



EUROPEAN
SPALLATION
SOURCE

The Integrated Control System at ESS

Miha Reščič, Cosylab

Speaker Introduction

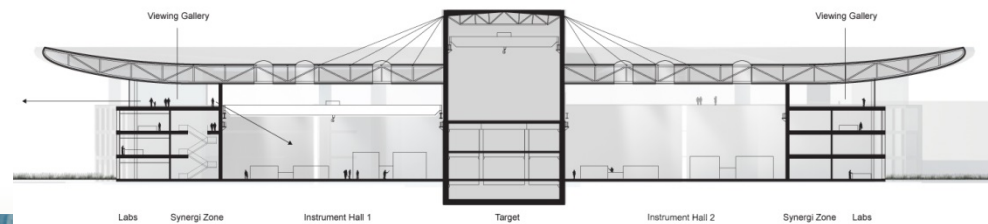
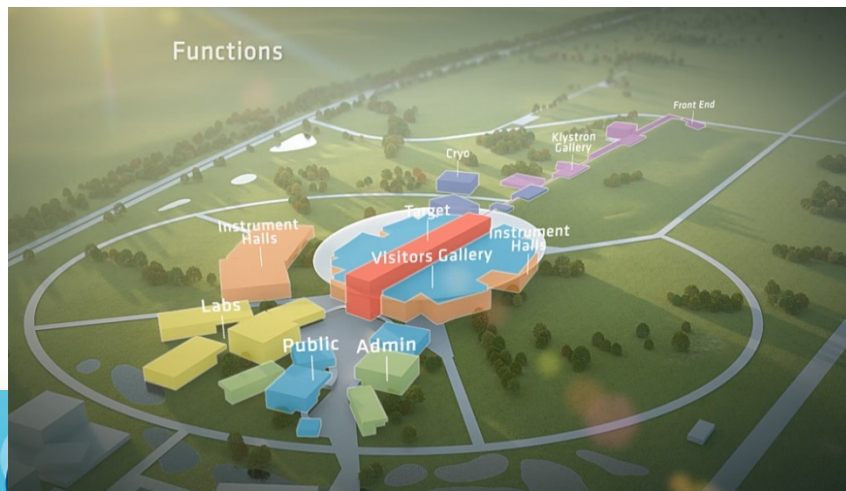
- Standing in for
Garry Trahern, Head of ICS Division at ESS
- Miha Reščič, Slovenia
 - Employed: Cosylab, Slovenia
 - Working at: ESS, Lund, Sweden
- Main responsibilities:
 - Setup the project and organization to start the Construction of ICS, act as the “ICS Enforcer”
 - 3 years on the project, 2 onsite embedded

ESS Overview

- The European Spallation Source (ESS) will house the most powerful proton linac ever built.
 - The average beam power will be 5 MW
- Built in Lund, Sweden with first neutrons in 2019
- End of construction in 2025 with 22 instruments online



What Will ESS Look Like?



SOURCE

ICS Programme and Organization evolution

- Organizational structure

[2010] Team

[2013] Division

[2011] Group

- Project structure

[2010] Activity

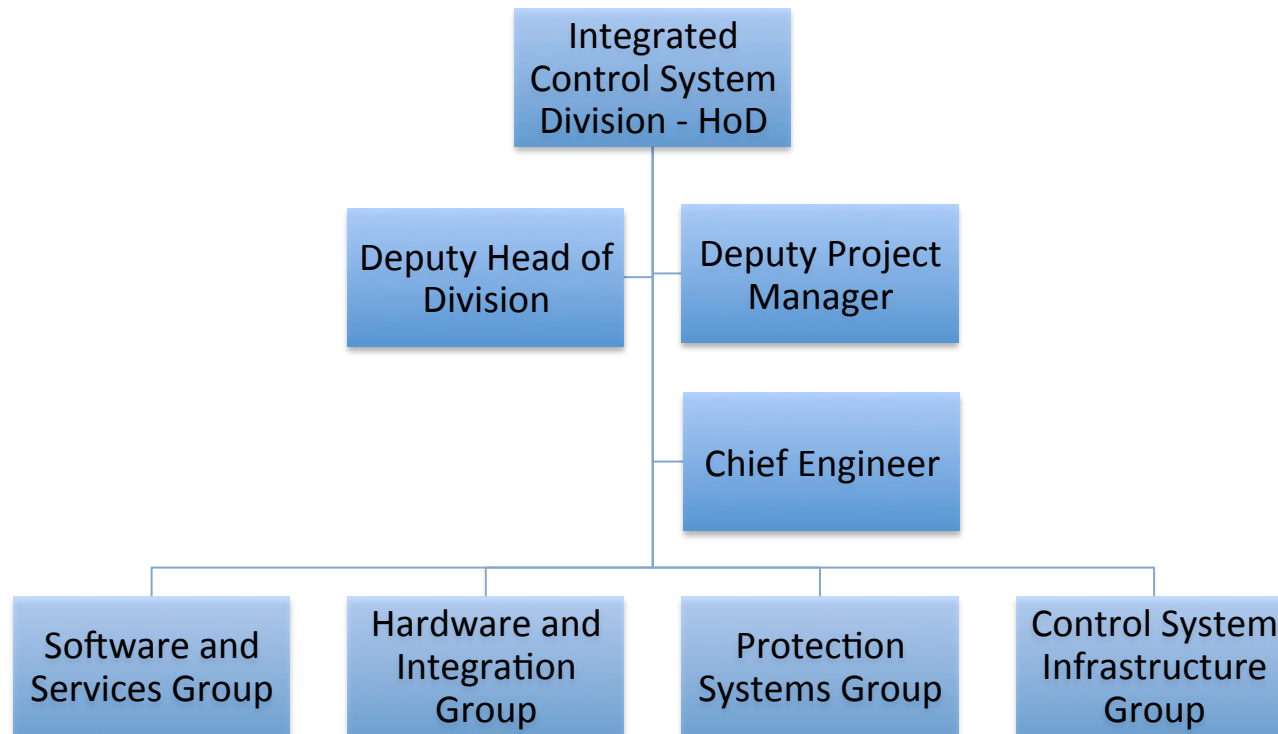
[2012] Project

Top Level Requirements

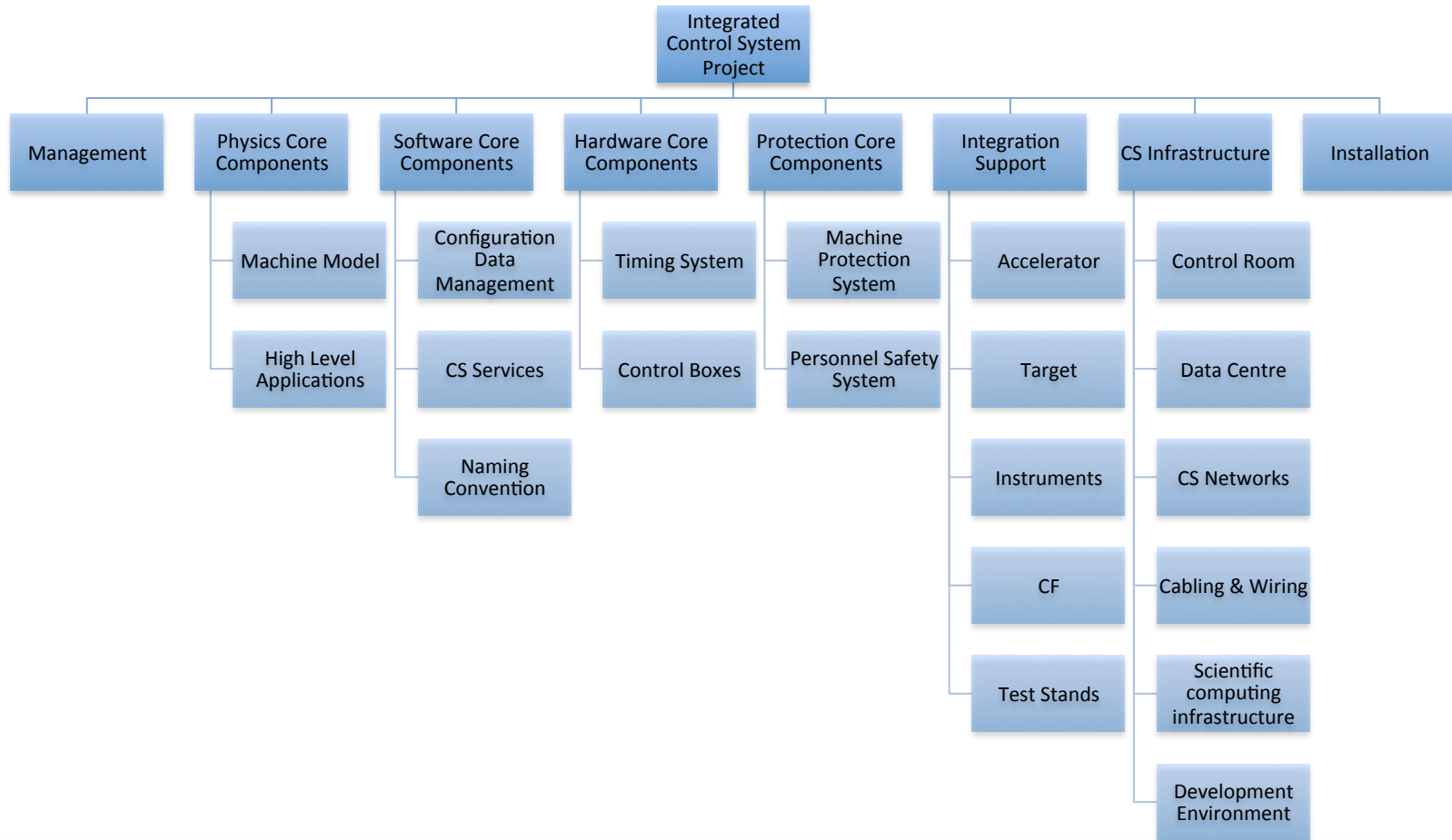
- Provide the following to ESS:
 - Control system framework for monitoring and control of **accelerator, target, instruments** and **CF**
 - Timing service for **generating events, synchronization** of devices and **time stamping** (in the ns range)
 - Control system services and applications to perform **commissioning** and **operations**
 - **Control Boxes** and **Integration Support** to stakeholders
 - **Machine Protection** and **Personnel Safety** systems
 - Control Room(s)
- Constraining requirements
 - High reliability and availability (**>95%**)!



