Effects of the Third Order Transfer Maps and Solenoid on a High Brightness Beam

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Abstract

We present a sketch of the formulation for obtaining Lie algebraic transfer maps for the solenoid through third order and its effect on the beam of charged particles. We discuss simulation results showing effects of solenoids on the laser driven high brightness photoelectrons for the proposed alternate injection system for Brookhaven Accelerator Test Facility (ATF) [1].

I. INTRODUCTION

A brief overview of a Lie algebraic formulation is given in section II. Using Hamiltonian dynamics we describe the motion of a charged particle through electromagnetic fields. With Lie transformations we obtain the maps and trajectories for a particle along the beamline in a magnetic field (e.g. of solenoid). We discuss the transfer maps for magnetic elements and solenoid through third order and their effects on the beam of charged particles. In section III we discuss the effects of the solenoids used in the design of the proposed alternate injection system for the Brookhaven Accelerator Test Facility (ATF) [1].

II. FORMALISM

In this section we present an overview of the formalism used to obtain the trajectories of a particle along the beamline via Lie transformation. Using Maxwell's equations, axi-symmetrical fields, and the relativistic equations for the charged particles motion along the beamline we can obtain the magnetic field components everywhere (e.g. of a solenoid given the on axis longitudinal component of the field \( B_z = (B_0, 0, 0) \)) and its effect on the particles motion.

We express the canonical equations in 2n-Dimensional phase space (e.g. 6 Dim., in our calculation), as

\[
\frac{d\psi_i}{dt} = [\psi_i, H], \quad i = 1, 2, \ldots, 2n
\]

and in terms of the Lie transformations as

\[
\frac{d\psi_i}{dt} = - : H : \psi_i, \quad i = 1, 2, \ldots, 2n
\]

Where the Lie operator \( (: H :) \) is generated by the Hamiltonian \( (H) \), and Lie transformation,

\[
M = e^{-tH},
\]

could generate the solution to Eq. (2) as

\[
\psi_i = M \psi_i (0)
\]

where \( \psi_i \) is the value of \( \psi_i(t) \) at \( t > 0 \) and \( \psi_i(0) \) is the initial trajectory. The interest is to find solutions to equations of motion which differ slightly from the reference orbit (e.g. the design orbit of an accelerator beamline. Design orbit for solenoid is along z-axis). Thus, we choose the canonical variables, from the values for the reference trajectory (for small deviations) and Taylor expand the Hamiltonian \( (H) \) about the design trajectory:

\[
H = H_2 + H_3 + \ldots
\]

Where \( H_n \) is a homogeneous polynomial of degree \( n \) in the canonical variables. After transformations to the normalized dimensionless variables, we obtain the effective Hamiltonian \( H_{\text{New}} \), expressed as

\[
H_{\text{New}} = F_2 + F_3 + F_4 + \ldots
\]

Thus the particle trajectory \( \psi = (X, P_X, Y, P_Y, \tau, P_\tau) \) through a beamline element of length \( L \) can be described by

\[
\psi_i = - : H_{\text{New}} : \psi_i, \quad i = 1, 2, \ldots, 2n
\]

The exact symplectic map that generates the particle trajectory through that element is,

\[
M = e^{-L \cdot H_{\text{New}}},
\]

where, \( M \) describes the particle behavior through the element of length \( L \). Using the factorization and expanding \( H_{\text{New}} \) as in Eq. (6), we obtain

\[
M = e^{-t \cdot H_{\text{New}}} = e^{f_2 \cdot e^{f_3 \cdot e^{f_4 \cdot \ldots}}}
\]

(for a map through 3rd order we need to include terms of \( f_2, f_3, \) and \( f_4 \)). Where \( f_2 = LF_2, f_3 = LF_3, f_4 = LF_4, \) etc.

