

# Femtosecond Timing System in SSRF

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2015.10

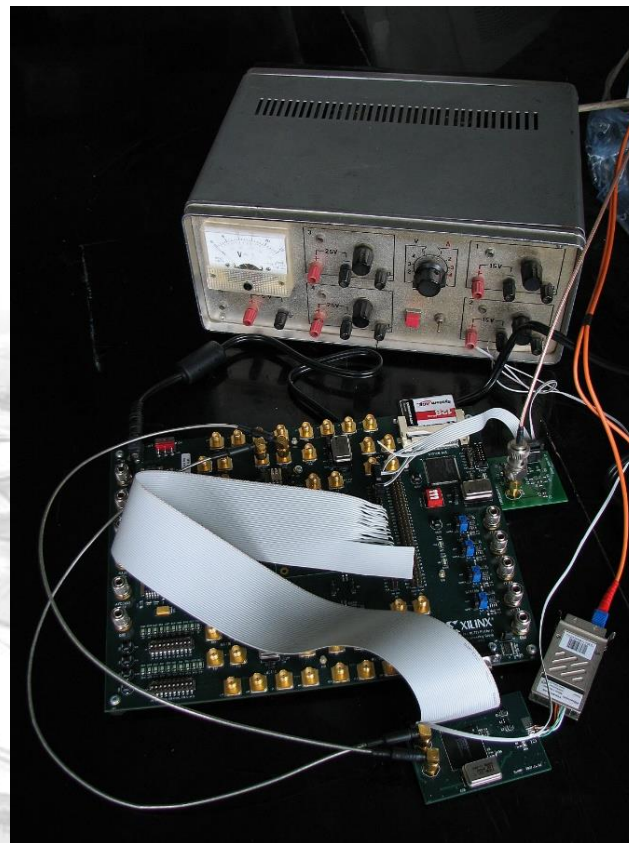


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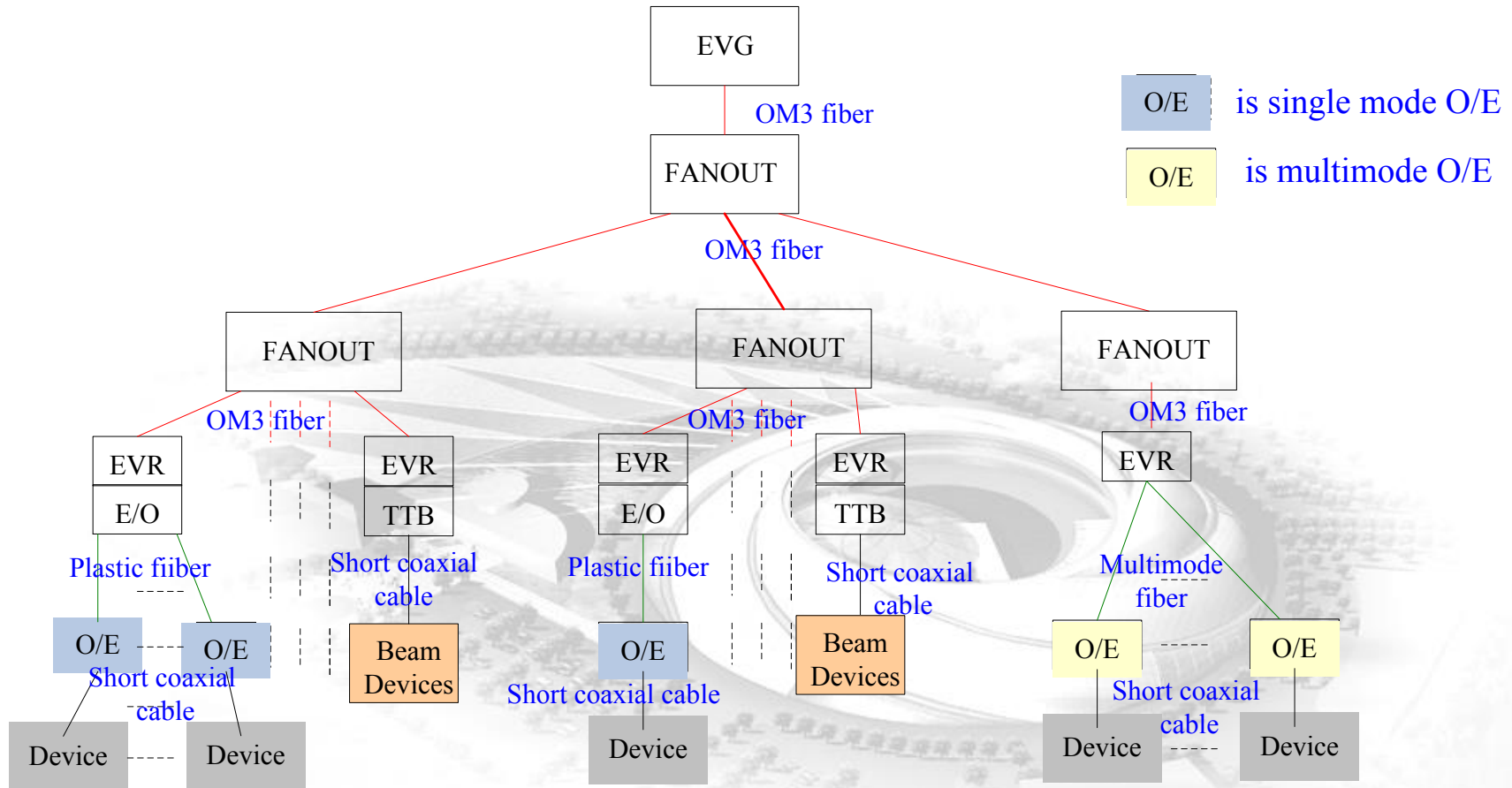
# Review of SINAP timing system development

- First EVR prototype based on 1Gbps optical fiber.

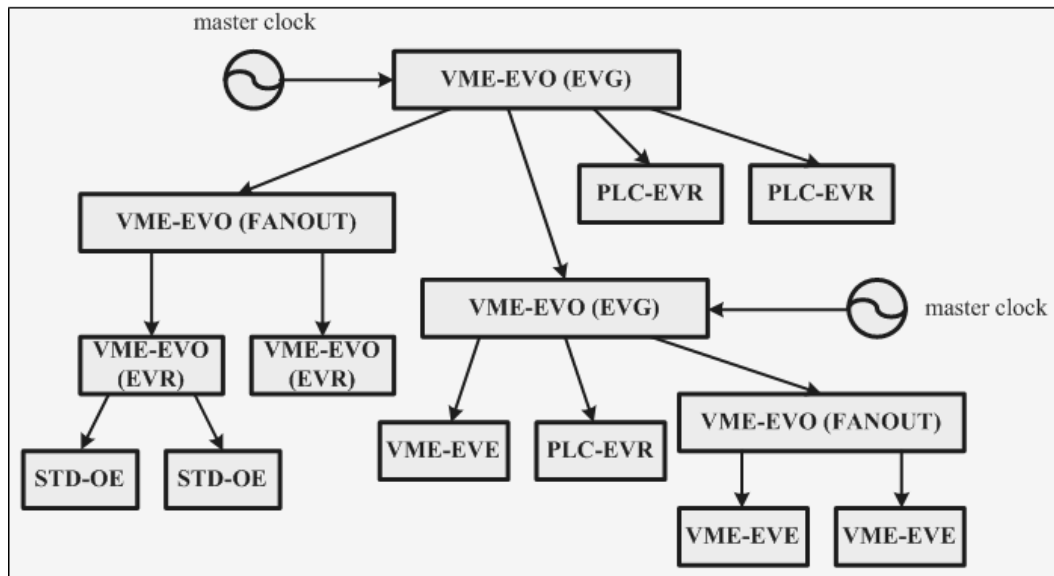
(2007)



# SINAP V1 Timing System Structure



# SINAP V2 Timing System Structure

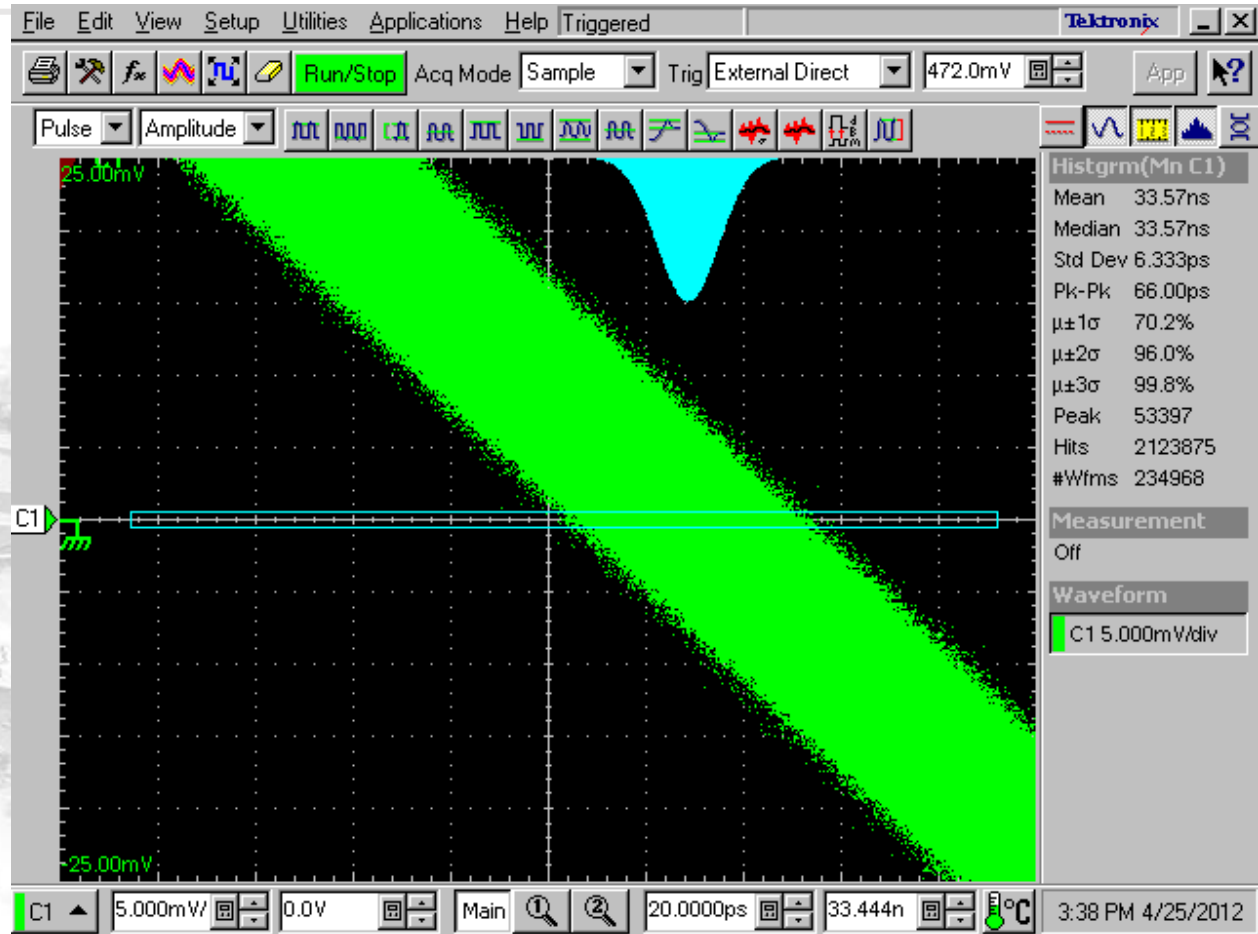




# Performance Testing in KEK LAB

- Jitter

EVE TTL output  
about 6ps



# Goal of Femtosecond Timing System

Providing RF signal and timing signal transmission with low temperature drift and low jitter for the experiment and the large accelerator device.

