

LHC COLLIMATION: DESIGN AND RESULTS FROM PROTOTYPING AND BEAM TESTS

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Abstract

The problem of collimation and beam cleaning is one of the most challenging aspects of the LHC project. A collimation system must be designed, built, installed and commissioned with parameters that extend the present state-of-the-art by 2-3 orders of magnitude. Problems include robustness, cleaning efficiency, impedance and operational aspects. A strong design effort has been performed at CERN over the last two years. The adopted phased approach is described. Robust and precisely controllable collimators have been designed. Several LHC prototype collimators have been built and tested with the highest beam intensities that are presently available at CERN. The successful beam tests are presented, including beam-based setup procedures, a 2 MJ robustness test and measurements of the collimator-induced impedance. Finally, an outlook is presented on the challenges that are ahead in the coming years.

INTRODUCTION

The LHC requires a stored energy of 360 MJ per beam. This is 2-3 orders of magnitudes above the stored energy that is handled in other proton colliders and must be compared to a typical 10 mJ/cm^3 quench limit of the superconducting magnets. A robust and highly efficient collimation system is required to withstand the high beam intensities and to absorb unavoidable beam losses [1]. At 7 TeV the specified peak loss rate corresponds to a total loss in beam intensity of 1% over 10s. This loss rate implies cleaning inefficiencies of around 5×10^{-4} . Proton losses must be intercepted at the collimators and not more than 0.05% of the impacting protons are allowed to leak out of the “cleaning insertions”. Two such cleaning insertions have been included into the LHC layout for betatron and momentum cleaning [2].

LHC COLLIMATION DESIGN

The LHC collimation design has been revisited. Important improvements have been implemented. A complete system description would go beyond the scope of this paper. However, we summarize the key features:

1. **Robust primary and secondary collimators** with 1.2 m long water-cooled carbon-carbon (CC) jaws (this includes 0.2 m of tapering), precise jaw position control and handling of image currents [3]. These col-

- limators intercept the primary and secondary beam halos and are the closest aperture to the circulating beam.
2. **Movable absorbers** (“high-Z collimators”) with 1.2 m long water-cooled, tapered Cu/W jaws. Absorbers intercept the tertiary beam halo and/or the shower products from the cleaning insertions or the p-p collisions. Absorbers have been integrated downstream of the cleaning insertions and in all experimental insertions.

In each of the two LHC rings 46 collimators and absorbers will be installed. The 92 collimators in total have been carefully positioned to respect space constraints while providing optimal cleaning efficiency and good machine protection.

The usage of the non-metallic CC collimators close to the LHC beam (full gaps down to 3 mm) optimizes robustness for the price of high induced impedance. Though this collimator-induced impedance was almost halved by proper positioning of the collimators, the overall effect is still strong and is estimated to limit the LHC proton beam intensities at around 40% of their nominal values [4].

The robust but impedance-limited initial LHC collimation system is called “**phase 1**”. In order to overcome the limitations in LHC performance the phase 1 secondary collimators are complemented by space reservations for 1.48 m long “**phase 2**” collimator tanks. In total 30 space reservations will allow to complement the collimation system in 2010 with advanced “hybrid” collimators that combine sufficient reliability with low impedance. The R&D on suitable phase 2 collimators is already on its way at CERN and in the US (LARP program).

Other important design work on the collimation system concerns energy depositions studies [5] and analysis of associated radiation issues [6]. A first result of cleaning efficiency with the full system is included in [7].

PROTOTYPING

The design of the robust CC collimators for the LHC is described in [3]. Two prototypes were built for installation into the SPS ring and the TI8 injection line at CERN. Photographs of the fully equipped LHC collimator are shown in Figures 1 and 2.

The collimator design team had to address challenging requirements including jaw flatness ($25 \mu\text{m}$ over 1 m), heat conductance ($\sim 10 \text{ kW/m}^2/\text{K}$), mechanical plays ($\sim 10 \mu\text{m}$) and clean vacuum performance.



Figure 1: Top view of the open LHC collimator tank with two 1.2 m long CC jaws installed.

