

DRIFT CONTROL ENGINES STABILIZE TOP-UP OPERATION AT BESSY II

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Motivation

Transversal Tune Feedback

Beam quality depends on pointing stability and stable shape and size of synchrotron beam. These parameters transform to electron beam orbit and tune stability.

Other systems need tunes to be kept stable:

- RF Knockout system - Single bunch purity
- Bunch-by-bunch feedback systems
- Pulse picking by resonant excitation (PPRE)

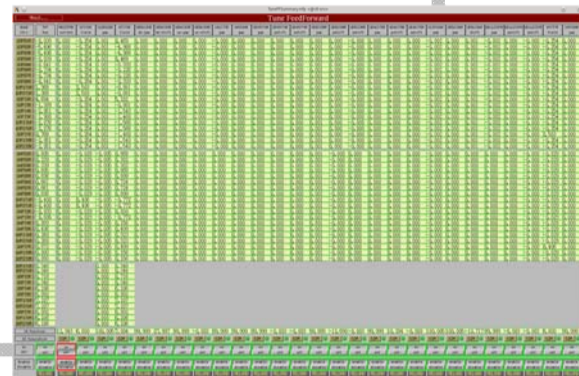
Pathlength Correction — Master Oscillator Feedback

Adjusting the RF master oscillator to the real pathlength of the beam is a central measure to keep beam energy stable at the desired value.

Transversal Tune Feedback

Standard ID-gap Feedforward

1st order correction of ID-induced tune shift made by interpolating empirically produced tune-feedforward tables (27 tune-shifting-parameters × max. 49 quadrupole magnets → 1059 active tables).



