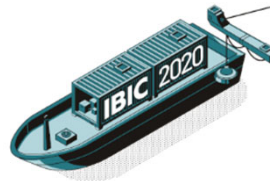




Direct digitization and ADC parameter trade-off for bunch-by-bunch signal processing

Irene Degl'Innocenti
Università di Pisa, CERN

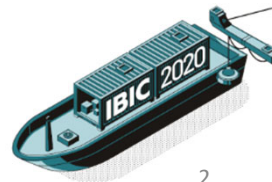
International Beam Instrumentation Conference
September 2020



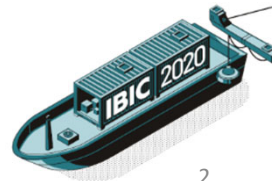


Outline

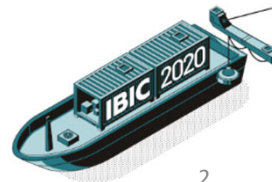
- Introduction
 - Direct digitization of bunch signals in beam instrumentation
 - ADC parameter trade-off



- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse signal
 - The effect of a limited sampling rate
 - The effect of a limited sampling resolution
 - A combined SNR expression



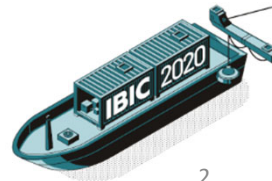
- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse
- Application example
 - A proposed architecture for the LHC BPM read-out electronics
 - Expected position resolution with commercial ADCs





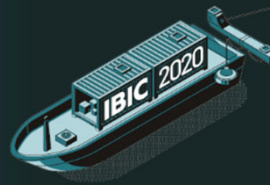
Outline

- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse
- Application example
- Summary

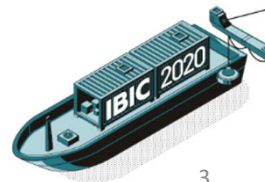
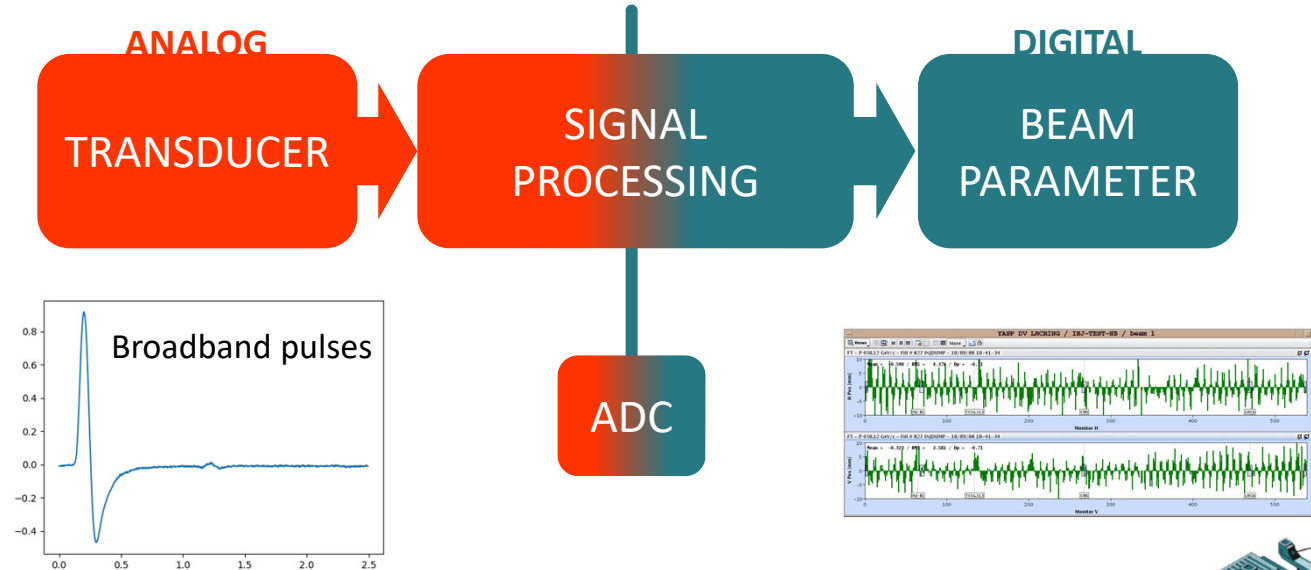




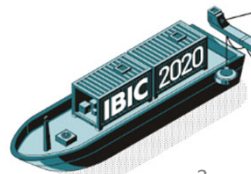
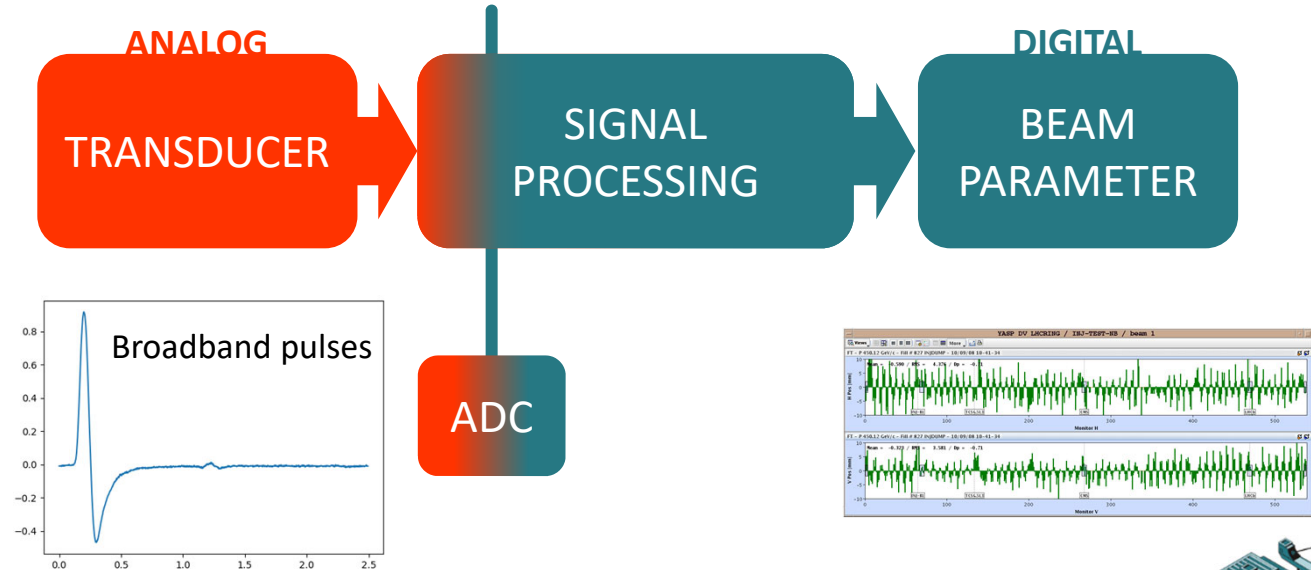
Introduction



Direct digitization in Beam Instrumentation

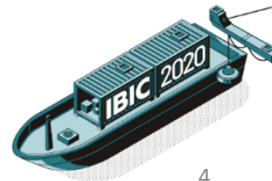


Direct digitization in Beam Instrumentation

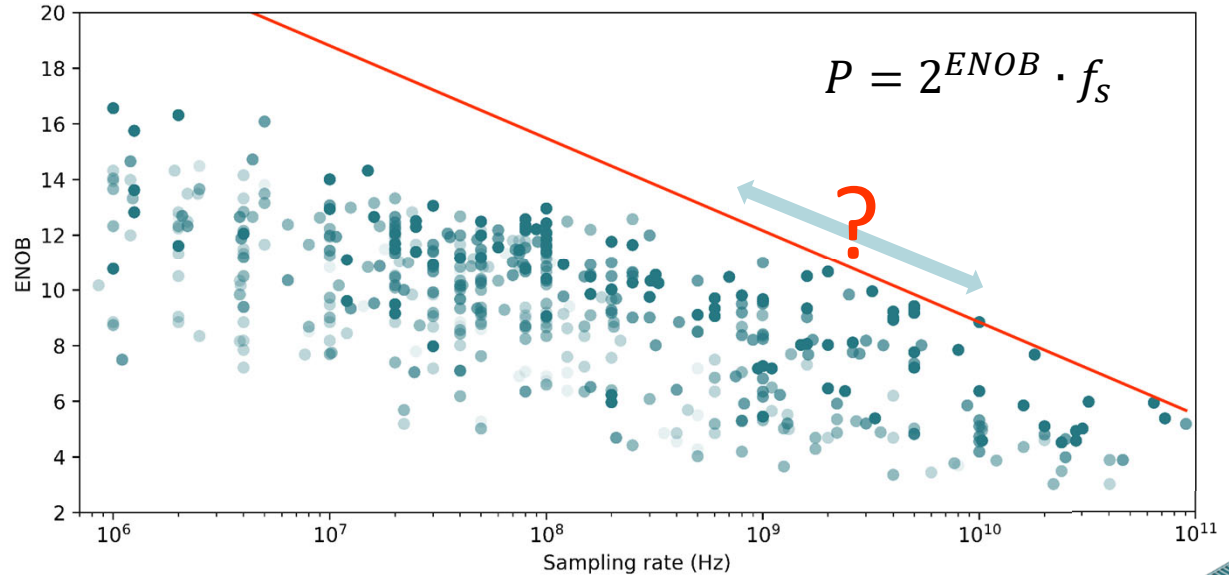


Direct digitization in Beam Instrumentation

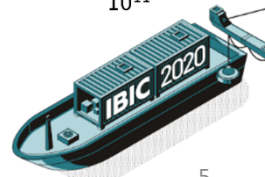
- Less analogue components
 - Less parameter spread
 - Less parameter drifts effects
- Reprogrammable algorithms
- BUT demanding requirements in terms of resolution and sampling rate on the digitization stage



Analog to Digital Converter trade-off

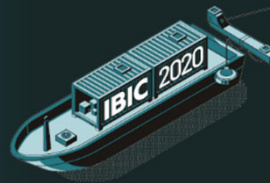


Data source: B. Murmann, "ADC Performance Survey 1997-2020," [Online].
 Available: <http://web.stanford.edu/~murmann/adcsurvey.html>



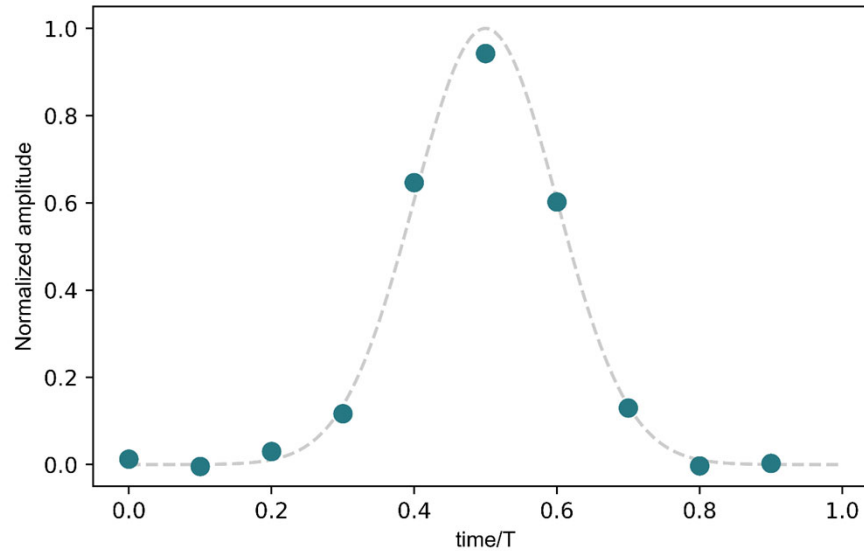


Analysis of the error in the power measurement of a direct digitally acquired pulse signal



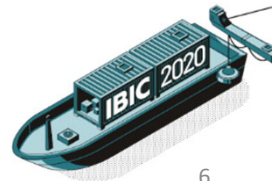
Problem Definition

Power measurement of a pulsed signal



$$P_T = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

$$\overline{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_{n,\tau} + v_n)^2$$

