



# Tests of Low Emittance Tuning techniques at SLS and DAΦNE

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# Low emittance: requirements for SuperB

SuperB e<sup>+</sup>e<sup>-</sup> collider luminosity is:

$$\mathcal{L} \simeq 10^{36} \text{ cm}^{-2} \text{ s}^{-1}$$

This requires very low emittances for both rings:

**LER e<sup>-</sup>**

$$\epsilon_x = 2.5 \text{ nmrad}$$

$$\epsilon_y = 6.2 \text{ pmrad}$$

**HER e<sup>+</sup>**

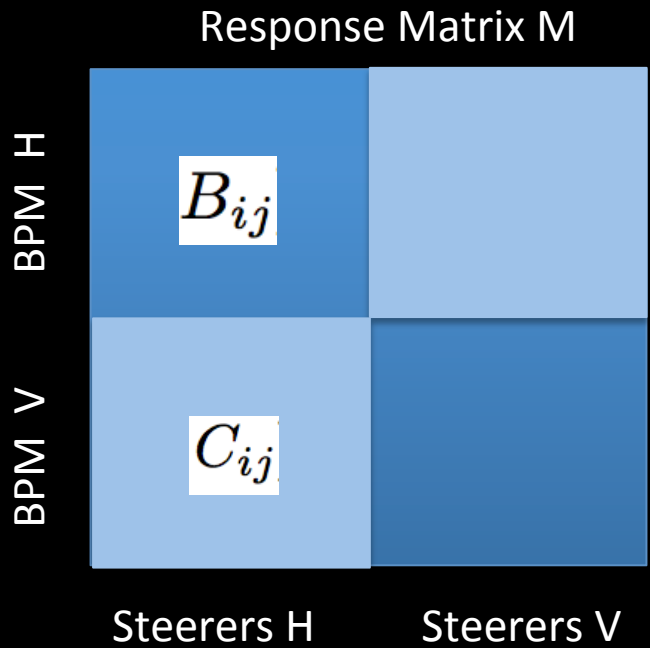
$$\epsilon_x = 2 \text{ nmrad}$$

$$\epsilon_y = 5 \text{ pmrad}$$

Within the reach  
of 3<sup>rd</sup> generation  
light sources

Low Emittance Tuning (LET) Algorithm

# Response matrix



Orbit correction

$$\vec{x} = M\vec{\theta}$$

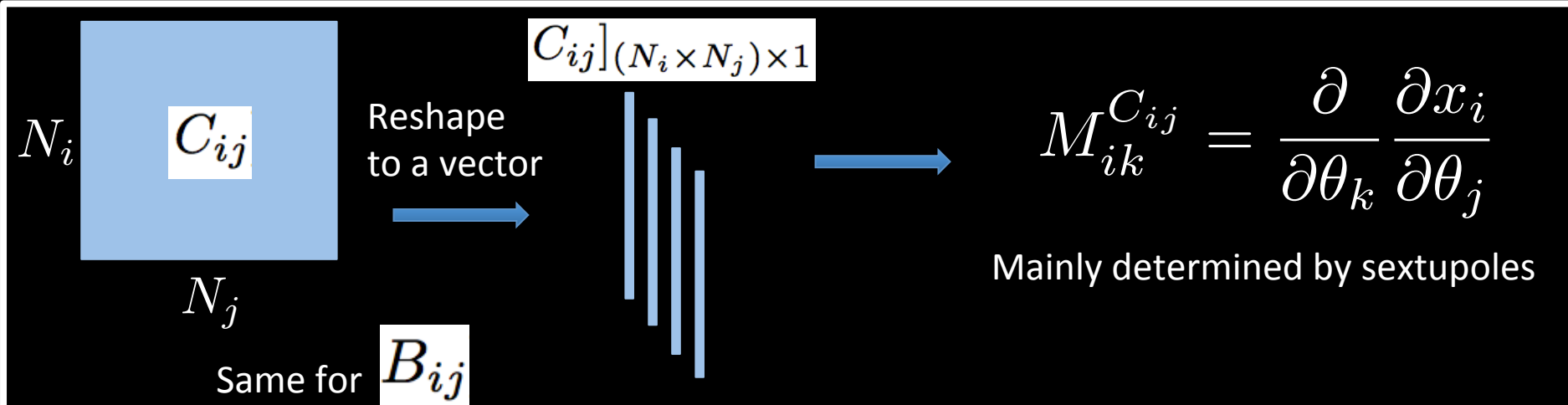
$$M_{ij} = \frac{\partial x_i}{\partial \theta_j}$$

