

HIAT2012, ANL, Chicago



THE AUSTRALIAN NATIONAL UNIVERSITY

Terminal Voltage Stabilization of Pelletron Tandem Accelerator

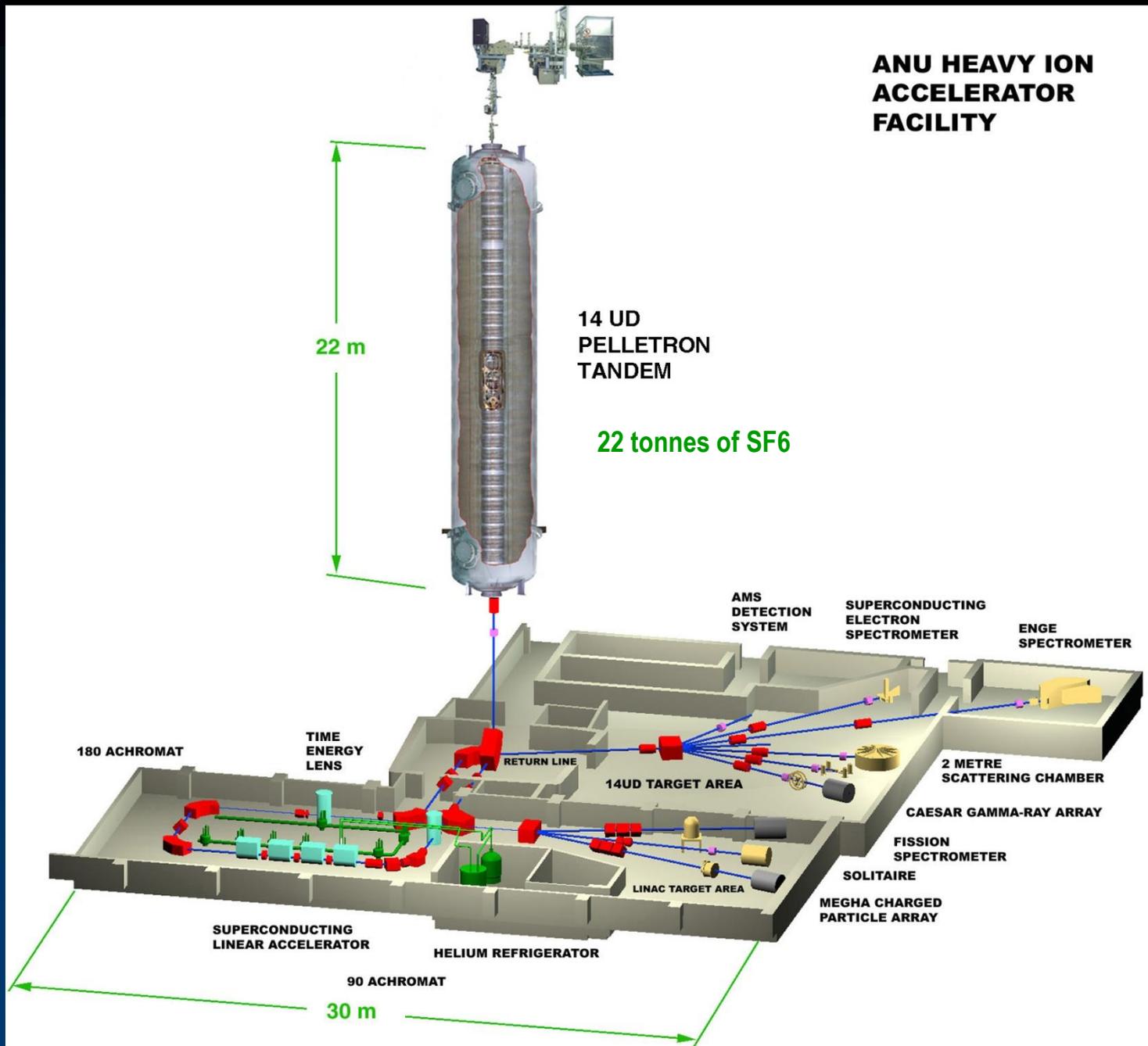
Nikolai R. Lobanov

on behalf of Accelerator Operation and Development Team

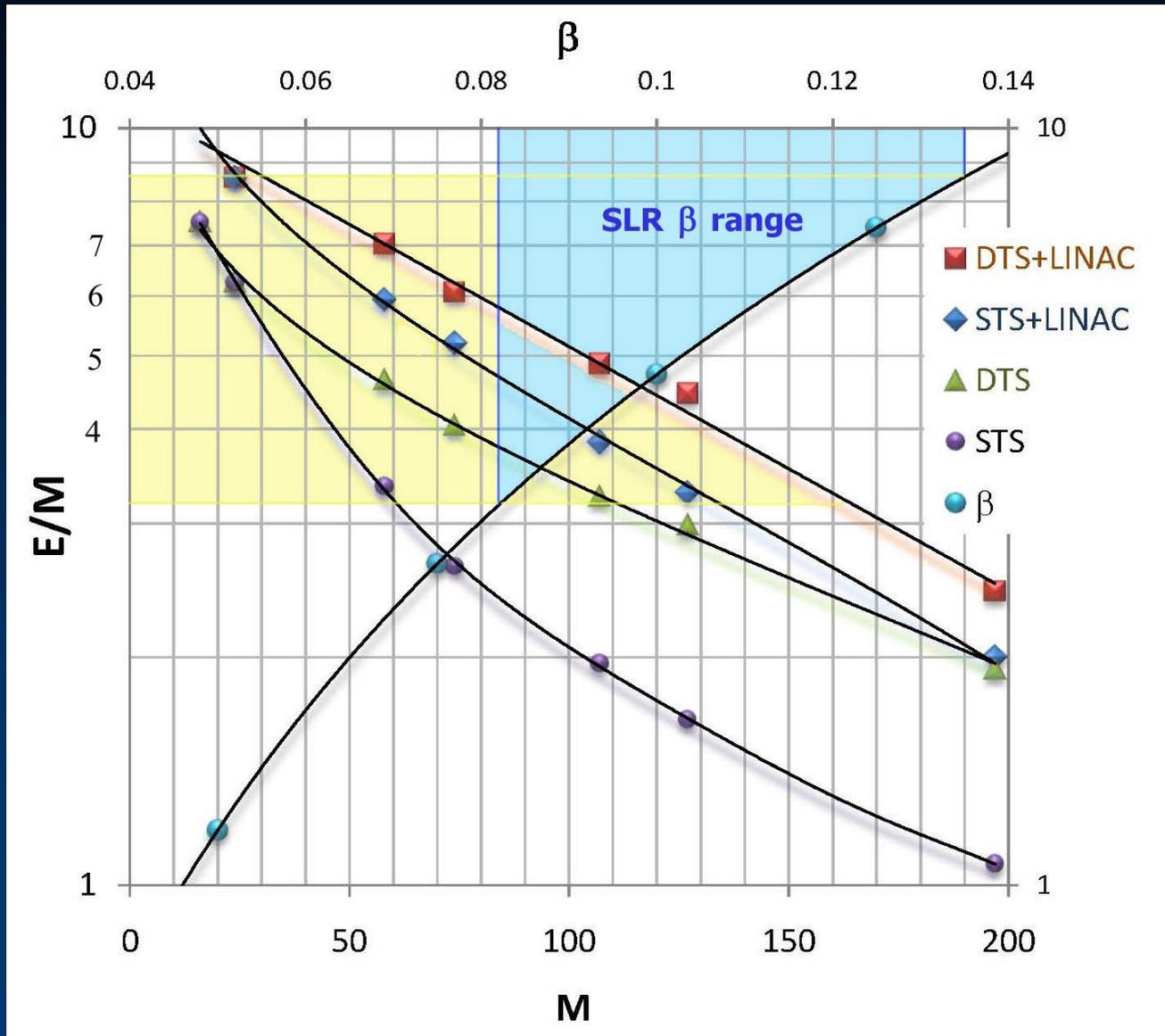
Heavy Ion Accelerator Facility



ANU HEAVY ION ACCELERATOR FACILITY



14UD and Linac capability





One of many Superscience projects

1	Computer control, DA	New VAX emulation server (Nucserver 3) New EPICS computer control: basic hardware New EPICS computer control: software New hardware for computer control Data acquisition: hardware Data acquisition: software Network infrastructure 14UD Facility New radiation protection terminals	N1 N1 N1 Various N1 N1 N1 N1
	Migration from unsupported computer platform		
2	Heavy beam enhance	Turbo pump systems*15 Titanium elements for ion pumps New leak chaser New roughing system based on scroll pump L5 Vac Gauges, 2/5 x15, Bayard-Alpert x 4 Vacuum components storage facility Portable vacuum turbo station for detectors storage Magnet power supplies (18 Sorensen) Magnet power supply 300A Magnet power supply 155A *2 New Hall probes Linac 180 achromat and ENGE	N2 N2 N2 N2 N2 N2 DanFysik DanFysik Group 3 N2
		Better accel. trans.: 150KV Entrance lens control Emission compliance, new SF6 purchase New chains, idlers etc New NMR Top up SFS -5PSI Spare gas cathode ion source Gas Source upgrade, more efficient Cs delivery Brushless generator at L5 Grounding plunger and hook on GC and BoxVolts New cathode power supply for GC and immersion lens ps for Mc New power supply for Cs reservoir McS Upgrade safety cage around McS Upgrade water-cooling circuit and pump L5 Fast gas nitrogen cooling system for Cs oven McS and GC Ar storage system for reactive source samples Replenish stock of isotopic materials for user experiments Commissioning fast acting SFS valves Implementation two RGA stations Implement oxygen depletion monitor system Commissioning terminal voltage stabilization system New steerer power supplies (16 each) New beam line valves LE, McS, GC Build 10 24 Vdc valves controllers Build 15 turbo controllers Build ion beam diagnostic box Build LE beam emittance measurement jig Upgrade 14UD Control Console Upgrade clutch system for shorting rods Eight new accelerator posts Re-stock of tube, column HV resistors New LE, Tank and HE Faraday cups Terminal Faraday cup and automatic scale pA New computer controlled HE object 4-jaw and two 2-jaw image slits Spare suppressor/charging system power supplies Entrance tube upgrade BPMs on all beam lines, HE	Glassman NEC Drusch N2 Hallmark Intra MWS MWS N2 MWS N2 MWS N2 Glassman N2 N2 MWS N2 N2 MWS N2 MWS N2 TRACE N8 AS/N, MWS N2 SRS N2 MicroRack N8 NEC N2 EU N2 VAT N2 EU N2 MoU TRIUMF N2 MoU TRIUMF N2 N1 MWS N2 NEC N2 Welwyn N2 NEC N2 NEC N2 NEC N2 Glassman NEC NEC 10
Reliable operation, better beam intensity, diagnostics, higher energy			
3	Beam pulsing enhance	Slow chopper pfs from 1:2 Switching mode power supply	AppPulPow
		RF resonators and phase detector Chopper #1 B1,3 B2 New vacuum system and rf diagnostics Phase detector or new 4 slits RF Electronics 9.375 MHz rf control loop 37.5 MHz rf control loop 18.75 MHz rf control loop Main control loop based on phase detector or slits Saw tooth generator: pilot project	MWS N3 MWS N3 MWS N3 MWS N3 MWS, NEC N3 EU N3 EU N3 EU N3 EU N3 EU N3

