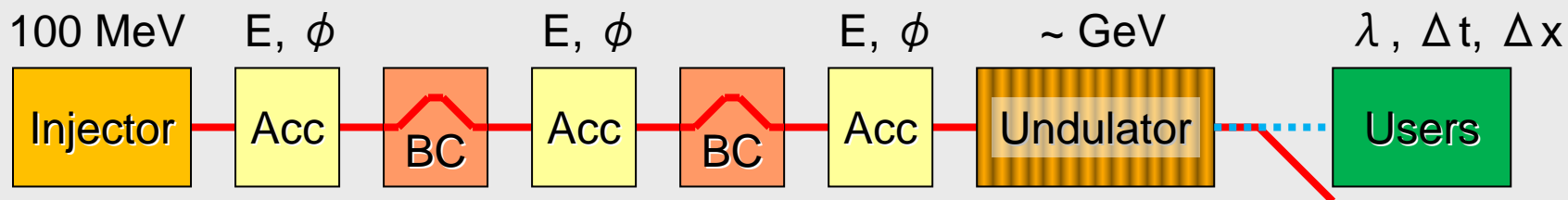


Feedback Requirements for SASE FELS

Henrik Loos, SLAC
IPAC 2010, Kyoto, Japan

- Stability requirements for SASE FELs
- Diagnostics for beam parameters
 - Transverse: Beam position monitors
 - Longitudinal: Bunch length/compression/arrival monitors, synchrotron radiation monitors
- Feedback implementations
 - LCLS transverse feedback
 - XFEL orbit IBFB
 - LCLS longitudinal feedback
 - FLASH longitudinal IBFBs
- Summary

- Ensure electron beam quality for lasing
- Provide stable photon beam for users



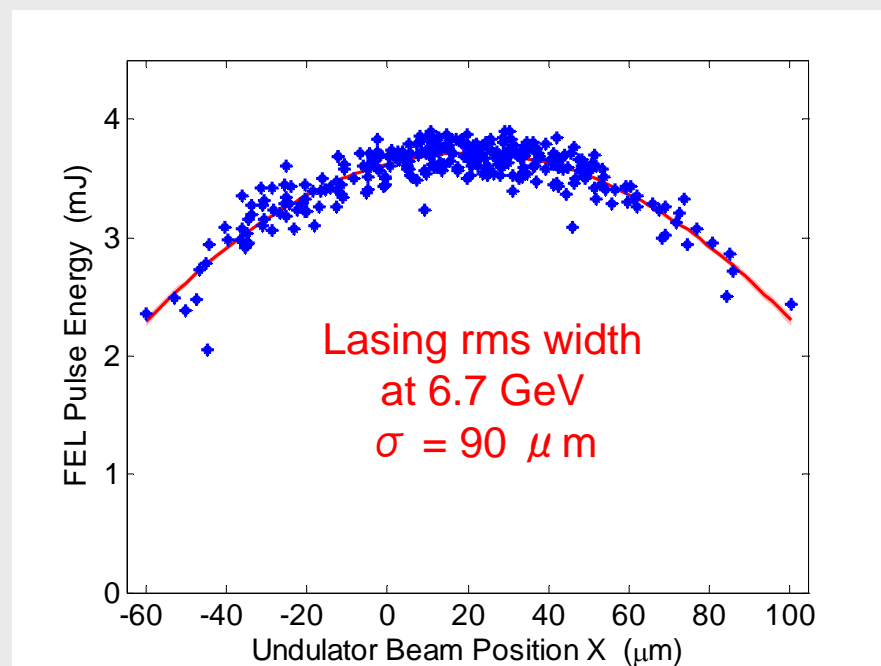
Energy (GeV)	Wave length	Und. length	Bunch Charge	Peak Current	Gain length	Beam size	Rate (Hz)
13.6	1.5 Å	100m	0.25-1nC	3kA	3.5 m	30 μ m	120
8	1 Å	100m	0.3nC	2.5kA	~10 m	35 μ m	60
17.5	1 Å	130m	0.1-1nC	5kA	3.7 m	45 μ m	10/5E6



■ Transverse requirements

- Undulator orbit $x' < \sqrt{\lambda/L_G}$ for efficient SASE
- $L_G \sim 3 - 10$ m, $\lambda \sim 1$ Å
→ $x' < 5$ μrad over several L_G
- Beam position $x < \sigma/10$ for stable photon beam
- $\beta \sim 30$ m, $\varepsilon_n \sim 1$ μm
→ $x < 5$ μm

LCLS example:
Transverse jitter in undulator
from leaked dispersion



■ Longitudinal requirements

- SASE process: ρ parameter $\sim 10^{-4}$
- Photon BW $\sim \rho \rightarrow$ energy stability 10^{-4}
- Bunch compressor $R_{56} \sim 4$ cm
 \rightarrow timing jitter $\Delta t \sim R_{56} \rho / c \sim 10$ s of fs
- Energy measurement $R_{16} \sim 10$ cm $\rightarrow R_{16} \rho \sim 10 \mu$ m
- Energy in BC from position measurement in BC or from TOF measurement with beam arrival monitors

■ Bandwidth requirements

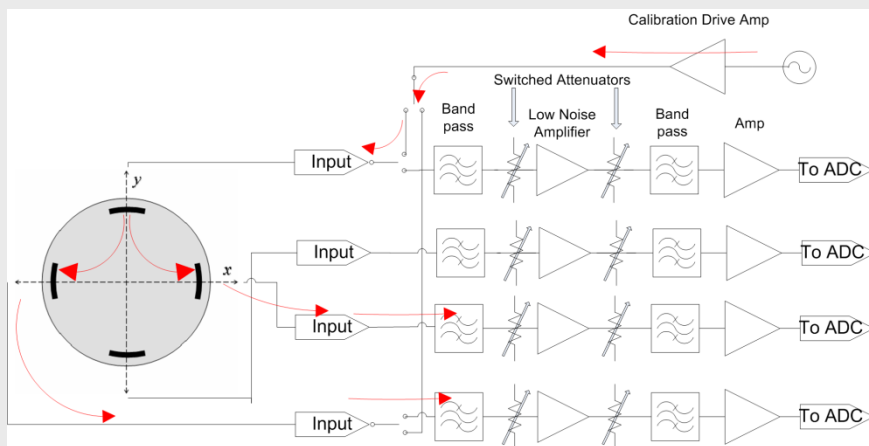
- NC accelerator ~ 100 Hz rate \rightarrow Feedback stabilizes slow drifts
- SC accelerator bunch train MHz rate \rightarrow Intra Bunch FB required

