



**HELMHOLTZ
ZENTRUM BERLIN**
für Materialien und Energie

Automated Operation of the Metrology Light Source Electron Storage Ring

Thomas Birke

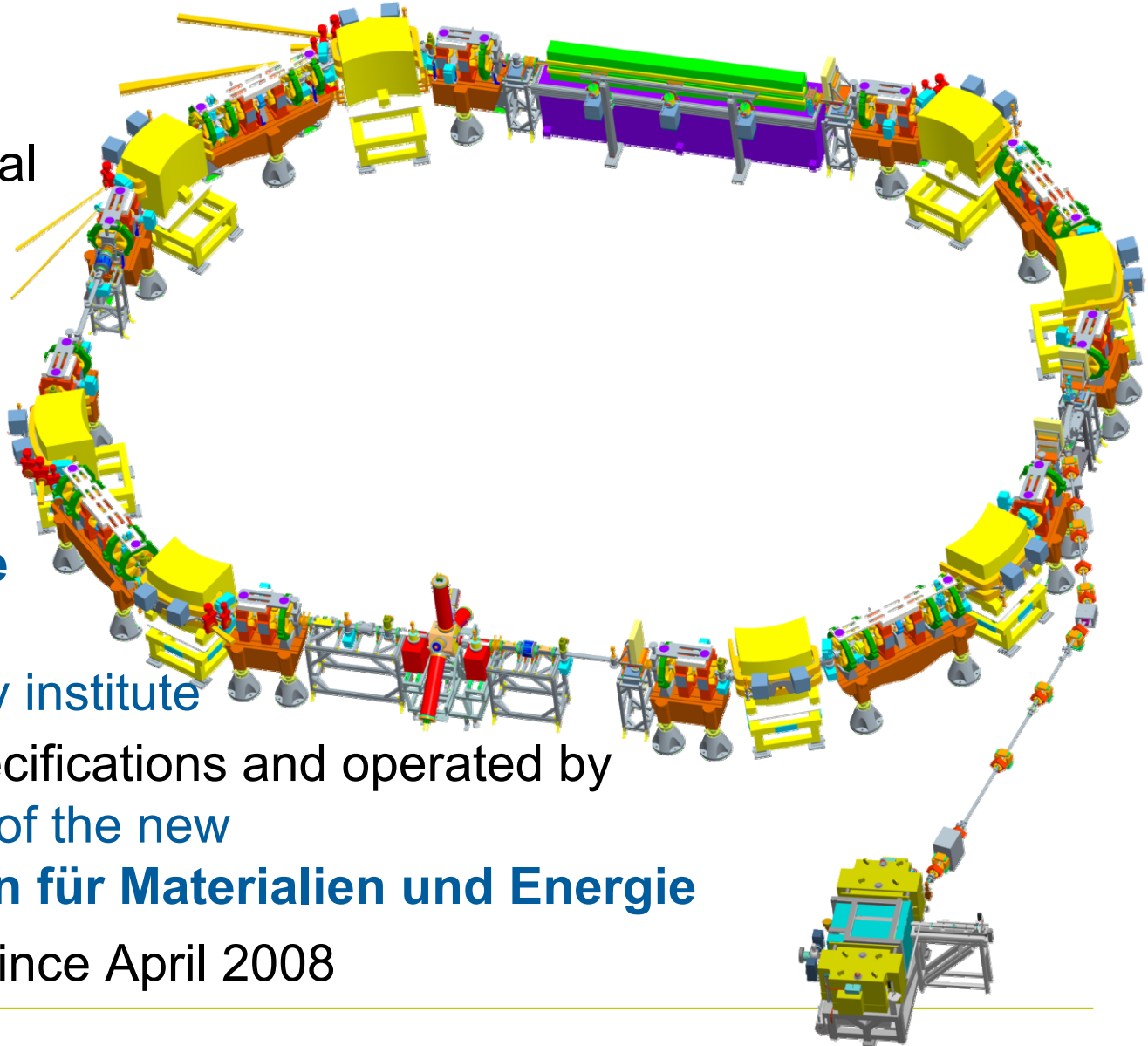
based on work of

T. Birke, M. Abo-Bakr, J. Feikes, B. Franksen, M. v. Hartrott, G. Wüstefeld

May 2009 – Particle Accelerator Conference '09 – Vancouver, BC, Canada

What is the Metrology Light Source (MLS)?

