EVALUATION OF SYNCHROTRON RADIATION INTEGRALS*  
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Introduction

Many of the important properties of the stored beam in an electron storage ring are determined by integrals, 1 taken around the whole ring, of various characteristic functions of the guide field. Some of the integrals are handled easily, but a few are usually handled graphically — particularly for alternating-gradient guide fields. This report describes a convenient method for evaluating numerically these recalcitrant integrals.

In the usual linear approximation, the integrals we wish to consider are most conveniently expressed in terms of four (somewhat redundant) functions of the azimuthal coordinates: p(s) the radius of curvature of the design orbit, n the field index, F(s) the radial betatron function and T(s) the off-energy (or "dispersion") function.

The Integrals

We restrict our attention to guide fields made up of a number of magnetic segments — magnets or straight sections. The functions p and n are assumed to have constant values within a given magnet, but vary abruptly at the entrance and exit boundaries. The integrals of interest are given by:

\[ I_1 = \int \left( n / \rho \right) ds = \sum_{i} \frac{1}{\rho_i} \langle n \rangle_i \]  
\[ I_2 = \int \left( 1 / \rho^2 \right) ds = \sum_{i} \frac{1}{\rho_i^2} \]  
\[ I_3 = \int \left( 1 / \rho \right) ds = \sum_{i} \frac{1}{\rho_i} \]  
\[ I_4 = \int \left( -2n \eta \right) / \rho^3 ds = \sum_{i} \frac{1}{\rho_i^3} \langle \eta \rangle_i \]

We have used the notation \( \langle \cdot \rangle \) for the mean value of \( \cdot \) in the \( i \)th segment whose length is \( \ell_i \). The function \( H(s) \) is defined by

\[ H = \frac{1}{\rho^2} \eta^2 + \left( \frac{d^2}{ds^2} \rho^{-1} n \right)^2 \]

with \( \rho = d\ell / ds \) and \( n = d\eta / ds \). It should be noted right away that at least one factor of \( 1 / \rho \) appears in each integral; so the straight sections or pure quadrupoles make no contribution.

The integrals \( I_2 \) and \( I_3 \) are, evidently, simple sums. Our purpose is to show that the factors \( \langle n \rangle_i \), \( \langle \eta \rho \rangle_i \), and \( \langle H \rangle_i \) that appear in the remaining integrals can be expressed as relatively simple algebraic expressions involving the values of \( \beta \) and \( \eta \) together with their derivatives only at the segment boundaries.

The Beam Parameters

The various performance parameters of storage rings that can be expressed in terms of these integrals are as follows. 1

1. The dilation factor \( \alpha \), also known as the "momentum compaction," is \( \alpha = I_1 / L \) where \( L \) is the length of the design orbit.
2. The energy loss \( U_0 \) in one revolution from synchrotron radiation is

\[ U_0 = \frac{2}{3} \frac{r_e}{m_e} \frac{E_0^2}{(me^2)^3} I_3 \]

where \( E_0 \) is the nominal energy of the stored electrons, \( r_e \) is the classical electron radius, and \( mc^2 \) is the electron rest energy.
3. The damping of radial betatron oscillation and of energy oscillations are proportional to the damping partition factors \( J_x \) and \( J_e \). In terms of our integrals:

\[ J_x = 1 - \frac{I_4}{I_2}; \quad J_e = 2 + \frac{I_4}{I_2} \]

Alternatively, we may write the exponential damping coefficients \( a_x \) and \( a_e \) as

\[ a_x = \frac{r_e}{3} \frac{E_0^2}{mc^2} \frac{C}{L} (I_2 - I_4) \]  
\[ a_e = \frac{r_e}{3} \frac{E_0^2}{mc^2} \frac{C}{I_2} \]

where \( C = 1 + \frac{I_3}{I_1} \).
4. The distribution of energies induced by quantum emission in a stored beam is — under stationary conditions — characterized by the root-mean-square energy spread \( \sigma_E \). We may write

\[ \frac{\sigma_E^2}{E_0^2} = \frac{56}{32 \sqrt{3}} \frac{2}{mc} \frac{E_0^2}{(mc)^2} \frac{I_5}{2I_2 + I_4} \]

where \( h/mc \) is the reduced Compton wavelength.
5. The quantum excited radial betatron oscillations will, under stationary conditions, have a local root-mean-square displacement \( \sigma_\beta(s) \) given by

\[ \frac{\sigma_\beta^2(s)}{\beta(s)} = \frac{56}{32 \sqrt{3}} \frac{2}{mc} \frac{E_0^2}{(mc)^2} \frac{I_5}{2I_2 + I_4} \]

Normal Boundary Magnet

We consider now the evaluation of \( \langle n \beta \rangle \), \( \langle \eta \rho \rangle \beta \rangle \), and \( \langle H \rangle \beta \rangle \) for a particular magnet of length \( \ell \). For this section we assume that the fringe field boundaries are normal to \( s \), and that within the magnet \( \rho \) and \( n \) are constant. Under these assumptions the values of \( \eta \) and \( \beta \) inside the magnet may be expressed in terms of the values of these functions and their derivatives at the magnet entrance:

\[ \eta = \eta_0 C + \eta_0 \frac{S}{k} \frac{1}{r_k^2} (1 - C) \]  
\[ \beta = \beta_0 C^2 - 2\beta_0 \frac{C S}{k} + \frac{\gamma_0 \frac{S^2}{k^2}}{2} \]

where \( k^2 = (1-r) \mu^2 \), \( C = \cos ks \), \( S = \sin ks \), and \( k \) is the dis-
tance from the entrance edge of the magnet. The quantity $k^2$ is the "restoring force" constant of the particle oscillations. A magnet is focusing if $k^2 > 0$ and $k = (1-n)1/2/p$, and is defocusing if $k^2 < 0$ and $k = (n-1)1/2/p$.