Strip line BPMs

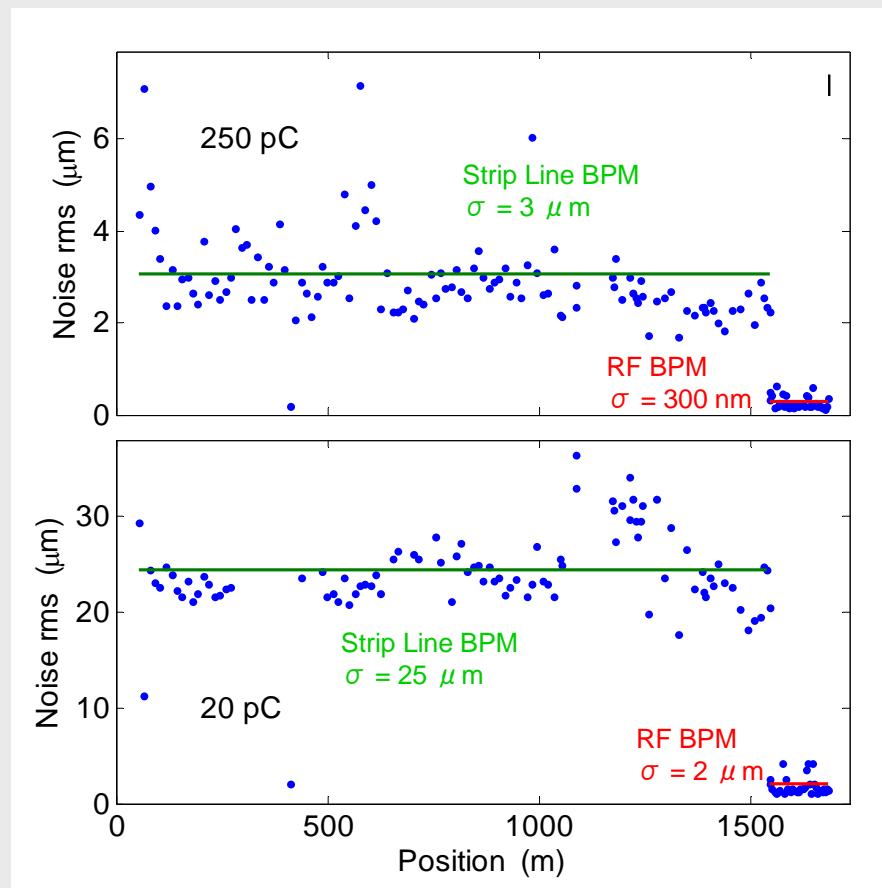
- Continuous calibration with test pulse between beam triggers
- Beam synchronous data acquisition system at 120 Hz

Noise level measurement

- Measure beam orbits at ~150 BPMs for 500 shots in main linac through undulator
- Average value for strip-line $3.5 \mu\text{m}$, for RF cavity 250 nm at 250 pC



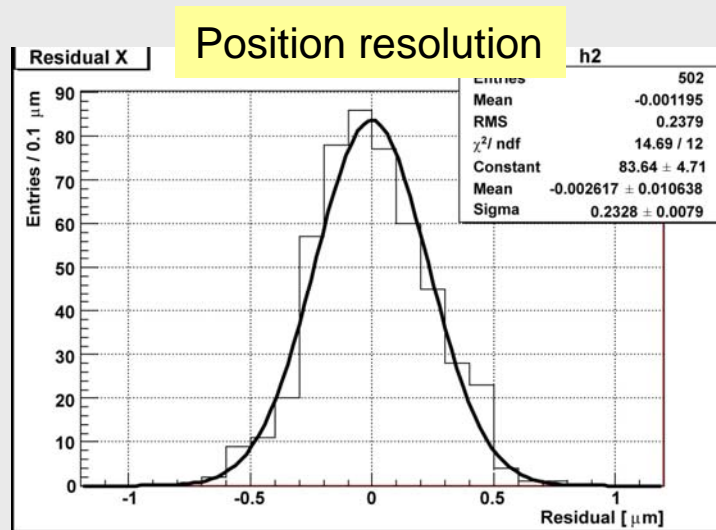
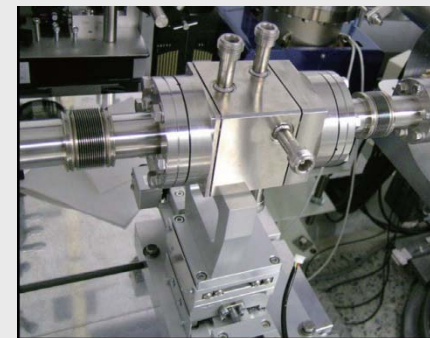
E. Medvedko et al., BIW 2008, TUPTPF037



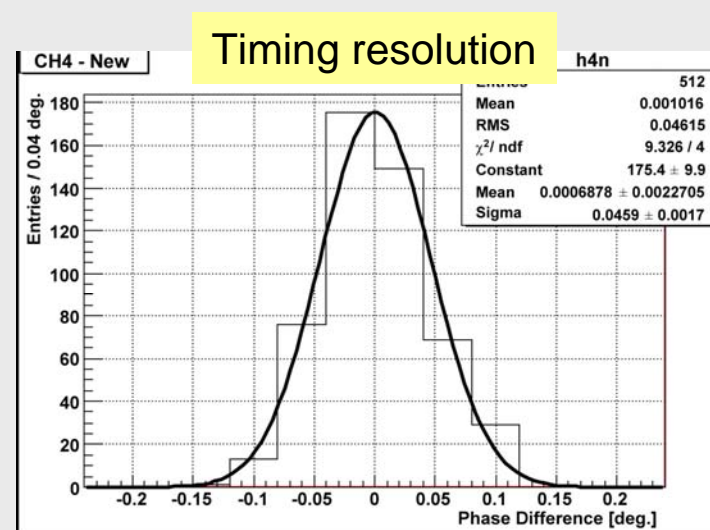
- Few micron beam orbit straightness in undulator required for FEL operation
- Sub-micron resolution met with RF cavity BPM design
- 11.4 GHz dipole cavity
- Reference cavity for normalization
- Calibration with beam signals
 - Move supporting girder of undulator
 - Induce known orbit oscillation upstream of undulator