Dispersion response matrix  
(deviation from reference)

$$\vec{\eta} = M^{disp}\vec{\theta}$$

$$M_{ij}^{disp} = \frac{\partial \eta_i}{\partial \theta_j}$$

SVD of M to calculate Correction  $\vec{\theta}$



# Low Emittance Tuning Technique

$$\begin{pmatrix} (1 - \alpha - \omega) \vec{y} \\ \alpha \vec{\eta}_y \\ \omega C_{ij}]_{(N_i \times N_j) \times 1} \end{pmatrix} = \mathcal{M}_v \begin{pmatrix} \vec{\theta}_V \\ \vec{K} \\ \vec{T} \end{pmatrix}$$

$$\begin{pmatrix} (1 - \alpha - \omega) \vec{x} \\ \alpha \vec{\eta}_x \\ \omega B_{ij}]_{(N_i \times N_j) \times 1} \end{pmatrix} = \mathcal{M}_h \begin{pmatrix} \vec{\theta}_H \\ \vec{T} \end{pmatrix}$$

- CORRECTORS USED**
- V steerers
  - Skew quad gradients
  - Bpm Roll (Gains in progress)
  - H Steerers
  - Bpm Roll

$N_j$  may be only 1 corrector

$C_{ij}]_{(N_i \times N_j) \times 1}$

Deviation from reference off diagonal block of the ORM reshaped to be a vector

$B_{ij}]_{(N_i \times N_j) \times 1}$

Deviation from reference diagonal block of the ORM reshaped to be a vector

Off axis orbit in quadrupoles and sextupoles used as correctors

- Matrix M simulated from Model without errors
- **SVD** inversion for simultaneous minimization of dispersion coupling and  $\beta$ -beating

# Measurements at Diamond (UK)

Diamond aerial view



Diamond is a third generation light source open for users since January 2007

100 MeV LINAC; 3 GeV Booster; 3 GeV storage ring

2.7 nm emittance – 300 mA – 18 beamlines in operation (10 in-vacuum small gap IDs)

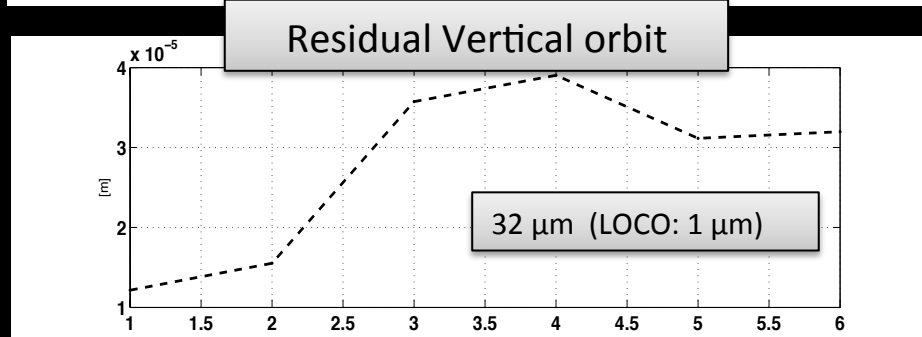
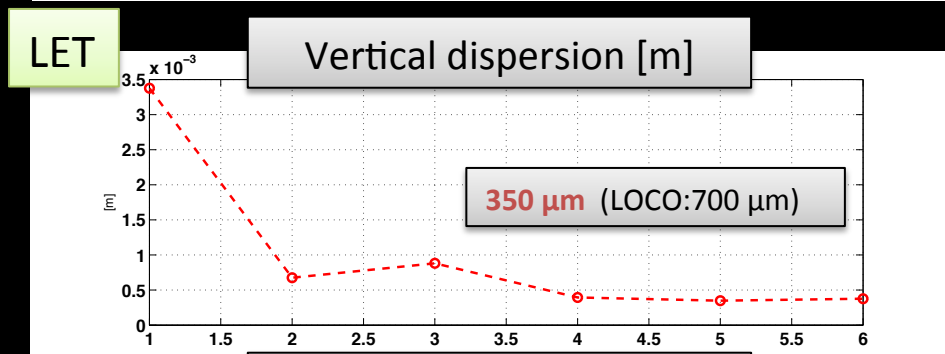
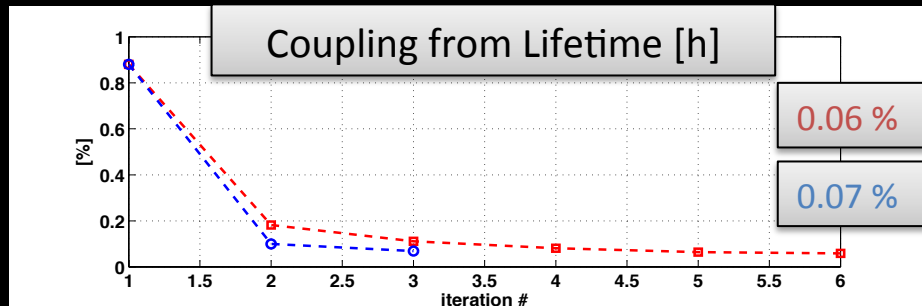
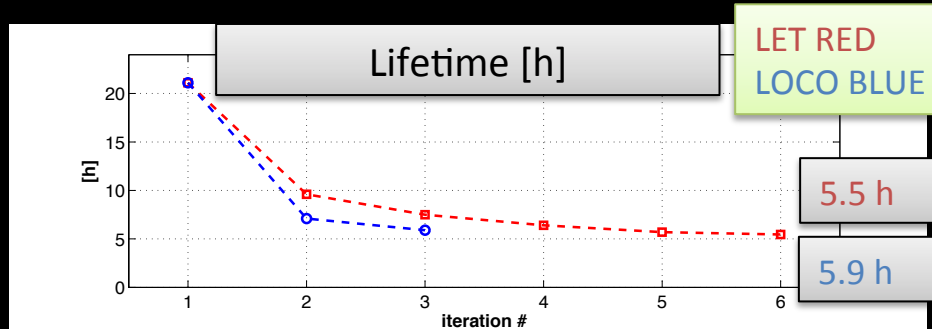
Courtesy R.Bartolini

