

# The ESRF Extremely Brilliant Source

## A 4<sup>th</sup> generation light source

Jean-Michel Chaize on behalf of ESRF accelerator Control Unit



# Outline



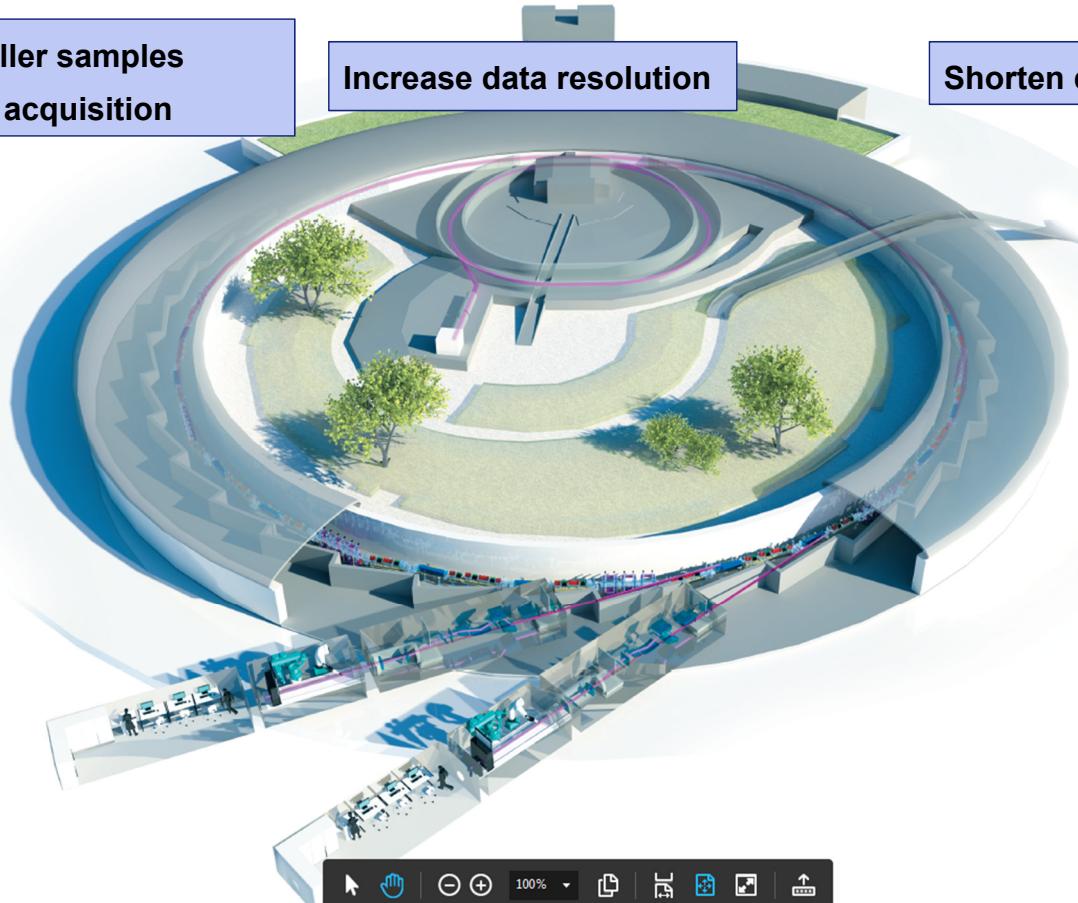
- **ESRF-EBS Project:** goal, characteristics
- **EBS components**  
(from control system point of view)
- **Project management and planning**
- **Accelerator Control system**
  - Hardware infrastructure
  - Software
  - New synchronization system
  - New archiving system
  - Experiment control

# Why EBS? -> Increase the science outcome

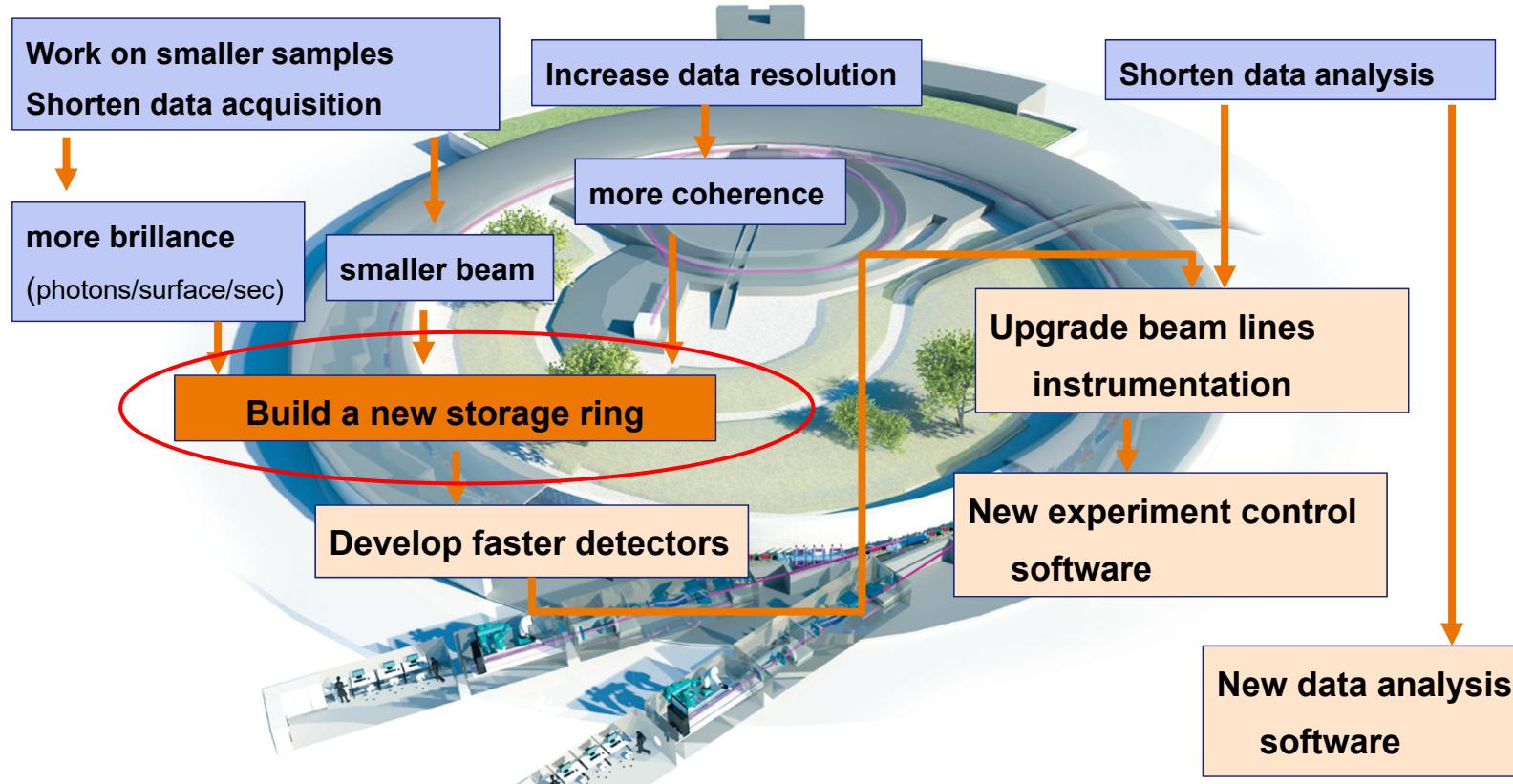
Work on smaller samples  
Shorten data acquisition

