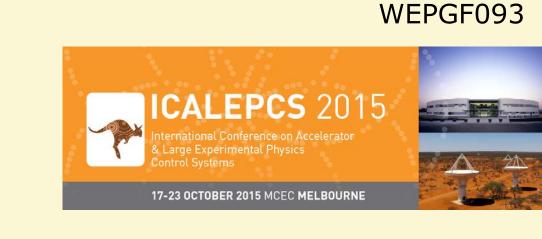


CXv4, a Modular Control System



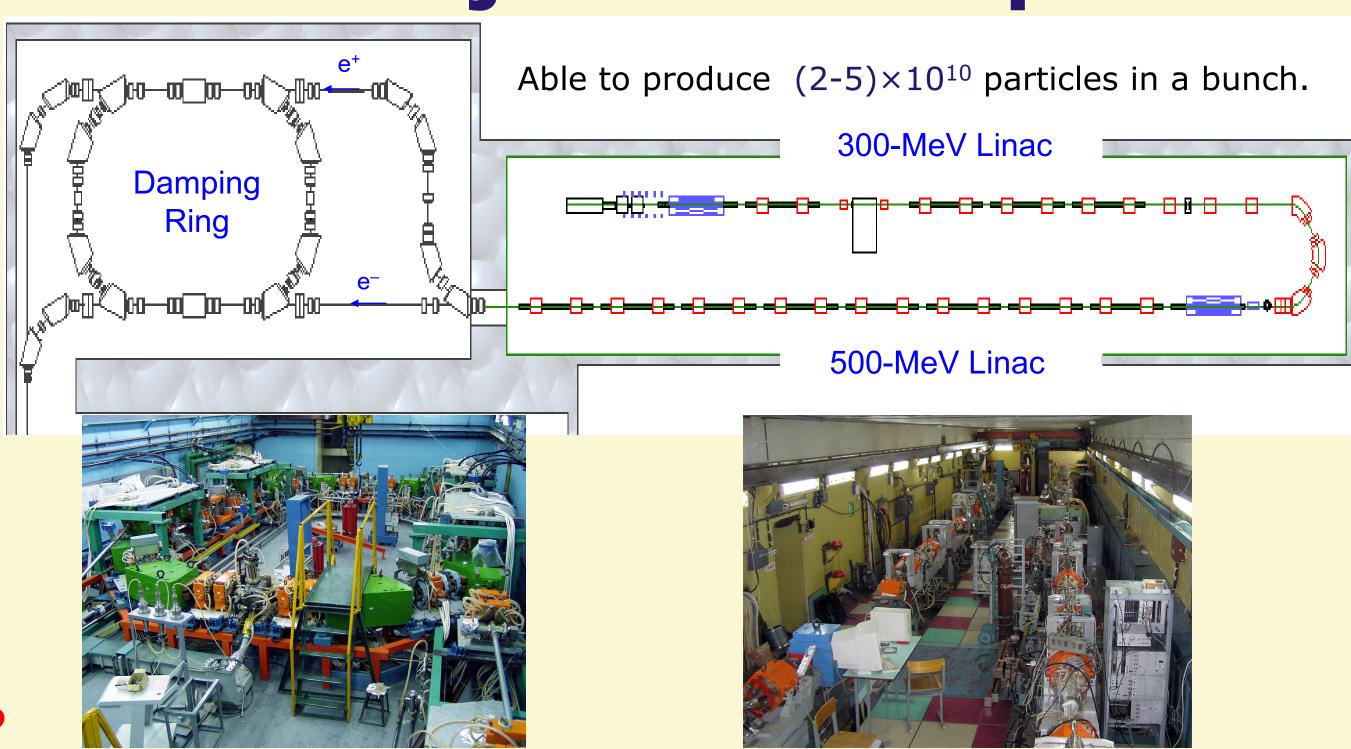
Dmitry Bolkhovityanov, Fedor Emanov, Pavel Cheblakov Budker Institute of Nuclear Physics, Novosibirsk, Russia

CX

- Developed in BINP since late 1990s
- Runs on Linux and *NIX
- Supported hardware includes CAMAC, PCI/cPCI, VME, CAN, RS485
- Used at VEPP-5, LIA-2 and several smaller facilities

VEPP-5 will supply e+ and e- to BINP e+/e- colliders VEPP-4 and VEPP-2000. Thus, communication with their diverse control systems is required in CX. HOW?

