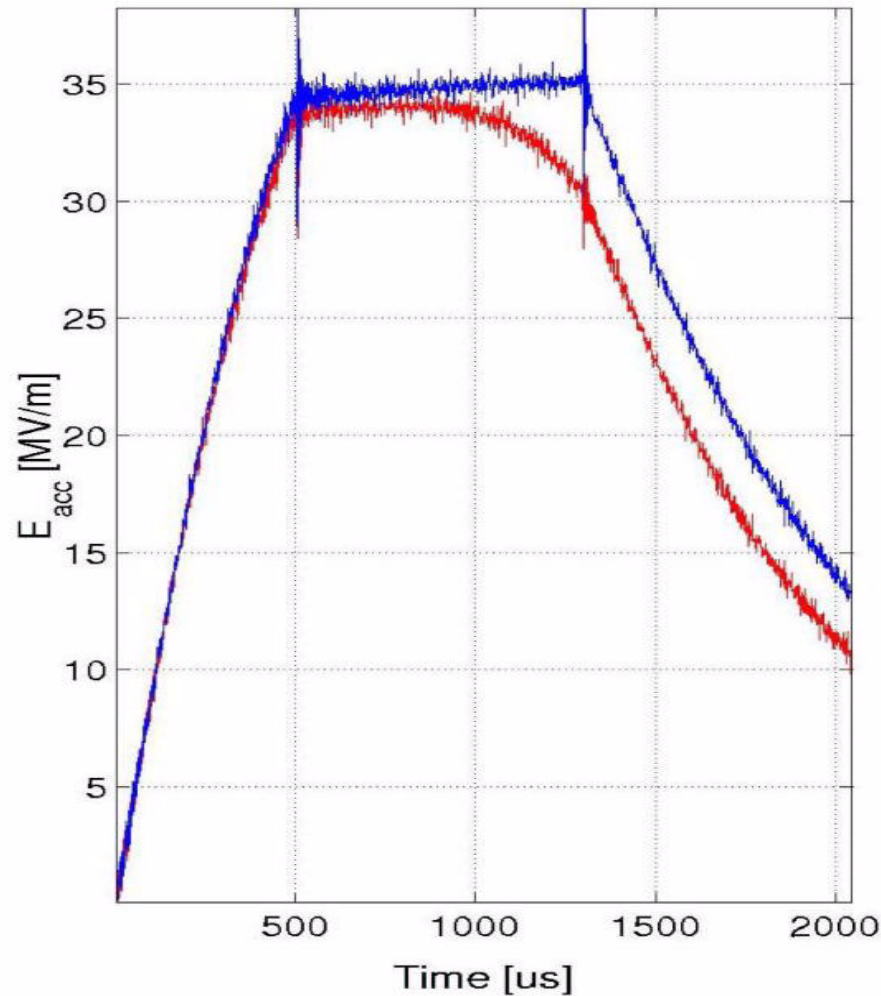


courtesy: J. Delayen, JLAB



Control of Lorentz Force Detuning Control

