

that can be calculated with the Slater formula [2]. An accurate approximation of such shift can be given by simply determining the corresponding variation of the, mean aperture R_0 , of the pole tip radius ρ and of the of the upper wall height with respect to beam axis H , with the relationship

$$\delta f = \alpha_{R_0} \delta R_0 + \alpha_\rho \delta \rho + \alpha_H \delta H \quad (1)$$

In general α_{R_0} , α_ρ , α_H are different for each RFQ module, In the following table their values for the initial and final RFQ cells are reported.

Table 1: The α_{R_0} , α_ρ , α_H coefficients

Module	α_{R_0} [MHz/mm]	α_ρ [MHz/mm]	α_H [MHz/mm]
1 to 6	11.3	-5.3	-1.2
13 to 18	7.6	-4.1	-0.9

The cooling channels are optimized so to minimize the cut off frequency shift between RF on and RF off, at the beginning and at the end of the cooling channel (water inlet and outlet). Moreover, by keeping cold the vanes channel and varying the vessel channels temperature the necessary cooling range is obtained.

3D SIMULATIONS

Due to the fact that transverse and longitudinal dimension of the modules are comparable, 3D simulations were necessary to evaluate the effects of the following details on the entire modules, as in Figure.4:

- The holes for tuners and for vacuum port;
- Presence of steel flanges;

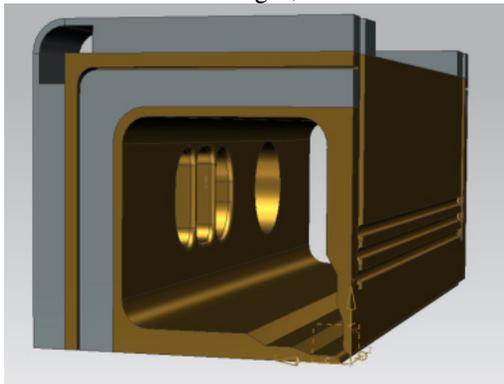


Figure 4: Layout of the module 16.

Three dimensional integrated fluid-thermal-structural simulations were performed in order to take into account directly and to calculate accurately heat exchange between cooling fluid and the module.

First of all, since a single manifold that feeds all the vane cooling ducts was considered, simple fluid dynamics simulations were performed to dimension it for the last supermodule. In fact, due to the relatively short length of each mechanical module, a different arrangement would have led to predominant 3D effects, without any effective gain in cooling efficiency. At this point the goal was to dimension the diameter of the manifold and of the ducts in order to divide the flow as more uniformly as possible.

Next step was the integrated thermal structural fluid dynamics analyses, thus calculating the deformation of the entire module, as in Figures 5 and 6. The temperature on the pole tip is mostly uniform and its deformation is in a range of 10 μm .

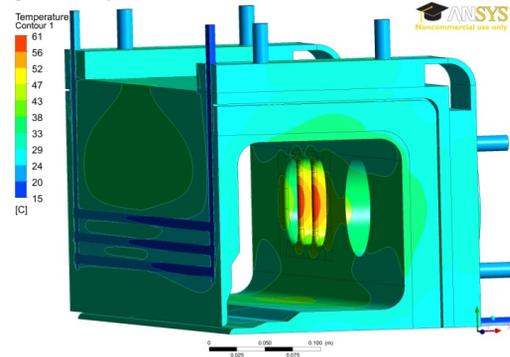


Figure 5: Temperature on 3D module 13 for an input water temperature of 15 °C for vane and 22 °C vessel cooling ducts.

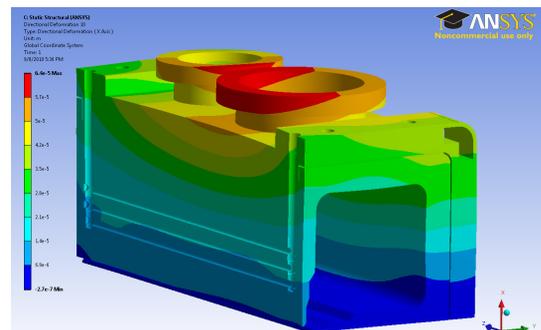


Figure 6: 3D y-deformation on module 13 for an input water temperature of 15 °C for vane and 22 °C vessel cooling ducts.

As for 2D analyses, power loads were derived from SUPERFISH calculations and 3D details (i.e. tuner holes and vacuum grids) were simulated with Ansoft HFSS [3]. Then the calculation of the frequency shift was possible by using Equation (1) the entire length of the modules.

Since the whole RFQ has to be tuned for a range of ± 100 kHz, each cooling module has to guarantee that range. It was necessary to merge the simulations of each of these modules, for example by taking the output temperatures of the channels of module 13 as the input temperatures of module 14 and so on.

The pattern of the TE_{21} cut-off frequency shift due to the above-mentioned deformation is shown in Figure 7.

