## Diagnostics for Free Electron Lasers

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**SLAC** 



# "Were you involved with LCLS lasing or did you only do the diagnostics?"

- Can't construct a FEL with sufficient accuracy to allow it to lase when you turn it on
  - Quads would need few-micron alignment over 100s of Meters
- Diagnose hardware problems in the FEL system
  - Magnet with bad multipole components.
- Understand new "physics"
  - COTR emission from profile monitors

# A Diagnostic is **NOT** an Experiment



Diagnostics need to be simple and reliable.

Usable by operations staff



# **Diagnostics Covered Here**

- RF-based electron beam centroid
  - Beam Position, Bunch Arrival Time
- Transverse and Longitudinal profile
  - Fluorescent screens, OTRs, wire scanners, Transverse cavities,
- X-ray profile
  - Fluorescent screens
- X-ray pulse energy

#### Lots of things NOT covered here

# Why RF Instrumentation?

#### •Electrons couple through electromagnetic interactions

- •Electromagnetism is linear
- •Coupling to the beam is nearly non-invasive



Complx RF devices are very common



# Intro to RF – Units / Signal Levels

"Bands" - basically random letters assigned to frequency ranges L = 1-2 Ghz, S = 2-4 Ghz, C = 4-8 Ghz, X = 8-12 GHz

Impedances: Most RF systems use 50 Ohm cables

**DBm** = Decibel milliwatt =  $10\log_{10}(1000P)$  with P in Watts.

**0dBm** = 1 mW = 224mV RMS into 50 Ohms Typical low level RF signal

**20dBm** = 100mW = 6 volts peak to peak is the maximum signal level in typical low level RF systems

**Thermal noise** = -174dBm in a 1Hz bandwidth

Typical accelerator diagnostic system bandwidth is 10MHz Implies approx -100dBm noise levels (10<sup>-13</sup> Watt, 2 uV RMS).

Note that high power RF systems produce ~ 100MW = 110dBm Range of RF signal levels is 210dB! (10<sup>21</sup>)





# Noise in RF Systems

"Noise Figure" is the ratio of the system noise (reference to the input of the circuit) to ideal thermal noise.

A 10dB noise figure implies that the circuit is 10X noisier (in power), than an ideal (room temperature) circuit, or ~3X larger in amplitude noise



Noise is generally dominated by the lowest level signals in the RF system.

For most well designed RF systems, losses in the input cable, filters and protection circuitry are a few dB. The noise figure on RF pre-amplifiers is usually < 3dB Generally safe to assume a noise figure < 10dB for a RF system. (can usually do better than this)



in the response

$$A = A_0 (1 - A_0 / V_0)$$
,  $B = B_0 (1 - B_0 / V_0)$ 

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You end up with a measured output position that depends on the beam charge.

$$X = X_0 - X_0 \frac{\alpha QD}{V_0}$$

For a 1 micron oribt accuracy at 1mm offset, need <0.1% nonlinearity over the expected charge range.

For a 10nm cavity BPM at 100 um offset, would need 10<sup>-4</sup> nonlinearity. This is often the performance limit in this type of system



In principal can measure nonlinearity varying input signal level and measuring the output.

This method is very sensitive to the accuracy of the measurement equipment an is difficult below 1% non-linearity

## **Measuring Linearity**



Two frequency sources in a linear combiner will produce only the original frequencies

Any non-linearity in the test circuit will result in sum and difference frequencies.

$$A = \sin(w_1 t), B = \sin(w_2 t), Y = (A + B) + \alpha (A + B)^2 + \beta (A + B)^3 + \dots$$

Second order term includes sum and difference frequencies  $AB = \sin(w_1 t) \sin(w_2 t) = (1/2)(\sin((w_1 + w_2)t) + \sin((w_1 - w_2)t))$ Third order term includes

 $A^{2}B = \sin(w_{1}t)\sin(w_{1}t)\sin(w_{2})t$  Which includes  $\sin(2w_{1}-w_{2})$  and  $\sin(2w_{2}-w_{1})$ 

These sidebands can easily be seen on a spectrum analyzer 10

# Non linearity: IP3



1% difference in raw signals barely visible

In most designs the 3<sup>rd</sup> order term is the most important because it produces frequencies near the signal frequency

The ration of 3<sup>rd</sup> order signal to fundamental is (in dB) 2X the ration between fundamental and "IP3" level



Slope = 3:1

2nd-Order Products

Slope = 2:1

Ры

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# Non-linearity - Implications

- Typical RF components have IP3 values from 15-45 dBm
- If you want 60dB linearity (0.1% in amplitude) you need to operate 30dB below the IP3.
- -10 to 15dBm typical
- Linearity is due to the largest signals the circuit may encounter.
- Linearity requires low signal levels, noise requires high levels: Circuit design is a compromise



# Gain and Phase Drift

For most BPM systems, changes in gain will result in changes in measured position.