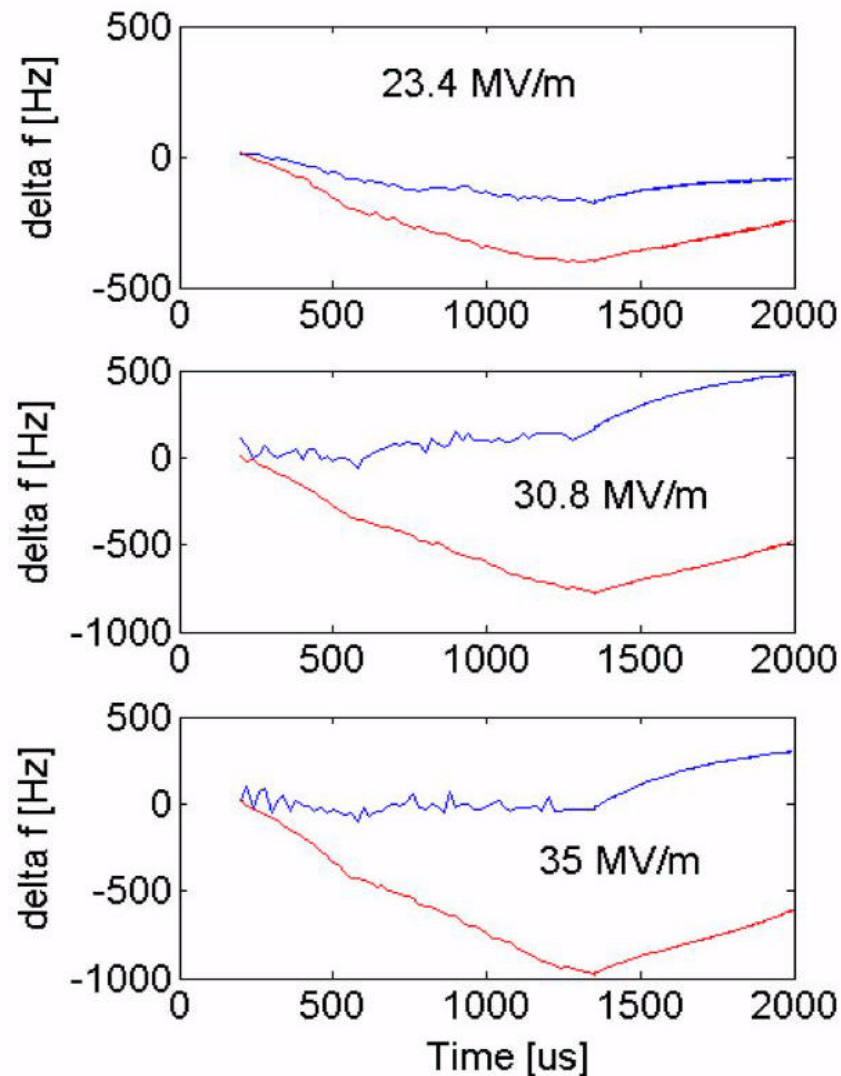
RF signals at 35 MV/m



courtesy: L. Lilje, DESY



Control of Lorentz Force Detuning (TTF)