4	Upgrade high and low power coaxial cables Room temperature 150 MHz superbuncher- pilot project Build three 10 kW 150 MHz resonators Vacuum system Facilities and services (main, water)	EU N3 MWS N3 Scitek N3 MWS, EU N3	
	RTB RF electronics Low level rf control loop 150 MHz 150 MHz 10 kW rf amplifier Interlocks and protection	EU N3 AS N3 EU N3	
Higher intensity, time stability, time resolution (+ helps linac beams)			
8	Enhanced accel supp	Alignment laser Digital lathe readout Target making equipment, supplies NIM electronics- fix, renew more cables Upgrade CAD office and capabilities	CAD Group, IT N
	Improved technical efficiency, support		
5	Linac enhancement	Renew time-energy lens and superbuncher LN2 precool Build 3 cryogenic controllers Nb resonators - pilot project Measure linac time structure when tuning Build fast Faraday cup and electronics Develop high sensitivity BPM Cryostats upgrade: new bake-out resistors	ANU N5 EU N5 MWS, EU N5 EU, MWS N5 EU, MWS N5
	Better time resolution, higher energy from linac, easier operation		
6	New beamlines	10 Faraday cups ansd 2 BPMs	NEC N6
	for Line -1 Line 4 Hyperfine Line 8 PAC Line 9 Fus-Fis Line C 2nd chamber	Line 4 Upgrade Line 7 Super-e	MWS N6 MWS N6
Wider capability, experimental efficiency (reduce changeover times)			
4	AMS Enhancements	Ion source SNICS body Fast switching 2 TREKS Einzel lens Off-axis cups etc Cups Vacuum box Analyzing magnet opening	NEC TREK N4 NEC N4 NEC N4 ANU N4 ANU N4
	Deflectors Current integrators Automatic computer control system and electronics	TREK NEC SYS EU, ANU N4	
Enhanced AMS efficiency, capability			
7	new RIB capability	New solenoid 7T (also is spare for Line B) New magnetic yoke Target and detector chamber, mounting Target and detector chambers, detectors Electronics? Development of new beams	PRICE NEGOTI MWS N7 MWS MWS
	Dedicated RIB capability Improved efficiency for solenoid applications, reserve solenoid		

Motivation



Slit controller



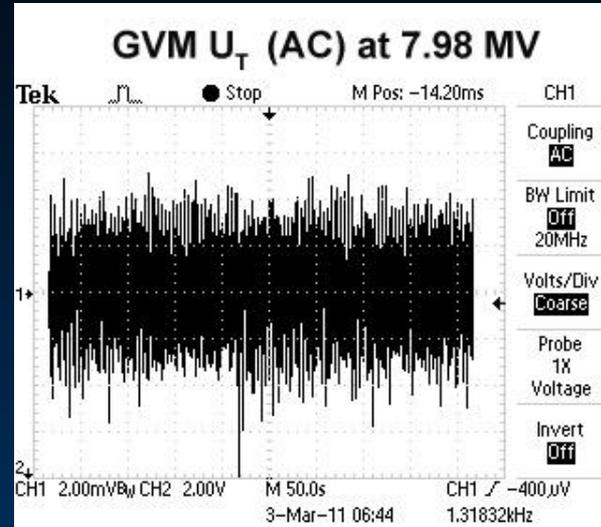
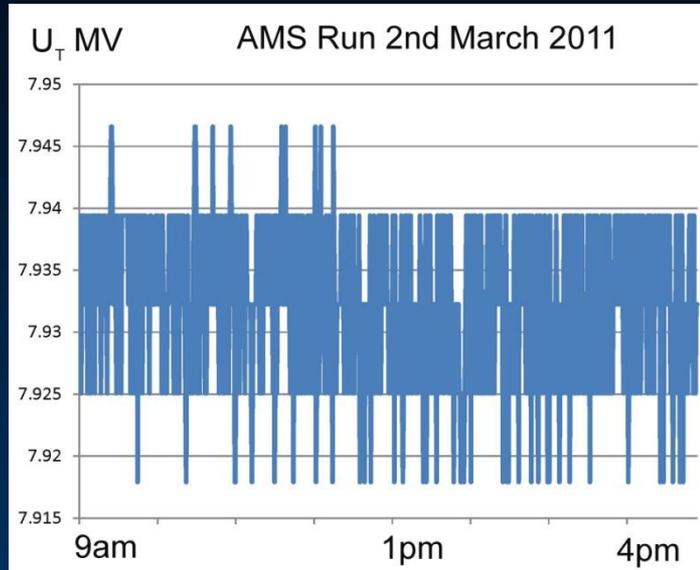
GVM controller



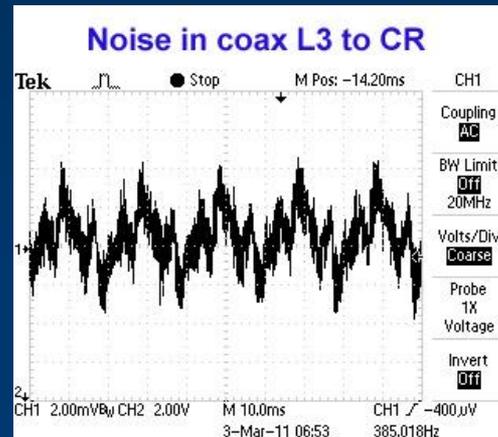
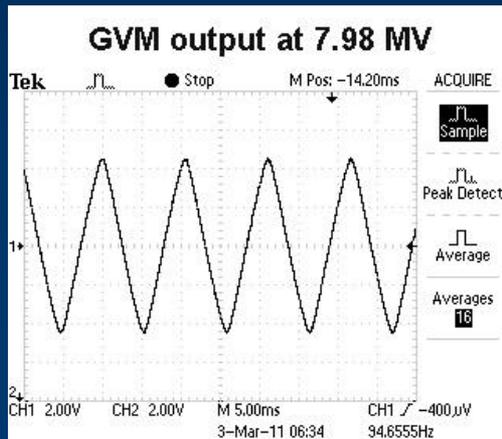
Corona Probe controller

- Replace old system
- Beam energy stability better than 10^{-5}
- Beam position stability
- Beam time focus stability when injecting into LINAC or conducting TOF experiment

14UD Performance with old system



Based on GVM, terminal voltage stability is ~ 0.2%, much higher than NEC specs of 0.02%



Noise in GVM coax is at the same level as GVM U_T (AC)

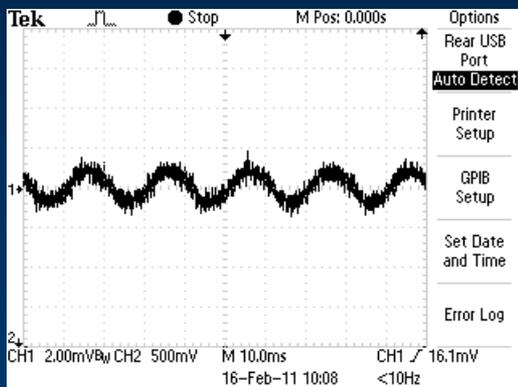
Noise in coax should be reduced and pre-amp moved to L3