short-term jitter  
10fs

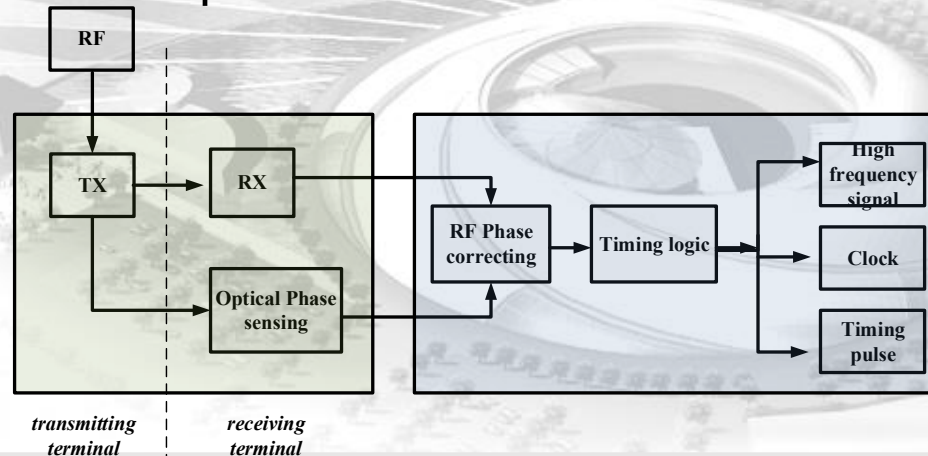
long-term temperature drift  
100fs

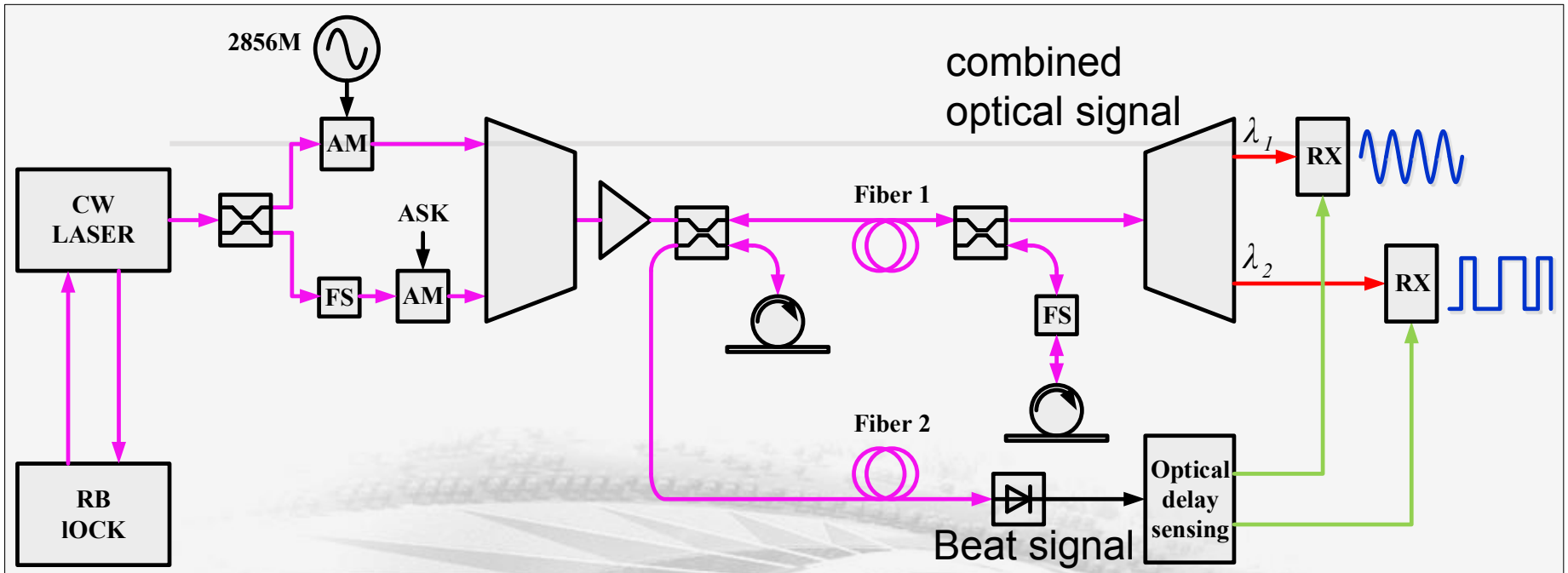
Femtosecond  
Timing System



# Femtosecond Timing System

- Based on microTCA platform.
- Electronic and optical hybrid system.
- Using ultra narrow linewidth CW laser to satisfy 10fs jitter requirement.
- To achieve femtosecond temperature drift , heterodyne interferometry is implemented to correct the phase shift.





- By implementing a wavelength division multiplexing system, the digital timing signal could be transmitted simultaneously.
- By the mode of phase detection and correction in the receiving node, whole system could be expanded.

Overcome  
long-term drift

phase detection algorithm

Improve short-  
term jitter

correction of group phase  
velocity

Digital timing  
signal  
transmission

Influence of polarization  
state on interference signal

System  
hardware  
structure

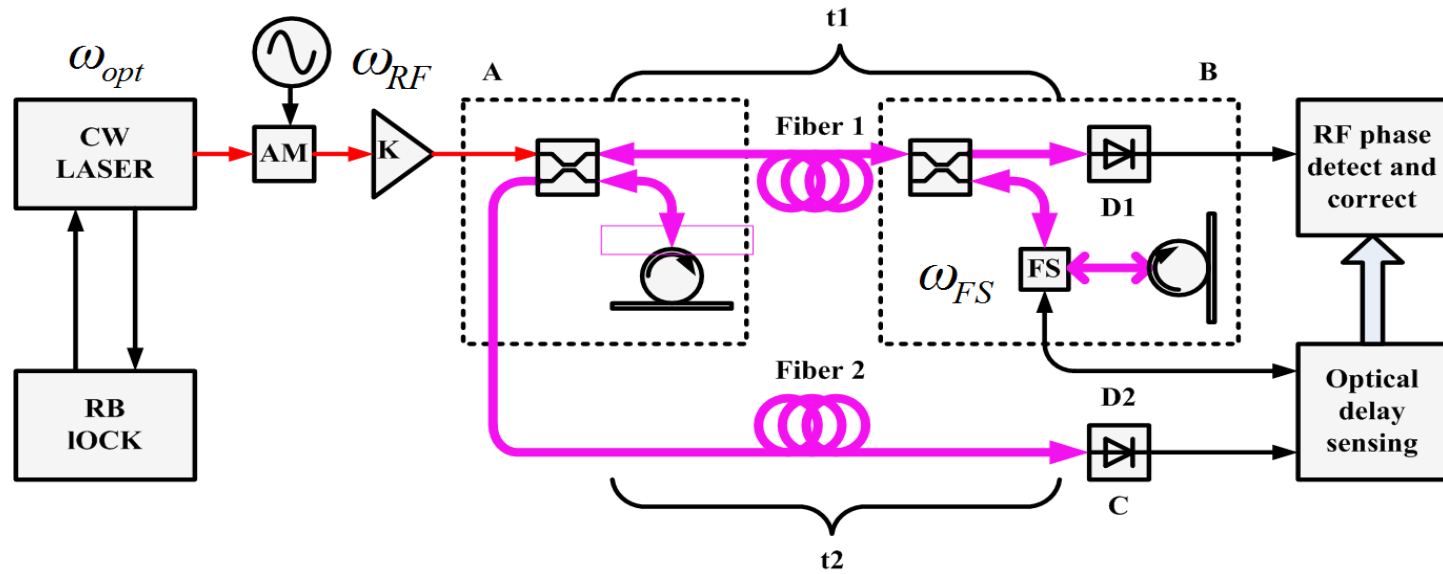


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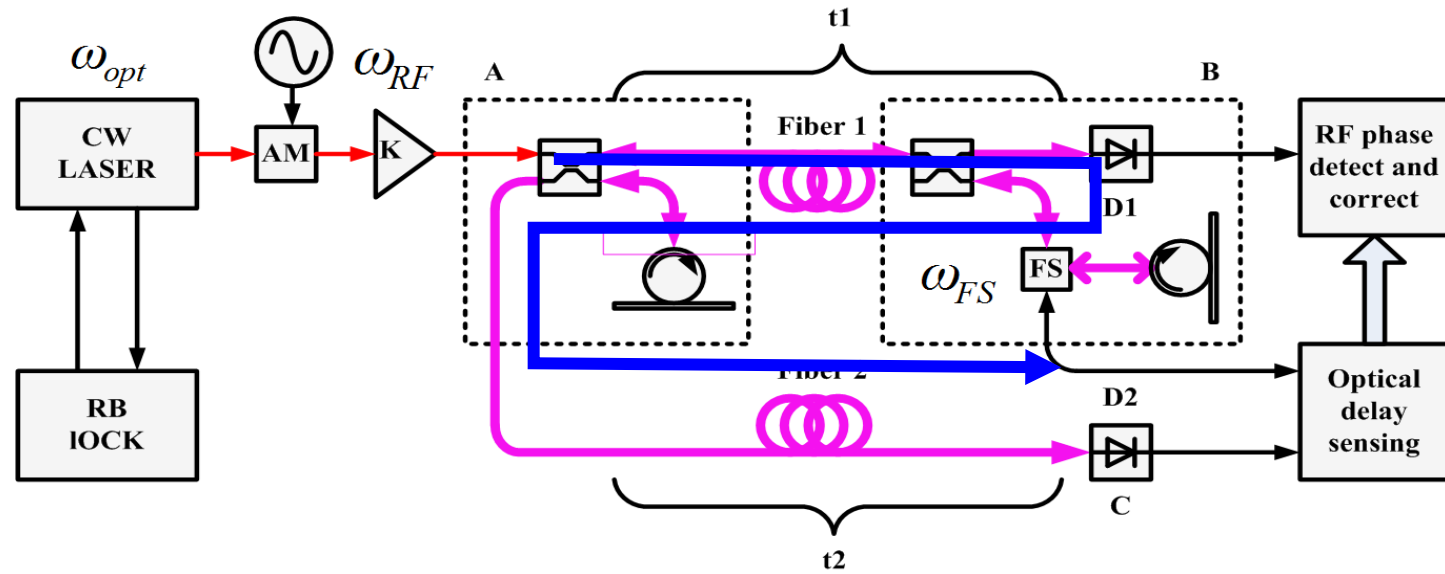
# 1. Optic Link-Phase Delay Measurement System



- Extremely high sensitivity.
- 1 deg RF=1 deg optical; 1 deg optical=0.014 fse.
- Precision: 10fs.
- frequency stability:  $1:10^9$



