

Reimplementing the bulk data system with DDS in ALMA ACS

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- ALMA & ACS
- Bulk data – overview
- The “old” bulk data based on CORBA A/V
 - limitations
- The “new” bulk data based on DDS
 - Development process
 - Challenges
 - Improvements
- Conclusions



- **Atacama Large Millimeter/submillimeter Array**
 - Collaboration between Europe, North America and East Asia organizations
 - 66 antennas: 54x12m + 12x7m
 - At 5000m on Chajnantor plateau in Atacama desert, Northern Chile
- **ALMA Common Software**
 - Container-component, CORBA based, middleware
 - Develop distributed (control) systems

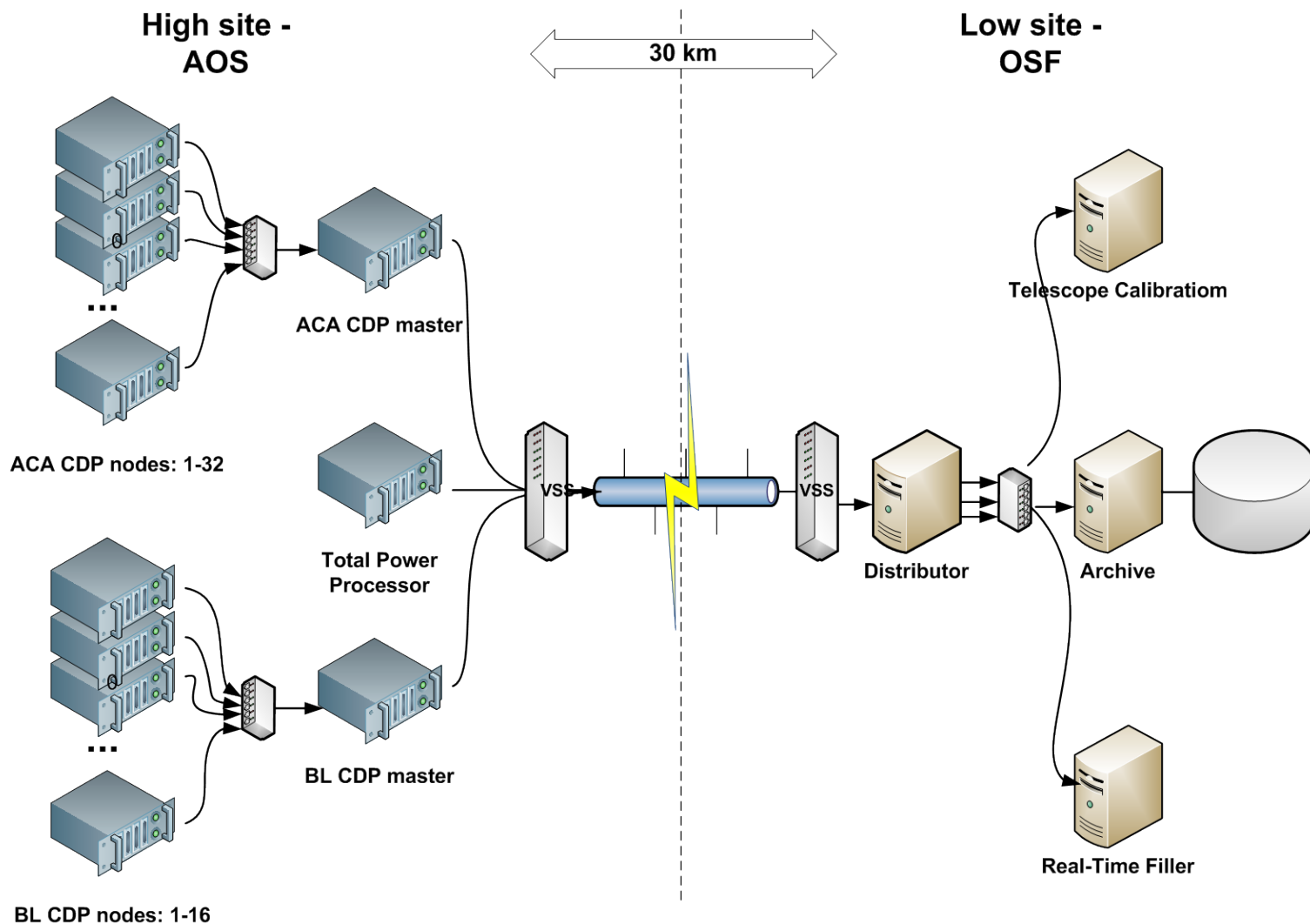


Bulk Data - BD

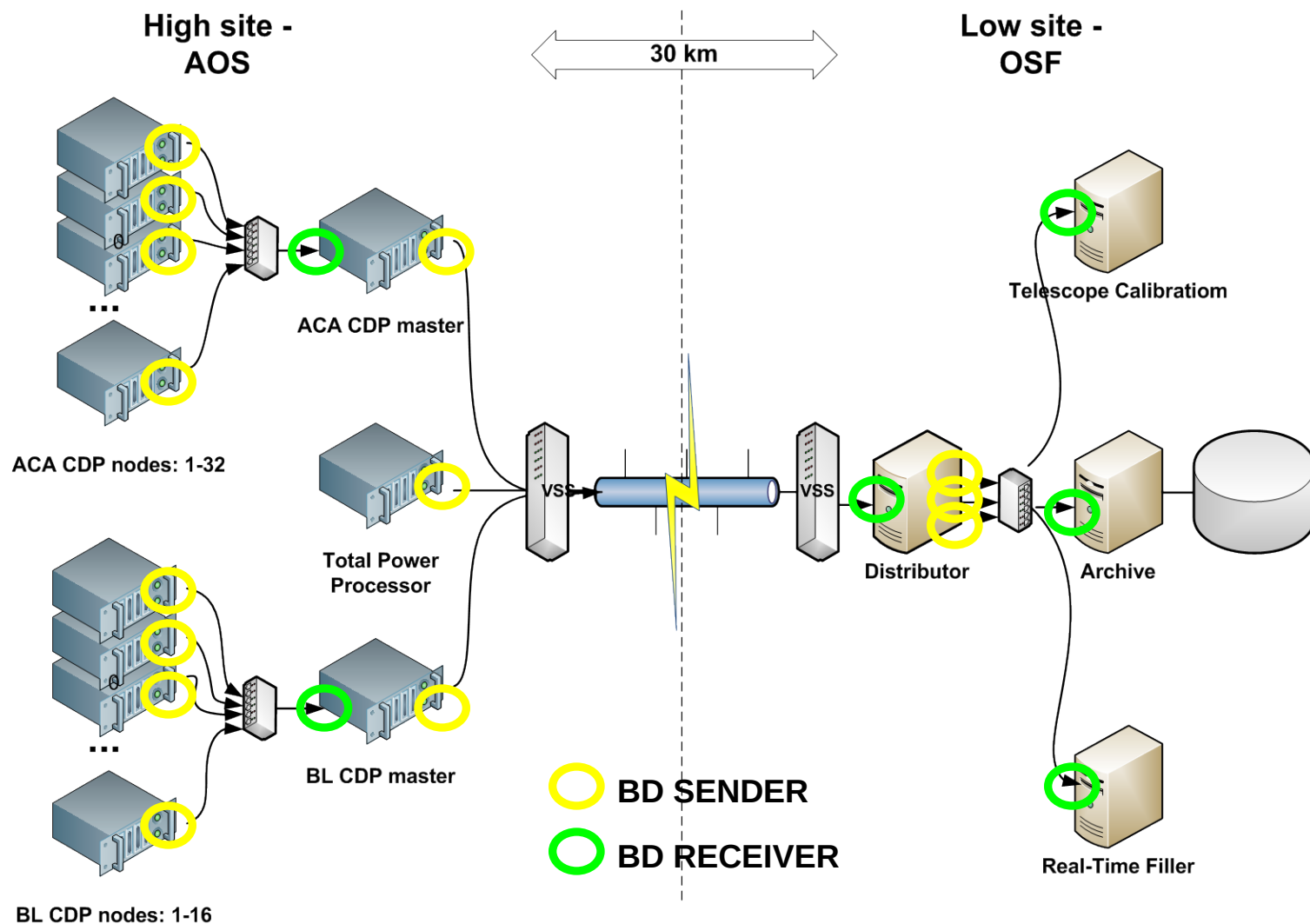
- ACS service for **reliable** and **concurrent** streaming of high volumes of (astronomical) data
- Used in two configurations:
 - Many senders to one receiver
 - One sender to many receivers - multicast
- Used by 6 ALMA SW sub-systems
- Total peak data rate: 64MBytes/sec