Frequency stabilization at 35 MV/m

Blue: With piezo

Red: Without piezo

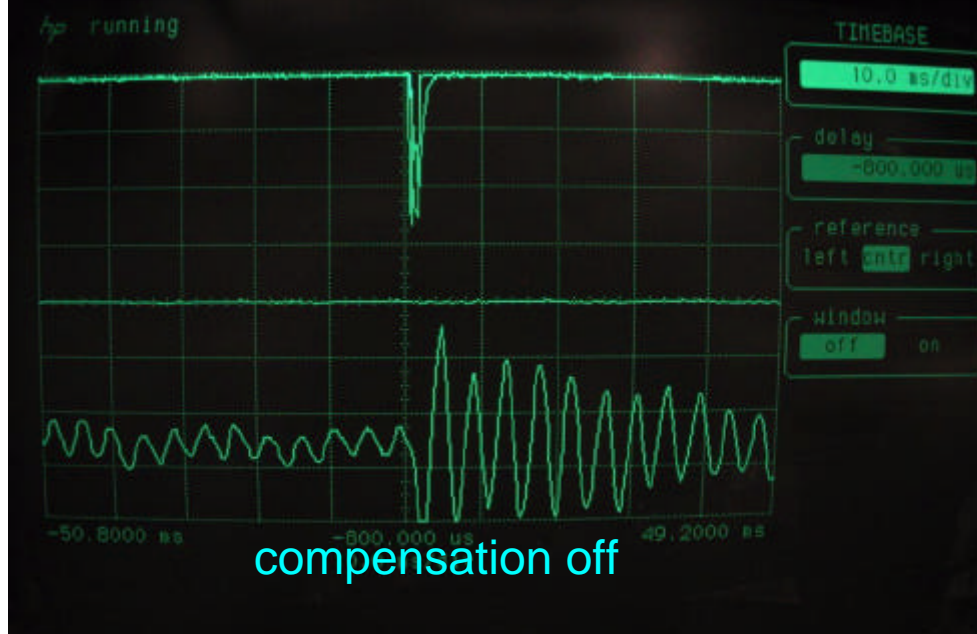
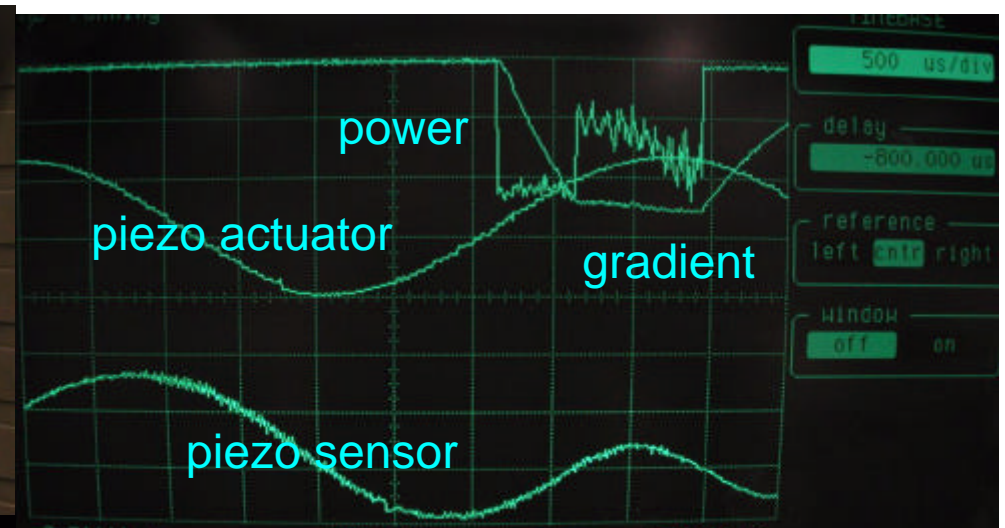
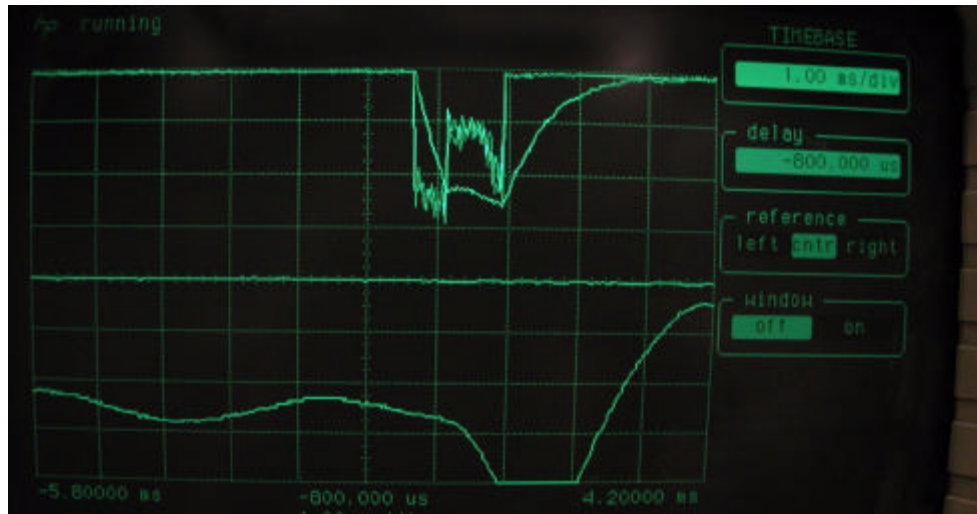
Frequency detuning of ~ 1000 Hz compensated with resonant excitation of a mechanical cavity resonance at 230 Hz.

NOTE: This is rather an demonstration of the capability of active tuning. Application in a real machine is probably difficult/impossible.

courtesy: L. Lilje, DESY



Control of Lorentz Force Detuning (TTF)