Analysis of spectrum to find the correct tune

Peak find

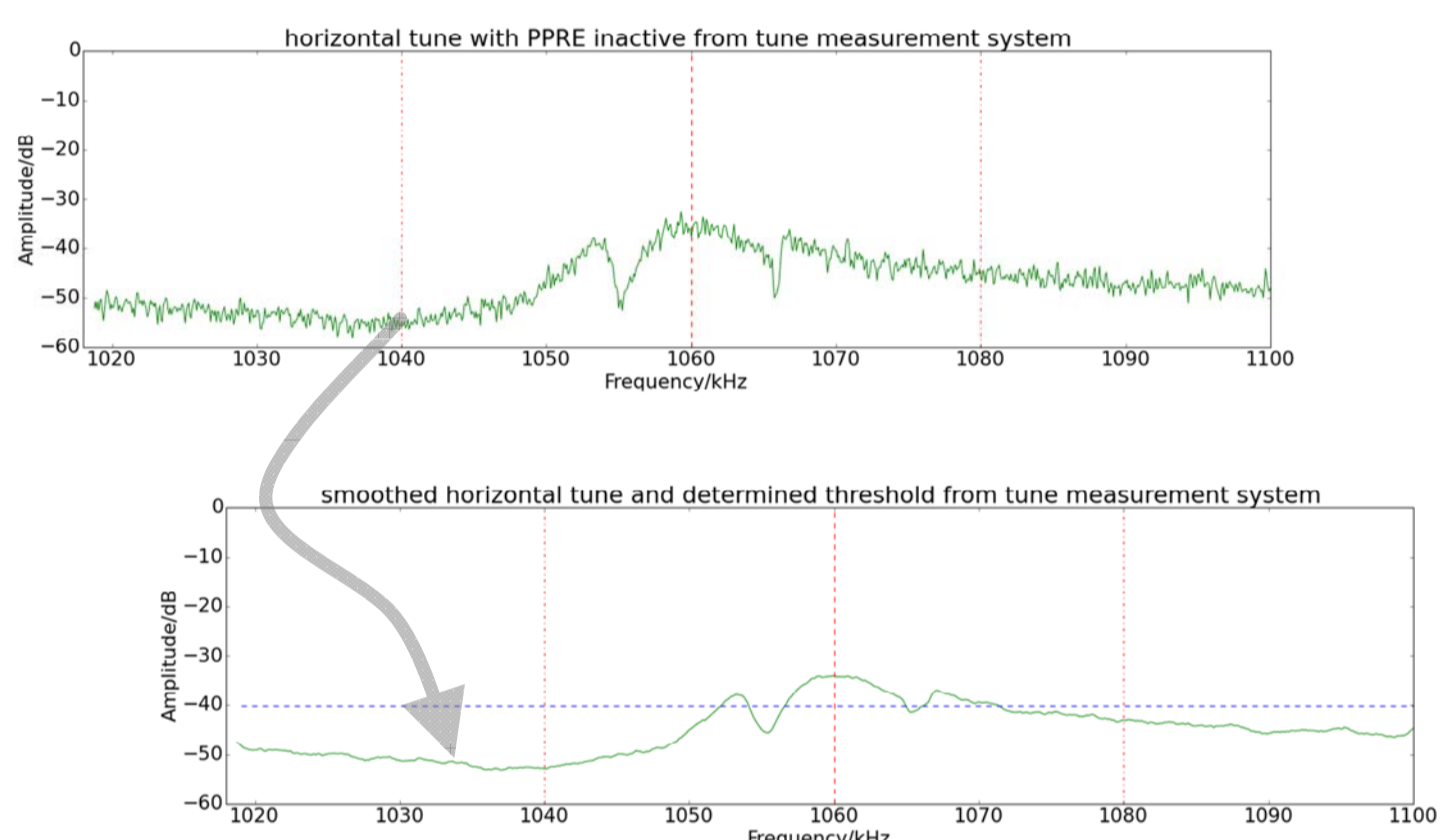
Typically not the best choice

Peak find smoothed

Better, but tune-peak often not highest

Area above threshold

Current method of choice if tune is identifiable. Lower threshold until several separate peaks exceed and select the peak with highest area below



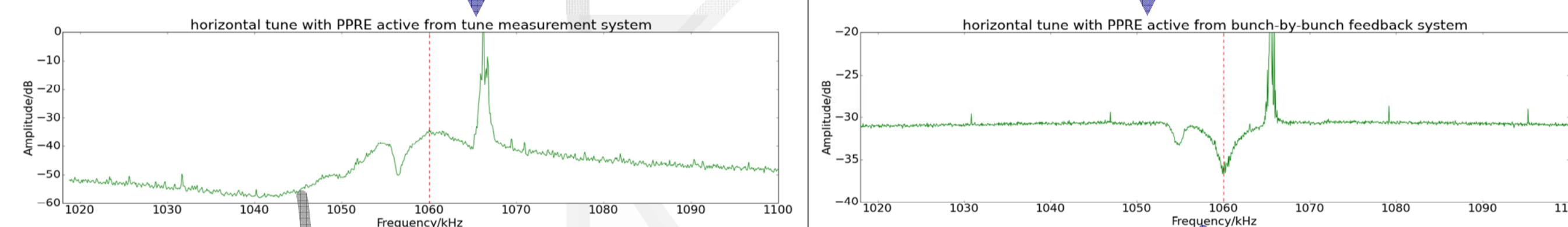
Multi-Source Tune determination from general Beammotion