Skew quadrupole Correctors only

Coupling estimated from lifetime:

$$K_{end} = \frac{\tau_{end}^2}{\tau_{initial}^2} K_{initial} = 0.06\%$$

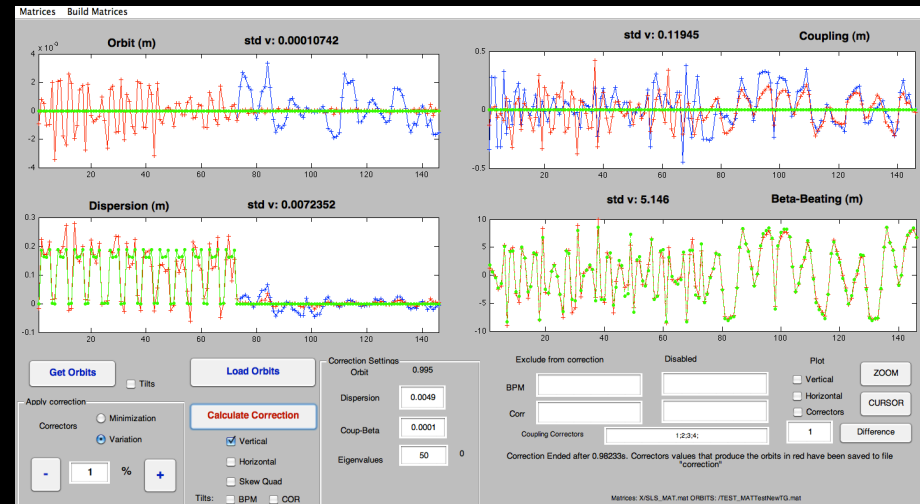
$$\epsilon_y = 1.7 \cdot 10^{-12} \text{ m rad}$$



# Measurements at SLS

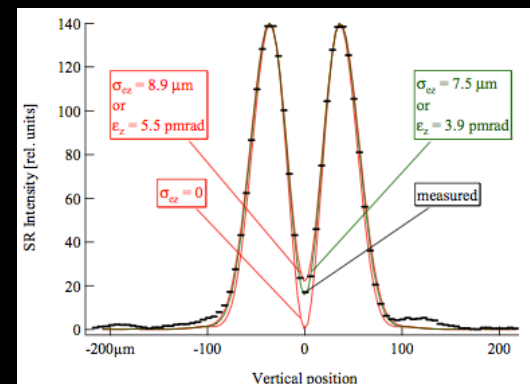
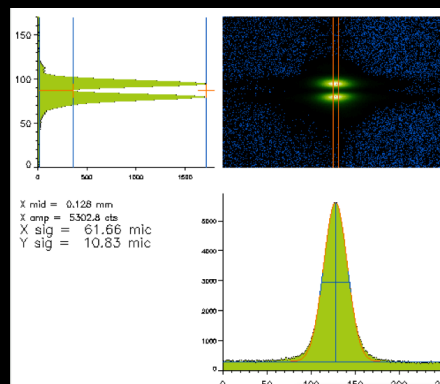
Measurements aimed to achieve low vertical emittance in the TIARA framework

SWISS LIGHT SOURCE  
2.411 GeV, 288m, 12 beamlines, 400 mA, 5.4 nm Hor. Emit.



Same Tool used for Diamond, modified for direct access to Control System

Vertical beam size measurements performed using vertically polarized Synchrotron Light Monitor



