TANGO CONTROL SYSTEM MANAGEMENT TOOL

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Abstract

TANGO [1] is an object oriented control system tool kit based on CORBA initially developed at ESRF[2]. It is now also developed and used by Soleil, Elettra, Alba, Desy, MAX-Lab, FRM II and some other labs. The TANGO concept is a fully distributed object oriented control system.

That means that several processes (called servers) are running on many different hosts. Each server manages one or several TANGO classes. Each class could have one or several instances (call devices).

This poster will show existing tools to configure, survey and manage a large number of TANGO components.

GOAL

The first goal is to know at a quick glance, if everything is OK in a control system, and otherwise to be able to diagnose a problem and solve it.

The second goal is to configure the control system and its components.

The third goal is to have long term analysis on components (logs, statistics, usage,....)

PRINCIPLE

On each host to be controlled, a device server (called Starter[3]) takes care of all device servers running (or supposed to be running) on this machine. The controlled server list is read from the TANGO database. A graphical client (called Astor[4]) is connected to all Starter servers and is able to:

- Display the control system status and component status using coloured icons,.
- Execute actions on components (start, stop, test, configure, display information, ...)
- Execute diagnostics on components.
- Execute global analysis on large number of crates or database.

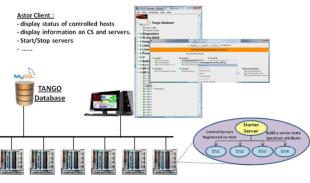


Figure 1: Astor/Starter principle.

STARTER DEVICE SERVER

This Tango device server, written in C++, is dedicated to control system management. An instance of the Starter must be running on each host in the control system.

Controlled Uervers Utatus

When a Tango device server starts, it registers itself automatically in the TANGO database as running on specified host. At start-up, the Starter takes this list of servers registered on the host.

Periodically, a system call gets the list of running processes. For each controlled server, the Starter checks if the server is the running processes list. If it is running a second check is done by a ping on the administrative device to know if the server is alive. And finally a list containing the server names and their status is built.

Starting Servers

For each server, a control level can be defined. Level 0 means not controlled. At start-up, the Starter takes a list of servers registered on the host and its control level. Starting at level 1 to level n, if the specified server is not already running, the Starter tries to start it.

In order to not overload the database, the servers are started sequentially. To start the next server, one of the following conditions must be met:

- Server is alive.
- Server has failed.
- Time out.

A server can be started at any time on a command from a client. Using the same manner, a client command is able to start all servers having the same control level.

It is possible to configure the starter, using a property, to re-start a server automatically if it fails. This property defines a minimum time that has be running, to ensure that this server is able to run a bit.

Implementation

The Starter device server is supported for 3 operating systems:

- Windows.
- Linux
- Solaris

One of the main problems has been the different API's for system calls. Mainly to get running processes.

ASTOR – CLIENT TANGO MANAGER

A graphical client, using the java swing frame containing a tree to display the control system status.

- On top of the tree we can find: • The database status
 - The access control status (if activated).

FEATURE OVERVIEW

Control System Status in a Quick Glance

The host status read from the Starter device server is displayed on a tree using coloured icons.

- Green if all controlled servers are running
- Blue if at least one server does not respond (start-up phase)
- Orange if at leas one controlled server is stopped
 Red if the starter itself does not respond.

The hosts can be grouped under branches by usage, operating system or whatever.... The status of the hosts under a branch is reported to the branch node.

Executing Cctions on Tango Fevice Uervers

A panel can be opened on a crate for more details. The status of each server is also displayed by a coloured icon.

- Green if the server is running
- Blue if the server is running but not responding.
- Red if the server is not running.

	Start New	Start All Stop All		
	12 Co	ntrolled Servers on I-c21-1		
	Event Notify I	Daemon		
Level 1 PLCmodbus/d20 PLCmodbus/d21	Level 3 VacGaugeServente VacGaugeServentse	VacGaugeServer/fe_d20-ip :		
PLCvacuumValve/sr_c21	VacGaugeServer/sr	Start Server		
Level 5	Level 6	Restart server		Not Controlled
VacTemperature/c21-wago	MagVadtik/sr2	Set startup level	00	 UnidosWrapper/c21
		Uptime	100	 VacCellGauge/fe_d20 VacGaugeServer/fe_d20-pen
		Polling Manager		- recomptonent_act par
		Polling Profiler		
		Pool Threads Manager		

Figure 2: Host panel for server management.