- Low energy e^- storage ring
- Metrology and technological developments in UV/XUV as well as IR and THz
- Optimized for generation of coherent SR in FIR/THz
- Owner:
Physikalisch-Technische Bundesanstalt (PTB)
German national metrology institute
- Built according to PTB specifications and operated by **BESSY** which is now part of the new **Helmholtz Zentrum Berlin für Materialien und Energie**
- In regular user operation since April 2008



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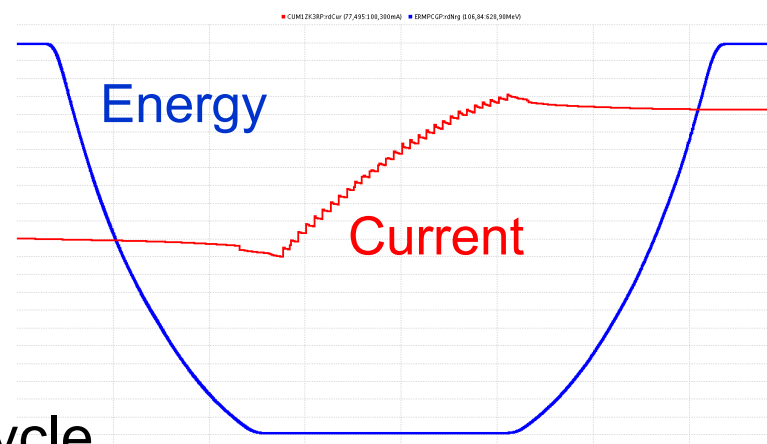
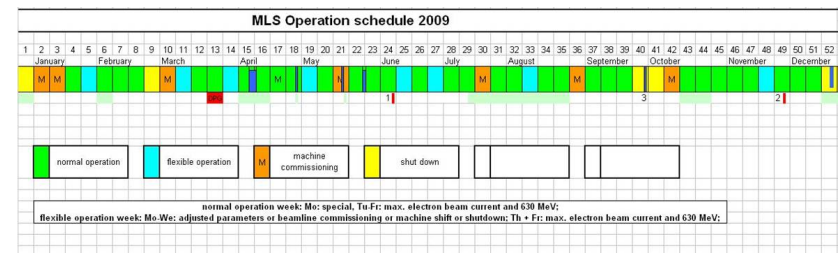
Machine and Operating Parameters	
Circumference	48 m
Revolution Time	160 ns
Injection Energy	105 MeV
Operational Energy	105 – 630 MeV
Beam Current	1pA – 200 mA
Values for momentum compaction factor α	$10^{-4} - 3 \times 10^{-2}$
Insertion Device	Electromagnetic Undulator 23 x 180mm

Operating the Metrology Light Source

- Wide range of operating modes and parameter settings
 - Current: **1 pA** (a single electron) up to **200 mA**
 - Energy: **105 MeV – 630 MeV**
 - Momentum compaction factor α : varies by factor of **~1000**
- Electromagnetic Undulator
 - strong **non-linear fields enforce compensation** with correction coils using **feed-forward system**
 - otherwise impossible to accumulate and store beam
- Injection setup differs from operation setup
 - Orbit bump
 - Asymmetric sextupole settings
 - RF frequency modified

Operating the Metrology Light Source

- Specialties require complex procedures
 - **Even on short notice**
- Setup changes often according to user demands
 - **Special procedure**
- Energy Ramp used as degaussing cycle
 - **But: Magnets not driven into full saturation**
 - Machine performance is very sensitive to magnet-setting-errors
- Optics change program to change momentum compaction factor
 - **Currently done manually – program is in development**

