## **MAGNETS FOR ELETTRA 2.0**

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# work, publisher, and DOI Abstract

Community with excellent results, Elettra need a major of the upgrade with a new compact lattice that will replace the existing double bend achromat for the reduction of the horizontal emittance and the increase of the brilliance and

Ecoherence of the X-ray beam. This paper reports the ma and optimisation carried out i This paper reports the magnetic design development and optimisation carried out in order to satisfy the layout

#### LAYOUT

feasibility and magnet strengths. The design of new machine optics with the constraint of maintaining the current size of the ring has produced a a layout with really short drifts between the magnetic lengths [1]. The design of magnets that can be installed so close to each other is therefore one of the most important  $\frac{1}{2}$  challenges of the Elettra 2.0 magnetic layout. Figure 1 shows the half-achromat section of the magnetic layout shows the half-achromat section of the magnetic layout work where several quadrupoles have a transverse offset in order to fulfil the reverse bend function.



Figure 1: Elettra 2.0 achromat magnet layout.

#### NOVEL KIND OF MAGNET

3.0 licence (© 2019). Any distribution of this Considering the fact that in the Elettra 2.0 magnetic layout the shortest drift among the various magnetic lengths is less than 50 mm, the first challenge was to  $\succeq$  design magnets with an overall length almost equal to the relative magnetic length ( $L_{tot} \approx L_{mag}$ ). Since the irondominated electromagnets have, generally, the Ltot bigger erms of the than the  $L_{mag}$  due to the size of the coils around the pole terminations, the idea was to design a magnet with coils longitudinally inside the poles. Starting from mushroomshaped terminations, the objective of obtaining a constant distribution of the field on the path has developed a comnder bination between the shape of the pole ends and the reverse winding of the coils. Figure 2 illustrates the geomeused try of the pole and the coils thus obtained.

It should be noted that the longitudinal elongation of g ≩ the poles terminations leads to mitigating one of the classic saturation effects on the pole profiles, improving the tion of the field within the roots of the poles requires yoke made of solid iron. This type of field quality in the range of use. The longitudinal distribumade of solid iron. This type of iron is also used to obtain rom higher mechanical precision as is generally required in small-aperture magnets such as those of Elettra 2.0.

Figure 2 shows the yoke shape and the reverse coil winding.



Figure 2: Quadrupole yoke and coil winding.

#### **PROTOTYPE**

The objective of the prototype is to prove the feasibility of this new novel kind of magnets. Other objectives are to study the possibility of having air-cooled coil and the study of dynamic supporting systems between the two separate parts in order to allow the optimization their intra-alignment by the magnetic measurements. As already done in other projects [2], also in this case the pole profile shimming was defined by geometric formulas with only four parameters. The used formulas has been the following:

$$y = \frac{R^2}{2x} - K_y \left(\frac{x - x_s}{x_t - x_s}\right)^N \tag{1}$$

Where:

$$K_{y} = \frac{R^2}{2x_t} - y_t \tag{2}$$

$$x_s = x_t + N \frac{K_y}{\tan \alpha + \frac{R^2}{2x}}$$
(3)

Figure 3 reports the pole profile parameters plot.



Figure 3: Pole profile equation and plot.

The optimization of the profiles was done using the Esteco MODEfrontier [3] optimization code, which, in turn, coordinated the VF Opera [4] Modeller, Tosca, Elektra and post-processor modules together with the special post-processing data via Matlab [5]. The MODEfrontier

> **MC7: Accelerator Technology T09 Room Temperature Magnets**

workflow is illustrated in Fig. 4. The prototype magnetic model is illustrated in Fig. 5 while Fig. 6 shows the longitudinal distribution of the calculated field.



Figure 4: MODEfrontier workflow.



Figure 5: Prototype magnetic model.



Figure 6: Prototype longitudinal field distributions.

The prototype calculated performances are listed in Table 1.

