CAN Over Ethernet Gateways

A Convenient and Flexible Solution to Access Low Level Control Devices

CAN (a) CERN

- A **recommended** fieldbus at CERN ٠
- Thousands of CAN nodes monitored and controlled from Front-End (FE) servers
- Technically challenging locations (strong magnetic fields, radiation areas)
- Long CAN cabling distance (> 100 m)
- CAN interfaces based on PCI and USB
- Communication via SIMATIC WinCC Open Architecture and OPC •

Max-Load (Z) Number of Ports (Y) Baud-Rate (X)					
	100	125	250	500	1000
1	100%	100%	100%	100%	100%
	800fr/s	1000fr/s	2000fr/s	4000fr/s	8000fr/s
2	100%	100%	100%	100%	60%
	1600fr/s	2000fr/s	4000fr/s	8000fr/s	9600fr/s
3	100%	100%	100%	80%	30%
	2400fr/s	3000fr/s	6000fr/s	9600fr/s	7200fr/s
4	100%	100%	90%	40%	20%
	3200fr/s	4000fr/s	7200fr/s	6400fr/s	6400fr/s
	/				

Throughput measurement results (5 mins duration test)

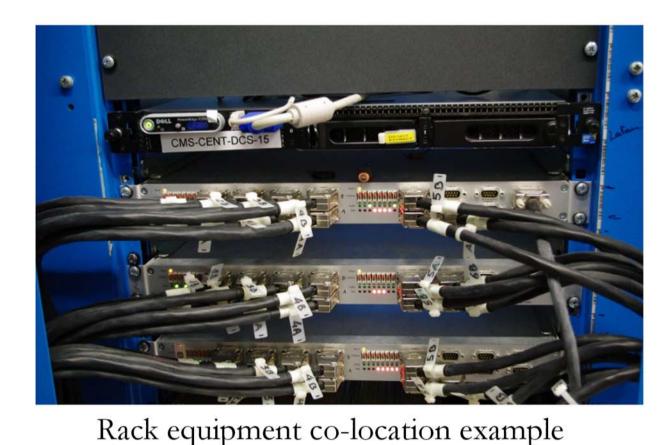
Results

2015

Performance

- The maximum load percentages are the thresholds at which no frames are discarded by the Anagate
- Maximum throughput corresponds to data provided by the company

Current Status and Limitations



Co-location of FE servers and CAN interfaces for PCI or USB

- Racks space limitation
- Requires direct connection to a single FE server
- Prevents from virtualization and redundancy

Selection and Evaluation Methods

User Requirements Market Survey Hardware Selection **Tests Specifications**

Needs?

- High density of CAN ports
- Rack mounted solution
- Independent CAN controllers