By a right click on a server, a pop up menu is displayed to have an action or information on this server.

- Start/Stop servers.
- Test devices (single command or attribute).
- Check device states.

With one of the top buttons, you can start or stop all controlled servers registered on the specified host.

Using the same approach you can start a new device server. It will become a controlled server after you have chosen the control level.

On the host panel (Figure 2), the displayed status, is the server status, and not the device status, as most of the people belong. The specified server is able to serve many devices, and a simple icon cannot represents a combination of several status.

To know the status of each device select the item "Check States" and a panel showing devices status, sorted by classes.

BpssMa	anager/sypc	Errors
Socket		
	sy/socket/bpss	ON .
BpssMana	ger	
	sy/bpss/manage	r STANDBY
BpssDC		
	sy/ps-d/dc	STANDBY .
	sy/ps-qd/dc	STANDBY .
	sy/ps-qf/dc	STANDBY .
BpssAC		
	sy/ps-d/ac	STANDBY
	sy/ps-qd/ac	STANDBY [.
	sy/ps-gf/ac	STANDBY .

Figure 3: Device status panel.

Configure and Display Information

A database browser (called Jive) can be launched to edit device or class properties (see Figure 4).

Server Device Class Alias Property		Device properties [sy/ps-d/dc]					
	MICIOEI and		ion			Property name	Value
 < < <		lock erfTest ir dt DC (/ps-d/dc Polling Event Attribute /ps-qd/dc /ps-qd/dc /ps-qd/dc Ac Manager	config properti	85		FaultNames MagnetFamily ReadSetCurrent SubDevices	Phase Pallure Mains Water Flow Passive Filter Cow Temporture Cow Temporture Cow Temporture DOCT Saluration DOCT Saluration DOCT Saluration DOCT Cover Voltage Loop DOC Cover Voltage Loop DOC Voltage DOC Voltage DOC Voltage Loop DOC Voltage DOC
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Figure 4: Jive (database browser).

It is also used to have information as to where a server is running, on which port, uptime,... Or to add new components, test devices (see Figure 5) and start a generic panel (called ATKpanel) to monitor devices (see Figure 6).

Commands Attributes	Admin	
Argin value		62
Remote State Status Voltage WaterLeak	Name Status Label Status Writable READ Data format Scalar	•
WaterOutpoutTemperature	Read Write Plot	
WaterOutpoutTemperature Attribute: sy/ps-d/dc/PSna Duration: 1 msec measure date: 21/09/2011 1 Juaity: VALID Read: Dipole-DC	ane	

Figure 5: Device test panel.

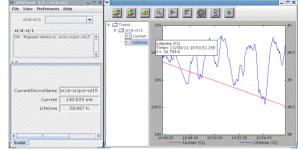


Figure 6: Device monitoring panel.

A wizard is available to guide the user to create a new server and to set class and device properties

Jive is able to set the polling period for device attributes and to set event parameters.

Help to Febug

To help debug a device, Jive and Astor propose a viewer (called LogViewer) to display on a specified device several outputs levels (see Figure 7). These outputs are time stamped and can be filtered to improve analysis.

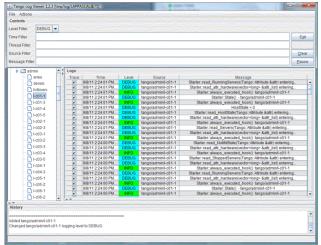


Figure 7: LogViewer (device outputs).

Attribute Polling Configuration and Tuning

A Tango device attribute can be polled periodically. To configure this polling, a diagnostic tool is available. It displays when each attribute has been polled the last four times (see Figure 8) and how much time was required to read and set it. It is very useful to tune the device attribute polling when a server has several devices with many attributes each. Or in case of a hardware problem with time out in reading.