Increase data resolution

Shorten data analysis



# Why EBS? -> Increase the science outcome

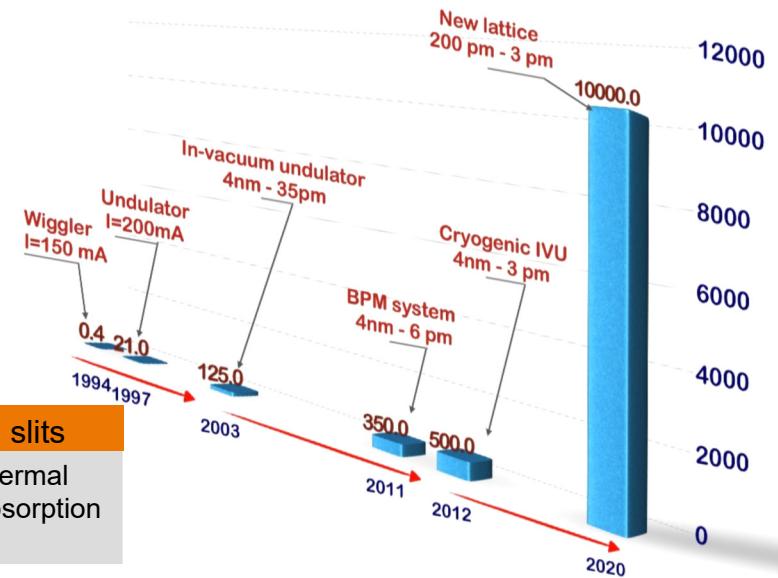
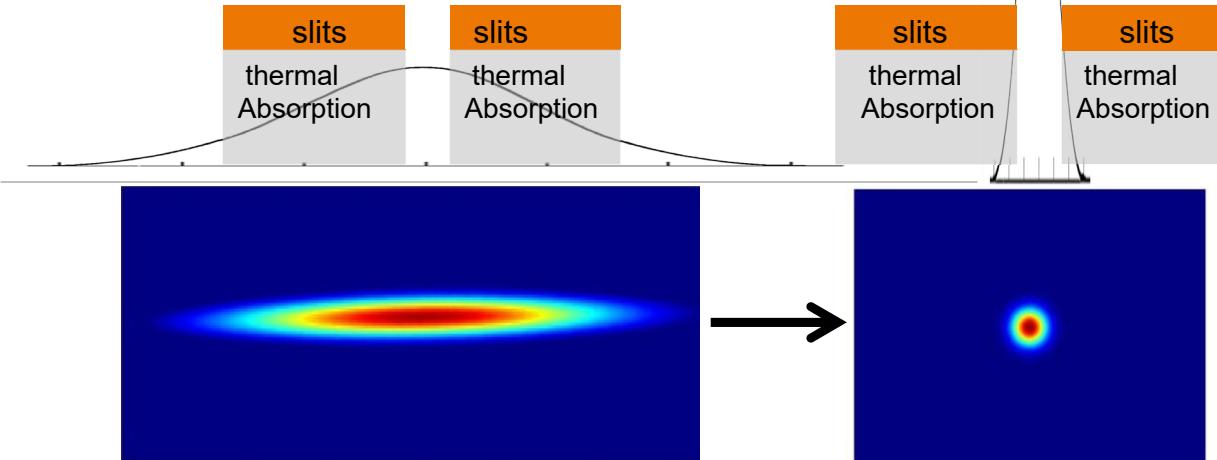


# EBS – Reduction of the horizontal emittance -> Increase of brilliance

Reduction of the **horizontal** emittance  
from **4nm.rad** to **0.14nm.rad**

$$\text{emittance} = \frac{6\pi \left( \text{width}^2 - D^2 \left( \frac{dp}{p} \right)^2 \right)}{B}$$

Expected gain on a monochromatic beam:  
**X100** in number of photons/s/surface on the sample.



Same number of photons on smaller array (x26)  
+ Higher monochromatic peaks (x2)  
+ Better capture at the sample place (x2).

# The EBS Storage Ring characteristics

	Now	EBS
Energy (GeV)	6.04	6
Multibunch current (mA)	200	200
Circumference (m)	844.39	843.98
Horizontal emittance (nm.rad)	4	0.14
Vertical emittance (pm.rad)	4	5
Number of beamlines	43	47

→ reduced by  
a factor of 29

→ 14 refurbished, 4 new

## Main engineering challenges:

- Reuse 90% of the infrastructure
- Fit new lattice in the same tunnel. Same circumference.
- Insertion devices at the same locations: keep beamlines where they are!
- Re-use injector complex, ID, FrontEnds, Infrastructure...
- High precision & high stability positioning requirements
- Little time for the project and in parallel to the normal operation of the facility

# Main EBS accelerator components

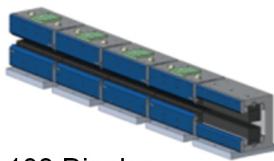
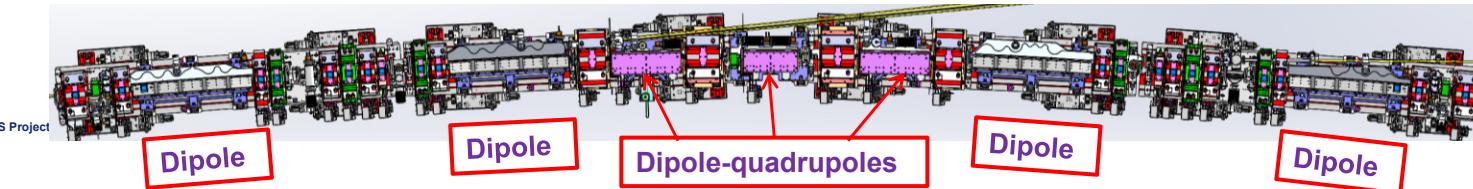


# Magnets

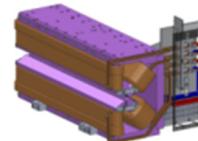
➤ **EBS magnetic lattice** (32 identical cells of 26m long)

Hybrid 7 Bend Achromat = (4 dipoles + 3 dipole-quadrupoles + 24 quadrupoles, sext., oct.) per cell

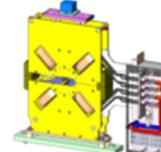
➤ +33 corrector channels (24 Inside sextupoles and 9 in corrector magnets)



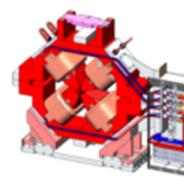
132 Dipoles  
Permanent magnets



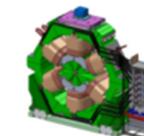
100 Dipole-quadrupoles  
Including 1 field corrector



66 Octupoles



524 Quadrupoles



196 Sextupoles  
Including 4 correctors  
channels each



98 Correctors  
3 channels  
each

**More than 1000 Magnets to be produced**

31 magnets per cell instead of currently 17

864 power supply channels for lattice instead of 17!

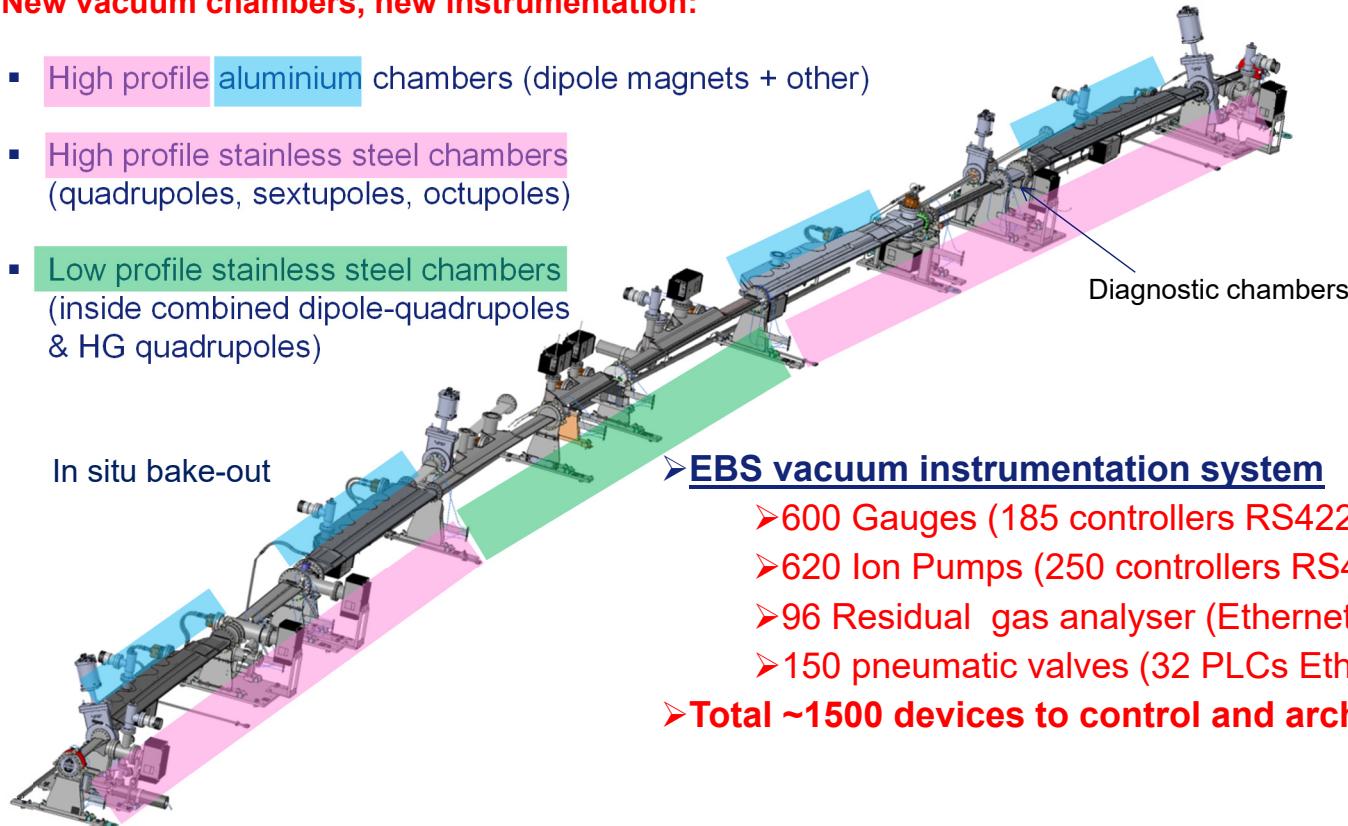
1354 power supplies channels for the correctors