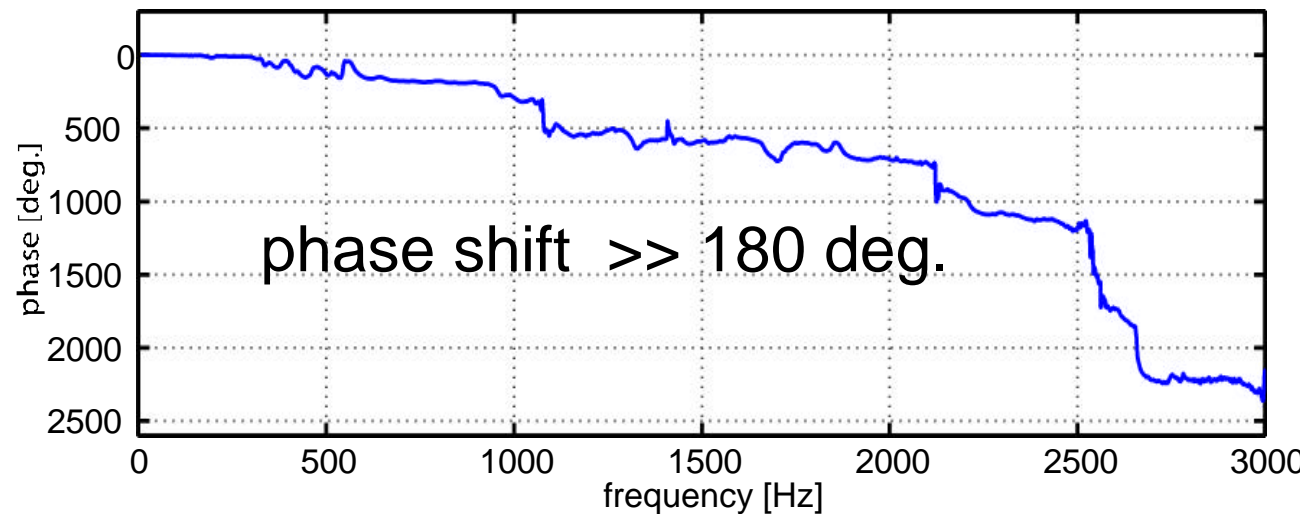
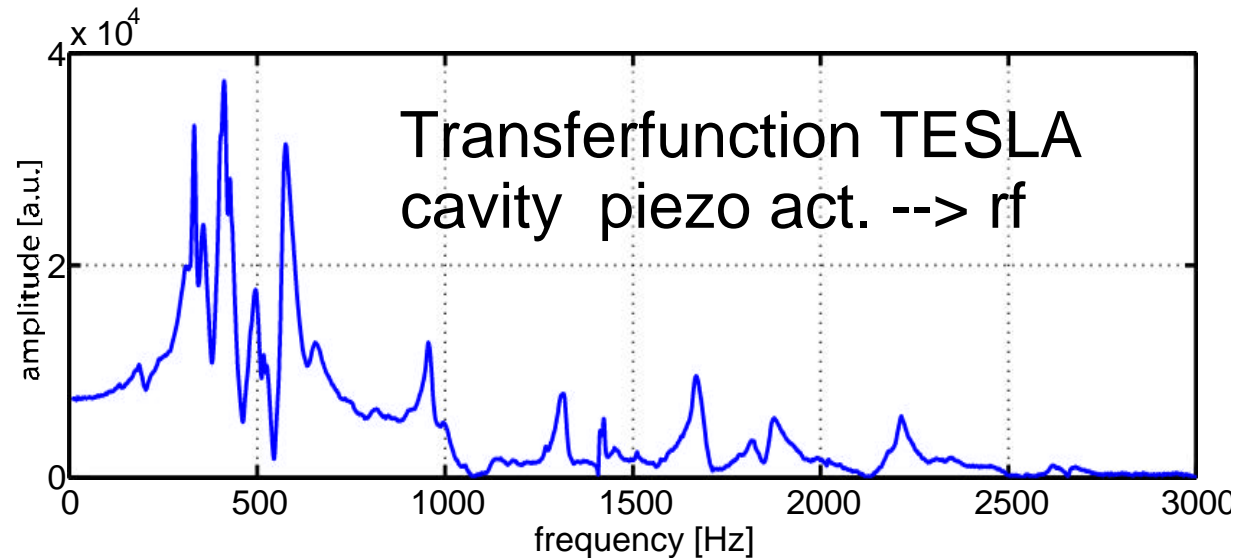