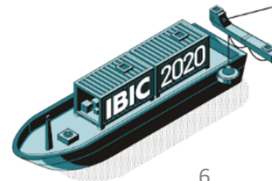


Power measurement of a pulsed signal

$$P_T = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

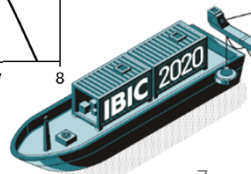
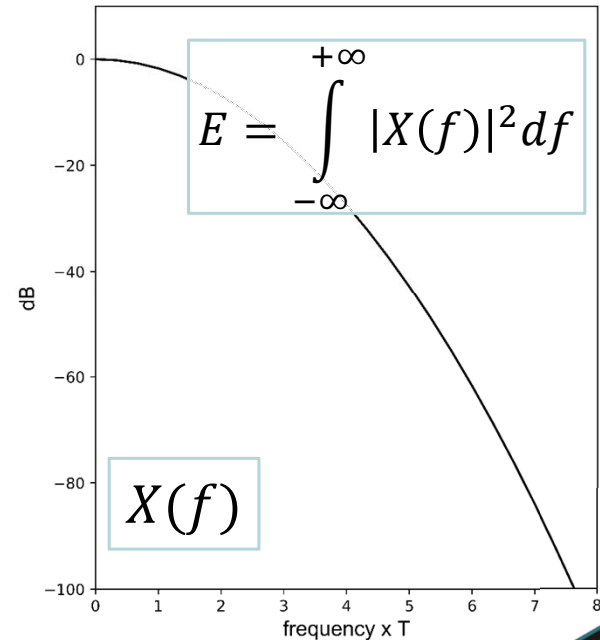
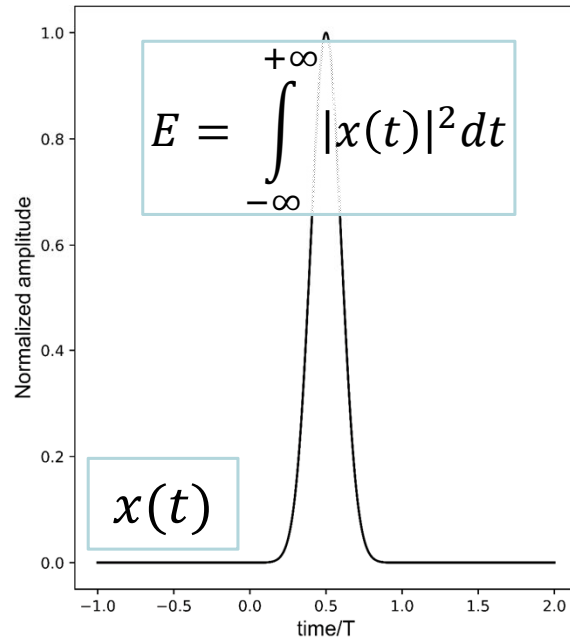
$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_{n,\tau} + v_n)^2$$

- Is $\overline{P_T}$ a good estimation of P_T ?
 - What is the effect of a limited unsynchronised sampling rate?
 - What is the effect of the finite resolution of the converter?



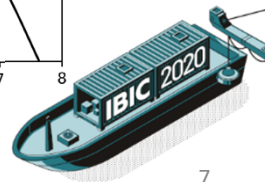
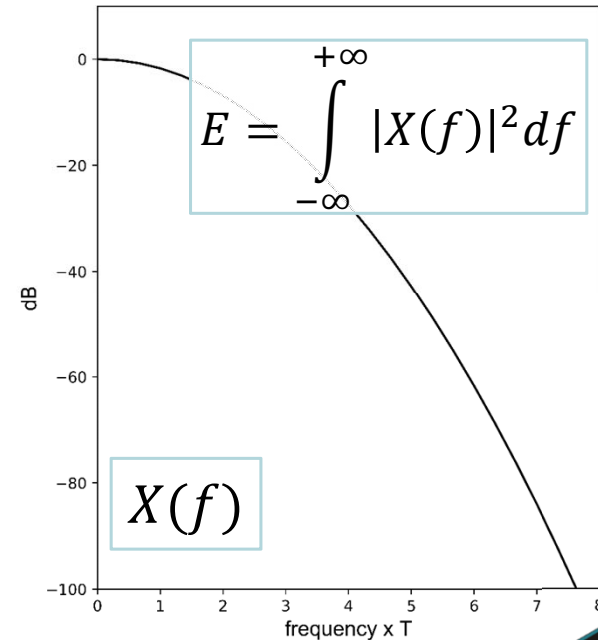
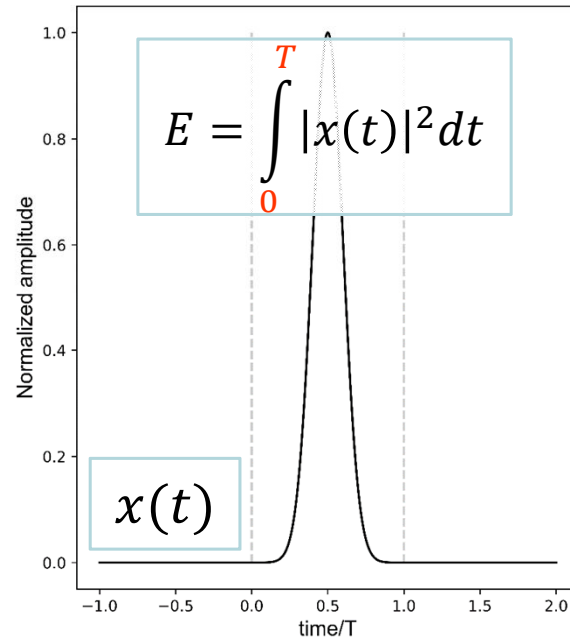
Limited Sampling Rate

Energy and power in time and frequency domain



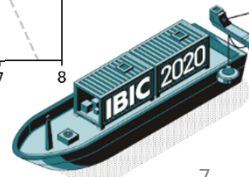
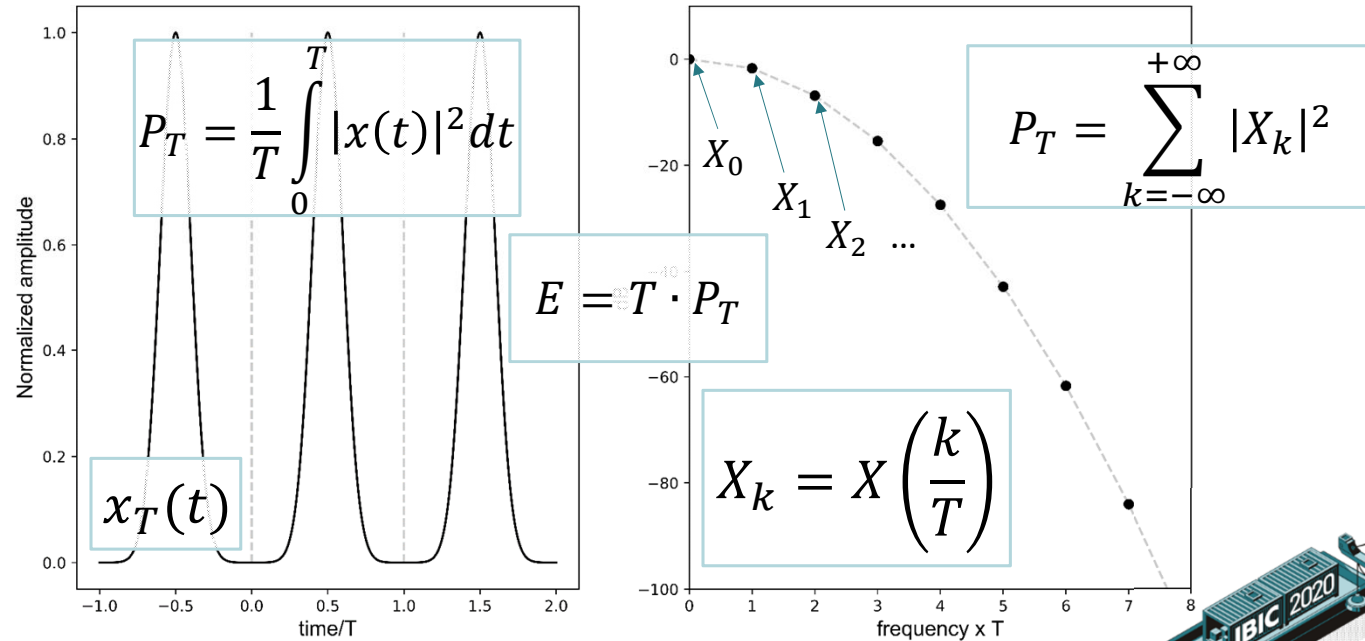
Limited Sampling Rate

Energy and power in time and frequency domain



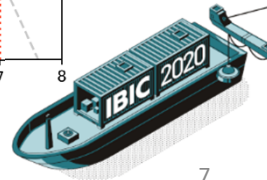
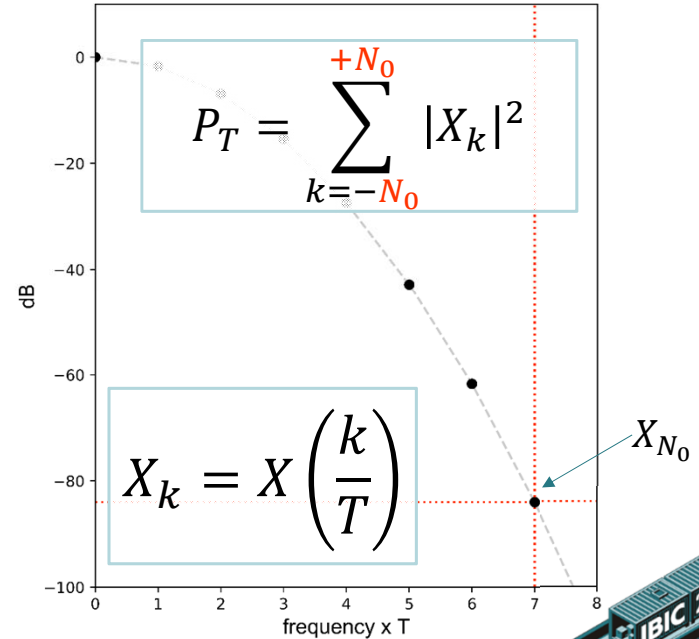
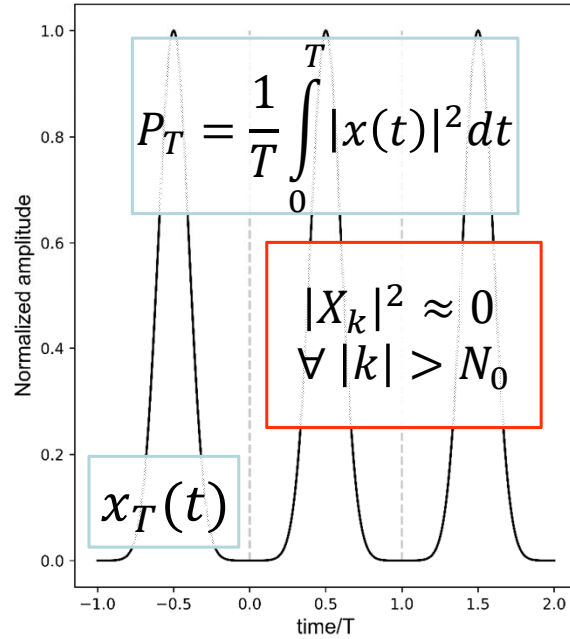
Limited Sampling Rate

Energy and power in time and frequency domain



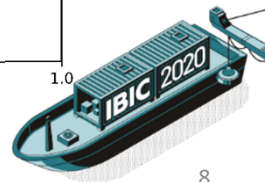
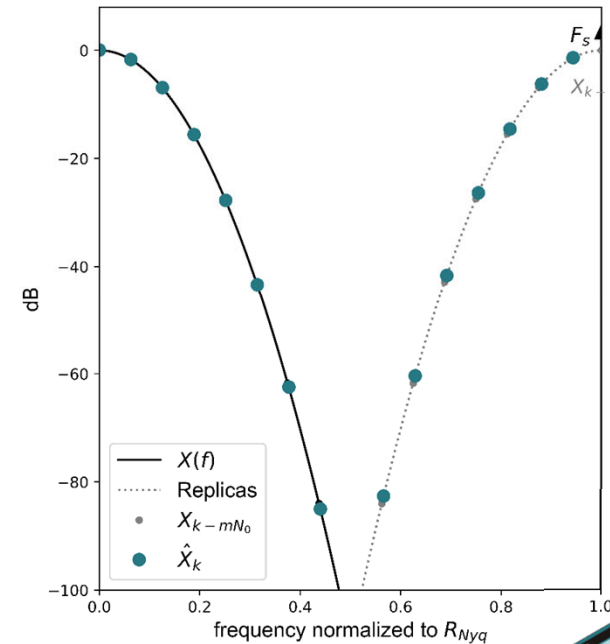
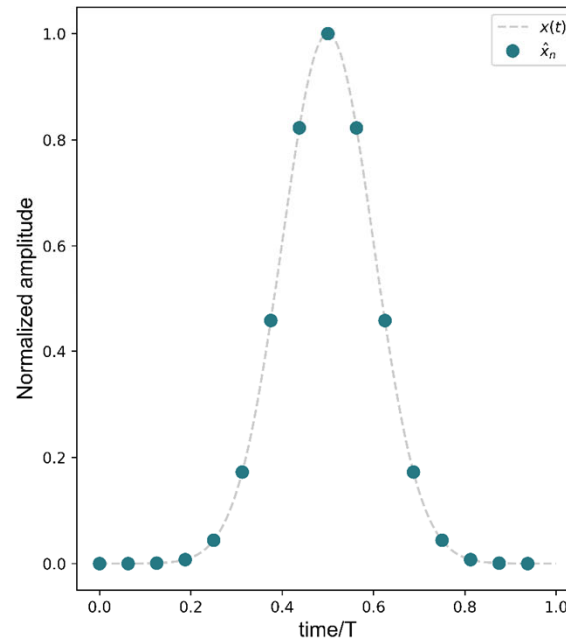
Limited Sampling Rate