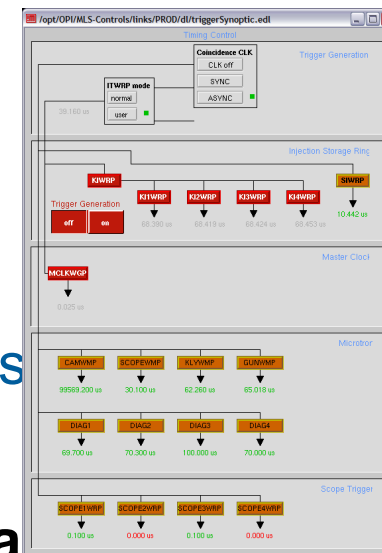
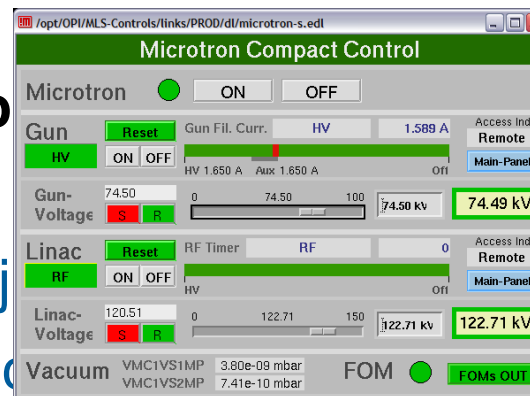


Operating the Metrology Light Source

- Several tasks to be performed by **operation personnel**
 - Inject up to desired current
 - Ramp energy – before and after injection as well as on user-demand
 - Change momentum compaction factor
 - All tasks require **several actions** and may require **sub-tasks**
 - Any **error** (esp. in magnet settings) may **strongly deteriorate** machine performance
- Operated by **BESSY/HZB** staff for **PTB**
 - Paid customer service
 - Deliver **high operational reliability** with minimum personnel effort
 - **High degree of automation required!**

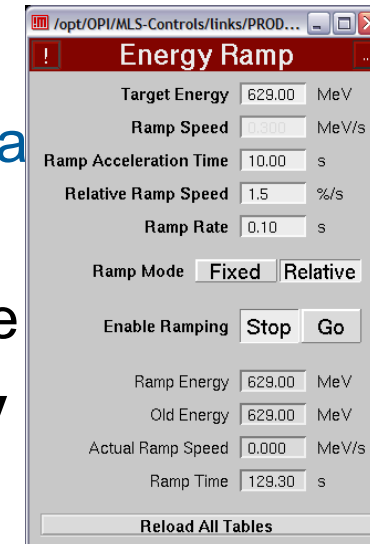
Operating the Metrology Light Source

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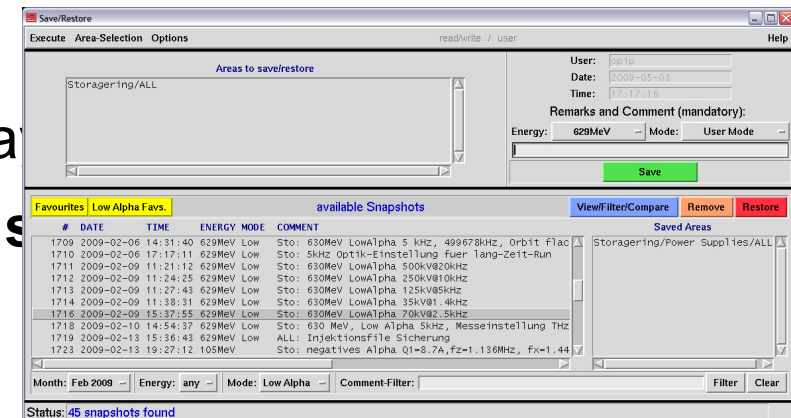
Operating the Metrology Light Source