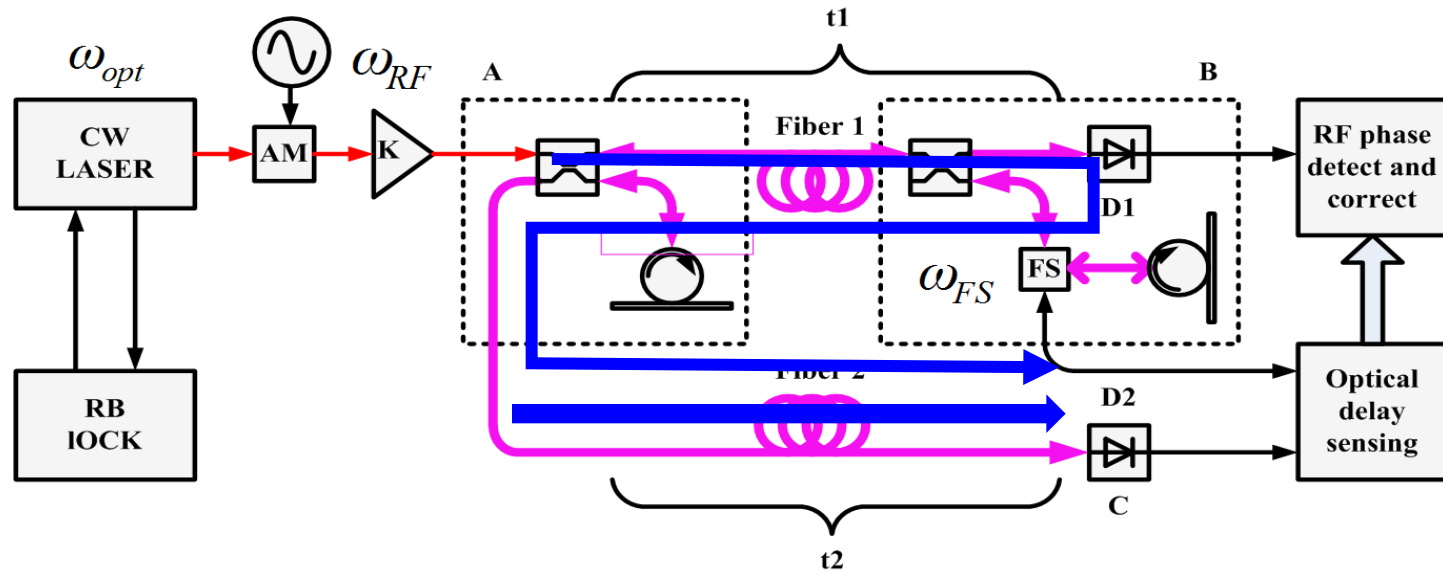
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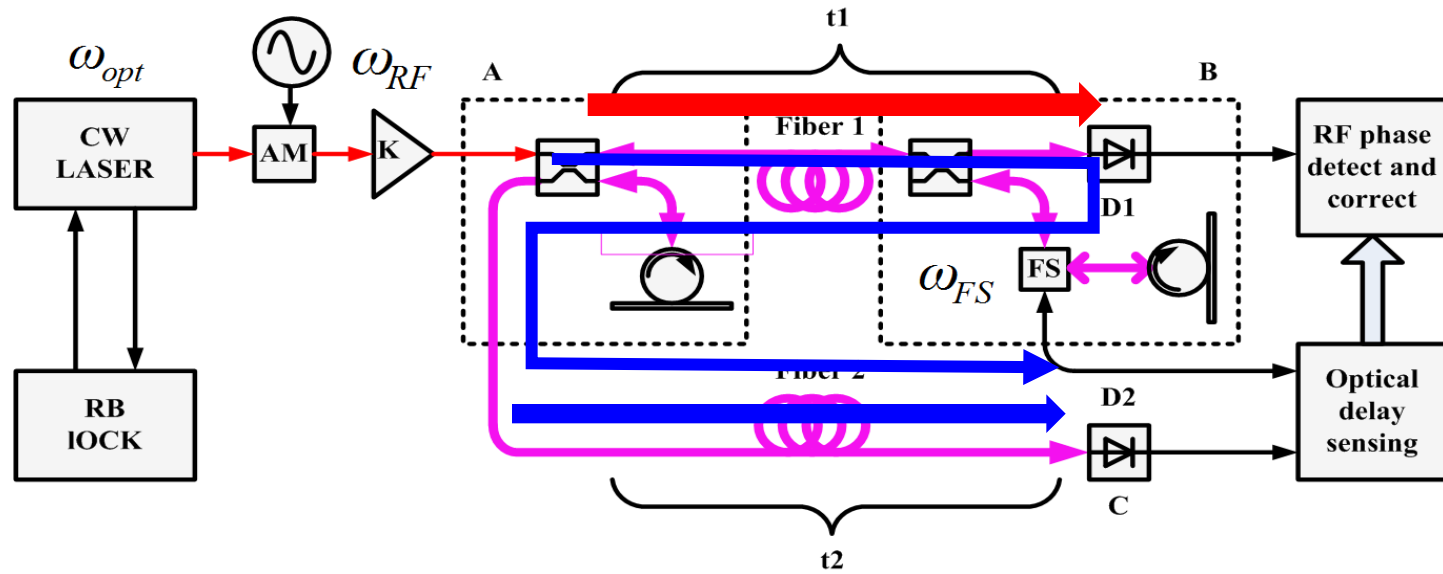
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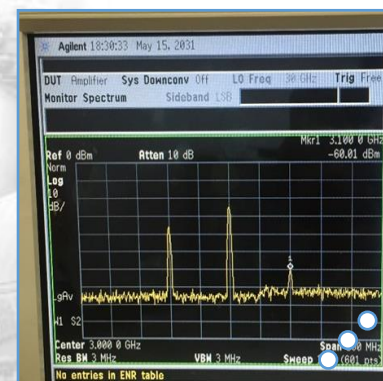
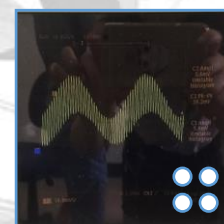
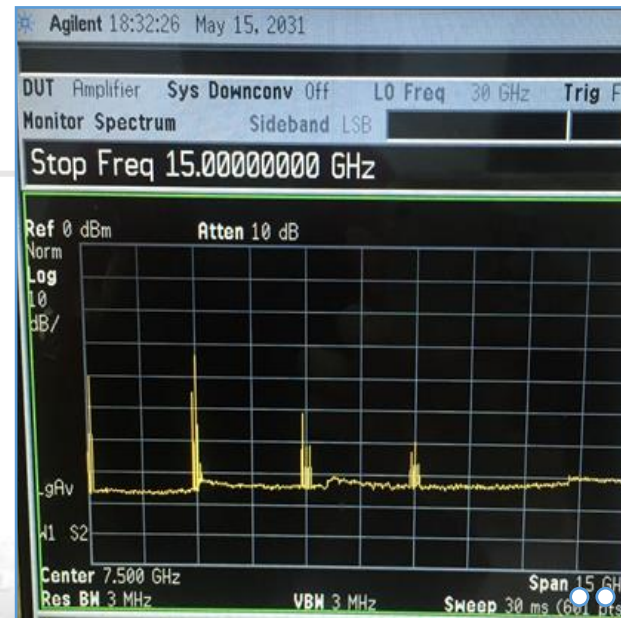
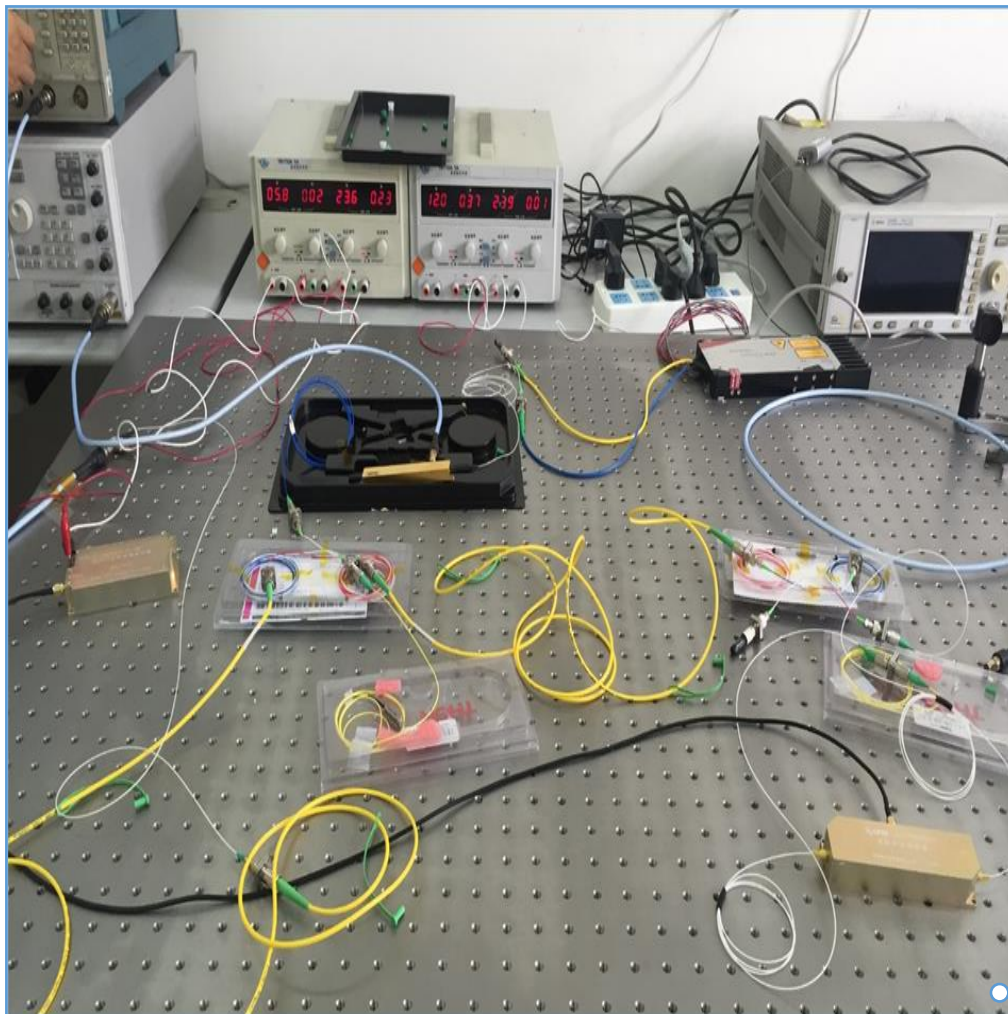


# 1. Optic Link-Phase Delay Measurement System



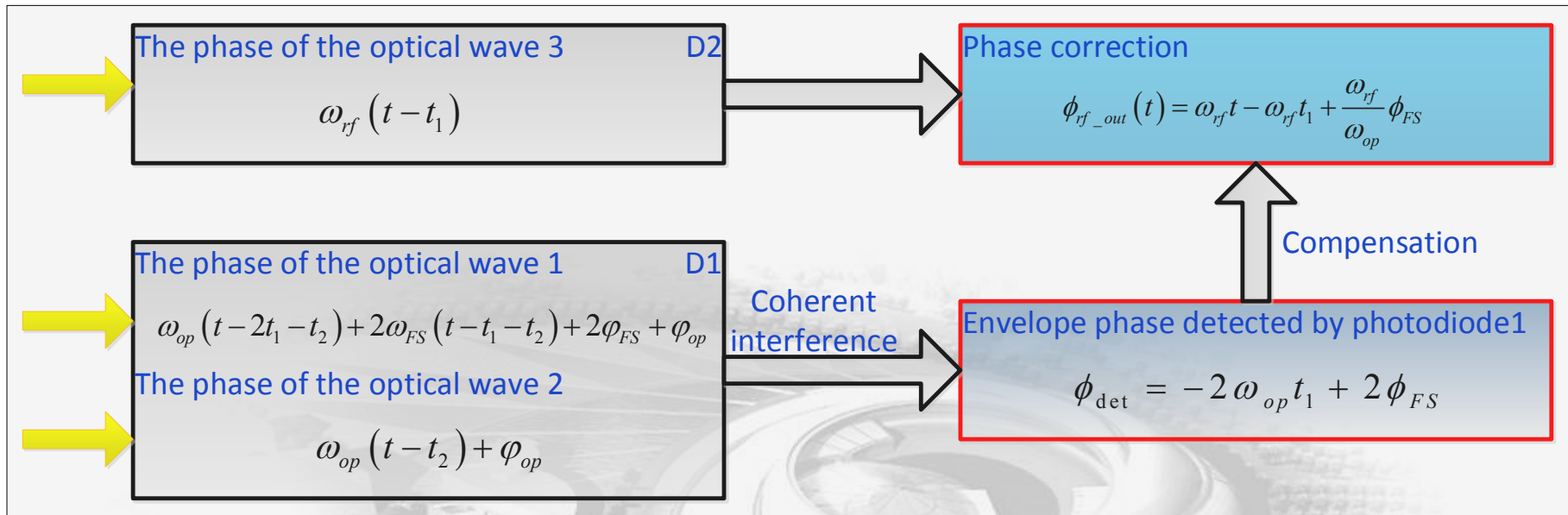
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## 2. Phase Compensation Algorithm



By controlling the size of  $\phi_{FS}$ , the additional changes brought by  $\omega_{rf}t_1$  can be offset by.





### 3. Line Width Calculation

Koheras BasiK E15 laser module, central wavelength 1560nm.