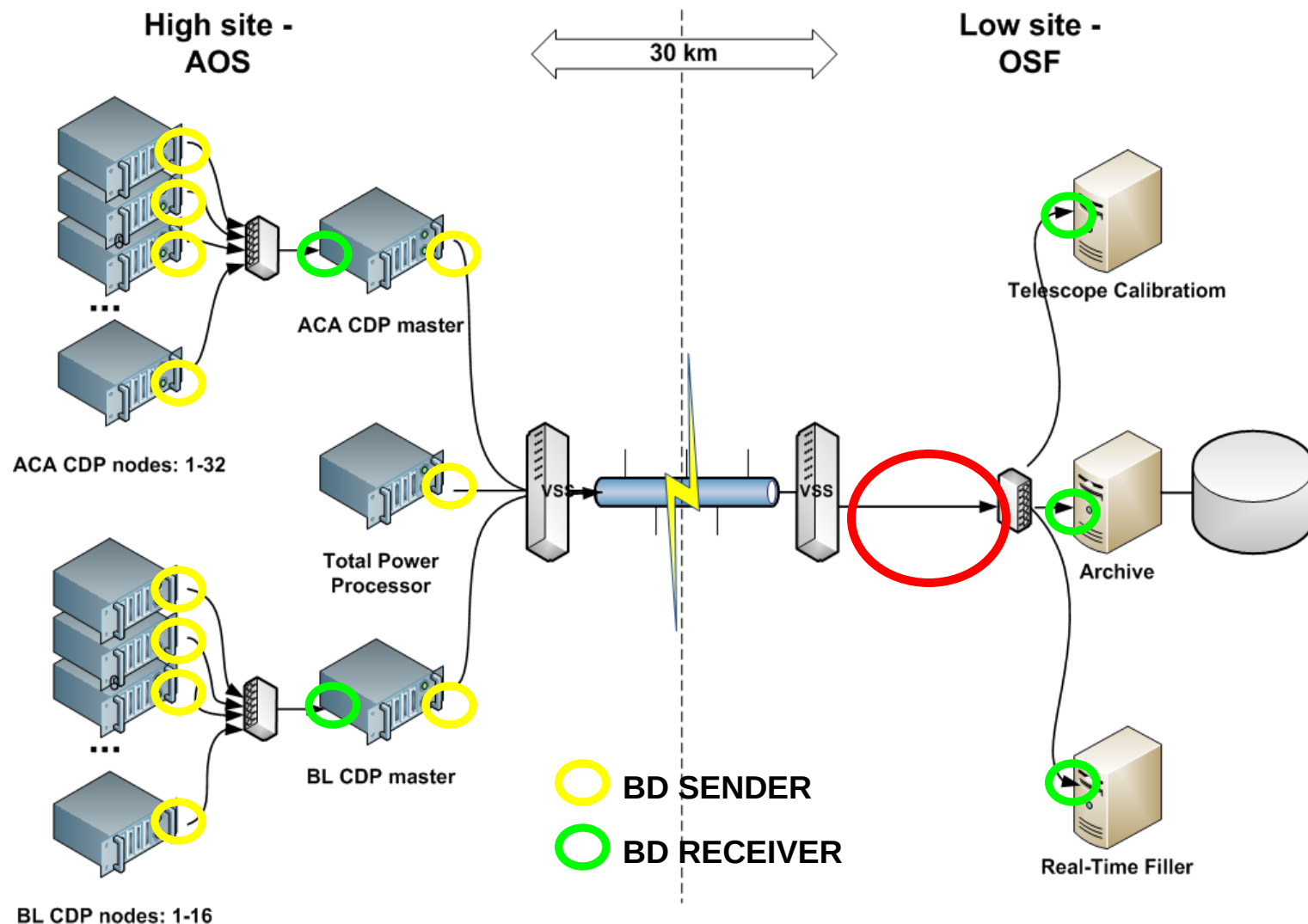
Deployment - old BD



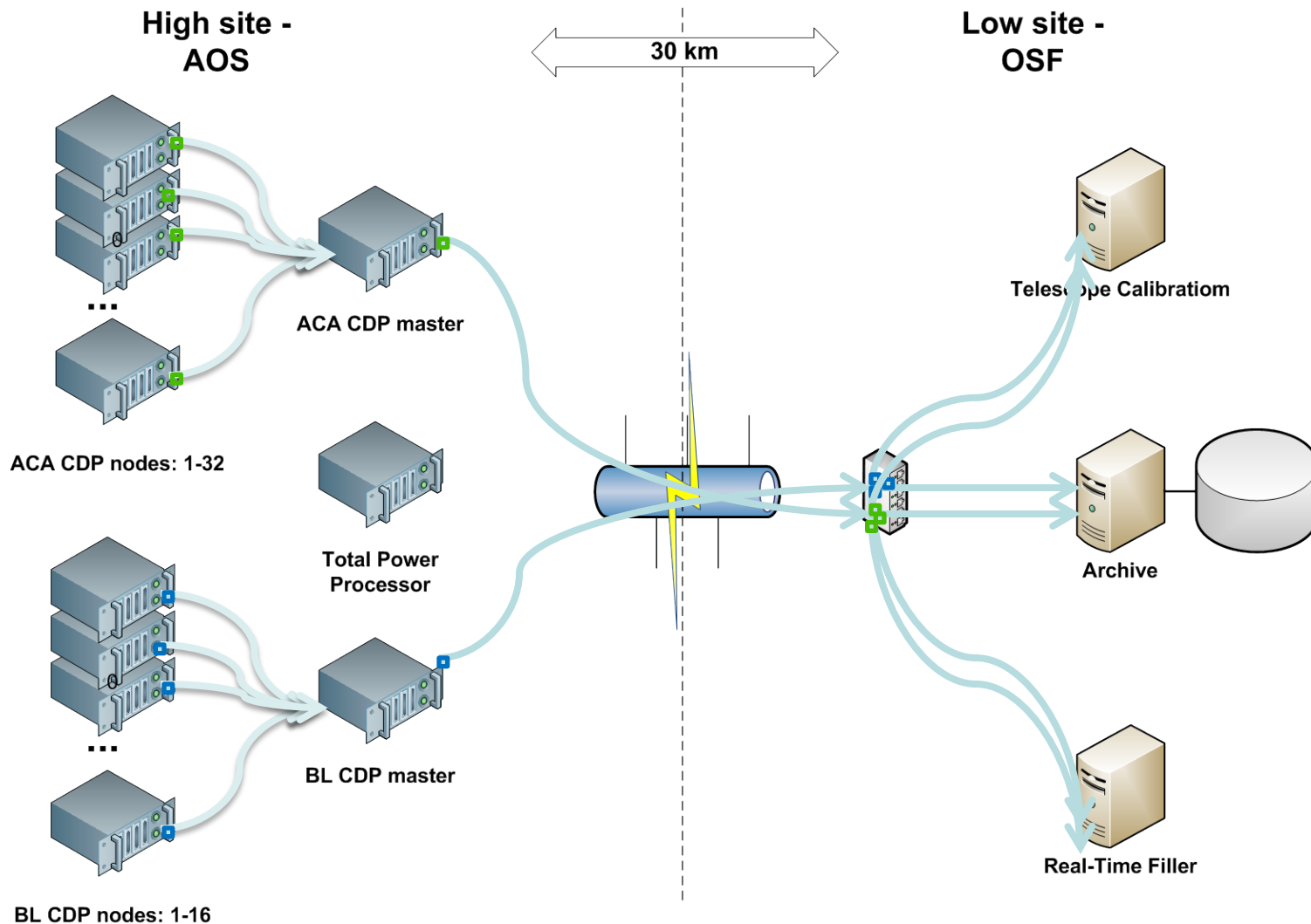
Deployment - old BD



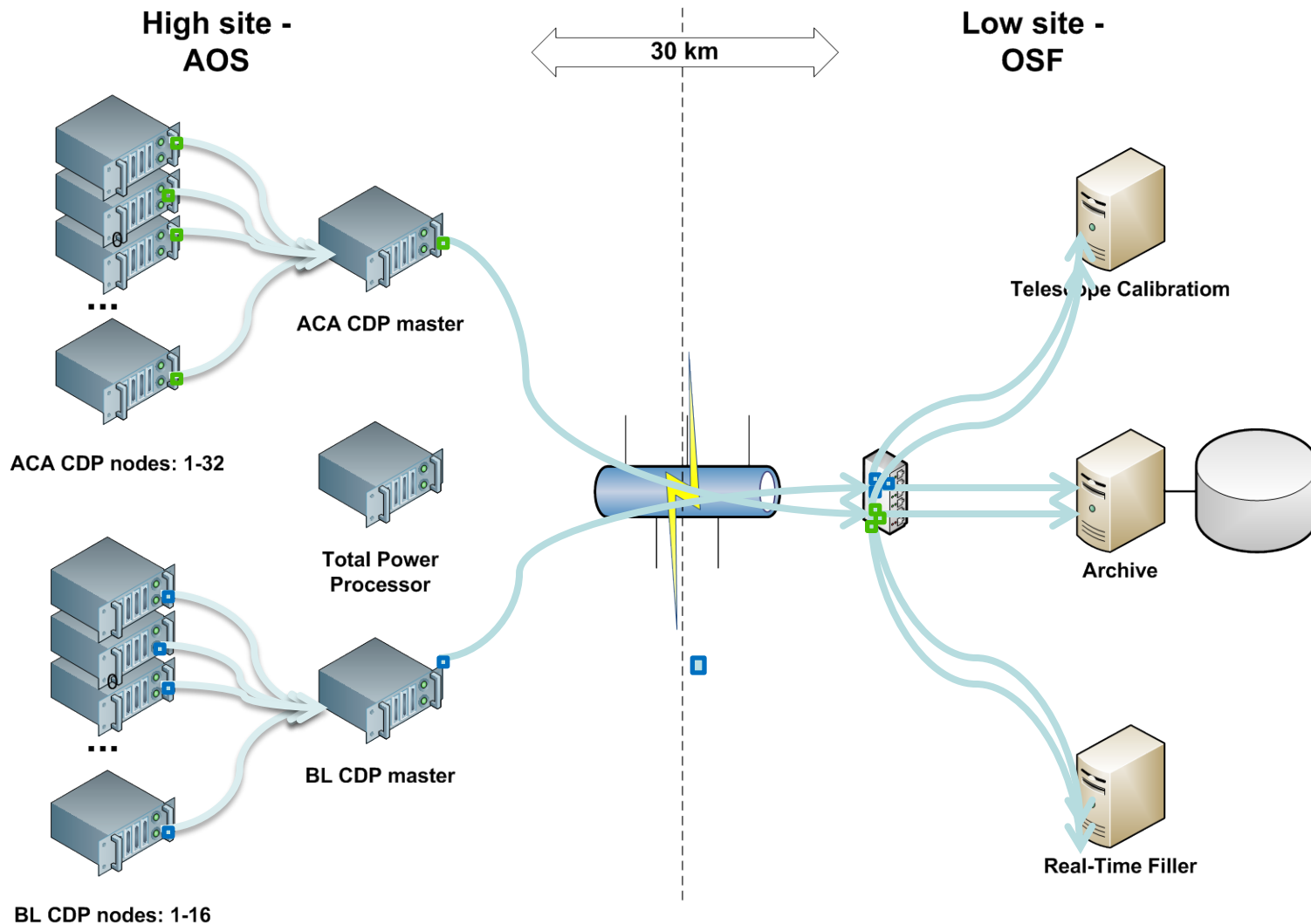
Deployment – new BD



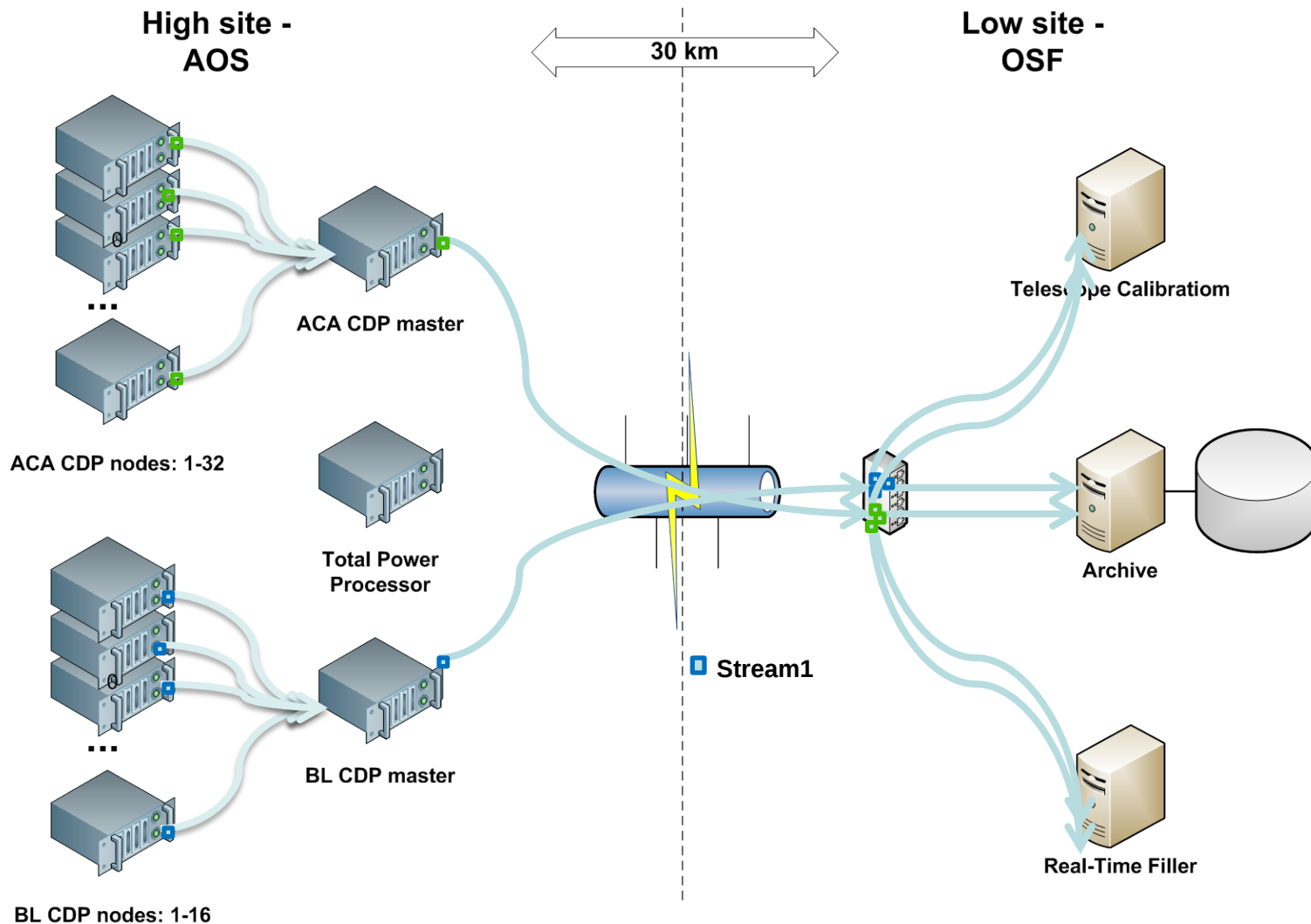
Data transfer



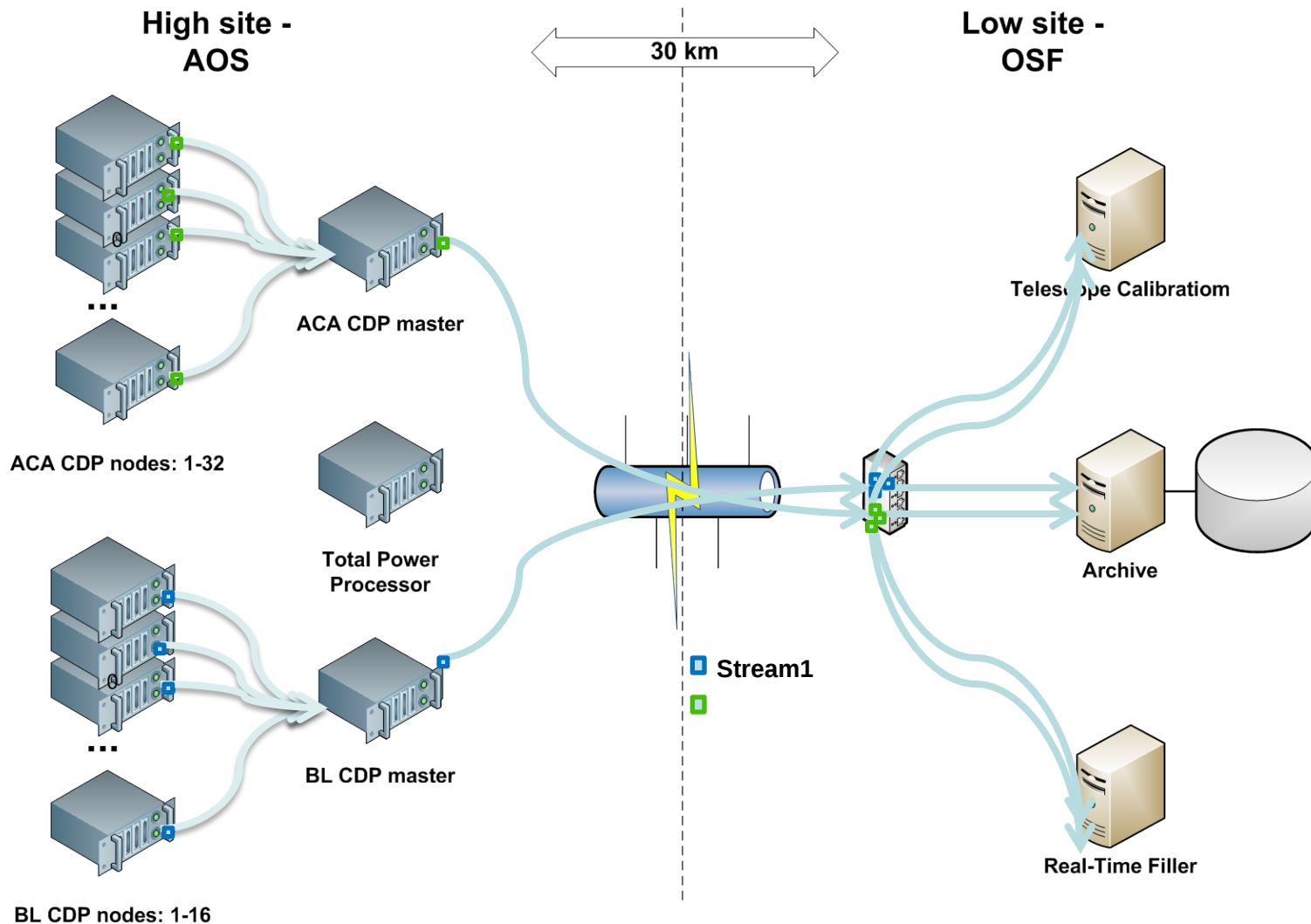
Data transfer



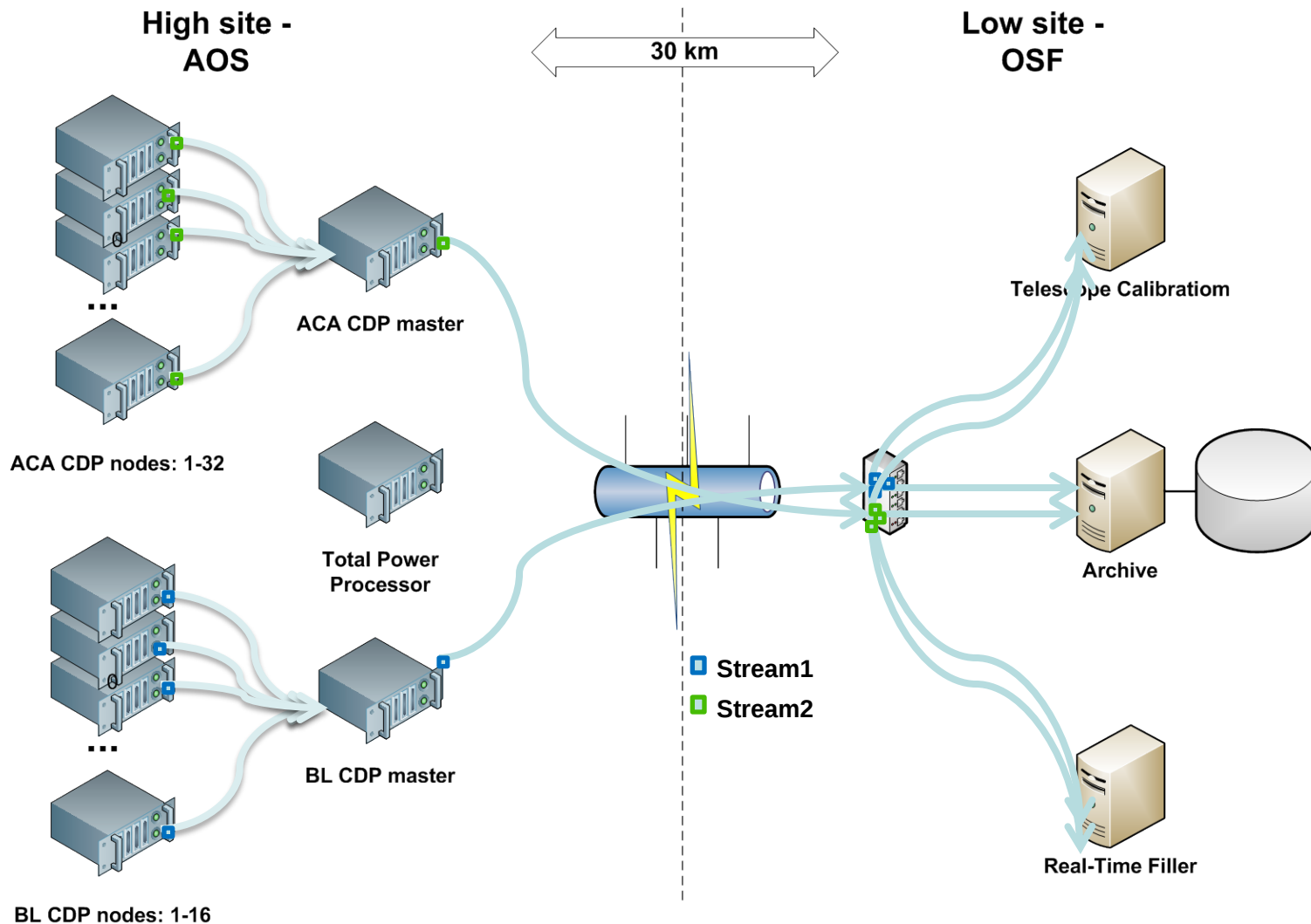
Data transfer