Energy and power in time and frequency domain



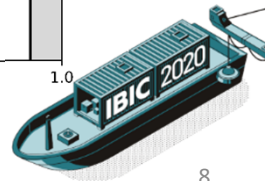
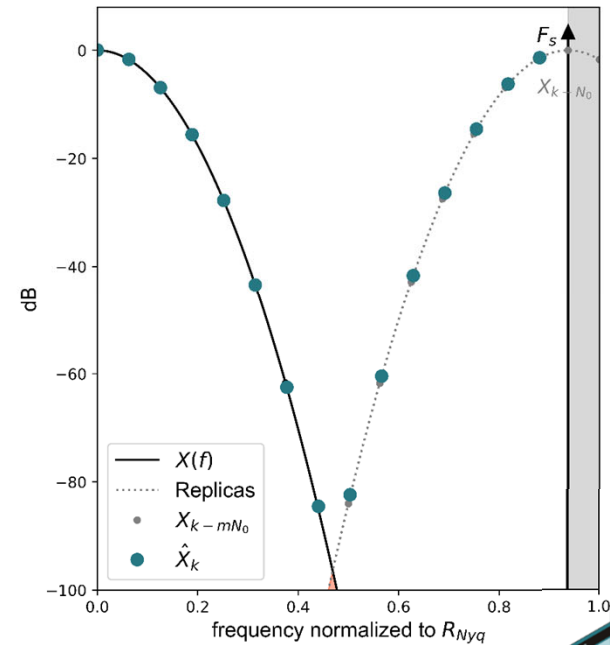
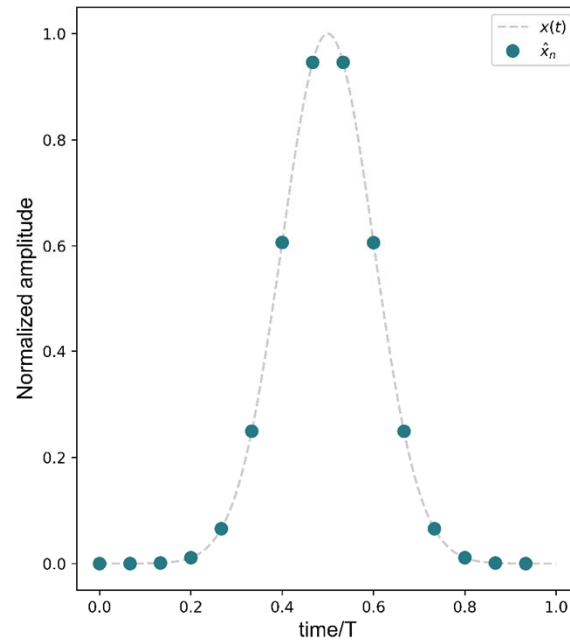
Limited Sampling Rate

What happens when we sample the pulse



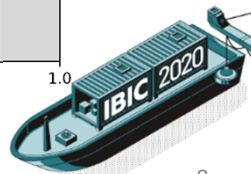
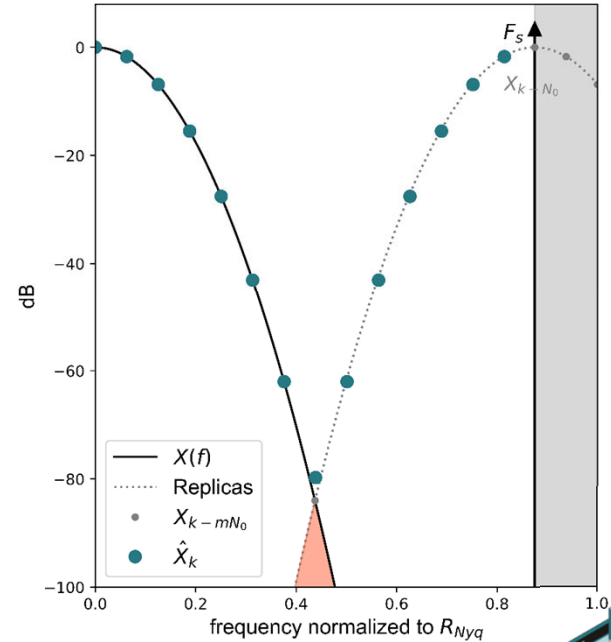
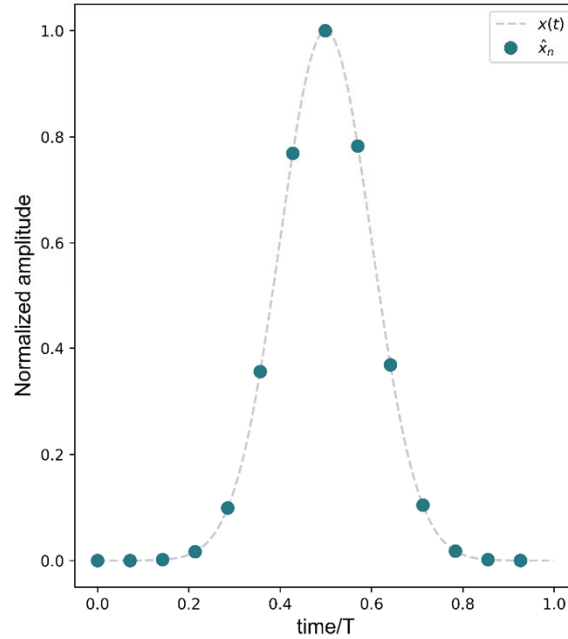
Limited Sampling Rate

What happens when we sample the pulse



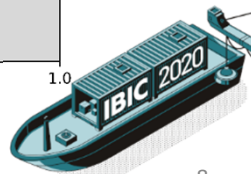
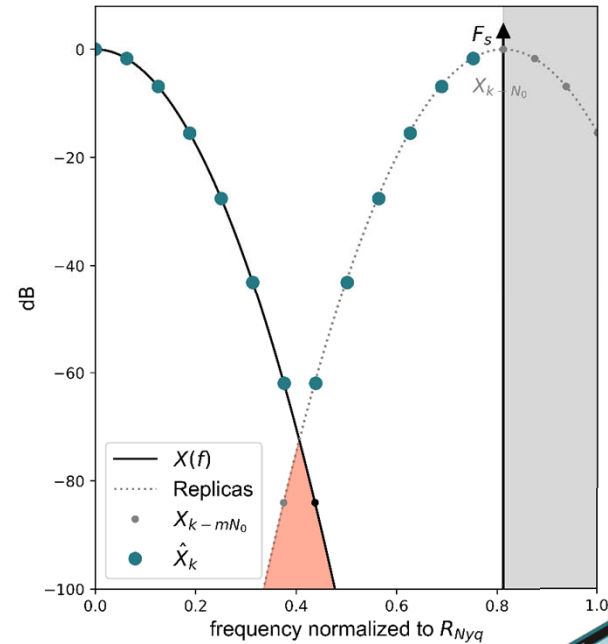
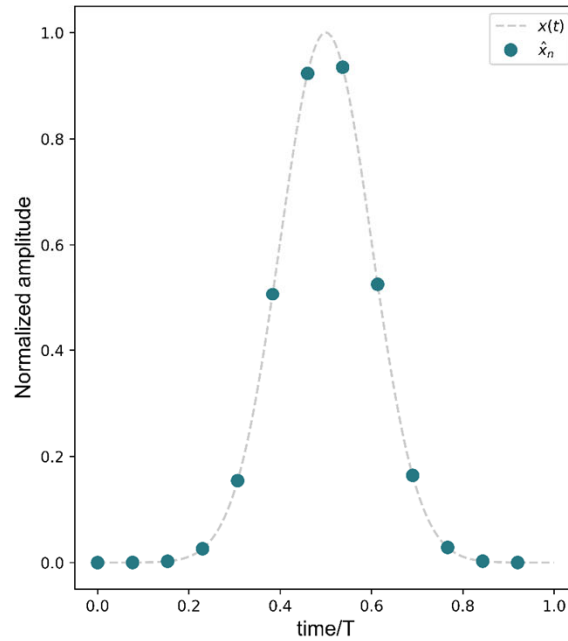
Limited Sampling Rate

What happens when we sample the pulse



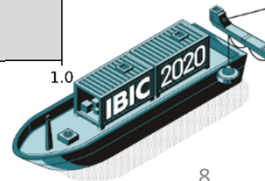
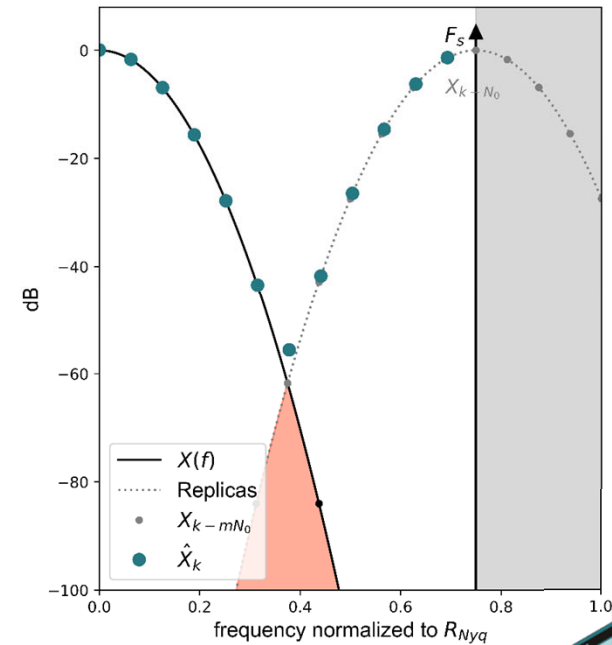
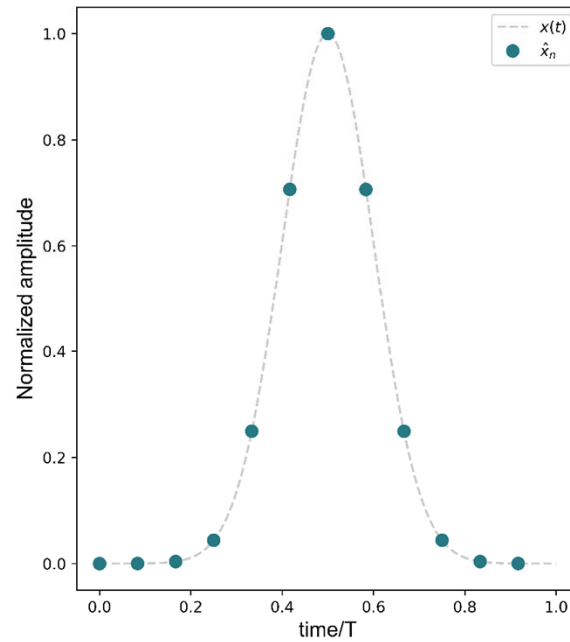
Limited Sampling Rate

