

IT INFRASTRUCTURE TIPS AND TRICKS FOR CONTROL SYSTEM AND PLC

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Abstract

The network infrastructure in Solaris (National Synchrotron Radiation Center, Krakow) carries traffic between around 900 physical devices and dedicated virtual machines running Tango 9 control system. The Machine Protection System based on PLCs is also interconnected by network infrastructure. We performed extensive measurements of traffic flows and analysis of traffic patterns that revealed congestion of aggregated traffic from high-speed acquisition devices. We also applied the flow-based anomaly detection systems that give an interesting low-level view on Tango control system traffic flows. All issues were successfully addressed, thanks to the proper analysis of traffic nature. This paper presents the essential techniques and tools for network traffic patterns analysis, tips and tricks for improvements, and real-time data examples.

INTRODUCTION

This paper is organized in six sections, where each section provides description of one real-life use case. The main goal of this paper is to provide recommendations for improvements of network architecture design.

USE CASE 1: MACHINE PROTECTION SYSTEM - PLC NETWORKS

Machine Protection System (MPS) is dedicated to ensure secure operation of machine elements. It is built on a dedicated PLC system collecting data from sensors (temperature, pressure etc.). When any of the predefined thresholds is reached, the MPS system stops the entire machine by closing valves, switching off power supplies or shutting down klystrons. Most of the equipment is capable of generating interlocks in the case of malfunction. Example: cooling water in klystron is not flowing properly – interlock is generated and MPS system stops the machine.



Figure 1: MPS CPU and IO.

The Solaris MPS is based on Rockwell Automation [1] PLCs . There are 6 CPU modules and hundreds of IO modules (Figure 1) interconnected via computer network. MPS traffic is logically separated into dedicated VLANs. There is a 20ms roundtrip for CPU – IO communication.

It means that CPU is pooling for data every 20ms and expecting result from IO. If communication is broken, the MPS system generates “communication interlock”, which in turn triggers immediate shutdown procedure for the machine.

First Approach - Bad Results

There is a natural inclination to minimize cost and design computer networks to handle different sources and types of traffic within shared equipment. The separation of traffic is done in the logical layer, but different sources share the same links infrastructure. The first approach was to aggregate MPS PLC traffic with other sources and utilize shared links and switches infrastructure.

During the building phase, it appeared that there were random occurrences of “lost communication” interlocks which stopped the operation of the entire machine. It could happen once a week or once a month, so it was difficult to catch and correlate the single event that might lead to such a case. But it was evident that some bursty traffic from other sources could increase the latency in PLC traffic to an unacceptable value. Prioritizing PLC traffic also did not help.

Recommendations

In order to address the issue of “lost communication” interlocks, it was decided to build a separate fiber optics infrastructure for PLC traffic only. Most of the network equipment was reused, but the MPS system was provided with dedicated links, with no other traffic sent over the same interfaces. In addition, there were new switches dedicated to handle traffic from beamline MPS systems.

After applying this solution, no further interlocks were observed in the period of more than 2 years of operation.

USE CASE 2: TRAFFIC SEPARATION BASED ON DEVICE TYPE

The computer network for the control system carries traffic for different types of equipment and control system software running in virtualized environment. There are hundreds of ion pump controllers, power supplies, scopes, diagnostic systems, RF systems, timing, and PLC. Also, there are multiple virtual machines running Tango9 control system. All of the network-attached systems produce different patterns of traffic. Figures 2, 3, 4 present examples of traffic from Ion Pump controller, Modulator and Control Room computer.



Figure 2: Ion pump controller traffic.

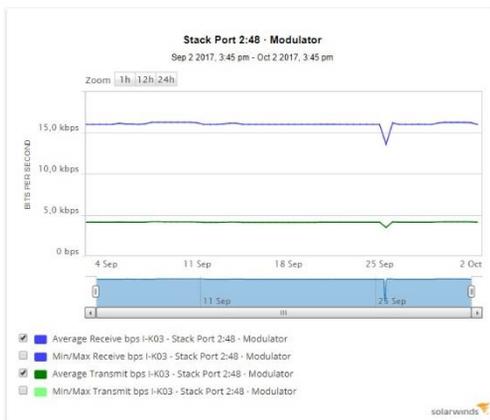


Figure 3: Modulator in section I-K03 traffic.

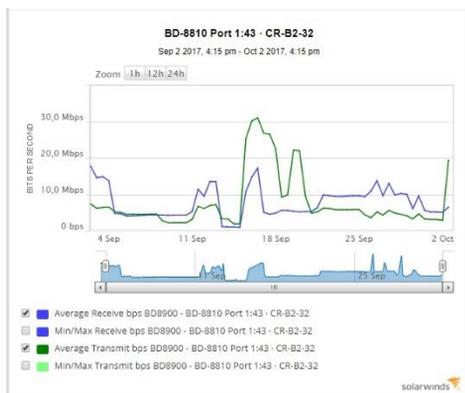


Figure 4: Control Room computer traffic.

Recommendations

Since there are different patterns of traffic depending on the type of equipment, it is recommended to make the logical separation of network by using 802.1q VLANs for each subsystem. It enables controlling the priorities and shaping the bandwidth based on the traffic pattern.

