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Action and Phase Jump Analysis for LHC Orbits

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Action and phase

The method Requirements

The LHC in simulations

Lattice model Error Simulations

The LHC experimental orbits Data IR3

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The method				

Action and Phase

$$z(s) = \sqrt{2J_z\beta_z(s)}\sin(\psi_z(s) - \delta_z)$$
(1)

When a magnetic error θ_z is present at $s = s_{\theta}$, the trajectory of the particle can be described independently before and after the error:

• Before the error $(s < s_{\theta})$

$$z(s) = \sqrt{2J_0\beta_z(s)}\sin(\psi_z(s) - \delta_0)$$
(2)

• After the error $(s > s_{\theta})$

$$z(s) = \sqrt{2J_1\beta_z(s)}\sin(\psi_z(s) - \delta_1)$$
(3)

 J_0 and δ_0 are the action and phase before de error J_1 and δ_1 correspond to the action and phase after the error.

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With this equations, using the Courant–Snyder parameters to propagate the particle trajectory through the error (and after some algebra and trigonometric identities...)

We obtain the KICK magnitude as

$$\theta_z = \sqrt{\frac{2J_1 + 2J_0 - 4\sqrt{J_1J_0}\cos(\delta_1 - \delta_0)}{\beta(s_\theta)}} \tag{4}$$

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The kick θ_z could be generated by any the multiple components in the magnetic field multipole expansion.

$$\theta_{x} = B_{0} - B_{1}x(s_{\theta}) + A_{1}y(s_{\theta}) + 2A_{2}x(s_{\theta})y(s_{\theta}) + B_{2}[-x^{2}(s_{\theta}) + y^{2}(s_{\theta})] + \cdots$$
(5)
$$\theta_{y} = A_{0} + A_{1}x(s_{\theta}) + B_{1}y(s_{\theta}) + 2B_{2}x(s_{\theta})y(s_{\theta}) + A_{2}[x^{2}(s_{\theta}) - y^{2}(s_{\theta})] + \cdots$$
(6)

with $A_n = B' Ia_n / B\rho$ and $B_n = B' Ib_n / B\rho$

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Linear errors

For **dipolar errors**, no dependence with any of the transverse coordinates is expected.

$$\mathsf{B}_0 = \theta_z \tag{7}$$

For **quadrupolar errors**, linear dependency with the transverse coordinates is expected.

$$A_{1} = \frac{\theta_{x}y(s_{\theta}) + \theta_{y}x(s_{\theta})}{x^{2}(s_{\theta}) + y^{2}(s_{\theta})}$$

$$B_{1} = \frac{\theta_{y}y(s_{\theta}) - \theta_{x}x(s_{\theta})}{x^{2}(s_{\theta}) + y^{2}(s_{\theta})}$$
(8)
(9)

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Requirements				

Requirements

- BPMs readings
 - Two before the error (to calculate (J_0, δ_0))
 - Two after the error (to calculate (J_1, δ_1))
- The lattice model
 - ► To obtain the Courant–Snyder parameters of the accelerator
- Multiturn runs
 - To increase the precision in the polinomial fitting (quadrupolar and sextupolar errors mainly), it is better if the multiturn run is made with high oscilations

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The LHC



Images taken from [1] and [5]

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Error Simulations				

Error simulations

Dipolar and quadrupolar errors were included in the accelerator.

Orbits with the errors were obtained by simulations

- MAD-X V4.01
 - Experiments off
 - Period lhcb1
 - Lattice model V6.5
 - Energy 450[GeV] (injection)
 - Particle PROTON

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Error Simulations				



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Error Simulations				

Including noise



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Data				

Phase range selection

Phase average is calculated per orbit, then orbits with similar phase have aproximatelly same behaviour.



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IR3				

Analysing IR3



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IR3				

s coordinate selection



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IR3				
IR3				

Error



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Conclusions

- Simulations show that LHC linear magnetic errors could be recovered withing 1.53%
- Extension to sextupolar error has not been possible with this run
- Local error in IR3 has been identified
- Still some noise in the plots from the multiturn data. Noise could be reduced with data from multiple bunches
- ► IRs can be analysed independently
- Phase should be a continuum function (it might affect averages).

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The authors want to thank Rogelio Tomás García and his team at CERN for providing the LHC data, interesting discussions and suggestions for the analysis presented here.

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Thank you.

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Coordinate system

The coordinate system is the usual (x, y, s), used for periodic accelerators



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LHC lattice model



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LHC lattice model

- LHC lattice model V6.5 (for MAD-X)
 - Monitors (BPMs), to extract simulated orbits
 - Sextupole correctors on arcs are turned off
 - \blacktriangleright All elements are used to extract β and ψ functions

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BPMs averages



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Phase range selection



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