What happens when we sample the pulse



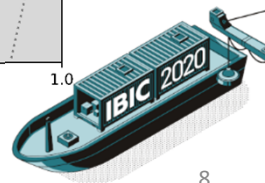
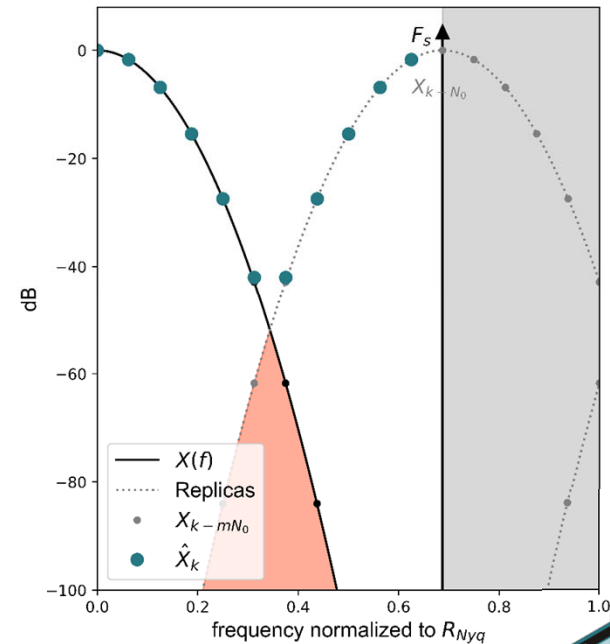
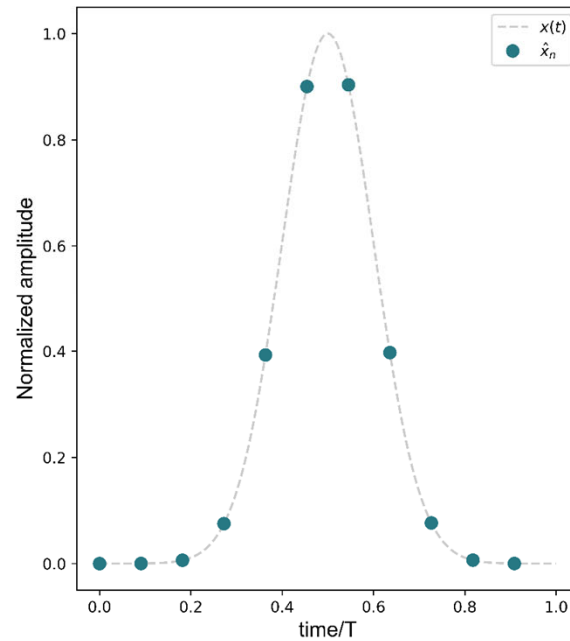
Limited Sampling Rate

What happens when we sample the pulse



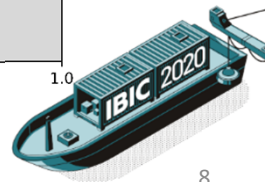
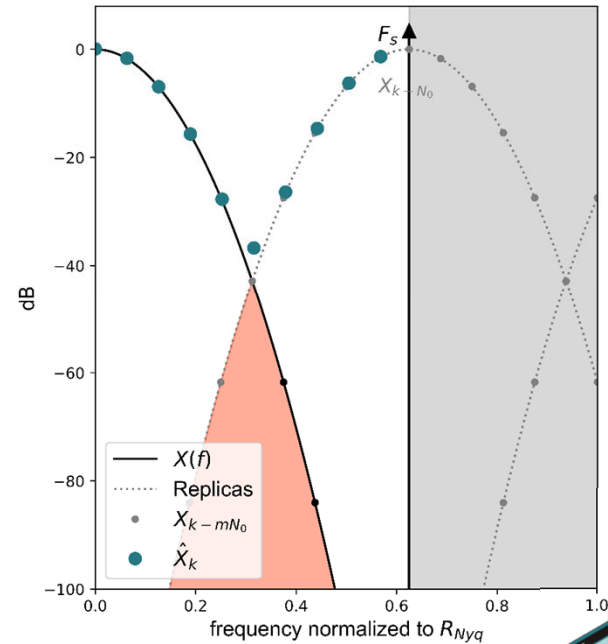
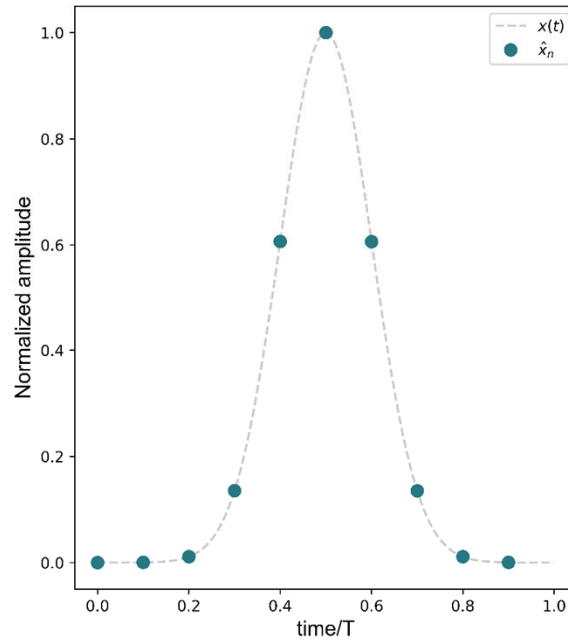
Limited Sampling Rate

What happens when we sample the pulse



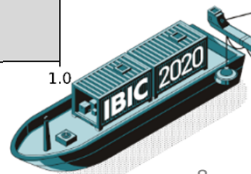
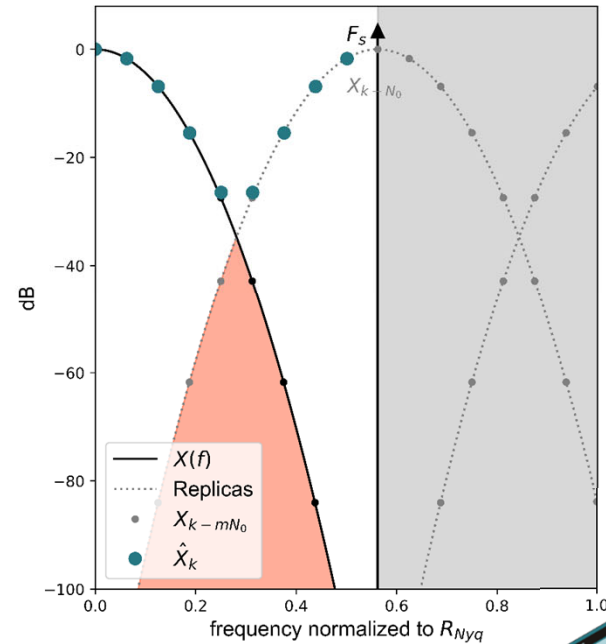
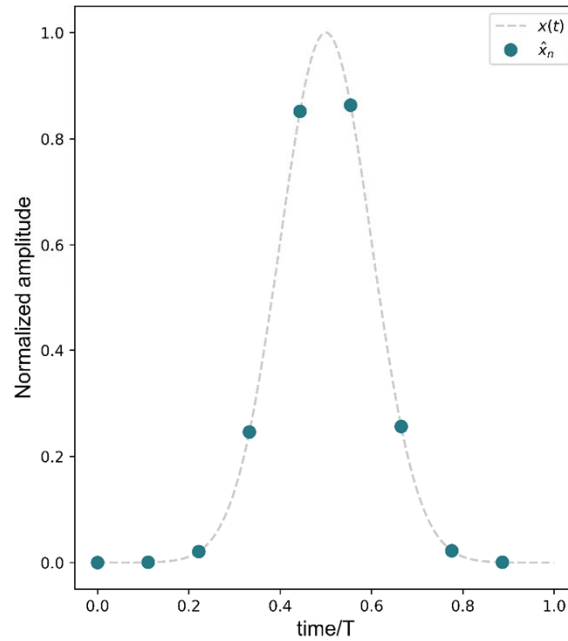
Limited Sampling Rate

What happens when we sample the pulse



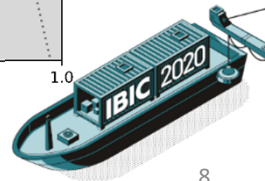
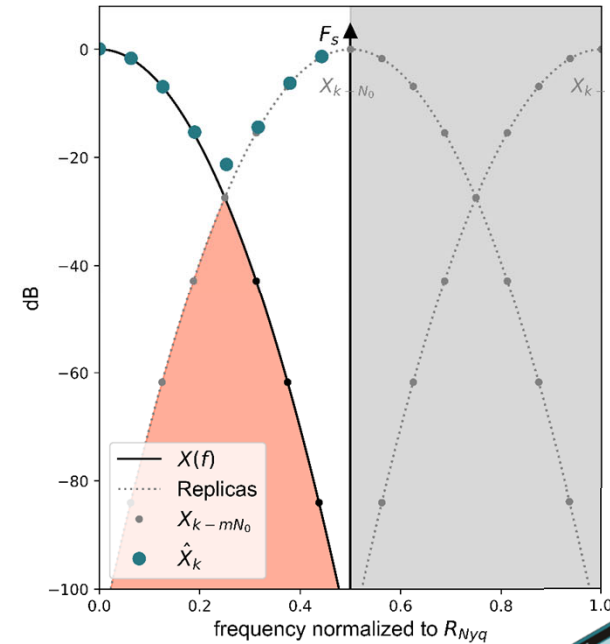
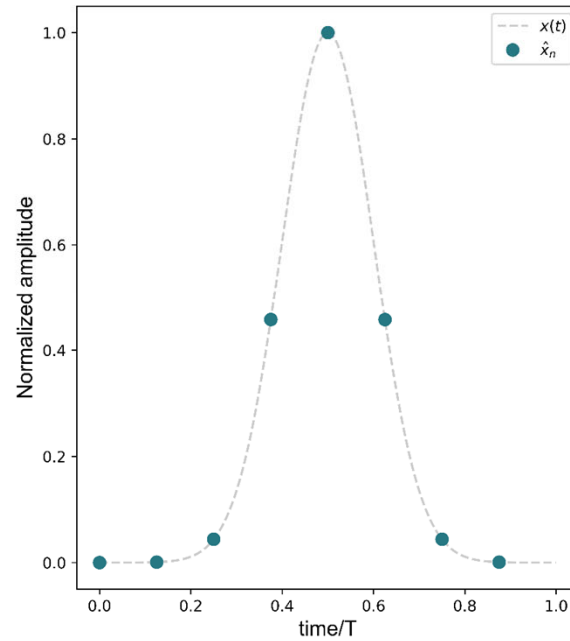
Limited Sampling Rate

What happens when we sample the pulse



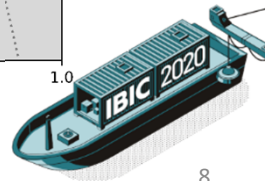
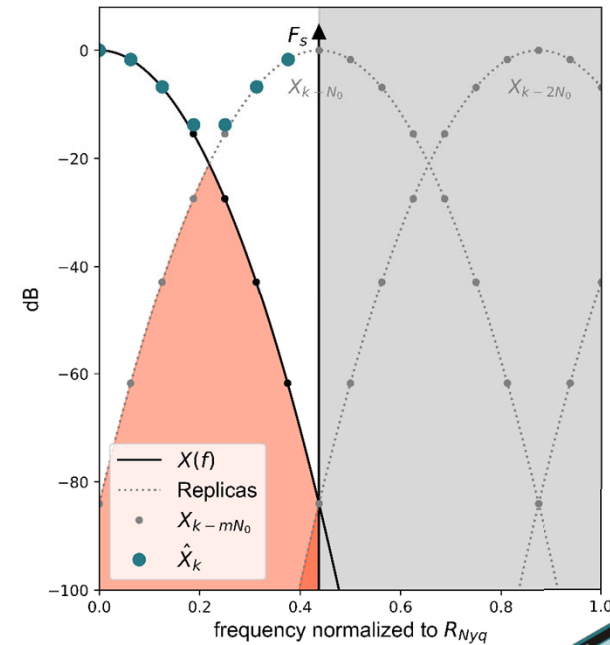
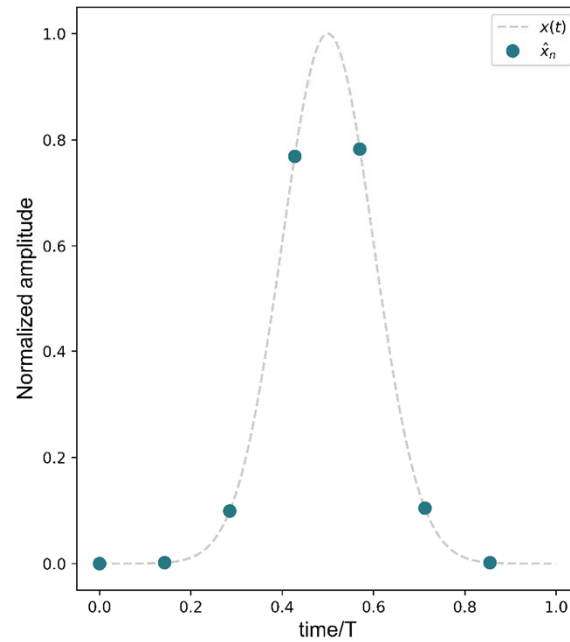
Limited Sampling Rate