VEPP-5 Injection Complex

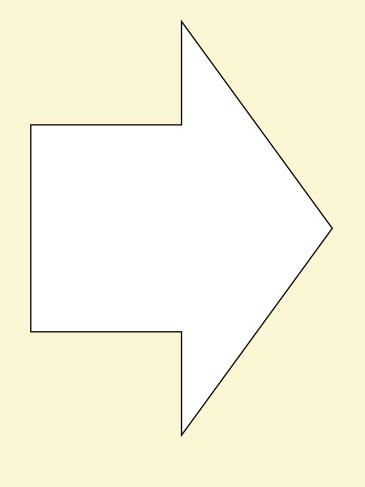


Solution: make everything modular.

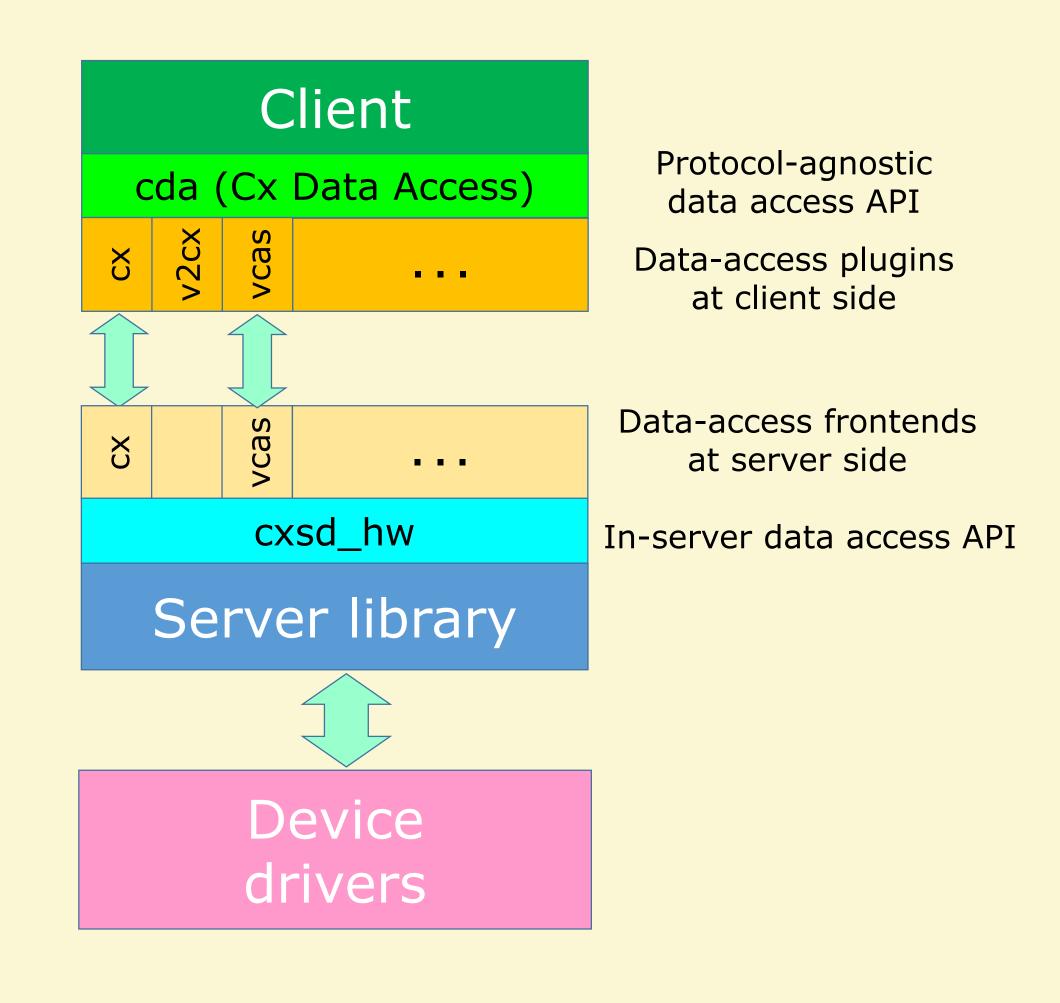
- Drivers, network protocol implementation (at both client and server sides) are plugins.
- Server is a library.