**Total ~2300 power supplies to control**

# Vacuum system

## New vacuum chambers, new instrumentation:

- High profile aluminium chambers (dipole magnets + other)
- High profile stainless steel chambers (quadrupoles, sextupoles, octupoles)
- Low profile stainless steel chambers (inside combined dipole-quadrupoles & HG quadrupoles)

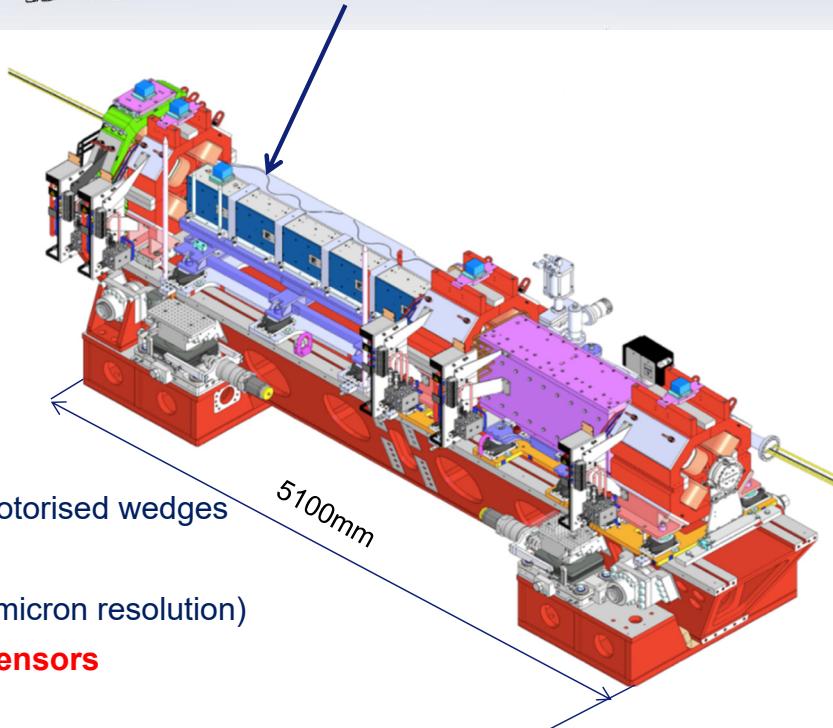
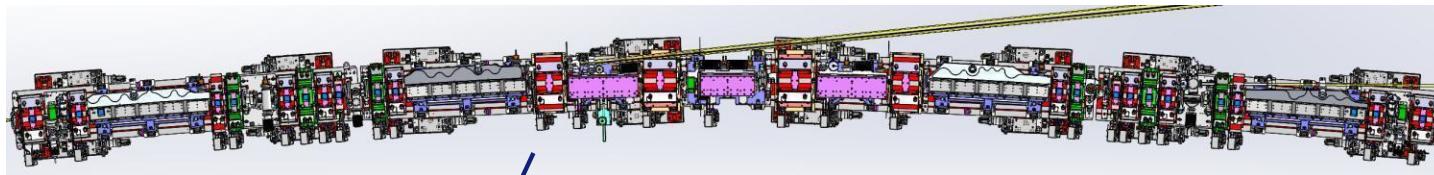


### EBS vacuum instrumentation system

- 600 Gauges (185 controllers RS422 or Ethernet)
- 620 Ion Pumps (250 controllers RS422 or Ethernet)
- 96 Residual gas analyser (Ethernet)
- 150 pneumatic valves (32 PLCs Ethernet)

➤ **Total ~1500 devices to control and archive**

# Girders

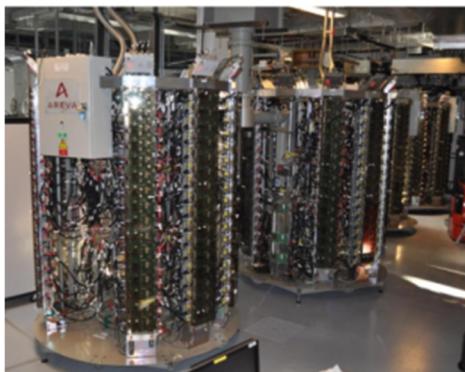


- 4 adjustable feet with motorised wedges
- Hyperstatic
- 4 Hydrostatic Sensors (micron resolution)
- Total: 512 axis + 512 sensors**

Four girders per cell to install:  
➤ Magnet supports  
➤ Magnets  
➤ Vacuum equipment  
➤ Diagnostics

Bare girder weight: ~6t  
Fully equipped girder: ~12-13t  
129 girders in total

# Radio Frequency Systems

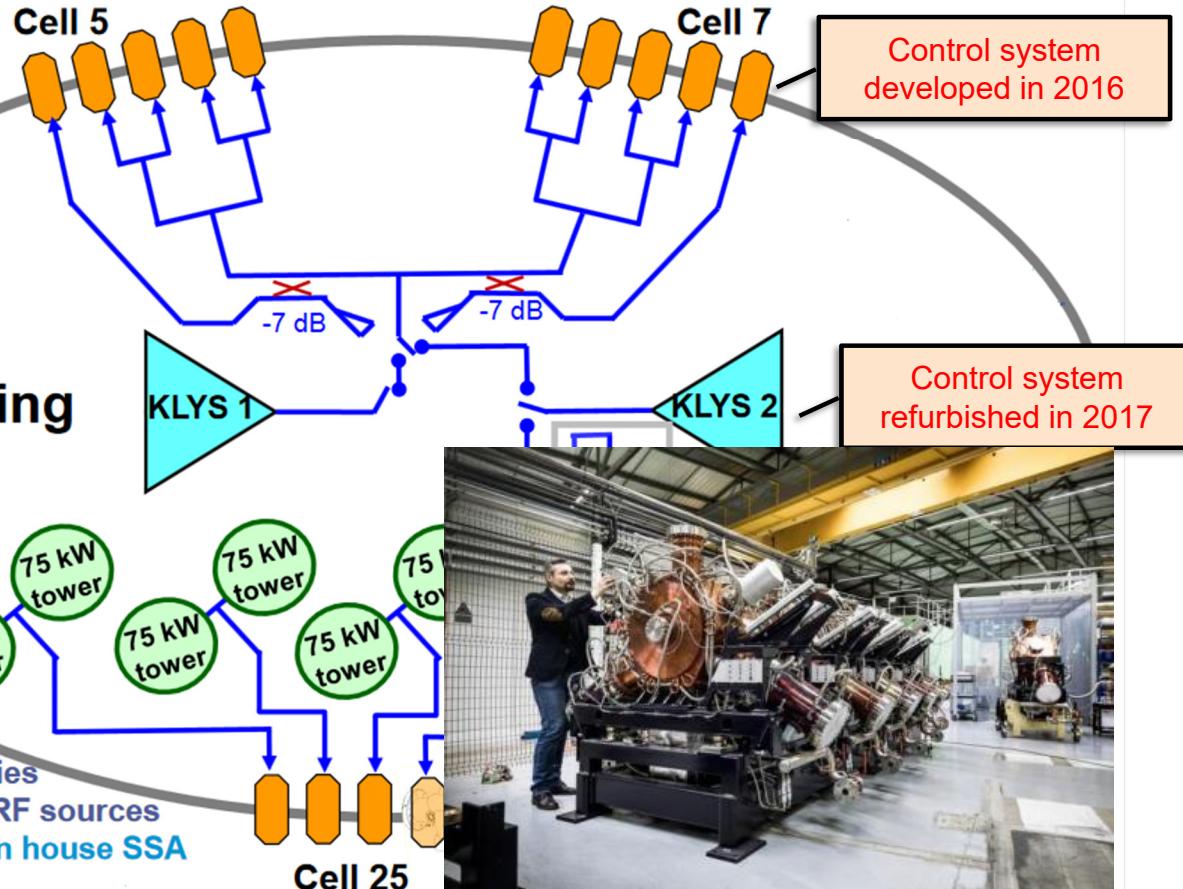


Storage Ring

3x existing  
150 kW SSAs

Control system  
developed in 2015

- ☛ Base line: 13 cavities
- ☛ Use only existing RF sources
- ☛ 14<sup>th</sup> cavity fed by in house SSA



# Project management and planning



# Main idea: Pre-Assembly the full storage ring on 128 + 1 girders

The Assembly phase takes place during the Operation of the facility!

- Need every pieces, magnets, vacuum chambers,... to start assembly of a girder
- Need storage space for individual pieces and for girders
- Careful management of human resources
- Maintain 24x7 user service of present ring.

