SKA Systems Engineer

SQUARE KILOMETRE ARRAY



Exploring the Universe with the worlds' largest radio telescope



16th International Conference on Accelerator and Large Experimental Physics Control Systems





SKA Key Science Drivers: The history of the Universe

Testing General Relativity (Strong Regime, Gravitational Waves)

Cradle of Life (Planets, Molecules, SETI)

Broadest range of science of any facility, worldwide

Cosmic Magnetism (Origin, Evolution)



Cosmic Dawn (First Stars and Galaxies)

> Galaxy Evolution (Normal Galaxies z~2-3)

Cosmology (Dark Energy, Large Scale Structure)

Exploration of the Unknown









SKA Observatory Vision

3 sites 2 telescopes 1 observatory

Design Phase: ~ €200M; 600 scientists+engineers, 80% complete

MeerKAT integrated

Observatory Development Programme (€20M/year planned)

SKA Regional centres out of scope of centrally-funded SKAO.

>50 years lifetime!

Drives need for reliability, and adaptability

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SKA Phase 1 (SKA1) Construction: 2019 – 2025 Construction cost cap: €674.1M (2016 inflation-adjusted)

Operations cost: (estimate) €89M/yr

SKA Phase 2: start mid-2020s

~2000 dishes across 3500km of Southern Africa

Major expansion of SKA1-Low across Western Australia



SKA Organisation

- Mustralia (Dol&S)
- Canada (NRC-HIA)
- China (MOST)
- India (DAE)
- Italy (INAF)
- Netherlands (NWO)
- New Zealand (MED)
- South Africa (DST)
- Sweden (Chalmers)
- ₩ UK (BEIS/STFC)





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In discussion with:

- Germany
- **France**
- Portugal
- **Spain**
- Switzerland
- Japan
- South Korea

In the process of becoming an Inter-Governmental **Organisation**

African partner countries (non-member SKA Phase 2 host countries)

This map is intended for reference only and is not meant to represent legal borders

SKA1 Design Consortia







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LOW-FREQUENCY APERTURE ARRAY









INFRASTRUCTURE SOUTH AFRICA

SKA1 Design Consortia











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SQUARE KILOMETRE ARRAY MID-FREQUENCY APERTURE ARRAY









SKA1 Sites









SKAI-LowSite

300 km

Murchison Radio Astronomy Observatory

Murchison Radio-astronomy Observatory

Geraldton Geraldton

Perth

Pawsey Supercomputing Centre Pawsey Supercomputing Centre





KALENTED STEE

SKA1-Mid site (Karoo dessert)

SKA1-Mid site (Karoo dessert) Carnarvon Carnarvon

Canarvon

500 km

Cape Iown

Cape Town

Google Earth





SKA1 Telescopes



SKA1-Mid Report

80 µm – 110 µm RMS

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Surface RMS 350 micron

SKA1-Mid Report MeerKAT

MeerKAT

49/64 antennas built

330.5°

SKA1-Low Report

Exploring the Universit

SKA1-Low Report

SKA HQ2 Aerial View

Lovell 70m

Building a Nexus for Radio Astronomy

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Council Chamber

Existing building

SKA1 Notional Data Flow

SKA Regional Centres

- Collaborative alliance
- Transparent and location agnostic interface to SRCs for users
- SKA users should not care where their data products are
- All SKA users should be able to access their data products, irrespective of whether their country or region hosts a regional centre

SKA Regional Centre Alliance

SKA Regional Centres

- SKA Regional Centres (SRCs) will host the SKA science archive
- Provide access and distribute data products to users
- Provide access to compute and storage resources
- Provide analysis capabilities & user support
- Multiple regional SRCs, locally resourced and staffed

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SKA Regional Centre Alliance

SKA Control: TANGO

Talk by Lorenzo Pivetta Decided in March 2015 MOBPL03

- Control Harmonisation Project started March $2016 \rightarrow CS_Guidelines$
- Good uptake from the community
- INAF, SKA SA, and SKAO are now members of the TANGO Controls Organisation

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TANGO is the collaborative effort of many people. It is a free open source project i.e. the source code is available under GPL and LGPL open source licences (on tango-cs and tango-ds on SourceForge) and it can be downloaded and modified by anybody. ANyone can send a patch with their changes but changes to the official source code are done by authorised developers. If you want your modifications to be included then send them to the TANGO Controls mailing list. TANGO Controls started at the ESRF but has since then been adopted by a number of sites. The following sites have committed to the sustainable development of TANGO Controls by signing a Collaboration Contract and committing to financing the development of TANGO:

SKA1 Control Hierarchies

SKA1-Low

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SKA1-Mid

Integrating TANGO Facilities

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Focus on diminishing global, cross-facility traffic

Use of logviewer tools, and potential for viewers direct to the devices, but most monitoring in remote

> **Slide courtesy** Lorenzo Pivetta

How to develop all this software?