ESS Integrated Control Systems Division Organization

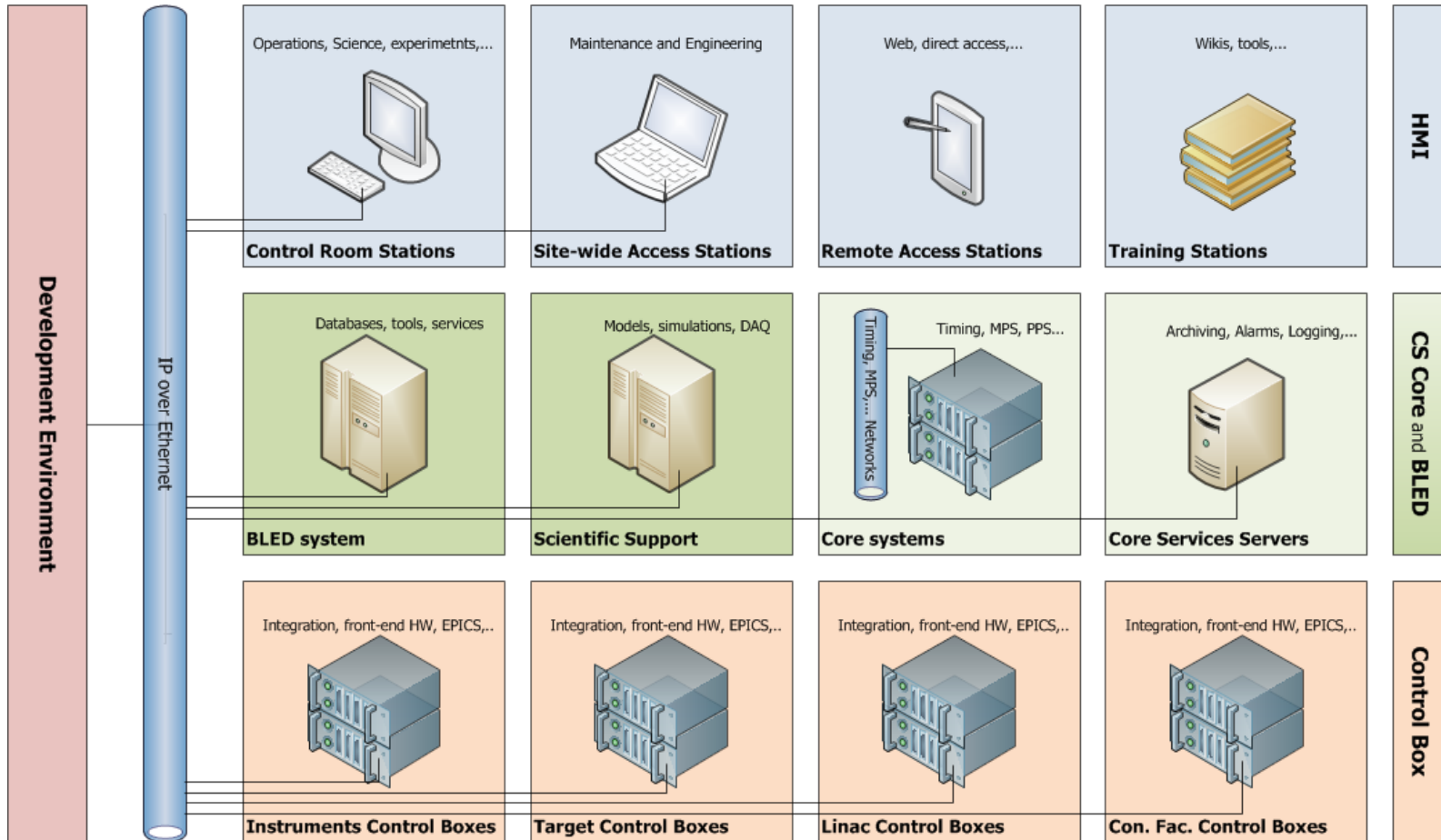


ESS Integrated Control Systems Project Organization

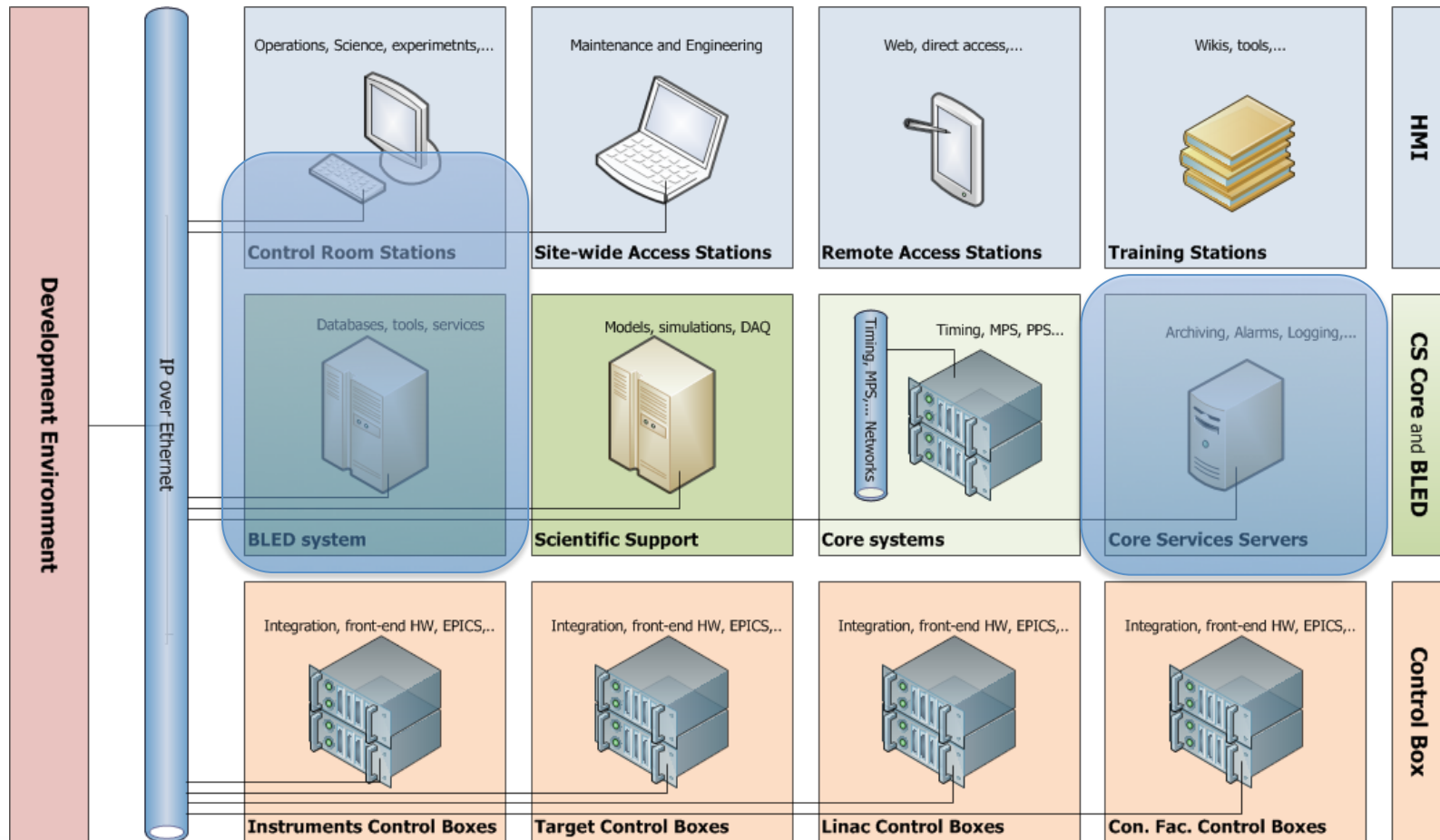


ICS Architecture

- The three-tier architecture



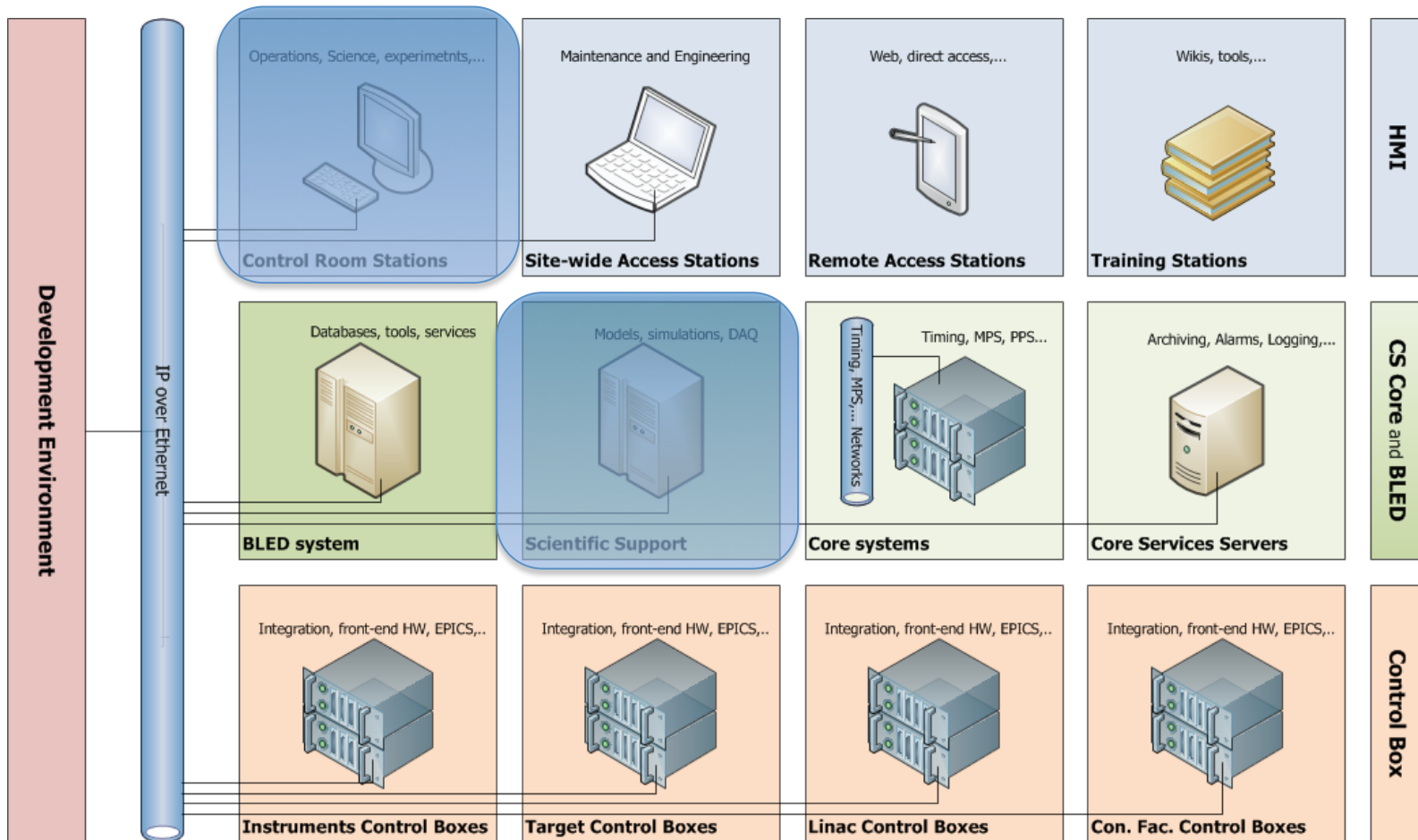
Software Core Components



Software Core Components

- **Configuration Data Management**
 - The collection, storage, and distribution of configuration, calibration, location ... data
- **Control System Services**
 - Alarm handling Archiving, logging, long term storage, CSS, Logbook, Role Based Access Control (RBAC) ...
- **Naming Convention**
 - *SSSS-BBBB:DDDD-III:TTTIIIXXX*
- **Scope**
 - Accelerator, Target, Neutron Instruments, and Conventional Facilities

Physics Core Components

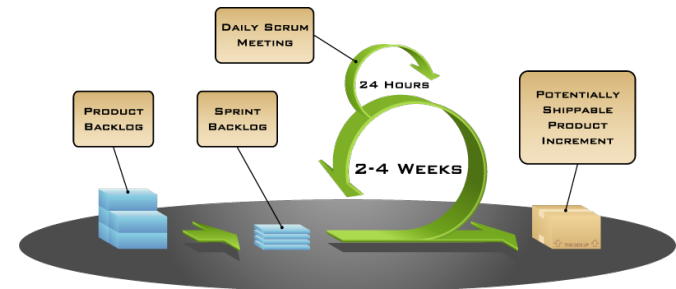


Physics Core Components

- **Purpose**