Diagonal Striplines

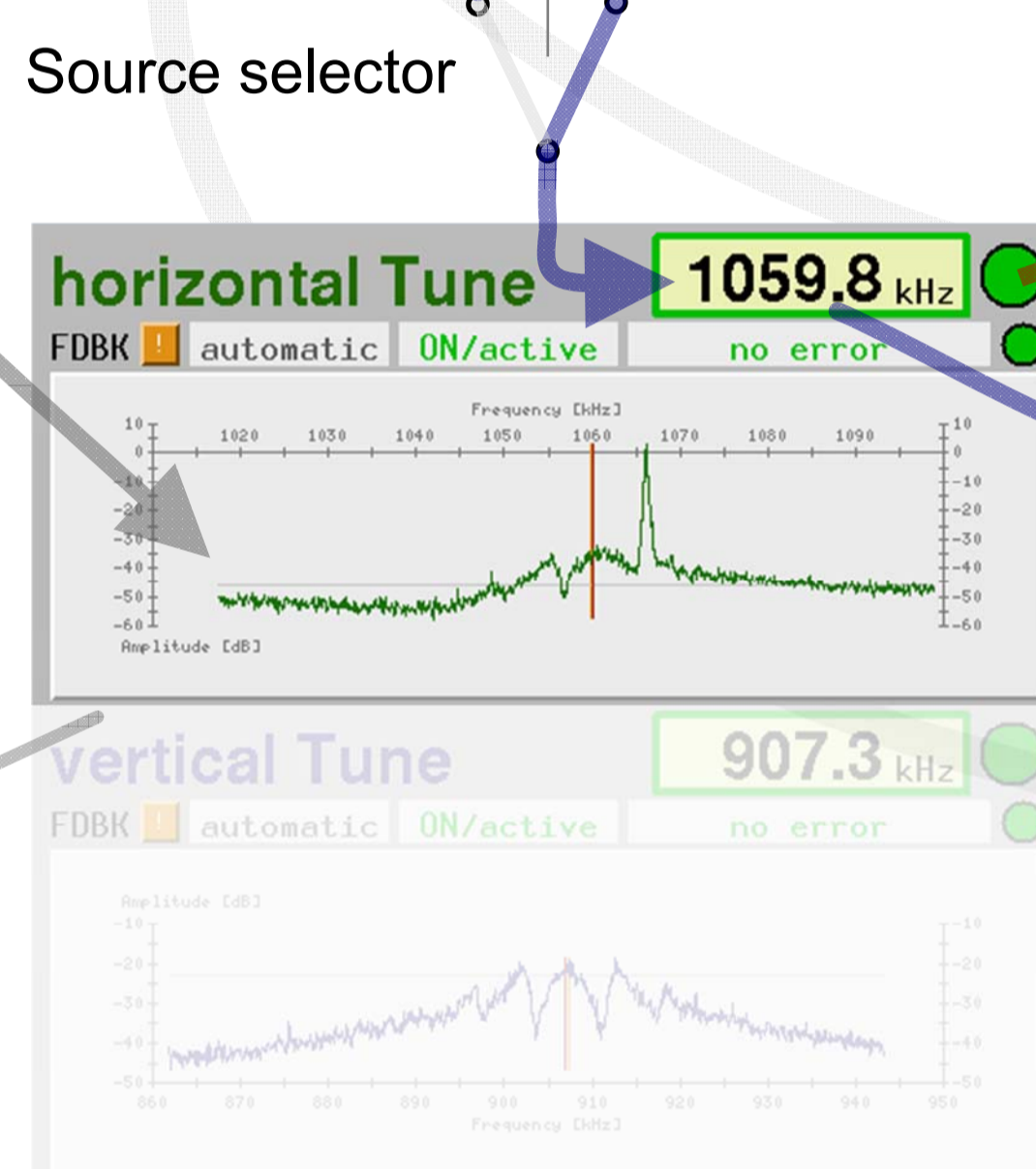
Pickup Electrode

Fast ADC/PXI
LabVIEW, FFT

dimtel
Bunch-by-bunch FDBK



Peak/notch finder



Source selector

Stripline Spectrum displayed for verification

Error Handling

Bad correction
Two consecutive ineffective corrections

Measurement Error
Measurement delivers unstable data or tune is undeterminable

Too much to correct
Measured tune is outside of configured window of allowed automatic corrections

Check for successful correction

Applying correction "with caution"

No corrections if

- Bunch-by-bunch Feedback not running
- Minimum ring current not reached
- Too close to injection
- Variation of tune too high