What happens when we sample the pulse



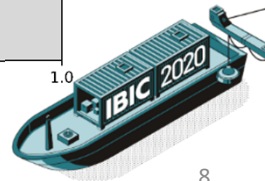
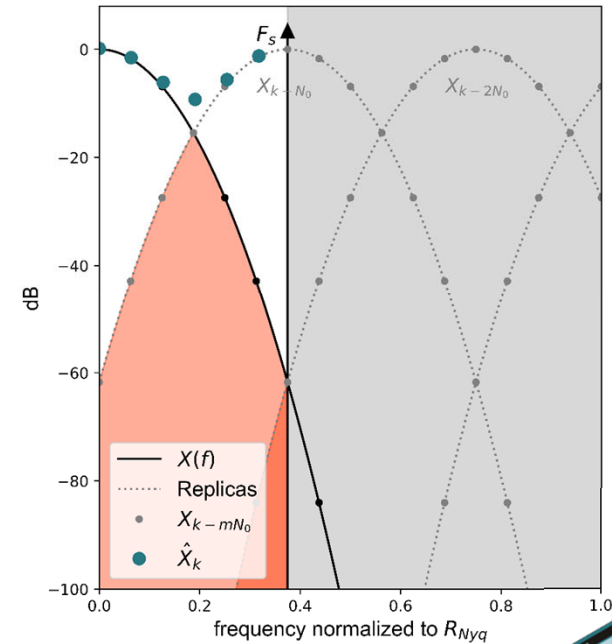
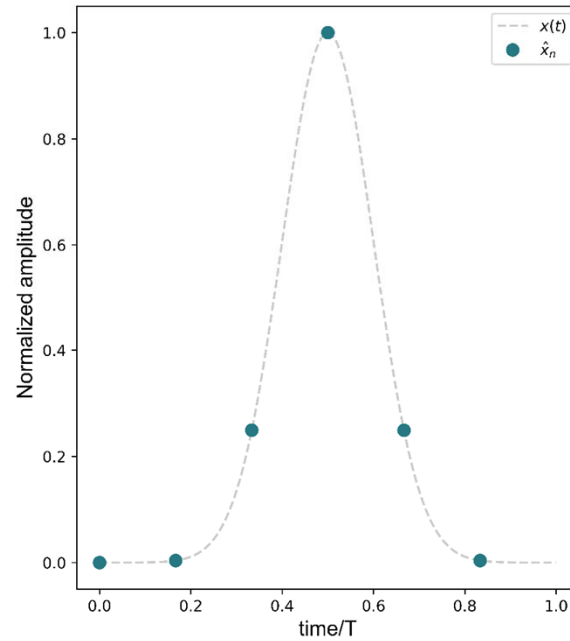
Limited Sampling Rate

What happens when we sample the pulse

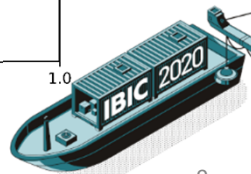
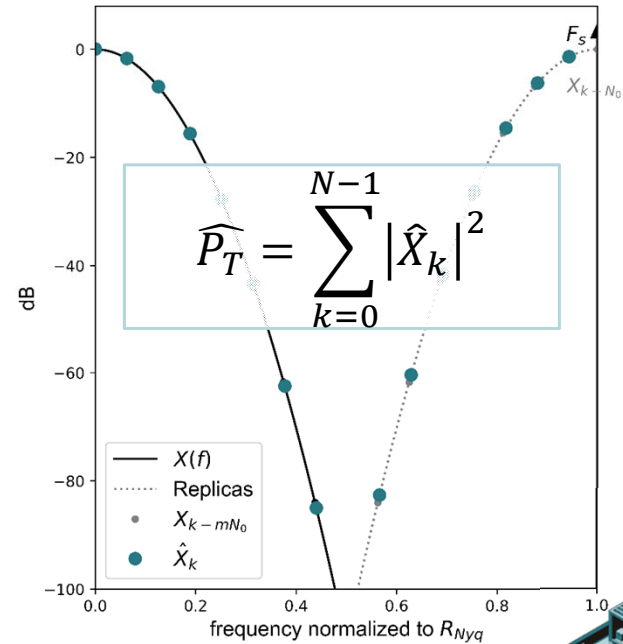
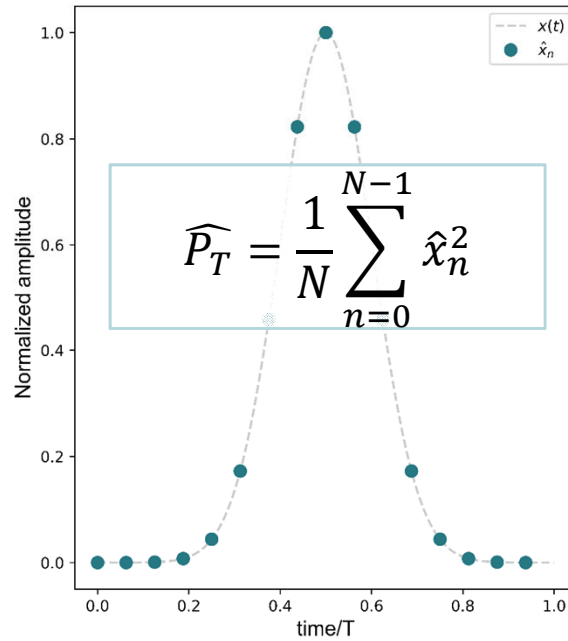


Limited Sampling Rate

What happens when we sample the pulse



And the energy estimation?



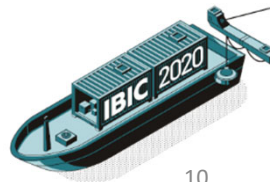
Limited Sampling Rate

And the energy estimation?

- If the *Nyquist-Shannon* criterion is met ($F_S > R_{Nyq}$)

$$\rightarrow \widehat{P}_T = P_T = E/T$$

- BUT what if $F_S < R_{Nyq}$?



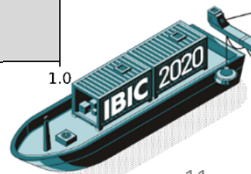
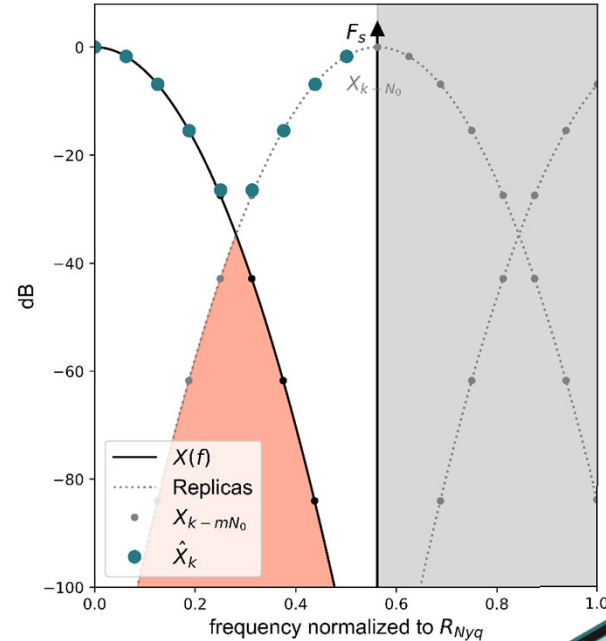
And the energy estimation?

$$\frac{R_{Nyq}}{2} < F_s < R_{Nyq}$$

$$\widehat{X}_k = X_{k-N} + X_k$$

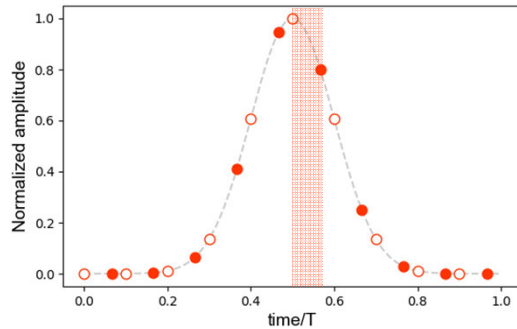


$$\widehat{P}_T = \sum_{k=0}^{N-1} |\widehat{X}_k|^2$$



Limited Sampling Rate

And the energy estimation?



Sampling rate



$$\text{Hyp: } \frac{R_{Nyq}}{2} < F_s < R_{Nyq} \leftrightarrow N_0 < N < 2N_0$$

Input signal spectrum



$$X_k = |X_k| e^{-i\phi_k}$$

Sampling delay

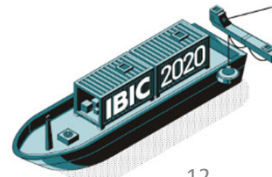


$$\tau$$

$$\widehat{P}_T = P_T + 2 \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \cos(\phi_k - \phi_{k-N} - 2\pi F_s \tau)$$

Quantity to estimate

Error term



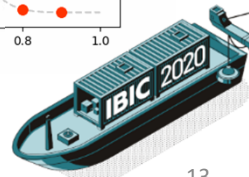
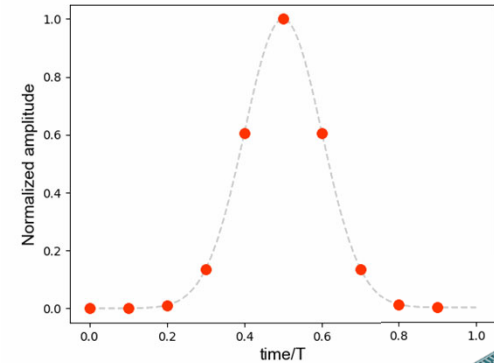
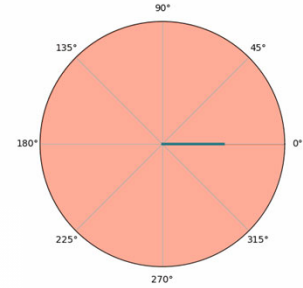
The estimation error

$$\epsilon(X_k, F_S, \tau) \triangleq \widehat{P}_T - P_T$$

$$\epsilon(X_k, F_S, \tau) = A_{X_{k,N}} \cdot 2 \cos(2\pi F_S \tau) + B_{X_{k,N}} \cdot 2 \sin(2\pi F_S \tau)$$

$$A_{X_{k,N}} \triangleq \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \cos(\varphi_k - \varphi_{k-N})$$

$$B_{X_{k,N}} \triangleq \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \sin(\varphi_k - \varphi_{k-N})$$



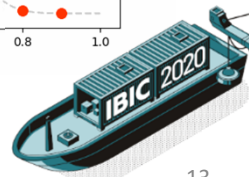
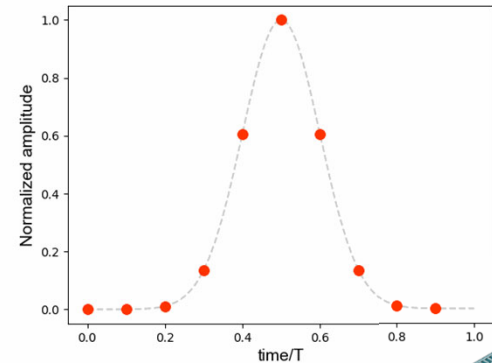
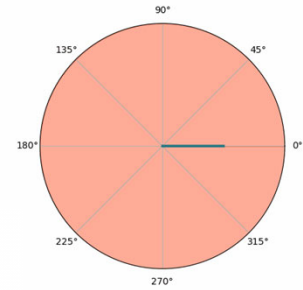
The estimation error

$$\epsilon(X_k, F_S, \tau) \triangleq \widehat{P}_T - P_T$$

$$\epsilon(X_k, F_S, \tau) = A_{X_{k,N}} \cdot 2 \cos(2\pi F_S \tau) + B_{X_{k,N}} \cdot 2 \sin(2\pi F_S \tau)$$

$$\text{Hyp: } \tau = U\left[0, \frac{1}{F_S}\right]$$

- $\mu_\epsilon = 0$;
- $\sigma_\epsilon^2 = 2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right)$



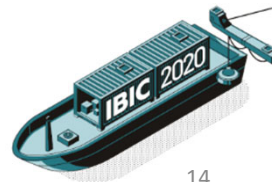
Limited Sampling Resolution

The introduction of the converter noise v

- We now take into account the limited resolution of the ADC
- How does it propagate in the estimator?

$$\widehat{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} \hat{x}_n^2 \quad \longrightarrow \quad \overline{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2$$

- Zero-mean Gaussian variable, with σ_v^2 variance



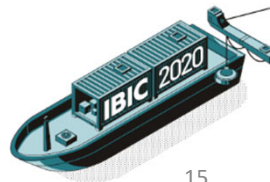
Limited Sampling Resolution

The introduction of the converter noise v

- We now take into account the limited resolution of the ADC
- How does it propagate in the estimator?

$$\overline{P_T} = \widehat{P_T} + \frac{1}{N} \sum_{n=0}^{N-1} v^2 + \frac{1}{N} \sum_{n=0}^{N-1} 2\hat{x}_n v_n \rightarrow \eta \triangleq \overline{P_T} - \widehat{P_T}$$