Usually this scales with the BPM radius, for some designs scales with offset position

Typical RF amplifiers specified at 0.001 dB/C° to .01dB/C°, ->  $2.3\times10^{-4}$  to  $2.3\times10^{-3}$ / C° Typical cable attenuation varies as  $2\times10^{-3}$ / C° For a 1cm BPM, this is 2.3-23 microns / C°



RF system stability (ratio of charge measured by 2 phase cavity systems at LCLS) shows  $3x10^{-3}$  stability for the entire system. Temperature stability was < 0.1 C°

## **Frequency Conversion - Mixers**

A non-linear combination of 2 signals will produce sum and difference frequencies:

 $A = \sin(w_1 t), B = \sin(w_2 t) Y = c_1 A + c_2 B + c_3 A^2 + c_4 B^2 + c_5 A B + \dots$ 

 $\sin(w_1 t) \sin(w_2 t) = \frac{1}{2} [\sin((w_1 + w_2)t) + \sin((w_1 - w_2)t)]$ 

Term produces a difference frequency

Used to shift the frequency of a narrow band signal to a more convienent frequency:



# Digitizers, Bandwidth, Nyquist Limit



With a 3MHz digitizer, 1MHz and 4MHz are indistinguishable



Without a bandpass filter noise will be aliased into the signal

For almost all digitizer applications an anti-alias filter is required

# Digitizers

Remarkable progress in last 20 years has changed the approach to instrumentation



100Ms/s, 16 Bit 8 channel VME module



Digitizer chip from Texas Instruments ADS5485 200MS/s >75dB noise and nonlinearity for 100MHz input frequency \$120/channel

TI ADS5400 12 bit, 1 Gs/s with ~60dB dynamic range at 1.2 GHz input frequency. \$750

Many modern digitizer chips have an input frequency > digitizing rate .Can make use a aliasing to measure higher frequency signals

"Modern" design: get the signal into a digitizer as soon as practical

# Beam Position Monitors

Pief Panofsky's question:



In an ultra-relativistic accelerator why doesn't the BPM measure the beam position hundreds of meters upstream?



Beam pipe should be small enough to cut off the frequencies the BPM uses.

Signals can not propagate from upstream

Exactly where a BPM measures is still a tricky question



Compression chicanes with wide vacuum chambers can be a problem:

For LCLS BC2 would need a 50cm wide vacuum chamber -> cutoff frequency of 300MHz

Operation of a BPM above this frequency would be unreliable. (actual LCLS design uses a movable chamber)

## LCLS Stripline BPMs

Calibration system corrects Switched Attenuators for gain drifts and changes Band Low Noise Band Amp pass in cable attenuation Amplifier pass Input To ADC V To ADC Input x Input To ADC To ADC Input

*Calibrator pulsing tone to the* Y+ *stripline. ADC digitize* X+ *and X*- *signals. R. Akre, E. Medvedko, R. Johnson,* 

S. Smith, A. Young

**Calibration Drive Amp** 



# **Other BPM Processors**



Tendency for early designs to explore a wide range of architectures, then gradually settle on an efficient design. (Dull but practical)

RF based BPMs have near theoretical noise for their input bandwidth, and have good linearity

Electronics cost is typically dominated by packaging, cables, etc.

Alternate designs are interesting if they have increased bandwidth, or improved linearity.

Steve Smith: "Its amazing the efforts people will go to in order to avoid dividing two numbers in a computer"



# Alternate Stripline Processors

- Just put an amplifier and diode on each pickup
  - Very broadband (~20 GHz possible).
  - Linearity and stability likely to be very poor but high bandwidth makes calibration difficult
  - Might make sense for very low beam charges (but why not cavity BPM)
- Alternate filtering
  - Bandpass filter primarily used to stretch the pulse out in time, looses signal
  - Maybe a dispersive line to do the same thing without losing bandwidth?
  - Maybe frequency multiplex to many downmix circuits?
- BPMs for very high power beams may need an entirely different design



Sometimes unusual designs do make sense



# Cavity BPMs

Beam deposits energy in a resonant cavity.TM<sub>110</sub> mode response is linear in position



Honda et al ATF2



Operating frequencies typicall between 2.5 and 12 GHz Energy coupled from beam to a cavity is similar to the energy coupled to a strip line

Cavity BPM "stores" the energy for a long time – don't need an external filter to fix nonlinearity.