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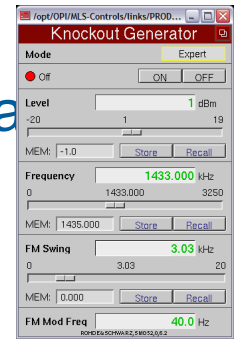
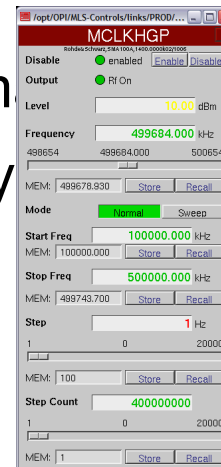
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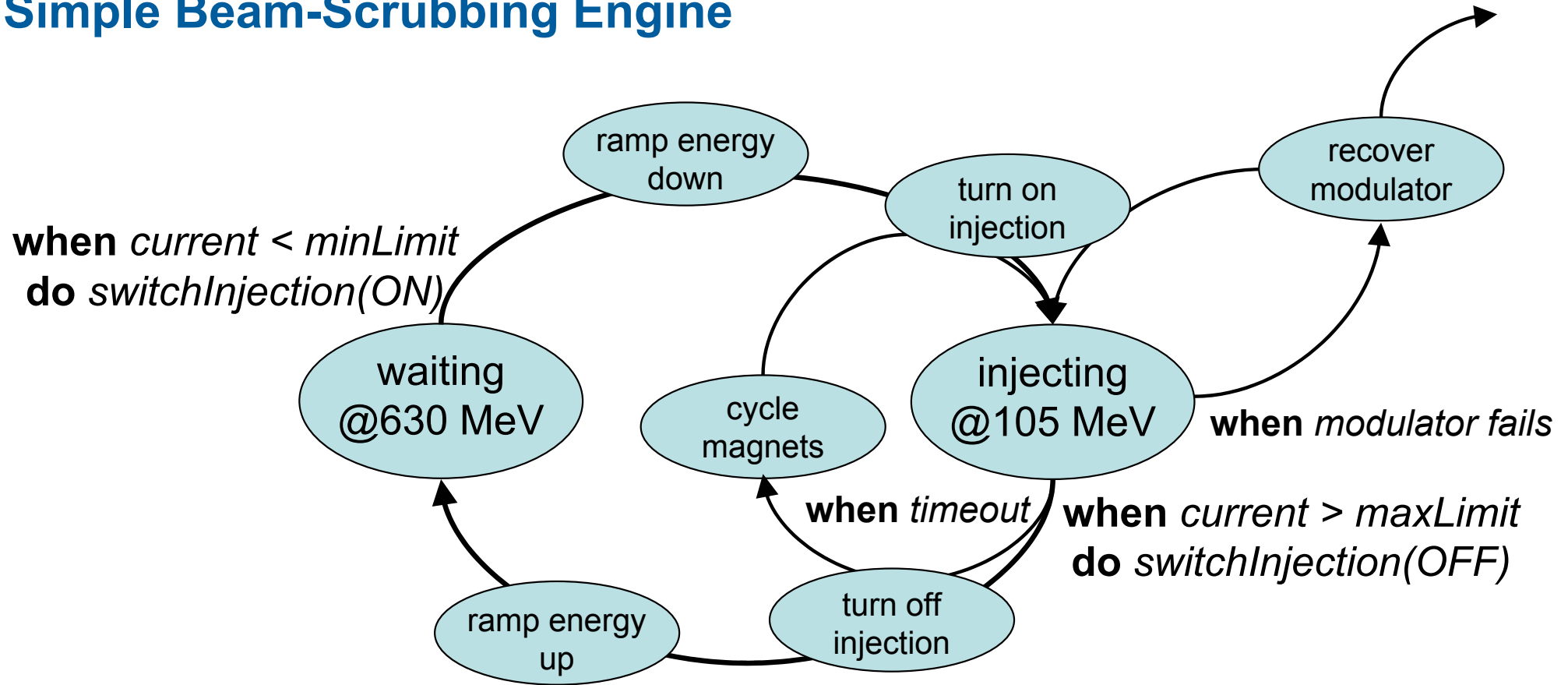
Software System

- Several localized sub-tasks already realized in separate applications
 - Energy Ramp
 - Optimizing microtron output
 - Momentum compaction factor – semi-automatic by restoring snapshots of magnet-settings and manually adjust the RF-Frequency
- *What* action to perform *how* and *when*? – Organized by operator
 - Expertise is in the heads – sometimes even documented
 - All signals needed for deciding what to do are available in control system (**EPICS** – Experimental Physics and Industrial Control System)
- Decided to develop one **central application** to coordinate necessary tasks
 - **Operation Master**
 - Software model: **State Machine**