CPOs calibration

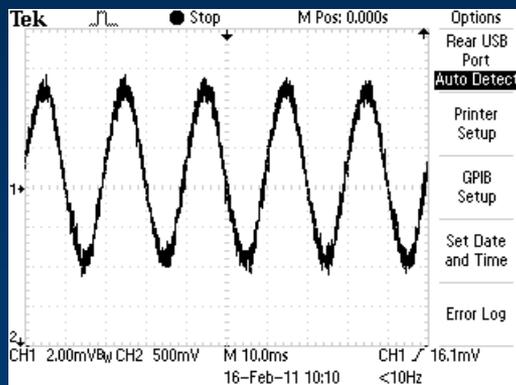


▪115 VAC at 50 Hz is applied to the terminal

▪Challenge: to deliver CPO signal noise-free to Control Room



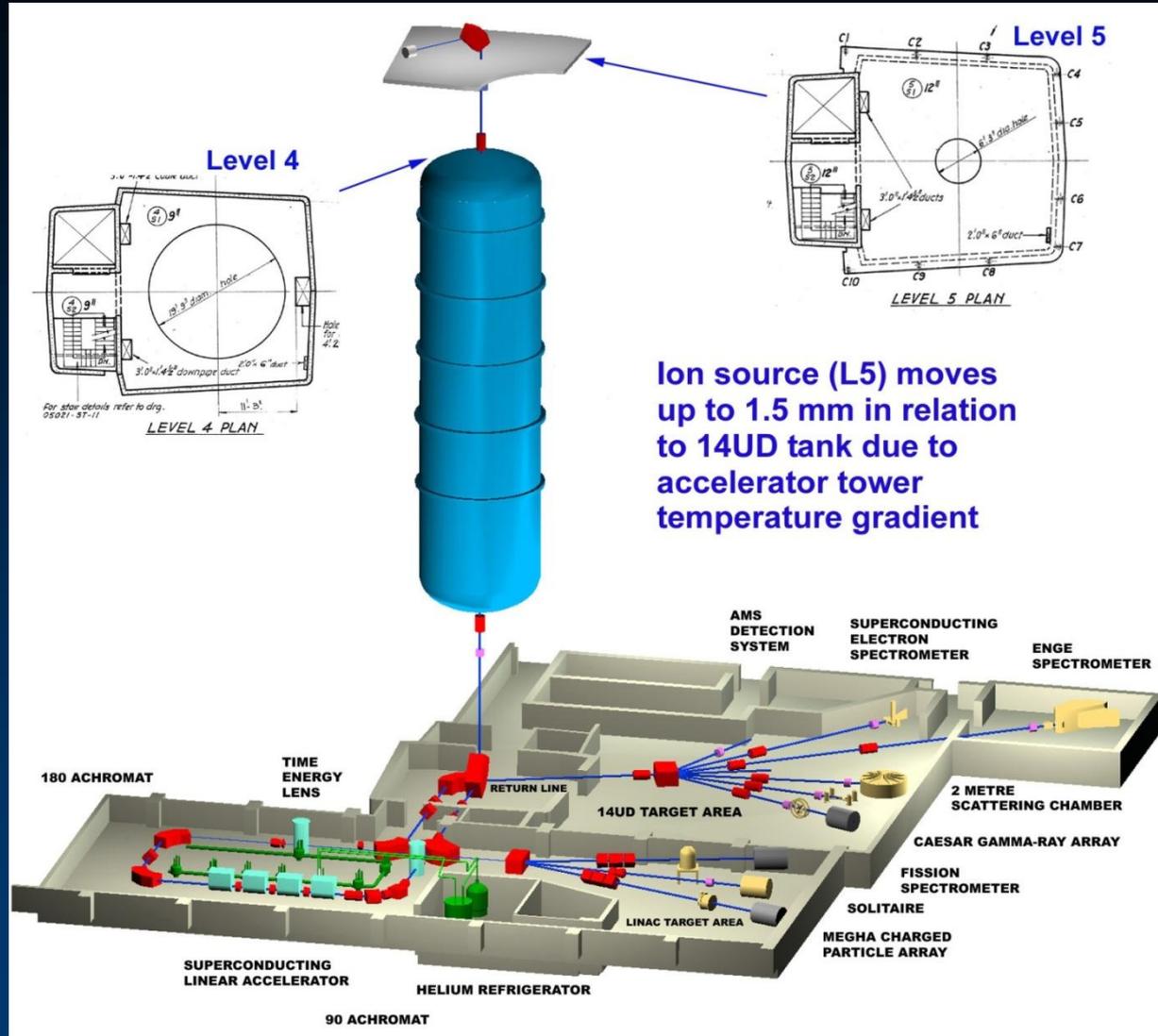
▪Raw signal on CPO, 16 μ V/V



▪CPO signal after pre-amp, 70 μ V/V

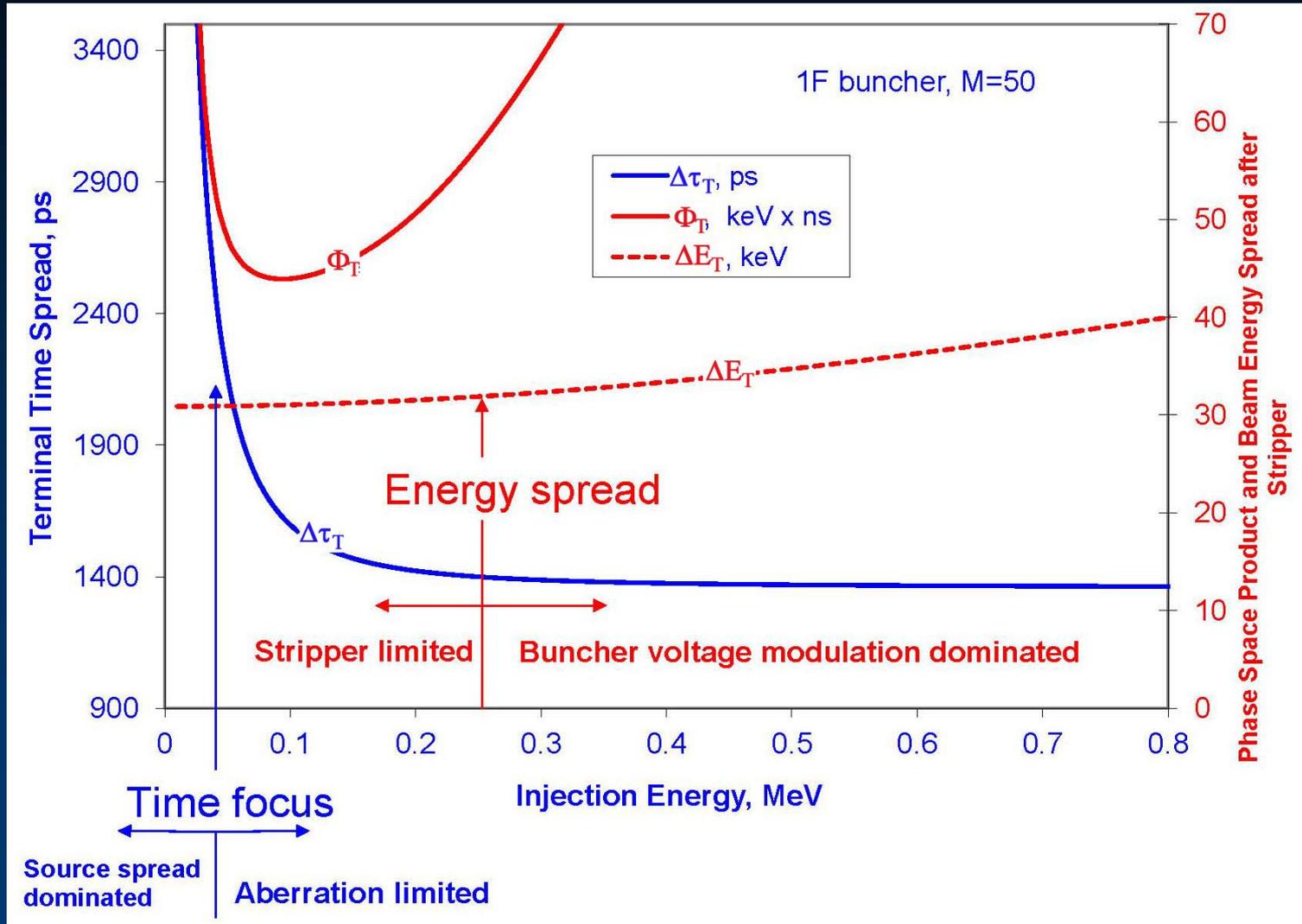
OPTION: increase diameter of CPO

Beam position stability



Automated tuning of the beam transport. Compensation of daily ion source displacement

Limitation to time focus: formation longitudinal phase space behind the 1st stripper



Commercial control systems

- New Terminal Potential Stabilisation system TPS 6.0 (NEC) including GVM, Slits and CPO amplifiers and corona probe controller