compensation off

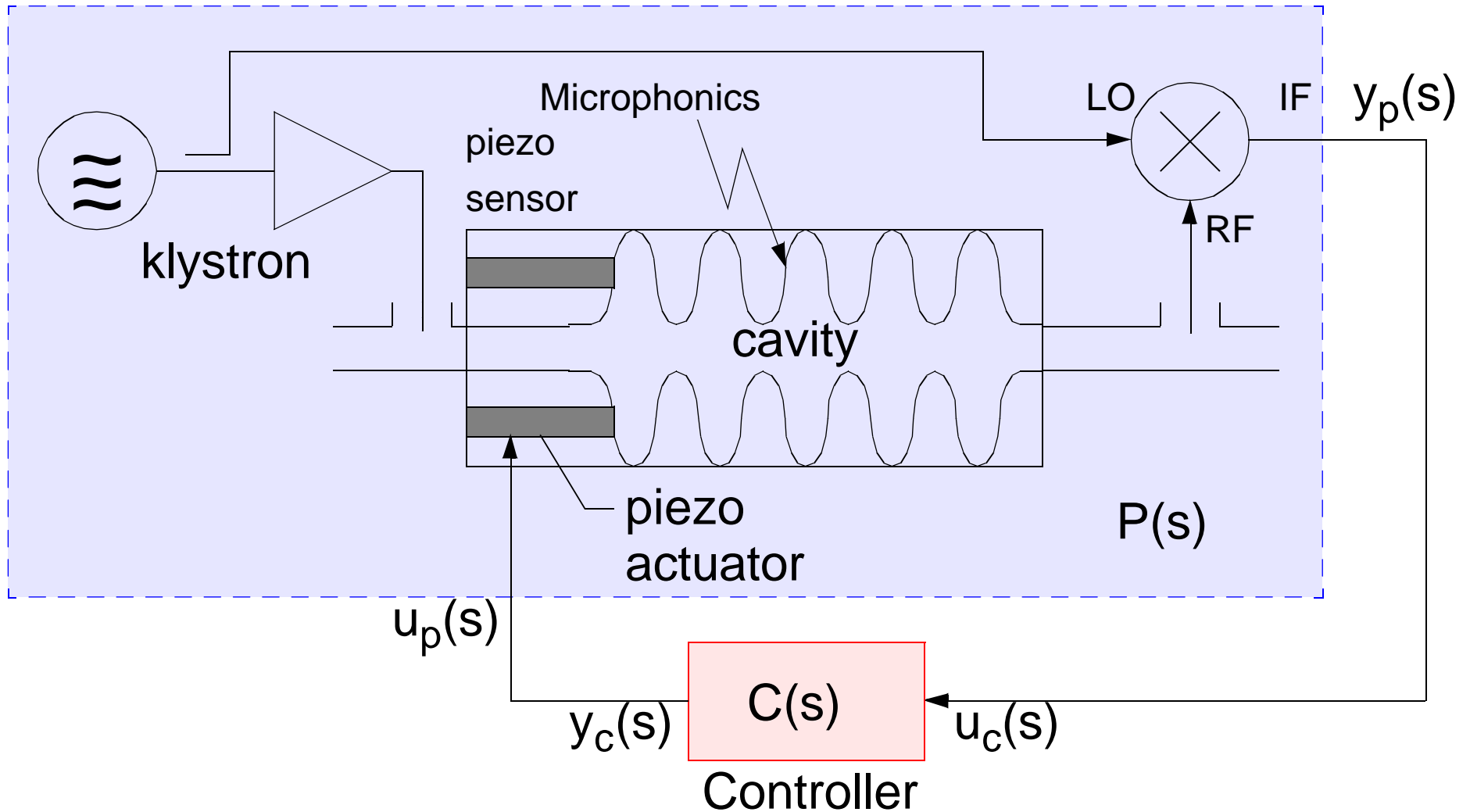
compensation on

Microphonics Control Problem

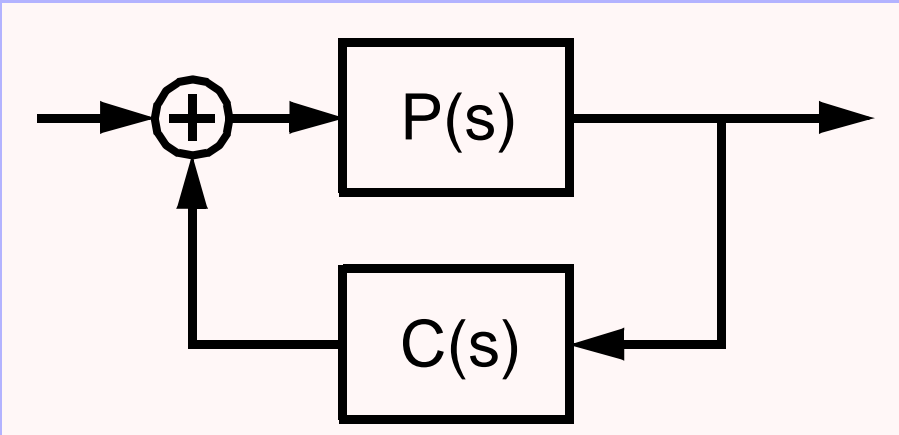
- Feedback is required due to stochastic nature of microphonics
- Transfer function piezo actuator --> cavity detuning shows many mechanical resonances from cavity
- Stability of Feedback loop ?