Software System – Finite State Machine (FSM)

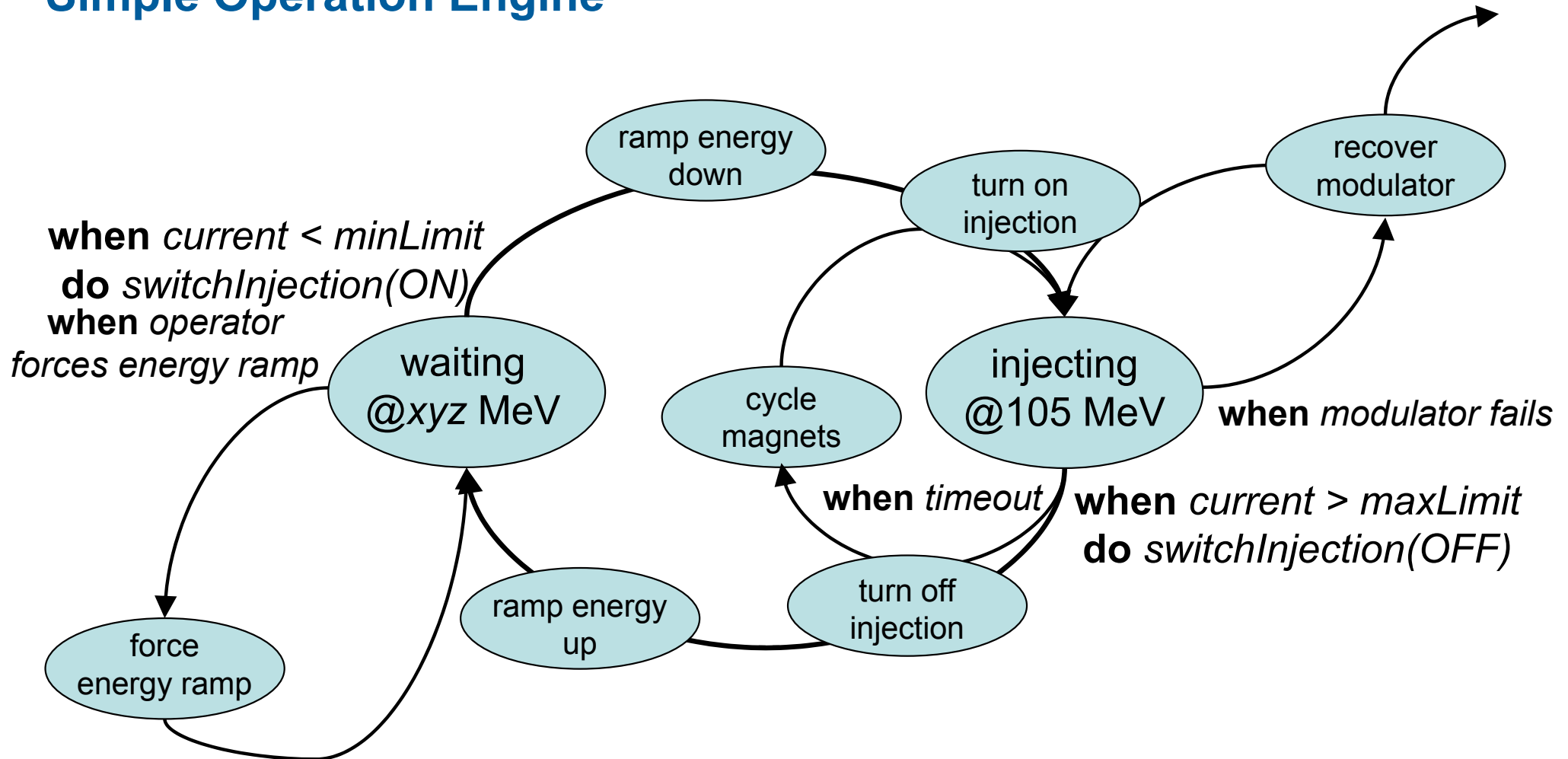
- Set of States of a described system
 - States describe all possible states of the machine
 - Active state resembles current machine-state
 - Software and machine are to be kept in sync
 - Transitions between these states
 - Well defined conditions force transitions into other states
 - All transitions/conditions of active state checked on every incoming event
 - Change of a control system process variable
 - Timeout
 - User interaction through graphical user interface
 - Actions may be performed when entering a state and/or on transition