 - Model the machine and provide users the access to the control system and models
- **Machine Model**
 - Online models: OpenXAL, ELS, (JELS) ...
 - Offline models: TraceWin, MadX ...
- **High level applications**
 - Everything interfacing the users, operators, engineers, integrators, physicists, scientists, observers, innocent bystanders ...
 - GUIs, Applications, Scripts, Tools ...
- **Scope**
 - **Accelerator, Target, Neutron Instruments, and Conventional Facilities**

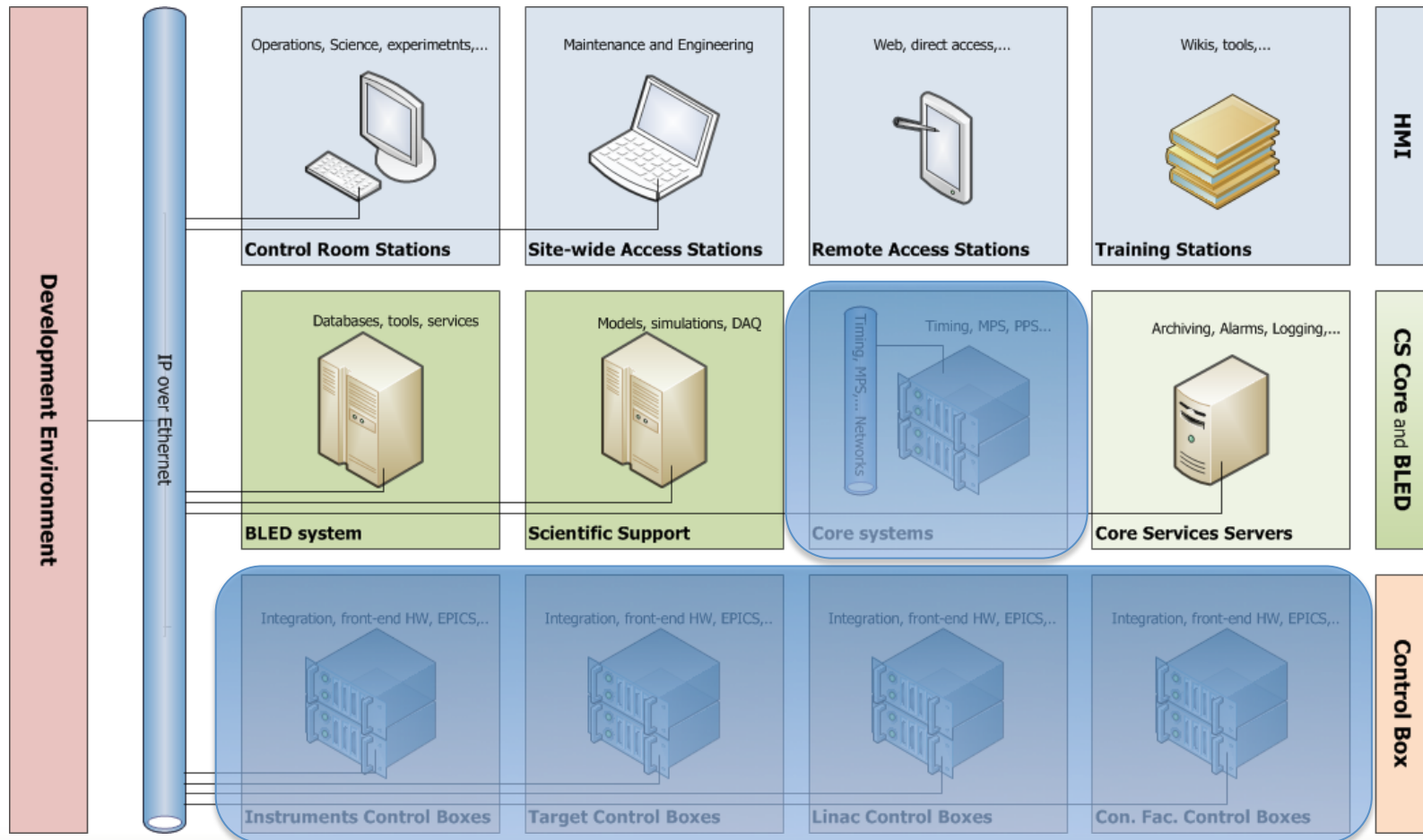
Issues and challenges

- Structuring of High-Level apps and Physics core
 - Scope of modelling, machine models as services?
 - What is (High level) Applications layer?
- (Re)usability
- Collaborations
 - DISCS (Distributed information Services for Control Systems)
 - OpenXAL
- Getting users on-board
 - Agile approach
 - Scrums, sprints, backlogs