Conventional 3-layer control system layout

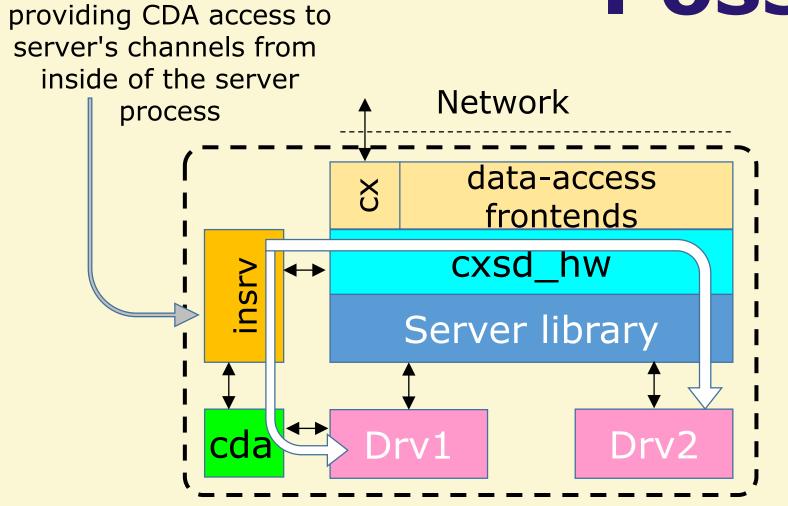
Application layer Client Cln-side proto impl Server layer Srv-side proto impl Server Device drivers



CXv4 modular structure



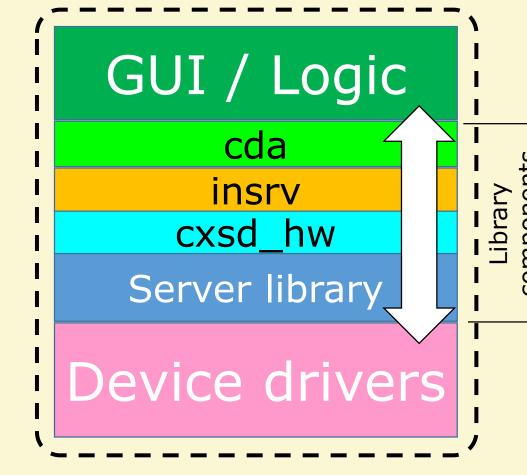
Possible combinations of CX modules



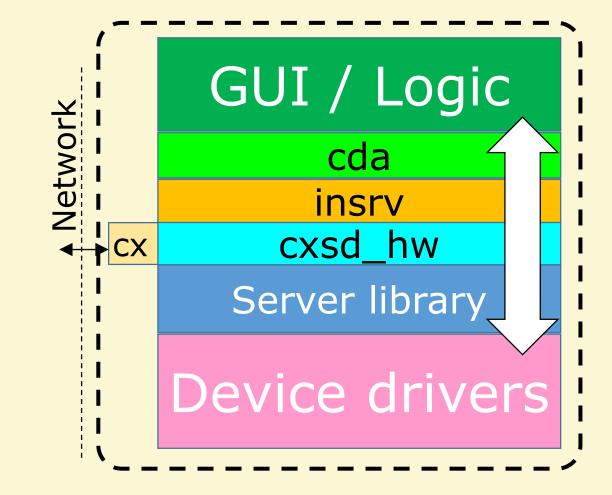
"insrv" is a null-link plugin,

Drivers can access channels from neighbor drivers like clients.

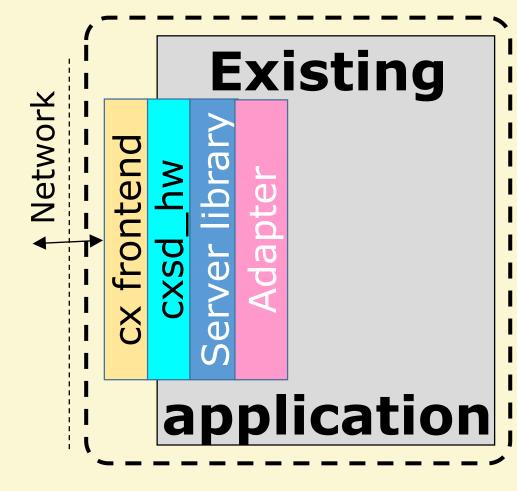
Unified API for local and remote.



GUI+server+drivers combined into a single simple application with no network



GUI+server+drivers combined into a single simple application with remote access



Network-access-enabled existing application