A comprehensive computer program for a high-current accelerator operating in the 100 ampere/10 MeV range has been developed. The accelerator is a narrow-bandwidth, coupled-cavity device with or without feedback between input and output cavities. Equations for the transient behavior of both the pumped or buildup phase and the accelerator phase have been programmed to allow for a wide range of design parameters such as number of cavities, cavity-cavity coupling, beam-cavity coupling, cavity loss or Q, stagger tuned cavities, input-output cavity coupling, and injected current as a function of time. The sinusoidal electric field in each cavity is expanded with the resonant modes, excited by the beam and boundary-matching magnetic current on the center holes. The irrotational field is computed as the unretarded Coulomb field of the beam as a collection of discs and their images. Feedback and feedforward waves in a waveguide which couples input and output cavities are represented by cutoff and propagating waveguide modes decomposed into Fourier components. Some computational properties of the program are discussed.

DESCRIPTION OF THE PROGRAM

The program has been developed for a high-speed large-memory digital computer to analyze the detailed behavior of a resonant ring accelerator in particular. This structure is pumped to a high energy during a time on the order of a microsecond and then depleted of energy during a time on the order of 15 nanoseconds or 45 rf periods of the microwave (S-band) frequency. In a high-current accelerator the space charge affects upon the solenoidal field and upon the irrotational or Coulomb repulsion between current elements (discs) are not negligible. In this program they are accounted for during each interval of time when the amplitudes of the solenoidal resonant cavity modes are integrated forward in time and the equations of motion for the various discs of charge are solved according to the total instantaneous axial electric field on each disc.

Specifically the program is written to describe the following phenomena. The entering prebunched current is decomposed into thin discs of varying charge and perhaps velocity, the total number limited by computer storage. As a disc approaches the first cavity it moves according to the Coulomb field of neighboring discs, their images, and the field created by magnetic current placed on the first centerhole to match boundary conditions there. A disc just leaving the last cavity is influenced by similar field components. A disc inside a given cavity moves according to the total axial electric field consisting of (a) a solenoidal portion represented by resonant cavity modes, the amplitudes of which are determined by the total cavity current and boundary-matching magnetic current on the centerholes and surfaces joining a feed-through rectangular waveguide, if one is present, and (b) the irrotational or unretarded Coulomb field of the discs in the given cavity and their images, the latter chosen to satisfy the boundary condition of normal electric field on the transverse walls of the given cavity before the holes are cut. In any cavity the magnetic current creates no Coulomb electric field.

The amplitude of each resonant cavity mode (so-called short-circuit mode) is evaluated by a straightforward procedure of solving Maxwell's equations within a closed volume containing electric currents inside and magnetic surface currents on part of the surface. Loss in the cavity walls and/or loss due to external cavity loading is accounted for by a phenomenological term in the equation of motion for each mode amplitude. The magnetic current on each centerhole is angularly flowing and a function of radial position on the hole, since the resonant modes and discs of charge are not angularly varying. This current is expanded in radial moments, each of which is determined by many radial moments of the total solenoidal and irrotational electric field on the centerhole so as to guarantee continuity of normal electric field across the hole. In addition the amplitude of each resonant cavity mode in the first or last cavity may be influenced by tangential electric field on a surface which joins the cavity to a feedthrough waveguide connecting the input and output cavities. This tangential electric field is expanded with the cutoff and propagating waveguide modes of (a) the wave arriving from the other cavity, (b) the "driving" wave which is present during the buildup phase, and (c) the wave which is launched to provide for continuity of tangential magnetic field across the surface which joins the first or last cavity to the waveguide. To obtain physical realism and minimize the accumulation of computational error it is necessary to expand the time dependent amplitudes of the waveguide modes into Fourier components over a fre-
frequency range of, say, twice the cutoff frequency of the dominant rectangular waveguide mode.

The irrotational component of the space charge field at any point within a cavity due to a disc or one of its images within that cavity, or on a center hole as due to a disc or one of its images within the cavities on either side, is computed from analytic approximations to the exact field in the vicinity of a disc as given by a Legendre-polynomial expansion. This representation is preferable to a slowly convergent expansion in irrotational modes because of the limitation on computer storage space.

**APPROXIMATIONS**

1. The accelerator chain of cavities is angularly symmetric; if a feedthrough waveguide couples input and output cavities in a nonsymmetric fashion the excitation of angularly-varying cavity modes is neglected.

2. The cavities all have the same radius, so that the resonant frequency of the first or TM\(_{010}\) mode is the same for all.

3. The surface which joins the input and output cavities to a rectangular feedthrough waveguide, if present is assumed to extend over the entire guide cross section; a smaller iris would require the solution of a set of simultaneous equations for the amplitudes of the guide cutoff and propagating modes launched at any instant of time. Curvature of these surfaces is neglected.