Data transfer



Data transfer



A/V based Implementation

- Based on: TAO Audio/Video Streaming CORBA service implementation
- Limitations:
 - insufficient robustness in case of application problems
 - need of a dedicated machine (w/ many NICs) for distributor
 - only one stream per component => set of distributor/receiver components per array
 - no multithread-safety => problem with parallel arrays/streams
 - “the one & only” implementation w/o support
 - not fit for changed/new requirements



New implementation BulkData New Technology - BDNT



Critical phase – early science operation
Careful planning
Switch between old and new BD

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2011

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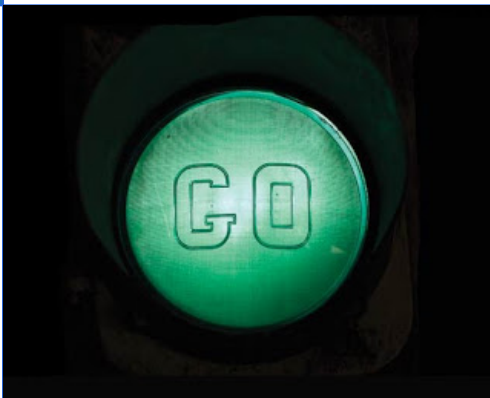


2011

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2011

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March 2013

BDNT- development process

- Reviewed requirements
- Investigated possible technologies => **DDS**:
 - Well established standard
 - Several implementations w/ (commercial) support
 - Used in institutes/industry/military
 - Satisfy our requirements: reliable multicast, ...
- Prototypes: **OpenDDS**, **RTI**, **OpenSplice** and **CoreDX**
- Selected specific implementation => **RTI DDS**:
 - Very stable/documented/supported
- Developed BDNT
- Ported applications: 6 sub-systems
- Tested in STEs and on site => **installed**