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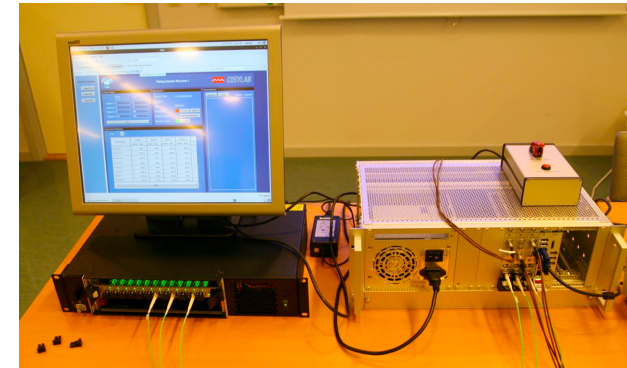
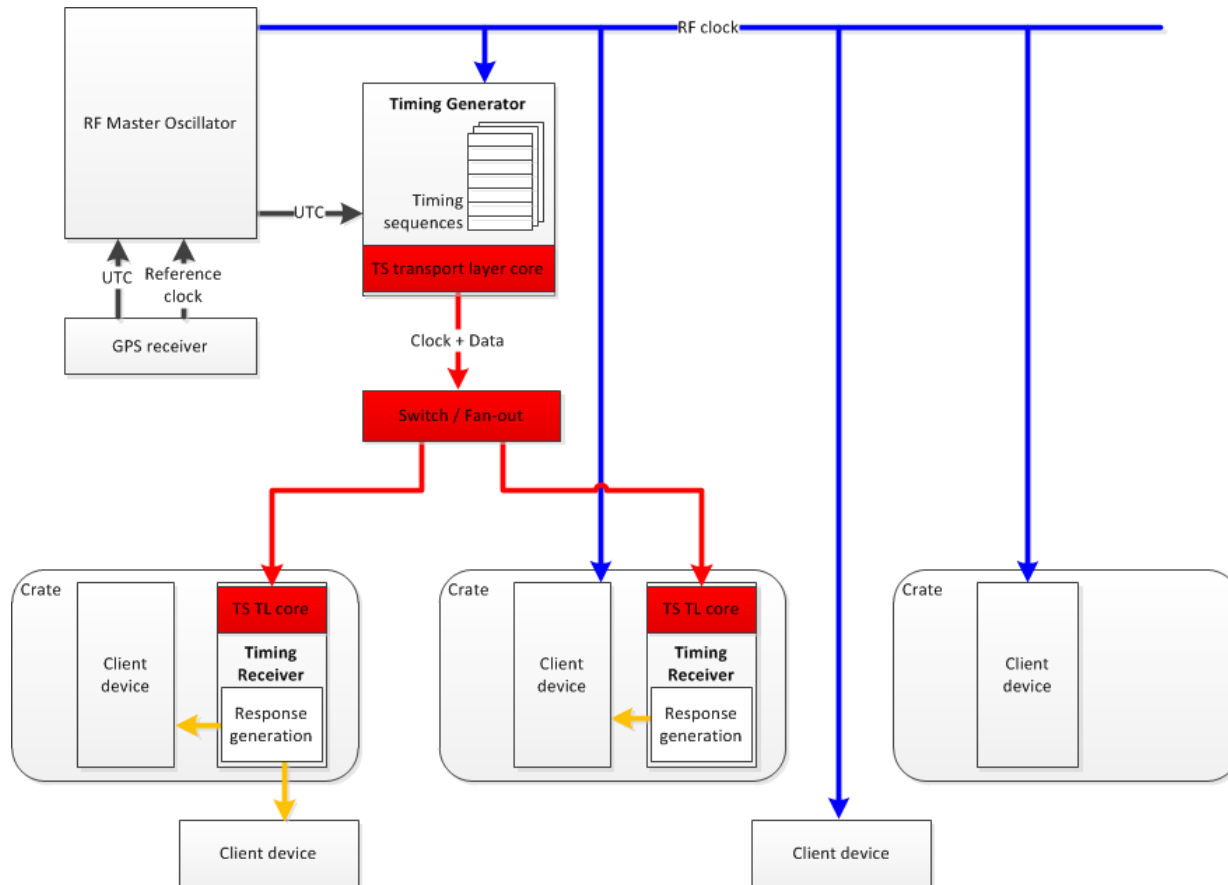
Hardware Core Components



ESS Timing System

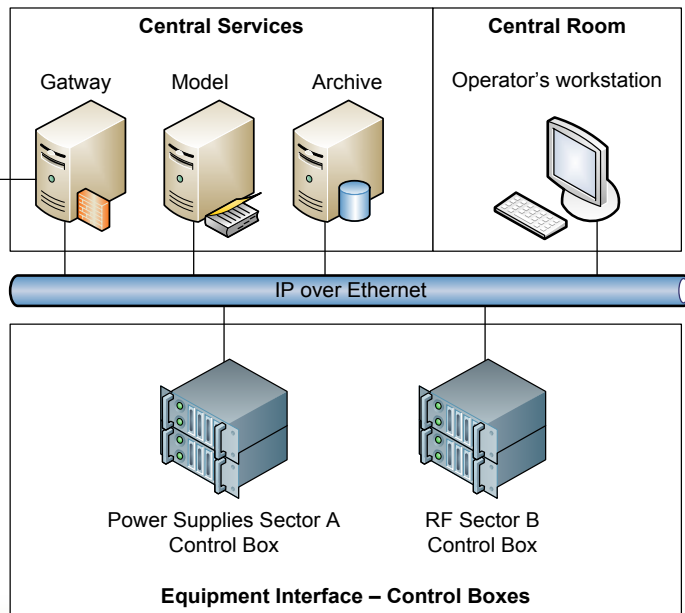
Characteristics

- Clock frequency:
88 Mhz
- Event Granularity:
20 ns
- Jitter: **40 ps**
- Prototype platform:
MRF
- Uni-directional system



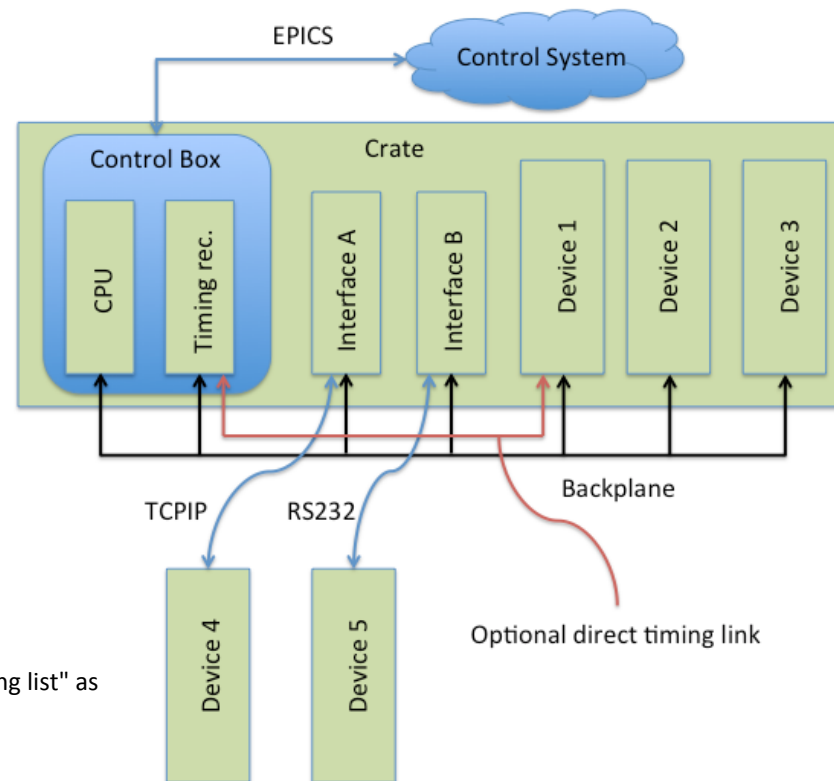
Control Boxes

- “Servers controlling a collection of equipment”
- Also, HW Standardization



Control Boxes, the scope and responsibilities

- Statement, Fact(!):
 - “ICS provides control boxes to **ALL** the stakeholders”!
 - ... Well accepted
 - ... **But**, what really is a control box?



Control Box: CPU board + Timing Receiver + ICS Software

ICS Software: ICS CODAC* distribution and support for items from the "ICS shopping list" as defined by the list

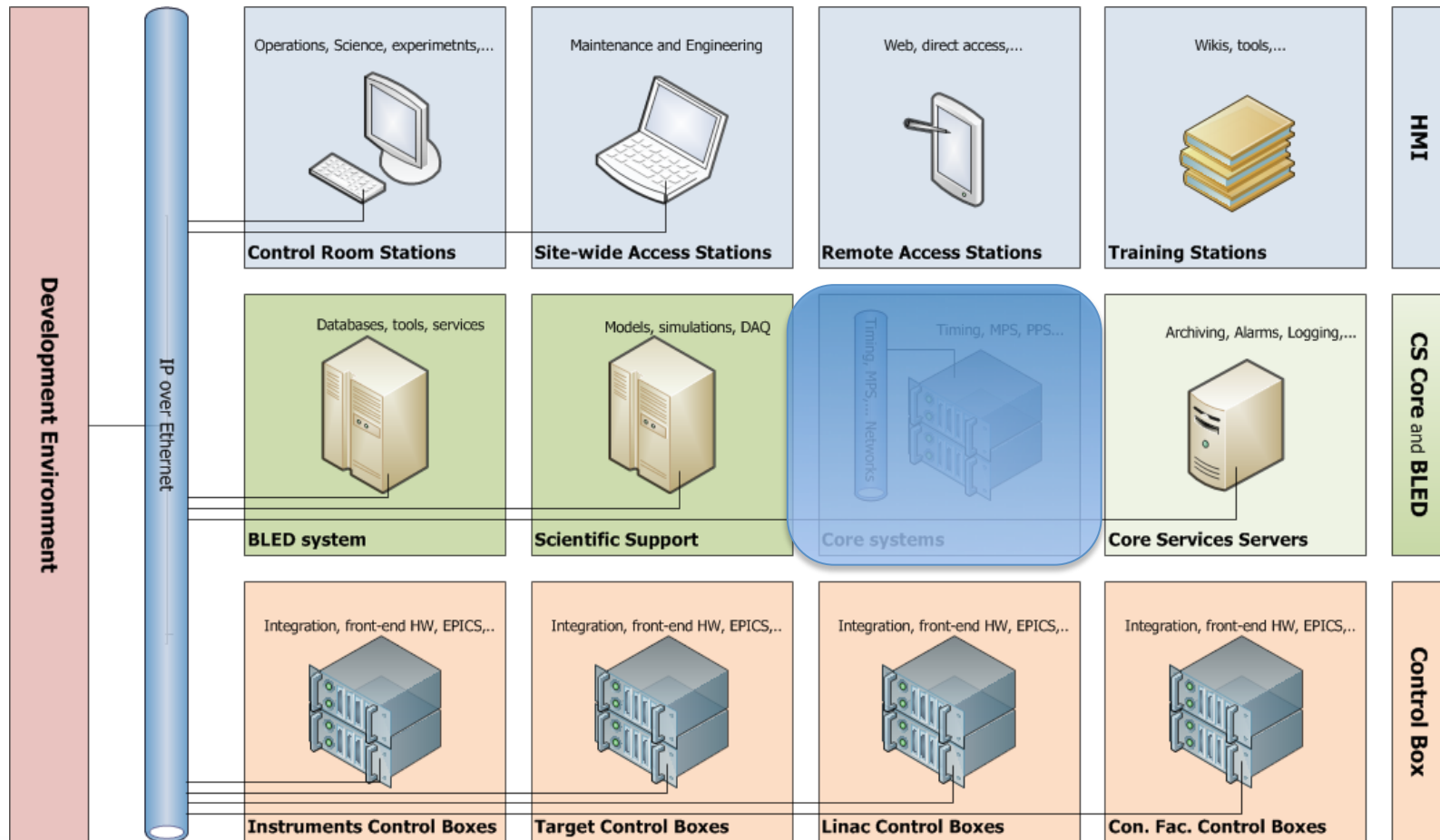
Ownership, responsibility and costing for Control Box: **ICS**