To illustrate the above formalism, consider the evolution of the motion of particles in an external electromagnetic field described by the Hamiltonian

\[
H = \sqrt{m^2c^4 + e^2 \left[(p_x - qAx)^2 + (p_y - qAy)^2 + (p_z - qAz)^2\right]}
\]

\[
+ e\phi(x, y, z; t)
\]

where \( m \) and \( q \) are the rest mass and charge of the particle, \( A \) and \( \phi \) are the vector and scalar potentials such that \( \vec{B} = \nabla \times \vec{A}, \vec{E} = -\nabla \phi - \nabla A/\partial t. \)
Making a canonical transformation from $H$ to $H_1$ and changing the independent variable from time $t$ to $z$ (for convenience) for a particle in magnetic field (e.g. of solenoid) results in:

$$p_z = \sqrt{(p_x - qAx)^2 + (p_y - qAy)^2 + p^2/c^2 - m^2c^2}^{1/2}.$$  

(11)

Where $H = -p_t$, $H_1 = -p_z$ and $t = (z/v_0) = z$ the time as a function of $z$. We next make a canonical transformation from $H_1$ to $H_{\text{New}}$, with a dimensionles deviation variables (for convenience), $X = x/l$, $Y = y/l$, $\tau = c/l (t - z/v_0)$, $p_x = p_x/\tau_0$, $p_y = p_y/\tau_0$, $p_z = (p_t - p_{0t})/\tau_0c$, where $l$ is a length scale (taken as 1 m in our analysis), with $P = \vec{P}_x + \vec{P}_y$ and $Q = \vec{X} + \vec{Y}$ defined as two dimensional vectors [3]. $p_0$ and $p_{0t}$ are momentum and energy scales. Where $p_0$ is the design momentum, $v_0$, is the velocity on the design orbit and $p_{0t}$ is value of $p_t$ on the design orbit ($p_{0t} = \sqrt{m^2c^4 + p_{0c}^2}$) (reminding that design orbit for the solenoid is along the $z$-axis).

Thus, expanding the new Hamiltonian (eq.(6)) leads to:

$$F_2 = \frac{P^2}{2(2\beta^2)^2} - \frac{1}{2} B_0 \left( \vec{Q} \times \vec{P} \right) : \dot{z}$$

$$+ \frac{1}{8} B_0^2 Q^2 + \frac{P^2}{2}$$

$$F_3 = \frac{P^2}{2(2\beta^2)^2} - \frac{P_t}{2\beta} B_0 \left( \vec{Q} \times \vec{P} \right) : \dot{z}$$

$$+ \frac{P_t}{8\beta} (B_0^2 Q^2 + 4P^2)$$

(12)

$$F_4 = \frac{P^4(5 - \beta^2)}{8\beta^4v^2} + \frac{P^2Q^2B_0^2(3 - \beta^2)}{16\beta^2}$$

$$- \frac{P^2}{2} \left( \vec{Q} \times \vec{P} \right) : \dot{z} \frac{B_0(3 - \beta^2)}{2\beta^2}$$

$$+ \frac{P^2}{2} \frac{P(3 - \beta^2)}{2\beta^2} + \frac{Q^4}{15} (B_0^4 - 4B_0B_7)/8$$

$$+ \frac{Q^2}{4} \frac{P^2}{4} \frac{3B_7^2}{4} + \frac{Q^2}{4} \left( \vec{Q} \times \vec{P} \right) : \dot{z} (B_2 - B_0)/4$$

$$- \frac{1}{8} \left( \vec{P} \cdot \vec{Q} \right)^2 B_0 - \frac{P^2}{4} \left( \vec{Q} \times \vec{P} \right) : \dot{z} B_0 + \frac{P_t}{8}$$

(13)

Following the hamiltonian flow generated by $H_{\text{New}} = F_2 + F_3 + ...$ from some initial $\psi_0$ to a final $\psi_f$ coordinates we can calculate the transfer map $M$ (eq. 9) for the solenoid. Where $F_2$, $F_3$, and $F_4$ would lead to the 1st, 2nd, and 3rd order maps. The effects of which can be seen from eqs. (12-14). For example, the 2nd order effects due to solenoid transfer maps are purely chromatic aberrations (eq. 13). In addition to chromatic effects, we note the third order geometric aberrations (eq. 14). The coupling between X, Y planes produced by a solenoid is rotation about the $z$-axis which is a consequence of rotational invariance of the Hamiltonian $H_{\text{New}}$ shown by eqs.(12-14), due to axial symmetry of the solenoid field.