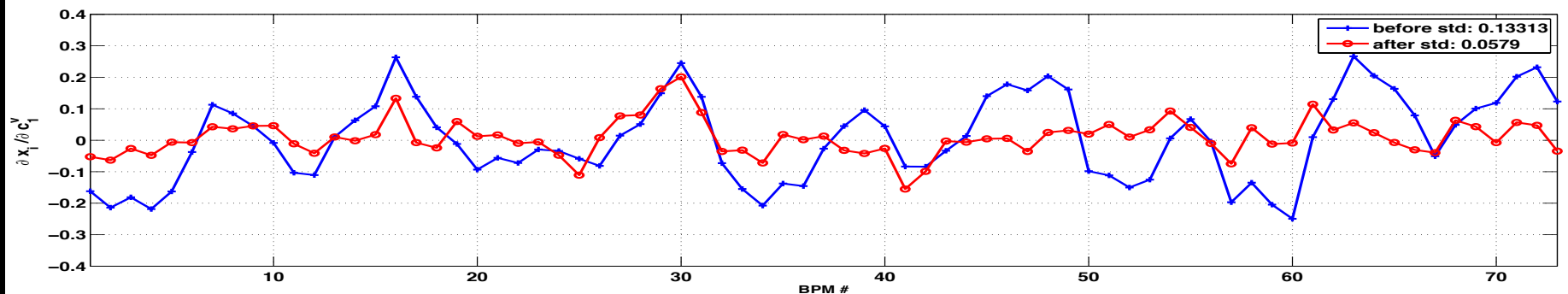
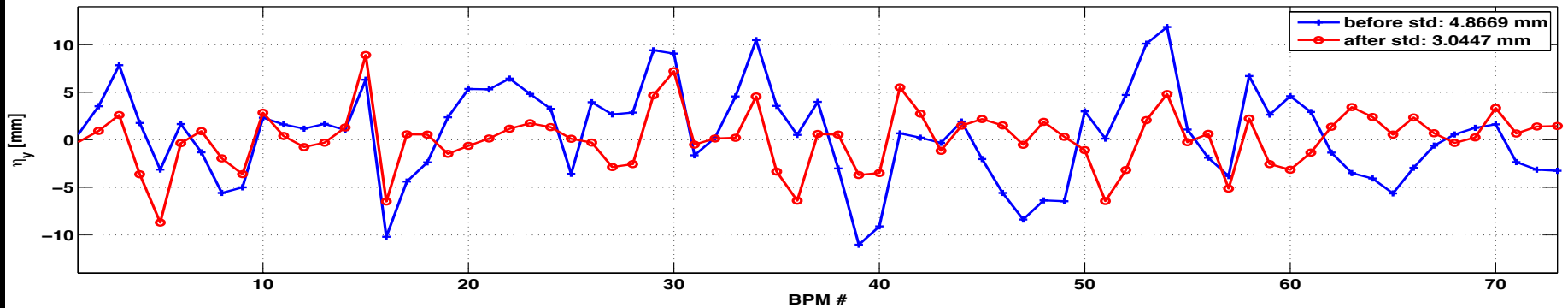
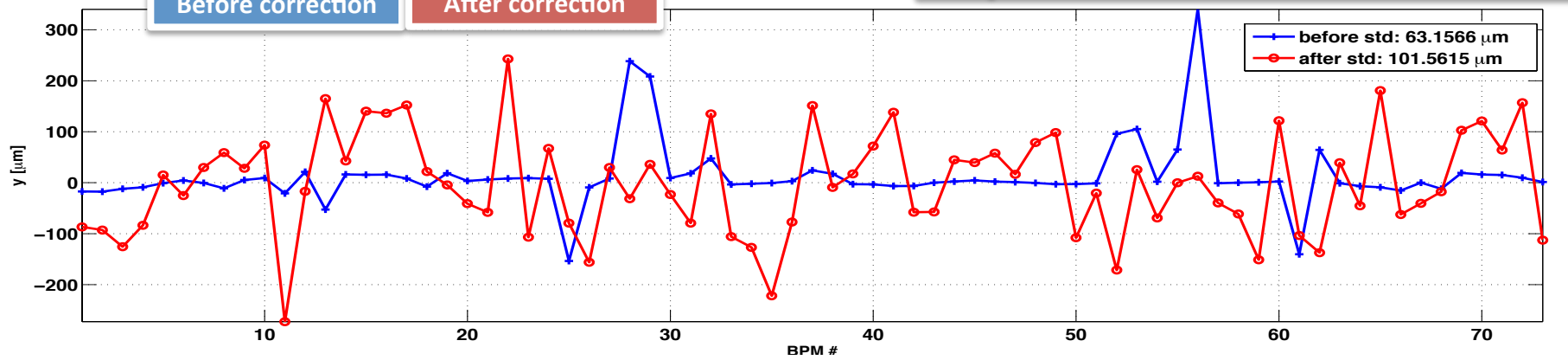
TUPB27 Proceedings of DIPAC 2007, Venice, Italy

# SLS measurements

Vertical steerers only  
 $\sigma_y$  from 16  $\mu\text{m}$  to 7  $\mu\text{m}$