Example: uTCA CPU board, Operating system (Scientific Linux 6.0), ICS CODAC 3.0 distribution (EPICS 3.14 including Struck SIS8300 kernel drivers, EPICS device support, CSS etc.), uTCA Timing Receiver with EPICS device support.

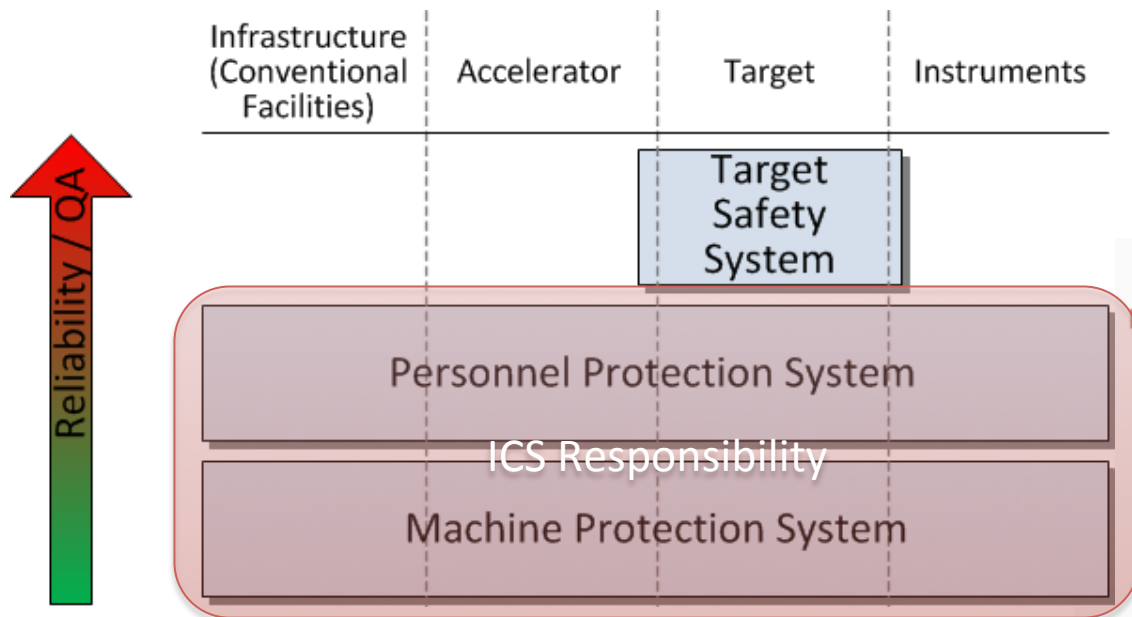
HW issues and challenges

- Interface control
 - ICS <-> Stakeholder,
 - Control Box <-> Stakeholder System
- Enforcing and maintaining responsibility
- Support and knowledge transfer
- Compliance to “standards”
 - HW, SW, tools etc.
- HW Platform(s)
 - cPCI, uTCA for Physics (MTCA.4)

Protection Core Components



Protection Core Components



Add another family member

Relationship Status:

Interested in:

Looking for:

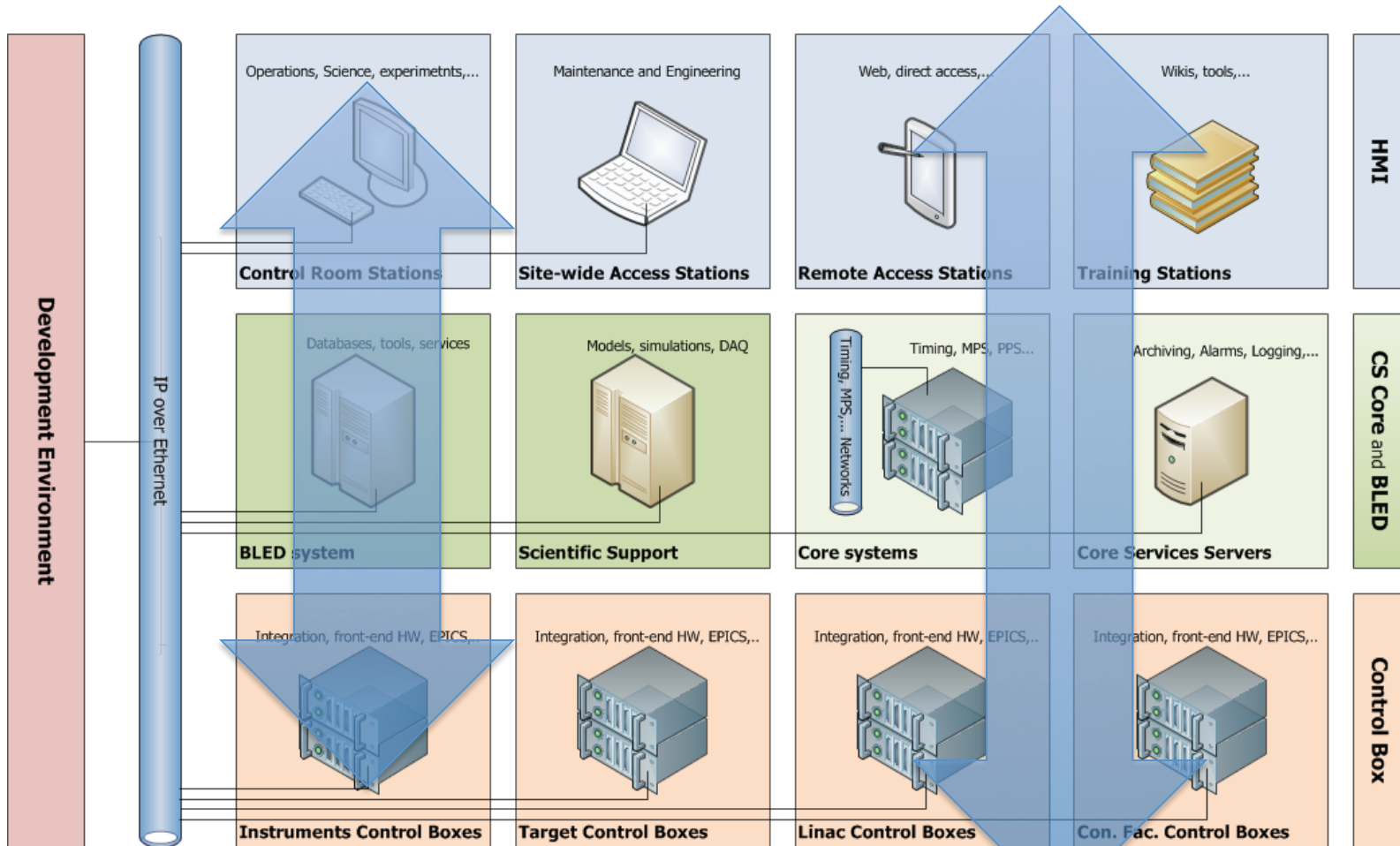
Single
In a Relationship
Engaged
Married
It's Complicated
In an Open Relationship
Widowed

☐ Networking

Political Views:

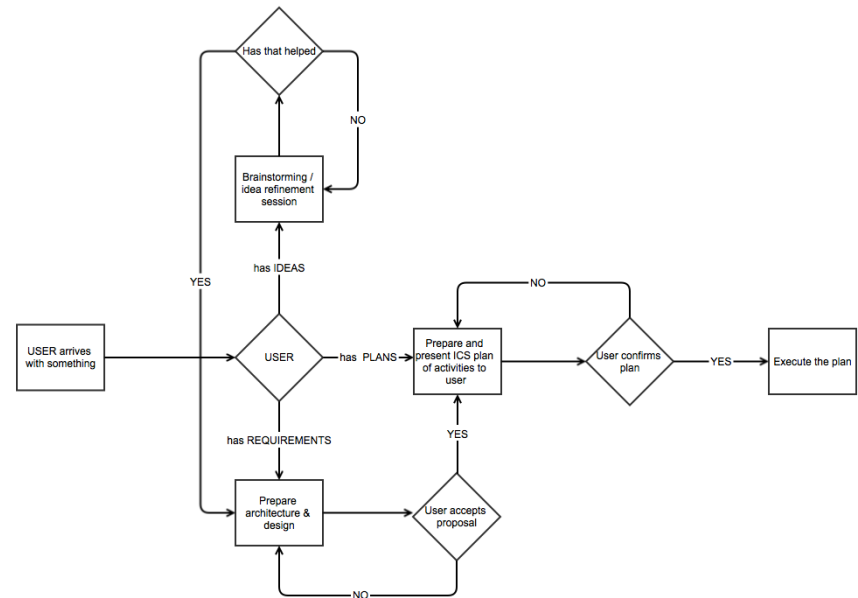
Religious Views:

Integration Support

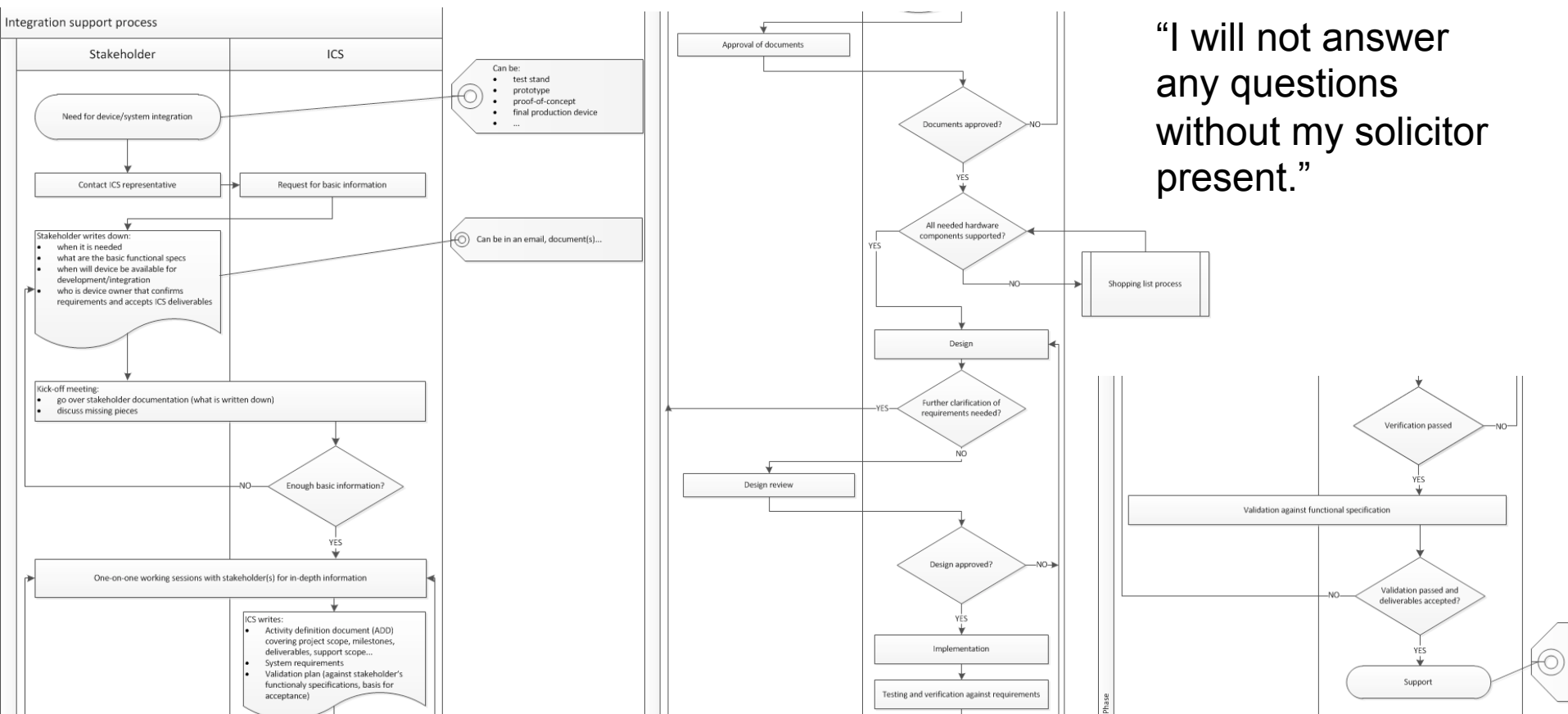


Integration Support, motivation

- A common way to meet stakeholder requirements and needs to get the job done!
- Stakeholders approach ICS with:
 - Requirements
 - Plans
 - Orders
 - Money
 - Equipment
 - Ideas
 - Other

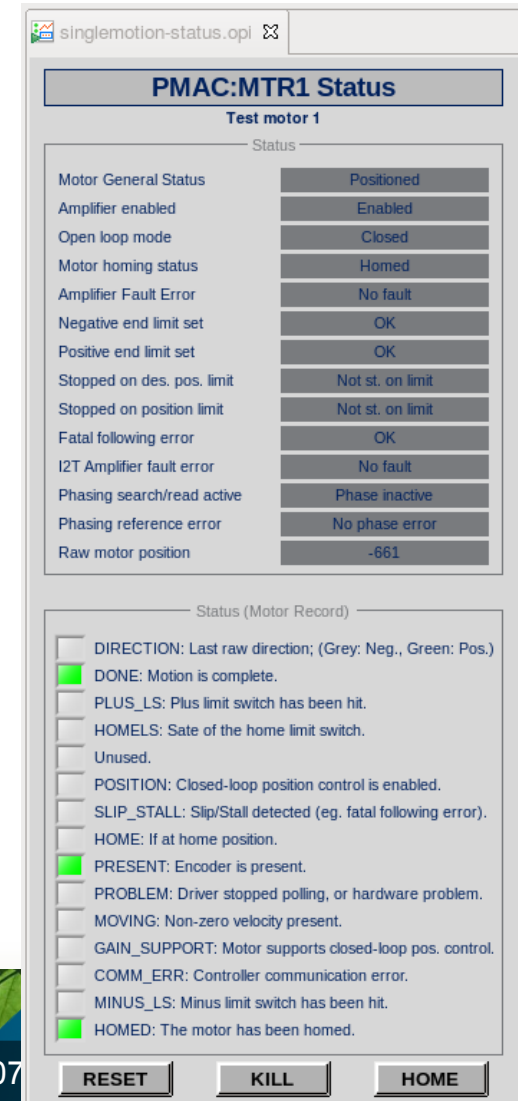
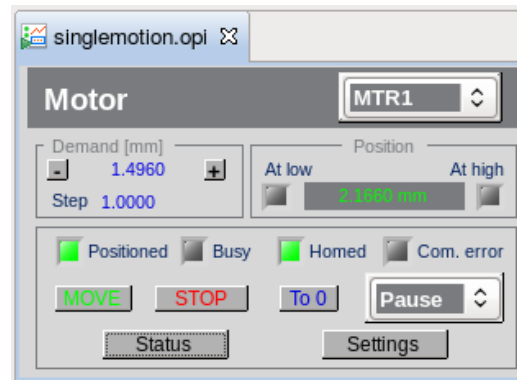
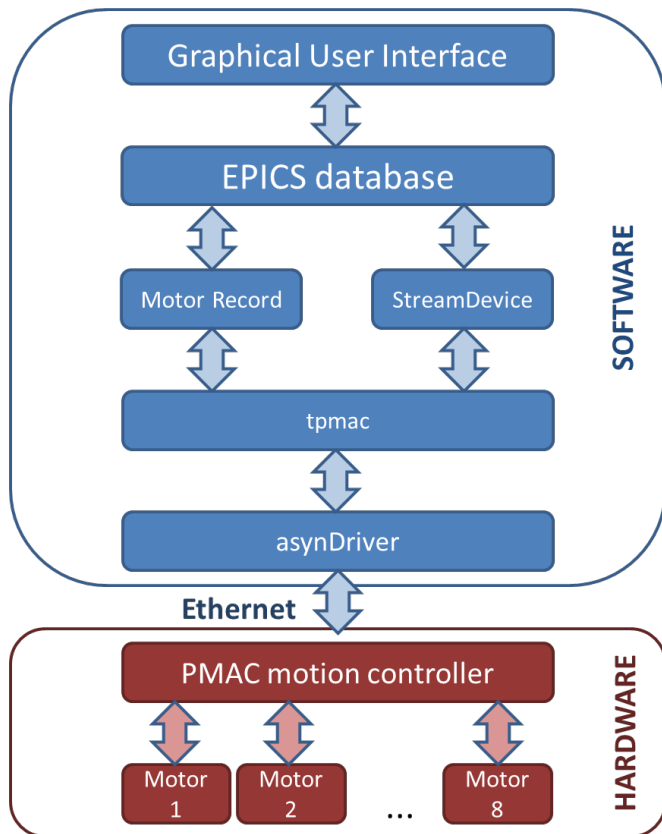