Full deposited energy can be delivered to the electronics

#### **Decoding Cavity BPM Signals** Power and Amplitude vs Position Simulated cavity BPM signal 0.8 0.8 0.6 0.6 0.4 0.4 0.2 0.2 0 0 -0.2 -0.2 -0.4 Power is second order. -0.4 -0.6 amplitude is linear -0.6 -0.8 -0.8 L 0 0.2 0.2 0.1 0.3 0.4 0.5 0.6 0.7 0.8 0.9 -0.8 -0.6 -0.4 -0.2 Π 0.4 0.6 Π8 x 10<sup>-6</sup>

Beam pulse produces a decaying exponential. Amplitude is linear in position and bunch charge Can use reference cavity to normalize and define 0 phase.

In general get better noise and linearity with a amplitude detection rather than power detection

# **Cavity BPM Electronics**



Low cost PC board construct for quantity production 6dB noise figure, 70dB linearity measured 27nm RMS noise at ATF2

# **Cavity BPM Performance**







LLNL cavity BPM support / mover system



# Beam Angle and Tilt Sensitivity



Front of BPM sees one phase signal, back sees opposite phase, result with time delay is a 90° out of phase signal.

Amplitude scales as beam angle \* cavity\_length



360 nR resolution demonstrated at ATF

BPM is also sensitivte to bunch tilts. Amplitude scales as head tail offset \* bunch length

Typically a small effect for short electron beams used in FELs (demonstrated in KEK / ATF ring)

# HOM mode BPMs for Superconducting Accelerators

Dipole modes act as "free" cavity BPMS.

System tested FLASH by SLAC / DESY collaboration.



# Limits to BPM Performance

- Theoretical thermal noise limit about 1nm for a 1nC bunch for a ~5 GHz cavity BPM
- Dynamic range
  - Better than 10<sup>3</sup>:1 is difficult.
  - Can allow signal to saturate early in the RF pulse, then fit to decaying exponential

- Tested at ATF2

- Mechanical mounting: 1 Meter, 1 C° is 10 microns for typical engineering materials!
  - Nanometer stability is a very challenging mechanical problem

# Multi-Bunch BPMs

- For Stripline BPMs the pickup responds in  $\sim$  1ns.
  - Filters used to improve linearity should have a time constant less than inter-bunch spacing
  - Digitizer must have a sample rate  $\sim$ 4X the inter-bunch spacing.
  - Small overlap between bunches can be fixed with proper calibration
- For cavity BPMs the situation is more complex

Stripline BPM trace: LCLS2 bunch test.8.4 ns bunch separation





# High / Low Q, Multibunch

- If cavity decay time >> interpulse spacing you don't integrate the entire signal for each bunch
  - Beam train average position resolution improves with higher Q, but single bunch noise and linearity start to degrade
- If cavity decay time << interpulse spacing (to allow independent measurements without math) the peak signals are higher and linearity suffers
- Adding damping (as opposed to increasing coupling) throws away signal – in most cases not a good solution.
- Ideal is probably for decay time ~interpulse spacing, but detailed study is required
- Multi bunch cavity BPMs for LCLS\_II (8.4ns spacing) may be challenging.

# Beam arrival time cavity (LCLS)

Similar to a cavity BPM but use the monopole mode

Phase drift from cavity temperature is the most significant problem

1us time constant, 10<sup>-5</sup> /C° temperature coefficient -> 10ps/C° (!)





# Beam Arrival Time Cavity - Noise

Compare 2 independant cavity systems to estimate noise

Present system designed for 250pC, needs more gain to operate properly at low charge



RMS difference between cavities ~12 femtoseconds RMS at 250pC, 25 femtoseconds at 20pC Drift is ~100 femtoseconds p-p over 1 day.

# EO Beam Time Measurement



# E-Beam Profile Monitors – YAG

Low energy beams (6 MeV) in LCLS 135 MeV in the injector spectrometer Main dump spectrometer

# High brightness, but saturates for high intensities

500 600 700 800 900 1000 200 400 600 800 x (Pixel) Solenoid adjusted to give an

Solenoid adjusted to give an electron emission image of the photocathode (6 MeV)



135 MeV spectrometer with TCAV on.

Saturation at 0.04pC/um<sup>2</sup> measured 250pC in 50um spot is 2X this density.