Table	1. Prototype	Calculated	Performances
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Curr [A]	∫G [T]	sat [%]	$\left  G_{6} \right  \left  G_{2} \right $	$\int G_{10} / \int G_2$
60	12.4772	-8.05	-1.1566e-4	4.5820e-7
50	10.9291	-3.36	-7.8197e-5	2.6946e-6
45	9.9662	-2.08	-6.4622e-5	3.6177e-6
40	8.9355	-1.23	-5.4567e-5	4.3751e-6
30	6.7638	-0.32	-4.1808e-5	5.4433e-6
20	4.5217	-0.04	-3.7949e-5	5.7793e-6
10	2.2617	0.00	-3.7774e-5	5.7953e-6

The prototype will be realized by a scientific collabora tion between CERN and Elettra by the end of 2019.

#### **QUADRUPOLES**

Starting from the development of the novel kind of magnets, the first magnets defined for Electra 2.0 were quadrupoles. Two families of quadrupoles based on the required magnetic length make it possible to cover all the quadrupoles defined in the Elettra 2.0 magnetic layout. Table 2 and Table 3 report the parameters of the required quadrupoles.

Table 2: Required Quadrupoles

Name L <sub>mag</sub>		k	B1	Ø	B <sub>pole</sub>
	(m)		(T/m)	(mm)	(1)
Q1	0.13	-2.840	-22.72		0.295
Q33a	0.13	-0.380	-3.04	26	0.040
Q2	0.24	5.490	43.82	20	0.571
Q33b	0.24	5.720	45.76		0.595

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Name	Lmag (m)	k	B1 (T/m)	Angle (°)	Ø (mm)	Bpole  (T)
Q333a		5.180	41.44	0.4		0.539
Q4_1	0.24	5.490	43.92	0.4	26	0.571
Q333b	0.24	5.500	44.00	0.5	20	0.572
Q4		5.687	45.50	0.5		0.591

#### SEXTUPOLES

Similary to the quadrupoles, also the sextupoles have been developed to have a magnetic length equal to the total length. Also in this case, in order to maximize the gap on the external side for the light exits, the yoke is made with separate parts and asymmetrical pole roots. The optic sextupole specifications required the use of four families that are S23, S18, S16 and S12. Table 4 lists the parameters of the required sextupoles.

ISBN: 978-	ISBN: 978-3-95450-208-0 Table 4: Required Sextupoles					
Name Name	L <sub>mag</sub> (m)	m	B2 (T/m <sup>2</sup> )	Ø (mm)	B <sub>pole</sub>   (T)	
5 SD0	0.12	-146.7	-2347.2		0.300	
SEXP	0.12	161.7	2587.2		0.331	
ਤ੍ਰੀ SD_1L	0.16	-204.0	-3264.0		0.418	
SF	0.16	209.4	3350.4		0.429	
SDE_1	0.16	-210.3	-3364.8	32	0.431	
ું SD_2	0.16	-213.1	-3409.6		0.436	
fu SD_1	0.16	-249.1	3985.6		0.510	
ខ្មី SFMS_L	0.18	286.6	4585.6		0.587	
SFIS	0.23	203.4	3354.4		0.417	
The Elett	BENDINGS					
and transversal gradient. The design of these magnetics under development with the task to achieve the require field distribution. In the previous versions the bends with the shaping of the starsverse gradient were obtained were obtained with the shaping obtained were obtained were obtained were obtained						

<sup>35</sup> transverse gradient were obtained with the shaping of the poles and appropriate shaping of the coils. Table 5 lists poles and appropriate shaping of the coils. Table 5 lists the parameters of the required bending.

Table 5: Required Bending

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	Name	Lmag (m)	B0 (T)	B1 (T/m)	Angle (°)
-	DE1	0.((	0.7(1)	17.0	26
	BFI	0.66	0./616	-1/.2	3.6
		0.29	0.9148	-22.4	1.9
•	BFSM	0.22	1.7771	0.0	2.8
		0.29	0.9148	-22.4	1.9
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#### **CORRECTORS**

Almost all correctors must be combined in the sextupoles. The use of two or more power converter is under study in order to overcome the issue due to the separated yoke parts.

#### CONCLUSIONS

The magnetic layout needs to be validated by the prototyping of all the required magnets. In particular from the prototyping of the girder assemblies that will have the purpose to test the air-cooling system and the dynamic je positioning of the combined quadrupoles. This activity will immediately follow the realization of the first quadrupole prototype.

### REFERENCES

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