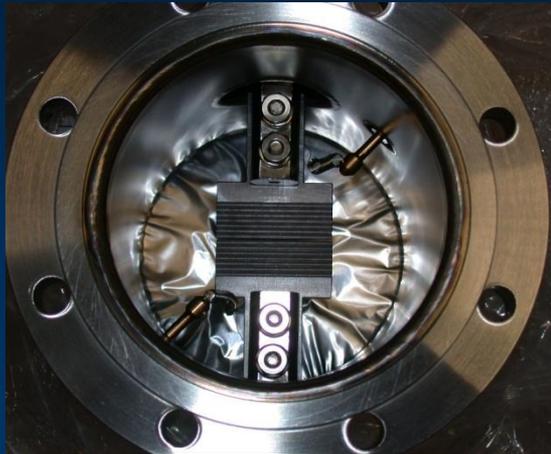


Corona Probe Controller and CPO amplifier

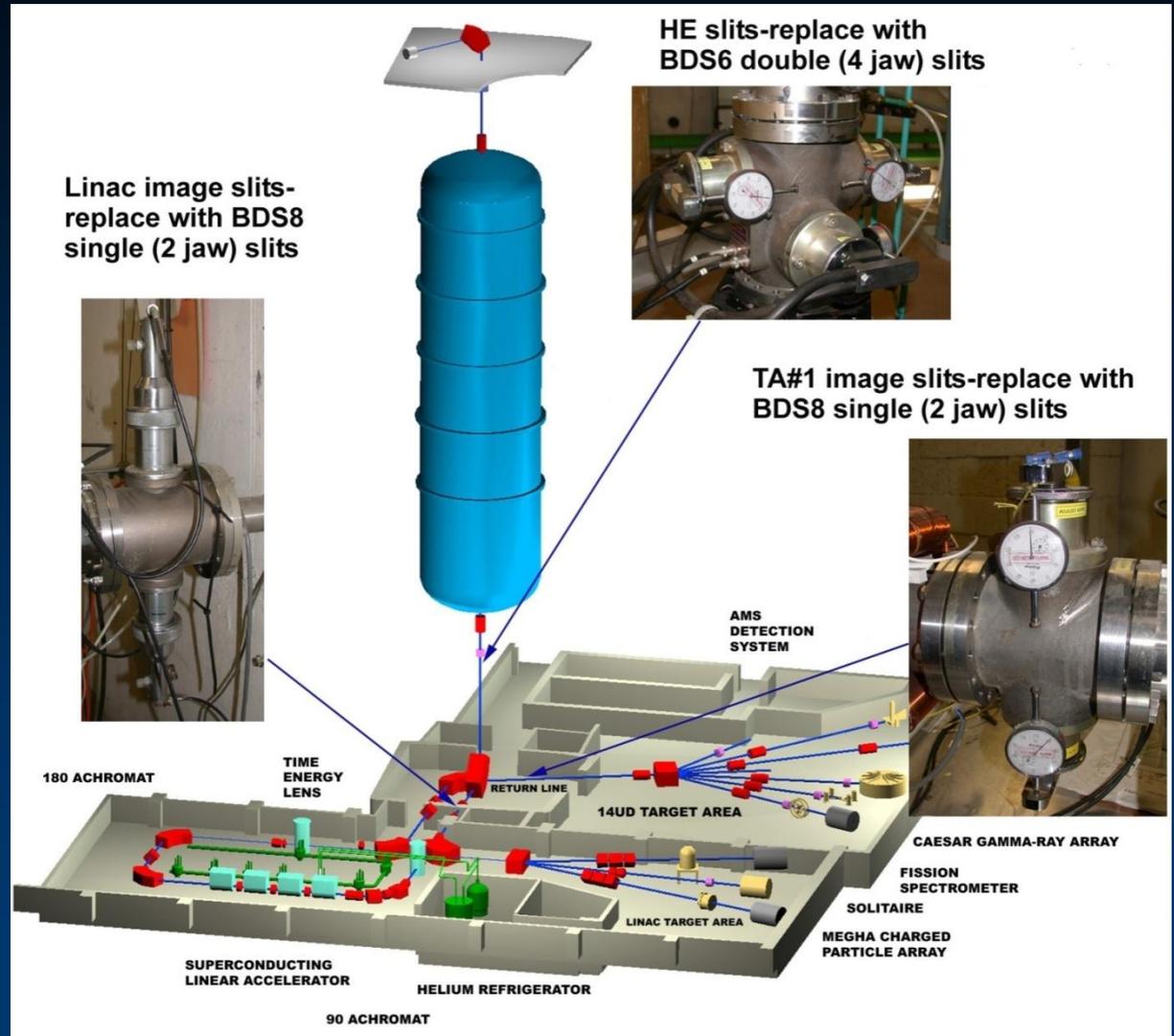


New High Energy remotely operated slits

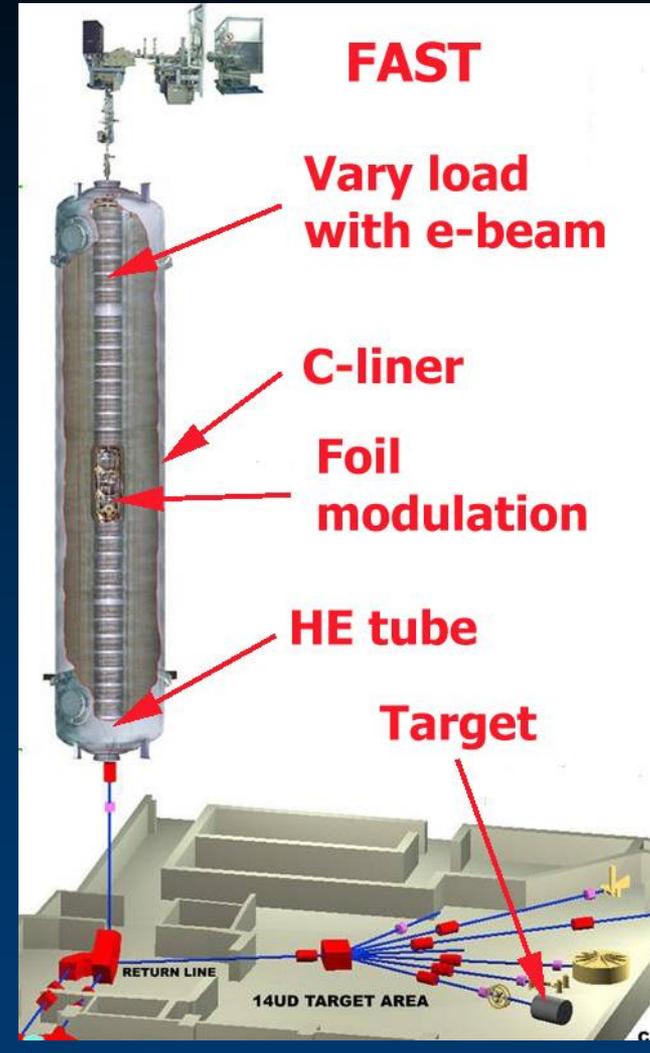
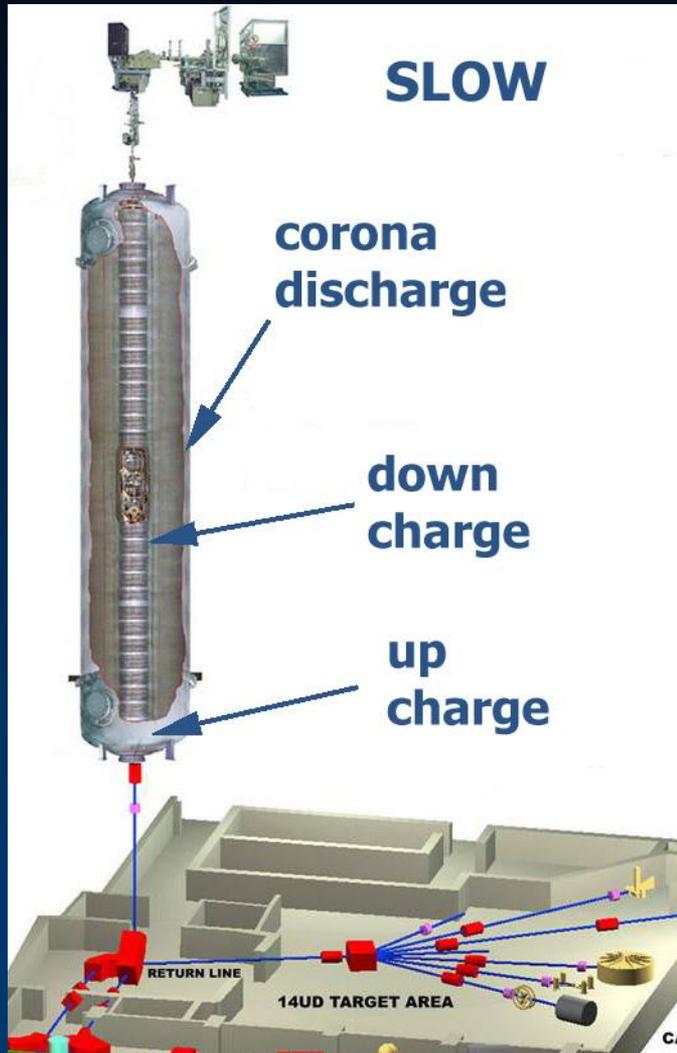
NEC BDS8 slits