A. Murokh et al PAC2001



Main dump, 4.5 GeV, over compression, laser heater off, showing microbunching instability

Fluorescent screens generally not usable for high energy high brightness beams<sup>7</sup>

# E-beam Profile Monitors: OTR

OTR emission is linear and can provide high resolution



OTR spot size monitor at ATF2 Measured 5um RMS spot. (calculated resolution 2um RMS)





OTR image of streaked beam at 135 Mev at LCLS

# COTR

Beam contains longitudinal structure at optical wavelengths. Coherent emission from this modulation dominates the OTR output and prevents measurements.

#### Cannot use OTRs at LCLS after first bunch compressor.

# COTR also observed at DESY/FLASH, BNL, SLAC/NLCTA , Fermi/ELETTRA





Incoherent image (foil used to ruin emittance)



Coherent image X100,000 optical attenuation!

# **Detecting COTR**



# Can We Fix COTR?

- COTR is NOT a mystery: simulations are in reasonable agreement with observed COTR enhancement at LCLS
  - The simulations assume only shot noise no reason to believe this is related to the type of source laser used.
- Laser heaters help but not enough
- If beam were fully coherent, maybe we could use the COTR, but with partial coherence it is difficult.

My Opinion: I think OTR screens will continue to be unusable on high brightness high energy accelerators – but I am happy to be proven wrong!

#### Wire Scanners

Move a wire through the beam, measure degraded electrons or gammas downstream.

Note: measuring secondary emission usually doesn't work well: space-charge limit on the wire causes non-linearity for short FEL type pulses.

Wire scans only provide 1-d integrated, mult-shot beam profiles but they are the only method we have found that work with the LCLS beam .



Wire scan in LCLS injector, 72um RMS beam size 42

# **Jitter Correction for Wire Scanners**

Wire scanner measurements are multi-shot so signal must be corrected for beam jitter Wire Scanner



# **TCAV Bunch Length Measurement**



# **Transverse Cavity Resolution**

- Resolution of transverse profile measurement is usually not a limit
- Transverse kick relative to uncorrelated transverse energy spread is a limit
  - Ideally would use large beta to match beam size to TCAV aperture – but may not be practical in many cases
- Higher deflection power and higher frequency improve resolution
  - 40 MV X-band deflector under development at SLAC
- Few-femtosecond resolution looks practical <sup>45</sup>



# X-ray FEL Measurements

High pulse energy density from XFELs is a significant diagnostics problem – will damage most materials and saturate detectors.



# Attenuating X-ray beams

3<sup>rd</sup> harmonic transmission always higher than fundamental transmission

FEL contains ~1% 3<sup>rd</sup> harmonic. At large attenuation 3<sup>rd</sup> harmonic light will dominate measurements



# X-ray YAG Screens DIAG:FEE1:481 Profile Monitor YAGS:DMP1-50



100um YAG, 10 KeV Beam



YAG screen showing saturation with low energy photons

Profile Monitor YAGS:DMP1:500 09-Jun-2009 09:17:14





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# X-ray Pulse Energy Measurement

Measurements with conventional detectors or fluorescent screens are difficult due to high beam intensity

Calorometric detectors can provide calibrated average power measurements

Electron beam energy loss measurement used at LCLS for calibrated pulse energy measurements. Energy loss from wakefields contributes significantly to noise, but can be removed by calibrating against peak current variation

Gas detectors used at LCLS for pulse to pulse measurements.

# E-beam Energy Loss Measurement





shot pulse energy to users and accelerator operations

# X-ray Grating Spectrometer



3 Spectra taken at 20pC, normal operation, few spikes visible



Spectra taken with 20pc, slotted foil in: maybe 1 spike. Simulations suggest 1-2 fs FWHM in this condition

# **Diagnostics** problems

- Transverse profile measurements for high brightness beams
- X-ray pulse temporal measurements
  - Several ideas, but most look more like experiments that diagnostics
  - Ultra short X-ray bunches will require femtosecond timing for experiments
- Non-invasive X-ray spectral measurements

# Important Things Not Covered Here

- Wide variety of diagnostics
  - Toroids, beam loss monitors, halo monitors, etc
- Everything after the digitizer
  - Firmware, software, applications
- Accelerator design to enable diagnostics
  - Beamline layout, lattice design, modeling
- Mechanical design
  - No point in a nanometer resolution BPM if the support structure moves by microns