When the line width is 10KHz, the coherence length is 30 km. The coherence time is:

$$\tau_c = \frac{\Delta_c}{c} = \frac{3 \times 10^4}{3 \times 10^8} = 1 \times 10^{-4} s$$

Transmission delay of two interference signal in optical fiber arm:

$$t = \frac{2L}{v} = \frac{2 \times 2 \times 10^3}{3 \times 10^8} = 1.3 \times 10^{-5} s < \tau_c$$



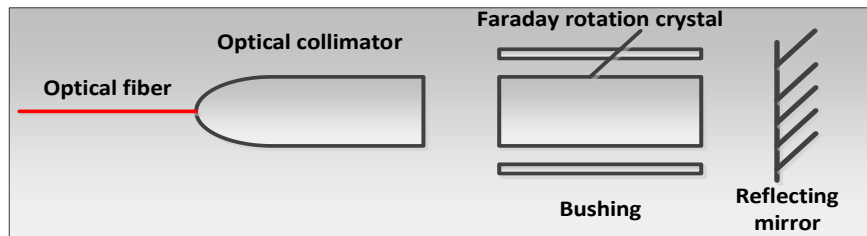
Meet the coherent condition



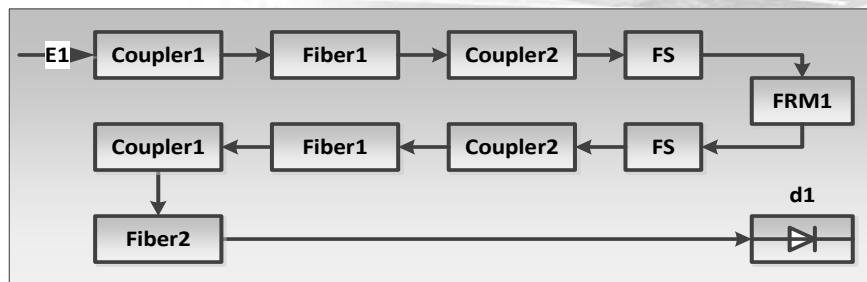
# 4. Influence of Polarization State on Interference Signal

Faraday rotation mirror  
eliminate polarization decline.

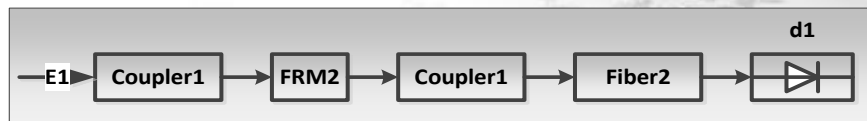
1. Faraday rotation mirror.
2. single mode fiber.
3. Laser polarization-maintaining output.



$$J = RTR' = \alpha^2 t \cdot \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$$



$$E_{19} = -\frac{j}{4} \cdot \alpha^2 t \cdot \exp(-j2(\omega_{FS}t + \phi_{FS})) \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} E_{in}$$



$$E_{23} = j \frac{1}{2} \cdot t \cdot \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} E_{in}$$



## 5. Correction of group phase velocity

The dispersion changes the phase of the amplitude modulation. This will lead to a delay in the modulation of the modulation of the RF phase in the signal transmission and the difference of the group delay.

***The difference between group delay and phase delay caused by the dispersion in optical fibers are corrected by factor  $k_{group\_phase}$***

$$\phi_{rf\_out}(t) = \omega_{rf}t - \omega_{rf}t_1 + \frac{\omega_{rf}}{\omega_{op}} \phi_{FS} \cdot k_{group\_phase}$$

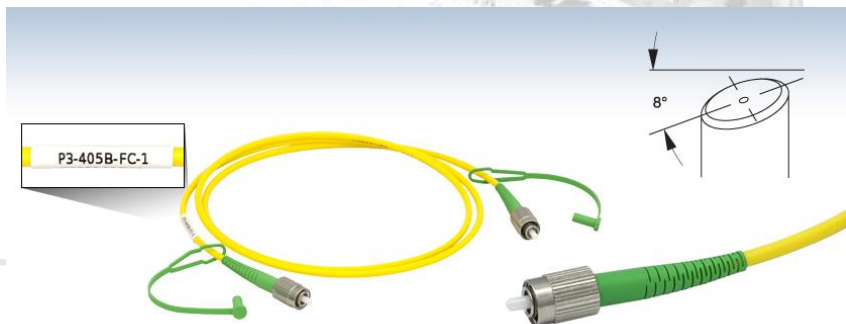
Photoelectric diode recovery RF signal in optical receiver, measure the change of group velocity, and compare to the change of optical fiber phase velocity.



## 6. optical reflection loss and temperature control

Due to the continuous nature of the signal, retroreflections anywhere in the fiber optic signal path can cause random fluctuations of the received rf signal phase. *Using APC connector and high return loss device to reduce optical reflection loss.*

In optical system, the error caused by temperature change can be eliminated. In the electronics system, *the temperature-controlled container is used to stabilize the temperature of the key parts.*



overcome  
long-term drift

Improve short-  
term jitter

Digital timing  
signal  
transmission

System  
hardware  
structure

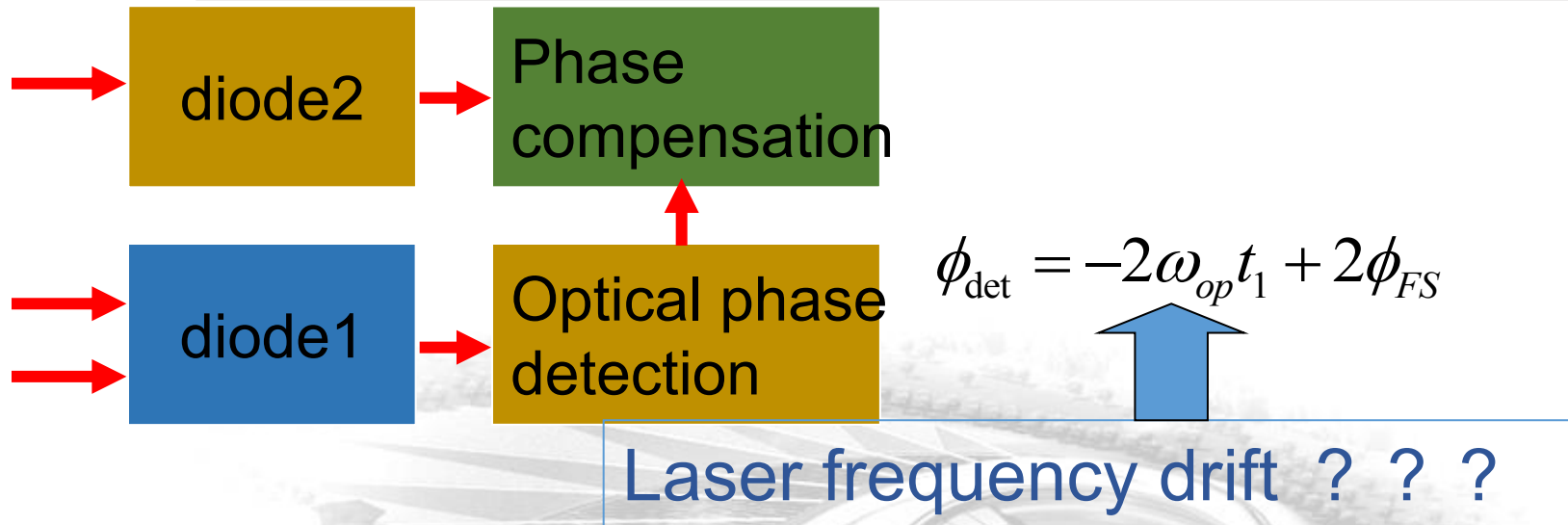
laser frequency  
stabilization

Frequency stability  
test





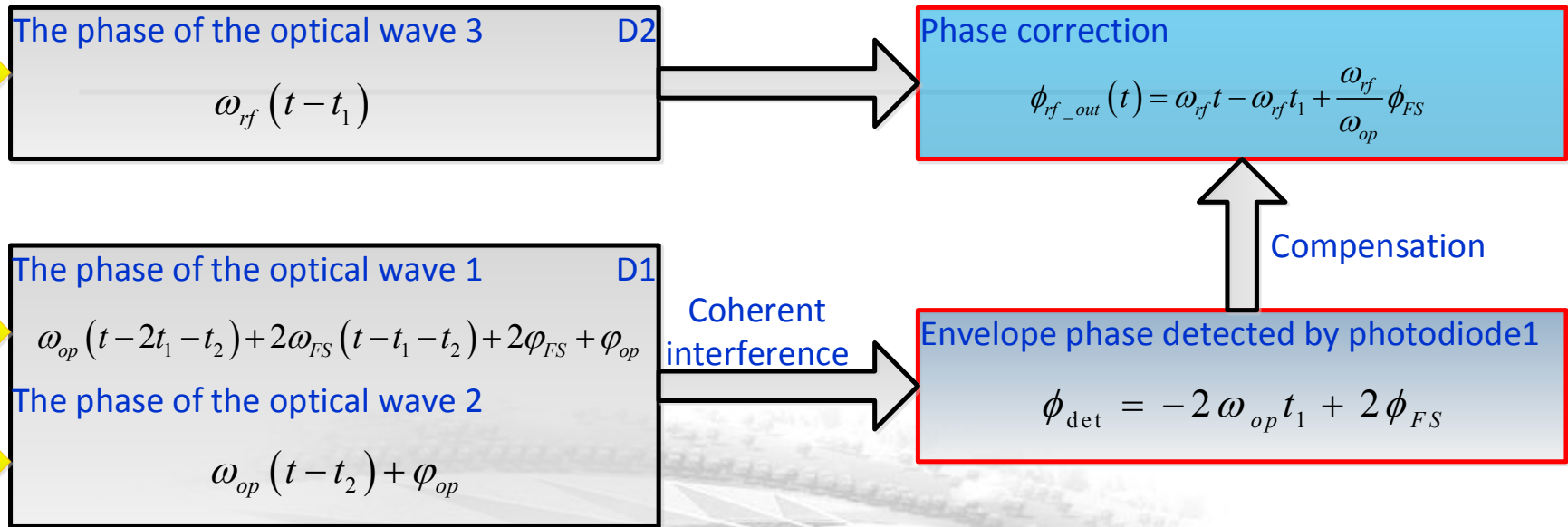
# The condition of coherent detection



## Frequency stabilization measures:

- Lasers with excellent frequency stability.
- The two beams from the same laser, the frequency offset of the light.
- laser frequency stabilization system.





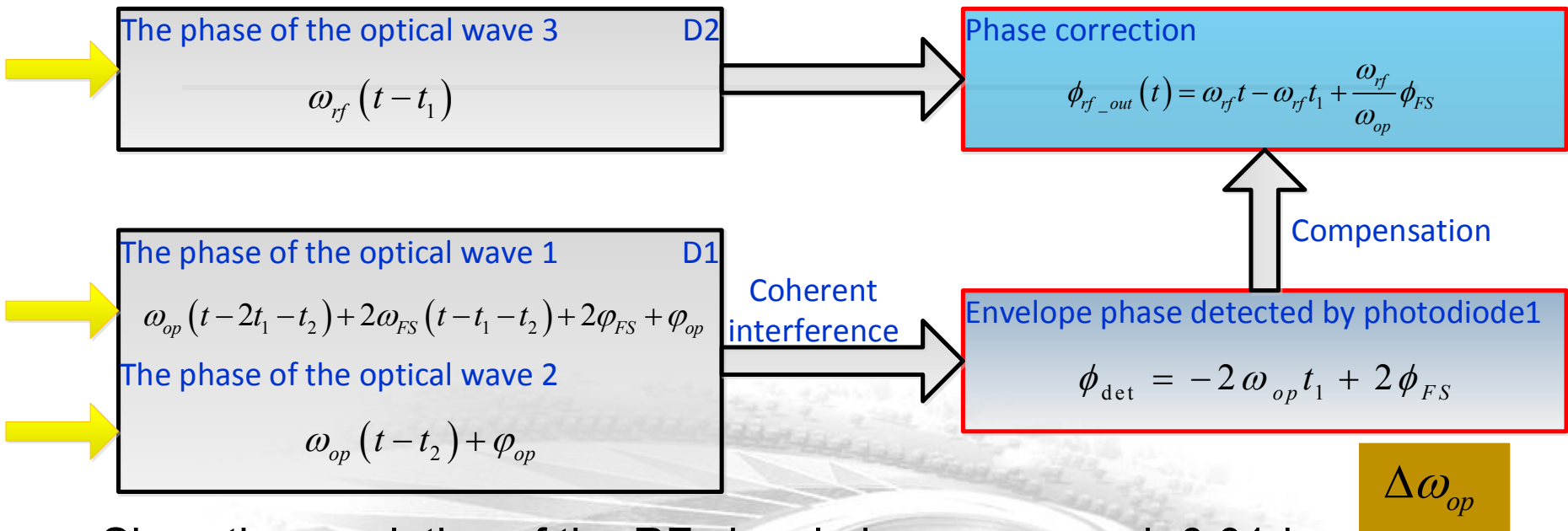
Since the resolution of the RF signal phase can reach 0.01drg.

$$0.01\text{drg @}2856\text{GHz} = 10\text{fs}$$

$$\frac{\Delta\omega_{op}}{\omega_{op}} = \frac{0.01}{\omega_{rf} \cdot t_1} = \frac{0.01}{360 \times 2856 \times 10^6 \times \frac{4}{3} \times 10^{-5}} = 10^{-9}$$

Through calculation, about 2 km long fiber optic network, to the resolution of 10 fs, the frequency of the laser must be stable to 1: 10<sup>9</sup>.