Also, it is recommended to attach the virtual machines with control system to the same VLAN as the controlled subsystem (cf. next use case).

USE CASE 3: COMMUNICATION BETWEEN DEVICES, DEVICE SERVERS AND CONTROL ROOM

In Tango9 [2] control system, all devices are managed by Device Servers. A Device Server is a piece of software that runs on a virtual machine and polls devices for data.

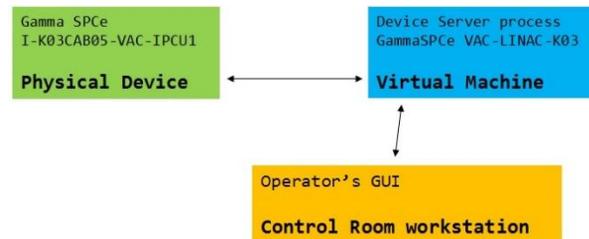


Figure 5: Tango9 communication principles.

Operators in the control room are using GUI applications that communicate with the device server in order to get data and manage devices (see Figure 5). There are two patterns used to receive data: polling and publish/subscribe. It is crucial that the computer network carrying traffic for the control system should be stable and should provide low-latency capabilities.

Recommendations

In order to provide low latency links, it is recommended to shorten the physical and logical path between control room computers and virtual machines running device servers. Also, the path between virtual machines and devices should be as short as possible.

```
Operator@CR2:~$ ping vac-linac.m.cps.uj.edu.pl
PING vac-linac.m.cps.uj.edu.pl (192.168.133.20): 56(84) bytes of data:
64 bytes from vac-linac.m.cps.uj.edu.pl (192.168.133.20): icmp_seq=1 ttl=63 time=0.228 ms
64 bytes from vac-linac.m.cps.uj.edu.pl (192.168.133.20): icmp_seq=2 ttl=63 time=0.199 ms
64 bytes from vac-linac.m.cps.uj.edu.pl (192.168.133.20): icmp_seq=3 ttl=63 time=0.292 ms
64 bytes from vac-linac.m.cps.uj.edu.pl (192.168.133.20): icmp_seq=4 ttl=63 time=0.208 ms
64 bytes from vac-linac.m.cps.uj.edu.pl (192.168.133.20): icmp_seq=5 ttl=63 time=0.159 ms
^C
--- vac-linac.m.cps.uj.edu.pl ping statistics ---
5 packets transmitted, 5 received, 0% packet loss, time 400ms
rtt min/avg/max/mdev = 0.159/0.216/0.292/0.046 ms
Operator@CR2:~$
Operator@CR2:~$
Operator@CR2:~$
Operator@CR2:~$ traceroute vac-linac.m.cps.uj.edu.pl
traceroute to vac-linac.m.cps.uj.edu.pl (192.168.133.20): 30 hops max, 60 byte packets
 0  vac-linac.m.cps.uj.edu.pl (192.168.133.20)  0.196 ms  0.194 ms  0.170 ms
Operator@CR2:~$
Operator@CR2:~$
Operator@CR2:~$
```

Figure 6: Path between the control room computer and the virtual machine running the device server for VAC subsystem.

As shown in Figure 6, the number of ‘hops’ between the control room computer and the virtual machine is merely “one”. It means that the path is very short in terms of routing, giving very low latency.

traffic and identify potential anomaly (Figure 10). One of them is Flowmon [4], a tool that brings ability to learn the nature of traffic and to categorize network events by the risk they pose on the infrastructure.



Figure 10: Example of unsuccessful connections captured by Flowmon.

USE CASE 6 : LOCAL NETWORK DIAGNOSTICS WITH TAP

The network monitoring software provides information on the state of infrastructure elements and particular network interfaces. If there is an issue with a single device attached to a network port (e.g. a huge number of dropped packets), it may be suspected that there is either a physical issue (cabling) or a traffic pattern which can not be handled properly by network equipment.



Figure 11: Network TAP [5].

Recommendations

If it is feasible, one can consider using a network TAP (Figure 11) located between the physical device and the network port. TAP is transparent and makes a copy of entire traffic sent between the device and the network port. It includes malformed frames, so it is easier to capture possible issues with cabling (e.g. an unshielded UTP cable interfering with some strong signal sources)

It needs to be noted that the port SPAN or mirroring do not replicate malformed frames, so a network TAP is the only way to capture entire traffic flowing between a device and network equipment.

CONCLUSION

The proper design and implementation of network infrastructure is critical for operation of control systems for Experimental Physics facilities. To achieve stability and predictability of network infrastructure, it is advised to:

- Monitor, analyze and understand network traffic
- Redesign network infrastructure to comply with the existing traffic patterns
- Proactively identify new traffic sources coming with IoT reality

Active monitoring and analysis of traffic patterns can offer a new perspective on how the control system exchanges data. By analysing flows, potential issues generated by software malfunction can be quickly identified.

REFERENCES

- [1] Rockwell Automation, Allan Bradley, PLCs, <https://www.rockwellautomation.com/>
- [2] Tango 9 Control System, <http://www.tango-controls.org/>
- [3] Basler cameras, <https://www.baslerweb.com>
- [4] Flowmon - flow based monitoring system, <https://www.flowmon.com>
- [5] Network TAPs by DatacomSystems, <http://www.datacomsystems.com/products/network-taps>