Software System – Finite State Machine Simple Beam-Scrubbing Engine



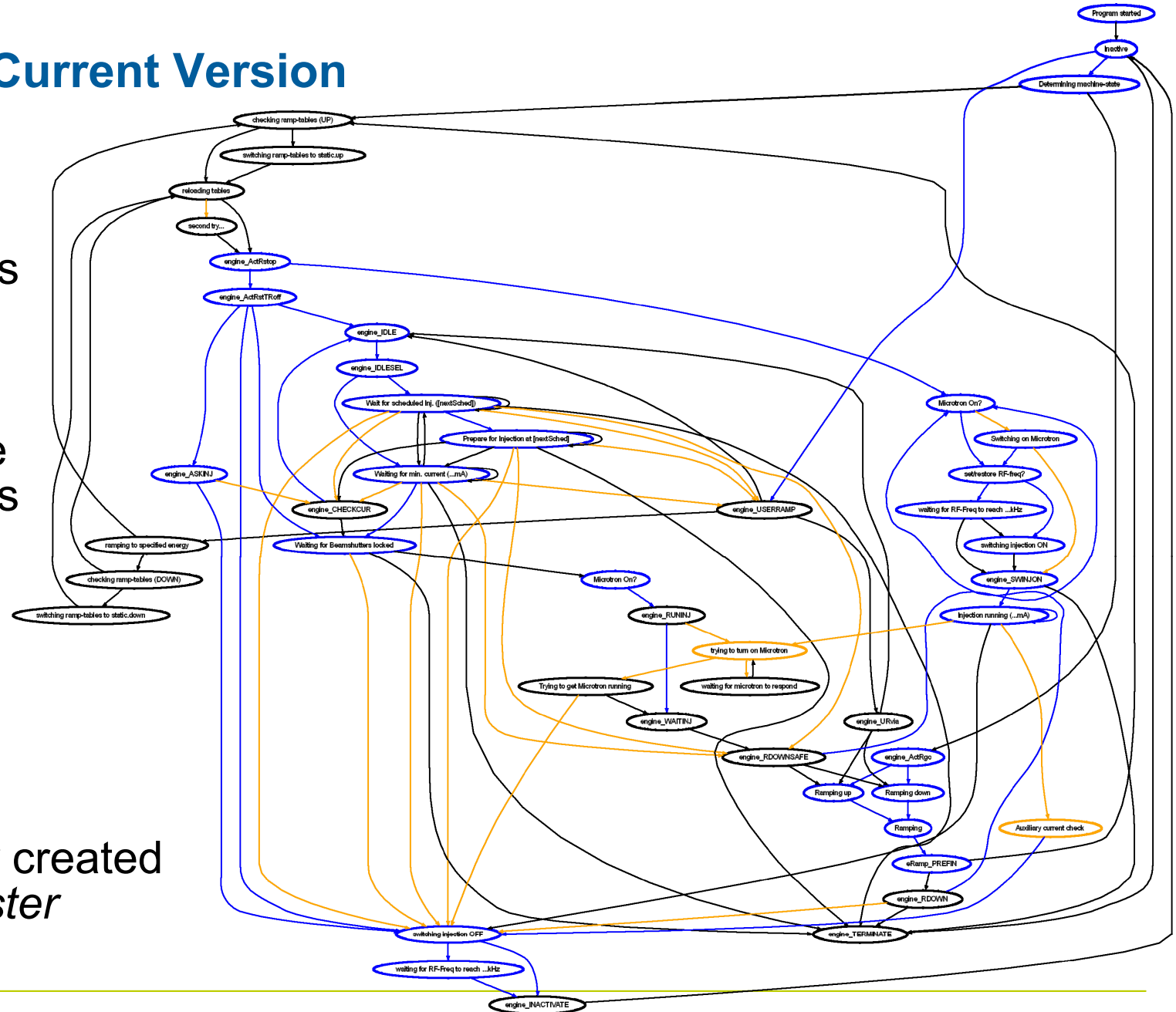
Software System – Finite State Machine

Simple Operation Engine



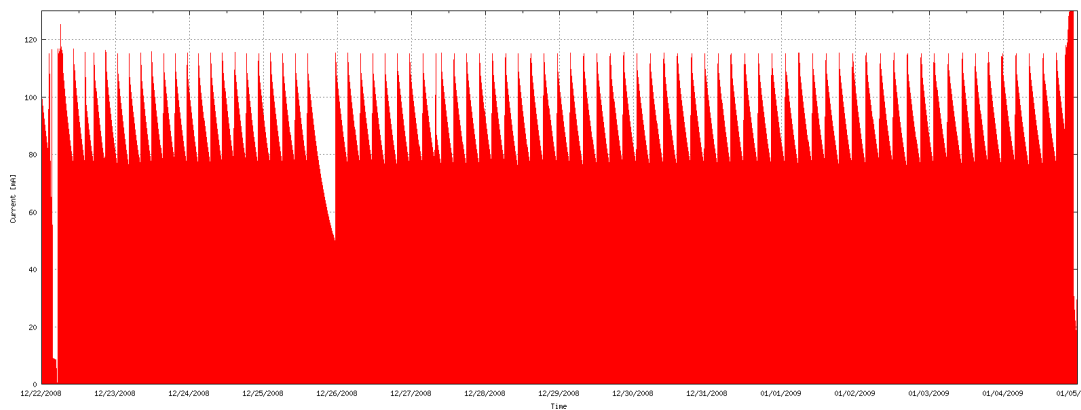
State Machine – Current Version

- **Blue**
 - in sequence states/transitions “expected”
- **Orange**
 - out of sequence states/transitions “unexpected”
- Image created by *GraphViz*
- Input to *GraphViz* created by *Operation Master*

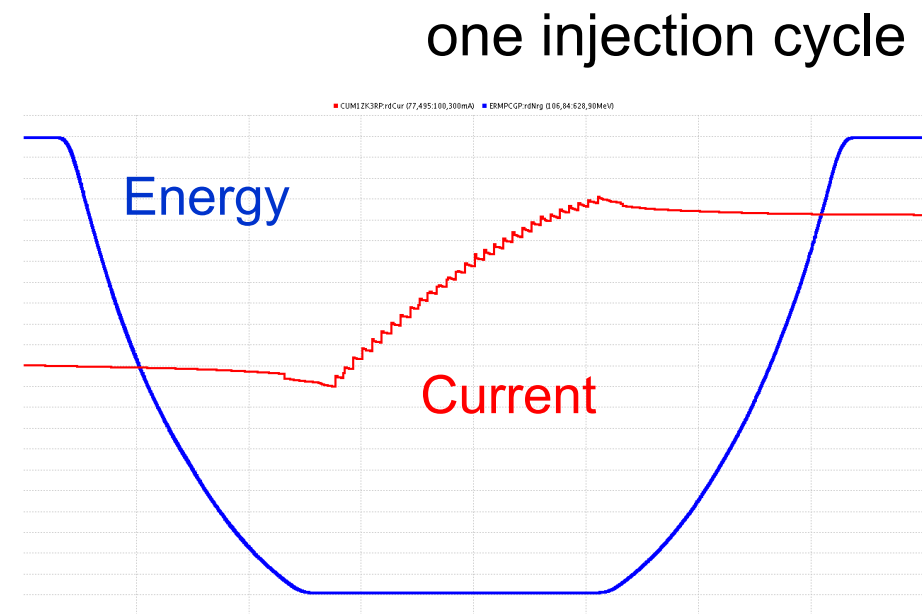


Operation Master – Successful Run

- Performed well for two unmanned weeks during holiday break 2008/2009
 - Just one unidentified problem with microtron modulator PLC
 - Manual intervention necessary
 - Action is now part of command sequence to recover from microtron errors



beamcurrent over two weeks



Operation Master – Development

- Whole system *not* developed by design according to full specification
 - **State Engine** – as generic as possible
 - **State Machine** – unspecified, very simple first version
- **Evolutionary** development process
 - **Experiences of commissioning and daily use** of application itself
 - Yet unhandled states only identified when using the application
 - Solutions to problems often roughly sketched → **refinement phase**
 - Clear view of solution often arises during discussions between developer and users/scientists → **close cooperation** drives development
 - Numerous **small development steps**
 - Some removed in favor of other solution or have proven obsolete during further commissioning