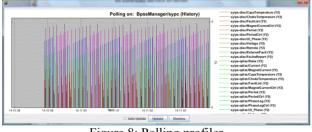


Figure 8: Polling profiler.

By default, a single thread is started to poll attributes. In case of several devices, a pool of threads is available. Astor proposes a graphic tool to distribute device(s) by thread as shown in Figure 9.

Edit			
	Polling Three	ads Mangement	
J. Bos	sManager/	svoc	
		sype	
thre	ad 1 y/bpss/manager		
thre	ad 2		
	wps-d/ac		
e 🛃 Thre			
	y/ps-qf/ac		
f 🚳 Thre	ad 4 wbs-od/ac		
Thre			
	wbs-didc		
Thre			
	wps-qf/dc		
🤋 🚳 Thre			
HQ S	y/ps-qd/dc		

Figure 9: Pool of threads management.

Events Configuration and Test

Tango communication between client and server, could be done on events. A client subscribes to on event (e.g. an attribute change value) and will be waken up when this event will be pushen by the device. To configure and test events, Astor proposes a tool able to browse database to select device attribute, configure event parameters (period, change value, ...) and start a test to check if events are received as expected (see Figure 10).

File View			t/1/Current			
- 5 cpci412 - 5 d-beam-pos - 5 d-beamloss - 5 d-beamloss		abs_ch	event properti- ange : 0.01 ange : Not sp			
 d-bpmliber d-bpmliber d-brems d-brems d-bunch-le 	a-spare	period				
- 🔣 Curr		abs_ch rel_ch	e event propert. ange : 2 ange : Not sp : 60000			
B Lifer B State B State B State B State C	2 18 5 0	Pollin Pollin Time n	attribute name g period (mS) = g ring buffer d meded for the 1: bot updated since	1000 epth = 3600 ast attribute	e reading (mS) = 0.404
• (1) ict-id1 • (1) ict-id1 • (1) ict1		Delta :	between last re	cords (in mS) = 1000, 999	, 999, 10
<u>4</u>				an general and		
Eile	Attribute	events	at 14:05:21 (08 Sep		
Signal names	Read Value	Mode	Last Time 14:05:23 08 Sep		Delta Value 0.010 (0.01 %)	
		Die	miss			

Figure 10: Event configuration and test panel.

Server Statistics

When a server, started by the Starter, is stopped by another way than a command on the Starter (kill signal, core dump, ...), this event is logged in a file. When the server is re started by the Starter, this information is logged too, Astor proposes to get information from this file for one host (see Figure 11) or for all controlled hosts, and compute statistics an availability for servers (see Figure 12).

I-c25-1						
Server	Run Time	Failures	Failure Duration			
PLCvacuumValve/sr_c25	22 days 5 h 01 mn 19 sec.	0				
PyPLC/c25-fans	22 days 5 h 00 mn 45 sec.	0				
TacoStarter/I-c25-1	22 days 5 h 00 mn 43 sec.	0				
VacCellGauge/sr_c25	22 days 5 h 01 mn 03 sec.	0				
VacGaugeServer/sr_c25-ip	21 days 22 h 11 mn 24 sec.	0				
VacGaugeServer/sr_c25-pen	21 days 5 h 21 mn 31 sec.	4	16 sec.			
VacTemperature/c25-wago	22 days 5 h 00 mn 57 sec.	0				

Figure 11: Statistics on a host.



Figure 12: Statistics on a server.

Miscellaneous

Astor propose also:

- Simple logging about start/stop servers
- A panel to send command on several servers.
- A panel to show server usage (useful for large number of instance).
- A panel to configure control access if it is activated.

CONCLUSIONS

The couple Starter/Astor and related tools, are very useful to manage a large number of servers running on several hosts distributed around an accelerator or a large experimental physic control system. They help to configure diagnose problems, and for doing analysis and statistics.

REFERENCES

- http://www.tango-controls.org/ http://www.esrf.eu/ [1]
- [2]
- [3] http://www.esrf.eu/computing/cs/tango/tango_doc/ tools_doc/astor_doc/index.html
 [4] http://www.esrf.fr/computing/cs/tango/tango_doc/
- ds_doc/tango-cs/System/startgt/