

Advanced methods & concepts for very high intensity beams

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Only in the sense of comparison: Beam A intensity is higher than Beam B intensity Only makes sense if <u>higher</u> intensity → <u>higher</u> issues to face





Classically: assimilation to high power



This graph is highly reductive:

Only last section, no upstream sections

- Each energy range ↔ specific acceleration-focussing technologies Source, LEBT, RFQ, DTL, CCL, SC-HWR, Spoke cav, Elliptical cav
- Challenges are not comparable at very different energies
- Challenging last section doesn't mean challenging upstream sections

• No space charge

- need of strong focusing
- non-linearities
- emittance growth
- halo creation
- sudden losses



Beam analysis (2)

<u>Advanced analysis:</u> Beam power & Space charge along the accelerator (average & peak intensity, start & final energy)

<u>Beam power</u> issues
 Only last section: B, A, C
 For a given section: A, B, C

• <u>Space charge</u> issues Only first section: C, A, B For a given section: A, C, B

Direct comparison between accelerators for a same acceleration component ⇒ challenging or not ⇒ adjust section start/end could help ⇒ see effects of combination of

high power & space charge





Beam analysis (3)

Examples of accelerators achieved or under construction or planned



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- 1. New idea for: Beam analysis
- 2. New protocol for: Beam loss prediction
- 3. New method for: Beam optimization
- 4. New strategy for: Beam measurement
- 5. New concept for: Beam characterization



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High power → even a tiny part of the beam, when lost, can take away a significant power

• Accidental loss \rightarrow brutal heat deposition \rightarrow damage equipment

 Permanent loss → activate materials → harmful radiations for personnel → cryogenic systems must be able to cool down Hands-on maintenance requirement: Losses << 1W/m MW beam → well less than 1 particle lost over 10⁶ is tolerated !! → microlosses

High intensity → High power on almost the whole accelerator → Carreful and exhaustive prediction of losses all along the accelerator is needed



Double issue:

- Define exhaustively all the loss situations in the accelerator lifetime
- Define the protocols to simulate and estimate them

Loss situations and protocols:

(Laser Part. Beams (2014), 32, 461-469)

- A. Ideal machine: nominal theoretical conditions, without any error
- B. <u>Starting from scratch</u>: errors as tolerances, not corrected, tunable param.±10%
- C. <u>Commissioning, tuning, exploration</u>: same as above but errors corrected
- D. Routine operation: errors corrected, tunable param. nominal
- E. <u>Sudden failure</u>: individual or combination of sudden trips of tunable param. from 100% up to 110%, or down to 0%.

→ CATALOGUE of LOSSES:

affects all the subsystems: hot points, beam stop system velocity, limitations for control system, maximum beam power for operation, dynamic range of diagnostics, etc.



Example: CATALOGUE of LOSSES for the IFMIF Prototype accelerator

Laser Part. Beams (2014), 32, 461-469





Beam loss power in case of sudden failure of the second LEBT solenoid



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What are the parameters to be optimized ?

Classically:

Global parameter: rms Emittance Minimize emittance growth Emittance matching Halo may be indirectly minimized

Emittance : figure of merit

But: MW beam → microlosses 10⁻⁶ of the beam must be avoided → very external part → halo

Advanced:

Extension of the outermost particles Minimize directly the halo Halo matching Maximize margin between beam border and pipe wall

Halo: figure of merit

Results: comfortable margin between beam external border and beam pipe wall



Beam Optimization (2)

Example: IFMIF SRF Linac

(Laser Part. Beams 32, 10-118, 2014)





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10 12

z (m)

14

16 18

0

2

4

6 8

20

22



Example: IFMIF SRF Linac





Advanced: Halo matching





Beam Optimization (4)

Issue: The beam must be optimised to an accuracy of <u>10⁻⁶</u>
 But simulations are not reliable to that accuracy components are not reproducible to that accuracy
 → Frequent in-situ fine tunings are mandatory

-)STRATEGY: SELF-RULE

Perform only Beam Dynamics optimizations that could be reproduced in-situ on the real machine with the appropriate Beam Diagnostics in sufficient quantities



In other words:

Each <u>BDyn tuning procedure</u> <u>MUST</u> have its <u>in-situ Avatar</u> on the machine





Beam Optimization (5)

Examples of beam matching ...