Wrapper DLL

• Maps API calls between existing

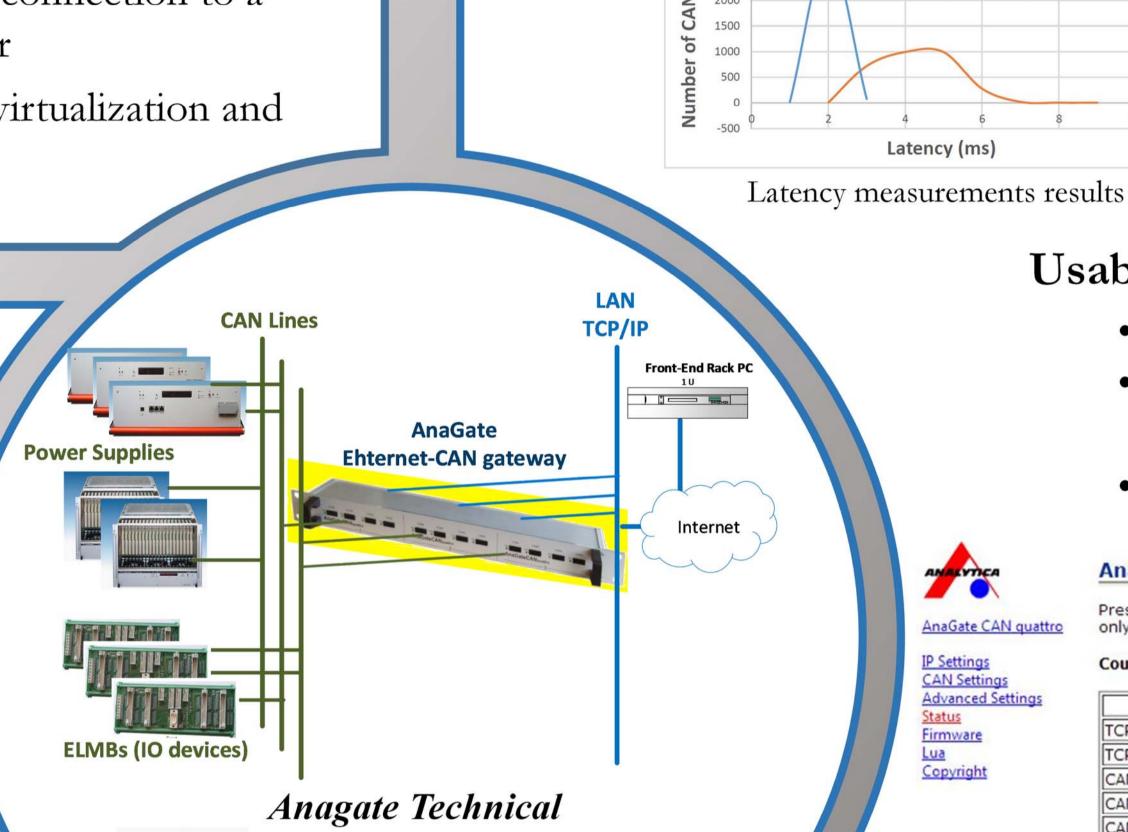
• C re-entrant multithreaded library

LAN/Power/CAN failures

OPC Servers and Anagate hardware.

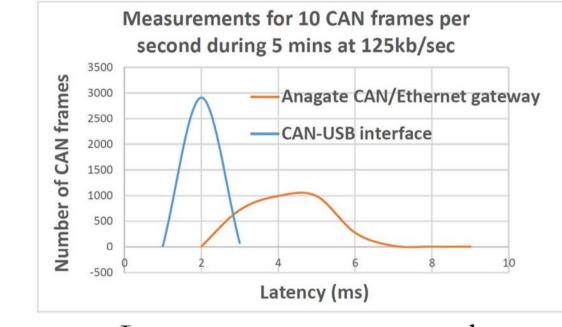
• Transparent recovery mechanism in case of

• Very high reliability Windows and Linux API



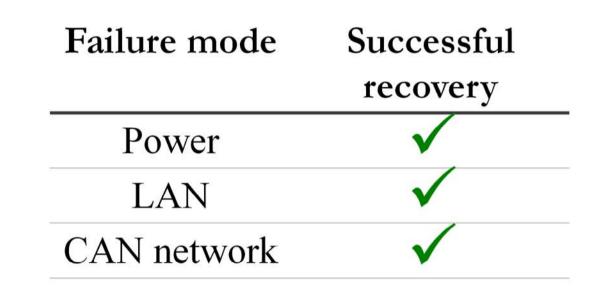
Latency

Distribution of latency when transmitting via Anagate in comparison to USB-CAN interface



Resilience

How well the hardware behaves?



Usability -Web server provided for:

- CAN ports configuration
- CAN frames statistics (sent, received and discarded)
- Firmware update •