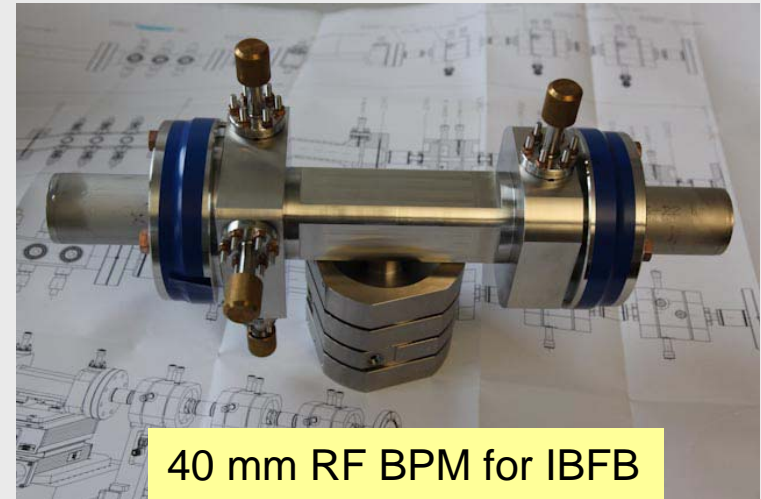
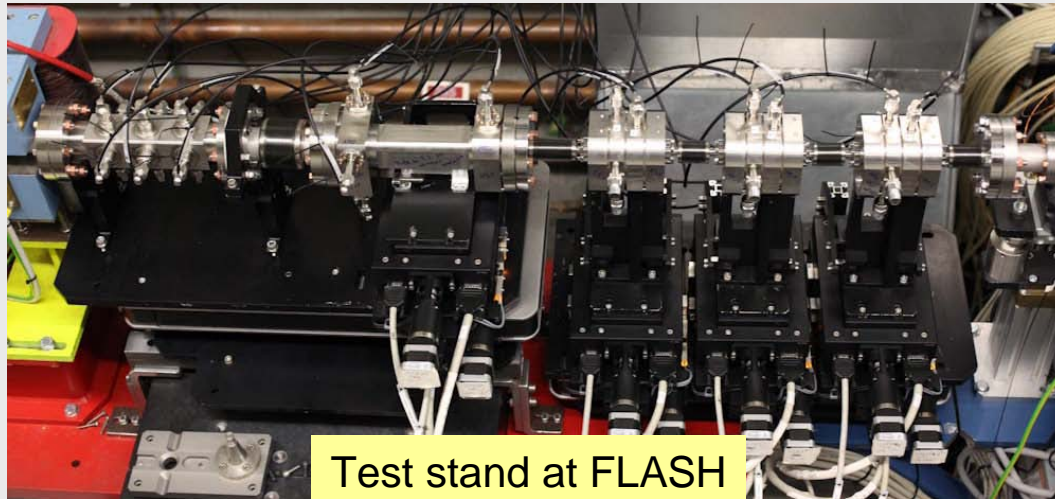
- Dipole mode cavity at 4.76 GHz + monopole cavity
- Shifted from main RF frequency to avoid dark current
- Measurements at SCSS test accelerator
- Position resolution < 200 nm
- Timing resolution from TM_{010} cavity < 25 fs



H. Maesaka et al., DIPAC09, MOPD07



See also H. Maesaka et al., MOPE003
S. Matsubara et al., MOPE004



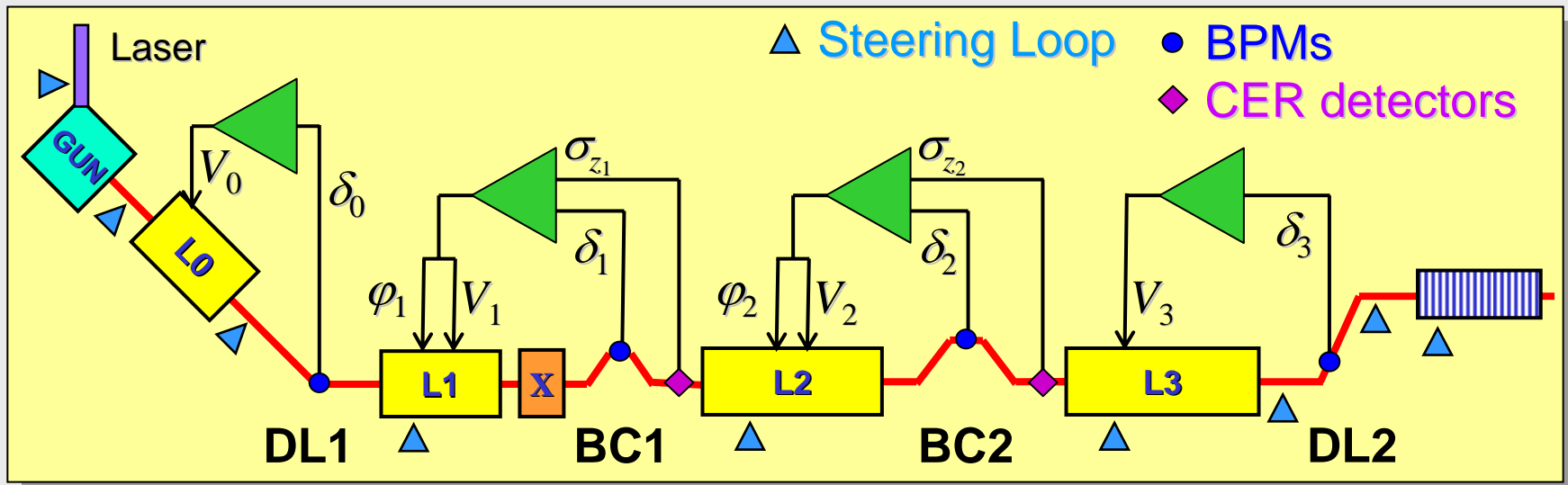
D. Noelle, BIW10, WECNB01

- Based on Spring-8 design
- Frequency 3.3 GHz
- Low Q to resolve bunch train at 5 MHz
- 10 mm high precision version for undulator
- 40 mm version for IBFB
- Designed for 1 μ m resolution



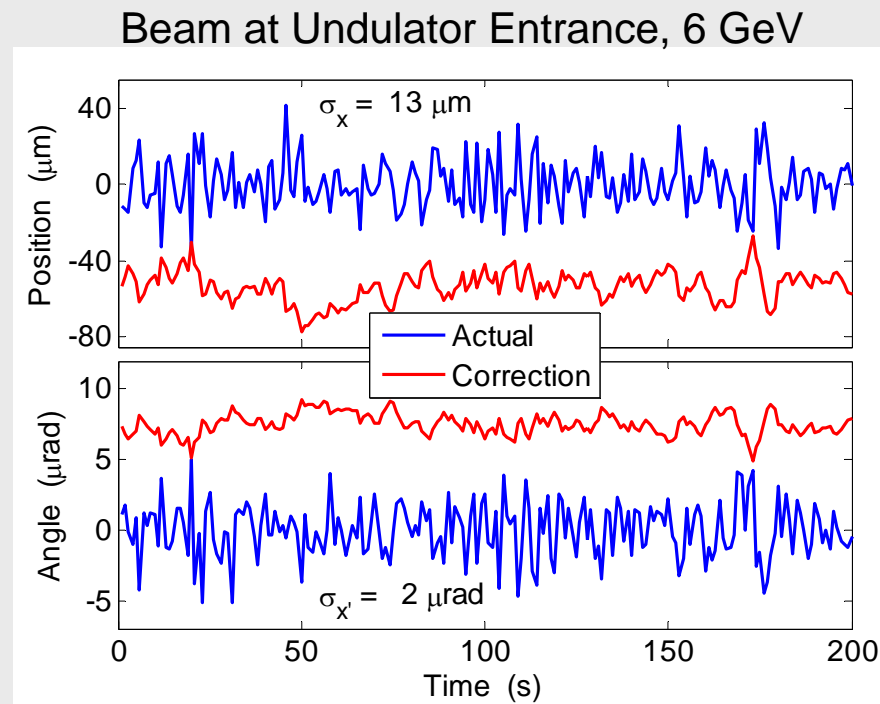
See also B. Keil et al., MOPE064

- Launch FB for each linac section
- Loops for transport line and undulator
- FB are independent of each other
- Decoupling by use of different time scales
- FB response matrix from online model