- Install magnets on girders & align
- Open magnets
- Install pre-assembled chambers
  - Including pums,gauges,valves
- Back-out
- Align BPM's & chambers
- Close magnets
- Final alignment check

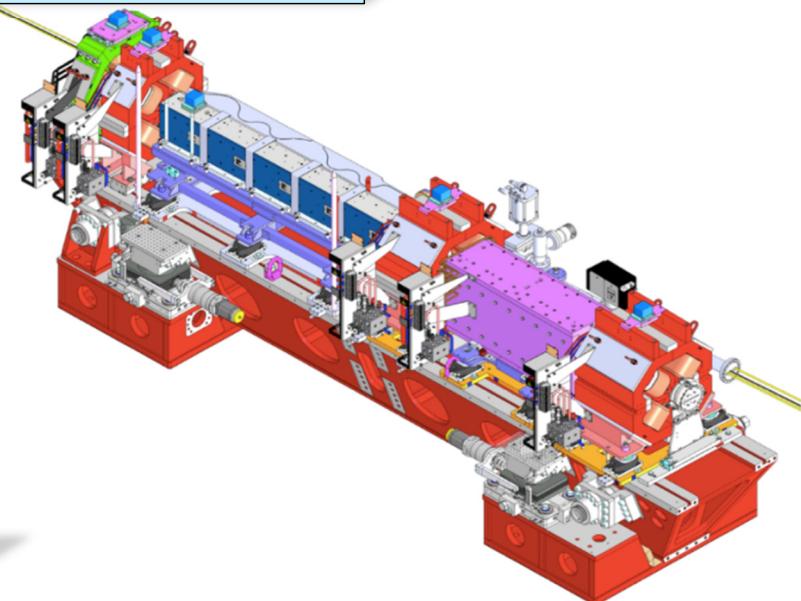
Then:

Dismantle the present ring (including cabling, fluids)

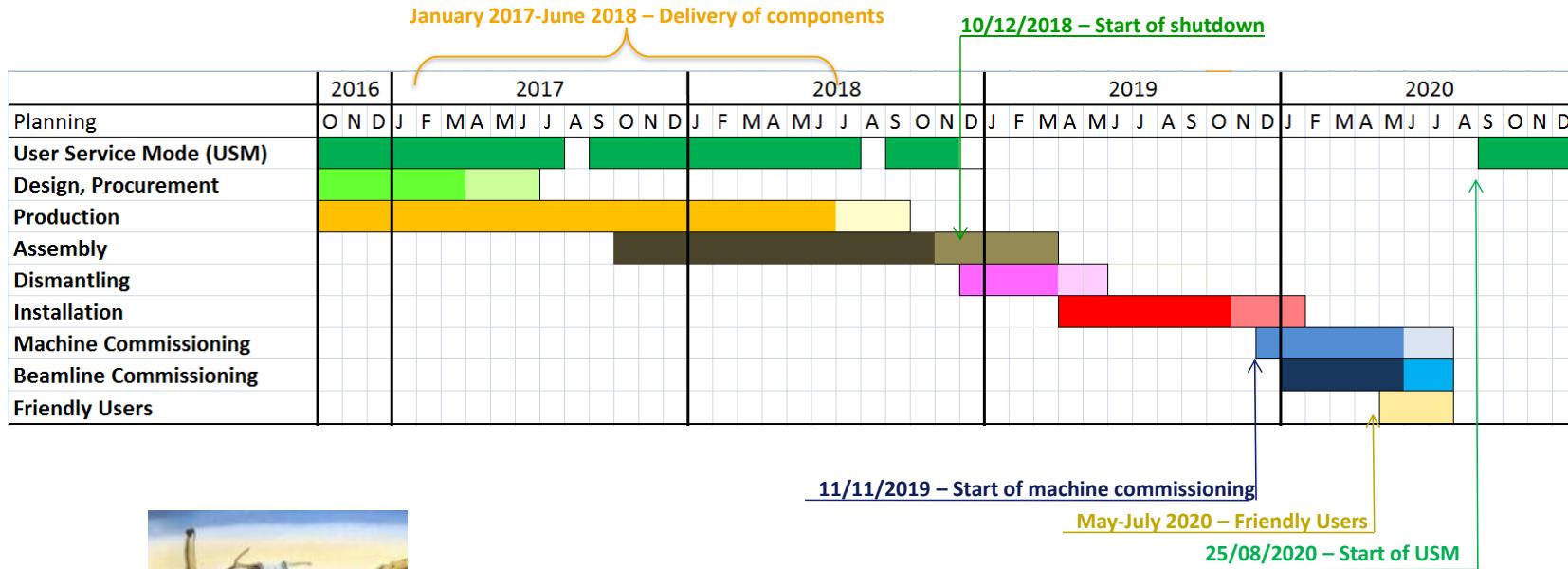
Roll the 129 newly assembled girders in the tunnel

Recable, install cooling and fluids...

Switch ON... and hope...



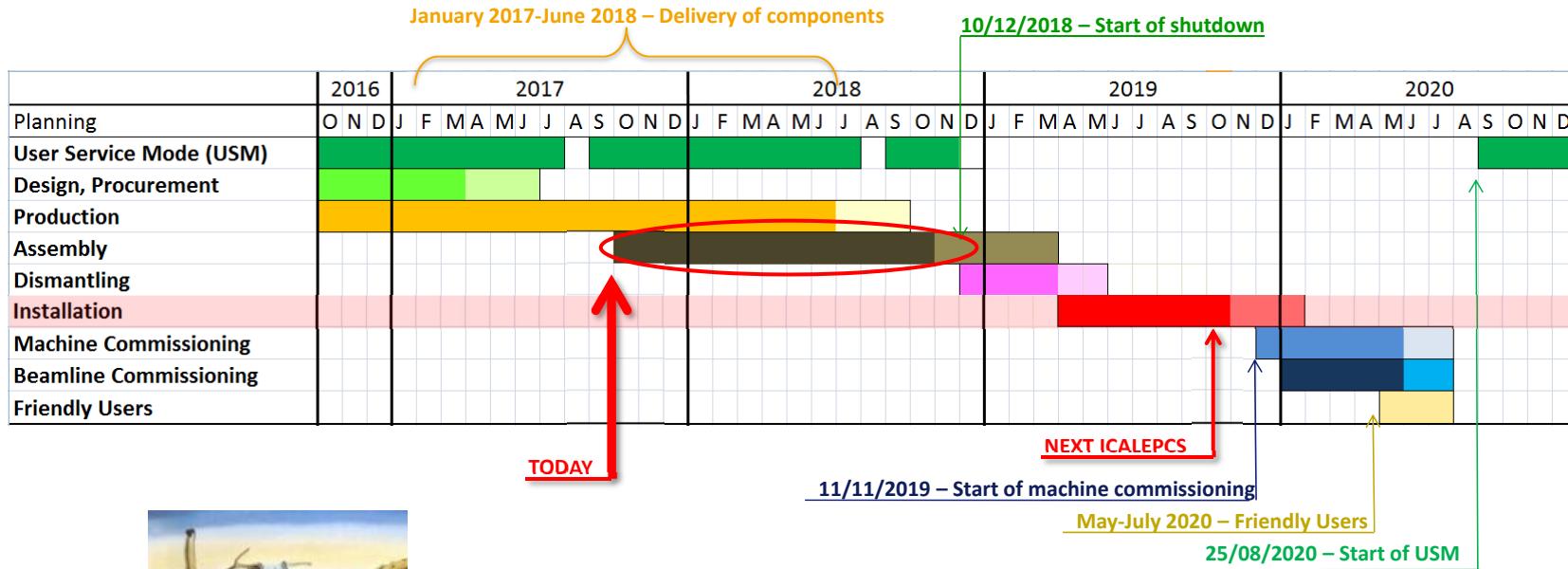
# EBS time line (2016-2020)



**Until 10 December 2018**  
**10 December 2018**  
**13 December ->April 2019**  
**11 March 2019 -> October**  
**11 November 2019**  
**02 March 2020**  
**25 August 2020**

**Standard ESRF User service Mode**  
**Start of the long shutdown,**  
**Dismantling**  
**Installation**  
**Commissioning starts**  
**Beamline commissioning starts**  
**EBS User Service Mode**