AnaGate CAN quattro status

Counter

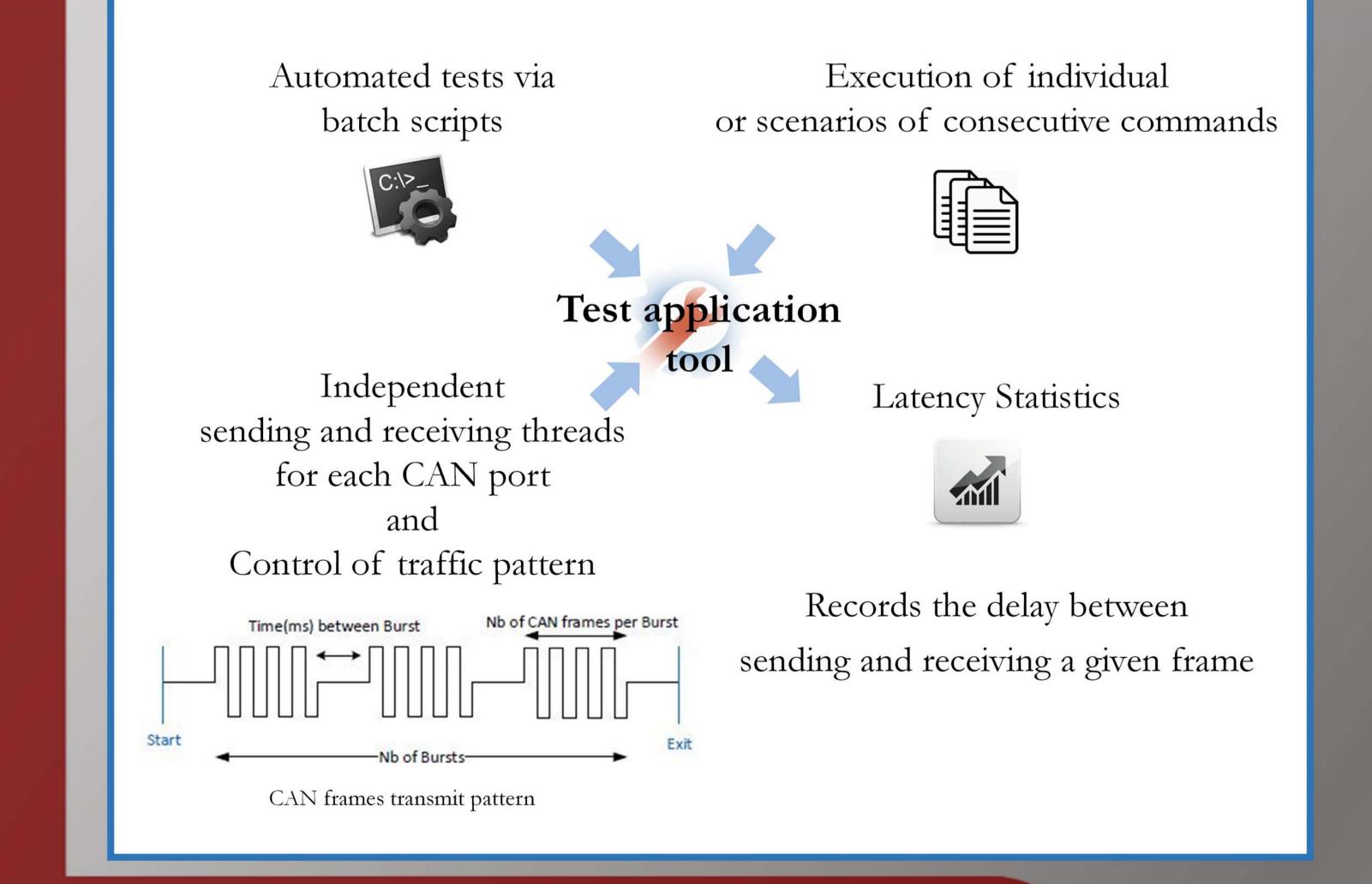
Press the clear button to delete the diagnostic messages. The counts could be zeroed by an reboot

	CAN A	CAN B	CAN C	
TCP Receive:	360000	360000	360000	
TCP Transmit:	336354	333894	327602	
CAN Receive:	337978	336455	329086	
CAN Transmit:	347923	347788	340455	
CAN Discard:	13704	14785	21032	



OPC SERVER
VENDOR 1 API
Software to Software connection inside a computer
VENDOR 1 API
WRAPPER DLL
VENDOR 2 CAN/ETH API
Ethemet connection
VENDOR 2 CAN/ETH HW
CANbus
TARGET DEVICE

OPC-wrapper-CAN API software layout



specifications ANALYTICA Up to 12 CAN ports

- Linux running ARM CPUs
- Windows and Linux API

CAN Receive Error:	0	0	0	0
CAN Transmit Error:	0	0	0	0
Network Error:	0	0	0	0

Copyright 2008-2013 Analytica GmbH, www.anagate.de, Stand: Nov 15 2013 Online CAN frames statistics

Practical Experience in CMS DCS

Integrated the Anagate gateways into the CMS DCS •

AnaGate CAN quattro

IP Settings CAN Settings

Firmware

Lua Copyright

Advanced Settings

- Tested with main CAN-based hardware (Wiener Power Supplies, crates, ELMBs) ٠
- More than **54 billion CAN frames** processed over a period of 4 months
- Very high reliability & robustness in production environment

Hardware Type	Devices	Buses	Baud rate
Wiener VME Crate	88	8	500 kb/s
Wiener Power Supply	136	10	100 kb/s
ELMB	104	8	125 kb/s



CAN D 360000

348594

348851

353959 6301

CMS CAN bus test applications

JACOW ID MOPGF120 Authors: G. Thomas, D. Davids, CERN, Geneva, Switzerland O.Holme, ETH, Zurich, Switzerland

Conclusions

- Good performance, stability and robustness •
- External solution (no direct connection to the FE server) •



- Web interface for online configuration and CAN frames statistics •
- Viable alternative to PCI and USB interface types
- Enables evolution towards virtualization and redundancy •
- Ongoing studies towards integration with OPC Unified Architecture