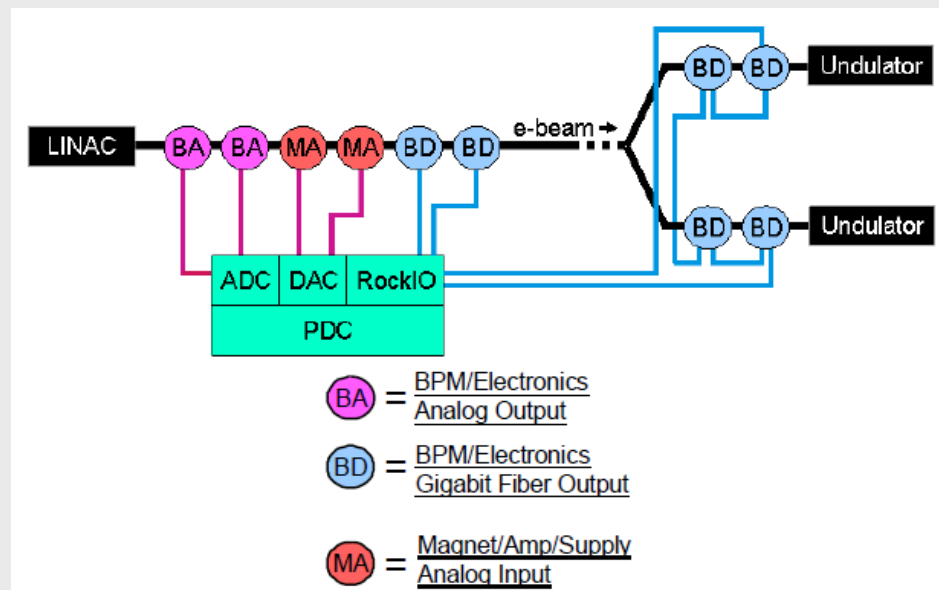


J. Wu et al., PAC 2009, WE5RFP046

- Upstream LTU FB runs at 10 Hz
- Undulator FB slower with 1 Hz
- Horizontal jitter $13 \mu\text{m} / 2 \mu\text{rad}$
- 30 – 40% larger than vertical due to dispersion leakage
- Residual jitter $\sim 25\%$ of beam size

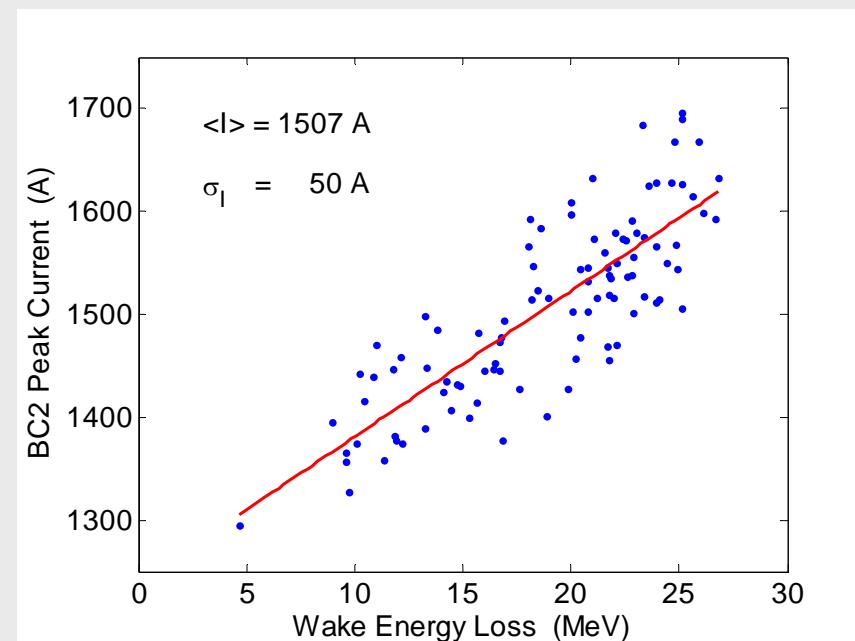
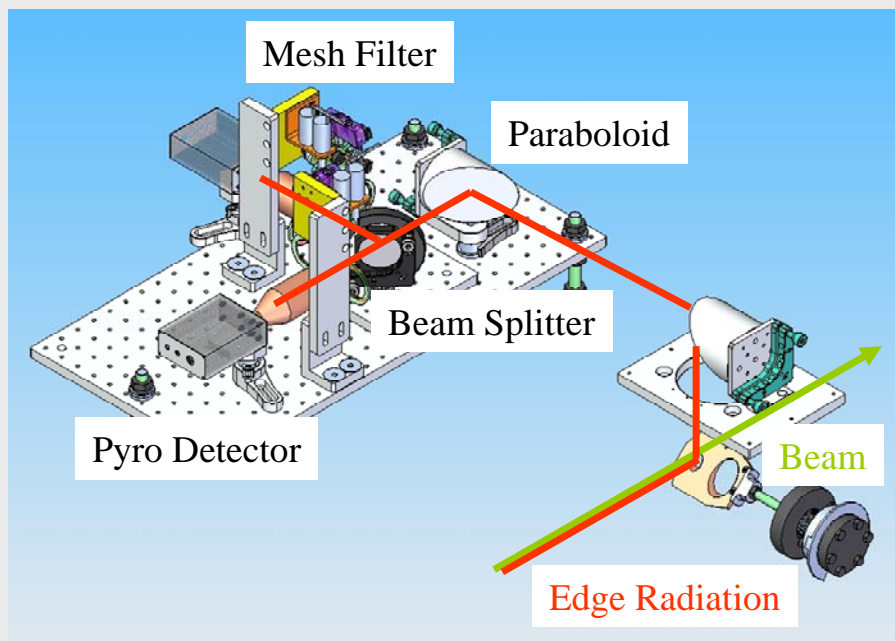


- Use downstream BPMs for feedback loop
- Latency $\sim 1 \mu\text{s}$ bunch spacing
- FPGA for feedback calculation
- Fast strip-line kicker for orbit correction
- Use upstream BPMs for calibration
- BPMs in undulator for slow feedback