Agile, Scaled Agile (Framework)

SAFe[®] for Lean Enterprises

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Agile Teams, 5-7 people (including Scrum Master), ±2 people

Agile Release Trains (ARTs) in Definition

Architectural Runway → Emulation & Simulation

Large Solution SAFe

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CERN-SKA Agreement

10

SKA Treaty Organisation

SKA Organisation member governments agreed in 2015 to develop an **Intergovernmental Organisation (IGO)**

- Rationale:
 - Appropriate for a genuinely global research analogous to successful IGOs such as infrastructure of SKA's scale ESO, EMBL, CERN
 - Government commitment: political stability, funding stability
 - A level of independence in structure
 - Availability of 'supporting processes' through Privileges and Immunities from members: functional support for project
 - 'Freedom to operate', specifically through procurement process, employment rules etc

• We are building an organisation

- Negotiations started October 2015 four Plenary meetings led by Italian government;
- Expect Convention to be signed December 2017, ratified 12 months later

SKA Timeline

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Prospective 'new' Members/A. Members/Cooperating bodies

Conclusion

SKA is happening

- Excellent technical progress
- Prototypes being constructed and deployed
- Cost control effective
- Inter-Governmental Organisation proceeding
- Construction will begin in 2019; operations in mid-2020s

The future?

- SKA time will be allocated to those who contribute to both construction and operations
- Young, vibrant community across the world
- Using industry-standard safe approaches, like SAFe and TANGO in constructoin

Code	Author	Organisation	Title
MOAPL3	Lorenzo Pivetta	SKAO	SKA
TUBPA06	Francois Joubert	SKA SA	Scal
TUCPL01	Paul Boven	JIVE	Whit
TUDPL03	Athanaseus Ramaila	SKA SA	Cont and
THAPL03	Valentina Alberti	INAF-OAT	Usak User
THBPA04	Anton Joubert	SKA SA	Orch Pipe
THCPL04	Ralph Braddock	UMAN	SKA Desi
THSH201	Athanaseus Ramaila	SKA SA	Integ Tran
FRAPL01	Juande Santander-Vela	SKAO	Statu

And SKA precursors & pathfinders!

- **Control System Guidelines**
- able Time Series Documents Store
- te-Rabbit for Radio Astronomy
- trol System Simulation Using DSEE High Level Instrument Interface Behavioural Description
- bility Recommendations for the SKA Control Room Obtained by a r-Centred Design Approach
- nestrating MeerKAT's Distributed Science Data Processing
- Synchronization and Timing Local Monitor and Control Software ign Approach
- gration of MeerKAT and SKA telescopes using KATCP <-> Tango slators
- us of the Square Kilometre Array

Author	Organisation	Title
Matteo Canzari	INAF-Teramo	Usin Man
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C. R. Haskins	CSIRO-ATNF	Dian
L.R. Brederode	SKA SA	Mee
Rajesh Warange	NCRA/TIFR	SKA Stati
Francois Joubert	SKA SA	Distr grati
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And SKA precursors & pathfinders!

ng of Artificial Intelligence in the Predictive Model of the Fault nagement of SKA Telescope Manager

- SKA Dish Local Monitoring and Control System
- AP: From Construction to Operation
- Service: An Architecture for Monitoring and Controlling the SKA scope Manager
- llenges and Solutions for the SKA TM Architectural Team
- noniCA: EPICS and Open-Source Data Analytics Platforms
- erKAT Project Status Report
- Synchronization and Timing Local Monitor and Control Project us
- ributing Near Real-Time Monitoring and Scheduling Data for Inteion With Other Systems at Scale

Code	Author	Organisation	Title
THPHA142	Alessio Marassi	INAF-Trieste	The Test
THPHA164	B. Xaia	SKA SA	Auto Mee
THPHA168	Rajesh Warange	NCRA/TIFR	Docł

And SKA precursors & pathfinders!

SKA Dish SPF and LMC Interaction Design: Interfaces, Simulation, ing and Integration

mated Software Testing for Controlling And Monitoring the rKAT Telescope

kers With TANGO – Control System Approach for SKA

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Thanks

f Square-Kilometre Array 🔰 @SKA_telescope 🔉 You Tube The Square-Kilometre Array –

www.skatelescope.org

Subarray State Machine