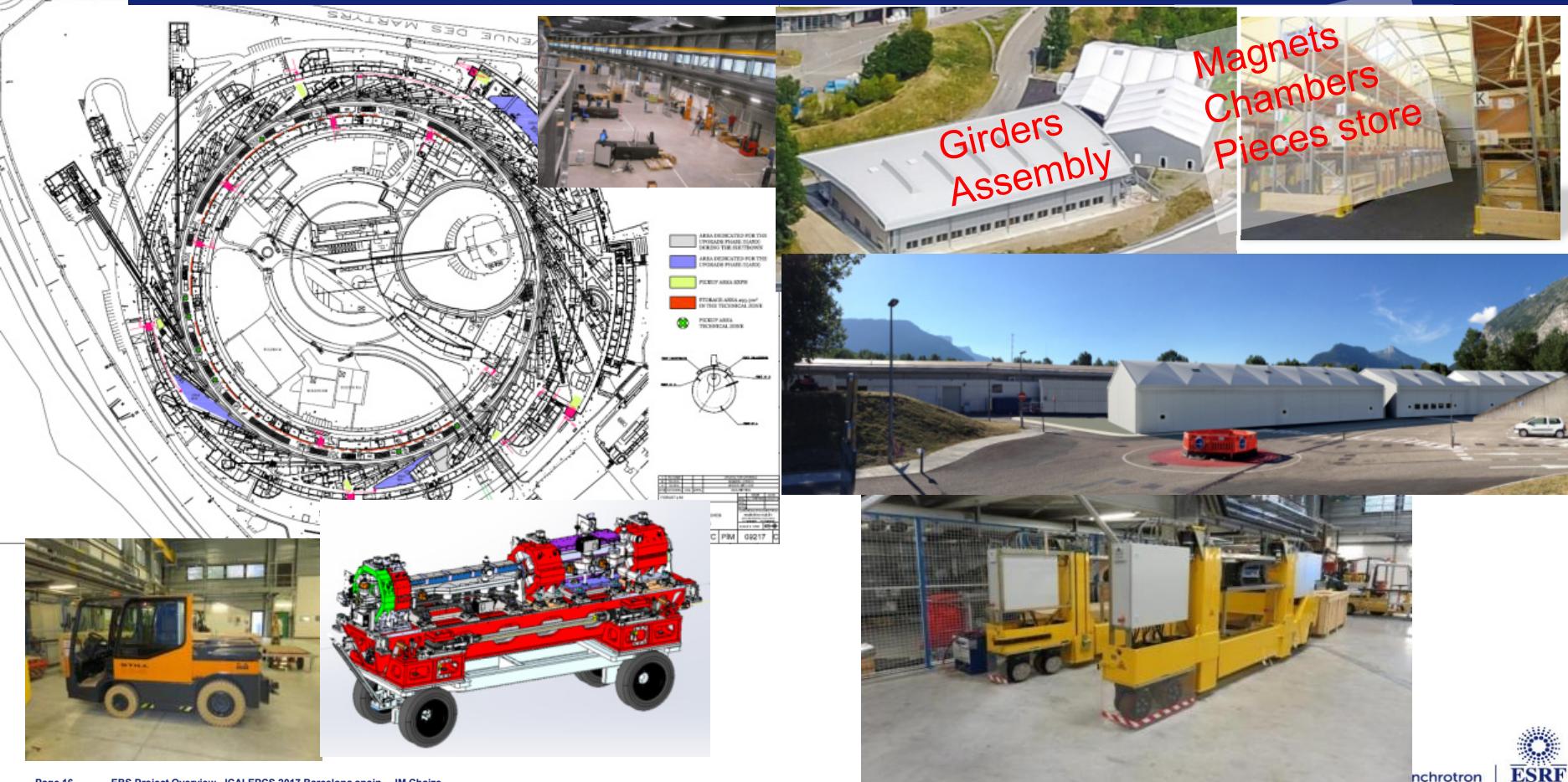
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# Need huge surface: New Buildings for Assembly, Storage, dismantling.



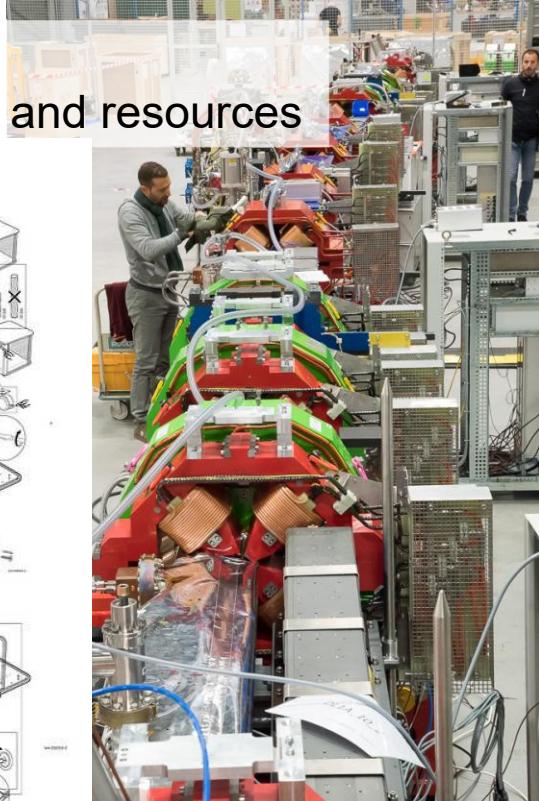
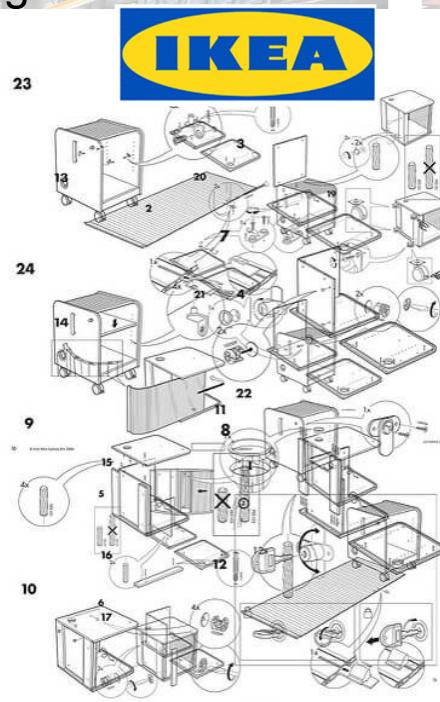
# The Mock-Up in the Chartreuse Hall



# The Mock-Up in the Chartreuse Hall



Build and test assembly procedure  
Verify good mounting and measure time and resources



# Control system



# Management of Obsolescence

- The EBS new control should be plugged on the injector

- A large part of equipment and electronic interfaces reused
  - *Linac, transfer lines, booster, Safety systems, Insertion devices, Vacuum control*
  - *Keep running until end of 2018. cannot be interrupted.*
- Need a system able to operate old and new devices together
  - *Interconnect different generation of software/hardware*

- Management of obsolescence is a permanent issue.

- There is no way to stay immobile, the landscape is moving
- Should go faster than the landscape (at least!)
- Hand-shaking necessary between incompatible stuff.



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  - Operating systems sometimes imposed by the market
    - No way to install old OS on new hardware
    - No way to change OS when closed source drivers are used
    - Windows-XP systems should co-operator with various linux distrib

- Choice of a conservative approach

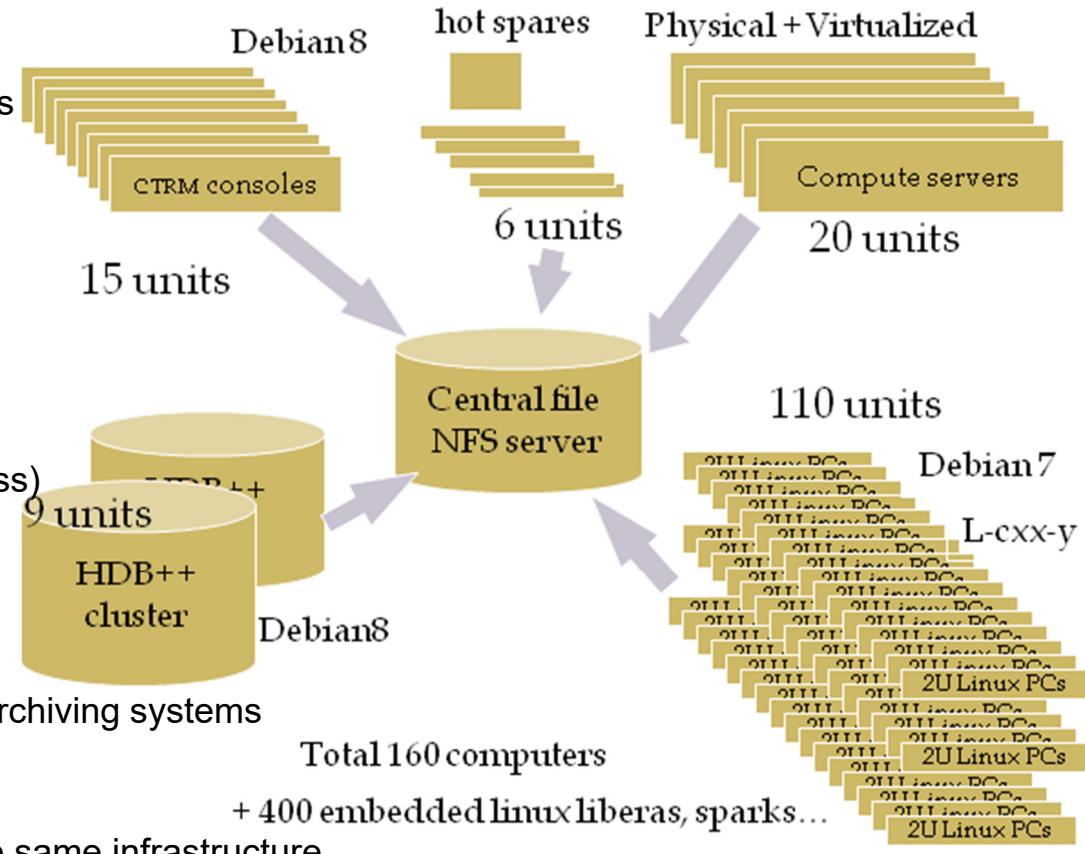


# Control System architecture

Big increase of Ethernet connected devices  
Power Over Ethernet  
Embedded devices  
I/O boards  
Field Busses replaced by Ethernet  
VME disappears  
Only Linux, few units in Windows