... to the RFQ <u>Optimization</u> Not to fulfill theor.Twiss param. But to maximize RFQ transmission

Diagnostic Current measurements at RFQ entrance and exit ... to the SRF Linac

Optimization Not to minimize RMS envelope, emittance But to minimize micro-losses

Diagnostic Micro-loss measurements the closest to solenoid vacuum chamber

Rev. Sci. Instru. 83, 02B320, 2012

Proc. of PAC. Vancouver, BC, Canada, 2009

Enough independent diagnostics: at least the same number as that of available tuneable parameters



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Classically: A lot of measurements, no need of sorting, classification

Advanced: clearly distinguish between

ESSENTIAL measurements

- for commissioning & tuning & operating the accelerator
- in order to meet required specifications of current and losses
- direct impact on the achievement of accelerator specifications
- available for everyday beam tuning at full power, non interceptive
- beam position, beam phase, current, losses, micro-losses



CHARACTERIZATION measurements

- for beam commissioning or beam study or beam dynamics understanding
- could be measurements during beam commissioning only, if lack of room
- could be interceptive devices for low duty cycle, if pb of power deposition
- transverse profile, emittance, halo, energy spread,
- mean energy, bunch length



<u>Characterization</u>: Knowledge, Understanding, Surveillance



Definition of the complete beam diagnostic system



Example of essential diag: Microloss monitors for IFMIF

Best µLM: CVD diamond (Proc. of DIPAC11, Hamburg, Germany) Best correction: PSO (Part. Swarm Opt.) algorithm (Proc. of PAC09, Vancouver, Canada) \Rightarrow Ideally as many μ LM as foc. elements upstream (one-to-one correspondence) \Rightarrow Located at foc.elements where loss probability is the highest, and the closest to the beam to allow locating losses 25 mm m 10^{-1} 20 Beam Density 10-2 Radius (mm) 1 macroparticle over 10⁶ 10^{-4} 10^{-5} 2 20 22 24 4 6 8 10 12 14 16 18 z (m) Performances: resolution 1/10 of maximum allowed losses



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Beam Characterization (1)





Example: IFMIF SRF Linac



(Laser Part. Beams 32, 10-118, 2014)



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Beam Characterization (2)



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Advanced:

1) Massive simulations with the actual number of particles

- 5 10⁹ particles (125 mA) for IFMIF-LIPAc (WEPOY032, IPAC'16)
- \rightarrow 175 processors for 25 days
- → confirm losses < 10⁻⁷
- → representative statistics of microlosses

2) Characterize the beam by its projections onto a few axes

MENT method: reconstruct a distribution from its projections (MOPOR032, IPAC'16)



2 projections

3) Characterize the beam by its core and halo separately

Loose fine details but gain more insight into the physics of the beam

6 projections

Actual distribution



We propose: Core-Halo limit based on the beam internal dynamics Appl. Phys. Lett. 104, 074109, 2014



Extreme case:

Core: uniform, sc force strictly linear Halo: tenuous, sc force nonlinear → core-halo limit: very steep (infinite) variation of the slope



<u>General case:</u>

Continuously varying density Core-Halo limit: steepest variation of the slope $\rightarrow \max \text{ of 2nd derivative}$

→ Core & Halo are submitted to two different space charge force regimes

Phys. Plasmas 22, 083115, 2015: This core-halo limit = good indicator of beam internal dynamics



Beam Characterization (6)

Example: Beam along the IFMIF prototype accelerator





Beam Characterization (8)

Example: Beam along the IFMIF Prototype accelerator





Beam Characterization (10)

MOPWA010, IPAC'15: Extension to 2D

"Wheel algorithm": Max of second derivative along many sections

➡ Core-Halo limit contour

➡ PHS, PHP

⇒ Emittance \mathcal{E} and Twiss parameters α , β , γ of the core and the halo separately

THPMR014, IPAC'16:

This Core-Halo limit contour is <u>consistent</u> with the well-established halo formation dynamics





Beam Characterization (11)

Classically





Advanced



For the five purposes of: Beam analysis, beam loss prediction, beam optimization beam diagnostic and beam characterization

Laser Part. Beams 32, 639-649, 2014