- Zero-mean Gaussian variable, with σ_v^2 variance



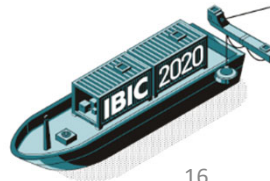
Limited Sampling Resolution

The introduction of the converter noise v

$$\eta \triangleq \overline{P_T} - \widehat{P_T}$$

$$\mu_\eta = \sigma_v^2$$

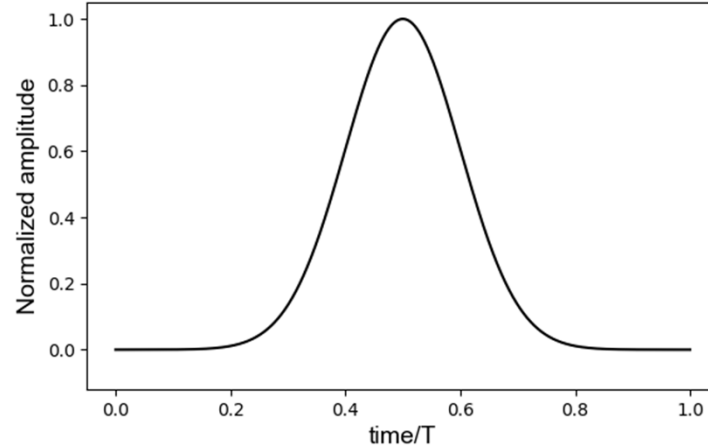
$$\sigma_\eta^2 = \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}$$



A combined SNR expression

Total error

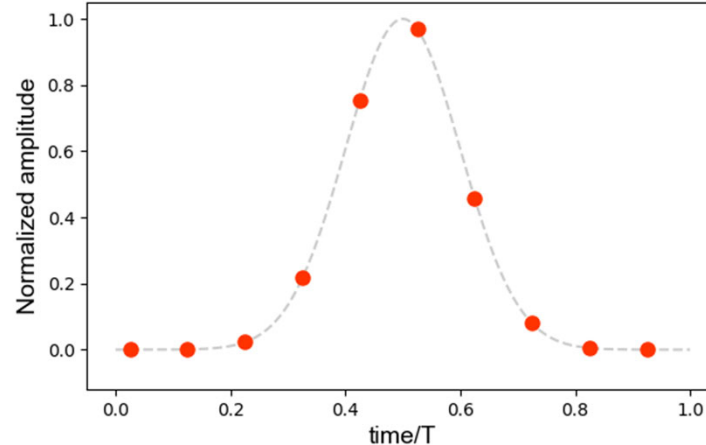
$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T$$



A combined SNR expression

Total error

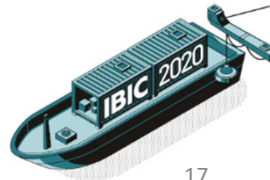
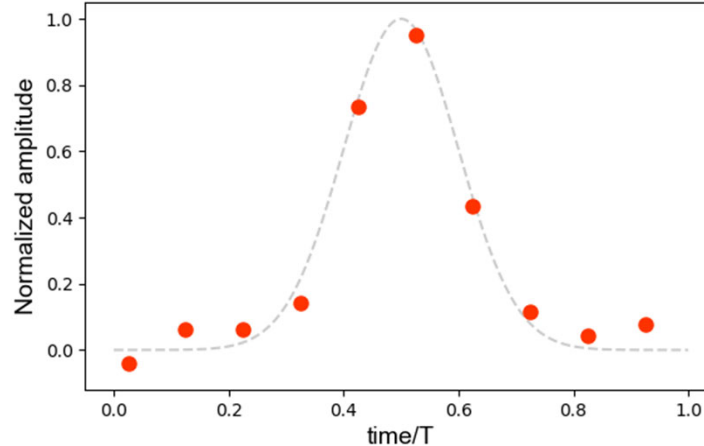
$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_S, \tau)$$



A combined SNR expression

Total error

$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_S, \tau) + \eta(P_T, \sigma_v^2, F_S)$$



A combined SNR expression

Total error

$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_S, \tau) + \eta(P_T, \sigma_v^2, F_S)$$

- Mean value:

$$\sigma_v^2$$

- Variance:

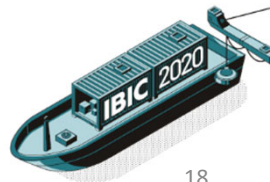
$$2 \left((A_{X_k, N})^2 + (B_{X_k, N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}$$



A combined SNR expression

SNR expression of the averaged power measurement

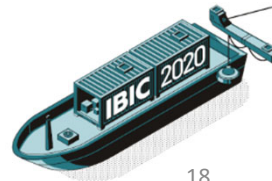
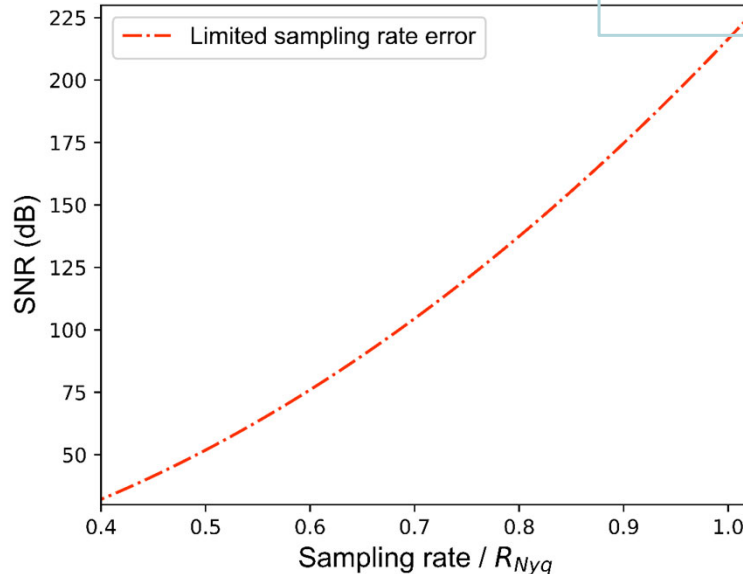
$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$



A combined SNR expression

SNR expression of the averaged power measurement

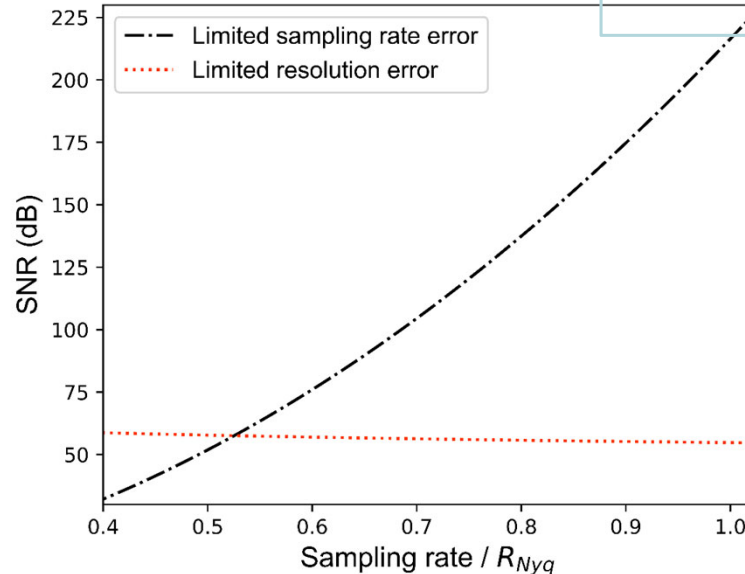
$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$



A combined SNR expression

SNR expression of the averaged power measurement

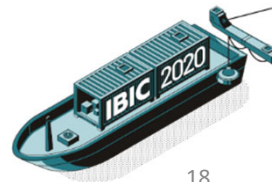
$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$



- ADC resolution in function of the sampling rate

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

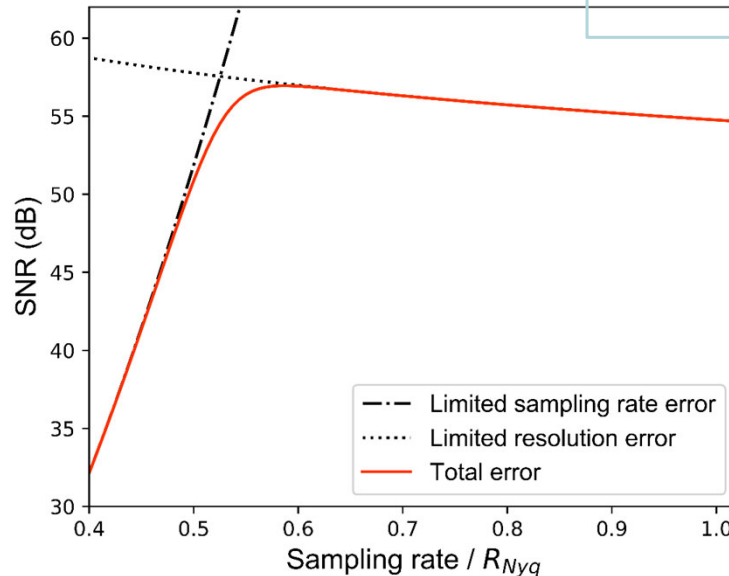
$$P = 2^{ENOB} \cdot f_s$$



A combined SNR expression

SNR expression of the averaged power measurement

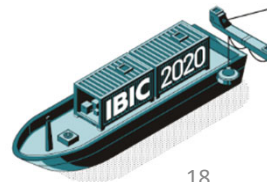
$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$



- ADC resolution in function of the sampling rate

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

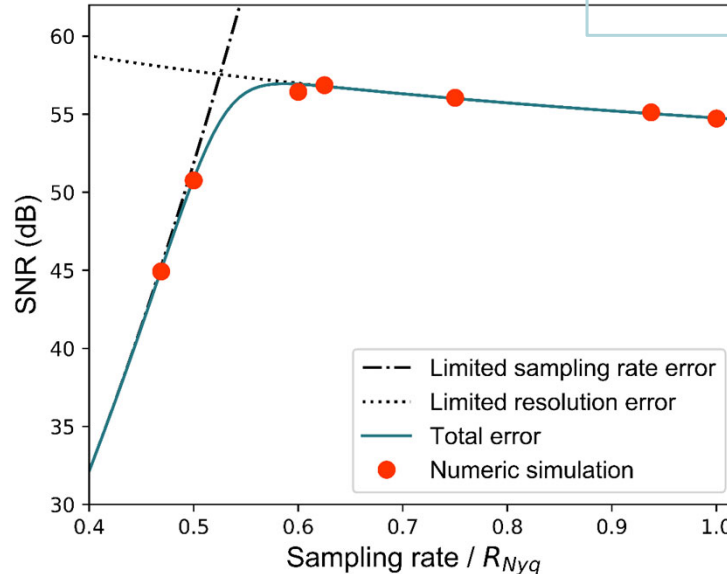
$$P = 2^{ENOB} \cdot f_s$$



A combined SNR expression

SNR expression of the averaged power measurement

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

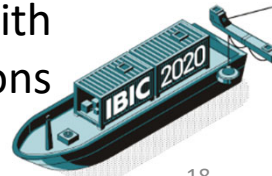


- ADC resolution in function of the sampling rate

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$

- Results verified with numeric simulations





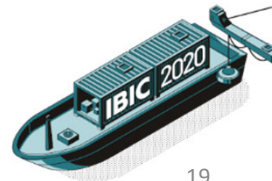
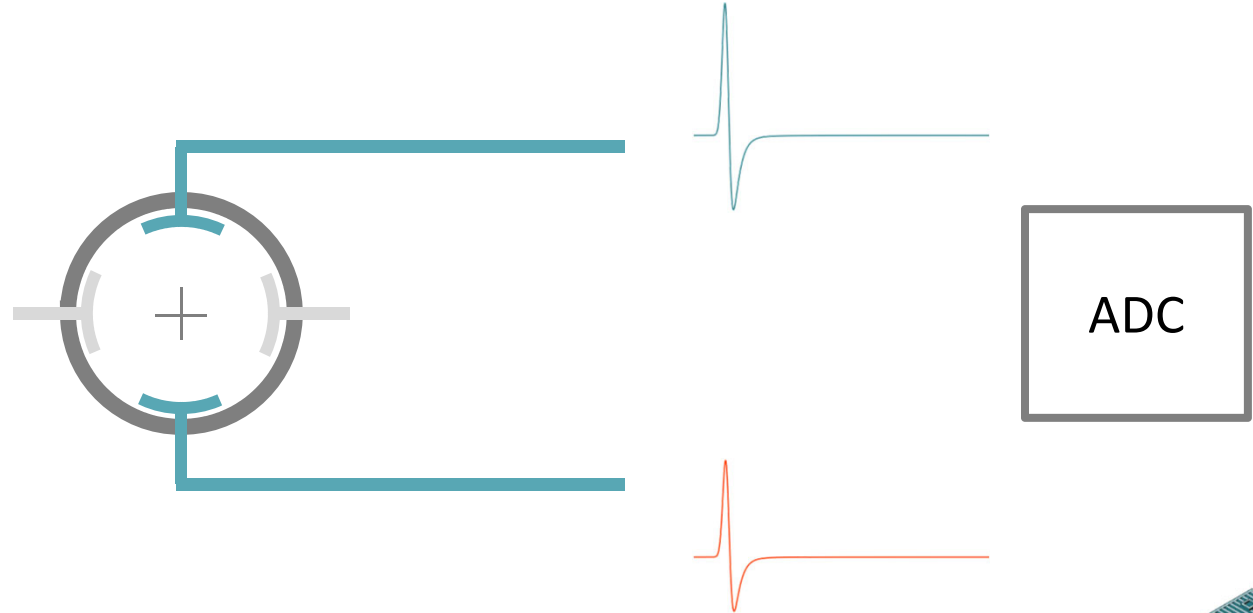
Application example