Before correction

After correction

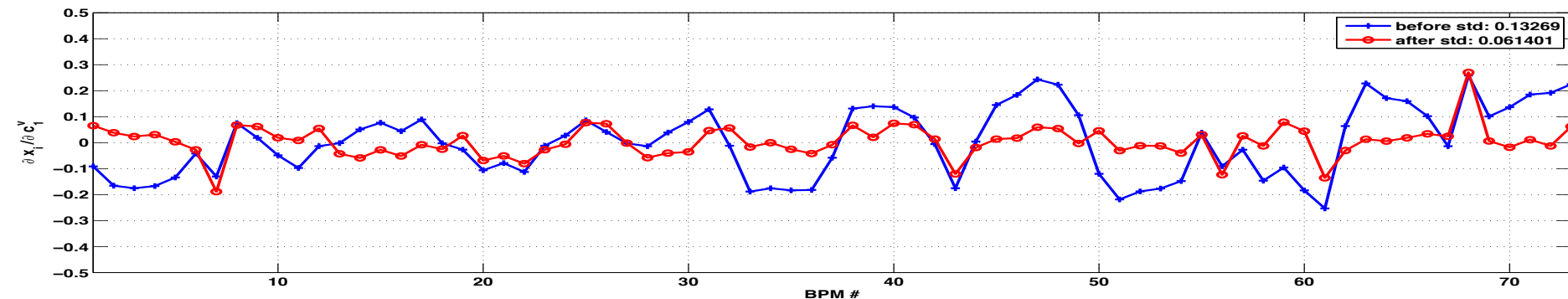
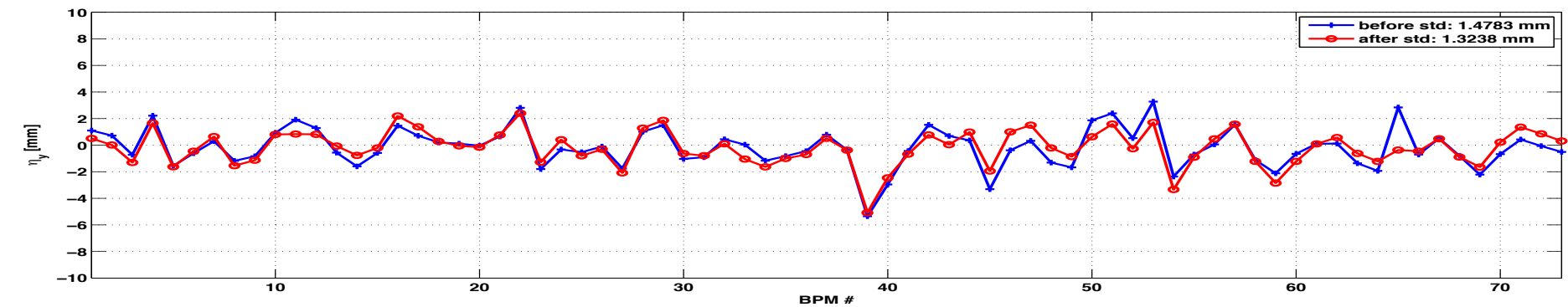
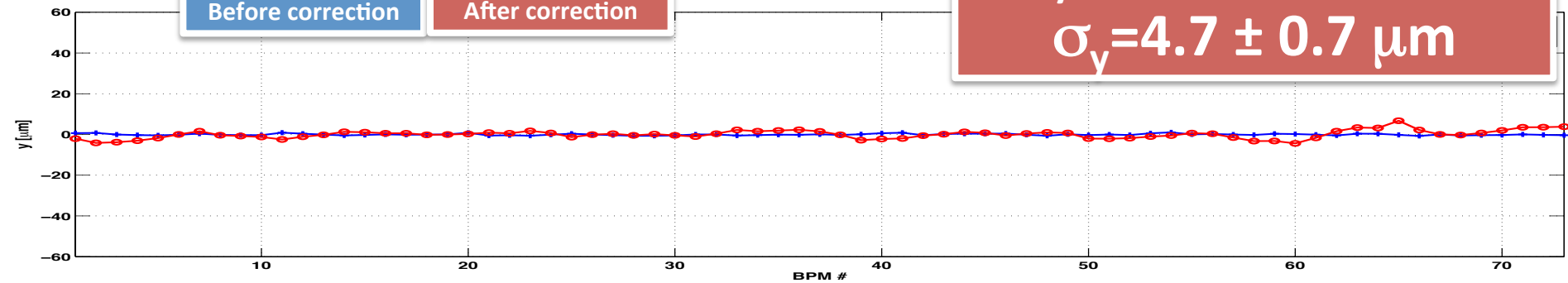


# SLS measurements

Skew Quadrupoles only  
 $\epsilon_y = 1.6 \cdot 10^{-12} \text{ m rad}$   
 $\sigma_y = 4.7 \pm 0.7 \text{ } \mu\text{m}$