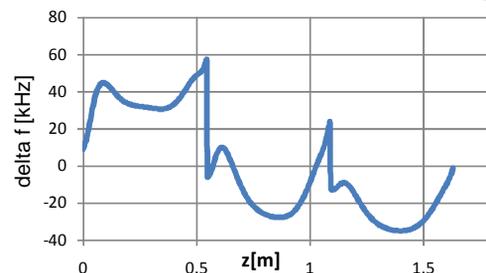


Figure 7: Frequency perturbation on modules 13, 14 and 15 for the tuned case, i.e. $T_v=15$ °C and $T_f=22$ °C.

The effect of such frequency perturbation on the voltage uniformity can be calculated with a perturbation approach [4] and it results being negligible respect to the $\pm 2\%$ specifications driven by beam dynamics (Figure 8). This effect was calculated by assuming a constant section RFQ and by replicating the profile of Figure 6 on all the 6 cooling modules.

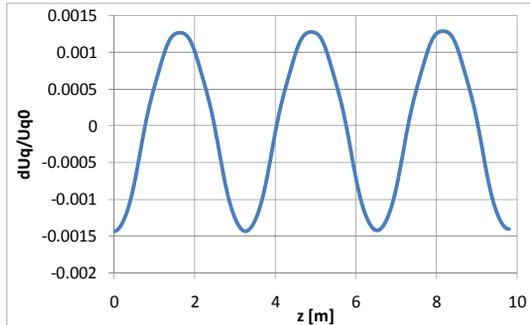


Figure 8: the voltage perturbation during high power operation.

A comparison of 2D and 3D thermo-structural simulation results has been made, in order to check the validity of the 2D initial design considerations.

For the module 13 the agreement is quite good, at low temperatures in the vessel, but at high temperature on the vessel the difference is a bit larger, 40 kHz. In the 3D case a range of ± 100 kHz is guaranteed.

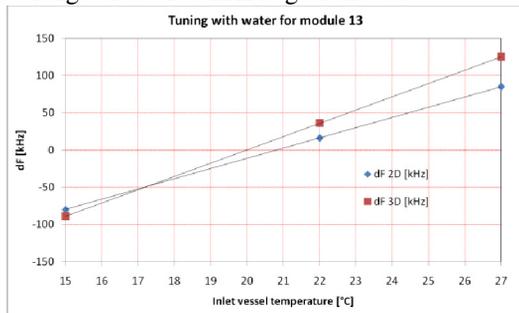


Figure 9: Frequency range on module 13, for a vane temperature of 15 °C as function of vessel temperature.

EXPERIMENTAL RESULTS

An experimental setup, using an EDM copper vane of the mechanical prototype [1], has been made to check:

- The heat exchange coefficients of ducts;
- The validity of ANSYS-CFX thermal-fluid simulations;
- The water pressure drops on the ducts.

The apparatus was composed of the copper piece, heat resistors of able to produce a heat flux of about 4 W/cm² on vane surfaces, a cooling water circuit and an infrared thermal camera, Figure 10. A mass flow of about 21 l/min with a average temperature of 15 °C was pumped in the vane cooling ducts.

The experimental heat exchange obtained was 11500 W/m²K, and it was used in the simulation of the RFQ cooling channel [1]. A similar result has been obtained

with CFX analyses. Because of different values of emissivity on the component, the actual temperature was measured in particular zones, Figure 11. The temperature distribution calculated with CFX is reported in Figure 12. The accordance between experimental results with calculated ones is discrete, as in Figure 13. The water pressure drop confirmed the expected value of about 0.26 bar.

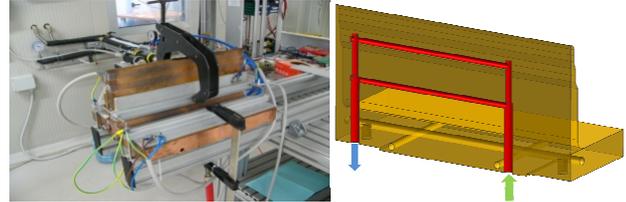


Figure 10: Layout of the cooling test system.

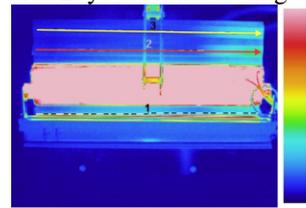


Figure 11: Infrared measured temperature distribution.

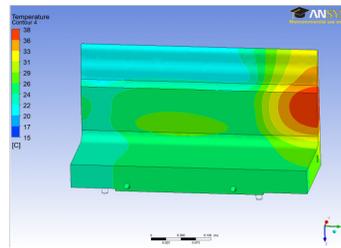


Figure 12: CFX thermal map [°C].

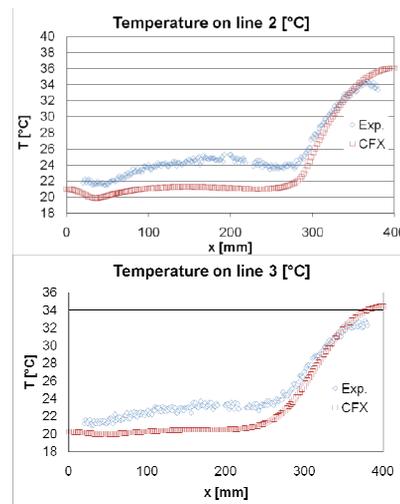


Figure 13: Temperature along the vane, from experimental and CFX simulation.

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