Keep physical I/O computers (quasi diskless)  
*No software packages on it, use NFS  
easy exchange with generic spares*

Virtualise servers in CTRM (KVM)  
No virtualization for CTRM consoles and archiving systems  
NFS infrastructure may be conservative  
Simple and efficient  
Allow old and new hardware to use the same infrastructure

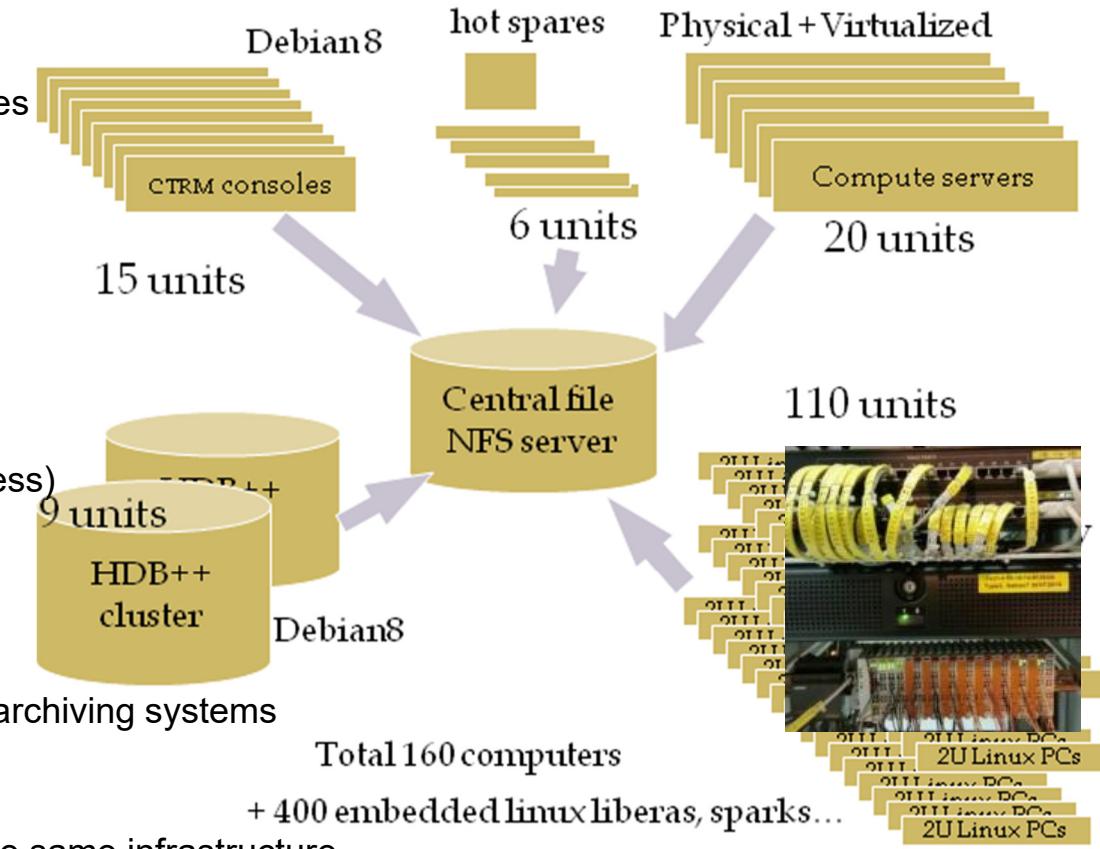


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# Ethernet becomes more and more critical

## The Ethernet network becomes the heart of the control system

Field bus -> Ethernet

I/O boards (e.g. PCI boards) -> Ethernet based remote I/O

VME systems -> Set of different dedicated embedded systems connected to Ethernet

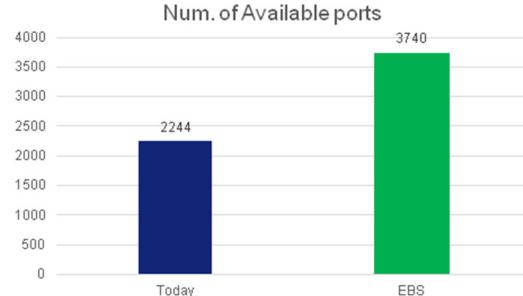
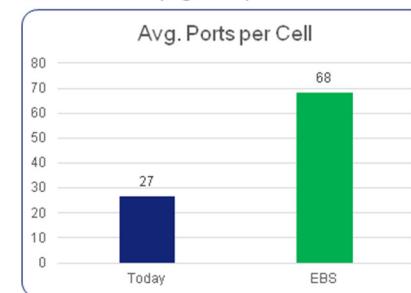
Serial lines -> Ethernet

Many Power Over Ethernet

(Gb ethernet cameras, power converters, bpms)



Identified needs (figures)



Ethernet monopoly for communication

must be highly reliable

Choice of Redundant PS, 48VDC + 230VAC

PoE+

PoE management integrated to control system software

# Software framework

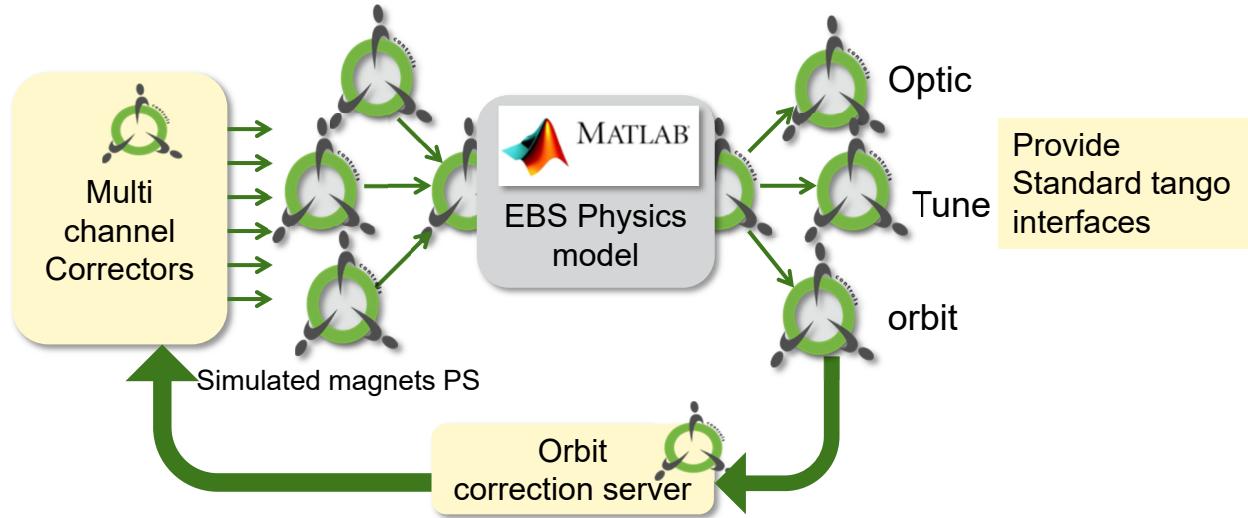


Connecting things together

- Need to manage heterogeneity
  - Operating systems, software versions, drivers,
- Need to manage high number of equipments
  - > 350000 sensors+actuators
- Tango is well adapted
  - Good scalability
  - No bottleneck
    - Thanks to massive distribution of micro services
  - Excellent management of heterogeneity
  - Live community, well organized, long term **sustainability**
    - Benefit from development done in other institutes and industry support

# EBS simulator

Simulates the accelerator and low level control  
Integrated to **TANGO** control system as a real hardware  
Middle layer and GUI developed on it