Before correction

After correction

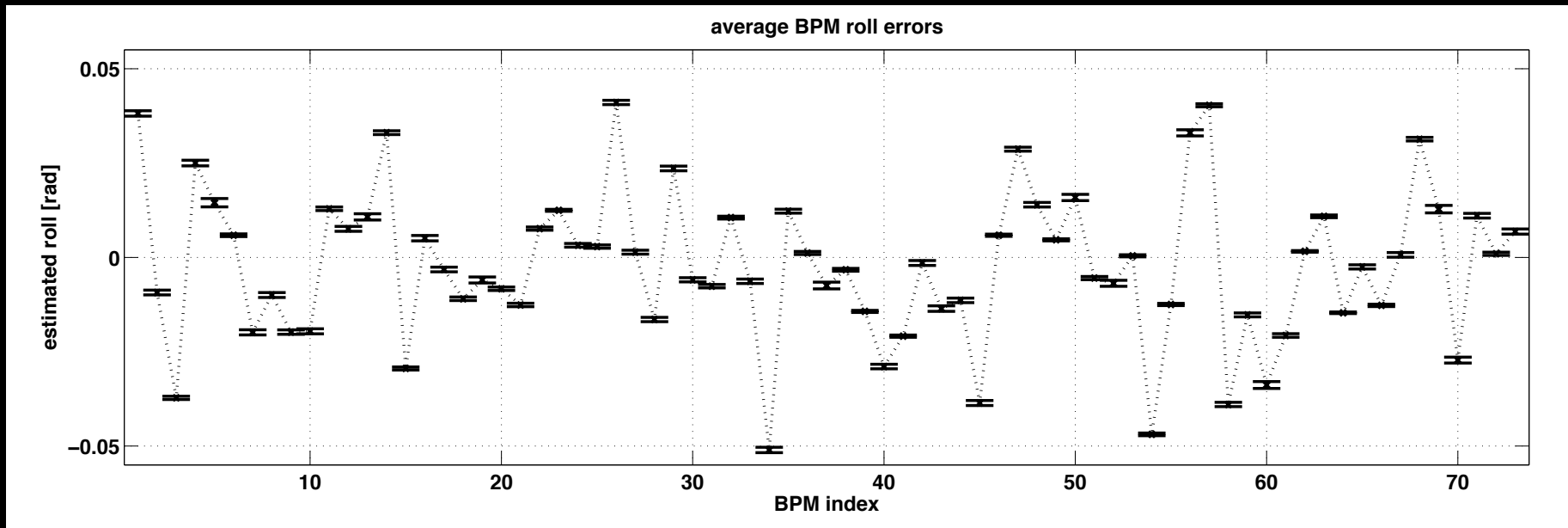




# BPM ROLL error estimation

Ex. For dispersion:  $\eta'_{yi} = \eta_{yi} \cos(\mathbf{T}_i) + \eta_{xi} \sin(\mathbf{T}_i)$

Evaluated simultaneously to the correction set evaluation



Comparable to the previous BPM roll estimates measured at SLS

# SLS measurements

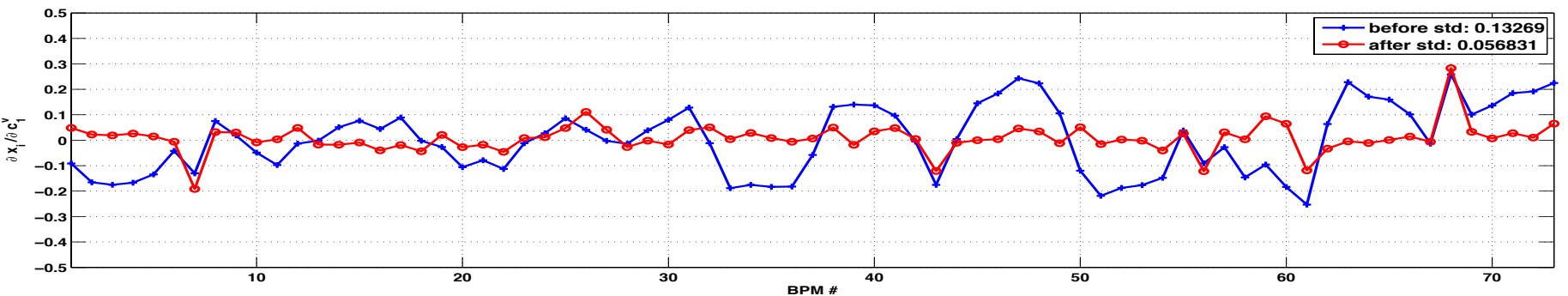
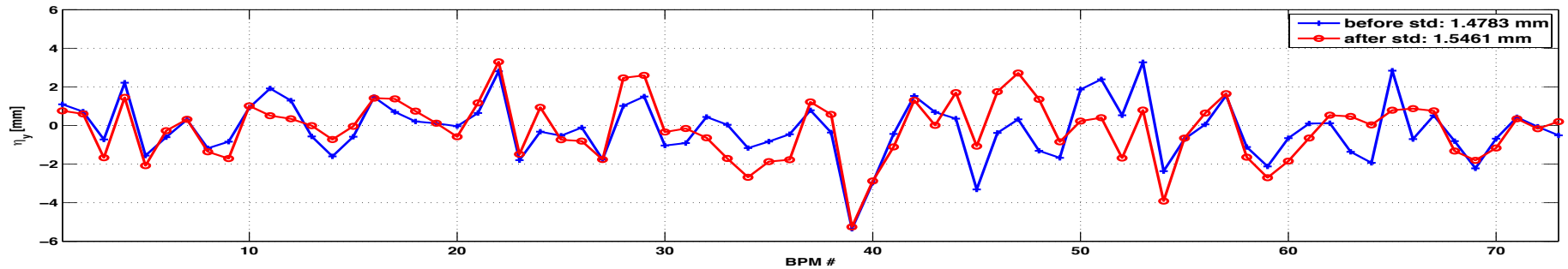
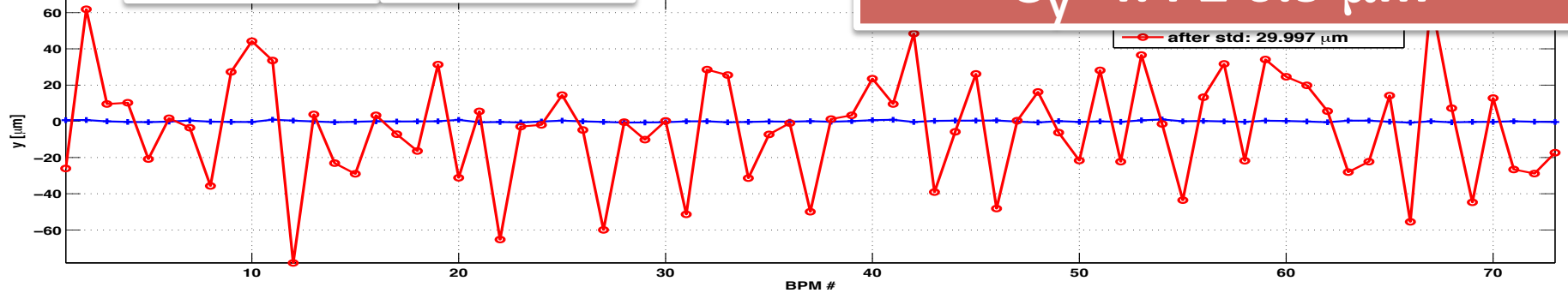
Skew Quad followed by vertical correctors and bpm roll estimations