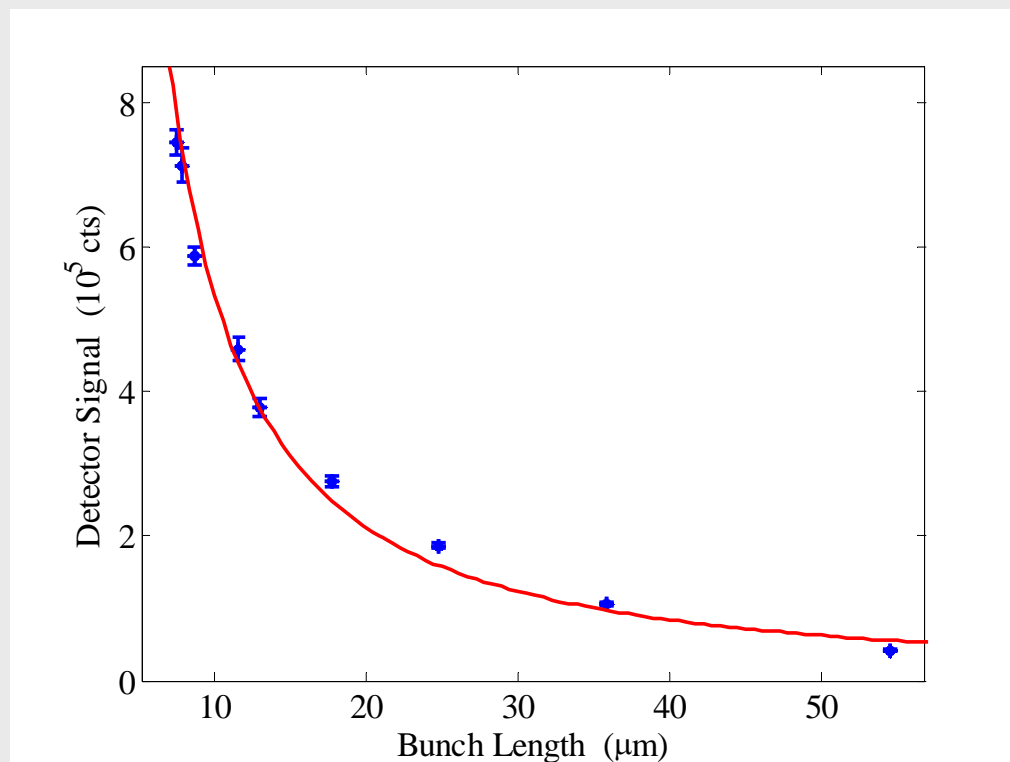
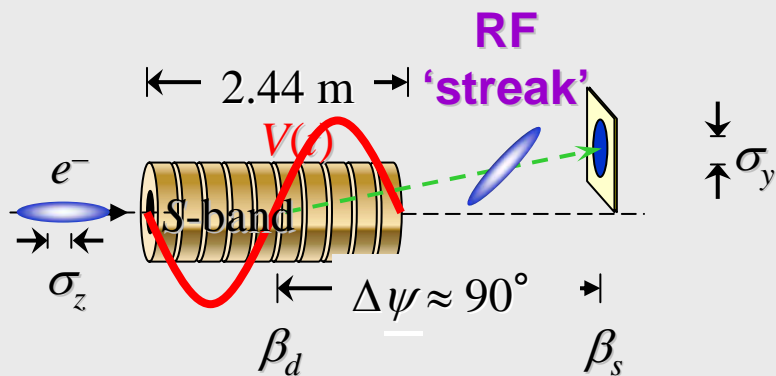


B. Keil et al., EPAC08, THPC123

- Edge radiation from last dipole of each BC
- Integrated measurement sensitive from mm to $20 \mu\text{m}$
- Block NIR radiation from bunching instability with filters
- 3% rms noise from correlation with bunch length dependent wake field energy loss in undulator

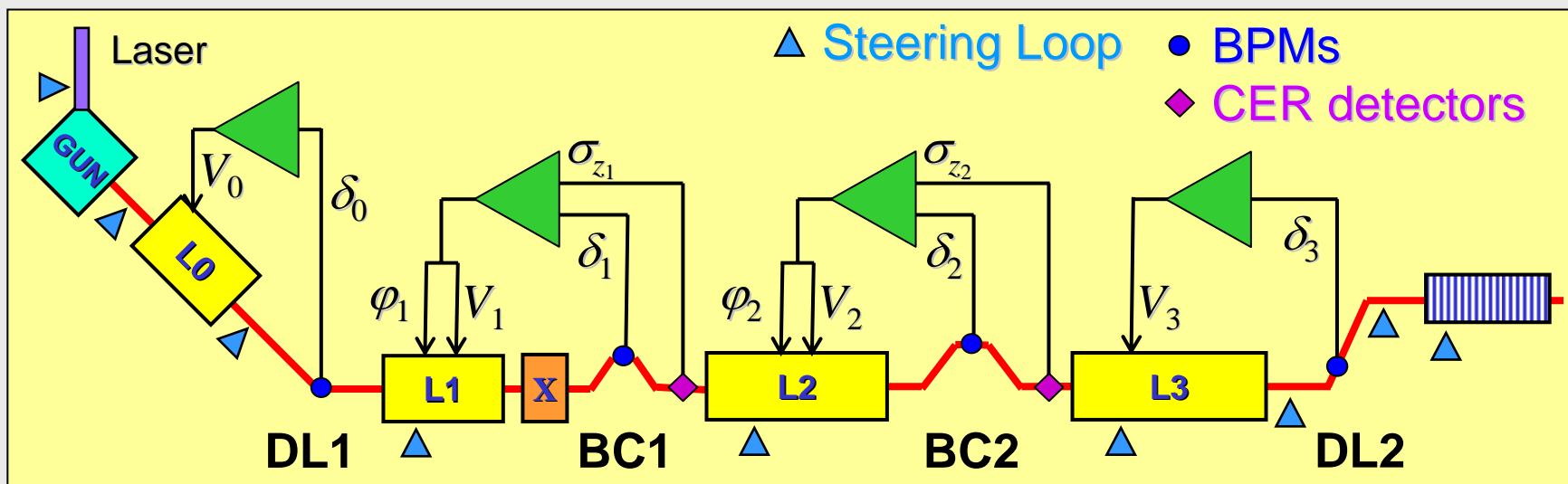


- BPM provides only signal related to bunch length
- Calibration with absolute measurement from transverse deflecting cavity

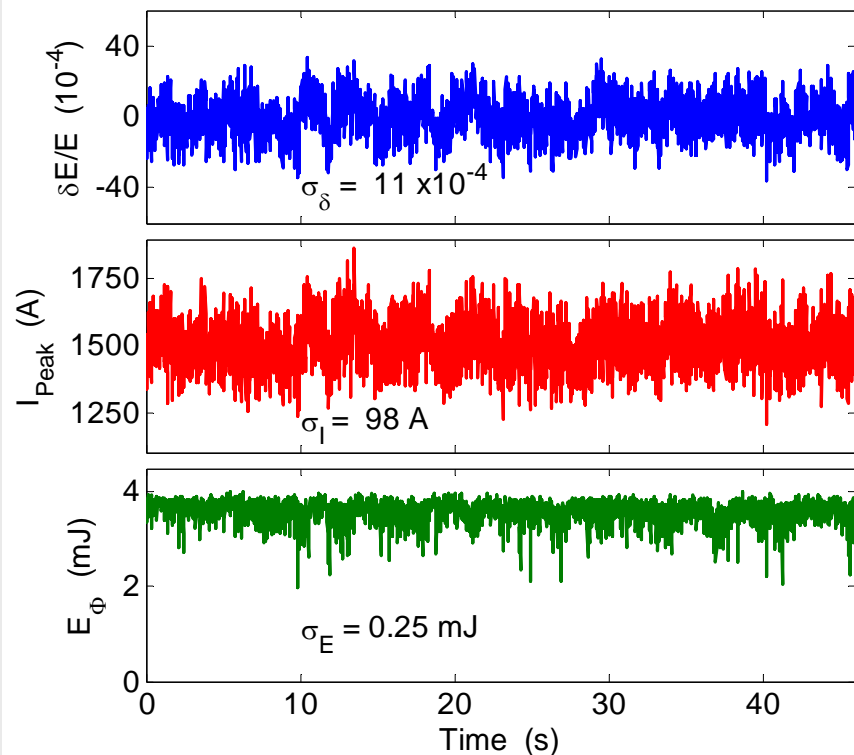


- Empirical fit of signal to $(\sigma_z)^{-4/3}$
- Use fit to calculate peak current