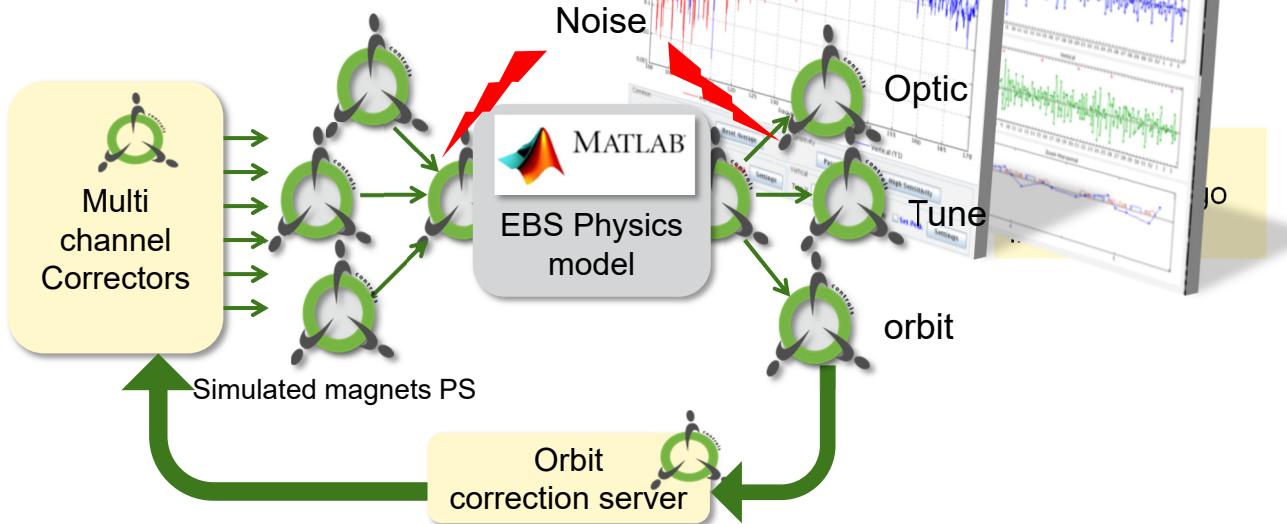
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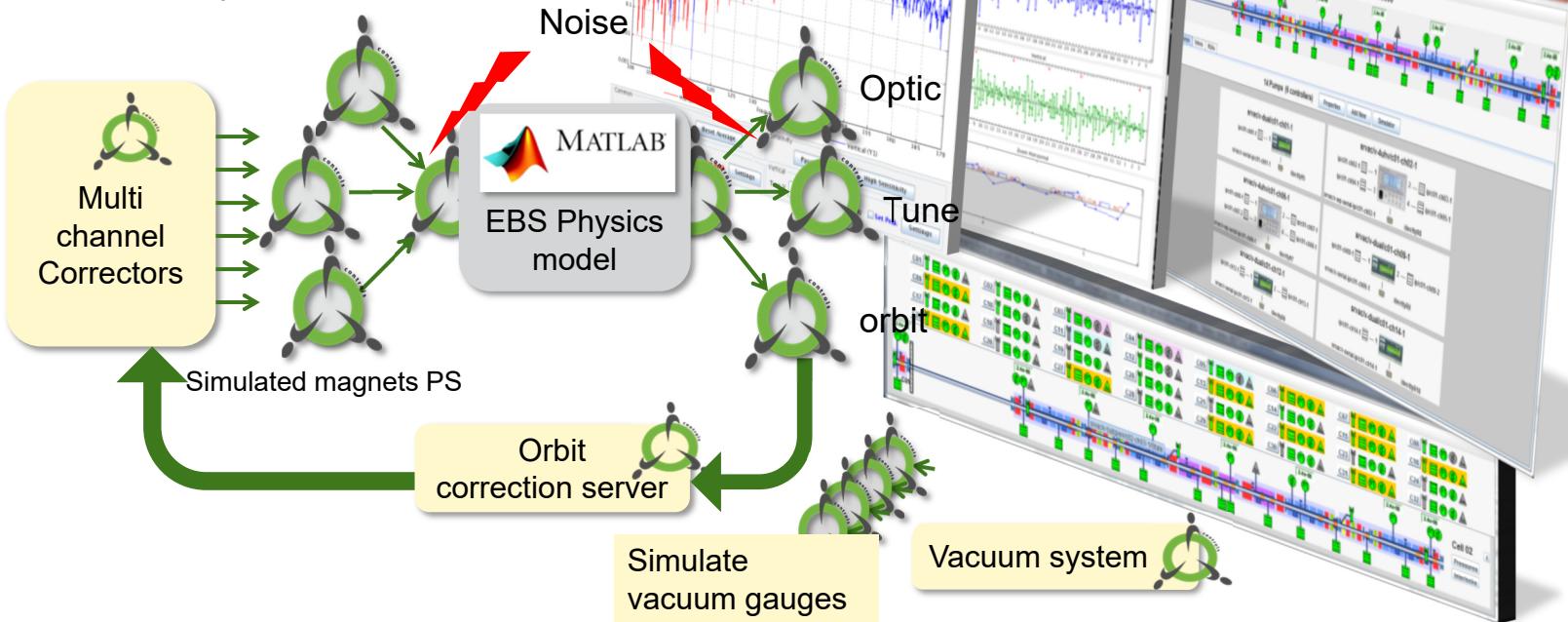
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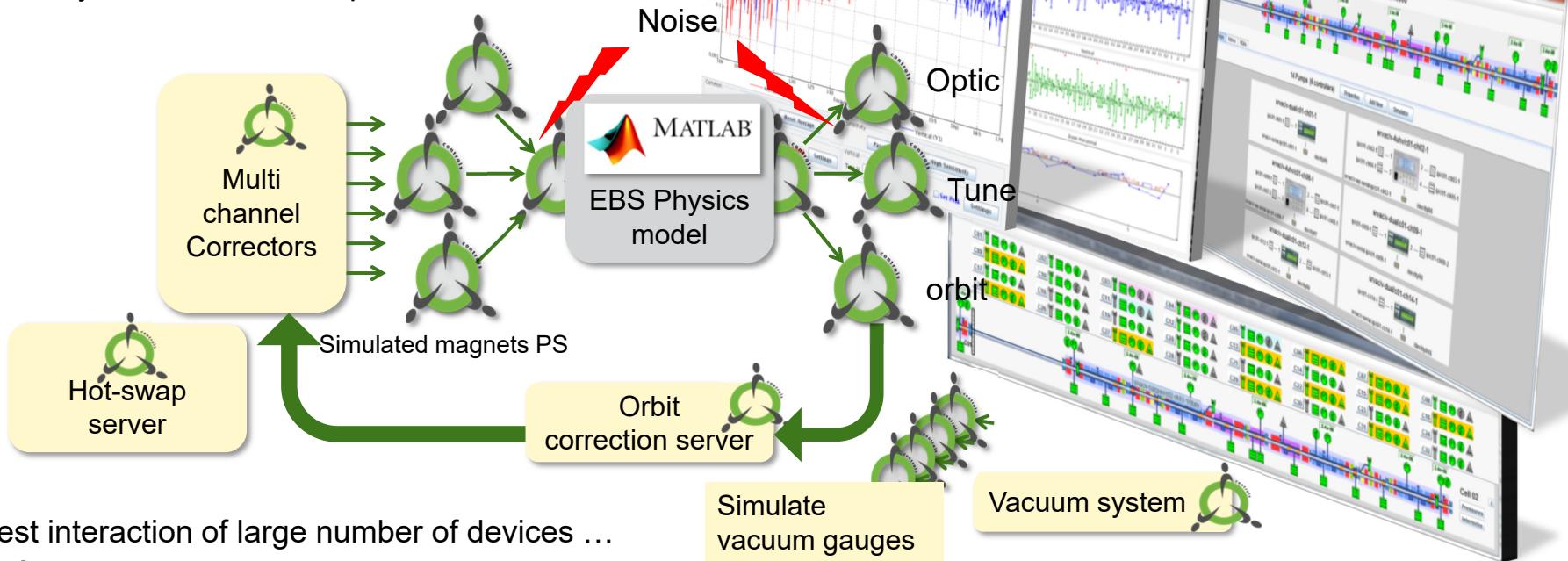
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Test interaction of large number of devices ...