*A proposed new bunch-by-bunch
read-out system for the LHC BPM*



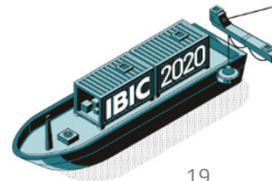
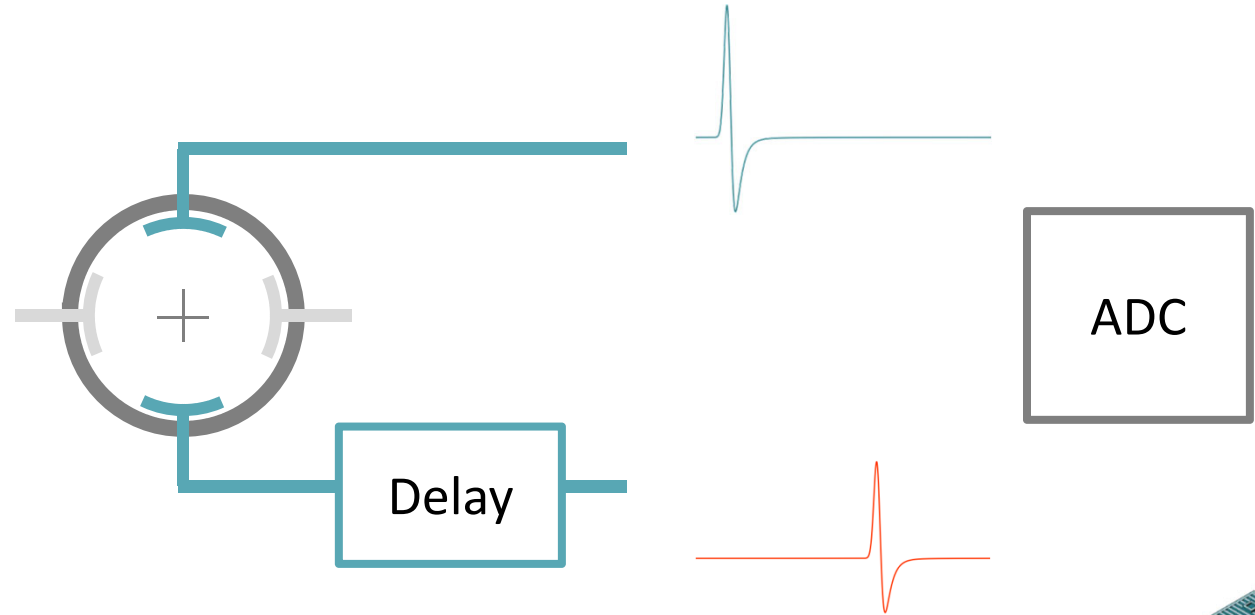
A possible architecture

Before the ADC: electrodes combination



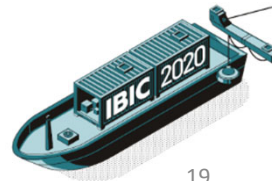
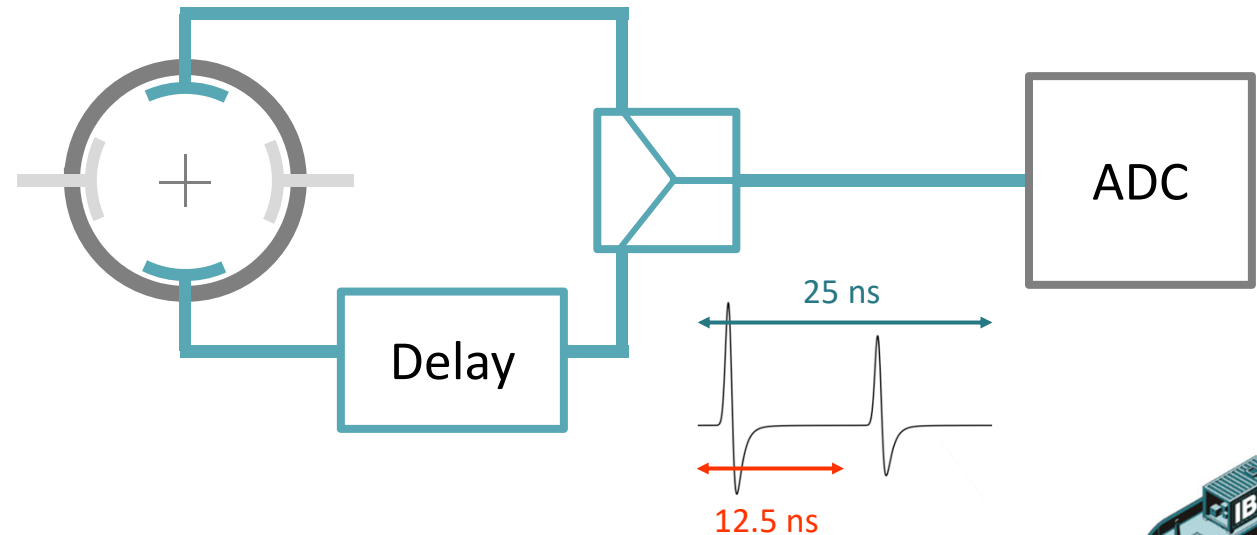
A possible architecture

Before the ADC: electrodes combination



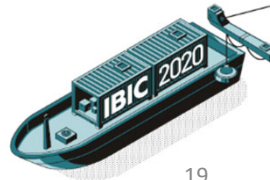
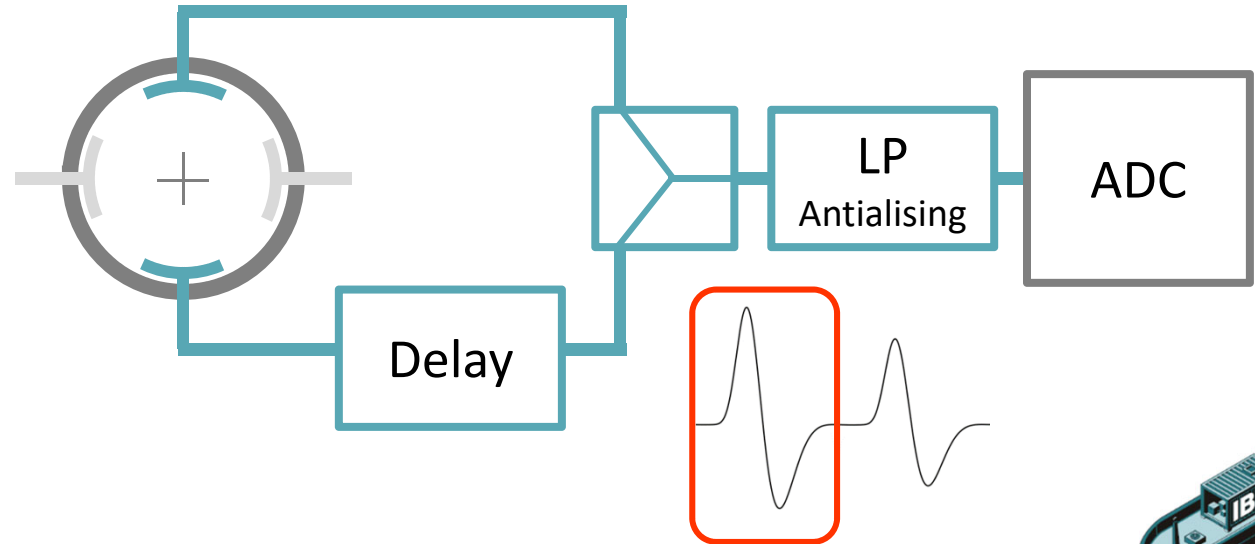
A possible architecture

Before the ADC: electrodes combination



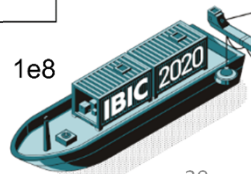
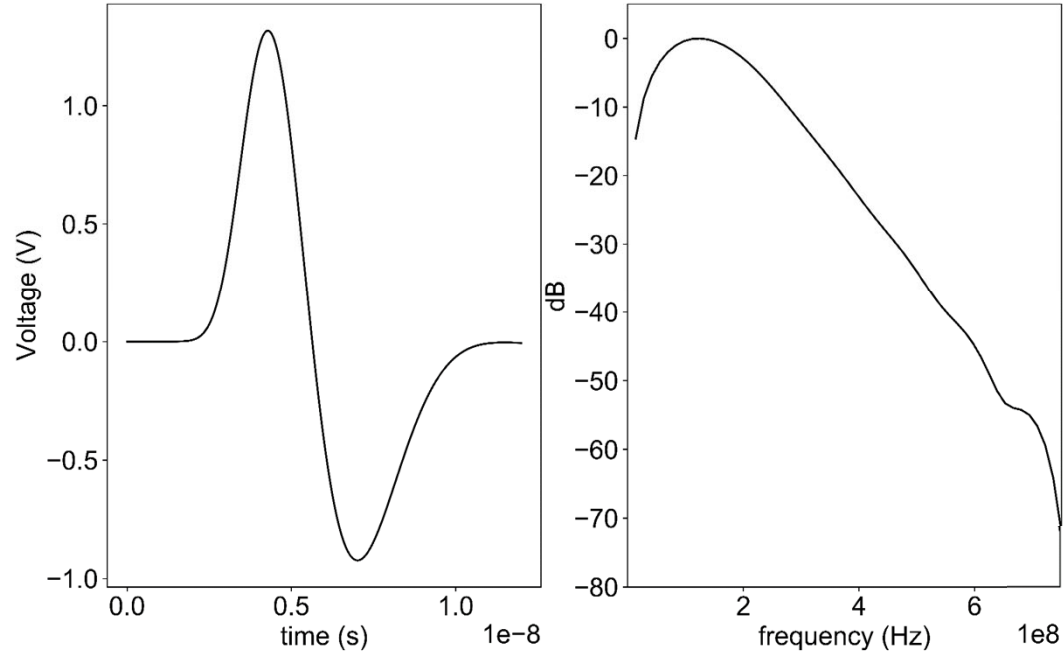
A possible architecture