All slits with 24 VDC motor drives, Ta elements
 Controllers are build in-house

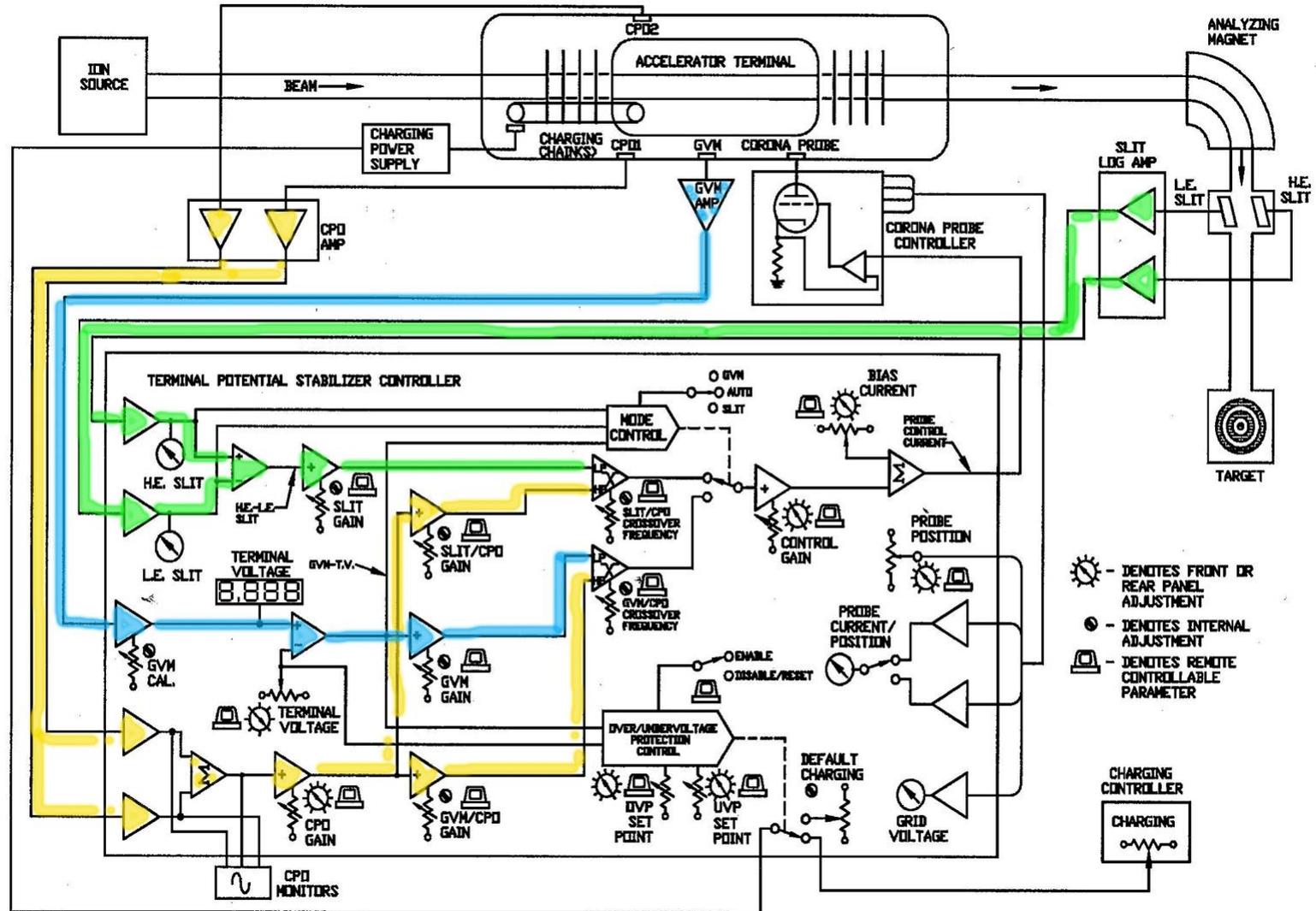


Beam energy stabilization

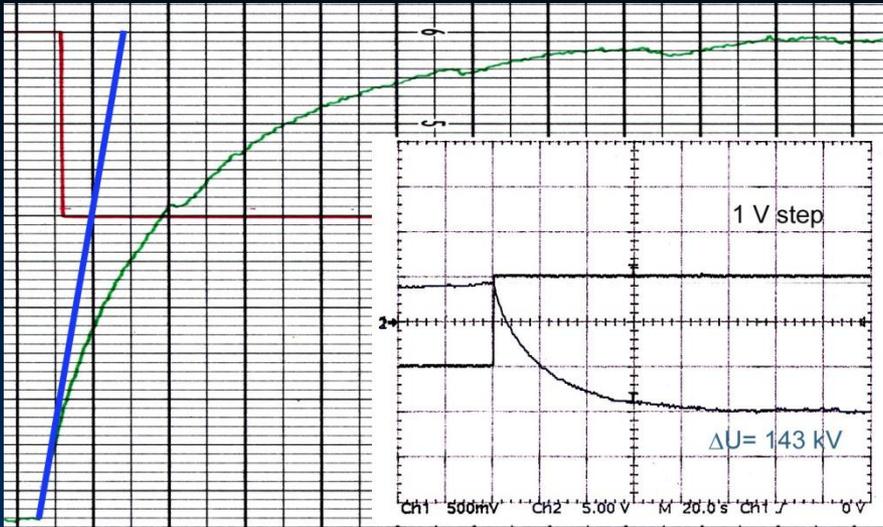


Also "predictive fluctuation" compensation

NEC Voltage control system

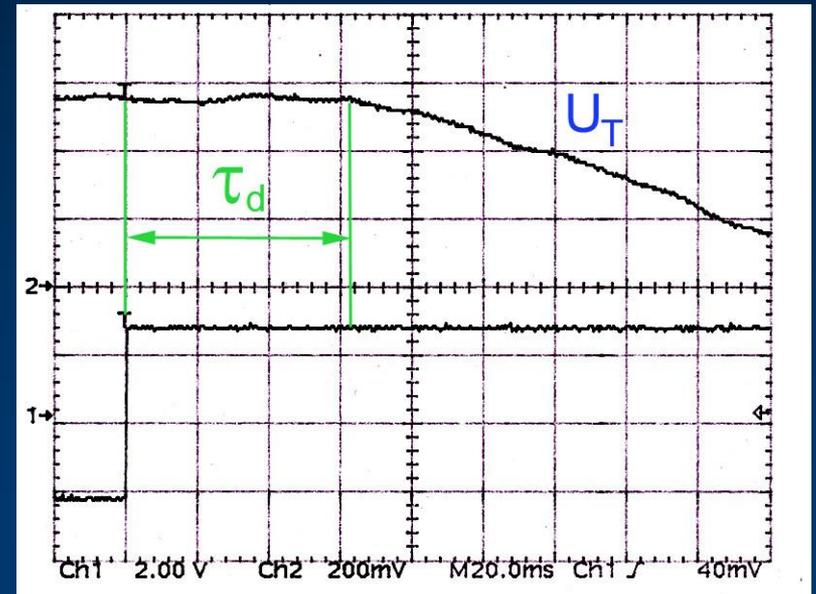


Open loop response



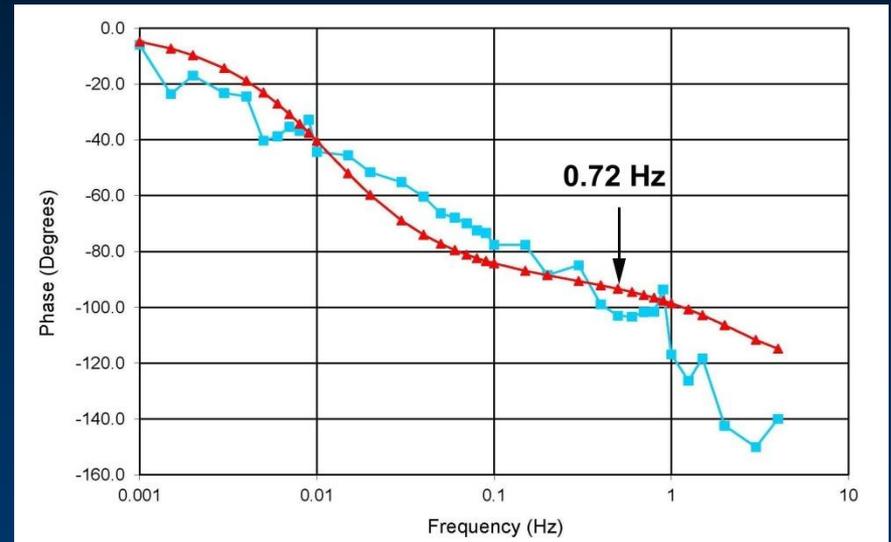
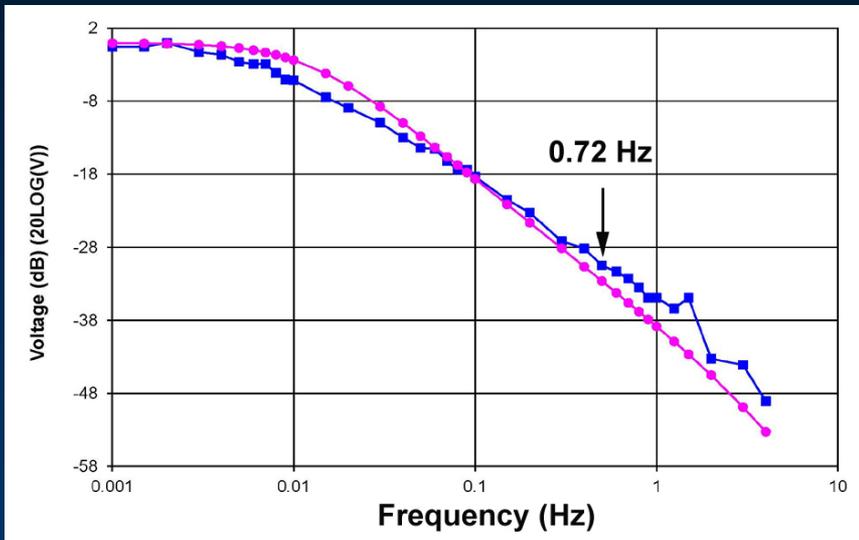
1 V Step Input,
time constant=10.2 s.

Measurement delay time
 $\tau_d = 31 \text{ ms}$



Corona Controller Bode plots

voltage and phase response to frequency
produced by sine wave measurements

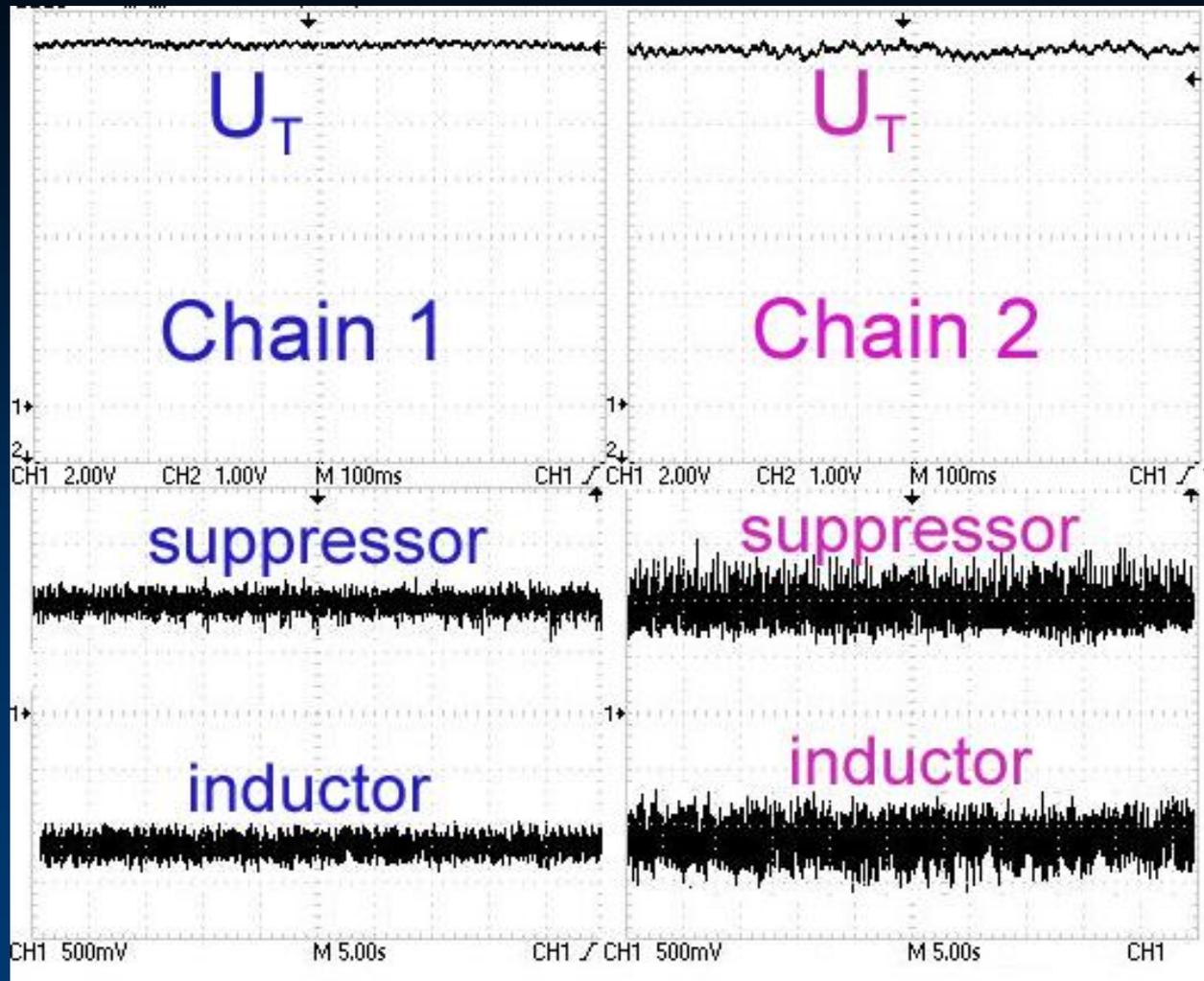


Voltage response with curve fitting

Phase response with curve fitting

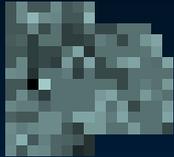
Stability requirement: Σ phase shift $< 180^\circ$

