LENS CALIBRATION FOR BEAM SIZE MONITORS AT THOMX Scott David Williams, Geoffrey N. Taylor (The University of Melbourne), Iryna Chaikovska, Nicolas Delerue, Viacheslav Kubytskyi, Hugues Monard, Alexandre Moutardier (Université Paris-Saclay, CNRS/IN2P3, IJCLab,

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Introduction

- Beam size meaurement is an important and necessary diagnostic feature of the ThomX injection line and beam dumps
- At each diagnostic station along the beamline a YAG screen, USAF1951 microscope resolution target, and blank screen are mounted on rails driven by a stepper motor, and can be driven into or out of the beam position. Digital cameras with Tamron telephoto lenses are mounted to observe the intended beam trajectory.

Pictures



Nomenclature

• To aid discussion, the following terms are used: **USAF1951 test chart** The entire glass slide **Target** A set of groups in a spiraling shape. There are nine targets on each of our USAF1951 test charts Group A set of six elements of different size. From largest to smallest in a group, the sizes differ by a factor $2^{-\frac{1}{6}}$

- Our work is to present methods for the automatic calibration of the camera and optical systems that observe the YAG screens
- We also will present work to repurpose readily available Canon EF mount autofocus capable lenses as a novel method for remotely controlled optical focusing system
- We note that our work makes heavy use of the OpenCV library |1|

Region Of Interest (ROI) detection

- First step is to isolate areas featuring only one target
- We use a method similar to and influenced by [2] based around morphological transformations
- The process is as follows:
- 1. Black hat transform used to highlight dark structures smaller than a given size
- 2. Image thresholded with combination of Otsu and distance map threshold
- 3. Opening and closing operations used to ensure rounded regular shapes, containing whole ROI plus border

Fig. 1: Image to be analysed

Overall algorithm flow

B. hat image







Find and filter



Element A pair of two bar patterns of same size but differing in rotation by 90 degrees **Bar pattern** A set of three bars of the same orientation • Other terms may be used elsewhere

• An example image may be seen in figure 1

Novel remote controlled optical system using readily available **Canon EF mount lenses**

- Canon EF mount lenses are readily available, and when attached to a camera body are able to precisely autofocus
- By repurposing the lens motor control, we are able to control the focus of the lens
- We can then use software autofocus algorithms (such as [3]) and lens motor control to focus images automatically



4. We then search for complete blobs with connected components algorithm, and filter based on area, dimesional raio and other criteria

Software - process and testing

- To calibrate the cameras we must identify each target visible, and the largest and smallest elements of each target
- We first identify regions of interest that potentially contain at most one target
- We then further analyse these regions, identifying the visiable USAF1951 groups and elements
- To assess the stability of the software, we tracked elements inside the image using the software as we moved the target in constant increments - see 5

ROI analysis

Fig. 2: ROI detection through morphological operations



Fig. 3: Binarised image, and image showing filtered connected components





Fig. 4: After clustering similarly sized and located horizontally or vertically

oriented elements

Normed successive distance / Pic. number diff of largest vert. element

Fig. 6:

- In figure 6 we present results of scanning an image using an image sharpness score from [3]. The large peak corresponds to focusing on the USAF1951 microscope chart, the secondary peak corresponds to focusing on the diagnostic station porthole.
- We plan to use image masks to ensure we only focus on the USAF1951 chart

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- ROI is binarised and potentially Fourier filtered
- Orientation of image estimated by looking at histogram/KDE of gradient directions in image; due to regular rectangular shapes, orientation has a clear peak
- Individual shapes are then found by connected components algorith, their size measured, and the filtered based on area, dimensional ratio, and closeness to image orientation
- Individual shapes are then clustered based on position, size, and orientation. Each cluster corresponds to a USAF1951 element
- The smallest element seen is used to measure the optical system resolution for this ROI, and the largest used to estimate the transformation from pixel coordinates to laboratory coordinates.



Fig. 5: Test of software stability - tracking largest vertical element

References

[1] G. Bradski. "The OpenCV Library". In: Dr. Dobb's Journal of Software Tools (2000).

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