

A REDUNDANT EPICS CONTROL SYSTEM BASED ON PROFINET

Z.Huang, Y. Song, K. Wan, C. Li, G. Liu*,

National Synchrotron Radiation Laboratory, University of Science and Technology of China, Hefei, Anhui 230029, P. R. China * gfliu@ustc.edu.cn



Abstract

This paper will demonstrate a redundant EPICS control system based on PROFIENT. The control system consists of 4 levels: EPICS IOC, PROFINET IO controller, the PROFINET media and the PROFINET IO device. Redundancy at each level is independent of redundancy at each other level in order to achieve highest flexibility. The implementation and performance of each level will be described in this paper.



PROFINET media

• The Media Redundancy Protocol (MRP) is used to realize the redundantly of PROFINET. MRP is a self-recovery media redundancy protocols based on physical ring topological network architecture, designed for the fault of single switch or single



- use the packet analyzer Wireshark to capture the communication frames between the PLCs and PROFINET IO Devices. The switch-over time can be analyzed from the captured frames, Table 1 is the test results, the average switchover time is 6.229 ms, the longest switch-over time is 7.078 ms.

switch link in ring network.

PROFINET IO device

• The redundant pair of PROFINET IO devices consists of two PROFINET IO stations, one is primary station and the other one is backup station. The wiring for the AO, AI, DO, DI modules installed on the PROFINET IO stations is redundant.

PROFINET Media

• The recovery time is a very important parameter for a MRP ring. We also use Wireshark to capture the communication frames between the switches and analyze the recovery time. Table 2 is the test results, the average recovery time is 69.338 ms, the longest recovery time is 87.778 ms.

PERFORMANCE

Figure 3: Switch-over of the softIOC monitored by Strip-

Table 1: PLC Switch-Over Time Test

Number	1	2	3	4	5
Time(ms)	6.964	4.571	6.986	6.953	6.969
Number	6	7	8	9	10

0	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	0.01	.		Ĵ	~~r
tool						

		in the second		
400miWhdiw	\$100		Armad Auto	509mstidiv 29.8kSis 50.8µsiyi Hati Sample
				1 acqs R5, 100k Auto September 16, 2015 10:20:37

iocHost:ai1	2015-09-22	16:48:06.251241	7	HIGH	MINOR
iocHost:ai1	2015-09-22	16:48:06.351407	8	HIHI	MAJOR
iocHost:ai1	2015-09-22	16:48:06.451520	9	HIHI	MAJOR
iocHost:ai1	2015-09-22	16:48:07.260921	0	LOLO	MAJOR
iocHost:ai1	2015-09-22	16:48:07.447481	1	LOLO	MAJOR

Figure 4: Switch-over of the softIOC monitored by camonitor

Figure 5: Switch-over of the PLC monitored by the oscilloscope

Table 2: MRP Ring Recovery Time Test

Number	1	2	3	4	5
Time(ms)	67.694	78.618	71.138	73.192	87.778
Number	6	7	8	9	10
Time(ms)	56.787	64.676	59.751	72.223	61.518

CONCLUSION

We set up the prototype system by integrating the commercial solution into EPICS environment. The prototype system consists of 4 levels: the EPICS IOC, the PROFINET IO controller, the PROFINET media and the PROFINET IO device. Redundancy at each level is independent of redundancy at each other level. This means each level can have different redundancy configurations. Beside its flexibility, the prototype system is also easy to implement, and the switch-over performance is good enough to adapt to the most control processes of the big scientific facility.