Pelletron charge transport

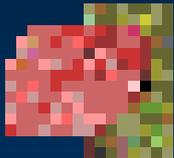


Terminal shorted through 1 $M\Omega$ resistor

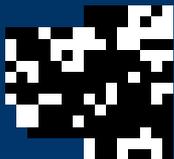
Chain oscillations



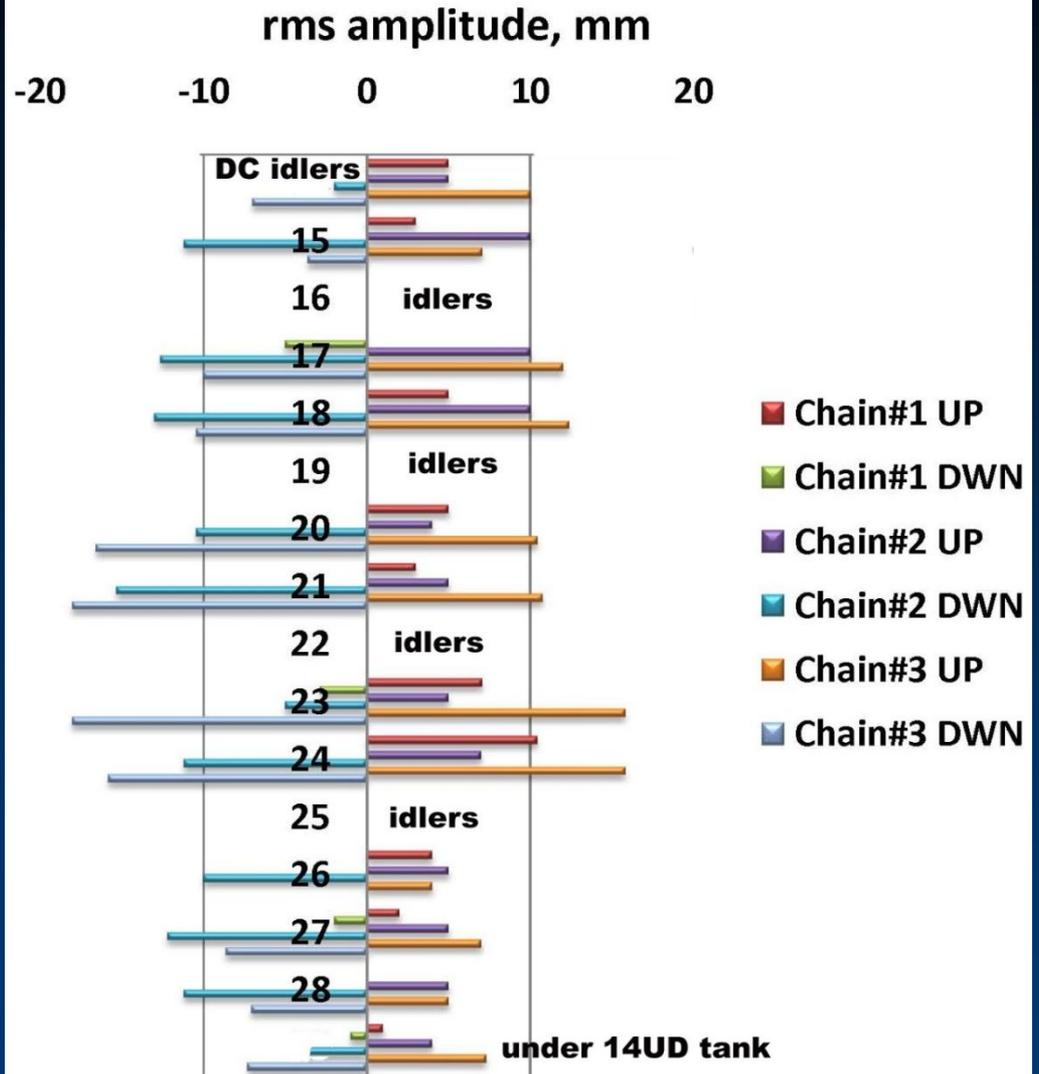
suppressor
under tank



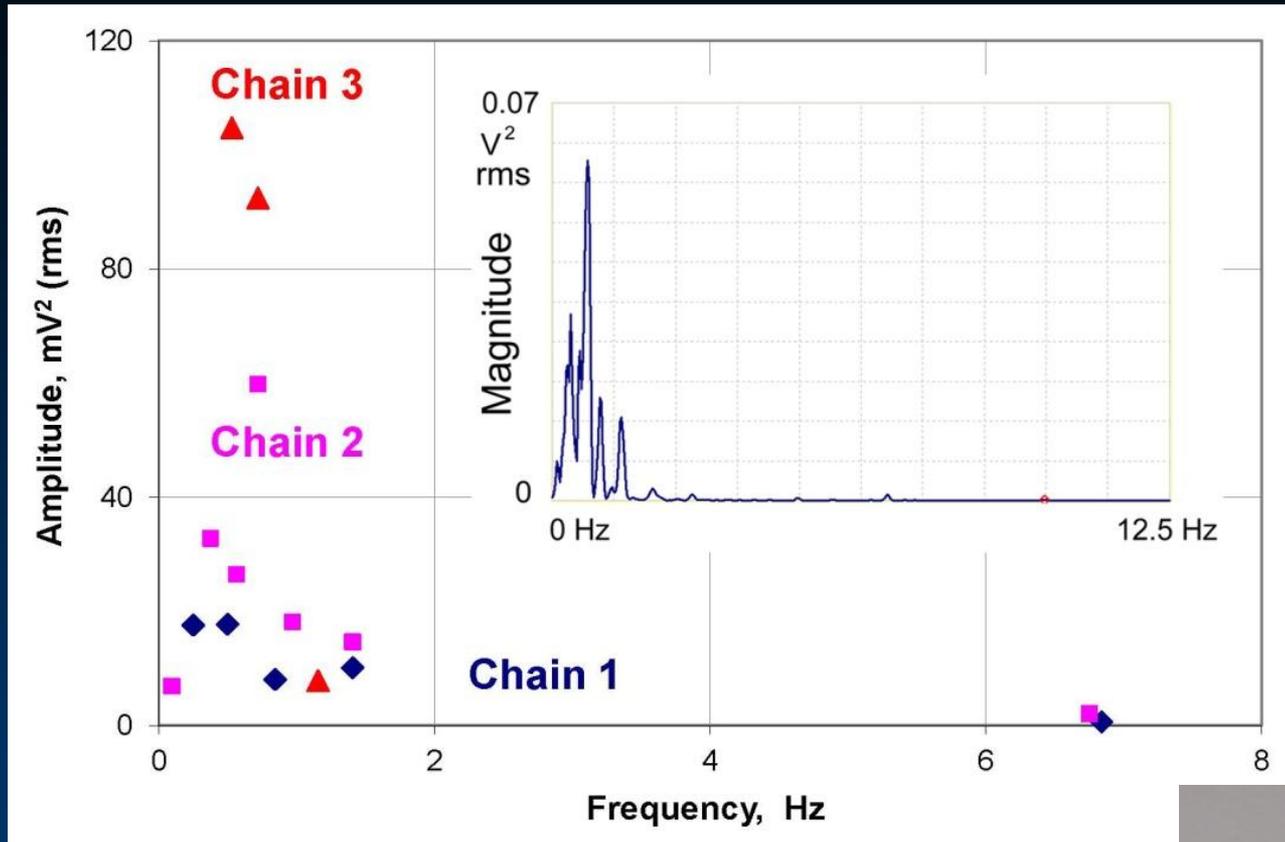
twist



Unit #21 stiff

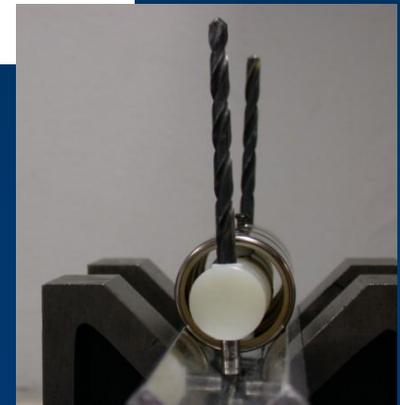


Chains mechanical modes low frequency

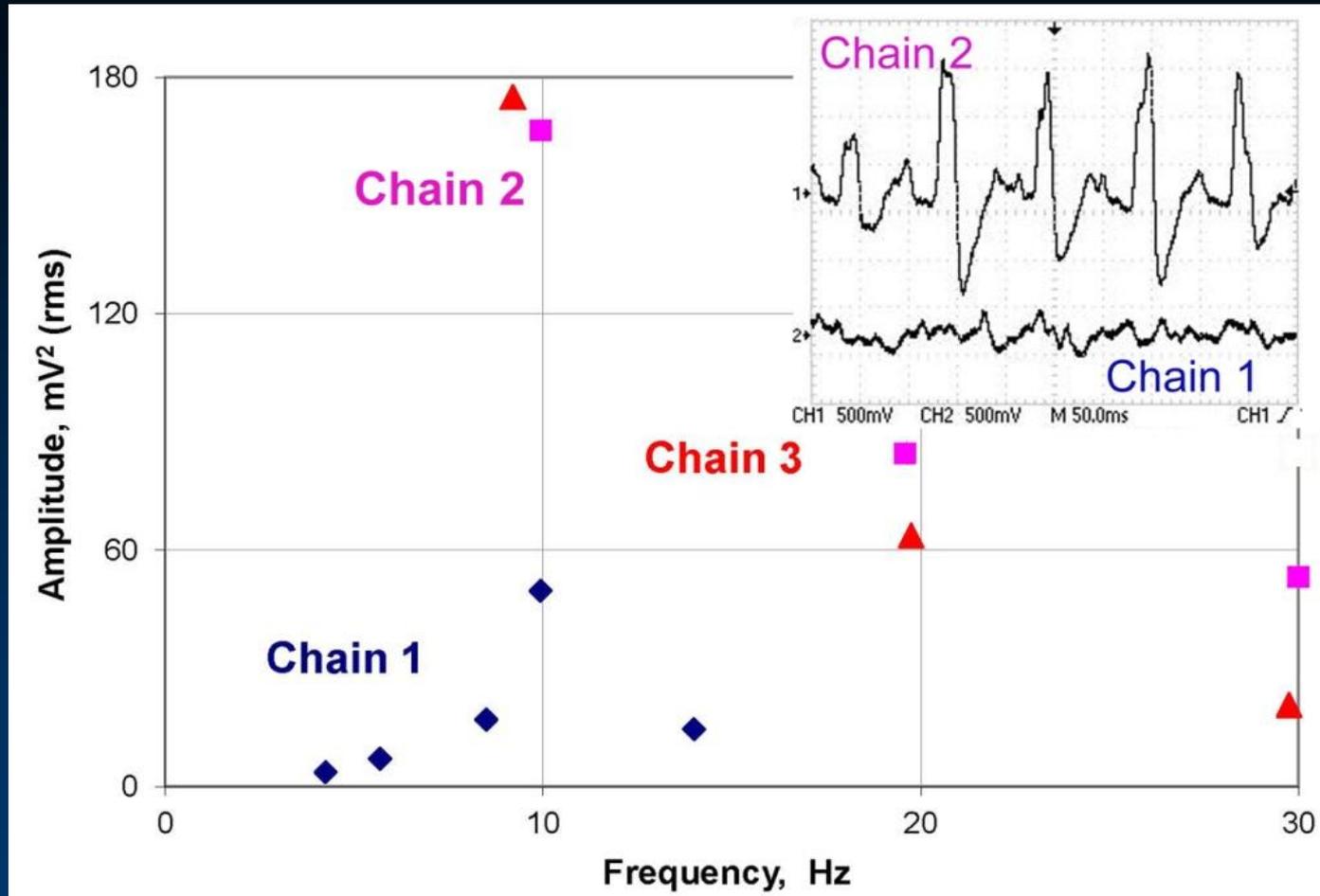


Low frequency band measured with CPO_{Σ}

0.72 Hz is the chain revolution frequency due to misalignment between pellets



Chains mechanical modes "high" frequency



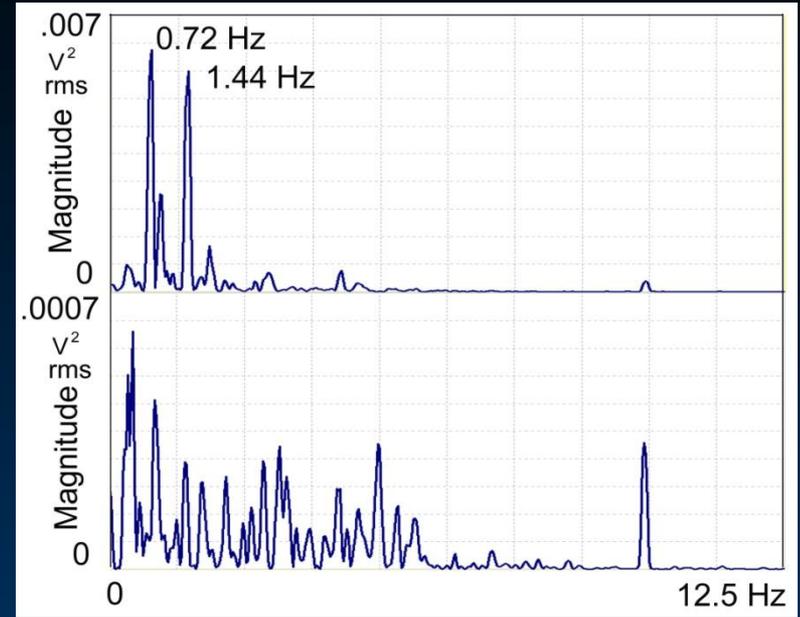
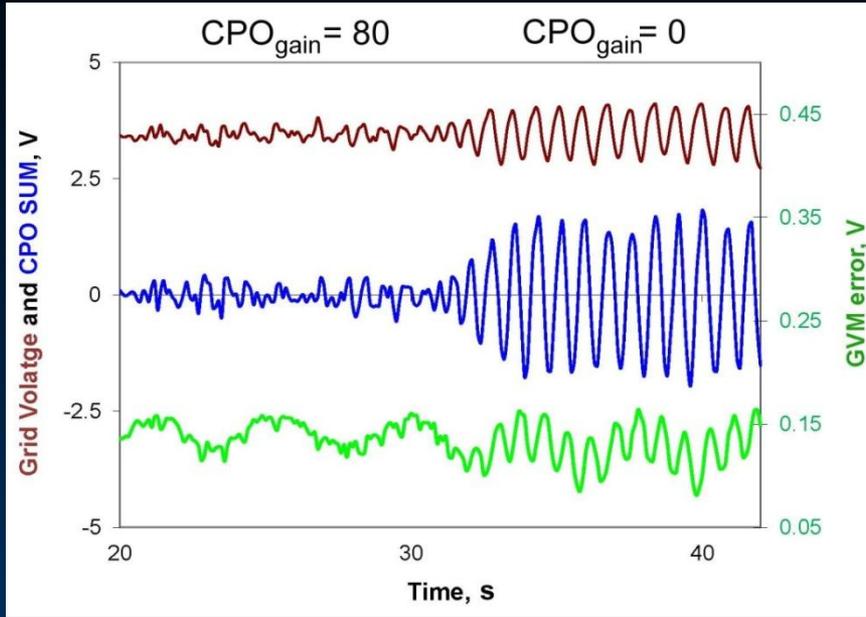