- Cascaded FB at 5 Hz (Matlab implementation)
- Fixed energy gain in L2 & L3 klystrons
- Change global L2 phase
- Adjust L2 & L3 energy with several klystrons at opposite phases
- Feedback uses orthogonal actuators to separate energy gain and chirp of L2



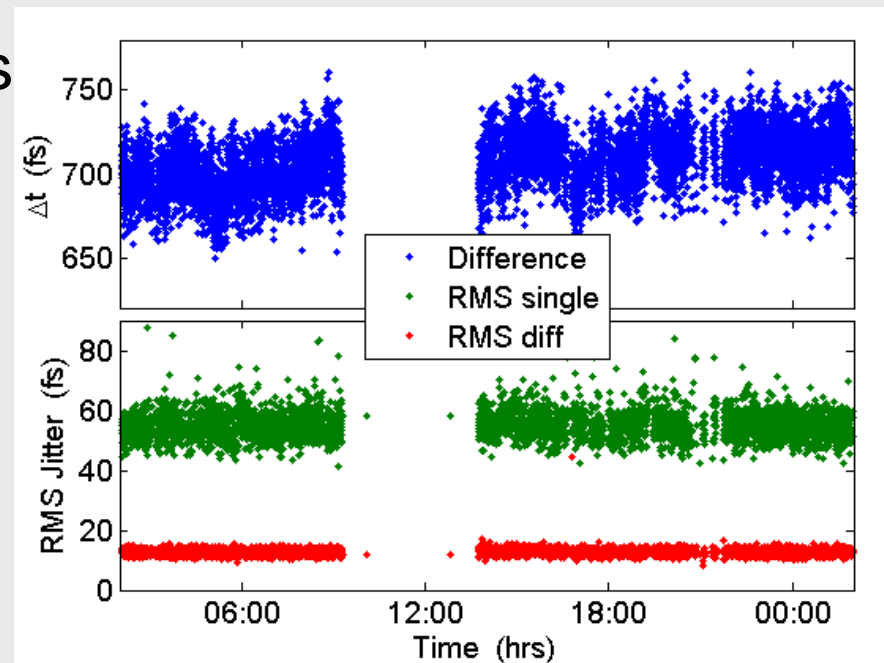
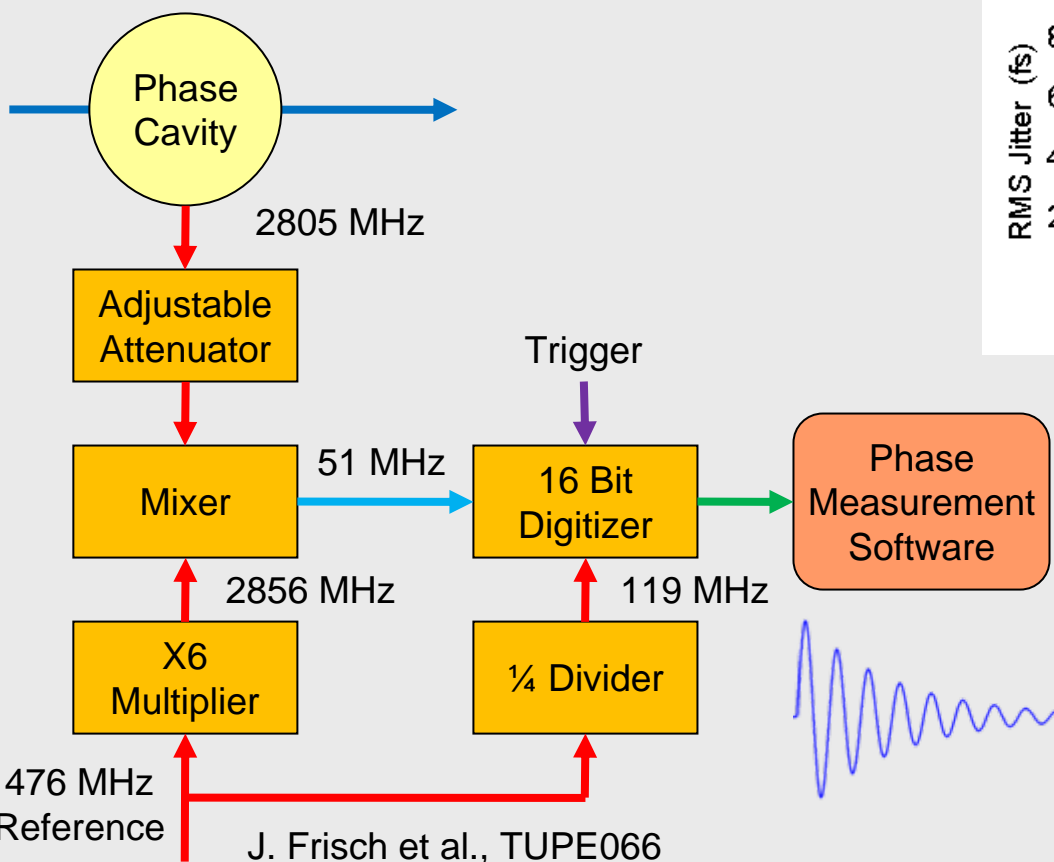
Beam energy/peak current, 6 GeV



See also F.-J. Decker et al., TUPE071

- 7% peak current jitter
- 6% X-ray pulse energy jitter (best 3%)
- Stability achieved over hrs
- Feedback controls enable bunch length & energy changes (few %) in 10s of seconds
- Operation soon at 120 Hz
- Fast orbit and energy/phase feedback in development
- Time-slot aware control for different 60 Hz phases