ICS Integration support flow chart



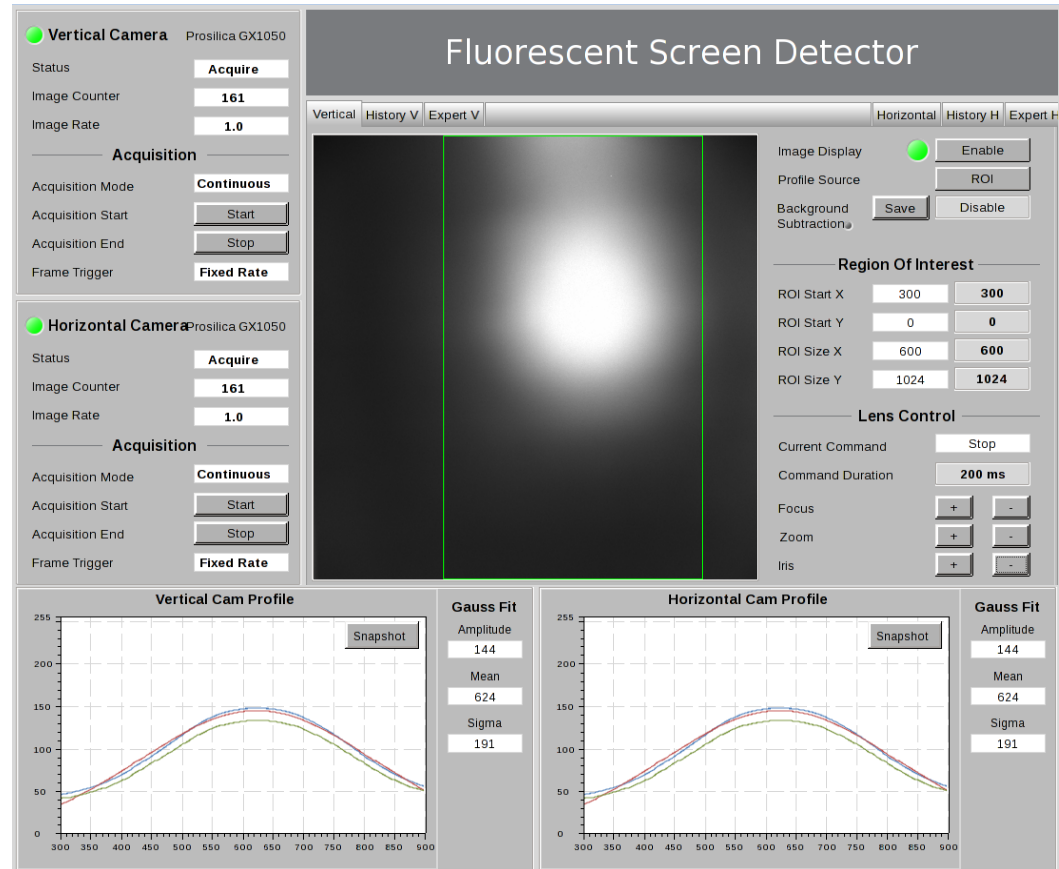
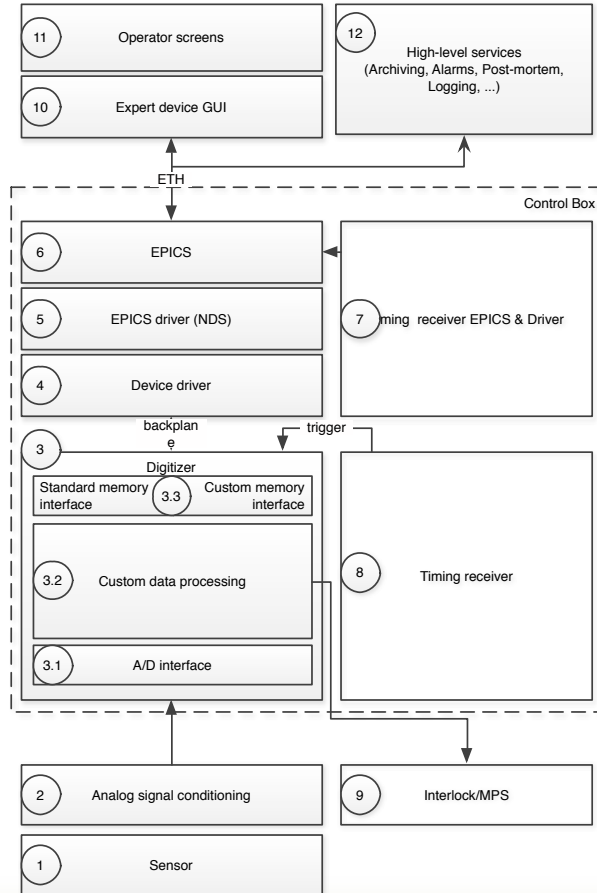
Integration support examples

