

### STATUS OF THE ACS-BASED CONTROL SYSTEM OF THE MID-SIZED TELESCOPE PROTOTYPE FOR THE CHERENKOV TELESCOPE ARRAY (CTA)

## Peter Wegner ICALEPCS 2013, San Francisco, Oct. 09<sup>th</sup>, 2013

# Cosmic rays





## Victor F. Hess 1912 (Nobel Prize 1936)

# Cosmic rays





## Victor F. Hess 1912 (Nobel Prize 1936)



# Origin of cosmic particles









































Intensity  $\rightarrow$  Energy Orientation  $\rightarrow$  Direction Image Shape  $\rightarrow$  Particle Stereo View  $\rightarrow$  Source

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# Cherenkov telescope projects





Cherenkov Telescope Array - CTA The next generation of gamma-Ray experiments





CTA consortium: 1100 authors from 27 countries from Europe, the Americas, Africa, Asia, Australia

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## **CTA** Physics





SNR **Supernova Remnants** 









Micro quasars



AGN **Active Galactic Nuclei** 



Detailed study of cosmic particle



**Dark matter** 







**Unknown Sources** 

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## CTA – Telescope Arrays





# Mid-Sized Telescope – MST- Prototype



### Mid-sized prototype in Berlin – Adlershof, operational since May 2013

(DESY, Humboldt University Berlin, University of Potsdam)

# Test and verification of basic hardware technologies:

Drive system, CCD cameras for monitoring/pointing, Active Mirror Control (AMC), Weather Station, Condition Monitoring, ....

#### Implementation and test of CTA Array Control and Data Acquisition software (ACTL) :

Commissioning of components for:

•Control of drive system, AMC, CCD, camera dummy, weather station, ..

- •Alarm and logging system
- •Data transfer mechanisms

•Database tests: For slow control and measurements storage and analysis. Scaling test for CTA array level usage.



# CTA ACTL basic software technologies



#### ALAMA Common Software - ACS:

- Framework for distributed applications used for control systems, esp. of the ALMA array, one of the largest astronomical projects, similar in many aspects to CTA
- C++, Java and Python implementations
- Uses Container/Component Model
- CORBA communication

#### **OPC UA:**

- OPC Specification from the OPC Foundation
- A cross-platform service-oriented architecture for process control
- Multi-platform implementation, including portable ANSI C, C++, Java and .NET implementations
- High scalability: from smart sensors and actuators to mainframes and servers on embedded systems



**DevIO**: is an ACS simple and generic abstraction of hardware monitor and control point, based on the Bridge design pattern.



# ACS Framework



ACS – the common middleware for the ALMA software development, runs under Scientific Linux (RedHat Enterprise based distr. – Fermilab, CERN)

provides an XML configuration database (CDB)

- Containers, Components, Manager
- Employs several standard CORBA services
  - Notification service
  - ✤ Naming service
  - ✤ Interface repository
- **Provides generic GUIs and tools for** 
  - ✤ ACS Command Center,
  - ✤ Logs Displayer, Object Explorer
  - CDB Explorer, Alarm Display System



•••

## **OPC UA – Device level abstraction**











# **Telescope Control server** Dell PowerEdgeR720xd Weather station 2 CPUs (12 CPU cores) **OPC UA** server 128GB main memory Java ACS component 6TB local disk space. Scientific Linux 6.4

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# MST – CCD camera readout & control



OPC UA server provides the camera information model (Data&State Model + Basic functions), uses the SDKs from the CCD camera manufacturer for hardware accessing

Java DevIO and Prosys Java SDKs for OPC UA and ACS communication.

Image data transferred (*push*) by a CORBA method call on one or more "listeners" (ACS components or CORBA objects). idea to test several other data transfer technologies.

For integration test, each ACS component includes an equivalent simulation component. (True also for OPC UA servers)



### CCD camera – ACS GUI



#### Acs Command Center

Project Tools Expert

ÀLMA



# Active Mirror Control (AMC) ACS interface



**Direct access from Active Mirror Control to ACS DevIO device abstraction layer** 



# MST - Data persistence and archives

TMCDB Database



#### **Configuration database (CDB)**

 Device configuration and default values

HibernateServer -loadXMLCDB

• Front End: ACS TMCDB

+ MAC

→ alma → schemas

• Backend: MySQL

ClassicCDB

CDB ->/Alarms

\$ACS\_CDB/CDB

/alma

#### Logging/alarms storage

- Front-End: ACD logging and alarm providers
- Backend: MongoBD



#### **CCD** Data storage

• Store the CCD images and headers in the same database

Containers Components Manager

- Front-End: CCD camera readout
- Back-End: MongoDB, images in GridFS

### Monitoring storage:

#### "Property Recorder"

- •Monitoring points in device properties
- •Periodic and/or value change monitors
- •Front-End: Python ACS applications
- •Back-End: MongoDB and MySQL

# First MST System test under full ACTL control

- CCD night sky data taking with MST prototype (Sep 13<sup>th,</sup> 2013) under ACTL control
- Took three 10 minutes runs:
  - Select a star from the star catalogue
  - Input RA/DEC coordinates to ACS drive system component and let telescope track star
  - Continuously readout CCD images with 5 seconds exposure
  - Images automatically stored in GridFS with metadata linked in mongoDB (NoSQL database)
  - Extract images from mongoDB
  - Analyse images with astronomy.net
- ACS alarm and logging system running
- Weather Station running



(picture - courtesy Louise Oakes)

### MST Prototype – On site server and remote control



#### **DESY Zeuthen**

#### Remote Control server 2xDell PowerEdgeR510

each 2 CPUs (12 CPU cores) 128GB main memory 5TB local disk space. Scientific Linux 6.4



#### **Berlin-Adlershof**

#### Telescope Control server Dell PowerEdgeR720xd 2 CPUs (12 CPU cores) 128GB main memory 6TB local disk space. Scientific Linux 6.4

#### Software development/deployment for the MST – Drive system example



# Summary - next steps



#### **Brief summary**

- First experience with ALMA Common Software positive
- OPC UA server development for various devices feasible
- Using new approaches for control data storage (NOSQL data bases) promising

#### Next

- Integrate Dummy camera and Active Mirror Control
- Add non-optical sensors (condition monitoring)
- Automatize operations
  - Use script-base operation
  - Central array control GUI
- Central Array Control Prototype
  - Simulate ~100 telescopes and components (data, error handling)
  - Integrate an expert system for error/alarm handling