

INTEGRATION OF EtherCAT HARDWARE INTO THE EPICS CONTROL SYSTEM AT iThemba LABS



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Introduction

iThemba LABS has adopted EtherCAT as its communication bus standard as of 2015. Building on prior community development, an open-source software stack has been developed. A variety of EtherCAT hardware have been successfully integrated into the EPICS control system.

Control at iThemba LABS

1980s – Mini computers and CAMAC

1990s – OS/2 and SABUS

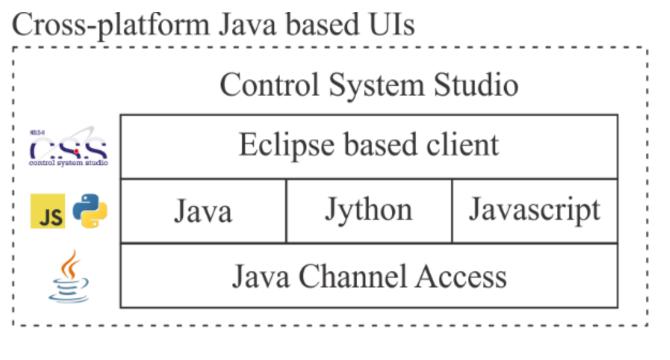
2000s – Move to EPICS

2015 – Adoption of EtherCAT

Migration to EtherCAT

EtherCAT is an open real-time Ethernet fieldbus developed by Beckhoff (Verl, Germany) and maintained by the EtherCAT Technology Group (ETG) . iThemba LABS adopted EtherCAT as its new industrial communication bus due to its high-speed performance, existing integration with EPICS and availability of off-the-shelf hardware.

Software Stack



Control System Studio client interfaces.

EPICS

EPICS IOCs

Comparison of EtherCAT Bus Scanner

Ether Lab EtherCAT Master

Linux Kernel and Device Drivers

EtherCAT

Server stack built on open EtherLab master and a bus scanner and Asyn drivers developed by Diamond Light Source UK.

Hardware Integration



EtherCAT terminals

- 25 year hardware support
- Wide selection of I/O cards
- Ease of integration and stability with open master

EtherCAT slave I/O interfaced into EPICS at iThemba LABS:

- Analogue I/O: ± 10 V and 0 to 20 mA; 12 to 24-bit
- Digital I/O: 5 to 24 V, potential free and negative switching I/O
- Temperature: thermocouples and RTDs
- Communication: RS232, RS485 and RS422
- Motion: Servo, DC and Stepper motors
- Position: pots, absolute and incremental encoders

System Installations



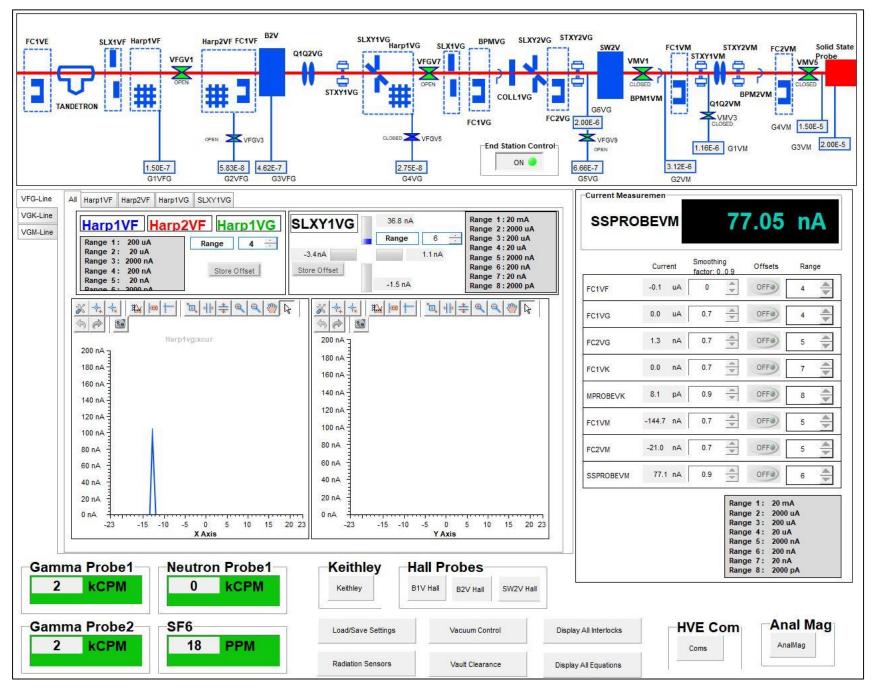
19-inch rack mount enclosures



Custom Unistrut mount enclosures



Custom 19-inch rack mount enclosures



CS-Studio user interfaces



React Automation Studio user interfaces

MOTION CONTROL -SULT IX ENGINEERING CONTROL ADVANCED SETTINGS Material Current 620 mA 16.5 mm 16.4 mm 16.4 mm 16.2 mm 16.5 mm 16.6 mm 16.6 mm 16.7 mm 16.7 mm 16.7 mm 16.8 mm 16.8 mm 16.8 mm 16.9 mm 16.8 mm 16.9 mm 16.8 mm 16.9 mm 16.9

Conclusions

Building on prior open-source development, a stable and mature EtherCAT software stack has been developed. The move to off-the-shelf hardware has mitigated obsolescence risk, shortened product development time and increased product life cycles. This process has also expedited the migration of our control system onto the EPICS platform.