$$\varepsilon_y = 1.3 \cdot 10^{-12} \text{ m rad}$$

$$\sigma_y = 4.4 \pm 0.9 \mu\text{m}$$

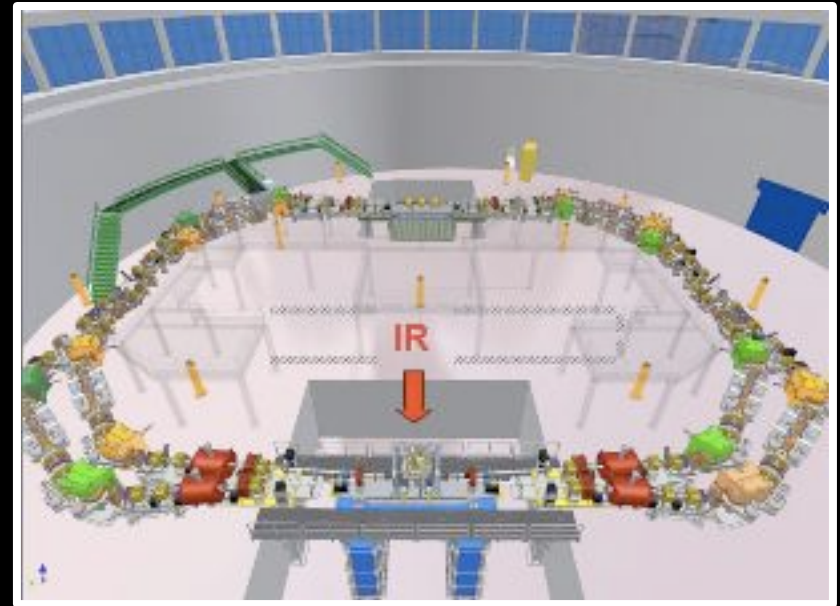
Before correction

After correction



# Low Emittance Tuning for DAΦNE

- Most similar to SuperB conditions.
- First tests with skew quadrupoles
- Colliding beams
- Short lifetime (20 min)
- High current (1200 mA  $e^-$ )
- Exclude IP from steering
- no tool



# DAΦNE alignments

Following previously used technique:

$$y_{q,m} = y_{q,\Delta H} k_q \Delta H + y_{q,\Delta V} t_q \Delta V$$

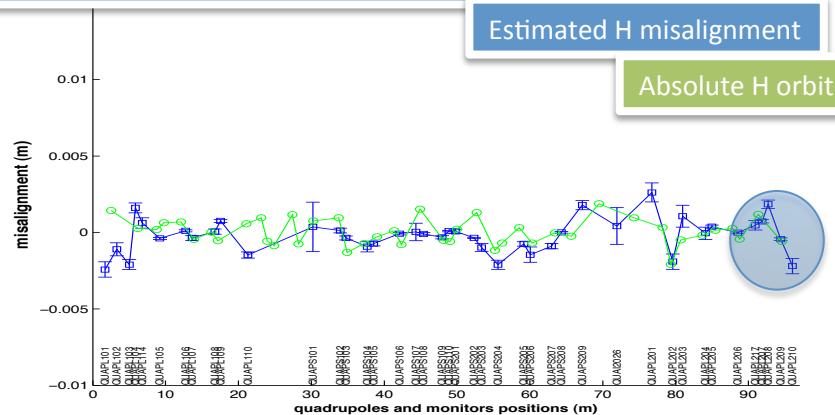
$$x_{q,m} = x_{q,\Delta H} k_q \Delta H + x_{q,\Delta V} t_q \Delta V$$