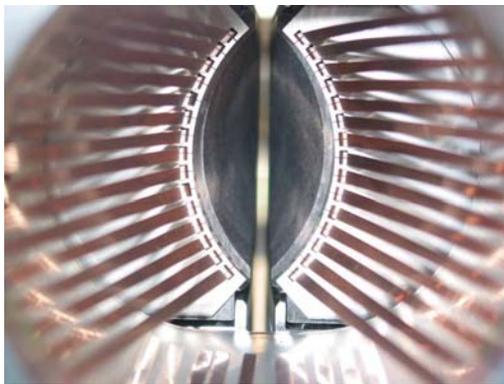


Figure 2: View along the free beam path of the CC collimator with a small collimation gap (~2 mm). The RF contacts guide the beam image currents.

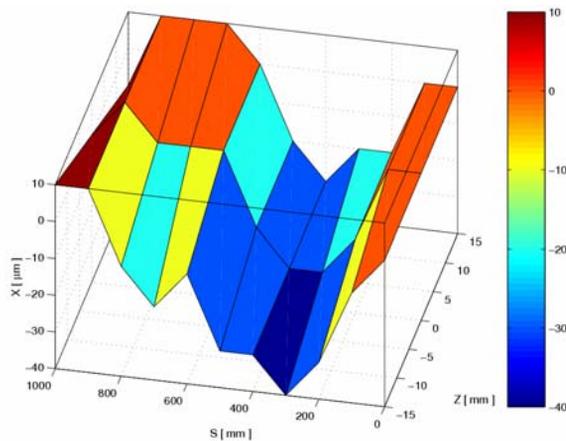


Figure 3: Flatness of the fully assembled CC jaw over its 1m long (S) flat top and for three positions along its width (Z). This was measured after bake-out at 250 °C.

Extensive simulations with beam tracking, showering (FLUKA) and thermo-mechanical (ANSYS) codes were relied on for optimizing the collimator design. The prototypes were then extensively measured in the laboratory for evaluating the achieved results. Of particular importance is the **flatness of the assembled collimator jaws**. A tolerance of 25 μm was specified based on the small 7 TeV beam size ($\sigma_{x,y} \approx 200 \mu\text{m}$) and the 1σ difference between primary and secondary collimator positions. A jaw flatness of 40 μm was achieved, as shown in Figure 3. Though not as good as specified, the achieved flatness is considered as an excellent success and as acceptable for phase 1 operation in the LHC. Beyond the flatness a number of other important parameters were measured in the laboratory:

1. The **electrical resistivity** of the CC jaw was measured to be 10.2 $\mu\Omega\text{m}$ along the jaw surface (both parallel and perpendicular to the beam direction). A smaller resistivity of 5-6 $\mu\Omega\text{m}$ was measured in the direction towards the back of the jaw.
2. The **thermal conductance** through the CC jaw with the clamped water cooling circuit was tested in a dedicated test stand. For a spring pressure of 6 bar a thermal conductance of 8.8 $\text{kW}/\text{m}^2/\text{K}$ was measured.
3. The wear, contact resistance and heating effects for the 0.5 mm thick **CuBe RF fingers** (coated with 8 μm Ag) were tested in a dedicated test stand. Contact resistance as low as 0.5 $\text{m}\Omega$ was achieved for the full bridge from CC to the flanges.
4. The **mechanical play** in the jaw movement was evaluated for each support point. Plays between 10 μm and 40 μm were measured with several precise sensors (LVDT, capacitive gauge, resolver).

It was found that the prototype collimators had properties close to the demanding specifications. The design choices were confirmed and the collimators were installed on schedule for beam testing.