Pathlength Correction

Slow Orbit Feedback

Fast Orbit Feedback

Horizontal Correctors

Master Oscillator

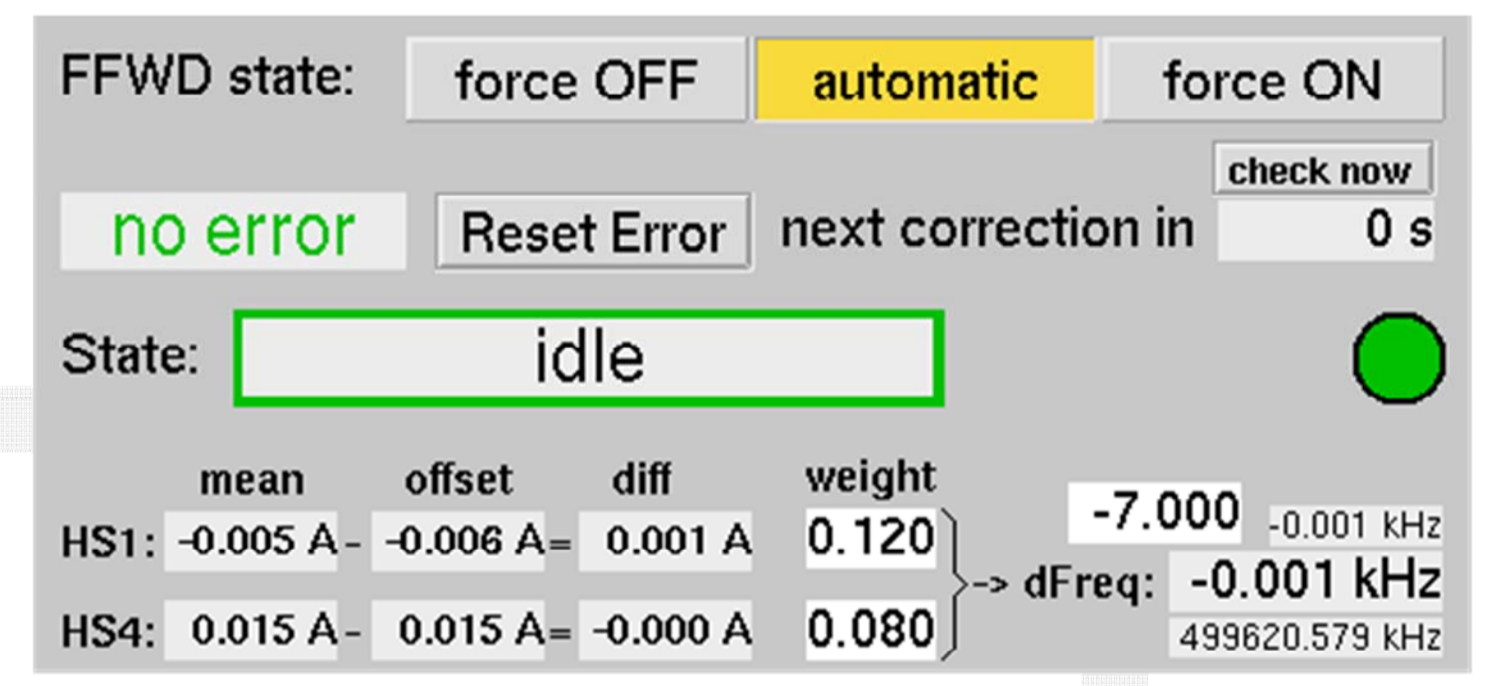
Horizontal Correctors

Beam Position + Path Length

Straight forward implementation of **SOFB** schema for modifying master oscillator is *not possible* for **FOFB**! Instead, excess values accumulate in setpoints of horizontal corrector families

Master oscillator frequency change is calculated from excess average strength of horizontal corrector settings according to previously observed relations

$$RF_{change} = \left[\frac{(\overline{HS1} - HS1_{offset}) \times HS1_{weight}}{(\overline{HS4} - HS4_{offset}) \times HS4_{weight}} \right] \times RF_{scale}$$