BDNT- benefits

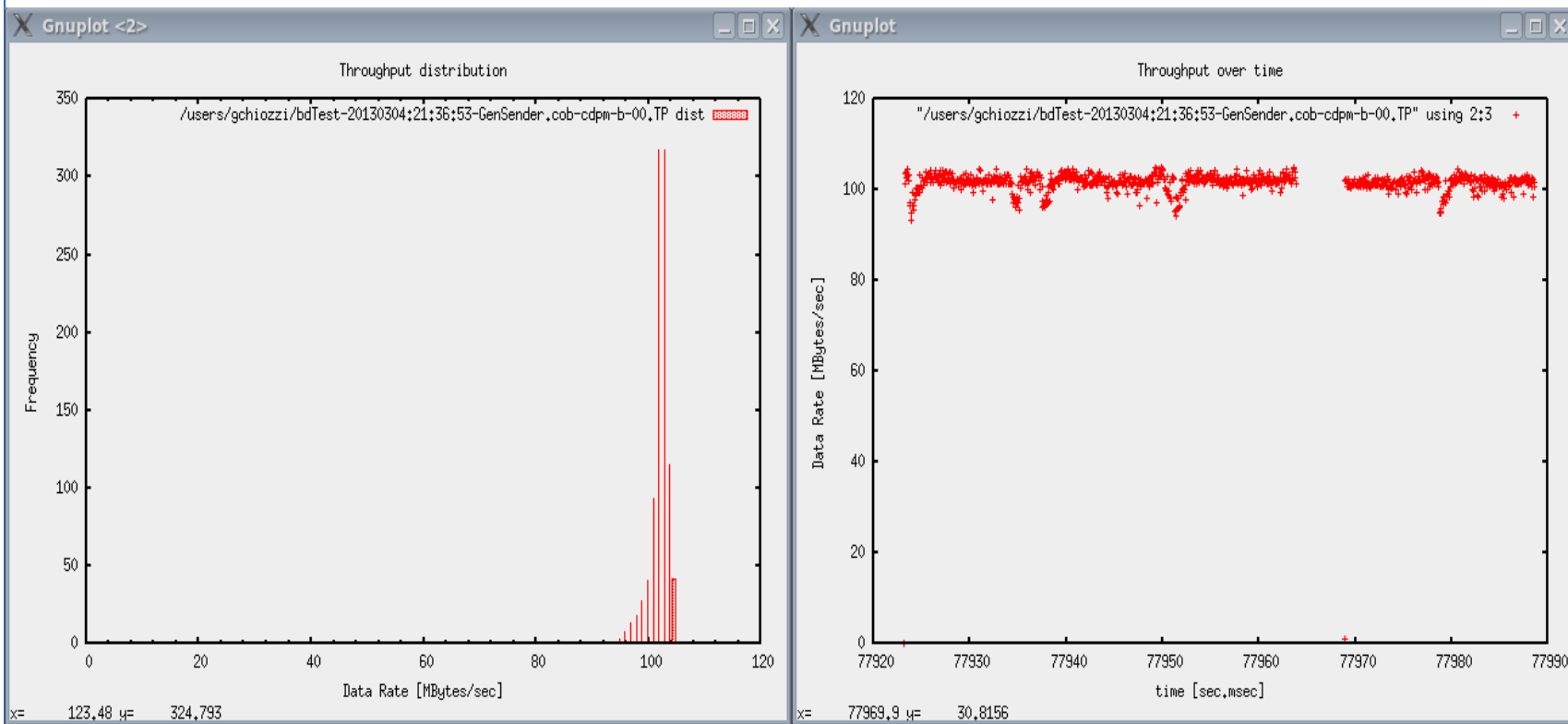
- Improved error handling => improve stability & robustness
- Simpler and more intuitive API
- Reliable multicast instead of distributor & more streams per component => simplified deployment
- Built-in “support” for trouble shooting:
 - Early detection of problems: receiver processing throughput,...
 - Logs details control: configurable levels for detailed protocol diagnostic and statistics
- Generic sender & receiver => synthetic test

Challenges

- Configuration of network infrastructure for DDS (UDP multicast)
 - IGMP
 - Network bonding
- Tuning of DDS QoS (TTL,...)
- Discovery mechanism
- High site -> low site (30km) to 3 receivers: 900Mbit/s
- “Mixing” underlying protocol of RTPS:
 - “Reliable” multicast UDP for one to many
 - TCP for many to one
- BD chain: proper deployment (of receivers), ...

Synthetic test example

Problem multicasting from a machine with network bonding (2 NICs) to 3 machines with a single NIC



Problem solved by DDS QoS tuning

Conclusions

- In operation since March 2013
- Not yet tested at “full speed” in operation.
Only with: 54 out of 66 antennas
50% of the expected CORR data rate
- Big improvement in stability and availability of the whole SW: no need to restart the whole SW, ...
- DDS is mature enough and the RTI implementation is very stable, well documented with good support
- Good understanding of what is going on in the whole BD chain, including applications, is necessary
- It is essential to have the right tools for troubleshooting



Questions