RESULTS OF BEAM TESTS

Robustness test

A beam line location at the exit from the SPS towards the LHC allows extracting 3×10^{13} protons at 450 GeV onto a collimator. The pulse length is 7 μs and the transverse size of the extracted beam is $0.7 \times 1.2 \text{ mm}^2$. It is interesting to note that the 2 MJ of extracted energy corresponds to the full Tevatron beam or 0.5 kg of TNT. The LHC collimator was designed to survive twice this energy. Robustness considerations included the CC jaw, metallic support parts and the water circuit at the CC jaw. The collimator was repeatedly hit with the 2 MJ beam (10 times at highest intensity) with distances up to 5 mm from the jaw edge. No sign of damage was observed, except the progressing loss of temperature sensors in the CC jaws (see also [3]). A photograph of the collimator after the robustness test is shown in Figure 4. Vibration and sound measurements during the tests are discussed in [8]. The robustness of the collimator design was confirmed.



Figure 4: Photograph of the downstream end of the collimator prototype after it was hit repeatedly by a 2 MJ beam, up to 5 mm from the jaw edge. The left jaw (structured surface) is CC and the right jaw simple Graphite.

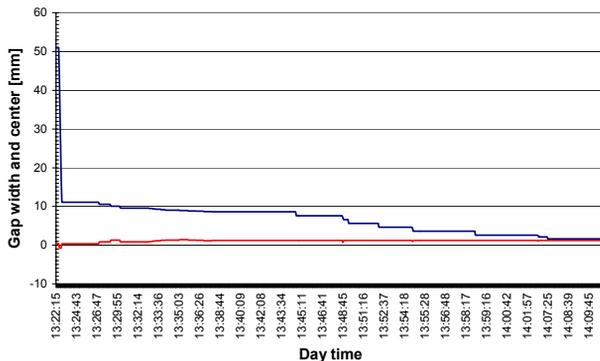


Figure 5: Centre and width of the collimation gap in the SPS ring with stored beam at 270 GeV.

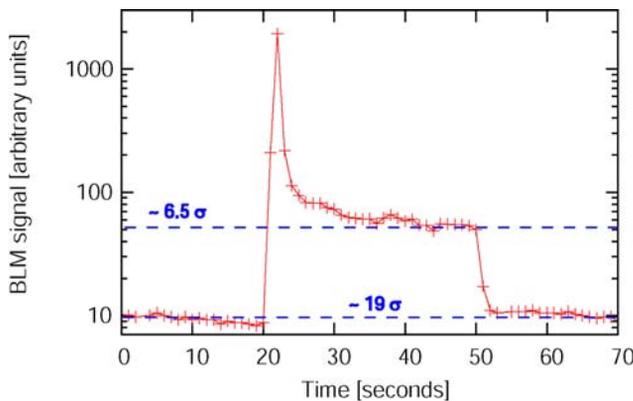


Figure 6: Measured beam loss signal after changing the collimator jaw position from 19 σ to 6.5 σ and back.

Operational tests

The stored SPS beam of 270 GeV protons was used for operational tests. The LHC prototype collimator was complemented by various beam loss monitors downstream. The operational tests included measurements of beam loss patterns, beam-based alignment of collimator gaps and impedance measurements. The impedance measurements are described in [9]. Figure 5 shows the

successful beam based alignment of the collimator gap around the stored beam. It is seen that the collimation gap could be adjusted to 1 mm with circulating beam. This gap is smaller than required for the LHC and illustrates the very satisfactory control and alignment of the LHC prototype collimator. The beam-based alignment was performed with 50-100 μm absolute accuracy. Gaps were known to better than 100 μm and the reproducibility of settings was about 20 μm . The accuracy of the beam-based alignment was limited by long decay times in the observed beam loss signals. This was proven to be a real beam dynamics effects and is shown in Figure 6.

CONCLUSIONS

A powerful collimation system has been designed for the LHC. The phase 1 collimation is robust and efficient but impedance limited. The initial system will be upgraded with phase 2 hybrid collimators, which have been fully integrated into the layout and will be installed several years after the LHC start-up.

The phase 1 collimator design has been worked out in detail. Prototyping and beam tests have proven all main features of the collimator design. In particular a good surface flatness and excellent robustness have been demonstrated. The operational tests with stored beam confirmed the full functionality of the collimator and the expected impedance. Beam-based set-up was limited by beam-dynamics effects.

Further work will include the series production and installation of all collimators, the definition of the collimation control system, the preparation of collimator commissioning and the design of phase 2 collimators.

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