The value of $\langle \eta \rangle$ can be found by integrating Eq. (12) directly which yields

$$\langle \eta \rangle = \eta_0 \frac{\sin k_0}{k_0^2} + \eta_0 \frac{1-\cos k_0}{\rho k_0^3} + \frac{1}{\rho^2} \frac{k^2 - \sin k^2}{k_0^2}$$

For a normal boundary magnet the variation of $n$ in the fringe field boundary does not contribute to the value of $\langle \eta \rangle$ (see Appendix). Thus

$$\langle \eta \rangle = \frac{\eta_0}{\rho^3} \langle \eta \rangle$$

(15)

To find the value of $\langle H \rangle$ first we rewrite Eq. (6), the definition of $H$, in a more convenient form:

$$H = \gamma^2 + 2\alpha \eta + \beta \eta^2$$

where $\alpha$, $\gamma$, and $\eta$ are given by

$$\alpha = \frac{1}{2} \beta^2 = \frac{\beta_0^2 + \alpha_0 (C^2 - S^2) - \gamma_0 CS}{k}$$

(17)

$$\gamma = \frac{1}{\beta} (1 + \alpha^2) = \frac{\beta_0^2 + \alpha_0 (C^2 - S^2)}{k}$$

(18)

$$\eta = -\eta_0 KS + \eta_0 C + \frac{8}{\rho k}$$

(19)

These expressions, together with Eqs. (12) and (13) for $\eta$ and $\beta$, can now be substituted into Eq. (16) for $H$ to give a form that can be straightforwardly integrated. After some manipulations, the result becomes:

$$\langle H(\eta_0, \beta_0, \eta_0) \rangle = \gamma_0^2 \frac{\sin k_0}{k_0^2} + \eta_0 \frac{1-\cos k_0}{\rho \beta_0 k_0^3}$$

$$+ \frac{2}{\beta_0^2} \left( (\gamma_0^2 + \alpha_0 \eta_0^2) \frac{k - \sin k^2}{k_0^2} + (\alpha_0 \eta_0 + \beta_0 \eta_0^2) \frac{1-\cos k}{k} \right)$$

$$+ \frac{1}{\rho^2} \left( 3k^2 - 4 \sin k^2 + \sin k^2 \cos k^2 \right)$$

$$- \frac{2}{k_0^2} \left( \eta_0 \frac{1-\cos k}{k} \right)^2 - \frac{2}{k_0^3} \left( 2k_0 \right)$$

(20)

**Non-Normal Boundary Magnet**

If the magnet boundaries are not normal to the direction of the design orbit, the above results are modified by the local gradients seen by a particle in passing through the fringe field at an angle (see Appendix):

$$\langle H \rangle = \langle H(\eta_0, \beta_0, \eta_0) \rangle$$

(21)

$$\langle \eta \rangle = \frac{n}{\rho^3} \langle \eta \rangle$$

(22)

$$\langle H \rangle = \langle H(\eta_0, \beta_0, \eta_0) \rangle$$

(23)

where

$$\eta_1 = \eta_0 + \frac{\eta_0}{\rho} \tan \phi_1; \quad \eta_2 = \eta_0 \cos k \frac{k^2}{k} + \frac{\eta_0}{\rho k} \tan \phi_1; \quad \beta_1 = \beta_0 + \frac{\beta_0}{\rho} \tan \phi_1.$$

The boundary rotation at the magnet entrance is $\phi_1$, and at the exit $\phi_2$. Positive $\phi$ means radial defocusing at either entrance or exit of the magnet.

**References**


**APPENDIX**

**Calculation of Effects of Non-Normal Boundaries**

The local gradients which arise from the non-normal boundaries perturb the slopes of the $\eta$ and $\beta$ functions and also contribute to the $\langle \eta^3 \rangle$ integral through its explicit dependence on $n(s)$. To calculate these effects, consider an entrance boundary and assume that the fringe field varies from $B = 0$ to $B = B_0$ in a very short distance, $2\epsilon$. i.e. $B(\alpha_1 - \epsilon) = 0$, $B(\beta_0 + \epsilon) = B_0$. The gradient index associated with the boundary rotation $\phi$ is approximated by

$$n(s) = -\frac{\partial B}{B} \frac{\partial \phi}{\partial s} \cong \frac{B}{B} \frac{d\phi}{ds} \tan \phi_1$$

(24)

In the familiar impulse approximation for edge focusing, we assume that $\eta$ and $\beta$ are unchanged in going through the fringe field. The changes in $\eta$ and $\beta$ are

$$\eta_1 = \eta_0 + \frac{(\eta_0 P_0)}{\rho \beta_0} \tan \phi_1$$

(25)

$$\beta_1 = \beta_0 + 2(\beta_0 P_0) \tan \phi_1$$

(26)

where $P_0$ is the bending radius in the interior of the magnet.

The increment of the integral $\langle \eta^3 \rangle$ in the same impulse approximation is

$$\delta \langle \eta^3 \rangle = \frac{\eta_0 \tan \phi_1}{\tan \phi_1} \tan \phi_1 \tan \phi_1$$

(27)

We employ the usual convention for the sign of the entrance and exit boundary angles (positive $\phi$ means radial defocusing at either entrance or exit). See Fig. A-1. The results for the exit boundary are completely analogous.