- DeltaTau GeoBrick motion control



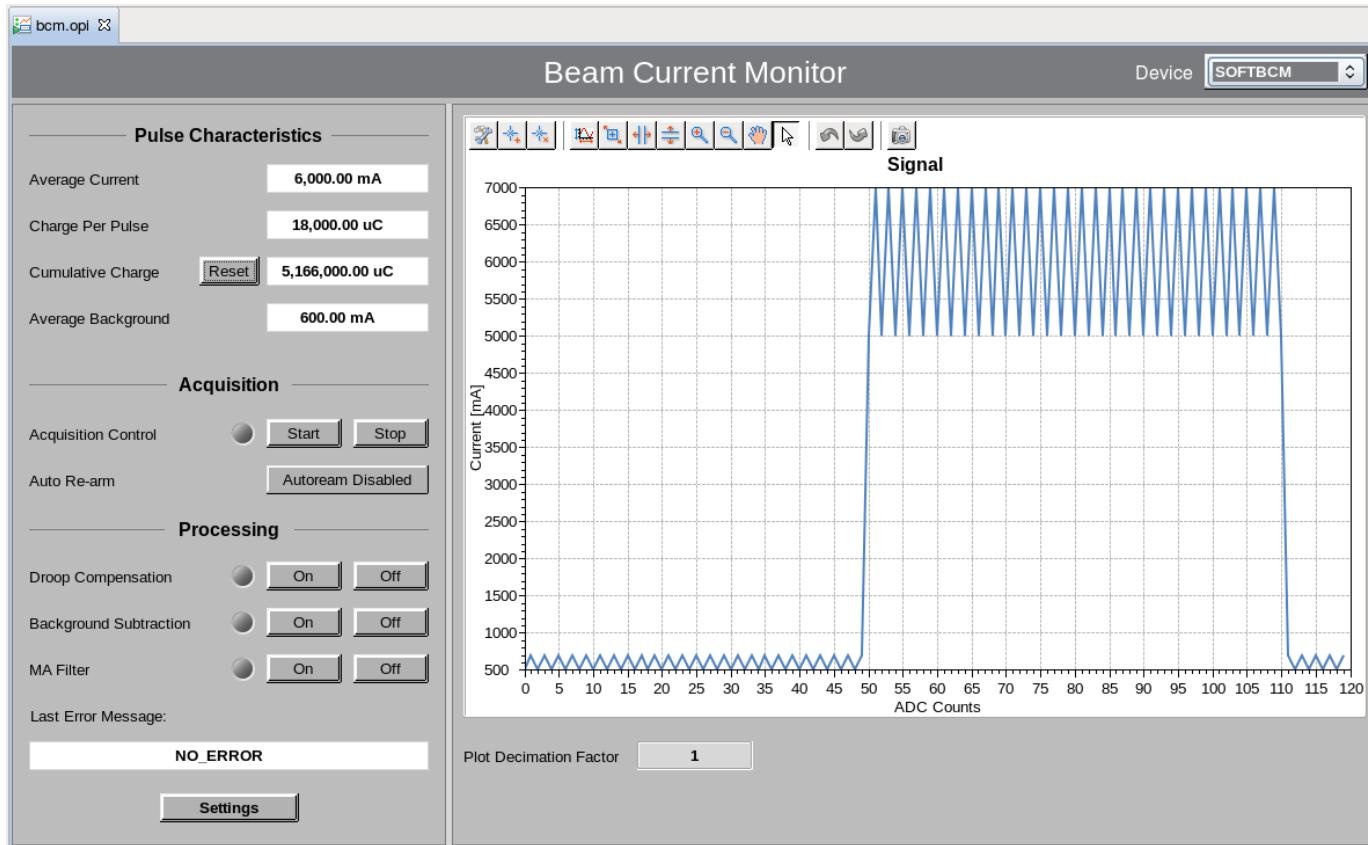
Integration support examples

- Beam diagnostics



Integration support examples

- Beam diagnostics



Integration support examples

- RF

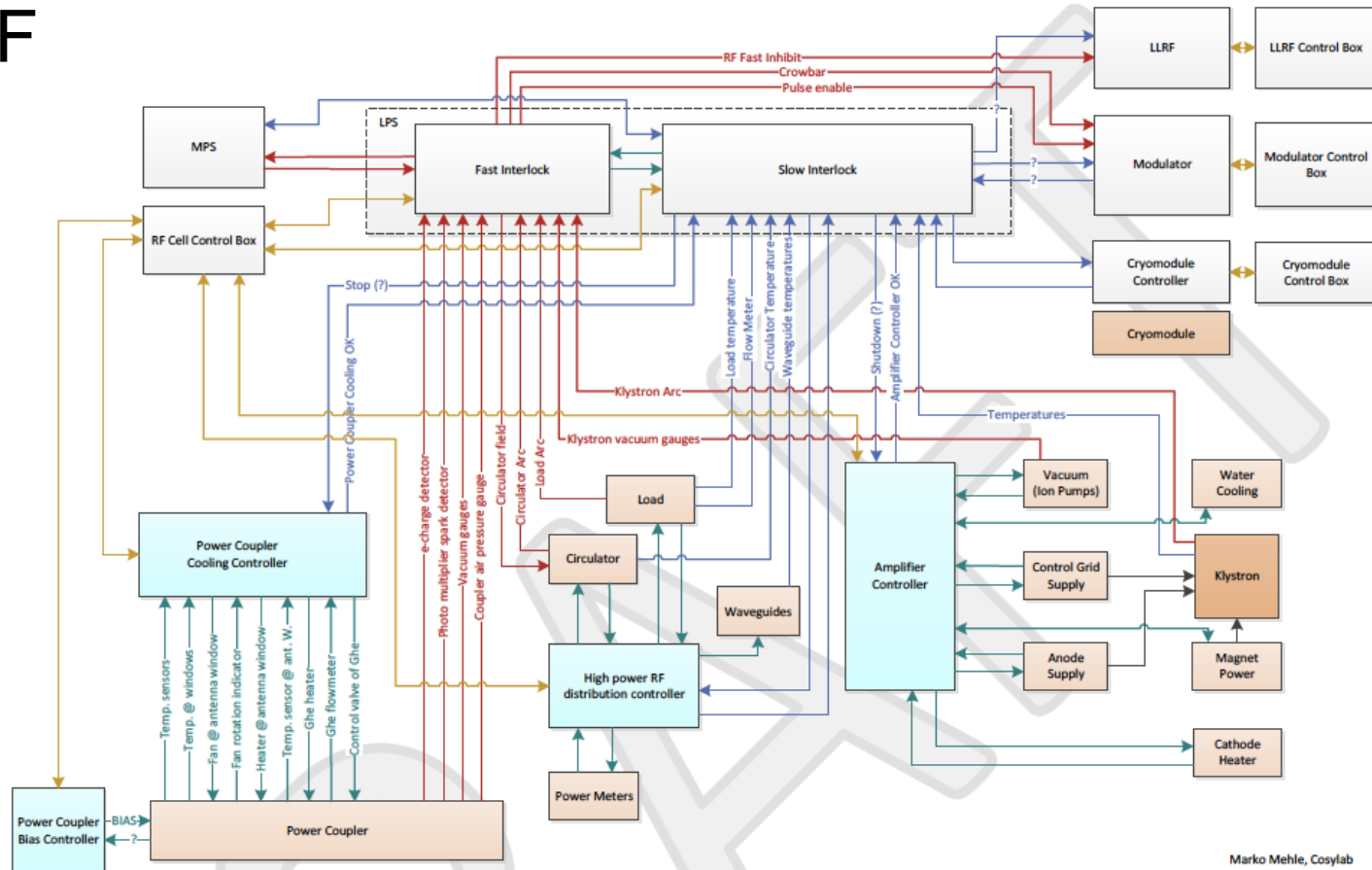
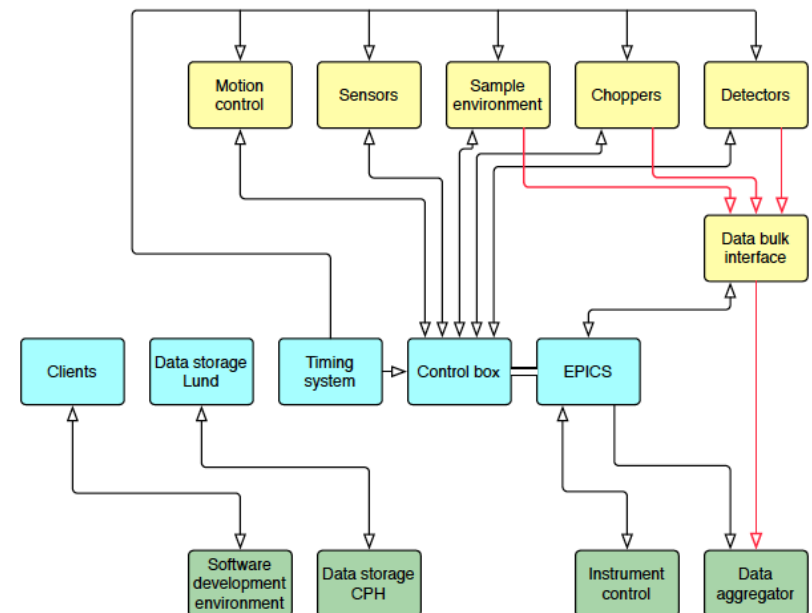
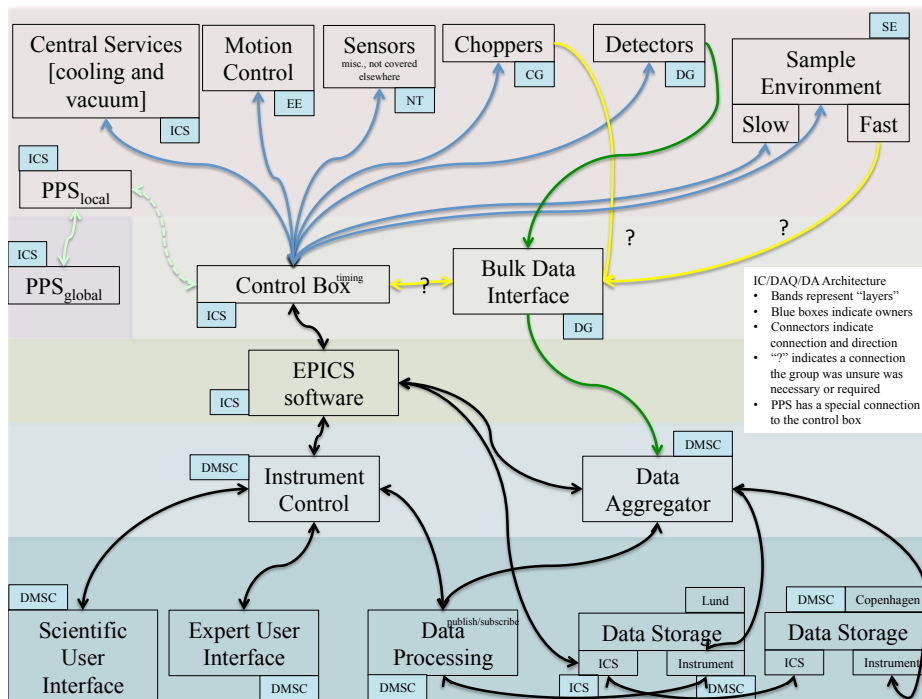


Figure 1: RF Cell Control & Protection systems

Marko Mehle, Cosylab

Integration support examples

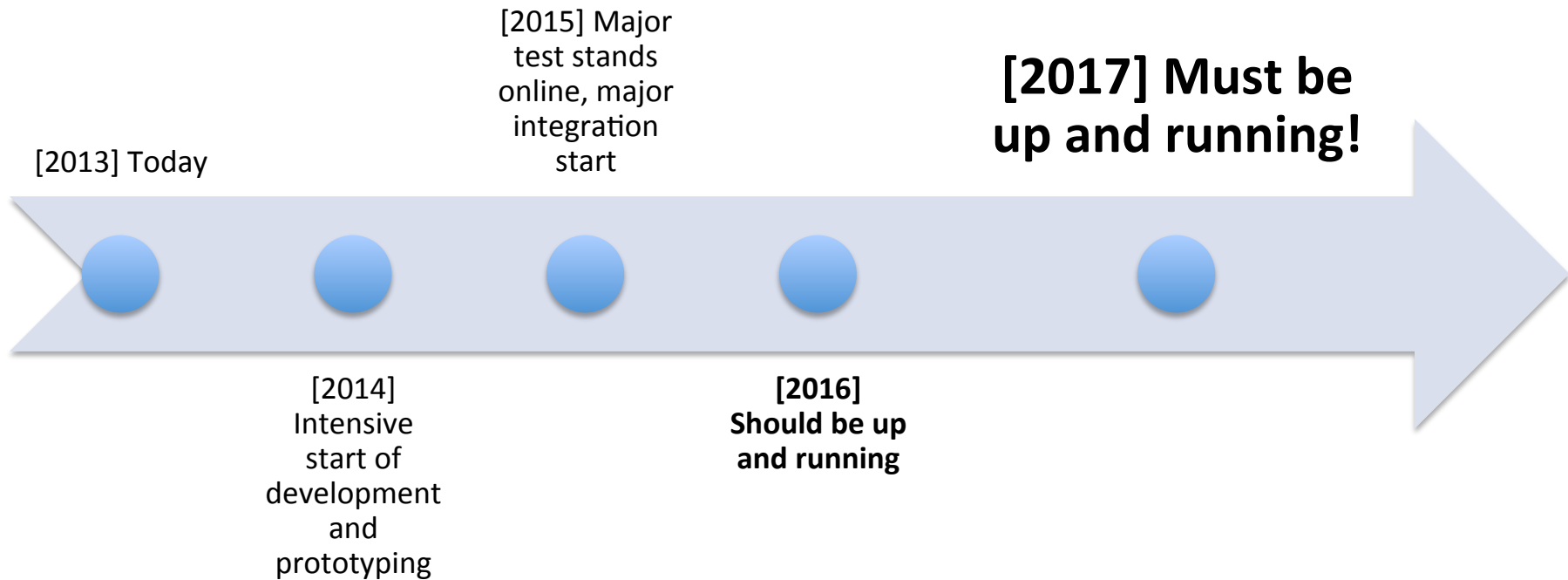
- Scientific Projects Division (Neutron Instruments)



Integration issues and challenges

- Establishing and driving the process
- Communication and transparency
 - Who is responsible for what, who does what, at what meeting we discuss what?
- Costing
- Bringing the users on-board

Facts



Conclusions

- We have: **the goal**, a **plan** and a **strategy**
- We are enforcing the strategy and modifying the plan accordingly
- We need: commitment, feedback, good team members and lots, **lots** of luck!

Thank You!