**EQUATIONS**

The \(m\)th solenoidal resonant cavity mode is defined with vector (denoted by a bar) patterns \(\vec{E}_n\) and \(\vec{H}_n\) within cavity \(n\) at point \(r\) as

\[
\nabla \times \vec{E}_n(r) = k_n^2 \vec{H}_n(r), \quad \nabla \times \vec{H}_n = k_n^2 \vec{E}_n
\]

(1a)

\[
\int_V \left( \vec{E}_n(R) \right)^2 dv = \int_V \left( \vec{H}_n(R) \right)^2 dv = \epsilon \omega_n m_0 c^2
\]

volume of cavity \(n\)

(1b)

\[
\vec{E}_n(R) = 0 \text{ on cavity } n \text{ surface}
\]

(1c)

If only the \(m=1\) or TM\(_{010}\) mode is employed to approximate the fields the electric field \(\vec{E}_n(r, t)\) in units of energy is

\[
\epsilon c \frac{\vec{E}_n(r, t)}{\omega_n m_0 c^2} = \frac{e c}{\omega_n m_0 c^2} \frac{\vec{E}_n(r, t)}{\omega_n m_0 c^2}
\]

\[
= W_n(t) \vec{E}_n(r)
\]

(2)

where \(e\) is the absolute charge of an electron of rest mass \(m_0\), \(c\) is light velocity, \(\omega_n = k_n c\), the same for all the cavities, and \(k_n R = 2.405\). \(W_n\) is

\[
W_n(t) = \frac{(\text{energy electron would gain from field } \vec{E}_n \text{ in a free space wavelength })}{\text{electron rest energy}}
\]

Furthermore, if the coupling holes between cavities are small the equation for \(W_n\) is, with \(\psi = \omega_n t\),

\[
W_n(t) = e^{-\frac{\psi^2}{2Q_n^2}} \left[ W_n(0) \cos (\psi) + W_n(0) \sin (\psi) \right] \frac{1}{2} \left[ e^{-\frac{\psi^2}{2Q_n^2}} \right]^2
\]

\[
+ \frac{1}{\tau} \int_0^\tau \int_0^\tau Q_n \frac{V}{c} \cos \frac{w_n}{w} \sin \frac{w_n}{2Q_n} \sin w_n (\psi - \psi') d\psi' \frac{d\tau}{(\psi - \psi')^2}
\]

(4)

4. The waveguide of a resonant ring accelerator is driven during the pumping phase, through a coupler assumed to be unidirectional. The guide transmission factor in either direction between input and output cavities is assumed to be frequency independent.

5. Radial motion of the discs of charge is neglected.

6. The circular walls of the cavities are assumed not to influence the Coulomb (irrotational) electric field due to the discs and their images chosen to keep the electric field normal to the walls between cavities before the center holes are cut.
If the two holes are the same size $m_0^{1/2} = m_{\text{hole}}^{1/2}$ and $w$ is the normalized phase shift frequency in an infinite chain of such cavities,

$$Q = \frac{e\gamma c}{\omega_0 m_0 c^2 \frac{j}{\omega_0 \tau}} = \left(\frac{\omega_0}{\omega_1}\right)^2,$$

where $\omega_0$ is the resonant frequency of the vacuum and $\omega_\text{pd}$ is the resonant frequency of an infinite plasma of charge density $q_\text{pd}$.

$$E_0 = \text{axial electric field pattern averaged over disc $d$.}$$

If $n=1$, signifying the first or input cavity, the right side of (4) would omit the $m_{n-1}$ term and would contain the term

$$-\frac{1}{w^2} C g \int_{-\infty}^{\infty} \left[ \int_{S_1} \frac{e\gamma c}{\omega_1 m_0 c^2} F(r, \psi) \bar{H}_1 \cdot \bar{n} ds \right] e^{-\frac{w(w)}{2Q^2}} \sin \frac{w}{2} d\psi \, d\tau \, d\theta \, d\phi \, (5)$$

where $C = \frac{A_g}{(\nu_1, \tau_1)}$, a dimensionless coupling coefficient in Fig. 1, $A_g$ being the waveguide cross sectional area.

A term analogous to (5) would appear in the equation for $W_n(\psi)$ of the last cavity, excited by electric field on $S_N$.