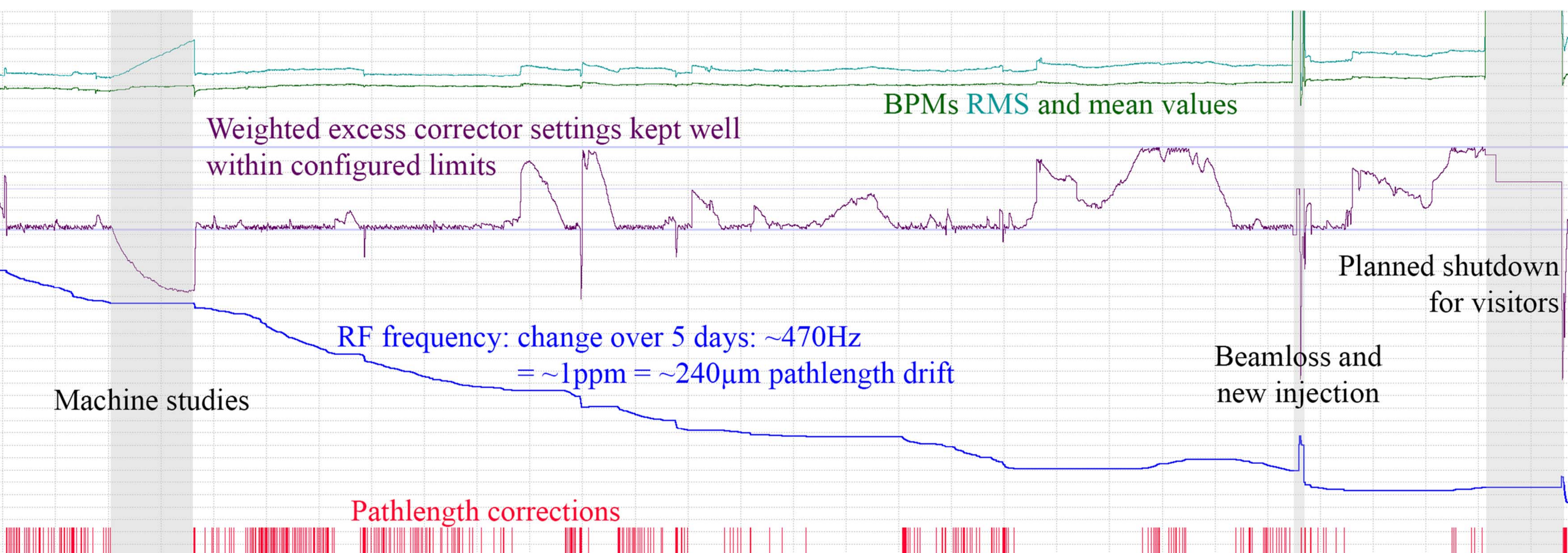
As frequency change is applied, FOFB reduces corrector settings accordingly

- No corrections if ...**
- Fast orbit feedback is not running
 - Minimum ring current not reached
 - Too close to injection

Error Handling

Bad correction
ineffective correction detected

Left:
Plot of ~ 400 pathlength corrections over 5 days after one week of low current low-α operation. Shown are the sum of the weighted excess corrector settings and the resulting RF frequency. BPM RMS and mean values are stable within 1 μm



[1] A. Schlicke, P. Goslawski, M. Ries, M. Ruprecht, „Status and Performance of Bunch-by-Bunch Feedback at BESSY-II and MLS“, IPAC2014, Dresden, Germany (2014) [2] K. Hollmack, R. Ovsyannikov, P. Kuske, R. Müller, A. Schlicke, M. Scheer, M. Gorgol, D. Kühn, T. Leitner, S. Svensson, N. Mårtensson, A. Föhlsch, „Single bunch X-ray pulses on demand from a multi-bunch synchrotron radiation source“, Nature Communications 5, Article Number 4010 (2014) [3] R. Müller, T. Birke, M. Diehn, D. Engel, B. Franksen, R. Görgen, P. Kuske, R. Lange, I. Müller, A. Schlicke, G. Schindhelm, „Fast Orbit Feedback at BESSY-II: Performance and Operational Experiences“, IPAC 2013, Shanghai, China (2013) [4] R. Bakker, K. Hollmack, P. Kuske, R. Müller, „Orbit Control at BESSY-II: Present Performance and Plans“, EPAC 2000, Vienna, Austria (2000)