High frequency band measured with inductive pick-offs
 9.68 Hz is the pulley revolution frequency and 19.4 Hz is its
 2nd harmonic

$f_n = n(c^2 - v^2) / 2lc$, $n = 0, 1, 2, \dots$,
where $c = (S/\rho)^{1/2} = 22.8$ m/s,
as S is the tension in the chain,
 $\rho = 0.99$ kg/m is mass per unit length,
 $v = 14.5$ m/s is the velocity and
 l is the free length of the chain.
The chain tension is 525 N.
This yields with $l = 2.8$ m
 $f_n = 2.42, 4.84, 7.26, 9.68$ Hz.

9.68 Hz is nearly equal to the
pulley frequency of 9.75 Hz.

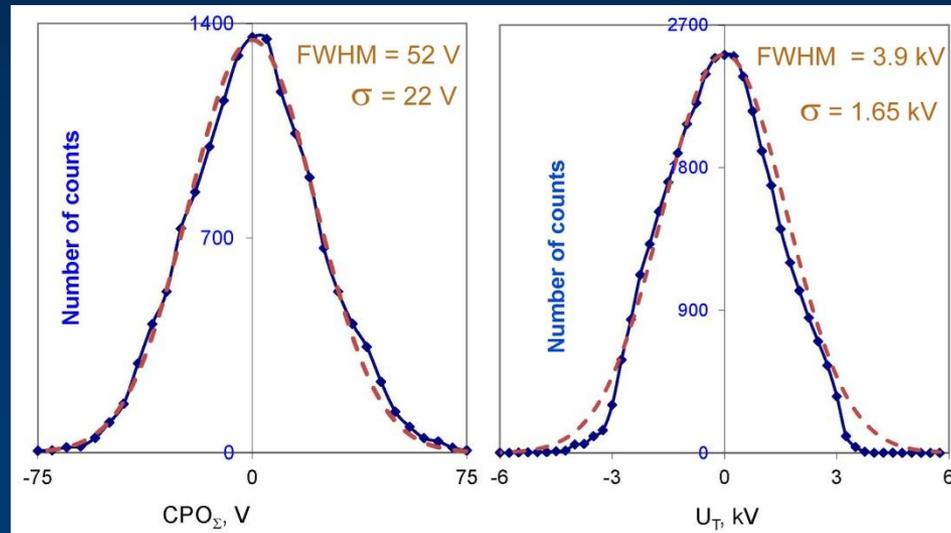


Control system performance



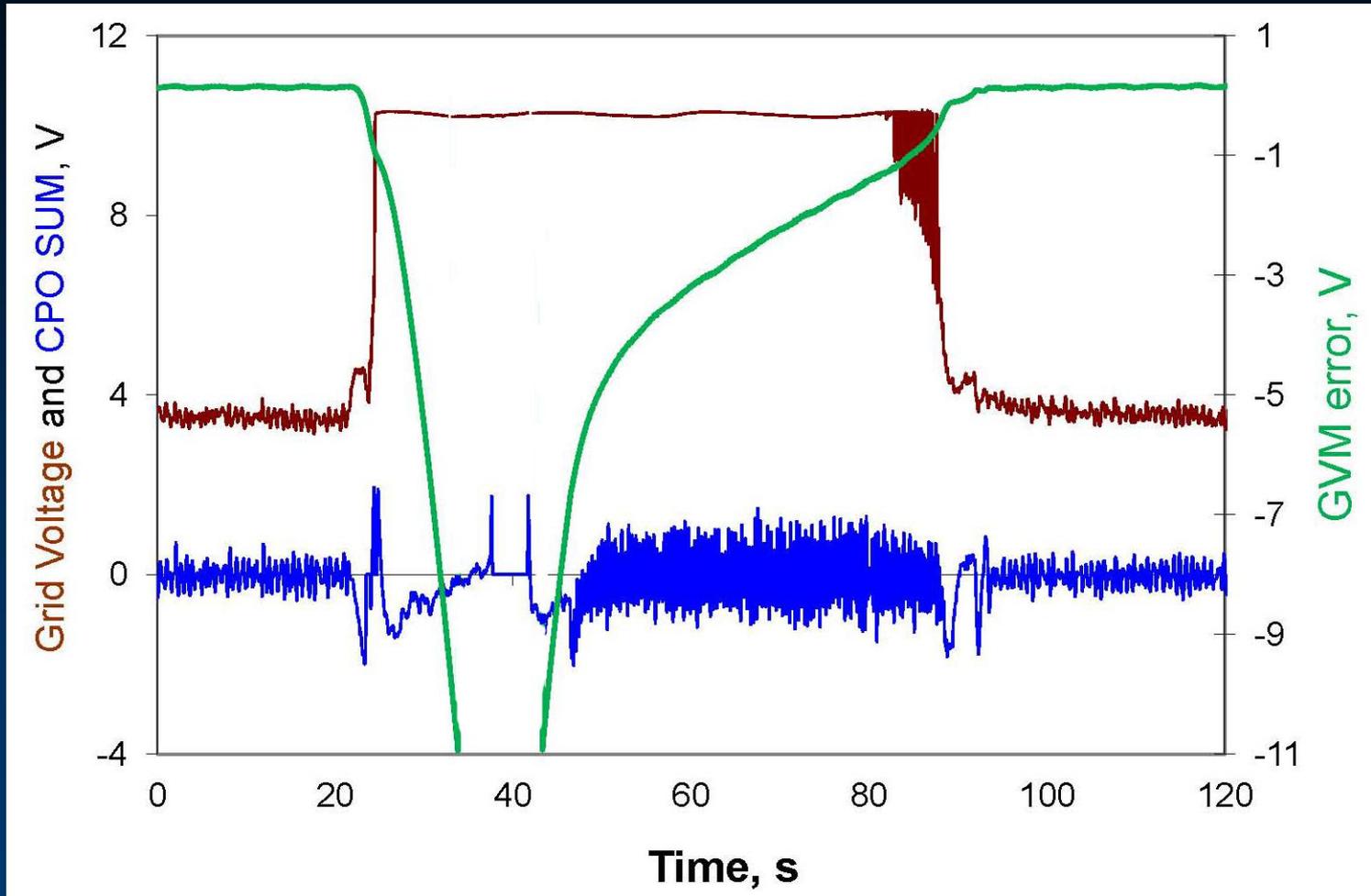
Terminal voltage distribution with optimum control:

Fast variation

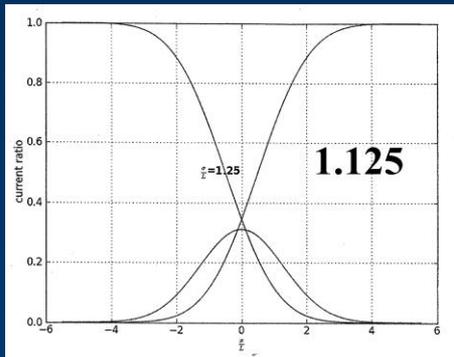
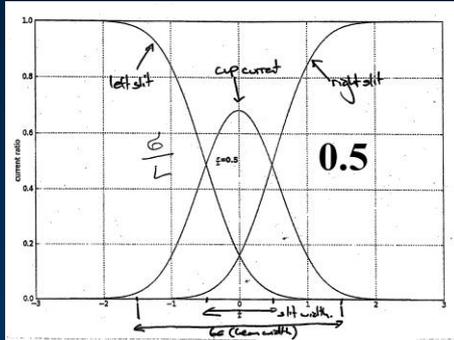
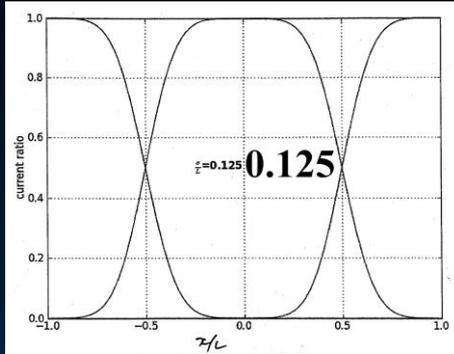


Slow voltage variation

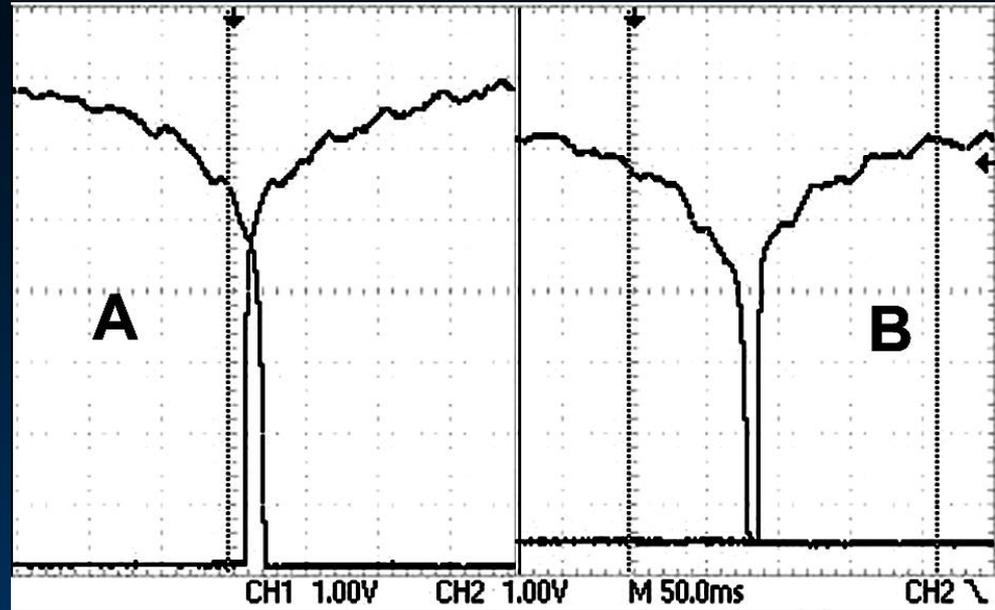
Recovery after spark event



Slits cross-talk



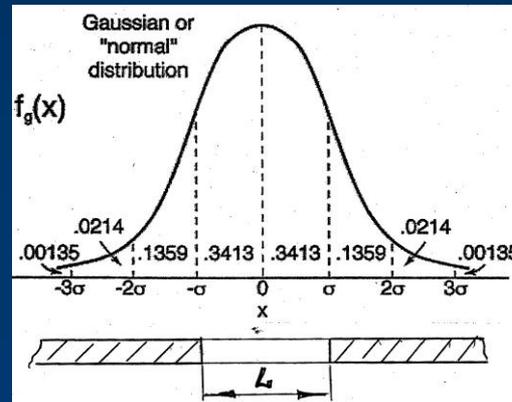
Simulation for normal distribution



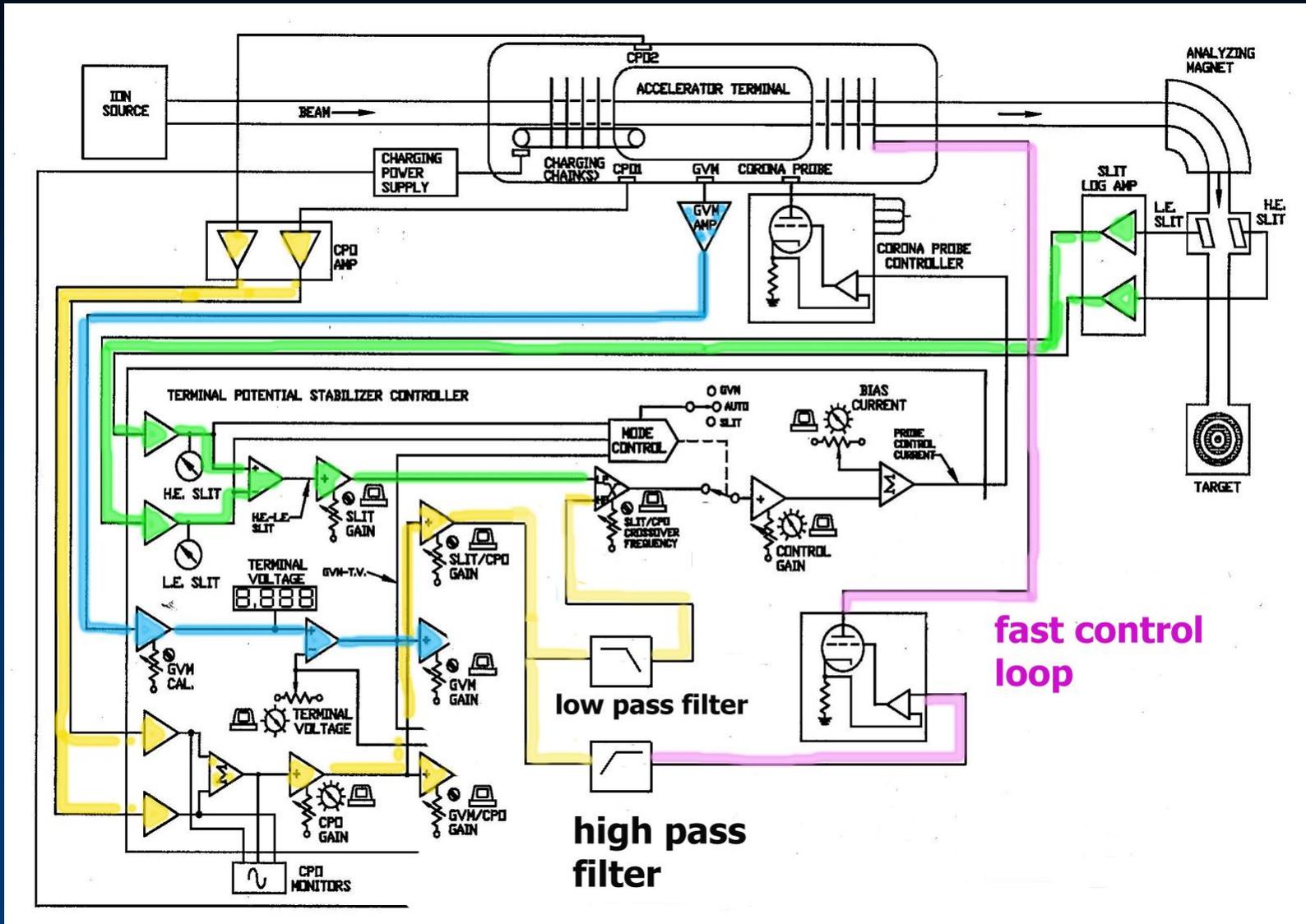
Slits current for $\sigma/L = 0.5$

A: no e-suppression

B: e-suppression



New Fast Control Loop



Acknowledgement





Motivated and skillful technical staff

Technical Staff:

A. Cooper, A. Muirhead, J. Bockwinkel,
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T. Tunningley, C. Gudu, L. Larioza

IT Staff:

D. Tsifacis, A. Grafton

EU Staff:

D. Gibson, D. Tempra,
D. Anderson, D. Kelly
T. Steele

Accelerator Director: Keith Fifield

Accelerator Guru: David Weisser

Q