LCLS-II BUNCH COMPRESSOR STUDY: 5-BEND CHICANE*

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ABSTRACT

In this paper, we present a potential design for a bunch compressor consisting of 5 bend magnets which is designed to compensate the transverse emittance growth due to Coherent Synchrotron Radiation (CSR). A specific implementation for the second bunch compressor in the LCLS-II is considered. The design has been optimized using the particle tracking code, ELEGANT. Comparisons of the 5-bend chicane's performance with that of a symmetric 4-bend chicane is shown for various compression ratios and bunch charges. Additionally, a one-dimensional, longitudinal CSR model for the 5-bend design is developed and its accuracy compared against ELEGANT simulations.

LO	L1		L2	L3	Lf	
φ=**	φ=–12.7°		φ=-21°	φ=0	φ=±34	BC3
V ₀ =100 MV	V ₀ =211 MV	HL	V ₀ =1446 MV	V ₀ =2206 MV	V ₀ =202 MV	E=4.0 GeV
I _{pk} =12 A	$I_{pk} = 12 \text{ A}$	φ=–150°	I _{pk} =80 A	I _{pk} =1.0 kA	I _{pk} =1.0 kA	R ₅₆ =0
$\sigma_z = 1.02 \text{ mm}$	p	V ₀ =64.7 MV	$\sigma_{z}=0.15\mathrm{mm}$	$\sigma_z = 9.0 \mu m$	σ_z =9.0 μ m	$\sigma_{s}=0.13\%$
CM01	CM02,03	3.9GHz	CM04 CM15	CM16 CM33	CM34,35	

DESIGN IMPLEMENTATION & ENGINEERING CONSIDERATION

Although the benefits of the 5-bend chicane is clearly evident, its complexity does provide some difficulties in actually engineering the design. We have revised the design with the following:



Fig. 6: Revised 5-bend chicane exhibiting highly optimized

Parameter	Symbol	5-Bend
		Chicane
Energy	E_0	1.6 GeV
Momentum	$ R_{56} $	59.9 mm
Compaction		
Chicane Total	L_T	17.8 m
Length	Ĩ	
First Drift	L_D	4.4 m
Length	Ľ	
Second Drift	L_F	9.4 m

Length		
Third Drift	L_G	1.3 m
Length		
Bend Angle 1	$ \theta_1 $	0.087 rad

 $|\theta_2|$

0.046 rad

Bend Angle 2



Fig. 1: A diagram of the LCLS-II beamline with relevant component details. LCLS-II plans to utilizes a two-stage magnetic chicane compression system; BC1 and BC2.

LCLS-II CURRENT BUNCH COMPRESSOR

The currently planned compression scheme of LCLS-II consists of a twostage magnetic chicane system. Each compressor is comprised of the



Parameter	Symb	ol	4-Bend Chicane	
Electron Energy		E_0	1.6 GeV	
Momentum		R ₅₆	59.9 mm	
Compaction				
Chicane 7	Total	L_T	23.0 m	
Length				
First Chicane I	Drift	L_D	9.8 m	
Length				
Bend Angle 1		$ \theta_1 $	0.05 rad	
Eff. Length	Of	L_B	0.54 m	
Magnet 1				
Dispersion A	fter	$ \eta_x $	562 mm	
Magnet 2				
ê 0.05	(mc)	0.5	· · · · · · · · · · · · · · · · · · ·	
	utu .	0.0		
B B B B B B B B B B B B B B B B B B B	Particle Momentum			
-0.10		-0.5		

t (sec)

4TH BEND

emittance preservation.



Fig. 7 (Left to right): The corrected transverse emittance (ecnx, ecny), normalized energy spread, longitudinal energy phase space, and the current profile for the revised 5-bend chicane.

5-BEND PERFORMANCE EVALUATION

For a comprehensive performance evaluation of the revised 5-bend chicane we compared its performance with that of the currently planned 4bend chicane for two common bunch distributions and various compression ratios. The results are displayed in the tables below. The revised 5-bend chicane clearly outperforms the 4-bend chicane in emittance preservation for all cases.

Compaction $ R_{56} $ (mm)	Length (µm)	ϵ_x Growth (%)	ϵ_{χ} Growth (%)	Compaction $ R_{56} $ (mm)	Length (µm)	ϵ_{χ} Growth (%)	ϵ_{χ} (%
45.3	5.5	239	8	36.6	5.5	178	23
45.1	6.5	171	5	36.3	6.5	135	13
44.9	7.5	113	3	36.0	7.5	91	8
44.7	8.5	71	3	35.7	8.5	59	5
44.5	9.5	45	2	35.4	9.5	37	4



Fig. 3: Top/Middle: The momentum difference for each particle in each bend in the planned LCLS-II BC2 4-bend chicane generated with ELEGANT. The CSR wake begins to take form in the third bend where the bunch is compressed to 7 microns. Bottom: (From left to right) The normalized energy spread, longitudinal energy phase space, and the current profile of the beam at the exit of BC2.



We developed a numerical treatment of the linear kick model for the emittance dilution cancelling 5- bend chicane, and test its results with that of ELEGANT. We have included the effects of bunch compression by approximating the bunch length as a linear function of angle traversed through the bending magnets :

$$\sigma_z(\theta) \rightarrow \frac{\sigma_{zbeg} - \sigma_{zend}}{\theta_B} \theta + \sigma_{zbeg}$$

On the treatment of the CSR self-interaction in the system we used two methods:

Steady State Regime

The CSR self-interaction is considered to be constant throughout the bunch's trajectory in the magnet (the slippage length approaches infinity) and we can calculate the RMS spatial and angular kicks by:

 $<\Delta x_i >= \int R_{16i}(s) \,\delta_{RMS-i} ds$ $<\Delta x_i^2>=\left(\int R_{16i}(s)\,\delta_{RMS-i}ds\right)^2$

$$<\Delta x'_i >= \int R_{26i}(s) \,\delta_{RMS-i} ds <\Delta x'_i^2 >= \left(\int R_{26i}(s) \,\delta_{RMS-i} ds\right)^2$$

Transient State Regime

We account for the transient effects of the CSR self-interaction as the beam is entering the magnet:



dispersion and slope of dispersion, corrected normalized transverse emittance (ecnx, ecny), normalized energy spread, longitudinal energy phase space, and the current profile.

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