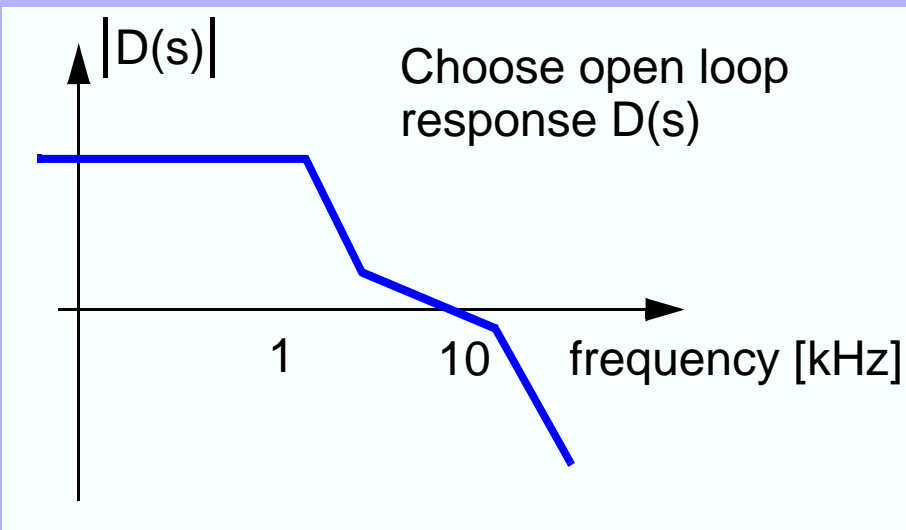
Microphonics Control



Controller Design



$$\Rightarrow C(s) = \frac{D(s)}{P(s)}$$



$D(s)$: stability criteria fulfilled
high gain at low freq.
fast roll-off at high freq.