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$$\Delta\phi = \frac{\omega_{rf}}{\omega_{op}} \cdot \Delta\omega_{op} \cdot t_1$$

The phase of the optical wave 3 D2  
 $\omega_{rf}(t - t_1)$

Phase correction

$$\phi_{rf\_out}(t) = \omega_{rf}t - \omega_{rf}t_1 + \frac{\omega_{rf}}{\omega_{op}}\phi_{FS}$$

Compensation

The phase of the optical wave 1 D1  
 $\omega_{op}(t - 2t_1 - t_2) + 2\omega_{FS}(t - t_1 - t_2) + 2\phi_{FS} + \phi_{op}$   
The phase of the optical wave 2  
 $\omega_{op}(t - t_2) + \phi_{op}$

Coherent  
interference

Envelope phase detected by photodiode1

$$\phi_{det} = -2\omega_{op}t_1 + 2\phi_{FS}$$

$$\Delta\omega_{op}$$

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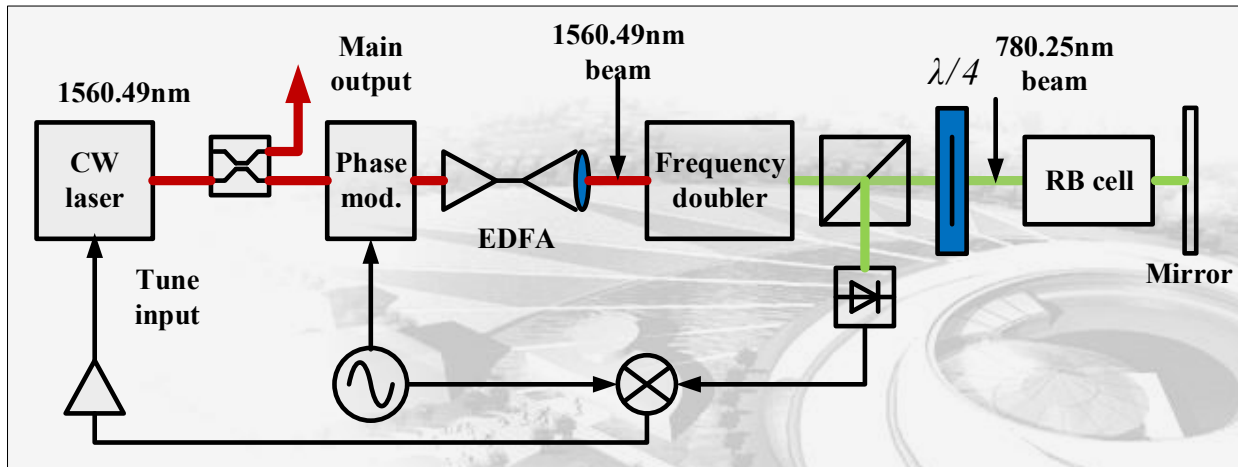
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# laser frequency stabilization

Extraction of laser sample, frequency doubling, locked to the saturated absorption spectrum of rubidium vapor cell line.



error signal:

the change of laser power.

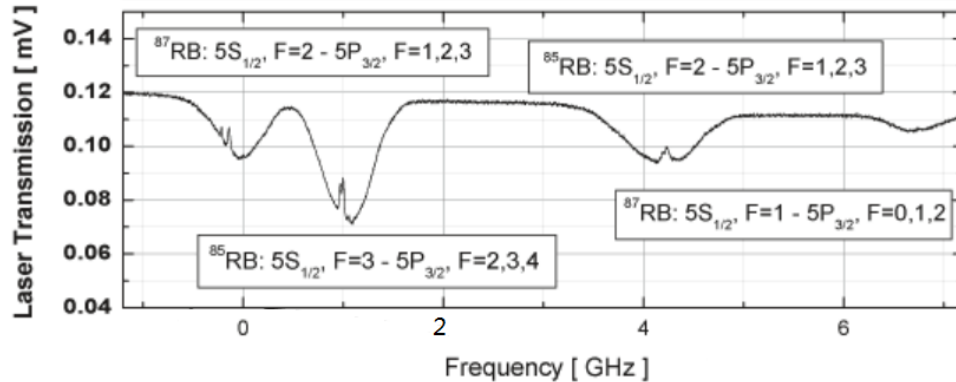
feedback signal:

value is proportional to the error signal.

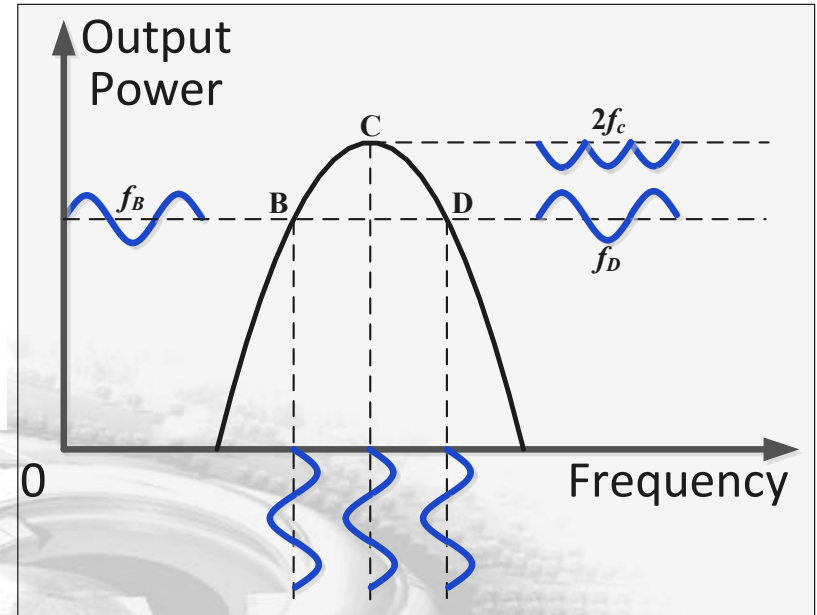
plus or minus depends on phase relationship between the error signal and the modulation signal



# laser frequency stabilization



*The spectra show the saturated absorption of the  $D_1$  line of Rubidium at 780nm*



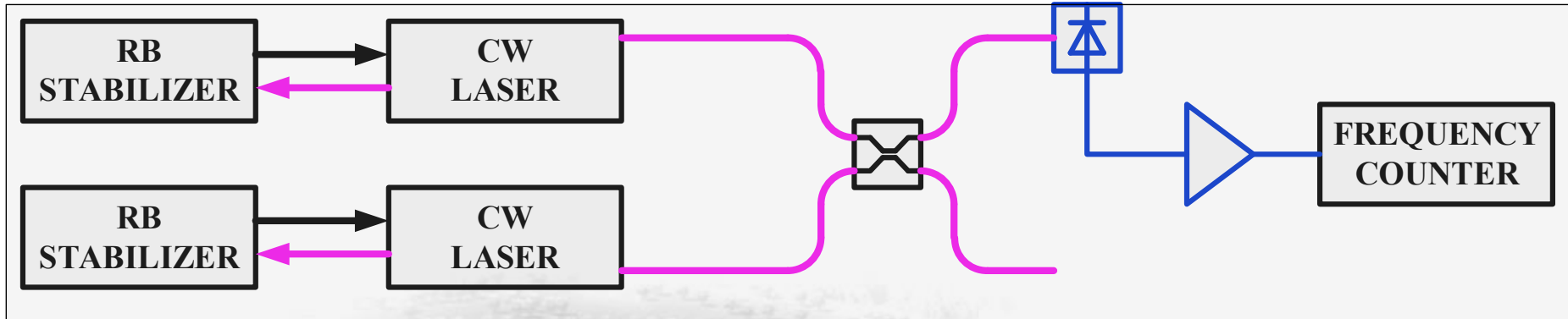
If error signal and modulation signal have the same phase , Output is a **positive** dc voltage.

If error signal and modulation signal have opposite phase , output is a negative dc voltage





# Frequency stability test



Two locked lasers beat together.

Measure the stability and frequency drift of the beat signal.



