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Longitudinal Bunch-by-Bunch Feedback Systems for SuperKEKB LER

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Abstract

Longitudinal bunch-by-bunch feedback systems to suppress coupled bunch instabilities with minimum bunch spacing of 2 ns have been constructed in SuperKEKB LER. Through the grow-damp and excite-damp experiments with several filling patterns and the transient-domain analysis of unstable modes, the behaviors of possible impedance sources have been evaluated. The measured performance of the system, together with the performance of the related systems such as slow phase feedback to the reference RF clock are reported.

Introduction		HER LER	Longitudinal Co
Target of SuperKEKB collider:	Energy (GeV)	7 4	Observed low situation (CB)
Design target : Realize x40 luminosity of KEKB	Maximum beam current (achieved mA)	3016	Unexpected low thresh
with 1/20 of IP vertical beam size	Max. bunch current (achieved, mA)	1 1.5	 Threshold current stron
X2 of Beam currents Phase-1: without IP	Bunch length (mm)	5 6	pattern
Phase-2 : with IP, Belle II detector and final focus system,	RF frequency (MHz)	508.886	 150 mA with by 2 fill modes around -330
without innermost detectors (SVD, Pixel)	Harmonic number	5120	 800 mA with by 3.0
Phase-3: Almost full set of detectors: Luminosity productio	n Typical synchrotron tune Momentum compaction factor	0.028 0.024	Another set of unstable
Fundamental modes (-1, -2,): Mode-by-mode FB in LLRF	Longitudinal radiation damping time (ms)	29 23	appeared with depende
Cavity induced instability : Anticipated growth time was	Natural horizontal emittance (nm)	4.6 3.2	D2H4.
slow: 21 ms@3.6A(LER) Observed unexpected L-CBI during Phase-1 and 2 with mu	Peak luminosity (achieved, cm ⁻² s ⁻¹)	1.23x10 ³⁴	
lower beam current.	Number of longitudinal kicker	0 1	6.00.00 1.00.00
			1340.000 1340.000 1340.000
Longitudinal bunch-by-bunch feedback system			
		A A AN AN AN AN AN	can the can the can the fact the
HPM (Description) Break			Change of longitudinal unstable (left) and half gap=9.5mm (right
		M	with the narrower gap.
Source So			
SuperKEKB Longitudinal Bunch Feedback System		13	Longitudinal Fe
			Transient-domain analysi
		C AMER	Excite(pos. FB)->FB OFF(r
			C.42
		THE P	
Digital QPSK modulator (2 ½ * RF carrier)	Colby switch delay (10ps step, max 2)	ns or 10ns)	
			177-182 8418
		The second in	B
		100 m	Transmission Annual State
			di d
			n n
Longitudinal Feedback Kicker (DA	FNE type over-dampe	ed cavity)	1.7+-+= ====
ANSYS HFSS simulation	GdfidL simulation		
		<u></u>	of Annual to the second of
			-
	4 12"		las las las
Quality factor ~5 (3dB bandwidth ~ 240MHz)	20 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0 .100,0we	
Calculation of Rsh 1) Calculate the longitudinal E-field		1,00	Example excite-free experiment of
$E_{z}(z) = \sqrt{E_{z}^{2}(z, \Phi = 0^{\circ}) + E_{z}^{2}(z, \Phi = 90^{\circ})}$			Transient-domain analysi
$\varphi_z(z) = \tan^{-1} \left(\frac{E_z(z, \Phi = 90^\circ)}{E_z(z, \Phi = 0^\circ)} \right)$			Excite(pos. FB)->Neg. FB
($E_c(z, \Psi = 0)$) 2) Calculate effect of transit time	10 52 64 68 68 1 12 14 16 Finquency(SH2) Finquency(SH2)	-1,000 - 5 10 15 20 Time(rd)	A
$\operatorname{Re}(V_{g}(\omega)) = \int_{z=1}^{z} E_{z}(z) \cos(\omega z / c - \phi_{z}(z)) dz, \stackrel{\scriptscriptstyle 2}{=} 2^{20}$	Input / Output ports	2/2	
$Im(V(\alpha)) = \int_{L_2}^{L_2} E(z) \sin(\alpha z / c - \phi(z)) dz$	Center frequency	1.145 GHz	
$\frac{-L/2}{-L/2}$ 3) Integrate Real part and Imaginary part and	3dB bandwidth Shut impedance	240 MHz 1 68 kQ/cavity	Rentife Contife
Int(Re)=10.2, Int(Im)=39.6, in this case (1) Reh = 1/0.2, Int(Im)=39.6, in this case (1) Reh = 1/0.2, Int(Im)=39.6, in this case Distance(rrm)	Longitudinal loss factor	0.406 V/pC /cavity	2
4) nsii = V··2/2µ, =>nsii 1.00x52	Transverse kick factor 2.	.06 V/pC /m / cavity	0.8
	Length (flange-to-flange)	0.44 m	i 0.6
Commissioning of the Longitudinal	Bunch Ecodhack Sys	Lom	20 gate
1) Tuned the timing and phase of the bunch phase detector, ADC timing of the	e iGp12.		
2) The fine DAC timing within 2 ns of the iGp12 has been adjusted to synchro	nize the DAC output to the switch timing of the d	igital QPSK.	
Fine sweep of feedback kicker timing	Feedback phase, gain, etc		0.1
reequack loop open, single bunch (pilot bunch) excitation (iGp12 FG) around fs.	Close the feedback loop to find the negative fee by changing the feedback phase of FIR filter in t	dback phase he iGp12.	0 0.2 0.4 0.6 0.8 l Longitudinal feedback gain
* LK3 only, 10ps /step	The fine tuning, including the feedback gain (shi iGp12) has been performed using heam with ex-	ft gain in the cite-damp (or	Transient-domain analysis
* FFT Amplitude response of the <i>fs</i> of the target bunch	grow-damp) scheme.		Excite(pos. FB)->Neg. FB C
Peak (blue) and RMS (yellow)	Displa Confident Generator Distance Generator Dista	and the second second	
Peak : 980 ps			2,00,000 2,00,000 1,00,000
		and an a	Lato.com
feedback signal appears roughly	1 mm	THE REAL PROPERTY AND INC.	Source Charles Charles Charles
1ns before the beam induced signal	FIR filter (down-sample 3)	sient beam loading and	200.000 0 2,000 4,000
	Shift gain=3 RF p	ohase servo (software)	Mode ID
$ \begin{array}{c} & & & \\ & & & \\ \hline \\ \hline$	to 4 FB Synchrotron oscillation of injected bunch	ANT (20112) SOUICE TOP	C
LK4 sweep, with LK3=980ps			Summary
a reak. 11/ups			We have commission
20			SuperKEKB LER. The
0 500 1,000 1,500 2,000			with the feedback g
Tune other kickers, LK1 and LK2 with LK3. to find the hest delay.	Marcine and Constraints of the second	MI MI MI A	operation was not r
the first dealers, and the with this, to find the best delay.	LFB OFF	LFB ON	system worked very