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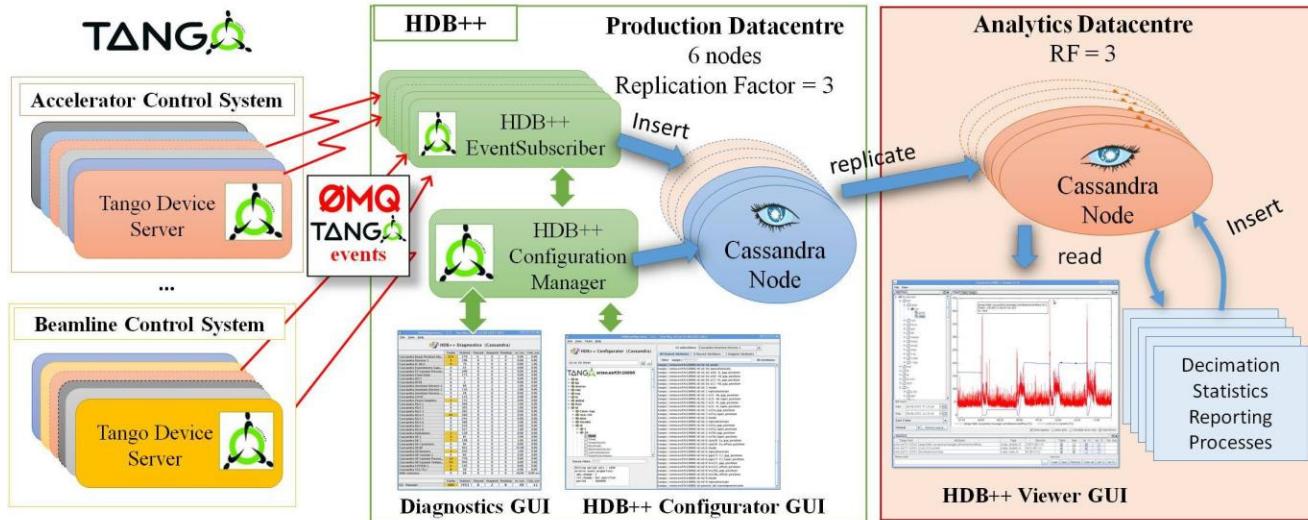
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# A new New Archiving System

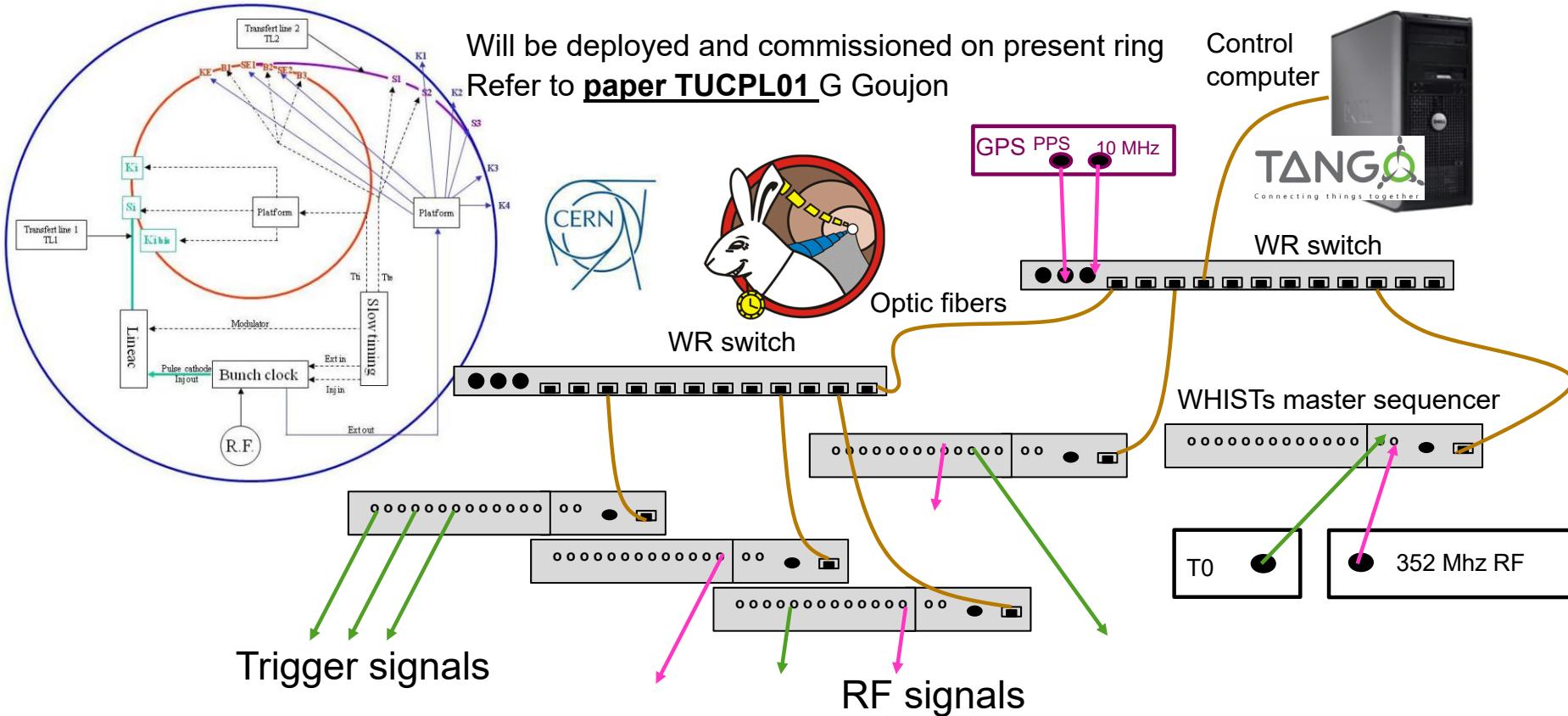
Operational on present ring

Refer to [paper TUCPL01](#) L. Pivetta

	former HDB	HDB++
<b>Time precision</b>	1 s	1 $\mu$ s
<b>Insertions/hour</b>	120K	6M
<b>Filling mode</b>	Polling/events	events
<b>No. Signals total</b>	6K	24K/56K
<b>Beam line signals</b>	2K	10K
<b>Extraction tools</b>	C GUI	Java /Python / Matlab / web
<b>Database size</b>	0.5TB/y	20TB/y
<b>Online capacity</b>	9 months	Unlimited
<b>Database</b>	Oracle	Cassandra

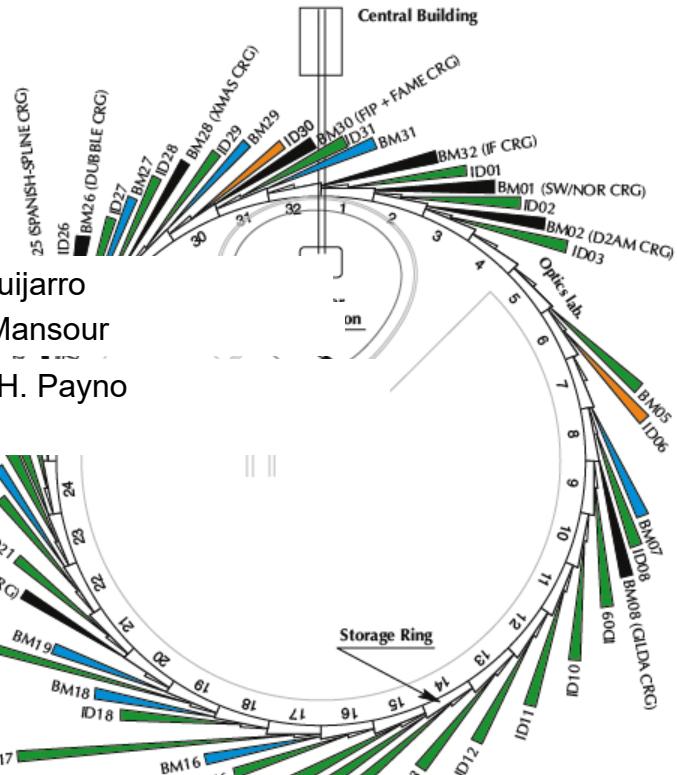
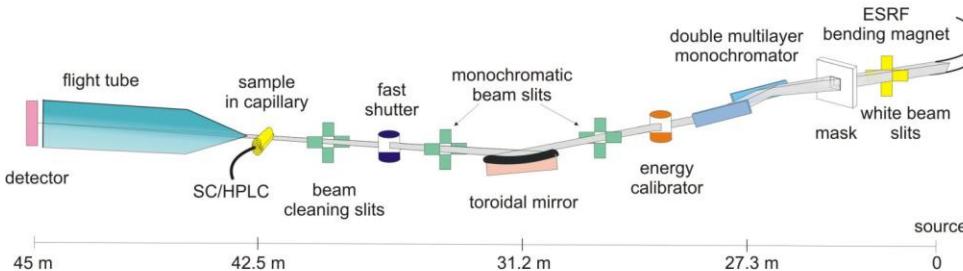


# New synchronization system



# Experiment control & detector development

- 14 beamlines refurbished
- 4 new beam lines to construct
- Prepare the acceptance of much more photons
  - Higher data throughput to manage
  - Higher thermal effects
- New experiment control system (BLISS) Refer to [WEBPL05](#) M. Guijarro
- Ambitious detector development program Refer to [THBPL06](#) W. Mansour
- Ambitious Data analysis software framework Refer to [TUPHA183](#) H. Payneo  
[THPH039](#) J Kieffer



Many thanks for your attention

More news at next ICALEPCS