Feedback Successfully Applied to QWR

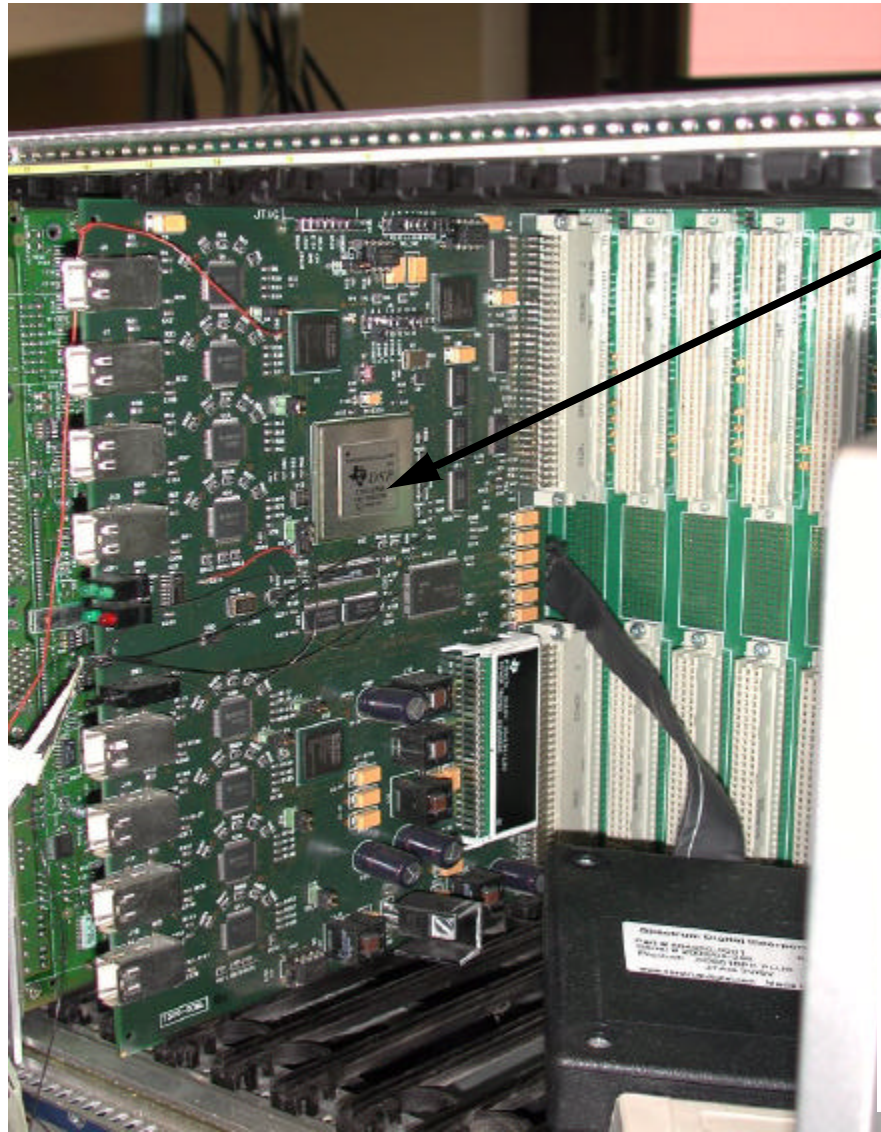
- C6701 processor from TI on PCI board (M67) with 4 ADCs and DACs (200kHz sampling rate)
- Programmed state space equation for 20th order system:

$$\begin{aligned}\hat{\mathbf{x}}_{k+1} &= \mathbf{A}\hat{\mathbf{x}}_k + \mathbf{B}\hat{\mathbf{u}}_k \\ \hat{\mathbf{y}}_{k+1} &= \mathbf{C}\hat{\mathbf{x}}_{k+1} + \mathbf{D}\hat{\mathbf{u}}_{k+1}\end{aligned}$$

- **Latency only 20 μ s for 20x20** matrix multiplication (C++)
- Applied only **notchfilter (672 Hz) and low pass (1kHz)** to control microphonics in QWR



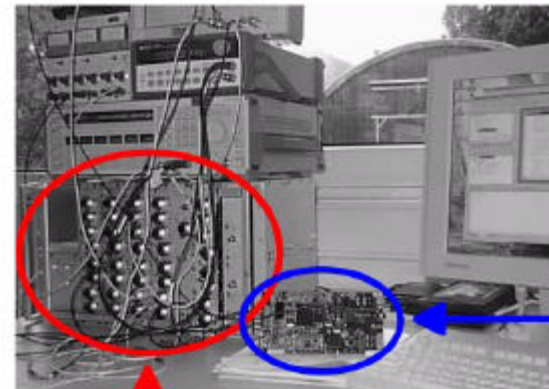
Digital Controller



DSP

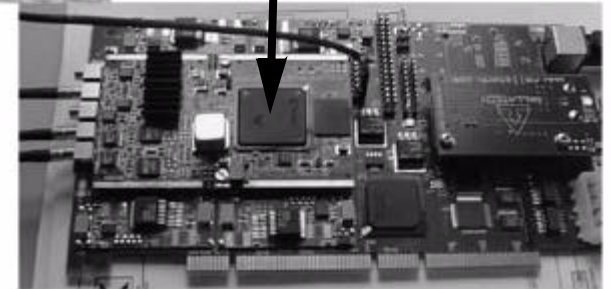
FPGA

RF_Controller - how it is tested now



Xilinx demo board
(with Virtex II XC2V3000)

Cavity simulator



Conclusion

- Mechanism of Lorentz force detuning well understood
- Successful demonstration of Lorentz force compensation for TESLA and SNS cavities
- Differences in coupling from Lorentz force and piezo to cavity detuning may result in suboptimal performance of compensation scheme
- Lifetime issue for piezo actuator requires careful design of piezo tuner
- Limited Feedback control of microphonics in multicell cavities appears potentially possible but requires sophisticated controller design.