overcome  
long-term drift

Improve short-  
term jitter

Digital timing  
signal  
transmission

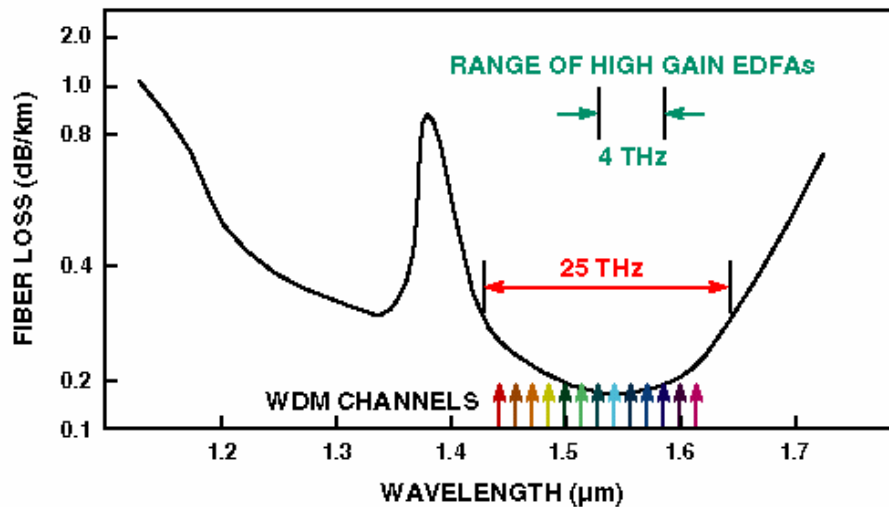
System  
hardware  
structure

Wavelength Division  
Multiplexing

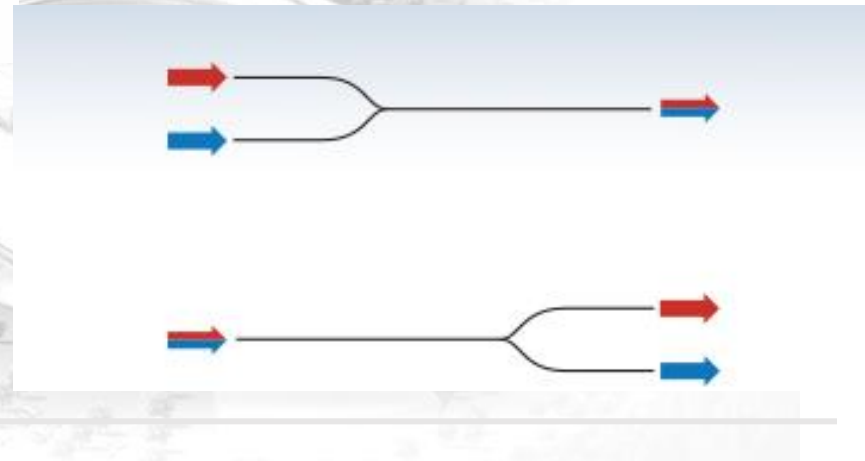
ASK signal demodulation



# Wavelength Division Multiplexing

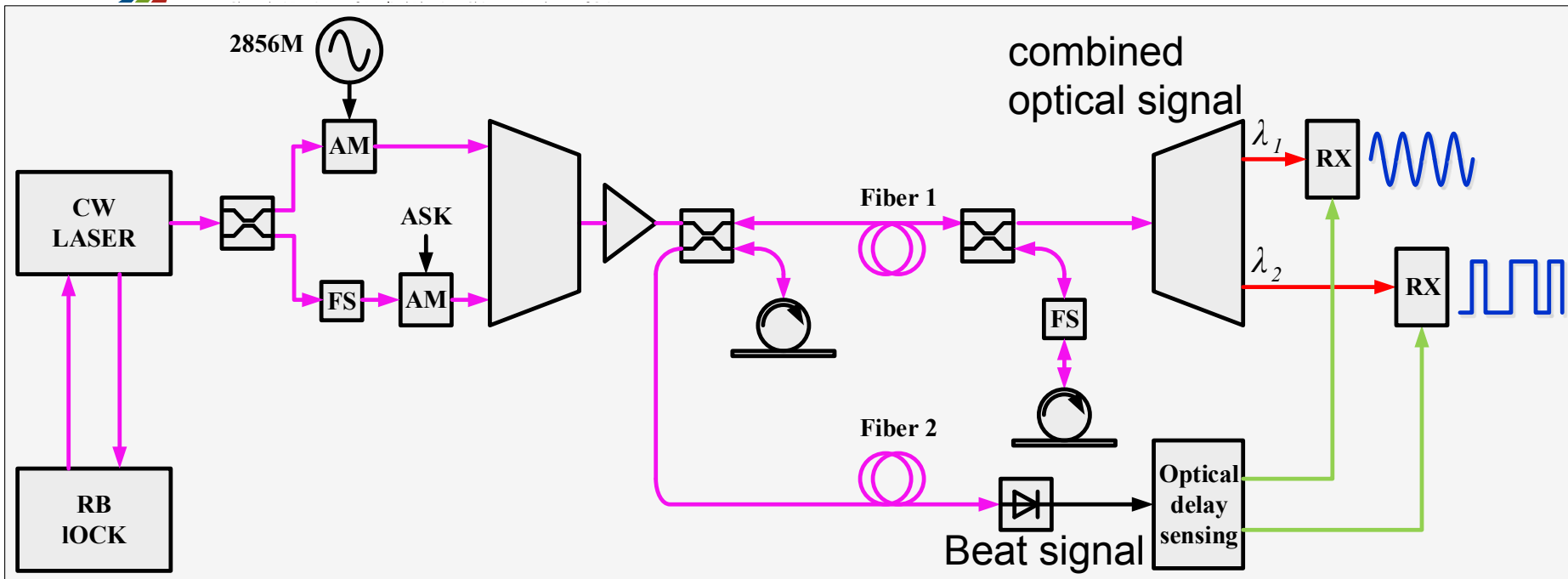


WDM: Combine or Split Single Mode Signals by Wavelength.



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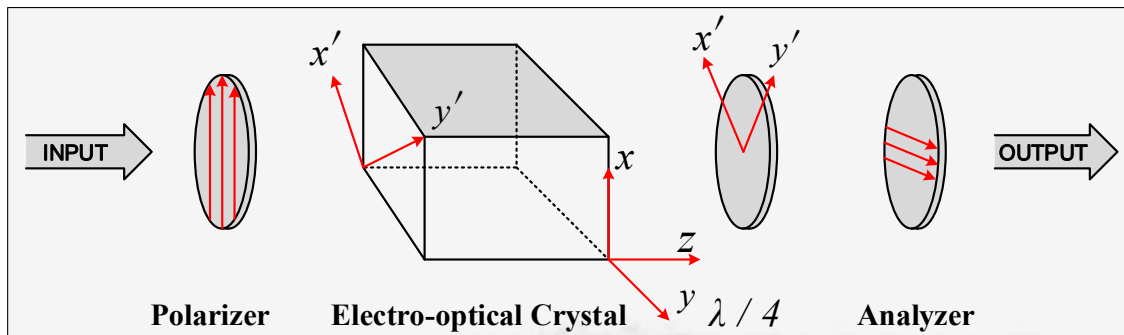
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- Full use of the huge bandwidth of fiber (low loss band) .
- Simultaneous transmission of a variety of different types of signals, digital signal and analog signal, etc.
- By constructing a wavelength division multiplexing system, the digital timing signal is transmitted simultaneous.

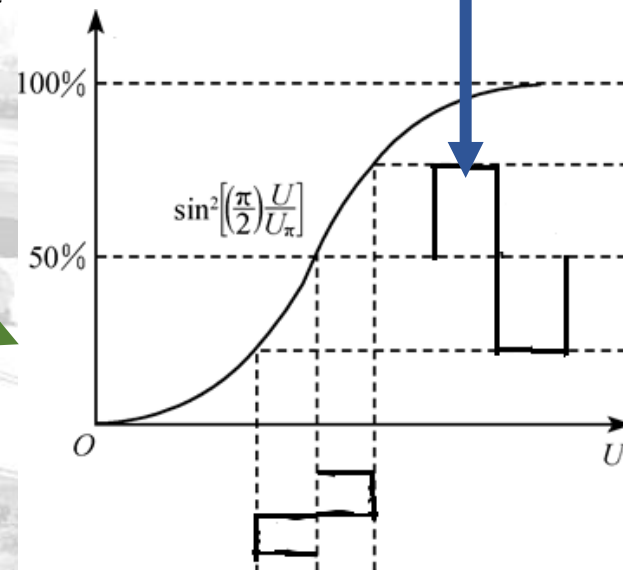


# digital signal modulation

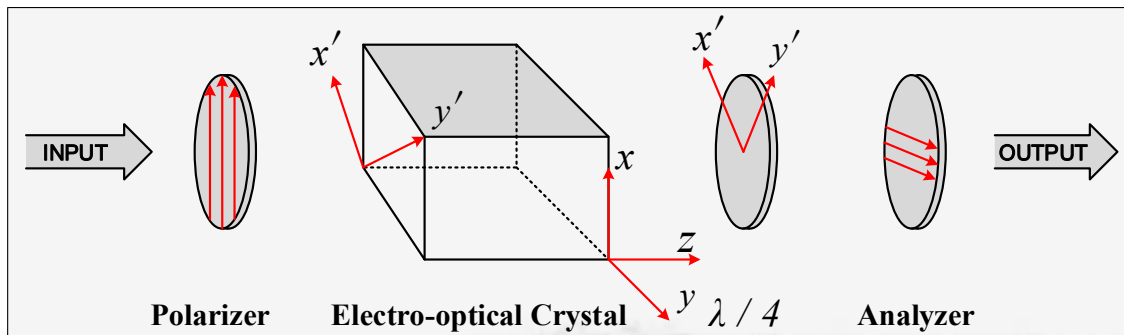


Amplitude Shift Keying

Light intensity modulation signal

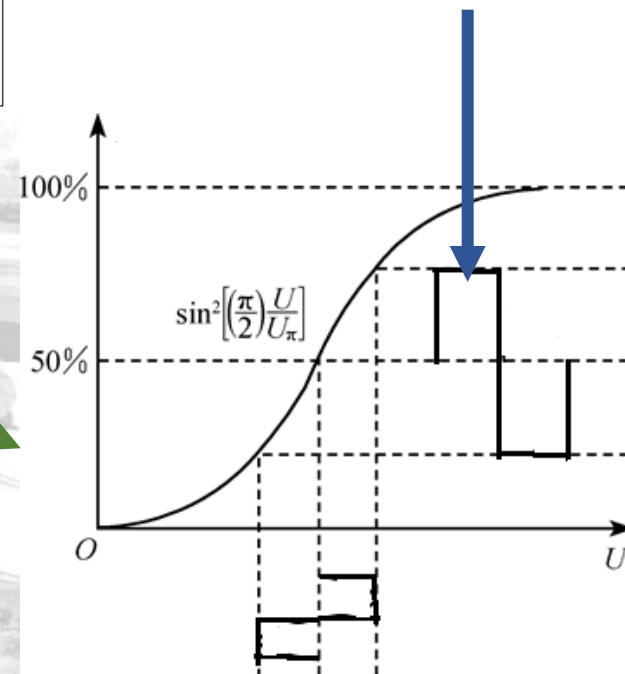


# digital signal modulation



Amplitude Shift Keying

Light intensity modulation signal

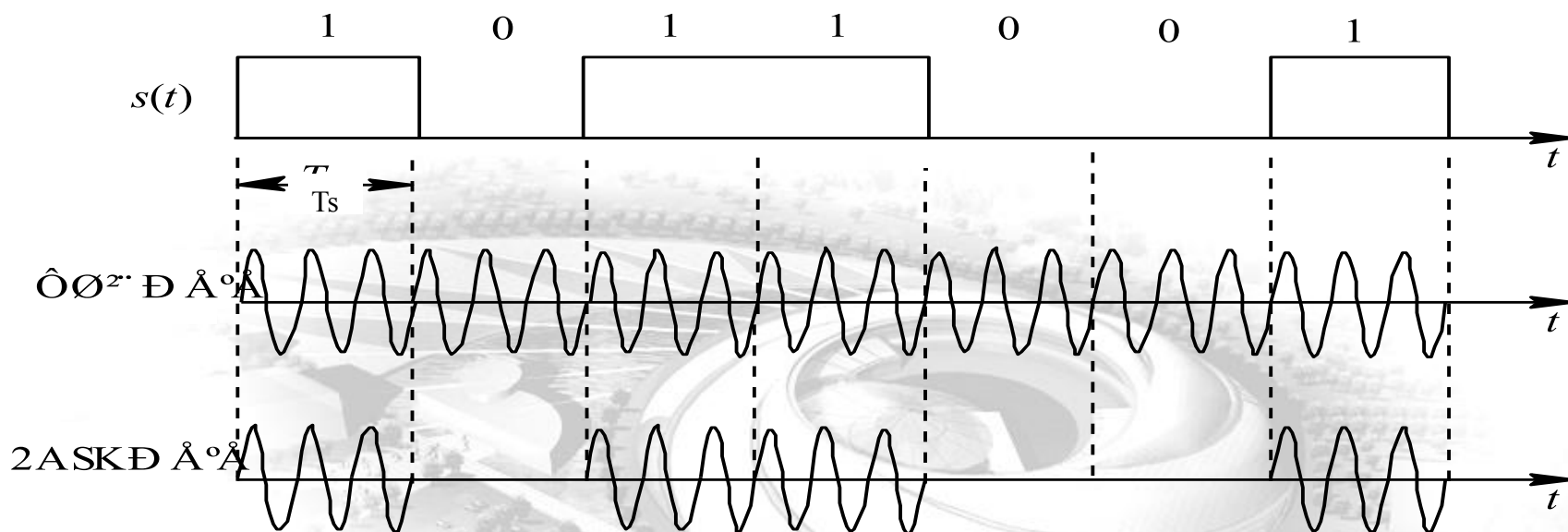


The transmitted light intensity is modulated by the signal voltage.