Operation Master – Implementation

- Current version written in **Tcl/Tk**
 - Proper choice for **rapid prototyping**
 - **Monolithic** application
 - State machine, state engine, graphical user interface (GUI)

MLS Operation Master (About)

Settings | Mode | Injection | Energy Ramp

Damping Time before Ramp Up: 0.1 s [set]

Target Energy to ramp up to: 450 MeV [set]

this Target Energy is used in "Beam Scrubbing" mode and also in "User Operation" mode if no "E-...MeV" is given in schedule

Ramp to specified Energy

previous ramp direction: **Down**
changing ramp direction will need to ramp through the end-point of the ramp in current ramp-direction (105MeV resp. 629MeV)

Force RF-voltage to be energy ramped

Cycle Magnets using Energy Ramp

Readbacks and Status

act. Current: **105.2140** mA

act. Energy: **470.2** MeV

Ramp-State: **Go** [↘]

Ramp-Tables: **static.down**

Injection/Trigger: **off**

RF-Freq: 499684.000 kHz

Ramping

Commands

Active! [Stop] [Standby] [Quit]

History

```

08:59:22 Target Current reached
08:59:22 Damping
08:59:22 switching injection OFF
08:59:22 Damping finished
08:59:22 Ramping up
08:59:22 tables reloaded
08:59:34 Ramping finished
08:59:35 Waiting for min. current (80mA)
08:59:53 Ramping Energy on Operator-Request
08:59:53 Ramping to 450 MeV
08:59:53 switching ramp-tables to static.down
08:59:56 tables reloaded
    
```

MLS Operation Master (About)

Settings

Mode | Injection | Energy Ramp

Beam Scrubbing | **User Operation**

Minimum Current: 80 mA [set]

Maximum Current: 110 mA [set]

Aux. Current (if Inj. timed out): 80 mA [set]

Force Injection now!

Readbacks and Status

act. Current: **109.4476** mA

act. Energy: **630.0** MeV

Ramp-State: **Stop**

Ramp-Tables: **static.up**

Injection/Trigger: **off**

RF-Freq: 499684.000 kHz

Waiting for min. current (80mA)

Commands

Active! [Stop] [Standby] [Quit]

History

```

08:52:54 change RF-Freq
08:52:55 waiting for RF-Freq to reach 499684kHz
08:53:10 switching injection ON
08:53:10 Injection running (110mA)
08:53:17 Target Current reached
08:53:17 Damping
08:53:17 switching injection OFF
08:53:17 Damping finished
08:53:17 Ramping up
08:53:17 tables reloaded
08:53:19 Ramping finished
08:53:19 Waiting for min. current (80mA)
    
```

be running at a time
on a single screen

Operation Master – Future

- *Operation Master* redesigned and **new implementation** in progress
- **Headless server** process
- State machine and state engine only
- Written in **Python** programming language
- All interaction using **control system process variables**
- **Remote-control** from other application

- Use of **standard control system tools** (EPICS-Toolkit) for
- **Display** – graphical display manager can be run on **any screen**
- EPICS Channel Access Security used to control permissions
- **Alarm monitoring** and **logging** – operator notification and analysis
- **Archiving** – for later analysis and debugging

Conclusion

- *Operation Master*: **indispensable operator instrument** since day one
- **Minimizes errors** by performing complex command sequences
- Implements **standard mechanisms** to set up certain states as well as to recover from failure situations
- Will be **extended** to cover all **future tasks** at MLS as well

Experiences and success encourage using the same system for existing as well as future projects at BESSY/HZB