If the waveguide excitation is represented by the dominant $\text{TE}_{01}$ mode in this notation mode then $E(r, \psi)$ on $S_1^0$ is composed of (a) the driving field coupled into the feedthrough waveguide through a directional coupler, (b) the incoming or feedback wave which has been launched from the last cavity, and (c) the outgoing or feedforward wave which is launched from the first cavity in order to satisfy the boundary condition of continuous tangential $H$ field on $S_1^0$. The Fourier decomposition of $E$ on $S_1^0$ is, with $\psi = \omega t$ and $\tau = \nu t$,

$$\frac{e\gamma c}{\omega_1 m_0 c^2} F(r, \psi) \bar{H}_1 \cdot \bar{n} ds$$

instead of by the first integral term in (4). If the total normal incident field on a hole is $E_1^0$, expanded in radial moments or powers of $\zeta/b$ ($b =$ hole radius $a$ as

$$\frac{e\gamma c}{\omega_1 m_0 c^2} F(r, \psi) \bar{H}_1 \cdot \bar{n} ds$$

More generally $W_n(\psi)$, the amplitude of the $n$th mode in cavity $n$, would be determined by the total magnetic current $H_\text{M}(F, \psi)$ on the centerholes by the term

$$\frac{1}{2w_\text{r}^2} \int_{-\infty}^{\infty} \left[ \int_{S_1} \frac{e\gamma c}{\omega_1 m_0 c^2} F(r, \psi) \bar{H}_1 \cdot \bar{n} ds \right] e^{-\frac{w^2/2Q^2}{w}} \sin \frac{w}{2} d\psi \, d\tau \, d\theta \, d\phi \, (6)$$

where $H_\text{feed forward}$ is given by the second term of (6) but without the relevant factor in brackets, with the overall sign changed to $+$. and with $[\psi, \gamma, \tau]$ changed to $[\psi, \gamma, \tau]$.
and $K_m(z, \psi')$ is expanded as

$$\frac{ec}{\omega \mu_0 m^2} \sum_{n=0}^{M} A_{2n}(\psi')(z/b)^{2n}$$

and $R_m(z, \psi')$ is expanded as

$$\frac{ec}{\omega \mu_0 m^2} R_m(z, \psi') = \frac{ec}{\sqrt{b^2 - z^2}} \sum_{n=0}^{M} B_{2n}(\psi')(z/b)^{2n}$$

where $\mathbf{z}$ is the unit vector in the $z$-direction, then the $B_2$ are determined by the $A_2$ so as to maintain continuity of normal electric field as

$$B_{2m} = \left(-\frac{2A_{2m}}{(m+1)!}\Gamma(m+3/2)\right) - \frac{1}{m!} \sum_{n=m+1}^{M} (B_{2n} n!)$$

where $\Gamma$ is the ordinary gamma function, and

$$S(m,n) = \sum_{n=0}^{m} \frac{(\alpha+1)!}{(n-m)!} \frac{1}{\alpha+1} \frac{1}{\alpha-m}$$

Eqs. (9) - (11) enable a computation of the cavity excitation term (8) from knowledge of the total axial electric field on each centerhole.

The analytic expressions for the irrotational field in the vicinity of a disc due to its charge are not quoted here.

The equations of motion for each disc to be solved during each short time interval $\Delta \psi$ are written

$$\Delta v_d(\psi)/c = -\left[1-v_d(\psi)/c\right] \frac{ec}{\omega \mu_0 m^2} \frac{1}{\pi} \sum_{n=0}^{M} A_{2n}(\psi')(z/b)^{2n}$$

$$\int_0^{\psi_{total}} E_z, \text{total}(\psi) \frac{d \psi}{d \psi}$$

where $a$' being the disc radius. Last of all,

$$\Delta \psi = \frac{v_d(\psi)}{c} \Delta \psi$$

expresses the change in position of disc $d$.

**RESULTS**

To date the initial pumping phase of a resonant ring structure has been studied in the absence of a beam via Eqs. (6) - (7). In order to reduce computation time, integral Eq. (4) has been applied over a succession of short time intervals comprising the interval of interest rather than over one long interval. Early in the program the feedback and feedforward waves were not decomposed into Fourier components but instead were approximated by propagating TE01 waves of a single velocity which were launched and reacted back upon the cavities according to instantaneous steady-state equations. This representation caused intolerable error in computation of the cavity voltages over a few rf cycles. With the feedthrough waves decomposed into Fourier components traveling at different velocities through the waveguide the feedthrough effect is less of a step function on both the input and output cavities. Even so, the computations to date indicate that the errors in computing cavity voltages by Eq. (4) from the succession of convolutions over short time intervals tend to be acceptably large. Subsequent work may demonstrate that the voltages are computed more accurately from the difference equation approximations to their differential equations rather than from integral equations.

**REFERENCES**

1. R.M. Bevensee, Electromagnetic Slow Wave Systems (J. Wiley and Sons, 1964) Chap. 5, Section 3C.
2. P. M. Morse and H. Feshbach, Methods of Theoretical Physics (McGraw Hill Book Co., 1953) P. 1267.