Before the ADC: signal “stretching” with LP filter



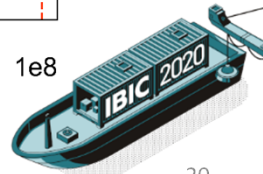
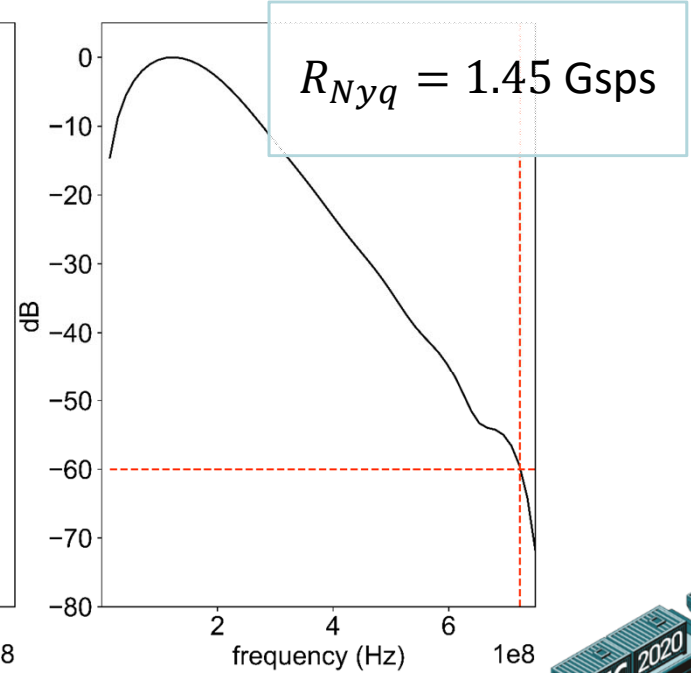
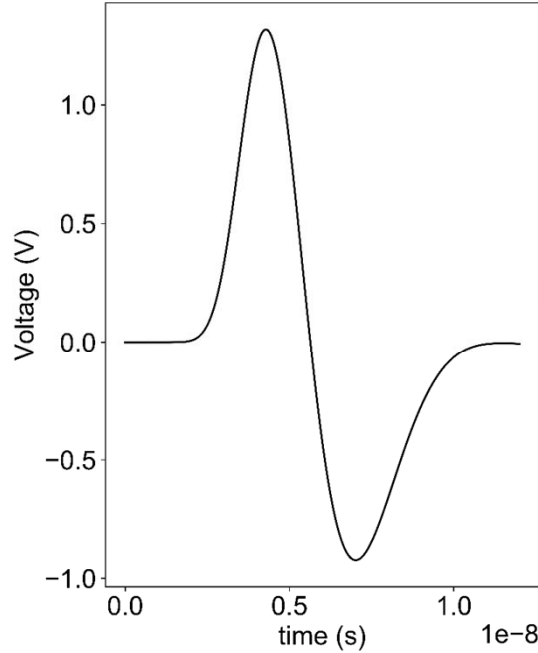
Single bunch pulse signal

- LP Filter
 - 200 MHz
 - N=4
- Antialiasing
 - 600 MHz
 - N=8



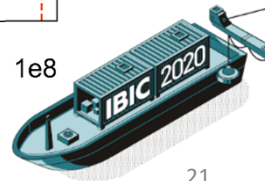
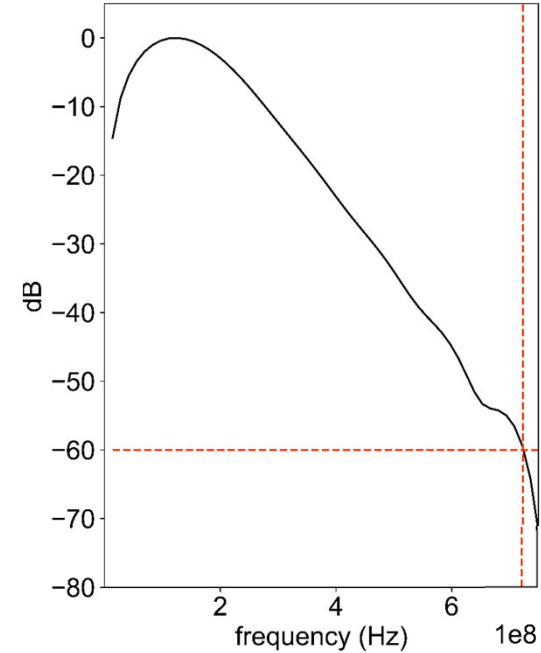
Single bunch pulse signal

- LP Filter
 - 200 MHz
 - N=4
- Antialiasing
 - 600 MHz
 - N=8



Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

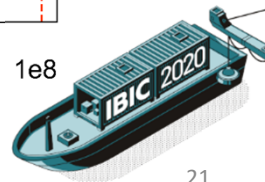
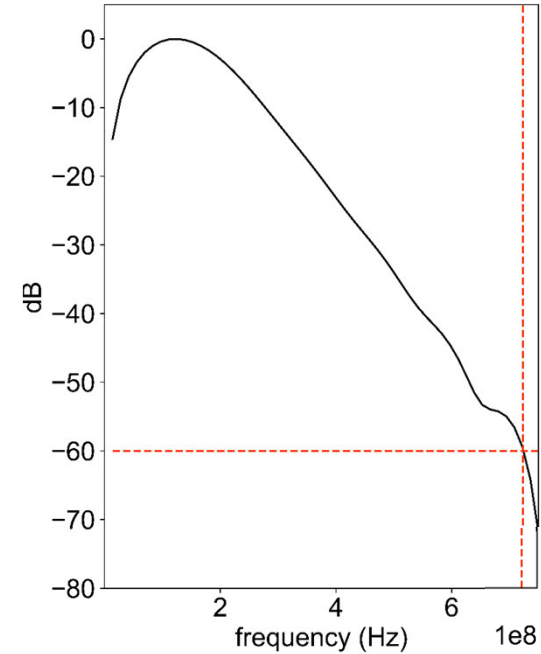


Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$

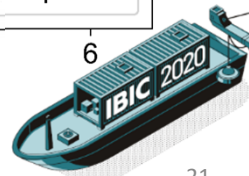
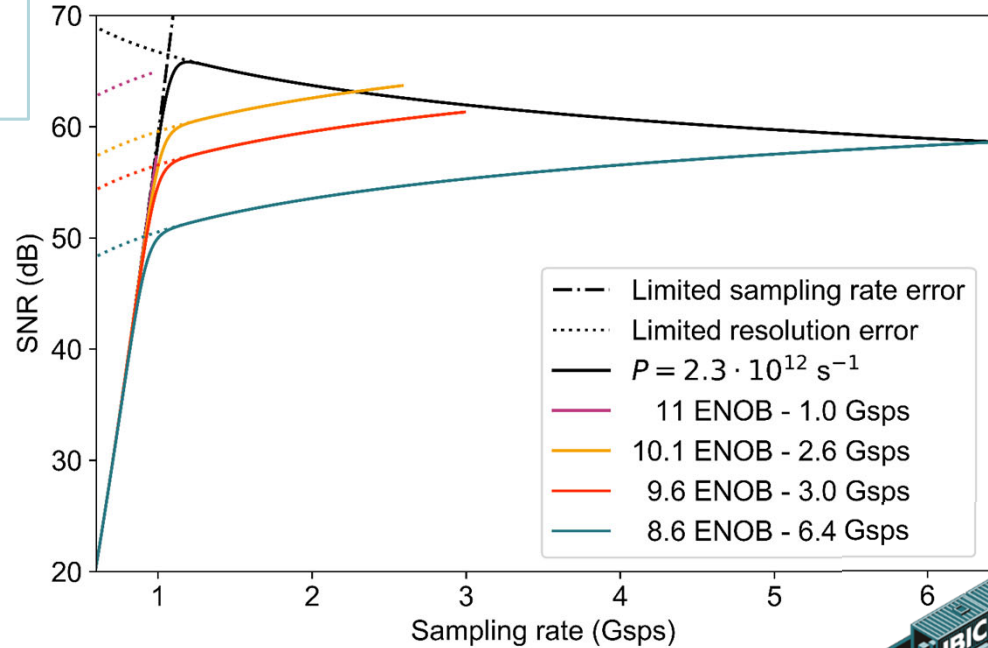


Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_k, N})^2 + (B_{X_k, N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

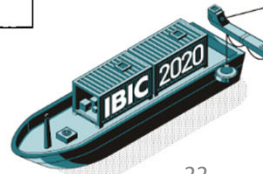
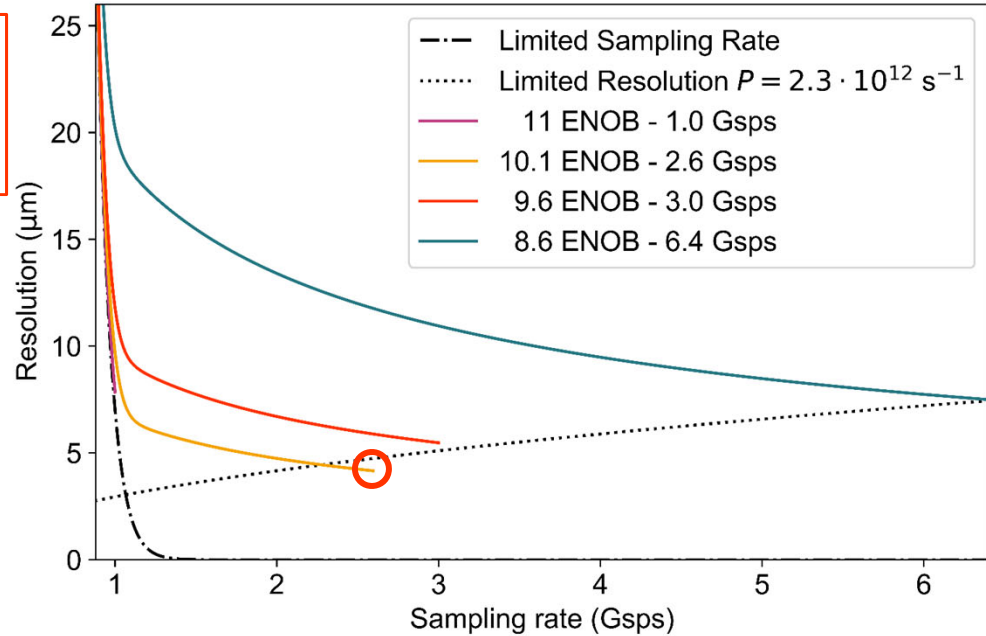
$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$



Position Resolution Analysis

$$\partial y \approx \boxed{\frac{k_{mm}}{dB}} \cdot 20 \log_{10} \left(\sqrt{1 + \frac{\sqrt{\sigma_\epsilon^2 + \sigma_\eta^2}}{P_T}} \right)$$

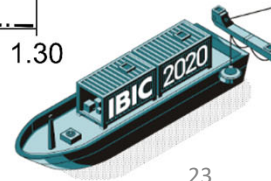
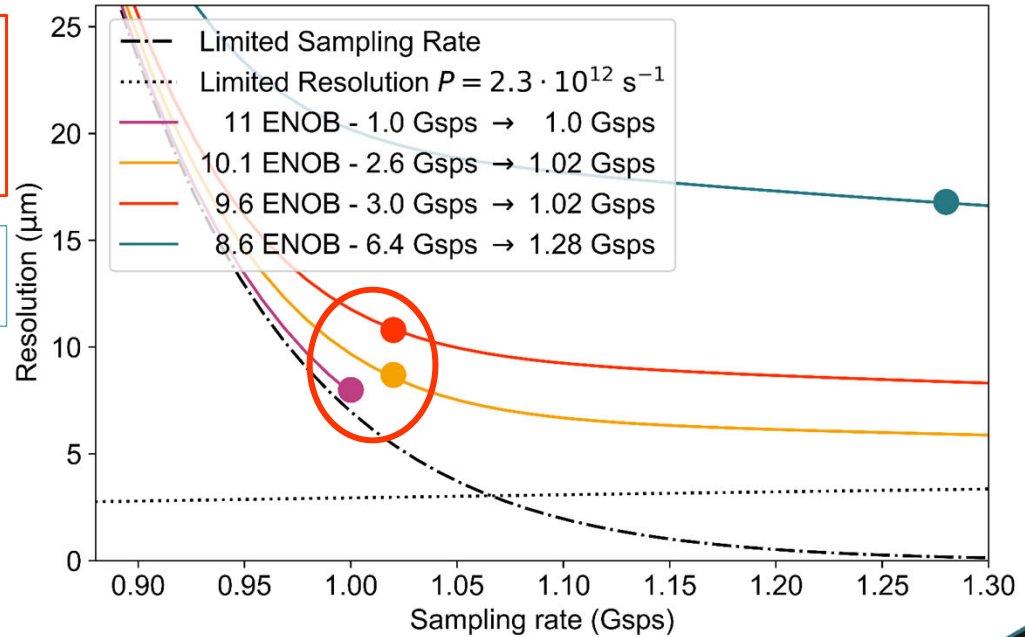


Position Resolution Analysis

With transmission bandwidth limit

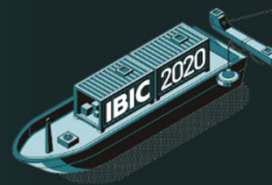
$$\partial y \approx \frac{k_{mm}}{dB} \cdot 20 \log_{10} \left(\sqrt{1 + \frac{\sqrt{\sigma_\epsilon^2 + \sigma_\eta^2}}{P_T}} \right)$$

2 serial links x 10.24 Gbps





Summary



- **Direct digitization** based systems are of growing interest for Beam Instrumentation applications.
- ADC state-of-the-art imposes a **trade-off** between sampling rate and resolution.
- It is possible to **estimate the error** introduced in the energy estimation of a digitized pulse as a function of the sampling rate and resolution.
- This analytic tool can facilitate the **analysis** of the performance of a system, but also assist in the **design** of a new system, especially in the selection of the ADC.