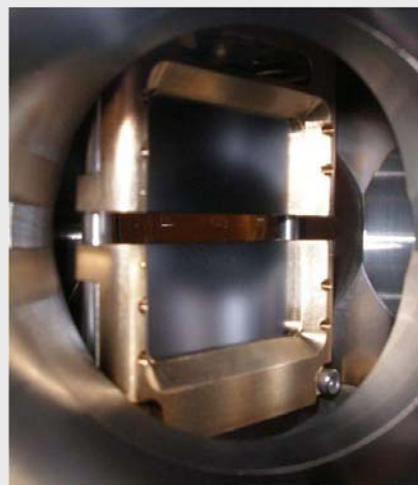
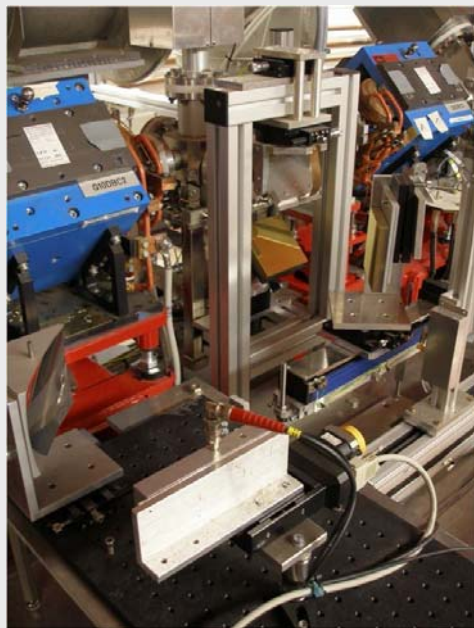
- Jitter between two cavities 15 fs
- Not used for e-beam FB
- Signal used for offline analysis



- Synchronize laser of user experiment to electron beam

J. Byrd et al., MOOCRA03

See also J. Byrd et al., TUPEA033
T. Ohshima et al., TUPEA030



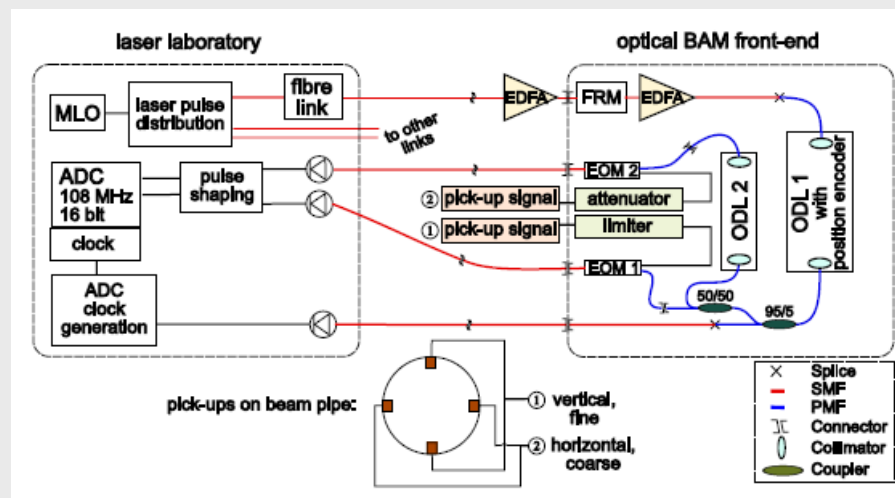
C. Behrens et al., MOPD090

- Coherent diffraction radiation detector
- Radiator is metal screen with slit
- Optical radiation transport with GHz to THz bandwidth
- Signal from pyroelectric detector
- Fast detection resolves bunch train

- Laser clock via length stabilized fiber with 6 fs stability
- Beam signal from 4 button pick-ups
- Electro-optic modulator encodes beam signal on laser amplitude
- Fast sampling with 108 MHz ADC
- Operate at zero-crossing of amplitude modulation
- Delivers arrival time of each bunch in bunch train with < 10 fs resolution



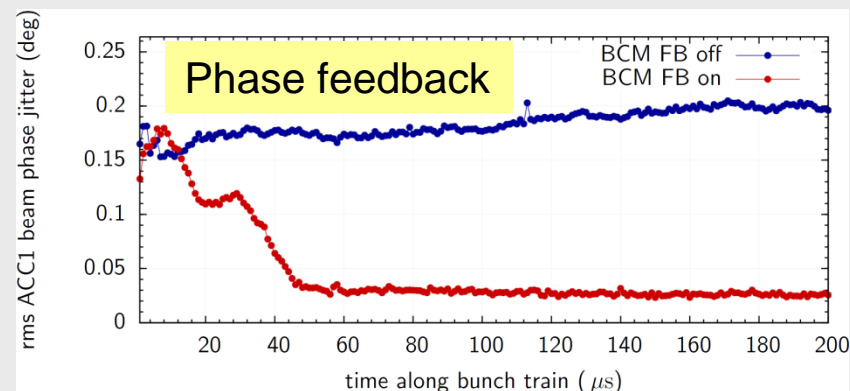
F. Loehl, TESLA-FEL2009-08



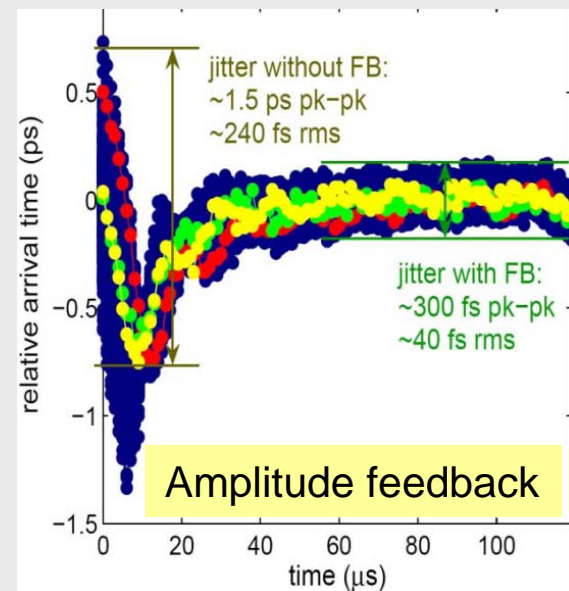
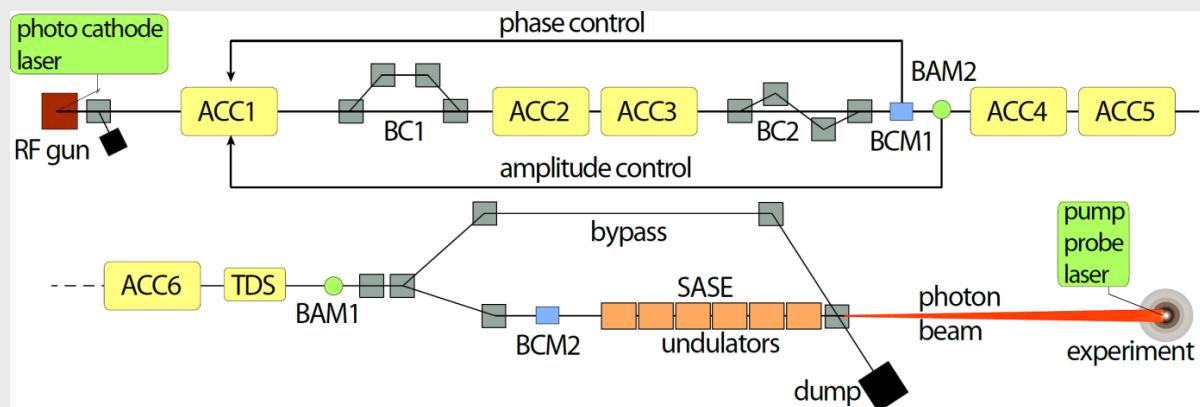
M. Bock et al., FEL09, WEPC66