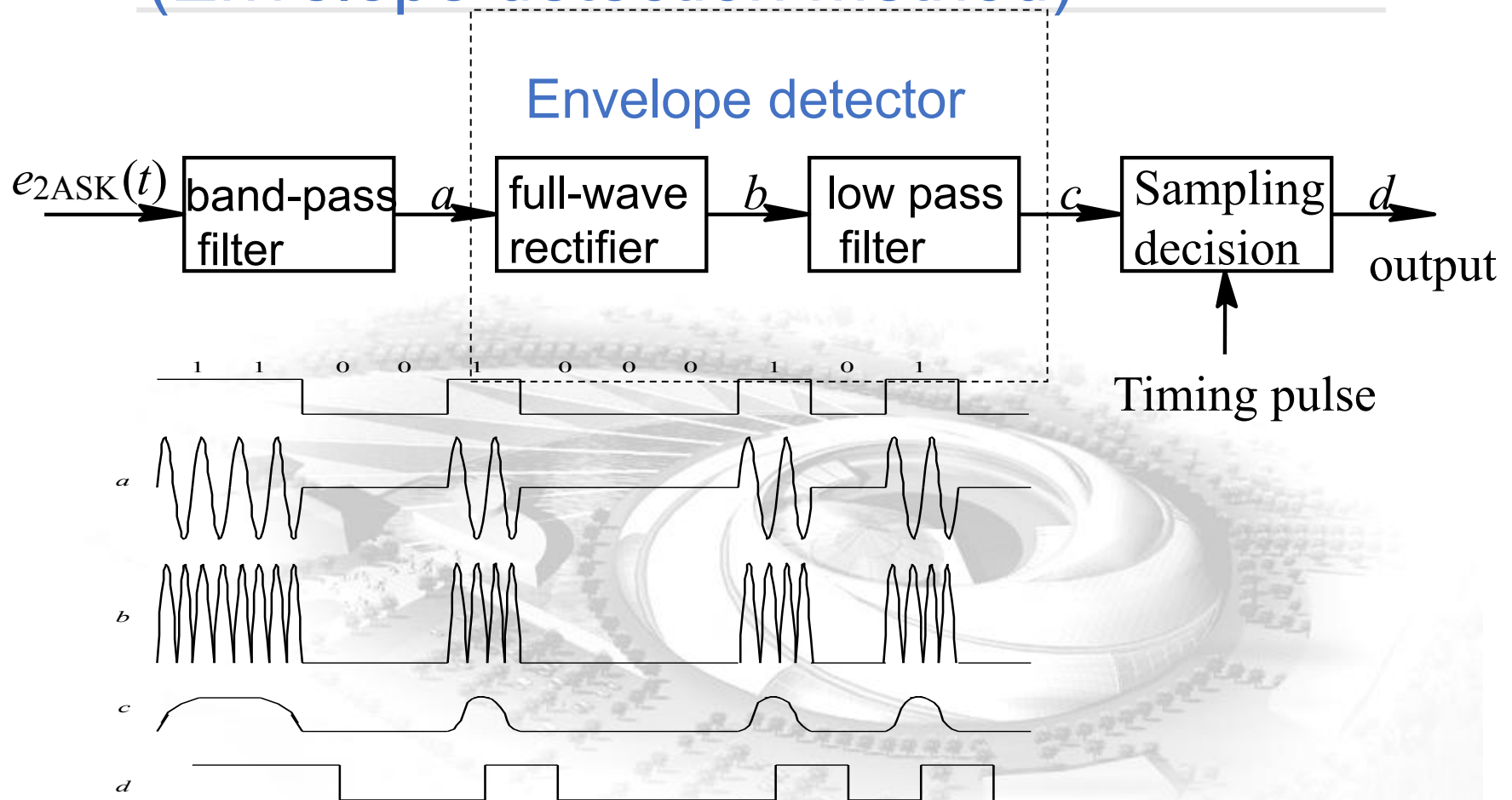




# Time waveform of ASK signal



# ASK signal demodulation (Envelope detection method)



overcome  
long-term drift

Improve short-  
term jitter

Digital timing  
signal  
transmission

System  
hardware  
structure

TX module

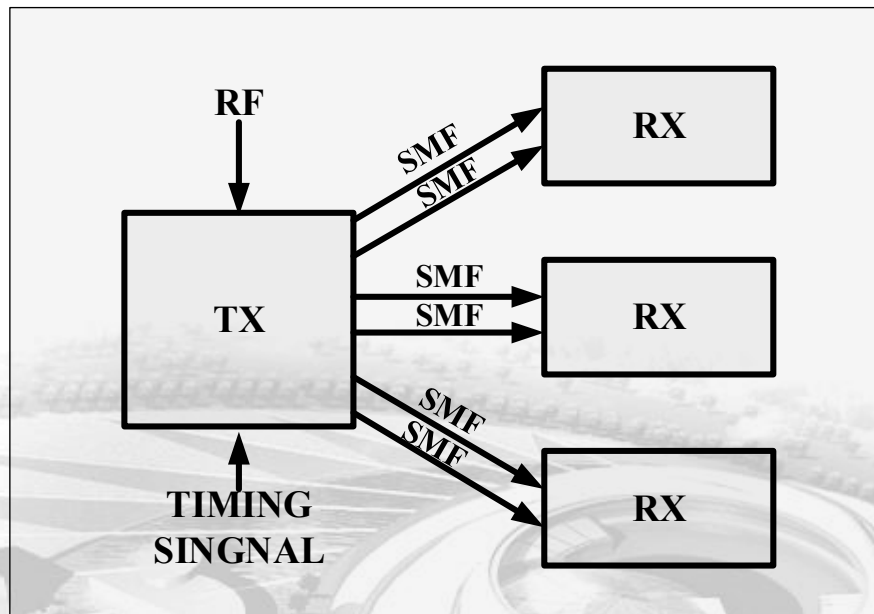
RX module

SMF28 fiber

组

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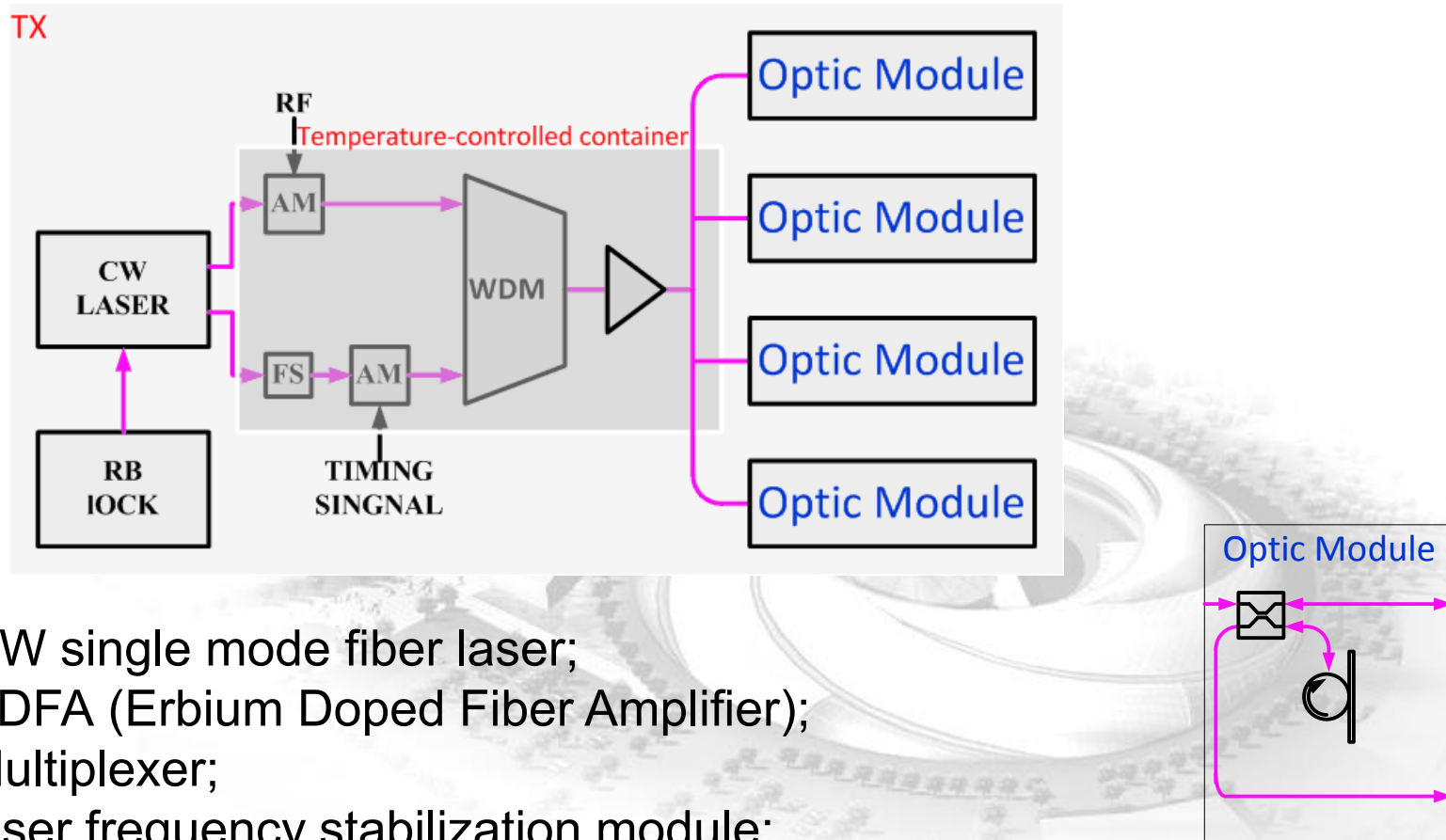
# System hardware structure



## Hardware List

- TX
- RX
- SMF28 fiber

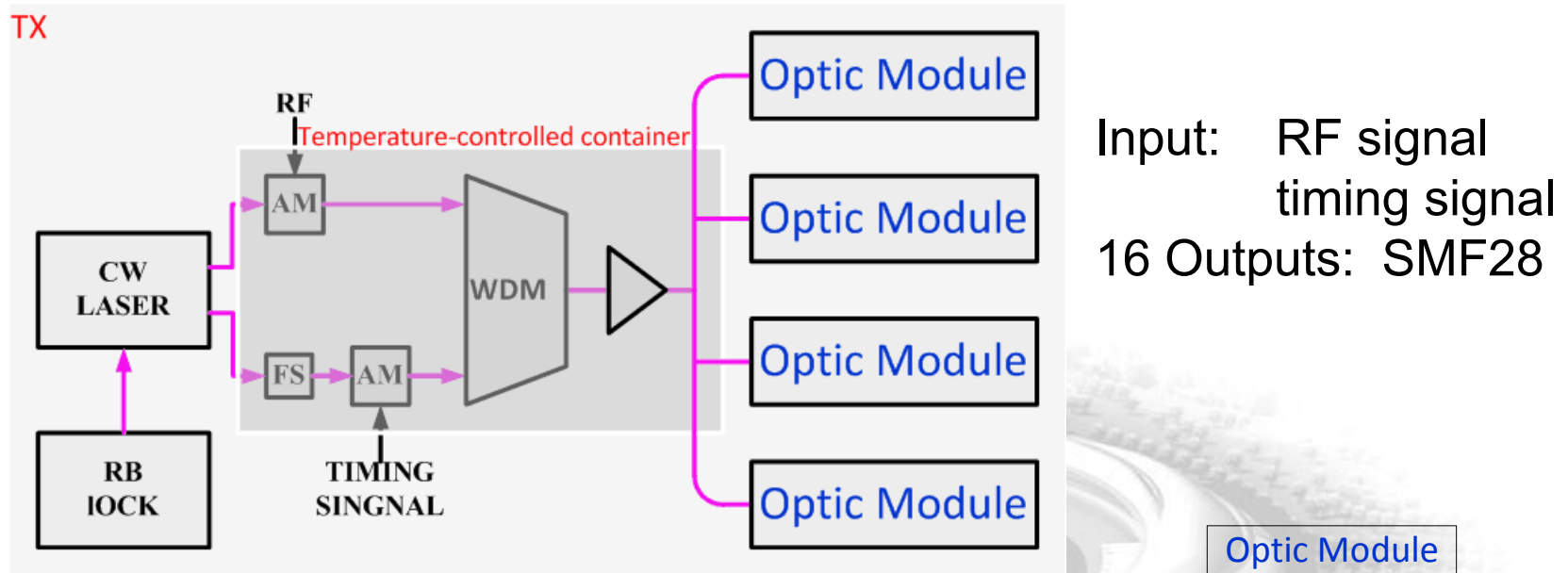
# TX module



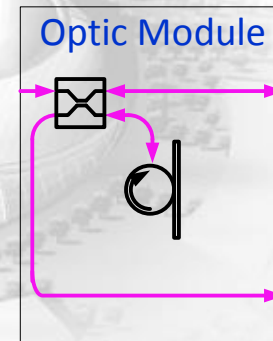
CW single mode fiber laser;  
EDFA (Erbium Doped Fiber Amplifier);  
Multiplexer;  
laser frequency stabilization module;  
temperature-controlled container;