![Figure 1: Sketch of the alternate injection system for ATF. A solenoid + gun + solenoid combination is placed straight ahead into the linac. (Not scaled).](image1)

For beam simulations, $M$ can be calculated to any order using numerical integration techniques such as Runge-Kutta method depending on the computer memory and space available [3].

### III. BNL ATF INJECTION SYSTEM

In this section we present some of our calculations and simulation results obtained for the proposed alternate (straight-ahead) injection system which consists of a pair of solenoids and an rf gun placed directly into the linac [1,7].

![Figure 2: Shows the change in position x [cm], phase $\phi - \phi_0$ [degree] and energy $w - w_0$ [KeV] of particles at each element location, from the cathode through the linac exit. With solenoid current of 2140 A and $d = 62$cm and $\sigma_z = .9mm$, $\sigma_z = 5ps$.](image2)

Present injection system consists of 2 sets of quadrupole triplets and a 180° achromatic double bend [1], where beam diverges quickly as it exits the gun and gets large as it traverses through the dipoles and the linac. We have used a pair of solenoids (placed before and after the gun such that $B=0$ on the cathode) shown in Fig. 1, which controls the beam divergence at the gun exit, reduces the emittance dilution due to space charge forces, and improves the conditions for production of high brightness low emittance beam needed e.g., for Free Electron Laser, and Inverse Free Electron Laser experiments. Figure 2 shows how the beam size increases as it drifts from the

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Figure 3: Shows the change in position $x$ [cm], phase $\phi - \phi_0$ [degree] and energy $w - w_0$ [KeV] of particles at each element location, from the cathode through the linac exit. With solenoid current of 2180 A and $d = 62$ cm and $\sigma_1 = 3$ mm, $\sigma_2 = 3.5$ ps.

gun into the linac. The beam converges to a waist in the linac resulting in a beam of smaller emittance at the linac exit which is of interest at ATF.

Comparison of Figs. 2 and 3 show locations of the beam waist and beam envelopes along the beamline from cathode through the linac. In Fig. 3, a 2% increase in the solenoid current resulted in the shift in the position of the beam waist in the linac and an emittance increase from $(\epsilon_x^{\text{rms}} = 278$, $\epsilon_y^{\text{rms}} = 243)$ to $(\epsilon_x^{\text{rms}} = 390$, $\epsilon_y^{\text{rms}} = 333)$ at the linac exit (as compared to Fig. 2). This illustrates the effects due to variation of the solenoid strength on the beam dynamics. In this analysis we used an initial $E = 100$ MV/m on the cathode, laser pulse length ($2\sigma_z$) of 10 ps, spot size $\sigma_r = 0.9$ mm, initial phase of 43°, and $d = 62$ cm, (the distance from cathode to linac entrance). The solenoid for this design can vary up to 4.0 KG in strength. For example with a 2.2 KG solenoid strength we can preserve the beam quality and achieve high brightness, low emittance beam at the linac exit (as may be the present double bend system). With solenoid+gun+solenoid straight injection into the linac scheme we reduce the emittance dilution due to space charge forces, and produce the beam needed for FEL, IFEL and other laser acceleration experiments. We obtained small emittance (few tens of cm-mrad) and high brightness of orders of $10^{13}$. The solenoids used in the alternate injection system, controls the beam divergence at the gun exit, reduces the emittance dilution due to the space charge forces on the beam and produces a smaller beam emittance needed for the experiments at ATF.

V. REFERENCES

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2. Z. Parsa, “Lie Algebraic Transfer Maps of Magnet System and Nonlinear Aberrations in the Beam”, BNL Tech. Note ADD/CAP/TN 5 (1/31/89) and References therein. Additional Lie transfers maps for drifts, quadrupole, dipole etc. were included in this reference.

3. A. Dragt, Program MARYLIE, Private comm.; ibid “Numerical third-order transfer map for solenoid “, NIM, A298 (1990), and References therein. MARYLIE includes 3rd order maps for solenoid with soft-edge “bump” function model for the field. We thank A.Dragt for discussions and providing his code. We did not include any results with MARYLIE for our analysis of the ATF alternate injection system with solenoids, since this code does not provide acceleration through the rf gun and the linac. Results with MARYLIE for the beamline without rf and linac accelerations will be given in a separate note.