See also M. Bock et al., WEOCMH02

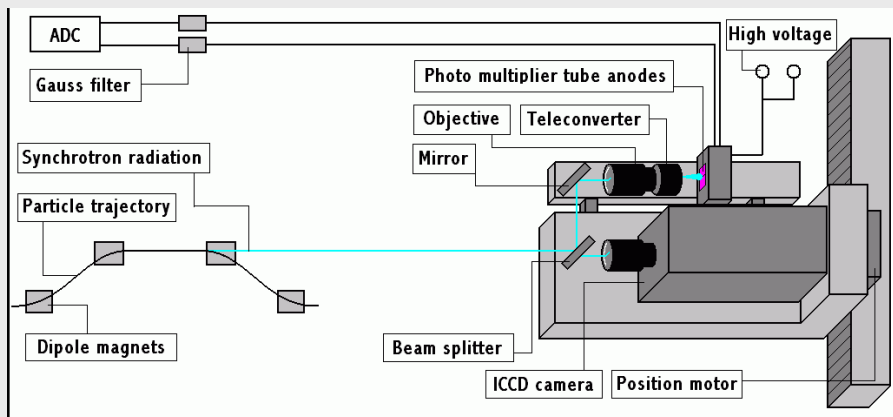
- FPGA based controller board
- PID controller for amplitude correction from BAM signal
- Phase control from BCM signal
- Rapid change at head of bunch train from beam loading
- Latency of 30 μ s due to SC RF



F. Loehl et al., FEL08, THBAU02

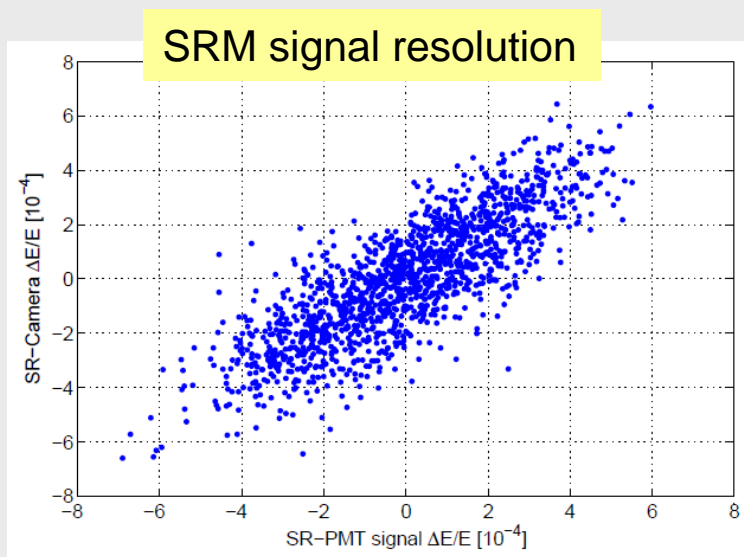


F. Loehl et al., EPAC08, THPC158



A. Wilhelm et al., DIPAC09, TUPD43

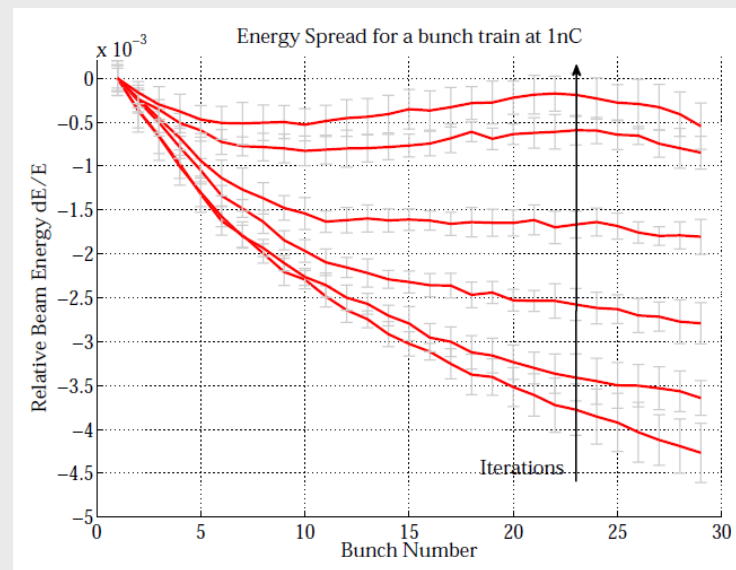
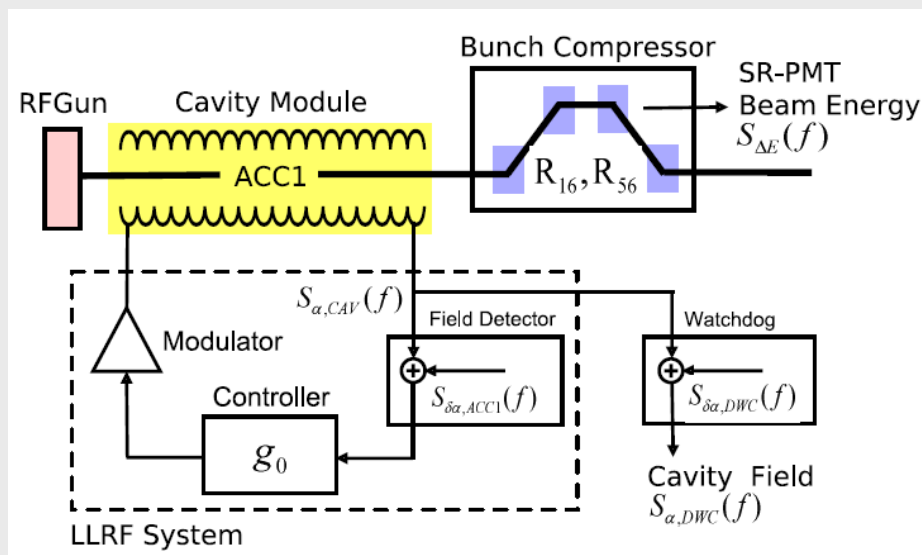
- Energy measurement with $< 10^{-4}$ resolution
- ICCD for energy spread of single bunches
- Fast centroid readout with multi-anode PMT
- 14-bit ADC at 1 MHz for bunch train resolution



C. Gerth et al., DIPAC09, TUPD22

- Correct stochastic and deterministic disturbances with a learning FF algorithm

- Effect of beam loading at head of bunch train minimized after a few iterations of the FF algorithm



C. Gerth et al., DIPAC09, TUPD22

- Diagnostics available to meet resolution requirements for SASE FELs
- SASE FEL feedback systems achieve beam stability to do user experiments over many hours
- Optical synchronization schemes enable < 10 fs timing measurements and synchronization of user experiments
- Energy stability of $\sim 10^{-3}$ still exceeds photon beam bandwidth

- Thanks to all the people working on X-ray laser facilities worldwide and to my colleagues from the LCLS commissioning team to make stable X-ray beams a reality