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- upled-Bunch Instability during Phase-1 and Phase-2 Phase-3 operation old beam current No spontaneous CBI (other than fundamental modes) igly depends on the filling has been observed up to: 500 mA with by 2 filling pattern ling pattern, unstable 575 mA with by 3 filling pattern 042623627 5 filling pattern modes around mode -470 ence of the gap width of the arest to interaction point Unstable modes with by 2 filling pattern, total beam current tof 500 mA LFB OFF (Horizontal: Mode ID, Vertical: Amplitude, Depth, Time evolution from 0ms to 22ms) node with half gap=13mm Mode around -470 vanisher Only mode 0(noise?), -1 and -2 has appeared. edback Experiments at Phase-3 5(1) Transient-domain analysis(4) diation damping) Effect of gap width of D2H4 with Excite-damp Example of mode pattern of by 2 filling pattern with several half gap of D2H4 Example of mode pattern of by 3 filling pattern with several half gap of D2H4 13mm 13mn 2 filling pattern, 500 mA total rowth rate (by pos. FB) ~0.5 ms tted growth rate (top), amping rate (medium), ifference (growth rate – damping ite, bottom) 10.5mm 7mm by 3 filling pattern ON(FB gain change) No obvious dependences on the gap of D2H4 has seen During normal operation (Luminosity runs) and special filling pattern with large bunch current. 1.5mA/bunch at ECI experiment Kept LFB and phase servo loop for 2GHz master for bunch feedback system ON. Until the maximum beam current of 830 mA on Change of the feedback damping rate with the longitudinal feedback gain Phase-3 operation, no indication of longitudinal CBI which could not be suppressed by the LFB. Clearly the damping rate During the e-cloud study (ECI experiment) with much shows linear dependence with feedback gain larger bunch current, shorter length of bunch train, though we have observed not so fast longitudinal CBI other than the fundamental modes (-1, -2), it was completely suppressed with the LFB. The recapture of the feedback after grow-damp experiment (10 ms FB-OFF) was not difficult where at larger amplitude (3) the final feedback amplifiers were already saturated
 - region).
 No significant difficulties in the LFB hardware has been found during operation. The temperatures of the power components (such as feedthroughs, dummy loads, cables, high-power components) were well controlled by the external water cooling.

with the current feedback gain (Bang-bang damping

We have commissioned the longitudinal bunch-by-bunch feedback system in SuperKEKB LER. The damping rates achieved have been confirmed to scale linearly with the feedback gain. The longitudinal CBI observed during Phase-1 and Phase-2 operation was not reproduced in Phase-3 tests to date, but in all these tests the LFB system worked very well to stabilize the longitudinal motion during the colliding operation and the machine developments.

FB damping time ~2ms

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