Fit  
parameters:  
t, k

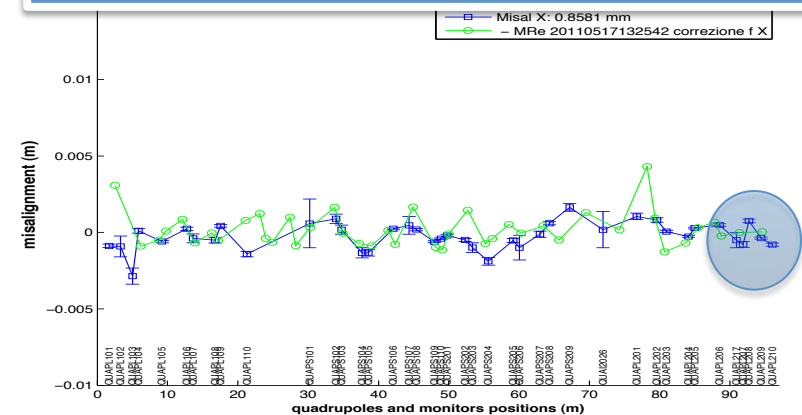
Orbit due to  
Change of quad K

Simulated orbit due to  
Quad misalignment  $\Delta H$  or  $\Delta V$

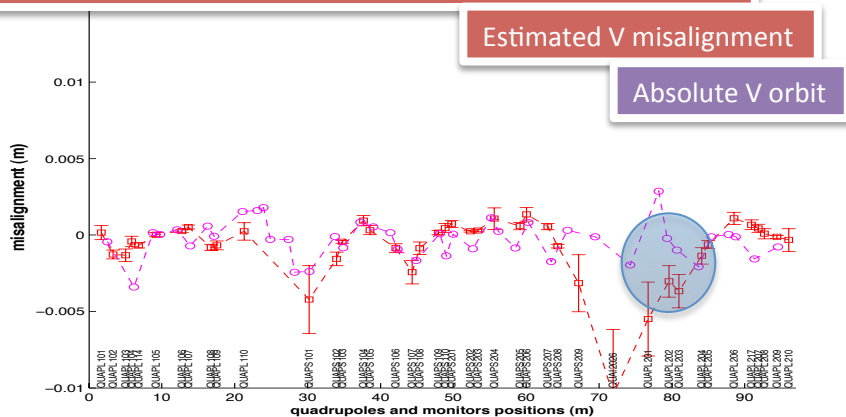
## e<sup>-</sup> Horizontal plane BEFORE realignment



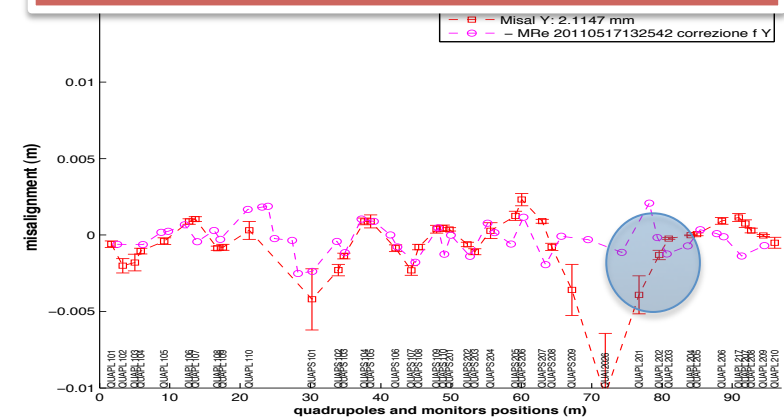
## e<sup>-</sup> Horizontal plane AFTER realignment



## e<sup>-</sup> Vertical plane BEFORE realignment



## e<sup>-</sup> Vertical plane AFTER realignment



# Conclusions

- Low emittance technique that exploits the off axis orbit in sextupoles and quadrupoles is tested at Diamond and at SLS:
  - Releasing the vertical orbit constraint to reduce dispersion and coupling allows reduction of vertical beam size
  - Skew quadrupole correction reach beam sizes and emittance comparable to previously obtained results at SLS (using skew quadrupoles)
  - Vertical steering including the evaluation of pseudo-bpm roll errors allows further improvement in the correction
- Measurements started at DAΦNE, but more complications arise. Preliminary studies of quadrupole alignments are performed.

# Future steps

- Include Quadrupoles correctors, steerers tilts and BPM gain errors in the correction parameters.
- Human readable quantities (coupling and beta functions)
- More measurements at SLS
- Introduce the possibility to exclude a region from the correction.