# TX module



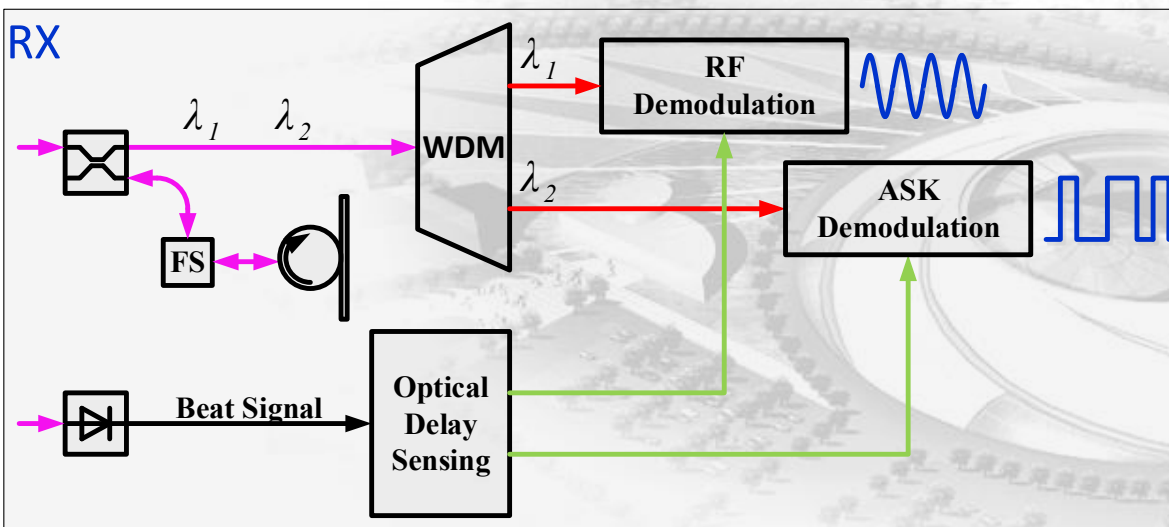
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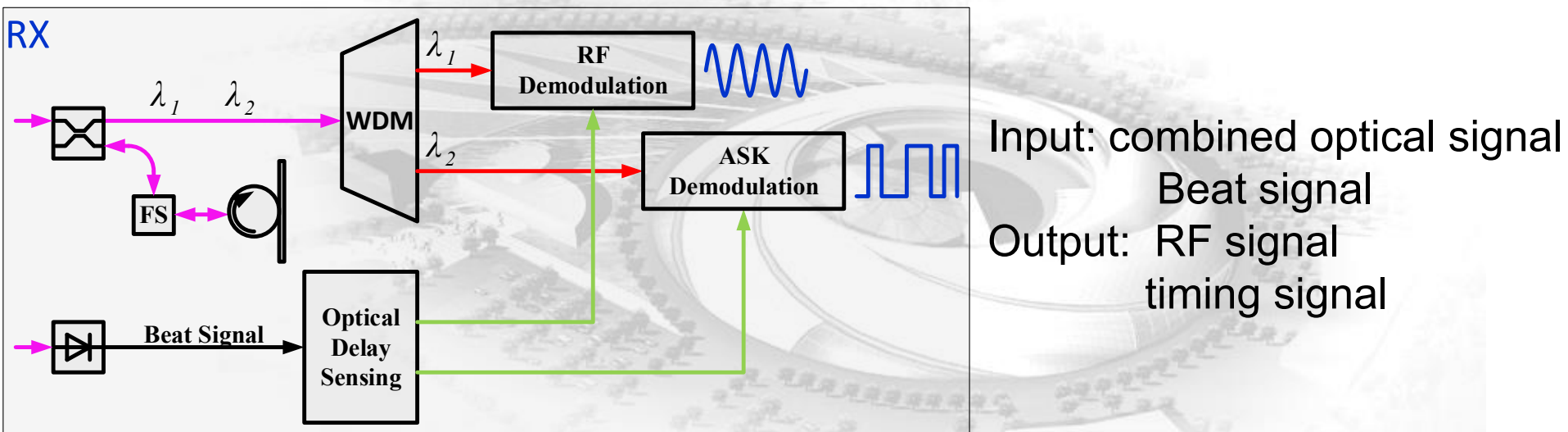
# RX module

- uTCA.4 module (Double-width and RTM)
- RF Demodulation
- ASK Demodulation
- Optical Delay Sensing module
- Demultiplexer



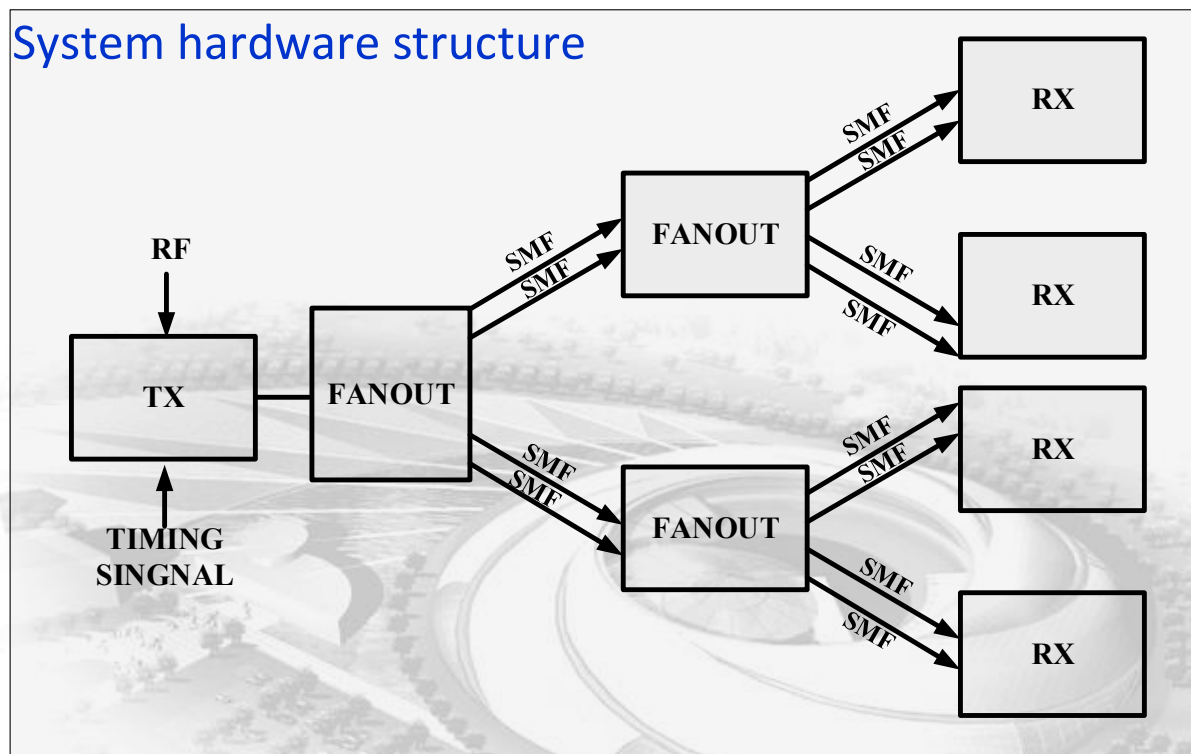
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# FOUT development in future

## System hardware structure

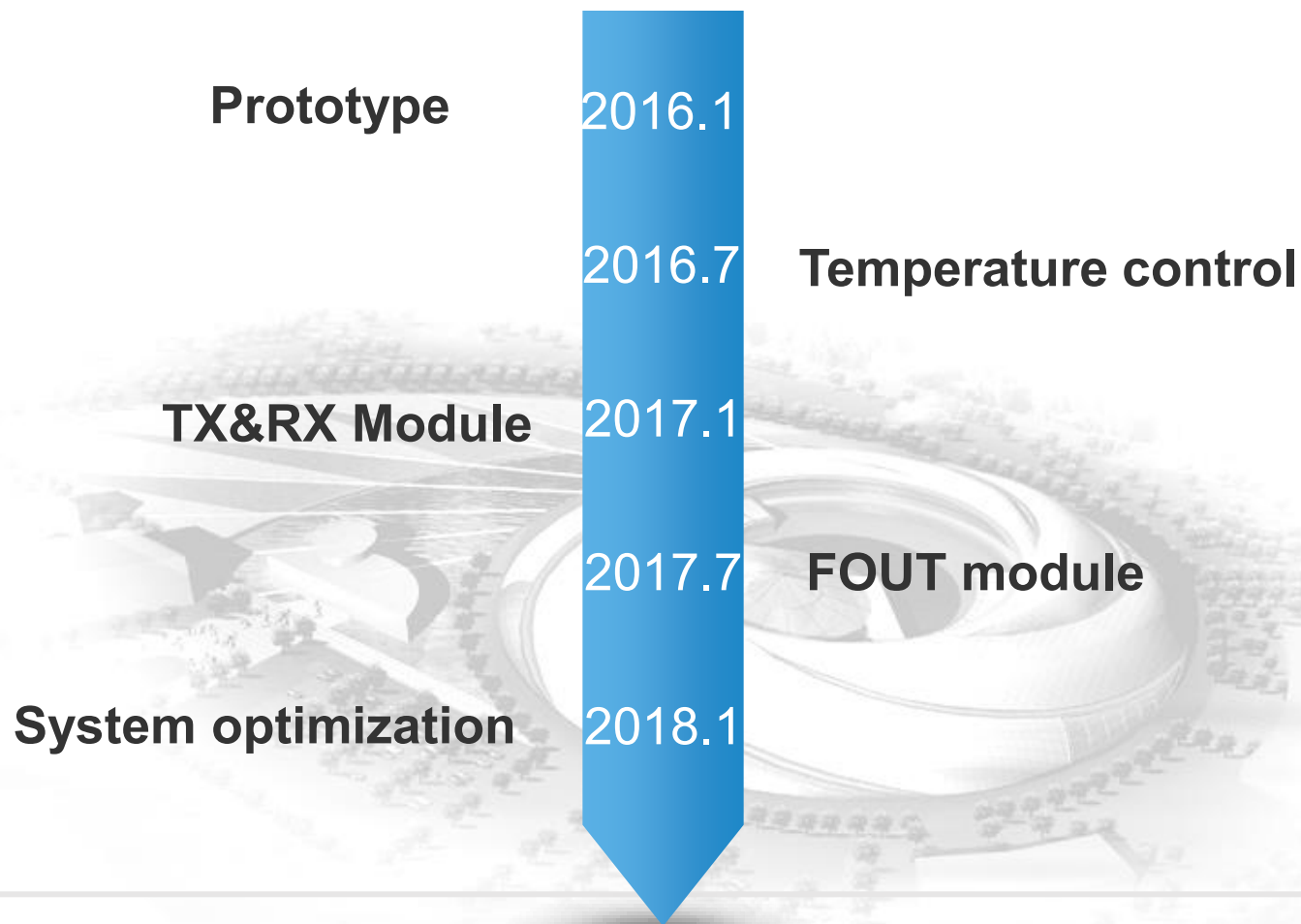


# Character of Femtosecond Timing System

- Providing RF signal and timing signal transmission with low temperature drift and low jitter
- Transmission distance can reach 30 km
- Simultaneous transmission of RF signal and digital timing signal



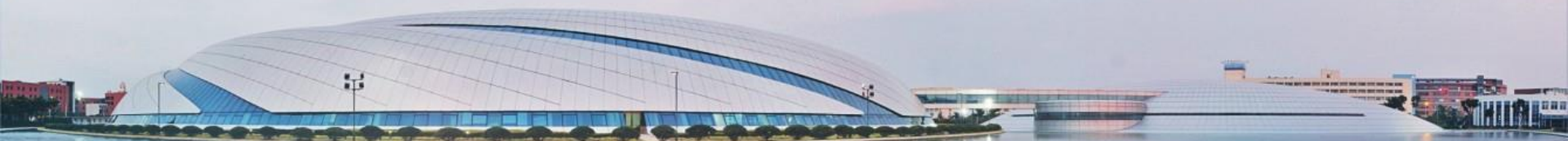
# Project schedule



# Thank you!

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## *Questions?*



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